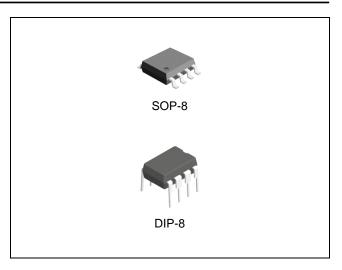
#### **FEATURES**

- Halts and restarts an out-of-control μ-processor
- Holds µ-processor in check during power transients
- Automatically restarts µ-processor after power failure
- · Monitors push-button for external override
- Accurate 5% or 10% μ-processor power supply monitoring
- Eliminates the need for discrete components

## **APPLICATIONS**

- μ-processor Power Monitoring
- · Intelligent Instruments
- · Computers and Controllers
- · Automotive Systems



#### ORDERING INFORMATION

Device	Package
DS1232D	SOP-8
DS1232N	DIP-8

### **DESCRIPTION**

The DS1232 Micro-Monitor monitors three vital conditions for a microprocessor: power supply, software execution, and external override. First, a precision temperature compensated reference and comparator circuit monitors the status of VCC. When an out–of–tolerance condition occurs, an internal power fail signal is generated which forces reset to the active state. When VCC returns to an in–tolerance condition, the reset signals are kept in the active state for a minimum of 250ms to allow the power supply and processor to stabilize. The second function the DS1232 performs is pushbutton reset control. The DS1232 debounces the pushbutton input and guarantees an active reset pulse width of 250ms minimum. The third function is a watchdog timer. The DS1232 has an internal timer that forces the reset signals to the active state if the strobe input is not driven low prior to time–out. The watchdog timer function can be set to operate on time–out settings of approximately 150ms, 600ms, and 1.2 seconds.

## **ABSOLUTE MAXIMUM RATINGS**

CHARACTERISTIC	SYMBOL	MIN.	MAX.	UNIT
Supply Voltage V <sub>CC</sub>		-0.5	7.0	٧
Input / Output Voltage	PBRST , TD, TOL, RST , RST, ST	-0.5	V <sub>CC</sub> +0.5	V
Operating Ambient Temperature Range	T <sub>A</sub>	-10	70	°C
Storage Temperature	T <sub>STG</sub>	-55	125	°C

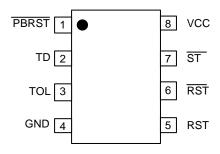
# **RECOMMENDED OPERATIONG CONDITIONS**

CHARACTERISTIC	SYMBOL	MIN.	MAX.	UNIT
Supply Voltage	Vcc	4.5	5.5	V
ST and PBRST Input High Level	V <sub>IH</sub>	2.0	V <sub>CC</sub> +0.3	V
ST and PBRST Input Low Level	V <sub>IL</sub>	-0.3	0.8	V

# **ORDERING INFORMATION**

Package	Order No.	Description	Supplied As	Status
SOP-8	DS1232D	Micro-Monitor	Reel	Active
DIP-8	DS1232N	Micro-Monitor	Tube	Active

# **PIN CONFIGURATION**



SOP-8 / DIP-8

# **PIN DESCRIPTION**

Pin	No.	Pin Name	Pin Function	
SOP-8	DIP-8	Pin Name	Pin Function	
1	1	PBRST	Pushbutton Reset Input	
2	2	TD	Time Delay Set	
3	3	TOL	Selects 5% or 10% V <sub>CC</sub> Detect	
4	4	GND	Ground	
5	5	RST	Reset Output (Active High)	
6	6	RST	Reset Output (Active Low, Open Drain)	
7	7	ST	Strobe Input	
8	8	Vcc	5V Supply Power	

## **ELECTRICAL CHARACTERISTICS**

Specifications with standard type face are for  $T_A = 25$  °C,  $V_{CC} = 5$ V, and those with **boldface type** are for **-10** °C **to 70** °C unless otherwise noted. (Note 1)

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
DC ELECTRICAL CHARACTERISTICS			•			
Input Leakage	I <sub>IL</sub>	(Note 3)	-1.0		1.0	μA
Output Current @ 2.4V	I <sub>OH</sub>	(Note 5)	-8	-10		mA
Output Current @ 0.4V	I <sub>OL</sub>		8	10		mA
Low Level @ RST	V <sub>OL</sub>	(Note 1)			0.4	V
Output Voltage @ -500μA	V <sub>OH</sub>	(Note 1, 7)	V <sub>CC</sub> -0.5	V <sub>CC</sub> -0.1		V
Operating Current	I <sub>CC</sub>	(Note 2)		0.5	2.0	mA
V <sub>CC</sub> Trip Point	V <sub>CCTP1</sub>	TOL=GND (Note 1)	4.50	4.62	4.74	V
V <sub>CC</sub> Trip Point	V <sub>CCTP2</sub>	TOL=V <sub>CC</sub> (Note 1)	4.25	4.37	4.49	V
AC ELECTRICAL CHARACTERISTICS			•			•
PBRST = V <sub>IL</sub>	t <sub>PB</sub>		20			ms
RESET Active Time	t <sub>RST</sub>		250	610	1000	ms
ST Pulse Width	t <sub>ST</sub>	(Note 6, 8)	20			ns
V <sub>CC</sub> Fail Detect to RST and RST	t <sub>RPD</sub>			100	175	μs
V <sub>CC</sub> Slew Rate 4.75V to 4.25V	t <sub>F</sub>		300			μs
V <sub>CC</sub> Detect to RST and RST Transition	t <sub>RPU</sub>	(Note 4)	250	610	1000	ms
V <sub>CC</sub> Slew Rate 4.25V to 4.75V	t <sub>R</sub>		0	5		μs
PBRST Stable Low to RST and RST	t <sub>PDLY</sub>				20	ms
CAPACITANCE			•			•
Input Capacitance	C <sub>IN</sub>				5	pF
Output Capacitance	Соит				7	pF

