

Datasheet

APM32F407xExG

Arm® Cortex® -M4 core-based 32-bit MCU

Version: V1.0

1 Product characteristics

■ Core

- 32-bit Arm® Cortex®-M4 core with FPU
- Up to 168MHz working frequency

■ Memory and interface

- Flash: The capacity is up to 1MB
- SRAM: System (192KB) + backup (4KB)
- EMMC: Support CF card, SRAM, PSRAM, SDRAM, NOR and NAND memories

■ Clock

- HSECLK: 4~26MHz external crystal/ceramic oscillator supported
- LSECLK: 32.768KHz crystal/ceramic oscillator supported
- HSICLK: 16MHz RC oscillator calibrated by factory
- LSICLK: 28KHz RC oscillator supported
- PLL1: Phase locked loop; output frequency is configured by four parameters
- PLL2: Phase locked loop specially used to provide clock signals to I2S; output frequency is configured by three parameters

■ Reset and power management

- V_{DD} range: 1.8~3.6V
- V_{DDA} range: 1.8~3.6V
- V_{BAT} range of backup domain power supply: 1.65V~3.6V
- Power-on/power-down/brown-out reset (POR/PDR/BOR) supported
- Programmable power supply voltage detector (PVD) supported

■ Low-power mode

- Sleep, stop and standby modes supported

■ DMA

- Two DMA; each DMA has 8 data streams, 16 in total

■ Debugging interface

- JTAG
- SWD

■ I/O

- Up to 140 I/O
- All I/O can be mapped to external interrupt vector
- Up to 138 FT input I/O

■ Communication peripherals

- 4 USART, 2 UART, supporting ISO7816, LIN and IrDA functions
- 3 I2C, supporting SMBus/PMBus
- 3 SPI (2 reusable I2S)
- 2 CAN
- 3 USB_OTG controllers
- 1 SDIO interface

■ Analog peripherals

- 3 12-bit ADCs
- 2 12-bit DACs

■ Timer

- 2 16-bit advanced timers TMR1/8 that can provide 7-channel PWM output, support dead zone generation and braking input functions
- 2 32-bit general-purpose timers TMR2/5, each with up to 4 independent channels to support input capture, output comparison, PWM, pulse count and other functions

■ RTC

- Support calendar function
- Alarm and regular wake-up from stop/standby mode

■ CRC computing unit

■ 96-bit unique device ID

- 8 16-bit general-purpose timers TMR3/4/9/10/11/12/13/14, each with up to 2 independent channels to support input capture, output comparison, PWM, pulse count and other functions
- 2 16-bit basic timers TMR6/7
- 2 watchdog timers: one independent watchdog IWDT and one window watchdog WWDT
- 1 24-bit autodecrement SysTick Timer

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2 Product information

See the following table for APM32F407xExG product functions and peripheral configuration.

Table 1 Functions and Peripherals of APM32F407xExG Series Chips

Product		APM32F407							
Model		RET6	RGT6	VET6	VGT6	ZET6	ZGT6	IET6	IGT6
Package		LQFP64		LQFP100		LQFP144		LQFP176	
Core and maximum working frequency		Arm® 32-bit Cortex®-M4@168MHz							
Working voltage		1.8~3.6V							
Flash(KB)		512	1024	512	1024	512	1024	512	1024
System + backup SRAM(KB)		192+4							
SMC		0		1					
DMC		1							
GPIOs		51		82		114		140	
Communication interface	USART/UART	4/2							
	SPI/I2S	3/2							
	I2C	3							
	OTG_FS	1							
	OTG_HS	2							
	CAN	2							
	Ethernet	0		1					
	SDIO	1							
Timer	16-bit advanced	2							
	32-bit general	2							
	16-bit general	8							
	16-bit basic	2							
	System tick timer	1							
	Watchdog	2							
Real-time clock		1							
DCI		0		1					
RNG		1							
12-bit ADC	Unit	3							
	External channel	13				21			
	Internal channel	3							
12-bit DAC	Unit	2							
	Channel	2							
Operating temperature		Ambient temperature: -40°C to 85°C Junction temperature: -40°C to 105°C							

