#### TETRODE THYRATRON

Tetrode, mercury vapour thyratron with negative control characteristic. Primarily designed for motor control and other industrial applications.

# XGQ2-6400

(MT105)

This data sheet should be read in conjunction with DEFINITIONS AND OPERATIONAL RECOMMENDATIONS—THYRATRONS, which precede this section of the handbook.

### LIMITING VALUES (absolute ratings, not design centre)

It is important that these limits are never exceeded and such variations as mains fluctuations, component tolerances and switching surges must be taken into consideration in arriving at actual valve operating conditions.

Max. peak anode voltage Inverse Forward	2.5 2.5	kV kV
Max. cathode current Peak (25 c/s and above) Peak (below 25 c/s) Average (max. averaging time 15s) Surge (fault protestion max. duration 0.1s)	40 12.8 6.4 400	A A A
Max. negative control-grid voltage Before conduction During conduction	, 1.0 10	kV V
Max. average positive control-grid current for anode voltage more positive than -10V (averaging time 15s)	250	mA
Max. peak positive control-grid current during the time that the anode voltage is more positive than -10%		A
Max. control-grid resistor (Recommended min. control-grid resistor 10kΩ	100	kΩ
Max. negative shield-grid voltage  Before conduction  During conduction	500 10	<b>v</b>
Max, average positive shield-grid current for anode voltage, more positive than -10V (averaging time 15s)		mA
Max, peak positive shield-grid current during the time that the anode-voltage is more positive than -10V	2.0	A
Min/cathode heating time	10 5 to 5.25 5.0	kΩ V min
Condensed mercury temperature limits	40 to 80	°C

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# CHARACTERISTICS

#### **Electrical**

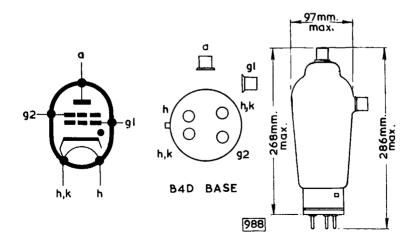
Heater voltage Average heater current at 5.0V Anode to control-grid capacitance Deionisation time (approx.) lonisation time (approx.) Anode voltage drop

5.0	٧
10	Α
2.0	рF
1000	μs
10	μς
16	V

#### Mechanical

Type of cooling Mounting position Max. net weight Convection
Vertical, base down

17 oz
500 g

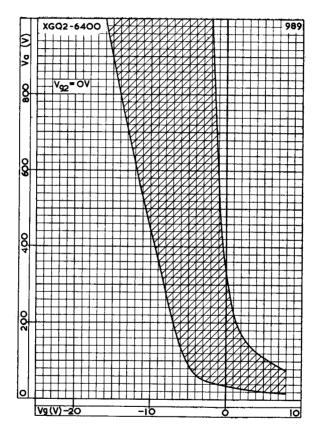


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CONTROL CHARACTERISTIC