freedom without a tenure system that effectively prevents many schools at all levels from keeping up with changing times.

It should come as no great surprise that many of the most capable teachers are leaving universities, colleges, and secondary schools for more rewarding jobs in industry. Having been compelled to go into industry because of the job market in academic physics and astronomy in the early 1970's, I would not now return to the academic community even though I love teaching. This is partly due to the financial rewards and the more challenging environment of industry and partly due to the lack of any real interest (reflected in hiring, promotions, and salary) on the part of universities in providing the product which is so desperately needed—quality education at a reasonable price. That educational programs are as good as they are in the face of institutional disinterest is a credit to the strong personal commitment of many faculty members. It is largely up to the college and university administrators themselves to find solutions to problems which they have in large part created.

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Space Shuttle: Remote Manipulator Arm

The article "Shuttle launch expected soon" (News and Comment, 9 Oct., p. 160) by R. Jeffrey Smith contains a description of the remote manipulator arm that requires elucidation. Smith describes the arm as having three joints. Technically speaking, the arm has six joints: shoulder yaw, shoulder pitch, elbow pitch, wrist pitch, wrist yaw, and wrist roll.

The $100 million (Canadian dollars) for the development of the remote manipulator arm was contributed entirely by Canada to the U.S. Space Shuttle Program. The National Aeronautics and Space Administration will procure the next three arms for only $25 million (Canadian dollars) each.

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Erratum. In the report entitled "Autoimmune encephalomyelitis: Simultaneous identification of T and B cells in the target organ" by U. Traugott *et al.* (11 Dec., p. 1251), the name of the fourth author should have been S. H. Stone.