3 Pin information

3.1 Pin distribution

Figure 1 Distribution Diagram of APM32F407xExG Series LQFP176 Pins

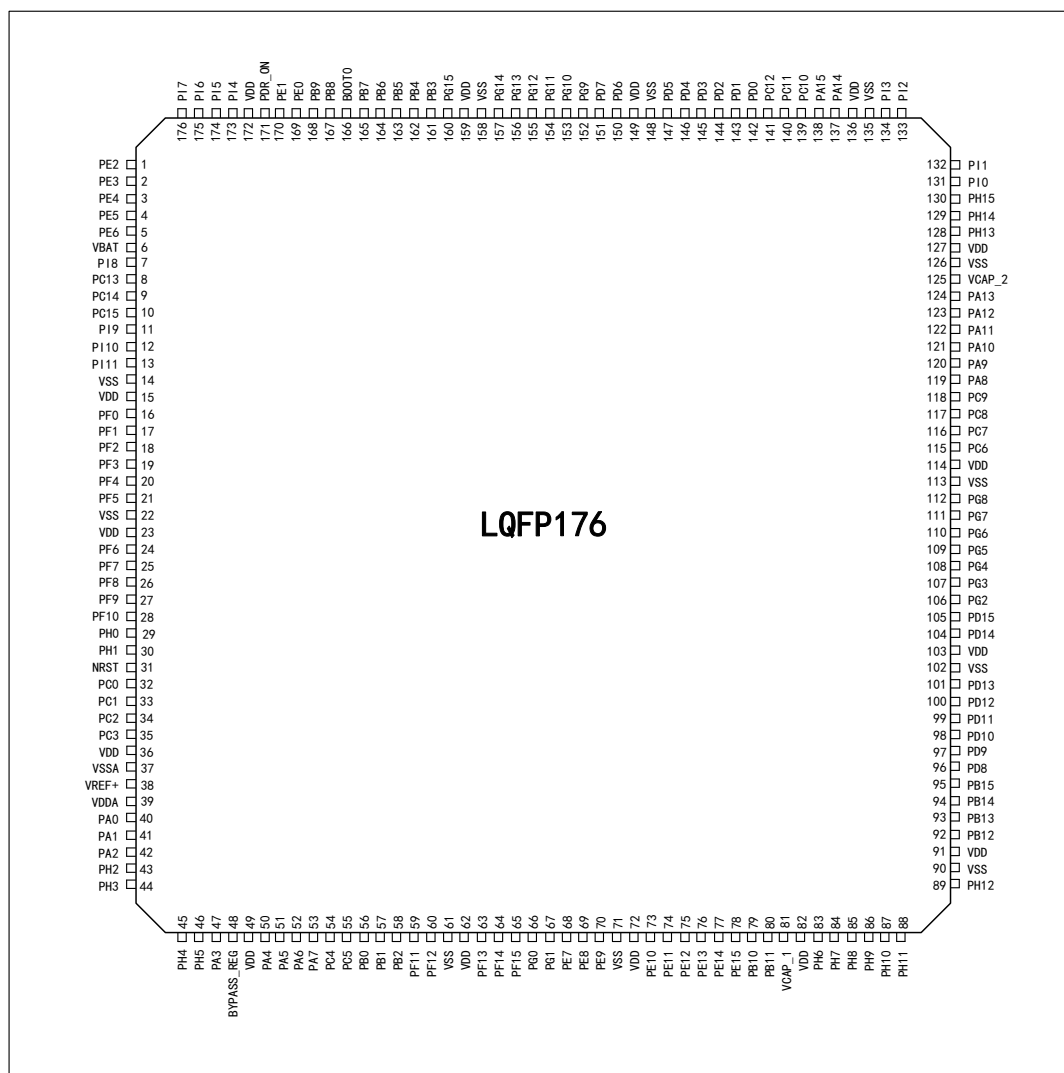


Figure 2 Distribution Diagram of APM32F407xExG Series LQFP144 Pins

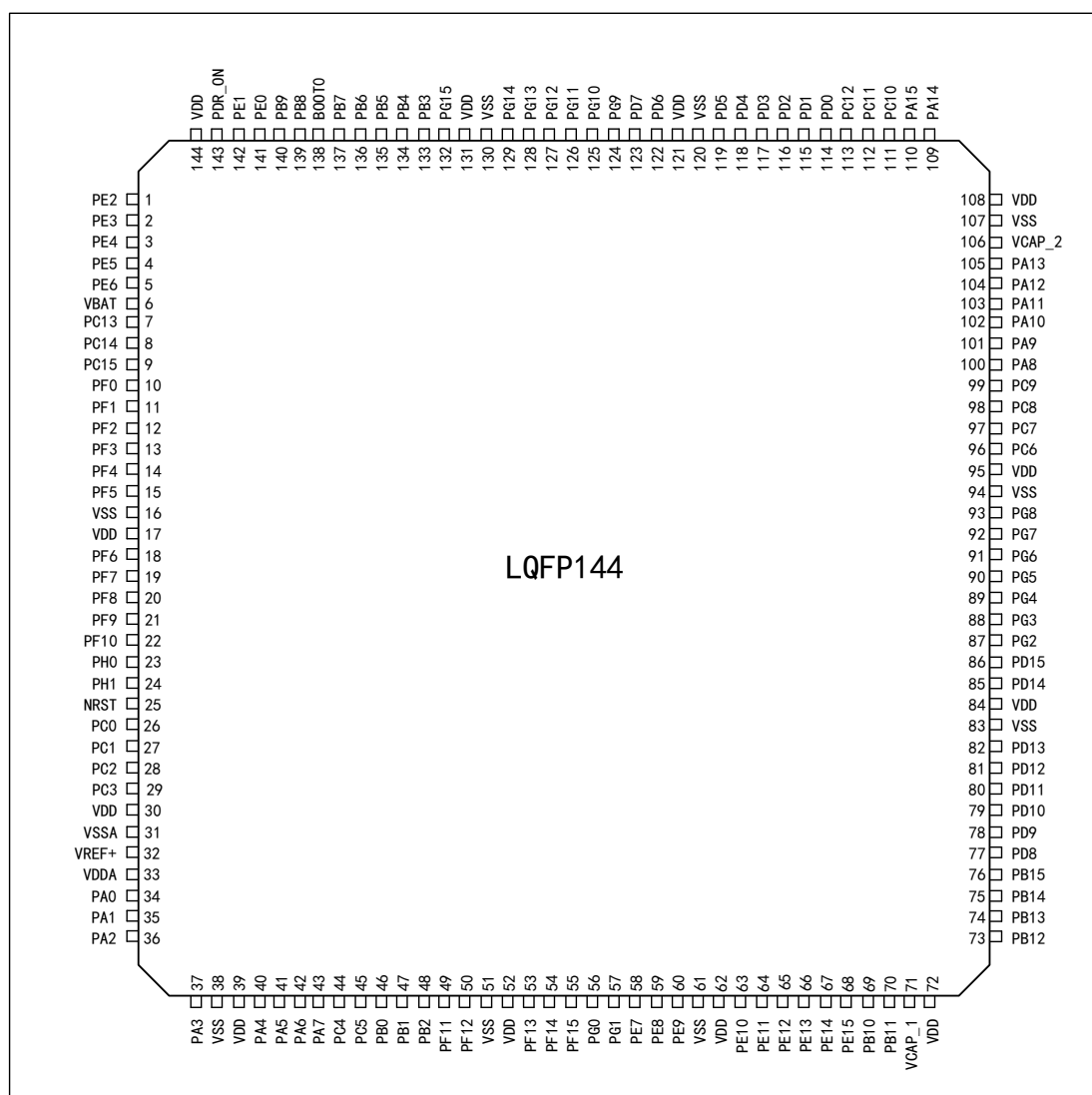


Figure 3 Distribution Diagram of APM32F407xExG Series LQFP100 Pins

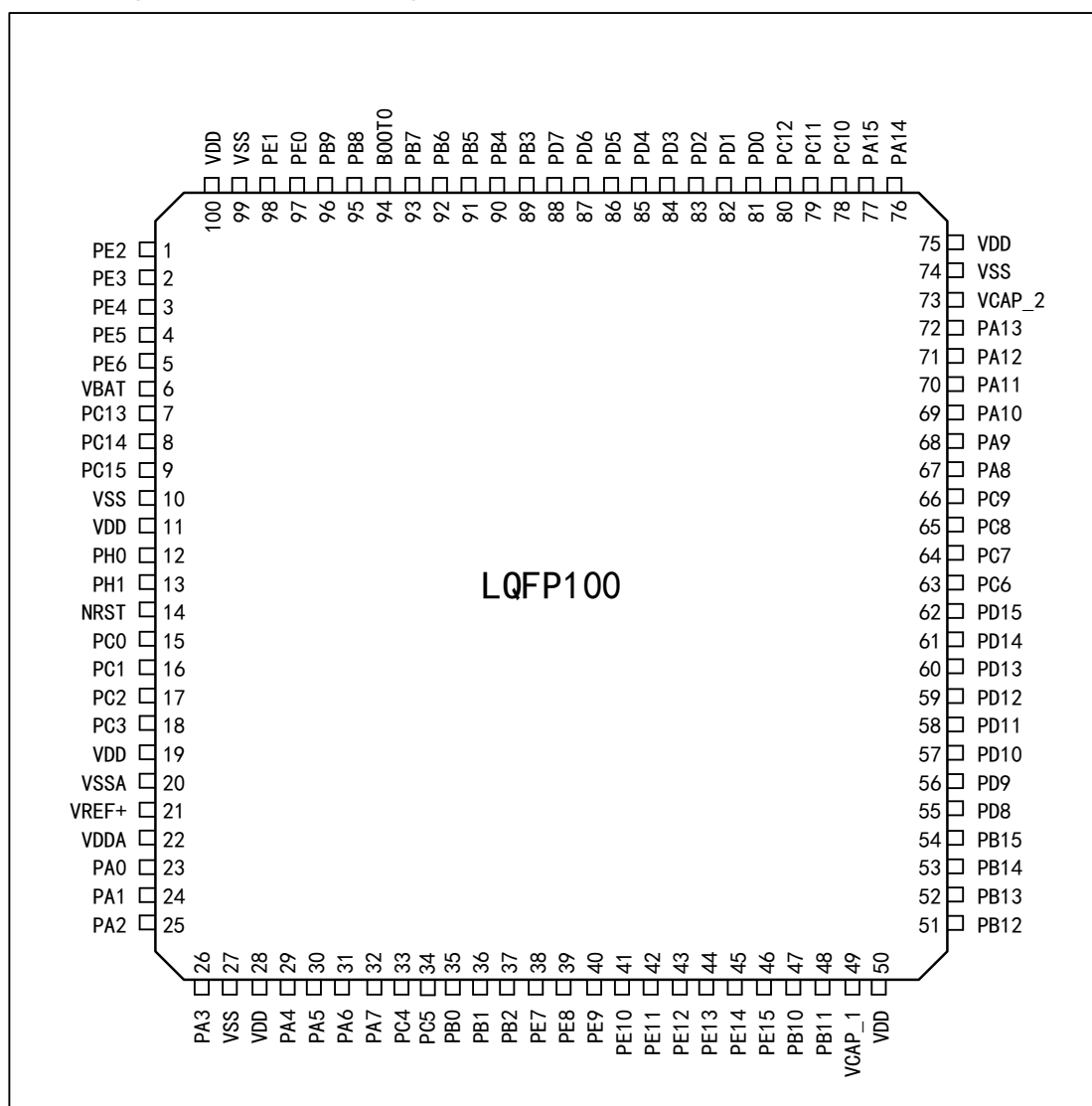
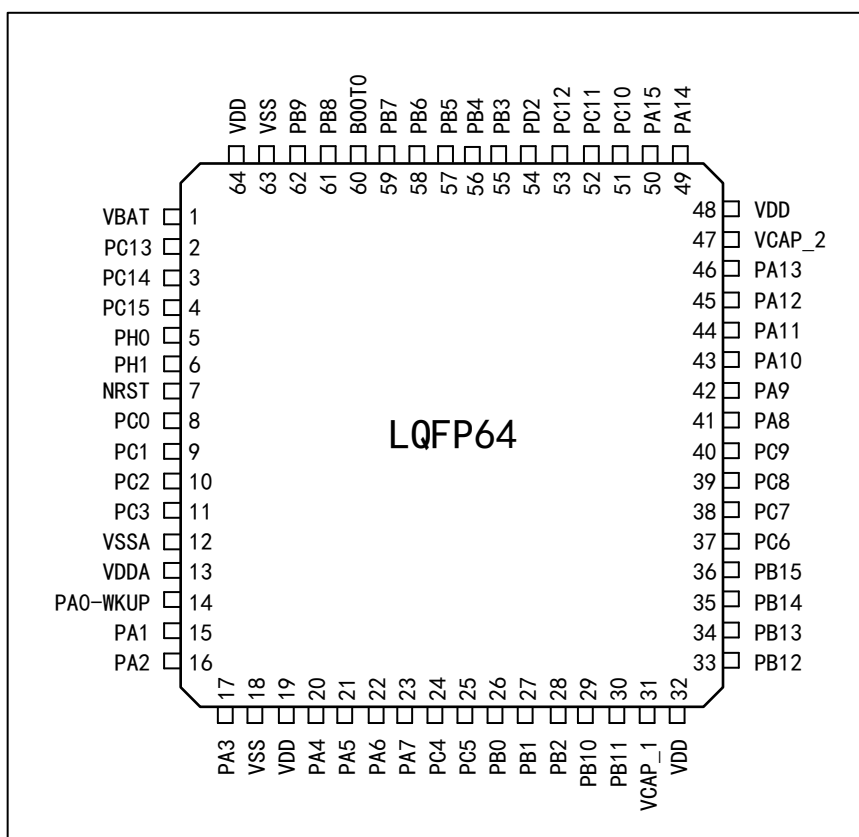


Figure 4 Distribution Diagram of APM32F407xExG Series LQFP64 Pins



3.2 Pin function description

Table 2 Legends/Abbreviations Used in Output Pin Table

Name		Abbreviation	Definition
Pin name		Unless otherwise specified in parentheses below the pin name, the pin functions during and after reset are the same as the actual pin name	
Pin type		P	Power pin
		I	Only input pin
		I/O	I/O pin
I/O structure		5T	FT I/O
		STDA	3.3V standard I/O, directly connected to ADC
		STD	3.3V standard I/O
		B	Dedicated Boot0 pin
		RST	Bidirectional reset pin with built-in pull-up resistor
Notes		Unless otherwise specified in the notes, all I/O is set as floating input during and after reset	
Pin function	Default multiplexing function	Function directly selected/enabled through peripheral register	

Name		Abbreviation	Definition
	Redefining function		Select this function through AFIO remapping register

Table 3 Description of APM32F407xExG by Pin Number

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
PE2	I/O	5T	TRACECK, SMC_A23, DMC_A23, ETH_MII_TXD3, EVENTOUT	-	-	1	1	1
PE3	I/O	5T	TRACED0, SMC_A19, DMC_A19, EVENTOUT	-	-	2	2	2
PE4	I/O	5T	TRACED1, SMC_A20, DMC_A20, DCI_D4, EVENTOUT	-	-	3	3	3
PE5	I/O	5T	TRACED2, SMC_A21, DMC_A21, TMR9_CH1, DCI_D6, EVENTOUT	-	-	4	4	4
PE6	I/O	5T	TRACED3, SMC_A22, DMC_A22, TMR9_CH2, DCI_D7, EVENTOUT	-	-	5	5	5
V _{BAT}	P	-	-	-	1	6	6	6
PI8	I/O	5T	EVENTOUT	RTC_TAMP1, RTC_TAMP2, RTC_TS	-	-	-	7
PC13	I/O	5T	EVENTOUT	RTC_OUT, RTC_TAMP1, RTC_TS	2	7	7	8
PC14- OSC32_IN (PC14)	I/O	5T	EVENTOUT	OSC32_IN	3	8	8	9
PC15- OSC32_OUT	I/O	5T	EVENTOUT	OSC32_OUT	4	9	9	10

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
(PC15)								
PI9	I/O	5T	CAN1_RX, EVENTOUT	-	-	-	-	11
PI10	I/O	5T	ETH_MII_RX_ER, EVENTOUT	-	-	-	-	12
PI11	I/O	5T	OTG_HS_ULPI_DIR, EVENTOUT	-	-	-	-	13
V _{SS}	P	-	-	-	-	-	-	14
V _{DD}	P	-	-	-	-	-	-	15
PF0	I/O	5T	SMC_A0, DMC_A2, I2C2_SDA, EVENTOUT	-	-	-	10	16
PF1	I/O	5T	SMC_A1, DMC_A1, I2C2_SCL, EVENTOUT	-	-	-	11	17
PF2	I/O	5T	SMC_A2, DMC_A2, I2C2_SMBAL, EVENTOUT	-	-	-	12	18
PF3	I/O	5T	SMC_A3, DMC_A3, EVENTOUT	ADC3_IN9	-	-	13	19
PF4	I/O	5T	SMC_A4, DMC_A4, EVENTOUT	ADC3_IN14	-	-	14	20
PF5	I/O	5T	SMC_A5, DMC_A5, EVENTOUT	ADC3_IN15	-	-	15	21
V _{SS}	P	-	-	-	-	10	16	22
V _{DD}	P	-	-	-	-	11	17	23
PF6	I/O	5T	TMR10_CH1, SMC_NIORD, EVENTOUT	ADC3_IN4	-	-	18	24
PF7	I/O	5T	TMR11_CH1, SMC_NREG, EVENTOUT	ADC3_IN5	-	-	19	25

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
PF8	I/O	5T	TMR13_CH1, SMC_NIOWR, EVENTOUT	ADC3_IN6	-	-	20	26
PF9	I/O	5T	TMR14_CH1, SMC_CD, EVENTOUT	ADC3_IN7	-	-	21	27
PF10	I/O	5T	SMC_INTR, EVENTOUT	ADC3_IN8	-	-	22	28
PH0-OSC_IN (PH0)	I/O	5T	EVENTOUT	OSC_IN	5	12	23	29
PH1-OSC_OUT (PH1)	I/O	5T	EVENTOUT	OSC_OUT	6	13	24	30
NRST	I/O	RST	-	-	7	14	25	31
PC0	I/O	5T	OTG_HS_ULPI_STP, EVENTOUT, DMC_WE	ADC123_IN10	8	15	26	32
PC1	I/O	5T	ETH_MDC, EVENTOUT, DMC_RAS	ADC123_IN11	9	16	27	33
PC2	I/O	5T	SPI2_MISO, OTG_HS_ULPI_DIR, ETH_MII_TXD2, I2S2ext_SD, EVENTOUT, DMC_CS	ADC123_IN12	10	17	28	34
PC3	I/O	5T	SPI2_MOSI, I2S2_SD, OTG_HS_ULPI_NXT, ETH_MII_TX_CLK, EVENTOUT, DMC_CKE	ADC123_IN13	11	18	29	35
V _{DD}	P	-	-	-	-	19	30	36
V _{SSA}	P	-	-	-	12	20	31	37
V _{REF+}	P	-	-	-	-	21	32	38
V _{DDA}	P	-	-	-	13	22	33	39
PA0-WKUP (PA0)	I/O	5T	USART2_CTS, UART4_TX, ETH_MII_CRS, TMR2_CH1_ETR,	WKUP, ADC123_IN0	14	23	34	40

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
			TMR5_CH1, TMR8_ETR, EVENTOUT					
PA1	I/O	5T	USART2_RTS, UART4_RX, ETH_RMII_REF_CLK , ETH_MII_RX_CLK, TMR5_CH2, TMR2_CH2, EVENTOUT	ADC123_IN1	15	24	35	41
PA2	I/O	5T	USART2_TX, TMR5_CH3, TMR9_CH1, TMR2_CH3, ETH_MDIO, EVENTOUT	ADC123_IN2	16	25	36	42
PH2	I/O	5T	ETH_MII_CRD, EVENTOUT	-	-	-	-	43
PH3	I/O	5T	ETH_MII_COL, EVENTOUT	-	-	-	-	44
PH4	I/O	5T	I2C2_SCL, OTG_HS_ULPI_NXT, EVENTOUT	-	-	-	-	45
PH5	I/O	5T	I2C2_SDA, EVENTOUT	-	-	-	-	46
PA3	I/O	5T	USART2_RX, TMR5_CH4, TMR9_CH2, TMR2_CH4, OTG_HS_ULPI_D0, ETH_MII_COL, EVENTOUT	ADC123_IN3	17	26	37	47
V _{SS}	P	-	-	-	18	27	38	-
BYPASS_REG	I	5T	-	-	-	-	-	48
V _{DD}	P	-	-	-	19	28	39	49
PA4	I/O	STDA	SPI1_NSS, SPI3_NSS, USART2_CK,	DAC_OUT1, ADC12_IN4	20	29	40	50

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
			DCI_HSYNC, OTG_HS_SOF, I2S3_WS, EVENTOUT					
PA5	I/O	STDA	SPI1_SCK, OTG_HS_ULPI_CK, TMR2_CH1_ETR, TMR8_CH1N, EVENTOUT	DAC_OUT2, ADC12_IN5	21	30	41	51
PA6	I/O	5T	SPI1_MISO, TMR8_BKIN, TMR13_CH1, DCI_PIXCLK, TMR3_CH1, TMR1_BKIN, EVENTOUT	ADC12_IN6	22	31	42	52
PA7	I/O	5T	SPI1_MOSI, TMR8_CH1N, TMR14_CH1, TMR3_CH2, ETH_MII_RX_DV, TMR1_CH1N, ETH_RMII_CRS_DV, EVENTOUT	ADC12_IN7	23	32	43	53
PC4	I/O	5T	ETH_RMII_RX_D0, ETH_MII_RX_D0, EVENTOUT	ADC12_IN14	24	33	44	54
PC5	I/O	5T	ETH_RMII_RX_D1, ETH_MII_RX_D1, EVENTOUT	ADC12_IN15	25	34	45	55
PB0	I/O	5T	TMR3_CH3 TMR8_CH2N, OTG_HS_ULPI_D1, ETH_MII_RXD2, TMR1_CH2N, EVENTOUT	ADC12_IN8	26	35	46	56
PB1	I/O	5T	TMR3_CH4 TMR8_CH3N, OTG_HS_ULPI_D2, ETH_MII_RXD3,	ADC12_IN9	27	36	47	57

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
			TMR1_CH3N, EVENTOUT					
PB2-BOOT (PB2)	I/O	5T	EVENTOUT	-	28	37	48	58
PF11	I/O	5T	DCI_D12, EVENTOUT	-	-	-	49	59
PF12	I/O	5T	SMC_A6, DMC_A6, EVENTOUT	-	-	-	50	60
V _{SS}	P	-	-	-	-	-	51	61
V _{DD}	P	-	-	-	-	-	52	62
PF13	I/O	5T	SMC_A7, DMC_A7, EVENTOUT	-	-	-	53	63
PF14	I/O	5T	SMC_A8, DMC_A8, EVENTOUT	-	-	-	54	64
PF15	I/O	5T	SMC_A9, DMC_A9, EVENTOUT	-	-	-	55	65
PG0	I/O	5T	SMC_A10, DMC_A10, EVENTOUT	-	-	-	56	66
PG1	I/O	5T	SMC_A11, DMC_A11, EVENTOUT	-	-	-	57	67
PE7	I/O	5T	SMC_D4, DMC_D4, TMR1_ETR, EVENTOUT	-	-	38	58	68
PE8	I/O	5T	SMC_D5, DMC_D5, TMR1_CH1N, EVENTOUT	-	-	39	59	69
PE9	I/O	5T	SMC_D6, DMC_D6, TMR1_CH1, EVENTOUT	-	-	40	60	70
V _{SS}	P	-	-	-	-	-	61	71

