High-Mu Triode

CERAMIC-METAL PENCIL TYPE
FAST WARM-UP TIME STURDY COAXIAL-ELECTRODE STRUCTURE

For Use as a Low-Noise Amplifier Tube in Receiver Applications up to 1000 Mc

GENERAL DATA

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Electrical:
Heater, for Unipotential Cathode: Voltage (AC or DC)
Cathode Warm-Up Time to reach 90% of operating plate current: For conditions: heater volts = 6.3, dc plate supply volts = 80, dc grid volts = 0, cathode resistor (ohms) = 0. and load resistor (ohms) = 10 10 max. sec
Direct Interelectrode Capacitances:▲
Grid to plate 2.4 $\mu\mu$ f
Grid to cathode and heater 4.4 $\mu\mu$ f
Plate to cathode and heater 0.03 max. $\mu\mu$ f
Heater to cathode
Cathode to plate 0.03 max. μμf Cathode to grid and heater 7 μμf
Cathode to grid and heater
Trace to grid and heater $\mu\mu$
Characteristics, Class A Amplifier:
Plate Supply Voltage 125 volts
Cathode Resistor 50 ohms Amplification Factor 80
Plate Resistance (Approx.)
Transconductance
Plate Current
Mechanical:
Operating Position Any Dimensions See Dimensional Outline
Weight (Approx.)
Sockets:
Heater-terminals connector Amerac No.1018-88* or Grayhill No.22-5, or equivalent
Cavities (Including heater-
terminals connector) J-V-M No.D-7980♠ Series
Terminal Connections (See Dimensional Outline):
P D

H - Heater K - Cathode



G-Grid P-Plate

RF AMPLIFIER — Class Ap (Cathode-Drive Service)

Maximum and Minimum CCS Ratings, Absolute-Maximum Values:

For altitudes up to 100,000 feet and frequencies up to 1000 Mc

DC PLATE-TO-GRID VOLTAGE	250 max. 0 min.	
DC PLATE CURRENT	25 max.	та
PLATE DISSIPATION	2.5 max.	watts
PEAK HEATER-CATHODE VOLTAGE:		
Heater negative with respect to cathode .	50 max.	
Heater positive with respect to cathode .	50 max.	
PLATE-SEAL TEMPERATURE	225 max.	oC

Typical CCS Operation:

At 550 Mc	
DC Plate-to-Grid Supply Voltage 125	volts
Cathode Resistor 50	ohms
Input-Signal Level	dbm
DC Plate Current 12.5	ma
Power Gain for a bandwidth of 5 Mc 16.5	db
Noise Factor 6.5	db

Maximum Circuit Values:

Grid-Circuit Resistance:					
For fixed-bias operation				. Not	recommended
For cathode-bias operation				0.25	max. megohm

- Without external shield.
- Amerac, Inc., Dunham Road, Beverly, Massachusetts.
- * For use with cavities.
- ♦ Grayhill, Inc., 561 Hillgrove Ave., LaGrange, Illinois.
- Continuous Commercial Service.

CHARACTERISTICS RANGE VALUES FOR EQUIPMENT DESIGN

	Note	Min.	Max.	
Heater Current	1	0.205	0.245	amp
Direct Interelectrode				•
Capacitances:				
Grid to plate	-	2.1	2.8	μμf
Grid to cathode	-	3.8	4.8	μμf
Plate to cathode	-	-	0.03	μμf
Transconductance	1,2	10000	16000	μ mhos
Reverse Grid Current	1,3	-	0.3	μ a
Heater-Cathode Leakage Current.	1,4	-	30	μa
Leakage Resistance:				
From grid to plate and cathode				
connected together	1,5	100	-	megohms
From plate to grid and cathode				
connected together	1,6	100	_	megohms
Plate Current (1)	1,2	8.5	16.5	ma

Plate Current (2)	1,7	_	50	μ a
Plate Current (3)	1,8	100	_	μa
Power Gain	1,9	14		db
Noise Factor	1,9	-	7	db
Change in Power Gain	1,9,10	-	-1	db
Change in Noise Factor	1,9,10	-	+0.5	db

