Carbonic Anhydrase in Seawater: Carbonato Complexes

With regard to the equilibration of atmospheric carbon dioxide with seawater and possible enzymatic control, as discussed by Berger and Libby (1), there is experimental evidence for the occurrence of carbonic anhydrase in marine and freshwater algae (2). The enzyme itself is a white crystalline solid, stable and active on storage at room temperature. I have used this material in our studies on the fractionation of carbon-13 between gaseous CO_2 and dissolved inorganic carbon species for obtaining rapid chemical and isotopic equilibrium (3).

The hydration and dehydration of CO₂ is a fundamental natural process, and it has been estimated that over 200 billion tons of CO₂ are annually exchanged across the ocean surface (4). I am studying the participation of any metal carbonato complexes aiding this process in view of the fact that the zinc moiety in carbonic anhydrase is reported to be significant in the enzymic reaction as a whole. The Zn-free enzyme is inactive, and the activity can be restored by the addition of Zn^{2+} ions. It is not clear under open-ocean conditions whether ion-pair complexes like ZnCO₃⁰, CuCO₃⁰, MgCO₃⁰, CaCO₃⁰, and the corresponding bicarbonate ionpair complexes and the mixed amine carbonato complexes have something to do with the overall hydration and dehydration process (5).

I shall indeed be grateful for exchange of ideas and information in the field of metal carbonato complexes and their possible participation in the hydration and dehydration of CO_2 .

KOTRA V. KRISHNAMURTY Department of Oceanography, Texas A & M University, College Station 77843

References

- 1. R. Berger and W. F. Libby, Science 164, 1395 (1969).
- C. D. Litchfield and D. W. Hood, Verh. Int.

- C. D. Litchneid and D. W. Hood, Vem. Int. Ver. Theor. Angew. Limnol. 15, 817 (1964).
 H. G. Thode, M. Shima, C. E. Rees, K. V. Krishnamurty, Can. J. Chem. 43, 582 (1965).
 G. N. Plass, Sci. Amer. 201, 28 (July 1959).
 K. V. Krishnamurty, G. M. Harris, V. S. Sastri, Chem. Rev., in press.

30 June 1969

Plasticity of Hypothalamic Motivational Systems

Valenstein, Cox, and Kakolewski (1) have criticized an explanation that I offered (2) to account for an interesting phenomenon they had reported (3). This note is in reply to their criticism.

In their original study (3), Valenstein et al. examined the effects of electrical stimulation in the lateral hypothalamic area of the sated rat placed in a box with three "goal" objects-food, water, and a piece of wood. First, in preliminary tests, they found the level of current that reliably produced either eating of the food, drinking of the water, or gnawing of the wood at a particular electrode site. Then, using the same current level, they gave additional "stimulation experience" in the absence of the goal object to which each rat had responded in preliminary testing (for example, food), but in the presence of the two remaining goal objects (water and wood). They found that the additional stimulation experience made rats respond appropriately to a new goal object-that is, drinking or gnawing emerged as a result of further stimulation experience at the site that had originally produced only eating. Valenstein et al. explain this finding by suggesting (i) that the second stimulation-29 AUGUST 1969

bound response was mediated by the same lateral hypothalamic drive system that originally mediated the first response, and (ii) that this drive system became capable of mediating the second response as a consequence of its modification by stimulation experience with the first goal object removed. Essentially, then, they postulated a single, plastic lateral hypothalamic drive system, whose behavioral influence is not genetically fixed, but can be altered by experience.

My alternative explanation was based on the assumptions (i) that the electrical stimulation simultaneously excited the fibers of two or more genetically fixed drive-specific systems, and (ii) that the emergence of a new response at a given current intensity reflected a change in the stimulation threshold for that response. The first of these assumptions was supported by my finding that if the stimulation intensity was raised after one stimulation-bound response was observed, a second response could always be elicited during the same testing session. The second assumption was supported by the finding that the threshold for the second behavior did in fact decline with repeated testing, until it was possible to elicit it at the same current level that had produced the first response. Thus my position was that the changes in the effects of the electrical stimulation which were observed in their experiment, as well as in mine, resulted from a change in the efficiency of transmission within genetically fixed, drive-specific systems, while the position of Valenstein et al. implied that it resulted from a modification of the efferent connections of a general plastic drive system.

In criticizing my explanation, Valenstein et al. (1) argue that the added variable in my experiment (manipulation of current level) produced no effect that they were not able to produce without it. They suggest that, in exploring for the current level at which I first elicited the second response, I gave my animals sufficient stimulation experience with the second goal object to produce the second behavior, just as they had done without raising the current. It is true that my animals received some stimulation experience with the second goal object before the current level was raised sufficiently to elicit the second response. However, it is clear from my data (2, Fig. 1) that this was not sufficient experience to produce the second behavior without current manipulation. The high thresholds that I found for the second response on the 1st day of testing represent, by definition, the lowest current level that would reliably elicit the response in question. Much more stimulation experience was required for the second response to emerge at the level of stimulation that was initially used to elicit the first response. Thus the threshold changes that I reported occur during the stimulation experience necessary to produce the "switching" observed in the experiment of Valenstein et al., and not after that experience. It is because stimulation experience produces both the changes in stimulation-bound responding reported by Valenstein et al. and also the threshold changes that I reported, that I suggest a single explanation for both findings. The hypothesis that stimulation experience changes the efficiency (or sensitivity) of organized drive systems is necessary to explain my finding of threshold changes and is sufficient to explain the finding of Valenstein et al. The hypothesis that stimulation experience changes the drive specificity of a plastic drive system, while it does explain their finding, does not account for mine.