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
V _{DD}	P	-	-	-	-	-	62	72
PE10	I/O	5T	SMC_D7, DMC_D7, TMR1_CH2N, EVENTOUT	-	-	41	63	73
PE11	I/O	5T	SMC_D8, DMC_D8, TMR1_CH2, EVENTOUT	-	-	42	64	74
PE12	I/O	5T	SMC_D9, DMC_D9, TMR1_CH3N, EVENTOUT	-	-	43	65	75
PE13	I/O	5T	SMC_D10, DMC_D10, TMR1_CH3, EVENTOUT	-	-	44	66	76
PE14	I/O	5T	SMC_D11, DMC_D11, TMR1_CH4, EVENTOUT	-	-	45	67	77
PE15	I/O	5T	SMC_D12, DMC_D12, TMR1_BKIN, EVENTOUT	-	-	46	68	78
PB10	I/O	5T	SPI2_SCK, I2S2_CK, I2C2_SCL, USART3_TX, OTG_HS_ULPI_D3, ETH_MII_RX_ER, TMR2_CH3, EVENTOUT	-	29	47	69	79
PB11	I/O	5T	I2C2_SDA, USART3_RX, OTG_HS_ULPI_D4, ETH_RMII_TX_EN, ETH_MII_TX_EN, TMR2_CH4, EVENTOUT	-	30	48	70	80

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
V _{CAP_1}	P	-	-	-	31	49	71	81
V _{DD}	P	-	-	-	32	50	72	82
PH6	I/O	5T	I2C2_SMBAL, TMR12_CH1, ETH_MII_RXD2, EVENTOUT	-	-	-	-	83
PH7	I/O	5T	I2C3_SCL, ETH_MII_RXD3, EVENTOUT	-	-	-	-	84
PH8	I/O	5T	I2C3_SDA, DCI_HSYNC, EVENTOUT	-	-	-	-	85
PH9	I/O	5T	I2C3_SMBAL, TMR12_CH2, DCI_D0, EVENTOUT	-	-	-	-	86
PH10	I/O	5T	TMR5_CH1, DCI_D1, EVENTOUT	-	-	-	-	87
PH11	I/O	5T	TMR5_CH2, DCI_D2, EVENTOUT	-	-	-	-	88
PH12	I/O	5T	TMR5_CH3, DCI_D3, EVENTOUT	-	-	-	-	89
V _{SS}	P	-	-	-	-	-	-	90
V _{DD}	P	-	-	-	-	-	-	91
PB12	I/O	5T	SPI2_NSS, I2S2_WS, I2C2_SMBAL, USART3_CK, TMR1_BKIN, CAN2_RX, OTG_HS_ULPI_D5, ETH_RMII_TXD0, ETH_MII_TXD0, OTG_HS_ID, EVENTOUT	-	33	51	73	92
PB13	I/O	5T	SPI2_SCK,	OTG_HS_VBUS	34	52	74	93

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
			I2S2_CK, USART3_CTS, TMR1_CH1N, CAN2_TX, OTG_HS_ULPI_D6, ETH_RMII_TXD1, ETH_MII_TXD1, EVENTOUT					
PB14	I/O	5T	SPI2_MISO, TMR1_CH2N, TMR12_CH1, OTG_HS_DM, USART3_RTS, TMR8_CH2N, I2S2ext_SD, EVENTOUT	-	35	53	75	94
PB15	I/O	5T	SPI2_MOSI, I2S2_SD, TMR1_CH3N, TMR8_CH3N TMR12_CH2, OTG_HS_DP, EVENTOUT	RTC_REFIN	36	54	76	95
PD8	I/O	5T	SMC_D13, DMC_D13, USART3_TX, EVENTOUT	-	-	55	77	96
PD9	I/O	5T	SMC_D14, DMC_D14, USART3_RX, EVENTOUT	-	-	56	78	97
PD10	I/O	5T	SMC_D15, DMC_D15, USART3_CK, EVENTOUT	-	-	57	79	98
PD11	I/O	5T	SMC_CLE, SMC_A16, DMC_BA0, USART3_CTS, EVENTOUT	-	-	58	80	99

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
PD12	I/O	5T	SMC_ALE, SMC_A17, DMC_BA1, TMR4_CH1, USART3_RTS, EVENTOUT	-	-	59	81	100
PD13	I/O	5T	SMC_A18, TMR4_CH2, EVENTOUT	-	-	60	82	101
V _{SS}	P	-	-	-	-	-	83	102
V _{DD}	P	-	-	-	-	-	84	103
PD14	I/O	5T	SMC_D0, DMC_D0, TMR4_CH3, EVENTOUT	-	-	61	85	104
PD15	I/O	5T	SMC_D1, DMC_D2, TMR4_CH4, EVENTOUT	-	-	62	86	105
PG2	I/O	5T	SMC_A12, DMC_A12, EVENTOUT	-	-	-	87	106
PG3	I/O	5T	SMC_A13, DMC_A13, EVENTOUT	-	-	-	88	107
PG4	I/O	5T	SMC_A14, DMC_A14, EVENTOUT	-	-	-	89	108
PG5	I/O	5T	SMC_A15, DMC_A15, EVENTOUT	-	-	-	90	109
PG6	I/O	5T	SMC_INT2, EVENTOUT	-	-	-	91	110
PG7	I/O	5T	SMC_INT3, USART6_CK, EVENTOUT	-	-	-	92	111
PG8	I/O	5T	DMC_CLK, USART6_RTS, ETH_PPS_OUT, EVENTOUT	-	-	-	93	112

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
V _{SS}	P	-	-	-	-	-	94	113
V _{DD}	P	-	-	-	-	-	95	114
PC6	I/O	5T	I2S2_MCK, TMR8_CH1, SDIO_D6, USART6_TX, DCI_D0, TMR3_CH1, EVENTOUT	-	37	63	96	115
PC7	I/O	5T	I2S3_MCK, TMR8_CH2, SDIO_D7, USART6_RX, DCI_D1, TMR3_CH2, EVENTOUT	-	38	64	97	116
PC8	I/O	5T	TMR8_CH3, SDIO_D0, TMR3_CH3, USART6_CK, DCI_D2, EVENTOUT	-	39	65	98	117
PC9	I/O	5T	I2S_CKIN, MCO2, TMR8_CH4, SDIO_D1, I2C3_SDA, DCI_D3, TMR3_CH4, EVENTOUT	-	40	66	99	118
PA8	I/O	5T	USART1_CK, TMR1_CH1, MCO, I2C3_SCL, OTG_FS_SOF, EVENTOUT	-	41	67	100	119
PA9	I/O	5T	USART1_TX, TMR1_CH2, I2C3_SMBAL, DCI_D0,	OTG_FS_VBUS	42	68	101	120

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
			EVENTOUT					
PA10	I/O	5T	USART1_RX, TMR1_CH3, OTG_FS_ID, DCI_D1, EVENTOUT	-	43	69	102	121
PA11	I/O	5T	USART1_CTS, CAN1_RX, TMR1_CH4, OTG_FS_DM, EVENTOUT	-	44	70	103	122
PA12	I/O	5T	USART1_RTS, CAN1_TX, TMR1_ETR, OTG_FS_DP, EVENTOUT	-	45	71	104	123
PA13 (JTMS-SWDIO)	I/O	5T	JTMS-SWDIO, EVENTOUT	PA13	46	72	105	124
V _{CAP_2}	P	-	-	-	47	73	106	125
V _{SS}	P	-	-	-	-	74	107	126
V _{DD}	P	-	-	-	48	75	108	127
PH13	I/O	5T	TMR8_CH1N, CAN1_TX, EVENTOUT	-	-	-	-	128
PH14	I/O	5T	TMR8_CH2N, DCI_D4, EVENTOUT	-	-	-	-	129
PH15	I/O	5T	TMR8_CH3N, DCI_D11, EVENTOUT	-	-	-	-	130
PI0	I/O	5T	TMR5_CH4, SPI2_NSS, I2S2_WS, DCI_D13, EVENTOUT	-	-	-	-	131
PI1	I/O	5T	SPI2_SCK, I2S2_CK, DCI_D8, EVENTOUT	-	-	-	-	132

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
PI2	I/O	5T	TMR8_CH4, SPI2_MISO, DCI_D9, I2S2ext_SD, EVENTOUT	-	-	-	-	133
PI3	I/O	5T	TMR8_ETR, SPI2_MOSI, I2S2_SD, DCI_D10, EVENTOUT	-	-	-	-	134
V _{SS}	P	-	-	-	-	-	-	135
V _{DD}	P	-	-	-	-	-	-	136
PA14 (JTCK/SWCLK)	I/O	5T	JTCK-SWCLK, EVENTOUT	-	49	76	109	137
PA15 (JTDI)	I/O	5T	JTDI, SPI3_NSS, I2S3_WS, TMR2_CH1_ETR, SPI1_NSS, EVENTOUT	-	50	77	110	138
PC10	I/O	5T	SPI3_SCK, I2S3_CK, UART4_TX, SDIO_D2, DCI_D8, USART3_TX, EVENTOUT	-	51	78	111	139
PC11	I/O	5T	UART4_RX, SPI3_MISO, SDIO_D3, DCI_D4, USART3_RX, I2S3ext_SD, EVENTOUT	-	52	79	112	140
PC12	I/O	5T	UART5_TX, SDIO_CK, DCI_D9, SPI3_MOSI, I2S3_SD, USART3_CK,	-	53	80	113	141

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
			EVENTOUT					
PD0	I/O	5T	SMC_D2, DMC_D2, CAN1_RX, EVENTOUT	-	-	81	114	142
PD1	I/O	5T	SMC_D3, DMC_D3, CAN1_TX, EVENTOUT	-	-	82	115	143
PD2	I/O	5T	TMR3_ETR, UART5_RX, SDIO_CMD, DCI_D11, EVENTOUT	-	54	83	116	144
PD3	I/O	5T	SMC_CLK, USART2_CTS, EVENTOUT	-	-	84	117	145
PD4	I/O	5T	SMC_NOE, USART2_RTS, EVENTOUT	-	-	85	118	146
PD5	I/O	5T	SMC_NWE, USART2_TX, EVENTOUT	-	-	86	119	147
V _{SS}	P	-	-	-	-	-	120	148
V _{DD}	P	-	-	-	-	-	121	149
PD6	I/O	5T	SMC_NWAIT, USART2_RX, EVENTOUT	-	-	87	122	150
PD7	I/O	5T	SMC_NE1, SMC_NCE2, USART2_CK, EVENTOUT	-	-	88	123	151
PG9	I/O	5T	SMC_NE2, SMC_NCE3, USART6_RX, EVENTOUT	-	-	-	124	152
PG10	I/O	5T	SMC_NCE4_1, SMC_NE3, EVENTOUT	-	-	-	125	153

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
PG11	I/O	5T	SMC_NCE4_2, ETH_MII_TX_EN, ETH_RMII_TX_EN, EVENTOUT	-	-	-	126	154
PG12	I/O	5T	SMC_NE4, USART6_RTS, EVENTOUT	-	-	-	127	155
PG13	I/O	5T	SMC_A24, USART6_CTS, ETH_MII_TXD0, ETH_RMII_TXD0, EVENTOUT	-	-	-	128	156
PG14	I/O	5T	SMC_A25, USART6_TX, ETH_MII_TXD1, ETH_RMII_TXD1, EVENTOUT	-	-	-	129	157
V _{SS}	P	-	-	-	-	-	130	158
V _{DD}	P	-	-	-	-	-	131	159
PG15	I/O	5T	DMC_CAS, USART6_CTS, DCI_D13, EVENTOUT	-	-	-	132	160
PB3 (JTDO/TRACESWO)	I/O	5T	JTDO, TRACESWO, SPI3_SCK, I2S3_CK, TMR2_CH2, SPI1_SCK, EVENTOUT	-	55	89	133	161
PB4 (NJTRST)	I/O	5T	NJTRST, SPI3_MISO, TMR3_CH1, SPI1_MISO, I2S3ext_SD, EVENTOUT	-	56	90	134	162
PB5	I/O	-	I2C1_SMBAL, CAN2_RX, OTG_HS_ULPI_D7, ETH_PPS_OUT,	-	57	91	135	163

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
			TMR3_CH2, SPI1_MOSI, SPI3_MOSI, DCI_D10, I2S3_SD, EVENTOUT					
PB6	I/O	5T	I2C1_SCL, TMR4_CH1, CAN2_TX, DCI_D5, USART1_TX, EVENTOUT	-	58	92	136	164
PB7	I/O	5T	I2C1_SDA, SMC_NL, DCI_VSYNC, USART1_RX, TMR4_CH2, EVENTOUT	-	59	93	137	165
BOOT0	I	B	-	V _{PP}	60	94	138	166
PB8	I/O	5T	TMR4_CH3, SDIO_D4, TMR10_CH1, DCI_D6, ETH_MII_TXD3, I2C1_SCL, CAN1_RX, EVENTOUT	-	61	95	139	167
PB9	I/O	5T	SPI2_NSS, I2S2_WS, TMR4_CH4, TMR11_CH1, SDIO_D5, DCI_D7, I2C1_SDA, CAN1_TX, EVENTOUT	-	62	96	140	168
PE0	I/O	5T	TMR4_ETR, SMC_NBL0, DMC_LDQM, DCI_D2,	-	-	97	141	169

Name (Function after reset)	Type	Structure	Multiplexing function	Additional function	LQFP 64	LQFP 100	LQFP 144	LQFP 176
			EVENTOUT					
PE1	I/O	5T	SMC_NBL1, DMC_UDQM, DCI_D3, EVENTOUT	-	-	98	142	170
V _{SS}	P	-	-	-	63	99	-	-
PDR_ON	I	5T	-	-	-	-	143	171
V _{DD}	P	-	-	-	64	100	144	172
PI4	I/O	5T	TMR8_BKIN, DCI_D5, EVENTOUT	-	-	-	-	173
PI5	I/O	5T	TMR8_CH1, DCI_VSYNC, EVENTOUT	-	-	-	-	174
PI6	I/O	5T	TMR8_CH2, DCI_D6, EVENTOUT	-	-	-	-	175
PI7	I/O	5T	TMR8_CH3, DCI_D7, EVENTOUT	-	-	-	-	176

Note:

(1) PC13, PC14 and PC15 are powered through the power switch. Since the switch only sinks limited current (3mA), the use of GPIO from PC13 to PC15 in output mode is limited:

- ① The speed shall not exceed 2MHz when the heavy load is 30pF;
- ② Not used for current source (e.g. driving LED).