- Note 1: With 6.3 volts ac or dc on heater.
- Note 2: With dc plate supply voltage of 125 volts, and cathode resistor of 50 ohms shunted by 1000 μf .
- Note 3: with dc plate voltage of 200 volts, grid resistor of 0.5 megohm, and dc grid voltage of -2 volts.
- Note 4: With 60 volts do between heater and cathode, and heater positive with respect to cathode.
- Note 5: With grid 100 volts negative with respect to plate and cathode tied together.
- Note 6: With plate 300 volts negative with respect to grid and cathode tied together.
- Note 7: With dc plate voltage of 125 volts and dc grid voltage of -5 volts.
- Note 8: With dc plate voltage of 125 volts and dc grid voltage of -2.5 volts.
- Note 9: In a single-tube rf amplifier of the cavity type having a bandwidth of 5 Mc, signal input of -70 dbm, and operating frequency of 550 Mc.
- Note 10: Reduce heater voltage to 5.7 volts. Change in Power-Gain and Noise-Factor values from those obtained with 6.3 volts on heater will not exceed indicated values.

SPECIAL TESTS & PERFORMANCE DATA

Low-Pressure Voltage Breakdown Test:

This test (similar to MIL-E-ID, paragraph 4.9.12.1) is performed on a sample lot of tubes from each production run. Tubes are tested in a chamber at an air pressure equivalent to an altitude of 100,000 feet. Breakdown will not occur when an rms voltage of 300 volts is applied between the plate cylinder and grid flange.

Low-Frequency Vibration Performance:

This test is performed on a sample lot of tubes from each production run under the following conditions: heater voltage of 6.3 volts, dc plate supply voltage of 125 volts, cathode resistor of 50 ohms, and plate load resistor of 10,000 ohms. The tubes are vibrated in a plane perpendicular to the tube axis at 40 cycles per second at an acceleration of 10 g. The rms output voltage across the plate load resistor as a result of vibration of the tube will not exceed 100 millivolts.

Variable-Frequency Vibration Performance:

This test is performed on a sample lot of tubes from each production run. Tube operating conditions are the same as for Low-Frequency Vibration. The tube is vibrated perpendicular to its major axis through a frequency range from 5 to 2000 cps and back. From 5 to 50 cps, the tube shall be vibrated at a constant displacement of 0.0400 \pm 0.0025 inch. From 50 to 2000 cps, the tube shall be vibrated at a constant

acceleration of 10 ± 2 g. Total time to complete a sweep cycle shall be 10 ± 5 minutes. During the test, the tubes will not show an rms output voltage across the plate load resistor in excess of 150 millivolts. Each tube shall be vibrated for 60 seconds at the frequency which gives maximum vibrational noise output. If, at the end of 60 seconds the vibrational noise output is still increasing, the test shall continue until there is no further increase. The rms output voltage across the plate load resistor as a result of the vibration of the tube must not exceed the specified limit at any time during the test.

Shock Test:

This test (similar to MIL-E-ID, paragraph 4.9.20.5) is performed on a sample lot of tubes from each production run. Tubes are held rigid and are subjected in three different positions to an impact acceleration of $500~\rm g$, $5~\rm blows$ in each position.

At the end of this test, tubes will not show permanent or temporary shorts or open circuits, and are required to meet the following limits:

- Heater-Cathode Leakage Current. 60 max. με
 For conditions shown under Characteristics Range Values,
 Notes 1,4.
- Low-Frequency Vibration Output. 200 max. mv For conditions shown above under Low-Frequency Vibration Performance.
- Change in transconductance. 10 max. %
 From initial value for conditions shown under Characteristics Range Values, Notes 1,2.
- Change in Reverse Grid Current. I max. μ a

 From initial value for conditions shown under Characteristics Range Values. Notes 1.9.