It should be emphasized that the is-

sue that divides us is not whether stimulation per se, as opposed to stimulation experience in the presence of appropriate goal objects, is the critical factor in determining the behavioral effects of lateral hypothalamic stimulation. Stimulation experience with a second goal object is necessary for the emergence of the second behavior in the procedure of Valenstein et al., and also for the threshold changes in my experiment; I have found no effect of stimulation on eating or drinking thresholds unless the stimulation occurred in the presence of relevant goal objects.

The issue that does divide us is whether the stimulation experience results in achange in the drive specificity of the hypothalamic neural elements affected by the stimulation. Valenstein et al. assume that the observed behavioral changes imply changes in the motivational state of the animals-that if the animal does not eat on the first trial, but does eat later, a change in drive must have taken place. I do not think we can conclude that an animal is not hungry on the first trial simply because it does not eat. The eating behavior of hungry animals depends on a number of factors in addition to the amount of food deprivation they have undergone. Important changes in feeding behavior occur, with food deprivation held constant, as animals are allowed to get accustomed to novel feeding situations and schedules (4). It is worth noting that in electrical stimulation experiments not even the initial (presumably dominant) response is produced on the first trial. Rather, it develops with stimulation experience, just as the second behavior does, and just as normal eating develops with familiarity with the feeding situation.

I suspect that the important effect of stimulation experience is that it gives the animal an opportunity to learn, by trial and error, just what acts and what goal objects are appropriate to the drive state (or states) elicited by the stimulation. I think that such learning must precede stable stimulation-bound responding to every new goal object used in this type of experiment, just as it must precede stable responding to new goal objects under normal drive states. We learn that an object is "food" by

tasting it and trying a little; we learn that a right turn at the corner leads to a restaurant also by trying it. Hunger prompts us to act; experience tells us what acts are appropriate. The fact that we are finicky with novel foods, or that we wander rather than go straight to a restaurant, does not necessarily mean that we are not hungry.

R. A. WISE Department of Psychology, California State College at Los Angeles

References and Notes

- E. S. Valenstein, V. C. Cox, J. W. Kakolewski, Science 163, 1084 (1969).
 R. A. Wise, *ibid.* 162, 377 (1968).
 E. S. Valenstein, V. C. Cox, J. W. Kakolew-ski, *ibid.* 159, 1119 (1968).
- ski, *ibid.* 159, 1119 (1968).
 L. Ghent, *Can. J. Psychol.* 5, 77 (1951).
 Supported by PHS grant (MH-03238-07) and National Research Council of Canada grant (APB-74) to Dalbir Bindra. I thank Dr. Bindra for his help.
- 7 February 1969; 28 April 1969

Spin-Orbit Resonance

of the Inner Planets

Radar measurements of the axial rotation of Mercury and Venus indicate that the spin and orbital motions of the inner planets are in resonance. Mercury's sidereal spin angular velocity is apparently 3/2 of its mean orbital motion about the sun (1). The spin angular velocity of Venus is retrograde and apparently synchronized with successive close approaches with the earth (2).

Shapiro observes that, "The length of the day on Venus is therefore about 117 days, apparently by coincidence almost exactly two-thirds of the length of the day on Mercury." I suggest that this commensurability may not be a coincidence, but may be associated with the mechanism responsible for locking Venus's spin period into resonance with the earth's orbit.

The necessary condition for capture into a spin resonance is the presence of an appropriate term in the tidal torque which will damp oscillations about the resonance state (3-5). This term is present in the case of Mercury, and the 3/2 resonance is fairly well understood (3, 5). In the case of Venus, however, the appropriate damping term is absent (4, 5). There is no obvious

reason why the spin of Venus should be synchronized with the earth's orbit rather than with its own orbit about the sun, as in the case of Mercury.

Venus makes four axial rotations as seen from the earth in one synodic period (6) of 583.9 days. The synodic spin period of Venus, 146.0 days, is something of a magic number among the inner planets. This period is almost exactly 2/5 of the earth's orbital period and is very close to 12/3 of Mercury's orbital period. The synodic period of Mercury as seen from Venus is 144.5 days. This suggests that Mercury's orbital motion is nearly commensurate with the earth-Venus spin resonance. If we assume that at some time in the past a triple conjunction of the earth, Venus, and Mercury occurred, one finds that Mercury is again very close to the earth-Venus-sun line after 583.9 days when the Venus spin resonance occurs.

The relation of Mercury's orbit to the earth-Venus spin resonance could provide the necessary mechanism for trapping Venus's spin into this commensurability. Although Mercury's mass is only 1/20 that of the earth, the small additional torques could have a cumulative effect when applied at the proper frequency.

The proof of this hypothesis would require a fairly difficult calculation of the capture probability along the lines set forth by Goldreich and Peale (5), including the additional tidal torques of Mercury. It might then be possible to show that this particular resonance occurred because of the combined tidal action of Mercury and the earth on Venus at a time when the three orbits were properly synchronized.

PHILIP M. CAMPBELL Department of Physics and Astronomy, University of New Mexico. Albuquerque 87106

References and Notes

- 1. G. H. Pettengill and R. B. Dyce. Nature 206.
- 1240 (1965).
 I. I. Shapiro, Science 157, 423 (1967) Goldreich and S. J. Peale, Nature 209, 1078 3. P
- (1966). -, *ibid.*, p. 1117.
- *Astronom. J.* 71, 425 (1966).
 Sidereal periods are measured with respect to the fixed stars, whereas synodic periods are measured from a rotating reference system, usually the earth.

2 July 1969