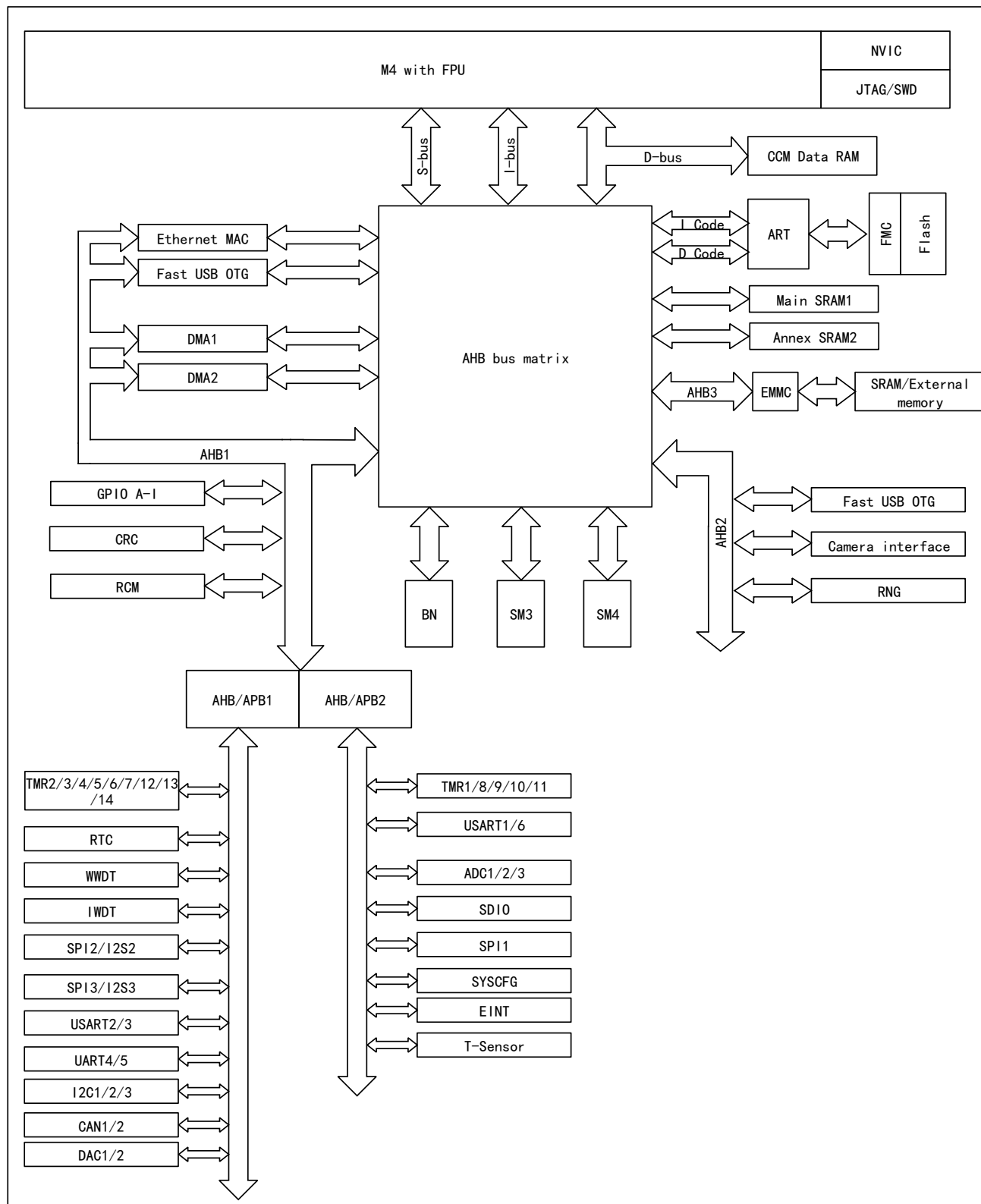
4 Function Description

This chapter mainly introduces the system architecture, interrupt, on-chip memory, clock, power supply and peripheral features of APM32F407xExG series products; for information about the Arm® Cortex®-M4 core, please refer to the *Arm® Cortex®-M4 Technical Reference Manual*, which can be downloaded from ARM's website.

4.1 System architecture

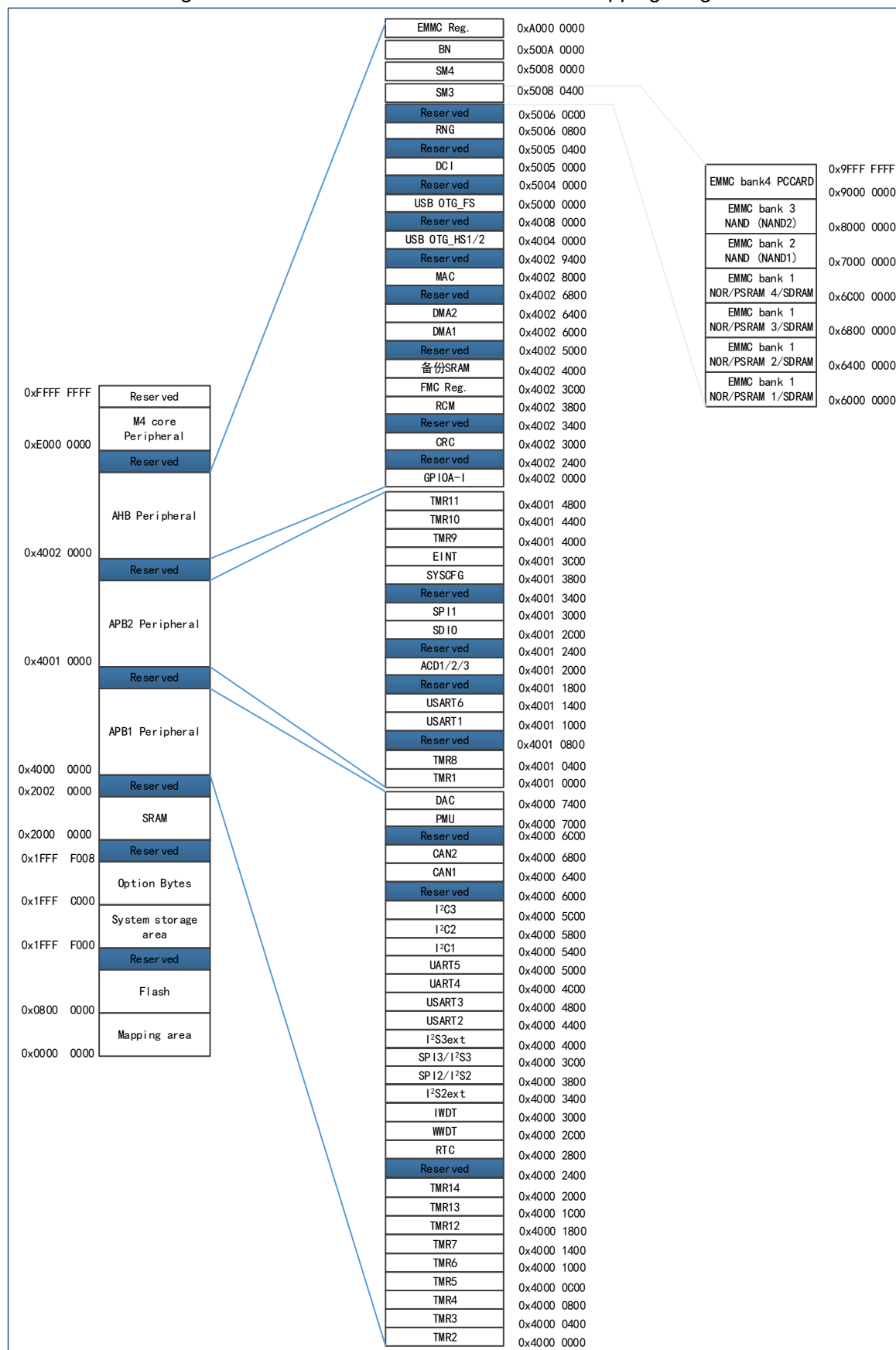
4.1.1 System Block Diagram

Figure 5 APM32F407xExG System Block Diagram



4.1.2 Address mapping

Figure 6 APM32F407xExG Series Address Mapping Diagram



4.1.3 Startup configuration

At startup, the user can select one of the following three startup modes by setting the high and low levels of the Boot pin:

- Startup from main memory
- Startup from BootLoader
- Startup from built-in SRAM

The user can use serial interface to reprogram the user Flash if starting up from BootLoader.

4.2 Core

The core of APM32F407xExG is Arm® Cortex®-M4 with FPU computing unit. Based on this platform, the development cost is low and the power consumption is low. It can provide excellent computing performance and advanced system interrupt response, and is compatible with all ARM tools and software.

4.3 Interrupt controller

4.3.1 Nested Vector Interrupt Controller (NVIC)

It embeds a nested vectored interrupt controller (NVIC) that can handle up to 82 maskable interrupt channels (not including 16 interrupt lines of Cortex®-M4) and 8 priority levels. The interrupt vector entry address can be directly transmitted to the core, so that the interrupt response processing with low delay can give priority to the late higher priority interrupt.

4.3.2 External Interrupt/Event Controller (EINT)

The external interrupt/event controller consists of 23 edge detectors, and each detector includes edge detection circuit and interrupt/event request generation circuit; each detector can be configured as rising edge trigger, falling edge trigger or both and can be masked independently. Up to 140 GPIOs can be connected to 16 external interrupt lines.

4.4 On-chip memory

On-chip memory includes main memory area, SRAM and information block; the information block includes system memory area and option byte; the system memory area stores BootLoader, 96-bit unique device ID and capacity information of main memory area; the system memory area has been written into the program when leaving the factory and cannot be erased.

Table 4 On-chip Memory Area

Memory	Maximum capacity	Function
Main memory area	512 KB	Store user programs and data
SRAM	128 KB	CPU can access at 0 wait cycle (read/write)
System memory area	2KB	Store BootLoader, 96-bit unique device ID, and main memory area capacity information

Memory	Maximum capacity	Function
Option byte	16Bytes	Configure main memory area read-write protection and MCU working mode

4.4.1 Configurable external memory controller (EMMC)

APM32F407xExG series integrates EMMC module, consists of SMC (static memory controller), DMC (dynamic memory controller), and supports PC card, SRAM, SDRAM, PSRAM, NorFlash and NandFlash.

Function introduction:

- Three EMMC interrupt sources, connected to NVIC unit through logic or
- Write FIFO
- The code can run in off-chip memories except NAND flash and PC card
- Connect to LCD