Fatique Vibration Test:

This test (similar to MIL-E-ID, paragraph 4.9.20.61 is performed on a sample lot of tubes from each production run. Tubes are rigidly mounted and subjected to 2.5 g vibrational acceleration in two positions (XI, YI) for 32 hours each. At the end of this test, tubes will meet the limits specified for the $Shack\ Test$.

Shorts and Continuity Test:

This test is performed on all tubes from each production run. In this test, a tube is considered inoperative if it shows a permanent or temporary short or open circuit, an air leak, or reverse grid current in excess of I microampere for the conditions shown under Characteristics Range Values, Notes 1.4.



Heater-Cycling Life Performance:

This test is performed on a sample lot of tubes from each production run. With 6.3 volts on heater and no voltage on plate or grid, the heater is cycled three minutes on and three minutes off for at least 2000 cycles. At the end of this test, tubes will not show temporary or permanent shorts or opens, and are required to meet the following limits:

Grid-to-Cathode Leakage Resistance. . . 50 min. megohms
For conditions shown under Characteristics Range Values,
Notes 1.5.

Heater-to-Cathode Leakage Current . . . 60 max. μa
For conditions shown under Characteristics Range Values,
Notes 1.4.

I-Hour Stability Life Performance:

This test is performed on a sample lot of tubes from each production run to insure that the tubes have been properly stabilized. Tubes are operated under the following conditions: heater voltage of 6.3 volts, plate supply voltage of 215 volts, and cathode resistor of 150 ohms. At the end of I hour, the change in transconductance value for each tube, referred to its initial transconductance reading, will not exceed 15 per cent of the initial value for conditions shown under Characteristics Range Values. Notes 1.2.

44-Hour Grid-Emission Life Performance:

This test is performed on a sample lot of tubes from each production run to insure excellent overall performance and to guard against epidemic failures of tubes to meet this test requirement. Tubes are operated under the following conditions: heater voltage of 7.5 volts, dc plate voltage of 215 volts, grid voltage of -2 volts, and grid resistor of 0.5 megohm. At the end of 44 hours, the reverse grid current will not exceed 2 microamperes when grid resistor is shorted and grid voltage is increased to -5 volts, other conditions remaining unchanged from the above values.

100-Hour Survival Life Performance:

This test is performed on a sample lot of tubes from each production run to insure a low percentage of early in-operatives. Life-test conditions are the same as those specified for *1-Hour Stability Life Performance* except that all voltages are cycled at the rate of 110 minutes on and 10 minutes off. At the end of 100 hours, the tubes will meet the following limits:

Transconductance. 8000 min. μmhos for conditions shown under Characteristics Range Values, Notes 1.2.

Plate Current (2) 50 max. μa

For conditions shown under Characteristics Range Values,
Notes 1,7.

500-Hour Average Life Performance:

For conditions shown under Characteristics Range Values, Notes 1, 2.

Insulation Resistance:

Grid to plate and cathode 60 min. megohms Plate to grid and cathode 60 min. megohms

For conditions shown under Characteristics Range Values, Notes 1,5, and 1,6, respectively.

Change in Noise Factor. I max. db
From initial value for conditions shown under Characteristics Range Values. Notes 1.0.

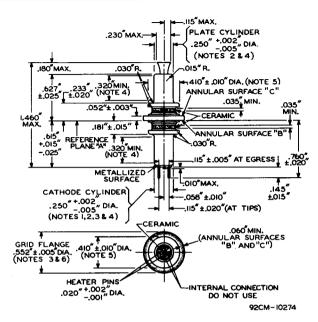
Change in Power Gain. -2 max. db
From initial value for conditions shown under Characteristics Range Values, Notes 1.0.

OPERATING CONSIDERATIONS

Connections to the cathode cylinder, grid flange, and plate cylinder should be made by flexible spring contacts. The connectors should make firm, large-surface contact, yet must be sufficiently flexible to insure that no part of the tube is subjected to excessive strain.