- Note 1. All voltages referenced to ground.
- Note 2. Measured with outputs open.
- Note 3.  $\overline{PBRST}$  is internally pulled up to  $V_{CC}$  with an internal impedance of 10K typical.
- Note 4.  $t_R = 5 \mu s$ .
- Note 5.  $\overline{RST}$  is an open drain output.
- Note 6. Must not exceed  $t_{TD}$  minimum. See Table 1.
- Note 7. RST remains within 0.5V of VCC on power–down until VCC drops below 2.0V.  $\overline{\text{RST}}$  remains within 0.5V of GND on power–down until VCC drops below 2.0V.
- Note 8. Watchdog cannot be disabled. It must be strobed to avoid resets.

### TYPICAL APPLICATION INFORMATION

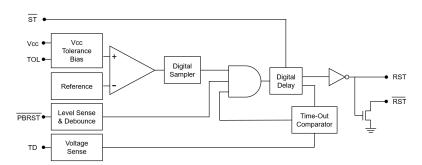


Fig.1. Block Diagram

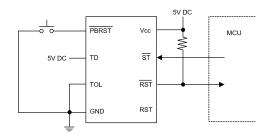


Fig 2. Typical Application

### **Power Monitor**

The DS1232 detects out-of-tolerance power supply conditions and warns a processor-based system of impending power failure. When  $V_{CC}$  falls below a preset level as defined by TOL (Pin 3), the  $V_{CC}$  comparator outputs the signals RST (Pin 5) and  $\overline{RST}$  (Pin 6). When TOL is connected to ground, the RST and  $\overline{RST}$  signals become active as  $V_{CC}$  falls below 4.75 volts. When TOL is connected to  $V_{CC}$ , the RST and  $\overline{RST}$  signals become active as  $V_{CC}$  falls below 4.5 volts. The RST and  $\overline{RST}$  are excellent control signals for a microprocessor, as processing is stopped at the last possible moments of valid  $V_{CC}$ . On power-up, RST and  $\overline{RST}$  are kept active for a minimum of 250 ms to allow the power supply and processor to stabilize.

#### **Pushbutton Reset**

The DS1232 provides an input pin for direct connection to a pushbutton. The pushbutton reset input requires an active low signal. Internally, this input is debounced and timed such that RST and  $\overline{RST}$  signals of at least 250 ms minimum are generated. The 250 ms delay starts as the pushbutton reset input is released from low level.

### **Watchdog Timer**

A watchdog timer function forces RST and  $\overline{RST}$  signals to the active state when the  $\overline{ST}$  input is not stimulated for a predetermined time period. The time period is set by the TD input to be typically 150 ms with TD connected to ground, 600 ms with TD left unconnected, and 1.2 seconds with TD connected to  $V_{CC}$ . The watchdog timer starts timing out from the set time period as soon as RST and  $\overline{RST}$  are inactive. If a high-to-low transition occurs on the  $\overline{ST}$  input pin prior to timeout, the watchdog timer is reset and begins to timeout again. If the watchdog timer is allowed to timeout, then the RST and  $\overline{RST}$  signals are driven to the active state for 250 ms minimum. The  $\overline{ST}$  input can be derived from microprocessor address signals, data signals, and/or control

signals. When the microprocessor is functioning normally, these signals would, as a matter of routine, cause the watchdog to be reset prior to timeout. To guarantee that the watchdog timer does not timeout, a high-to-low transition must occur at or less than the minimum shown in Table 1.

## **Timing Diagrams**

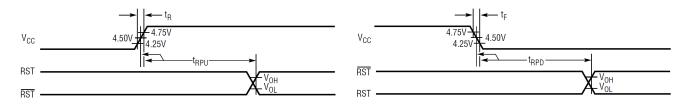


Fig. 3. Power Up Timing Diagram

Fig. 4. Power Down Timing Diagram

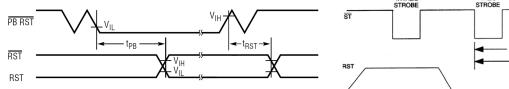


Fig. 5. Pushbutton Reset Timing Diagram

RST MIN. MAX.

INDETERMINATE STROBE

Fig. 6. Strobe Input Timing Diagram

Table 1. Watchdog Timeouts

TD Pin	TIME-OUT			
IDFIII	Min.	Тур.	Max.	
GND	62.5ms	150ms	250ms	
Float	250ms	600ms	1000ms	
Vcc	500ms	1200ms	2000ms	

# **REVISION NOTICE**

The description in this datasheet is subject to change without any notice to describe its electrical characteristics properly.