4.4.2 LCD parallel interface (LCD)

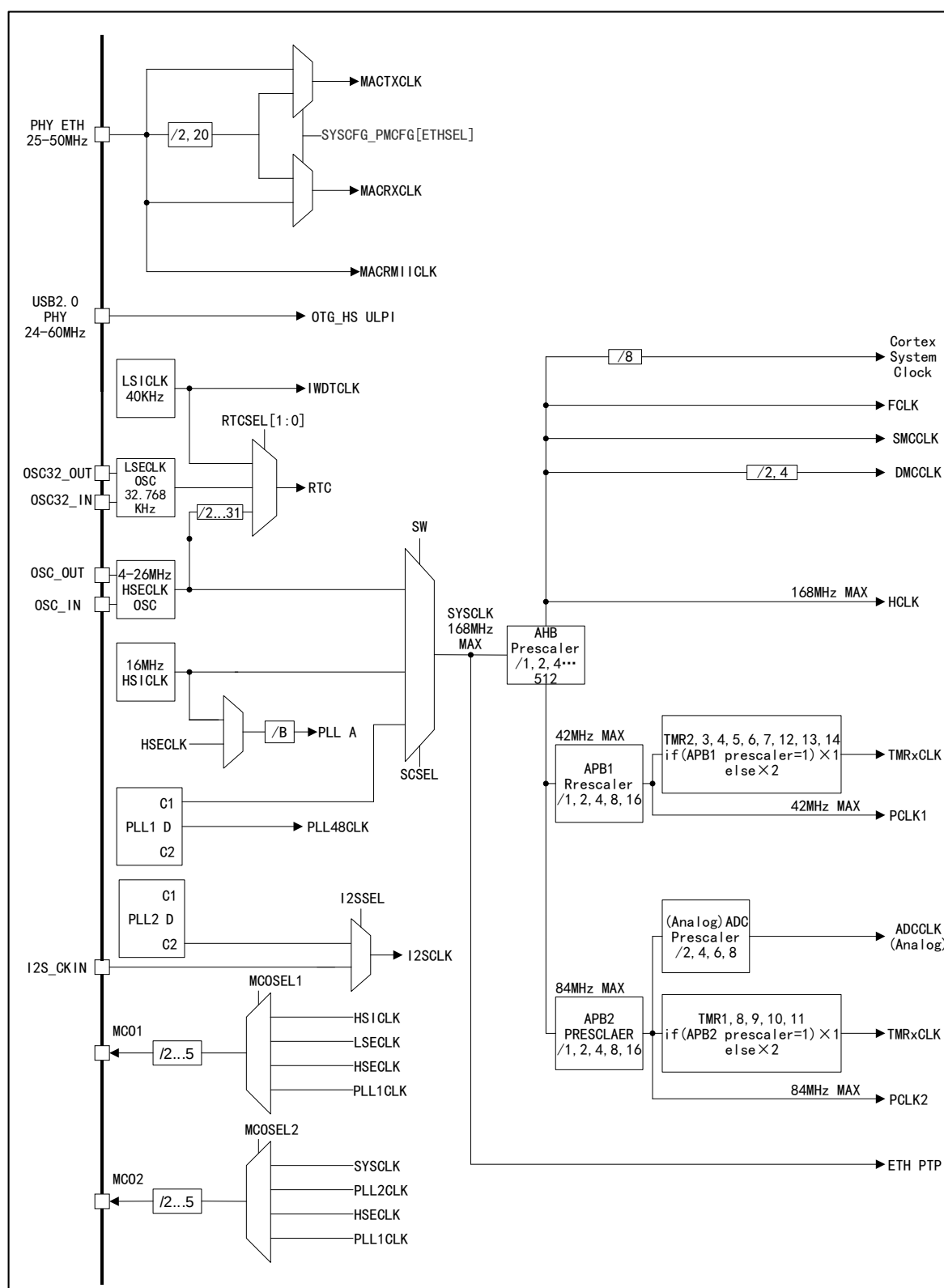
EMMC can be configured to seamlessly connect with most graphic LCD controllers, and supports the modes of Intel 8080 and Motorola 6800, and can flexibly connect with specific LCD interface. This LCD parallel interface can be used to easily build a simple graphics application environment or the high-performance scheme of the special acceleration controller can be used.

4.5 Clock

4.5.1 Clock tree

Clock tree of APM32F407xExG is shown in the figure below:

Figure 7 APM32F407xExG Clock Tree



4.5.2 Clock source

Clock source is divided into high-speed clock and low-speed clock according to the speed; the high-speed clock includes HSI CLK and HSE CLK, and the low-speed clock includes LSE CLK

and LSICLK; besides, some modules may have additional clock source pins to obtain the required clock frequency through external circuits.

4.5.3 System clock

HSICLK, PLLCLK and HSECLK can be selected as system clock; the clock source of PLLCLK can be HSICLK or HSECLK; the required system clock can be obtained by configuring PLL clock multiplier factor and frequency division factor.

When the product is reset and started, HSICLK is selected as the system clock by default, and then the user can choose one of the above clock sources as the system clock. When HSECLK failure is detected, the system will automatically switch to the HSICLK, and if an interrupt is enabled, the software can receive the related interrupt.

4.5.4 Bus clock

AHB, APB1 and APB2 buses are built in. The clock source of AHB is SYSCLK, and the clock source of APB1 and APB2 is HCLK; the required clock can be obtained by configuring the frequency division factor. The maximum frequency of AHB is 168MHz, the maximum frequency of APB2 is 84MHz, and the maximum frequency of APB1 is 42MHz.

4.5.5 Phase locked loop

APM32F407xExG series product has two PLL, one is PLL (PLL1), and the other is PLL (PLL2) specially used to provide specific clock frequency for I2S. They all need to generate different clock frequencies by configuring parameters. Please refer to the *User Manual* for specific parameters and configuration registers.

4.6 Reset and power management

4.6.1 Power supply scheme

Table 5 Power Supply Scheme

Name	Voltage range	Description
V _{DD}	1.8~3.6V	I/O (see pin distribution diagram for specific IO) and internal voltage regulator are powered through V _{DD} pin.
V _{DDA} /V _{SSA}	1.8~3.6V	Supply power for ADC, DAC, reset module, RC oscillator and PLL analog part; when ADC or DAC is used, V _{DDA} and V _{SSA} must be connected to V _{DD} and V _{SS} .
V _{BAT}	1.8~3.6V	When V _{DD} is disabled, RTC, external 32KHz oscillator and backup register are powered through internal power switch.

4.6.2 Voltage regulator

Table 6 Regulator Operating Mode

Name	Description
Master mode (MR)	Used in run mode
Low-power mode (LPR)	Used in stop mode

Name	Description
Power-down mode	Used in standby mode; when the voltage regulator has high-impedance output, the core circuit is powered down, the power consumption of the voltage regulator is zero, and all data of registers and SRAM will be lost.

Note: The voltage regulator is always in working state after reset, and outputs with high impedance in power-down mode.

4.6.3 Power supply voltage monitor

Power-on reset (POR), power-down reset (PDR) and brown-out reset circuits are integrated inside the product. These three circuits are always in working condition. When the power-down reset circuit monitors that the power supply voltage is lower than the specified threshold value ($V_{POR/PDR}$), even if the external reset circuit is used, the system will remain reset.

The product has a built-in programmable power supply voltage monitor (PVD) that can monitor V_{DD} and compare it with V_{PVD} threshold. When V_{DD} is outside the V_{PVD} threshold range and the interrupt is enabled, the MCU can be set to a safe state through the interrupt service program.

4.7 Low-power mode

APM32F407xExG supports three low-power modes, namely, sleep mode, stop mode and standby mode, and there are differences in power, wake-up time and wake-up mode among these three modes. The low-power mode can be selected according to the actual application requirements.

Table 7 Low-power Mode

Mode	Description
Sleep mode	The core stops working, all peripherals are working, and it can be woken up through interrupts/events
Stop mode	Under the condition that SRAM and register data are not lost, the lowest power consumption can be achieved in stop mode; The clock of the internal 1.3V power supply module will stop, HSECLK crystal resonator, HSICLK and PLL will be disabled, and the voltage regulator can be configured in normal mode or low-power mode; Any external interrupt line can wake up MCU, and the external interrupt lines include one of the 16 external interrupt lines, PVD output, RTC and USB_OTG.
Standby mode	The power consumption in this mode is the lowest; Internal voltage regulator is turned off, all 1.3V power supply modules are powered down, HSECLK crystal resonator, and HSICLK clocks are disabled, SRAM and register data disappear, RTC area and backup register contents remain, and the standby circuit still works; The external reset signal on NRST, IWDG reset, rising edge on WKUP pin or RTC event will wake MCU out of standby mode.

4.8 DMA

2 built-in DMA, 16 data streams in total. Each data stream corresponds to 8 channels, but each

data stream can only use 1 channel at the same time. The peripherals supporting DMA requests are ADC, SPI, USART, I2C, and TMRx. Four levels of DMA channel priority can be configured. Support "memory→memory, memory→peripheral, peripheral→memory" data transmission (the memory includes Flash、SRAM、SDRAM).

4.9 GPIO

GPIO can be configured as general input, general output, multiplexing function and analog input and output. The general input can be configured as floating input, pull-up input and pull-down input; the general output can be configured as push-pull output and open-drain output; the multiplexing function can be used for digital peripherals; and the analog input and output can be used for analog peripherals and low-power mode; the enable and disable pull-up/pull-down resistor can be configured; the speed of 2MHz, 10MHz and 50MHz can be configured; the higher the speed is, the greater the power and the noise will be.

4.10 Communication peripherals

4.10.1 USART/UART

Up to 6 universal synchronous/asynchronous transmitter receivers are built in the chip. The USART1/6 interfaces can communicate at a rate of 10.5Mbit/s, while other USART/UART interfaces can communicate at a rate of 5.25Mbit/s. All USART/UART interfaces can configure baud rate, parity check bit, stop bit, and data bit length; they all can support DMA.

USART/UART function differences are shown in the table below:

Table 8 USART/UART Function Differences

USART mode/function	USART1	USART2	USART3	UART4	UART5	USART6
Hardware flow control of modem	√	√	√	—	—	√
Smart card mode	√	√	√	—	—	√
IrDA SIR coder-decoder functions	√	√	√	√	√	√
LIN mode	√	√	√	√	√	√
Standard characteristics	√	√	√	√	√	√
SPI host	√	√	√	—	—	√
Maximum baud rate under 16-time oversampling (Mbit/s)	5.25	2.62	2.62	2.62	2.62	5.25
Maximum baud rate under 8-time oversampling (Mbit/s)	10.50	5.25	5.25	5.25	5.25	10.5
APB mapping	APB2	APB1	APB1	APB1	APB1	APB2

Note: √ = support.

4.10.2 I2C

I2C1/2/3 bus interfaces are built-in and they all can work in multiple-master or slave modes,

support 7-bit or 10-bit addressing, and support dual-slave addressing in 7-bit slave mode; the communication rate supports standard mode (up to 100kbit/s) and fast mode (up to 400kbit/s); hardware CRC generator/checker are built in; they can operate with DMA and support SMBus 2.0 version/PMBus.

4.10.3 SPI/I2S

3 built-in SPI, support full-duplex and half-duplex communication in master mode and slave mode, can use DMA controller, and can configure 4~16 bits per frame, and 3 SPI can communicate at a rate of up to 42Mbit/s, 21Mbit/s and 21Mbit/s respectively.

2 built-in I2S (multiplexed with SPI2 and SPI3 respectively), support half-duplex communication in master mode and slave mode, support synchronous transmission, and can be configured with 16-bit, 24-bit and 32-bit data transfer with 16-bit or 32-bit resolution. The configurable range of audio sampling rate is 8kHz~192kHz; when one or two I2S interfaces are configured as the master mode, the master clock can be output to external DAC or decoder (CODEC) at 256-time sampling frequency.

4.10.4 CAN

2 built-in CAN, compatible with 2.0A and 2.0B (active) specification, and can communicate at a rate of up to 1Mbit/s. It can receive and transmit standard frame of 11-bit identifier and extended frame of 29-bit identifier. It has 3 sending mailboxes and 2 receiving FIFO, and 14 3-level adjustable filters.

4.10.5 USB_OTG

Three USB controllers, namely, one OTG_FS and two OTG_HS, are embedded in the product. They all can support both host and slave functions to comply with the On-The-Go supplementary standard of USB 2.0 specification, and can also be configured as "Host only" or "Slave only" mode, to fully comply with USB 2.0 specification. OTG_FS clock (48MHz) is output by specific PLL, and OTG_HS clock (60MHz) is provided by external PHY.

4.10.6 Ethernet

Provides an IEEE-802.3-2002 compatible MAC for Ethernet LAN communication over MII or RMII. This MCU requires a PHY connection to a physical LAN bus. The PHY connects to the MII port, uses 17 signals for MII or 9 signals for RMII, and can use a 25MHz clock (MII) from the kernel.

4.10.7 Introduction

The secure digital input/output interface can connect SD card, SD I/O card, multi-media card (MMC) and CE-ATA card master interfaces, and provide data transmission between APB2 system bus and SD memory card, SD I/O card, MMC and CE-ATA device.

Analog peripherals

4.10.8 ADC

3 built-in ADC with 12-bit accuracy, up to 16 external channels and 3 internal channels for each

ADC. The internal channels measure the temperature sensor voltage, reference voltage and backup voltage respectively. A/D conversion mode of each channel has single, continuous, scan or intermittent modes, ADC conversion results can be left aligned or right aligned and stored in 16-bit data register; they support analog watchdog, and DMA.

4.10.8.1 Temperature sensor

1 temperature sensor (TSensor) is built in, which is internally connected with ADC_IN16 channel. The voltage generated by the sensor changes linearly with temperature and the converted voltage value can be obtained by ADC and converted into temperature.

4.10.8.2 Internal reference voltage

Built-in reference voltage V_{REFINT} , internally connected to ADC_IN17 channel; V_{REFINT} can be obtained through ADC; V_{REFINT} provides stable voltage output for ADC.

4.10.9 DAC

2 built-in 12-bit DAC, each corresponding to an output channel, which can be configured as 8-bit and 12-bit modes, and the DMA function is supported. The waveform generation supports noise wave and triangle wave. The conversion mode supports independent or simultaneous conversion and the trigger mode supports external signal trigger and internal timer update trigger.

4.11 Timer

2 built-in 16-bit advanced timers (TMR1/8), 8 16-bit general-purpose timers (TMR3/4/9/10/11/12/13/14), 2 32-bit general timers (TMR2/5), 2 16-bit basic timers (TMR6/7), 1 independent watchdog timer, 1 window watchdog timer and 1 system tick timer.

Watchdog timer can be used to detect whether the program is running normally.

The system tick timer is the peripheral of the core with automatic reloading function. When the counter is 0, it can generate a maskable system interrupt, which can be used for real-time operating system and general delay.