The cathode should preferably be connected to one side of the heater. When, in some circuit designs, the heater is not connected directly to the cathode, precautions must be taken to hold the peak heater-cathode voltage to the maximum-rated values shown in the tabulated data.





REFERENCE PLANE "A" IS DEFINED AS THAT PLANE AGAINST WHICH ANNULAR SURFACE "B" OF THE GRID FLANGE ABUTS.

ANNULAR SURFACE "B" IS ON THE SIDE OF THE GRID FLANGE TOWARD THE CATHODE CYLINDER.

ANNULAR SURFACE "C" IS ON THE SIDE OF THE GRID FLANGE TOWARD THE PLATE CYLINDER.

NOTE I: WITH ANNULAR SURFACE "B" RESTING ON REFERENCE PLANE "A", THE AXIS OF THE CATHODE CYLINDER WILL BE WITHIN 2° OF A LINE PERPENDICULAR TO REFERENCE PLANE "A".

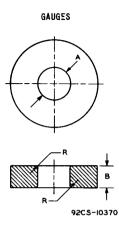
NOTE 2: THE AXES OF THE PLATE CYLINDER AND CATHODE CYLINDER WILL COINCIDE WITHIN 0.010"

NOTE 3: THE AXES OF THE CATHODE CYLINDER AND GRID FLANGE WILL COINCIDE WITHIN 0.005".

NOTE 4: THE DIAMETER ALONG THE 0.320" MINIMUM LENGTH IS MEASURED WITH "GO" AND "NO-GO" RING GAUGES $G_1 \sim 1$ AND G_1-2 , RESPECTIVELY.

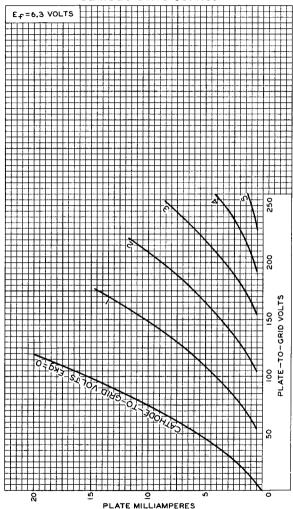
NOTE 5: THIS DIAMETER IS MEASURED WITH "GO" AND "NO-GO" GAUGES $\mathsf{G_2}{ ext{--}1}$ AND $\mathsf{G_2}{ ext{--}2}$, RESPECTIVELY.

NOTE 6: THIS DIAMETER IS MEASURED WITH "GO" AND "NO-GO" GAUGES G_3-I AND G_3-2 , RESPECTIVELY.



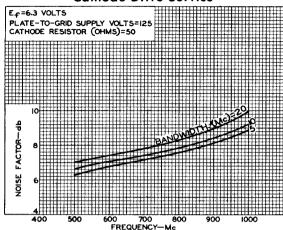
Gauge	Tuna	Dimension								
dauge	Туре	Diamo	eter A	Thick	ness B	Radius R				
G ₁ -I	GO	0.25200"	+0.00000" -0.00007"	0.320"	+0.001"	0.003"	MAX.			
G ₁ -2	NO-GO	0.24500"	+0.00007" -0.00000"		-	-				
G ₂ -I	GO	0.42000"	+0.00000"		_	-				
G ₂ -2	NO-GO	0.40000"	+0.00007" -0.00000"	-		-				
G3-1	GO	0.55700"	+0.00000" -0.00007"		_					
G3-2	NO-GO	0.54700"	+0.00007" -0.00000"	l	-	-				

AVERAGE PLATE CHARACTERISTICS Cathode-Drive Service



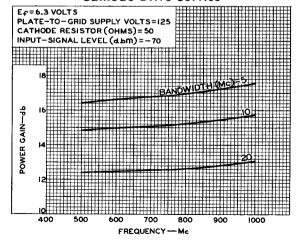
92CM-10458

NOISE-FACTOR CHARACTERISTICS Cathode-Drive Service



92CS-10455

POWER-GAIN CHARACTERISTICS Cathode-Drive Service



92CS-10456