Table 9 Function Comparison between Advanced/General-purpose/Basic and System Tick Timers

Timer type	System tick timer	Basic timer	General-purpose timer		Advanced timer
Timer name	Sys Tick Timer	TMR6/7	TMR2/5	TMR3/4/9/10/11/12/13/14	TMR1/8
Counter resolution	24 bits	16 bits	32 bits	16 bits	16 bits
Counter type	Down	Up	Up, down, up/down		Up, down, up/down
Prescaler factor	-	Any integer between 1 and 65536	Any integer between 1 and 65536		Any integer between 1 and 65536
Generate DMA request	-	OK	OK		OK

Timer type	System tick timer	Basic timer	General-purpose timer	Advanced timer
Capture/compare register	-	-	4	4
Complementary output	-	None	None	Yes
Pin characteristics	-	-	1-way external trigger signal input pin; 4-way non-complementary channel pin.	1-way external trigger signal input pin; 1-way braking input signal pin; 3-pair complementary channel pins; 1-way non-complementary channel pin.
Function Description	Special for real-time operating system. Automatic reloading function supported. When the counter is 0, it can generate a maskable system interrupt. Can program the clock source.	Used to generate DAC trigger signals. Can be used as a 16-bit general-purpose timebase counter.	Synchronization or event chaining function provided. Timers in debug mode can be frozen. Can be used to generate PWM output. Each timer has independent DMA request mechanism. It can handle incremental encoder signals.	It has complementary PWM output with dead band insertion. When configured as a 16-bit standard timer, it has the same function as the TMRx timer. When configured as a 16-bit PWM generator, it has full modulation capability (0~100%). In debug mode, the timer can be frozen, and PWM output is disabled. Synchronization or event chaining function provided.

Table 10 Function Comparison between IWDT and WWDT

Name	Counter resolution	Counter type	Prescaler factor	Function description
Independent watchdog	12 bits	Down	Any integer between 1 and 256	The clock is provided by an internally independent RC oscillator of 28KHz, which is independent of the master clock, so it can run in stop and standby modes. The whole system can be reset in case of problems. It can provide timeout management for applications as a free-running timer. It can be configured as a software or hardware startup watchdog through option bytes.

Name	Counter resolution	Counter type	Prescaler factor	Function description
				Timers in debug mode can be frozen.
Window watchdog	7 bits	Down	-	Can be set for free running. The whole system can be reset in case of problems. Driven by the master clock, it has early interrupt warning function; Timers in debug mode can be frozen.

4.12 RTC

1 RTC is built in, and there are LSECLK signal input pins (OS32_IN and OS32_OUT) and 2 TAMP input signal detection pins (RTC_TAMP1/2); the clock source can select external 32.768kHz crystal oscillator, resonator or oscillator, LSICLK and HSECLK/128; it is powered by V_{DD} by default; when V_{DD} is powered off, it can be automatically switched to V_{BAT} power supply, and RTC configuration and time data will not be lost; RTC configuration and time data will not be lost in case of system reset, software reset and power-on reset; it supports clock and calendar functions.

4.12.1 Backup domain

4KB backup SRAM and 20 backup registers are built in, and are powered by V_{DD} by default; when V_{DD} is powered off, it can be automatically switched to V_{BAT} power supply, and the data in backup register will not be lost; the data in backup register will not be lost in case of system reset, software reset and power-on reset.

4.13 RNG

A RNG is embedded, and it provides 32-bit random number generated by the integrated simulation.

4.14 DCI

DCI is used to receive high-speed data streams from CMOS camera. It supports different data formats and is applicable to black-and-white cameras, X24 cameras and so on.

4.15 CRC

1 CRC (cyclic redundancy check) computing unit is built in, which can generate CRC codes and operate 8-bit, 16-bit and 32-bit data.

4.16 Secure Encryption

4.16.1 BN

The BN module is a low-cost accelerator of RSA and ECC algorithms. It realizes almost all big number operations in finite field and the point operations on elliptic curves with K not equal to 2 or 3 characteristic p defined by Weierstrass equation. RSA encryption and decryption adopts modular exponentiation operation (MEXP). The elliptic curve point multiplication (ECPM), elliptic curve point addition (ECPA) and elliptic curve point verification (ECPV) are specific to ECC cryptosystems, such as SM2. The public key is generated in RSA and the internal parameters are generated in SM2 to realize modular inversion (MINV). Rabin-Miller prime number test is conducted for the numbers in the process of prime number generation. It also supports modular addition (MADD), modular subtraction (MSUB), modular multiplication (MMUL), addition (add), subtraction (sub), and most significant bit detection (MSBD). Currently it also supports pre-composing user-defined configurable defense countermeasures.

4.16.2 SM3

SM3_H is a high-performance IP core supporting AHB interface, and is widely applied in digital signature and message authentication. SM3 is the encryption hash function standard adopted by our government. The hash function is an iterative one-way function and it can process messages to generate a condensed representation called message digest.

4.16.3 SM4

SM4_H is a high-performance IP core supporting AHB interface. It is a symmetric encryption algorithm released in January 2006, and has been widely applied in China's wireless LAN WAPI (wired authentication and privacy infrastructure). The IP core implements SM4 standard algorithm and supports encryption and decryption in ECB and CBC modes. SM4 algorithm is a symmetric block cipher of 128-bit input data and key. In order to improve the operation speed, the data path module uses 8 s boxes for encryption and decryption operation and key expansion at the same time. It only takes 32 cycles to complete a round of encryption and decryption operation.

5 Electrical characteristics

5.1 Test conditions of electrical characteristics

5.1.1 Maximum and minimum values

Unless otherwise specified, all products are tested on the production line at $T_A=25^{\circ}\text{C}$. Its maximum and minimum values can support the worst environmental temperature, power supply voltage and clock frequency.

In the notes at the bottom of each table, it is stated that the data are obtained through comprehensive evaluation, design simulation or process characteristics and are not tested on the production line; on the basis of comprehensive evaluation, after passing the sample test, take the average value and add and subtract three times the standard deviation (average $\pm 3\Sigma$) to get the maximum and minimum values.

5.1.2 Typical value

Unless otherwise specified, typical data are measured based on $T_A=25^{\circ}\text{C}$, $V_{DD}=V_{DDA}=3.3\text{V}$.

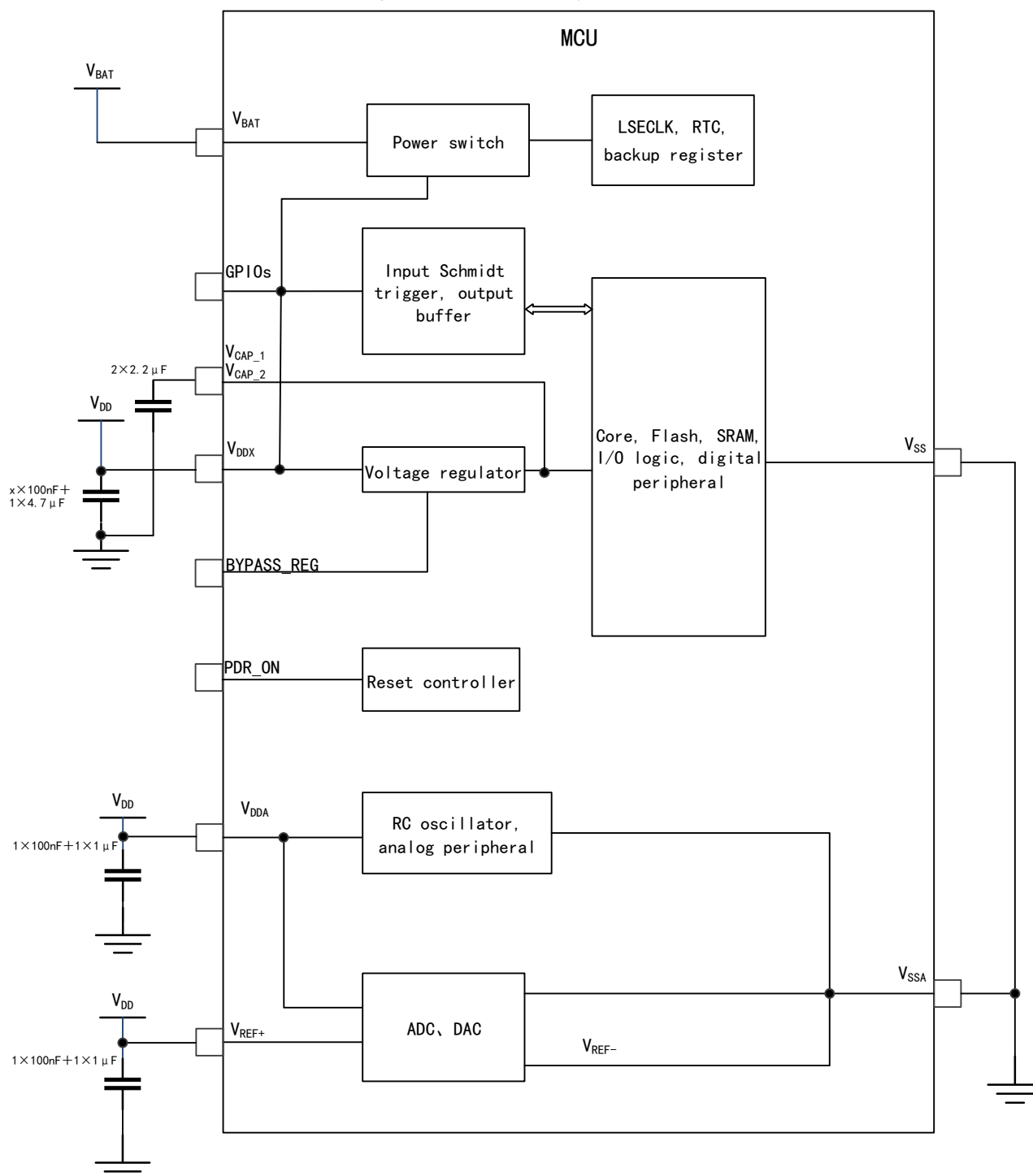
These data are only used for design guidance.

5.1.3 Typical curve

Unless otherwise specified, typical curves will only be used for design guidance and will not be tested.

5.1.4 Power supply scheme

Figure 8 Power Supply Scheme



Notes: V_{DDx} in the figure means the number of V_{DD} is x

5.1.5 Load capacitance

Figure 9 Load conditions when measuring pin parameters

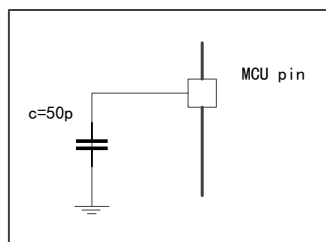


Figure 10 Pin Input Voltage Measurement Scheme

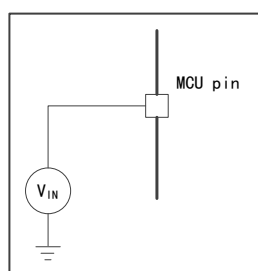
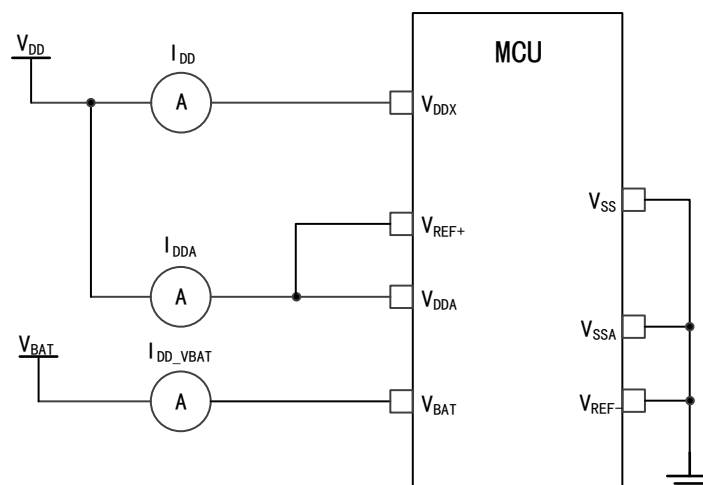


Figure 11 Power Consumption Measurement Scheme



5.2 Test under general operating conditions

Table 11 General Operating Conditions

Symbol	Parameter	Conditions	Minimum value	Maximum value	Unit
f_{HCLK}	Internal AHB clock frequency	-	-	168	MHz
f_{PCLK1}	Internal APB1 clock frequency	-	-	42	
f_{PCLK2}	Internal APB2 clock frequency	-	-	84	
V_{DD}	Main power supply voltage	-	1.8	3.6	V
V_{DDA}	Analog power supply voltage	Must be the same	1.8	2.4	V

Symbol	Parameter	Conditions	Minimum value	Maximum value	Unit
	(When neither ADC nor DAC is used)	as V_{DD}			
	Analog power supply voltage (When ADC and DAC are used)		2.4	3.6	
V_{BAT}	Power supply voltage of backup domain	-	1.65	3.60	V
T_A	Ambient temperature (temperature number 6)	Maximum power dissipation	-40	85	°C

5.3 Absolute maximum ratings

If the load on the device exceeds the absolute maximum rating, it may cause permanent damage to the device. Here, only the maximum load that can be borne is given, and there is no guarantee that the device functions normally under this condition.

5.3.1 Maximum temperature characteristics

Table 12 Temperature Characteristics

Symbol	Description	Value	Unit
T_{STG}	Storage temperature range	-65 ~ +150	°C
T_J	Maximum junction temperature	125	°C

5.3.2 Maximum rated voltage characteristics

All power supply (V_{DD} , V_{DDA}) and ground (V_{SS} , V_{SSA}) pins must always be connected to the power supply within the external limited range.

Table 13 Maximum Rated Voltage Characteristics

Symbol	Description	Minimum value	Maximum value	Unit
$V_{DD} - V_{SS}$	External main power supply voltage	-0.3	4.0	V
V_{IN}	Input voltage on FT pins	$V_{SS}-0.3$	$V_{DD}+4$	
	Input voltage on other pins	$V_{SS}-0.3$	4.0	mV
$ \Delta V_{DDx} $	Voltage difference between different power supply pins	-	50	
$ V_{SSx}-V_{SS} $	Voltage difference between different grounding pins	-	50	

5.3.3 Maximum rated current characteristics

Table 14 Current Characteristics

Symbol	Description	Maximum value	Unit
I_{VDD}	Total current through V_{DD}/V_{DDA} power line (supply current) ⁽¹⁾	240	mA
I_{VSS}	Total current through V_{SS} ground line (outflow current) ⁽¹⁾	240	

Symbol	Description	Maximum value	Unit
I_{IO}	Sink current on any I/O and control pin	25	
	Source current on any I/O and control pin	25	
$I_{INJ(PIN)}^{(2)}$	Injection current of 5T pin	-5/+0	
	Injection current of other pins	± 5	
$\Sigma I_{INJ(PIN)}^{(2)}$	Total injection current on all I/O and control pins ⁽⁴⁾	± 25	

1. All power supply (V_{DD} , V_{DDA}) and ground (V_{SS} , V_{SSA}) must always be within the allowed range.
2. The outflow current will interfere with the analog performance of the device.
3. I/O cannot be injected positively: when $V_{IN} < V_{SS}$, $I_{INJ(PIN)}$ cannot exceed the maximum allowable input voltage value.
4. If V_{IN} exceeds the maximum value, $I_{INJ(PIN)}$ must be externally limited not to exceed the maximum value. When $V_{IN} > V_{DD}$, the current flows into the pins; when $V_{IN} < V_{SS}$, the current flows out of the pins.
5. When the current is injected into several I/O ports at the same time, the maximum value of $\Sigma I_{INJ(PIN)}$ is the sum of instantaneous absolute value of inflow current and outflow current.

5.3.4 Electro-static discharge (ESD)

Table 15 ESD Absolute Maximum Ratings

Symbol	Parameter	Conditions	Range	Unit
$V_{ESD(HBM)}$	Electrostatic discharge voltage (human body model)	$T_A = +25^\circ\text{C}$, conforming to JESD22-A114	± 4500	V

Note: The samples are measured by a third-party testing organization and are not tested in production.

5.3.5 Static latch-up (LU)

Table 16 Static Latch-up

Symbol	Parameter	Conditions	Type
LU	Class of static latch-up	$T_A = +105^\circ\text{C}$, conforming to JESD78A	Class II A

Note: The samples are measured by a third-party testing organization and are not tested in production.

5.4 On-chip memory

5.4.1 Flash characteristics

Table 17 Flash Memory Characteristics

Symbol	Parameter		Conditions	Minimum value	Typical value	Maximum value	Unit
t_{prog}	8/16/32-bit programming time		$T_A = -40 \sim 105^\circ\text{C}$ $V_{DD} = 2.4 \sim 3.6\text{V}$	-	43	60	μs
t_{ERASE1}	Page (16KBytes) erase time	8 bits	$T_A = -40 \sim 105^\circ\text{C}$ $V_{DD} = 2.4 \sim 3.6\text{V}$	-	60	120	ms
		16 bits		-	60	120	
		32 bits		-	60	120	

Symbol	Parameter		Conditions	Minimum value	Typical value	Maximum value	Unit
t_{ERASE2}	Page (64KBytes) erase time	8 bits		-	250	500	
		16 bits		-	250	500	
		32 bits		-	250	500	
t_{ERASE3}	Page (168KBytes) erase time	8 bits		-	500	1000	
		16 bits		-	500	1000	
		32 bits		-	500	1000	
t_{ME}	Mass erase time	8 bits	$T_A = -40\sim 105^{\circ}\text{C}$ $V_{DD}=2.4\sim 3.6\text{V}$	-	10	20	ms
		16 bits		-	10	20	
		32 bits		-	10	20	
V_{prog}	Voltage of 8-bit programming		$T_A = -40\sim 105^{\circ}\text{C}$	1.8	-	3.6	V
	Voltage of 16-bit programming			2.1	-	3.6	
	Voltage of 32-bit programming			2.7	-	3.6	

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

5.5 Clock

5.5.1 Characteristics of external clock source

5.5.1.1 High-speed external clock generated by crystal resonator

For detailed parameters (frequency, package, precision, etc.) of crystal resonator, please consult the corresponding manufacturer.

Table 18 HSECLK4~26MHz Oscillator Characteristics

Symbol	Parameter	Conditions	Minimum value	Typical value	Maximum value	Unit
f_{OSC_IN}	Oscillator frequency	-	4	8	26	MHz
R_F	Feedback resistance	-	-	200	-	k Ω
$I_{DD}(HSECLK)$	HSECLK current consumption	$V_{DD}=3.3\text{V}$, $C_L=10\text{pF}@8\text{MHz}$	-	-	0.5	mA
$t_{SU}(HSECLK)$	Start-up Time	V_{DD} is stable	-	2	-	ms

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

5.5.1.2 Low-speed external clock generated by crystal resonator

For detailed parameters (frequency, package, precision, etc.) of crystal resonator, please consult the corresponding manufacturer.

Table 19 LSECLK Oscillator Characteristics ($f_{LSECLK} = 32.768\text{KHz}$)

Symbol	Parameter	Conditions	Minimum value	Typical value	Maximum value	Unit
f_{OSC_IN}	Oscillator frequency	-	-	32.768	-	KHz
$I_{DD(LSECLK)}$	LSECLK current consumption	-	-	-	1	μA
$t_{SU(LSECLK)}^{(1)}$	Start-up Time	V_{DD} is stable	-	2	-	s

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

(1) $t_{SU(LSECLK)}$ is the startup time, which is measured from the time when LSECLK is enabled by software to the time when stable oscillation at 32.768KHz is obtained. This value is measured by using a standard crystal resonator, which may vary greatly due to different crystal manufacturers.

5.5.2 Characteristics of internal clock source

5.5.2.1 High-speed internal (HSICLK) RC oscillator

Table 20 HSICLK Oscillator Characteristics

Symbol	Parameter	Conditions		Minimum value	Typical value	Maximum value	Unit
f_{HSICLK}	Frequency	-		-	16	-	MHz
$A_{CC(HSICLK)}$	Accuracy of HSICLK oscillator	Factory calibration	$V_{DD}=3.3\text{V}, T_A=25^\circ\text{C}^{(1)}$	-1	-	1	%
			$V_{DD}=2-3.6\text{V}, T_A=-40\sim 105^\circ\text{C}$	-2	-	4	%
$I_{DDA(HSICLK)}$	Power consumption of HSICLK oscillator	-		-	100	120	μA
$t_{SU(HSICLK)}$	Startup time of HSICLK oscillator	$V_{DD}=3.3\text{V}, T_A=-40\sim 105^\circ\text{C}$		-	3.7	5	μs

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

5.5.2.2 Low-speed internal (LSICLK) RC oscillator

Table 21 LSICLK Oscillator Characteristics

Symbol	Parameter	Minimum value	Typical value	Maximum value	Unit
f_{LSICLK}	Frequency ($V_{DD}=2-3.6\text{V}, T_A=-40\sim 105^\circ\text{C}$)	20	28	35	KHz
$I_{DD(LSICLK)}$	Power consumption of LSICLK oscillator	-	0.4	0.6	μA
$t_{SU(LSICLK)}$	Startup time of LSICLK oscillator, ($V_{DD}=3.3\text{V}, T_A=-40\sim 105^\circ\text{C}$)	-	16	40	μs

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

5.5.3 PLL Characteristics

Table 22 PLL1 Characteristics

Symbol	Parameter	Value			Unit
		Minimum value	Typical value	Maximum value	
f _{PLL1_IN}	PLL1 input clock	0.92	1	2.1	MHz
	PLL1 input clock duty cycle	40	-	60	%
f _{PLL1_OUT}	PLL1 frequency multiplier output clock (V _{DD} =3.3V, T _A =-40~105°C)	24	-	168	MHz
f _{PLL1_48_OUT}	PLL1 frequency multiplier output 48MHz clock (V _{DD} =3.3V, T _A =-40~105°C)	-	48	75	MHz
t _{LOCK1}	PLL1 phase locking time	60	-	120	μs

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

Table 23 PLL2 Characteristics

Symbol	Parameter	Value			Unit
		Minimum value	Typical value	Maximum value	
f _{PLL2_IN}	PLL2 input clock	0.92	1	2.1	MHz
	PLL2 input clock duty cycle	40	-	60	%
f _{PLL2_OUT}	PLL2 frequency multiplier output clock (V _{DD} =3.3V, T _A =-40~105°C)	20	-	144	MHz
t _{LOCK1}	PLL phase locking time	82	-	150	μs

5.6 Reset and power management

5.6.1 Test of Embedded Reset and Power Control Module Characteristics

Table 24 Embedded Reset and Power Control Module Characteristics

Symbol	Parameter	Conditions	Minimum value	Typical value	Maximum value	Unit
V _{POR/PDR}	Power-on/power-down reset threshold	Falling edge	1.68	1.70	1.70	V
		Rising edge	1.71	1.72	1.73	V
V _{BOR1}	Under-voltage threshold level 1	Falling edge	2.19	2.21	2.24	V
		Rising edge	2.27	2.29	2.30	V
V _{BOR2}	Under-voltage threshold level 2	Falling edge	2.49	2.51	2.55	V
		Rising edge	2.56	2.58	2.59	V
V _{BOR3}	Under-voltage threshold level 3	Falling edge	2.81	2.84	2.87	V
		Rising edge	2.89	2.91	2.92	V
V _{BORhyst}	BOR hysteresis	-	-	100	-	mV

Symbol	Parameter	Conditions	Minimum value	Typical value	Maximum value	Unit
V _{PDRhyst}	PDR hysteresis	-	-	40.00	50.00	mV
T _{RSTTEMPO}	Reset duration	-	0.70	0.95	1.48	ms

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

Table 25 Programmable Power Supply Voltage Detector Characteristics

Symbol	Parameter	Conditions	Minimum value	Typical value	Maximum value	Unit
V _{PVD}	Programmable power supply voltage detector voltage level selection	PLS[2:0]=000 (rising edge)	2.14	-	2.18	V
		PLS[2:0]=000 (falling edge)	2.03	-	2.10	V
		PLS[2:0]=000 (PVD hysteresis)	80.00	-	120.00	mV
		PLS[2:0]=001 (rising edge)	2.30	-	2.34	V
		PLS[2:0]=001 (falling edge)	2.18	-	2.23	V
		PLS[2:0]=001 (PVD hysteresis)	90.00	-	120.00	mV
		PLS[2:0]=010 (rising edge)	2.44	-	2.48	V
		PLS[2:0]=010 (falling edge)	2.32	-	2.37	V
		PLS[2:0]=010 (PVD hysteresis)	110.00	-	120.00	mV
		PLS[2:0]=011 (rising edge)	2.58	-	2.63	V
		PLS[2:0]=011 (falling edge)	2.49	-	2.53	V
		PLS[2:0]=011 (PVD hysteresis)	90.00	-	100.00	mV
		PLS[2:0]=100 (rising edge)	2.75	-	2.80	V
		PLS[2:0]=100 (falling edge)	2.64	-	2.68	V
		PLS[2:0]=100 (PVD hysteresis)	110.00	-	120.00	mV
		PLS[2:0]=101 (rising edge)	2.91	-	2.97	V
		PLS[2:0]=101 (falling edge)	2.81	-	2.86	V
		PLS[2:0]=101 (PVD hysteresis)	100.00	-	110.00	mV
		PLS[2:0]=110 (rising edge)	3.02	-	3.08	V
		PLS[2:0]=110 (falling edge)	2.90	-	2.96	V
		PLS[2:0]=110 (PVD hysteresis)	110.00	-	120.00	m.V
		PLS[2:0]=111 (rising edge)	3.12	-	3.19	V
		PLS[2:0]=111 (falling edge)	3.00	-	3.07	V
		PLS[2:0]=111 (PVD hysteresis)	110.00	-	120.00	mV

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

5.7 Power consumption

5.7.1 Power consumption test environment

- (1) The values are measured by executing Dhrystone 2.1, with the Keil.V5 compilation environment and the L0 compilation optimization level.
- (2) All I/O pins are in analog input mode and are connected to a static level at V_{DD} or V_{SS} (no load)
- (3) Unless otherwise specified, all peripherals are disabled
- (4) The relationship between Flash wait cycle setting and f_{HCLK} :
 - 0~30MHz: 0 wait cycle
 - 30~60MHz: 1 wait cycle
 - 60~90MHz: 2 wait cycles
 - 90~120MHz: 3 wait cycles
 - 120~150MHz: 4 wait cycles
 - 150~168MHz: 5 wait cycles
- (5) When the peripherals are enabled: $f_{PCLK1}=f_{HCLK}/4$, $f_{PCLK2}=f_{HCLK}/2$

5.7.2 Power consumption in run mode

Table 26 Power Consumption in Run Mode when the Program is Executed in Flash (ART is turned on)

Parameter	Conditions	f _{HCLK}	Typical value ⁽¹⁾		Maximum value ⁽¹⁾	
			T _A =25°C, V _{DD} =3.3V		T _A =105°C, V _{DD} =3.6V	
			I _{DDA} (μA)	I _{DD} (mA)	I _{DDA} (μA)	I _{DD} (mA)
Power consumption in run mode	HSECLK bypass ⁽²⁾ , enabling all peripherals ⁽³⁾	168MHz	751.56	67.70	802.20	74.02
		144MHz	693.94	52.75	745.20	57.66
		120MHz	637.4	44.49	691.10	49.39
		90MHz	780.88	34.37	831.70	39.375
		60MHz	636.86	23.86	689.60	28.7
		30MHz	636.62	13.29	689.40	18.099
		25MHz	115.372	10.83	127.76	15.627
		16MHz	115.42	7.21	127.93	11.905
		8MHz	115.36	3.93	127.77	8.587
		4MHz	115.33	2.31	127.78	6.967
		2MHz	115.36	1.49	127.82	6.17
	HSECLK bypass ⁽²⁾ , disabling all peripherals	168MHz	750.88	28.35	801.40	34.352
		144MHz	692.84	22.02	744.70	26.958
		120MHz	636.82	18.54	691.10	23.48
		90MHz	779.80	14.45	831.90	19.302
		60MHz	636.52	10.04	689.80	14.924
		30MHz	636.40	5.75	690.20	10.563
		25MHz	115.32	4.38	128.66	9.115
		16MHz	115.34	3.01	128.44	7.673
		8MHz	115.36	1.86	127.80	6.481
		4MHz	115.35	1.27	127.84	5.93
		2MHz	115.36	0.99	127.86	5.65

Note:

(1) The data are obtained from a comprehensive evaluation and are not tested in production.

(2) The external clock is 4MHz; when f_{HCLK}>25MHz, turn on PLL; otherwise, turn off PLL.

(3) When the analog peripherals such as ADC, DAC, HSECLK, LSECLK, HSICLK and LSICLK are turned on, extra power consideration needs to be considered.

Table 27 Power Consumption in Run Mode when the Program is Executed in Flash (ART is turned off)

Parameter	Conditions	f _{HCLK}	Typical value ⁽¹⁾		Maximum value ⁽¹⁾	
			T _A =25°C, V _{DD} =3.3V		T _A =105°C, V _{DD} =3.6V	
			I _{DDA} (μA)	I _{DD} (mA)	I _{DDA} (μA)	I _{DD} (mA)
Power consumption in run mode	HSECLK bypass ⁽²⁾ , enabling all peripherals ⁽³⁾	168MHz	751.66	64.25	802.00	70.52
		144MHz	693.58	51.09	745.30	56.05
		120MHz	637.26	43.99	690.20	48.92
		90MHz	780.86	34.91	831.40	39.97
		60MHz	636.78	25.02	689.40	29.90
		30MHz	636.66	14.33	689.00	19.32
		25MHz	115.36	11.80	127.72	16.725
		16MHz	115.36	7.83	127.75	12.53
		8MHz	115.35	4.27	127.80	8.99
		4MHz	115.35	2.45	127.88	7.13
		2MHz	115.362	1.57	127.76	6.28
	HSECLK bypass ⁽²⁾ , disabling all peripherals	168MHz	750.94	24.71	801.40	30.85
		144MHz	692.82	20.21	744.70	25.18
		120MHz	636.76	17.96	689.80	22.91
		90MHz	780.46	15.03	831.60	20.01
		60MHz	636.46	11.19	689.80	16.13
		30MHz	636.38	6.79	689.90	11.68
		25MHz	115.33	5.26	128.50	10.15
		16MHz	115.32	3.65	127.96	8.46
		8MHz	115.36	2.14	127.82	6.80
		4MHz	115.35	1.43	127.68	6.11
		2MHz	115.53	1.07	127.90	5.82

Note:

(1) The data are obtained from a comprehensive evaluation and are not tested in production.

(2) The external clock is 4MHz; when f_{HCLK}>25MHz, turn on PLL; otherwise, turn off PLL.

(3) When the analog peripherals such as ADC, DAC, HSECLK, LSECLK, HSICLK and LSICLK are turned on, extra power consideration needs to be considered.

Table 28 Power Consumption in Run Mode when the Program is Executed in RAM

Parameter	Conditions	f _{HCLK}	Typical value ⁽¹⁾		Maximum value ⁽¹⁾	
			T _A =25°C, V _{DD} =3.3V		T _A =105°C, V _{DD} =3.6V	
			I _{DDA} (μA)	I _{DD} (mA)	I _{DDA} (μA)	I _{DD} (mA)
Power consumption in run mode	HSECLK bypass ⁽²⁾ , enabling all peripherals ⁽³⁾	168MHz	752.14	70.29	803.80	76.51
		144MHz	693.74	54.73	745.50	59.73
		120MHz	637.60	46.22	690.40	51.16
		90MHz	781.00	35.67	832.00	40.53
		60MHz	637.02	24.70	689.8	29.65
		30MHz	636.74	13.74	689.2	18.596
		25MHz	115.42	11.23	127.85	16.02
		16MHz	115.374	7.42	127.88	12.21
		8MHz	115.37	4.05	127.81	8.836
		4MHz	115.376	2.38	127.72	7.12
		2MHz	115.347	1.53	127.76	6.28
	HSECLK bypass ⁽²⁾ , disabling all peripherals	168MHz	751.38	31.03	802.4	37.29
		144MHz	693.00	24.11	744.7	29.11
		120MHz	636.88	20.30	689.80	25.23
		90MHz	780.56	15.81	931.60	20.74
		60MHz	636.68	10.92	690.00	15.80
		30MHz	636.62	6.19	689.70	11.02
		25MHz	115.36	4.75	128.42	9.48
		16MHz	115.35	3.26	128.79	8.07
		8MHz	115.38	1.97	127.76	6.71
		4MHz	115.36	1.33	127.73	6.04
		2MHz	115.34	1.02	127.74	5.70

Note:

(1) The data are obtained from a comprehensive evaluation and are not tested in production.

(2) The external clock is 4MHz, and when f_{HCLK}>25MHz, turn on PLL, otherwise, turn off PLL.

(3) When the analog peripherals such as ADC, DAC, HSECLK, LSECLK, HSICLK and LSICLK are turned on, extra power consideration needs to be considered.

5.7.3 Power consumption in sleep mode

Table 29 Power Consumption in Sleep Mode when the Program is Executed in Flash (ART is turned off)

Parameter	Conditions	f _{HCLK}	Typical value ⁽¹⁾		Maximum value ⁽¹⁾	
			T _A =25°C, V _{DD} =3.3V		T _A =105°C, V _{DD} =3.6V	
			I _{DDA} (μA)	I _{DD} (mA)	I _{DDA} (μA)	I _{DD} (mA)
Power consumption in sleep mode	HSECLK bypass ⁽²⁾ , enabling all peripherals	168MHz	751.34	54.18	802.1	60.33
		144MHz	693.26	42.25	745.00	47.12
		120MHz	637.24	35.75	689.80	40.53
		90MHz	780.60	27.69	831.20	32.539
		60MHz	636.72	19.33	689.20	24.149
		30MHz	636.46	11.02	689.20	15.8
		25MHz	115.356	8.96	127.77	13.7
		16MHz	115.34	5.99	127.71	10.68
		8MHz	115.334	3.33	127.78	8.01
		4MHz	115.332	2.00	127.84	6.669
		2MHz	115.352	1.34	127.82	6.017
	HSECLK bypass ⁽²⁾ , disabling all peripherals	168MHz	750.52	13.91	801.00	19.86
		144MHz	692.58	10.82	743.90	15.64
		120MHz	636.46	9.20	689.00	13.99
		90MHz	780.24	7.44	830.60	12.21
		60MHz	636.42	5.33	689.00	10.07
		30MHz	636.36	3.38	688.80	8.10
		25MHz	115.37	2.41	127.84	7.08
		16MHz	115.35	1.79	127.74	6.46
		8MHz	115.35	1.23	127.83	5.91
		4MHz	115.36	0.96	127.86	5.63
		2MHz	115.42	0.83	127.84	5.54

Note:

(1) The data are obtained from a comprehensive evaluation and are not tested in production.

(2) The external clock is 4MHz; when f_{HCLK}>25MHz, turn on PLL; otherwise, turn off PLL.

5.7.4 Power consumption in stop mode

Table 30 Power Consumption in Stop Mode

Conditions		Typical value ⁽¹⁾ , (T _A =25°C)						Maximum value ⁽¹⁾ , (V _{DD} =3.6V)	
		V _{DD} =2.4V		V _{DD} =3.3V		V _{DD} =3.6V		T _A =105°C	
		I _{DDA} (μA)	I _{DD} (mA)	I _{DDA} (μA)	I _{DD} (mA)	I _{DDA} (μA)	I _{DD} (mA)	I _{DDA} (μA)	I _{DD} (mA)
The regulator is in run mode, and all oscillators are in off state	Flash is in stop mode, and RC internal oscillator and high-speed oscillator are turned off (with no independent watchdog)	9.28	0.69	9.80	0.70	10.05	0.71	12.36	20.00
	Flash is in power-down mode, and RC internal oscillator and high-speed oscillator are turned off (with no independent watchdog)	9.23	0.69	9.72	0.70	10.00	0.70	12.35	20.00
The regulator is in low-power mode, and all oscillators are in off state	Flash is in stop mode, and RC internal oscillator and high-speed oscillator are turned off (with no independent watchdog)	4.18	0.21	4.65	0.21	4.87	0.21	5.91	15.00
	Flash is in power-down mode, and RC internal oscillator and high-speed oscillator are turned off (with no independent watchdog)	4.19	0.20	4.64	0.20	4.86	0.20	5.86	15.00

5.7.5 Power consumption in standby mode

Table 31 Power Consumption in Standby Mode

Conditions		Typical value ⁽¹⁾ , (T _A =25°C)						Maximum value ⁽¹⁾ , (V _{DD} =3.6V)	
		V _{DD} =2.4V		V _{DD} =3.3V		V _{DD} =3.6V		T _A =105°C	
		I _{DDA} (μA)	I _{DD} (μA)	I _{DDA} (μA)	I _{DD} (μA)	I _{DDA} (μA)	I _{DD} (μA)	I _{DDA} (μA)	I _{DD} (μA)
Power supply current in standby mode	The backup SRAM is turned on, and the low-speed oscillator and RTC are turned on	2.15	8.38	2.56	9.73	2.83	10.19	3.76	59.39
	The backup SRAM is turned off, and the low-speed oscillator and RTC are turned on	2.15	3.52	2.62	4.46	2.81	5.11	3.48	32.00

Conditions	Typical value ⁽¹⁾ , (T _A =25°C)						Maximum value ⁽¹⁾ , (V _{DD} =3.6V)	
	V _{DD} =2.4V		V _{DD} =3.3V		V _{DD} =3.6V		T _A =105°C	
	I _{DDA} (μA)	I _{DD} (μA)	I _{DDA} (μA)	I _{DD} (μA)	I _{DDA} (μA)	I _{DD} (μA)	I _{DDA} (μA)	I _{DD} (μA)
The backup SRAM is turned on, and the RTC is turned off	2.13	7.33	2.62	8.24	2.81	8.64	3.45	58.24
The backup SRAM is turned off, and the RTC is turned off	2.13	2.51	2.61	3.31	2.78	3.68	3.45	19.2

Note: (1) The data are obtained from a comprehensive evaluation and are not tested in production.

5.7.6 Peripheral power consumption

Peripheral power consumption = current that enables the peripheral clock-current that disables the peripheral clock.

Table 32 Peripheral Power Consumption

Parameter	Peripheral	Typical value ⁽¹⁾ T _A =25°C, V _{DD} =3.3V		Unit
		168MHz	144MHz	
AHB1 (up to 168MHz)	DMA1	5.4	4.21	μA/MHz
	DMA2	5.56	4.3	
	ETH	3	2.35	
	OTG_HS	4.21	3.26	
	GPIOA	0.32	0.25	
	GPIOB	0.31	0.24	
	GPIOC	0.32	0.24	
	GPIOD	0.3	0.23	
	GPIOE	0.31	0.25	
	GPIOF	0.33	0.26	
	GPIOG	0.3	0.24	
	GPIOH	0.3	0.24	
	GPIOI	0.3	0.24	
	CRC	0.03	0.03	
	BAKPR	0.07	0.05	
AHB2 (up to 168MHz)	OTG_FS	3.12	2.41	
	DCI	0.79	0.61	
	RNG	0.16	0.12	
	HASH	1.3	1	

Parameter	Peripheral	Typical value ⁽¹⁾ T _A =25°C, V _{DD} =3.3V		Unit
		168MHz	144MHz	
	CRYP	0.25	0.19	
AHB3 (up to 168MHz)	EMMC	1.68	1.3	
APB1 (up to 42MHz)	TMR2	0.46	0.36	
	TMR3	0.35	0.27	
	TMR4	0.34	0.27	
	TMR5	0.46	0.35	
	TMR6	0.08	0.07	
	TMR7	0.08	0.06	
	TMR12	0.19	0.15	
	TMR13	0.14	0.11	
	TMR14	0.14	0.1	
	WWDT	0.02	0.02	
	SPI2/I2S2	0.12	0.1	
	SPI3/I2S3	0.12	0.1	
	USART2	0.11	0.09	
	USART3	0.12	0.09	
	UART4	0.11	0.08	
	UART5	0.11	0.08	
	I2C1	0.12	0.09	
	I2C2	0.12	0.09	
	I2C3	0.12	0.1	
	CAN1	0.18	0.14	
	CAN2	0.16	0.13	
	PMU	0.01	0.01	
	DAC	0.08	0.06	
APB2 (up to 84MHz)	SDIO	0.41	0.32	
	TMR1	0.99	0.77	
	TMR8	0.97	0.77	
	TMR9	0.41	0.32	
	TMR10	0.27	0.21	
	TMR11	0.26	0.22	
	ADC1	0.27	0.22	

Parameter	Peripheral	Typical value ⁽¹⁾ T _A =25°C, V _{DD} =3.3V		Unit
		168MHz	144MHz	
	ADC2	0.27	0.22	
	ADC3	0.28	0.23	
	SPI1	0.12	0.11	
	USART1	0.22	0.18	
	USART6	0.21	0.18	
	SYSCFG	0.05	0.05	

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

5.7.7 Backup Domain Power Consumption

Table 33 V_{BAT} Power Consumption

Symbol	Parameter	Conditions	Typical value ⁽¹⁾ , T _A =25°C		Maximum value ⁽¹⁾ , V _{BAT} =3.6V		Unit
			V _{BAT} =2.4V	V _{BAT} =3.3V	T _A =85°C	T _A =105°C	
I _{DD_VBAT}	LSECLK and RTC are in ON state	The backup SRAM is turned on, and the low-speed oscillator and RTC are turned on	1.894	2.262	6	11	μA
		The backup SRAM is turned off, and the low-speed oscillator and RTC are turned on	1.08	1.412	3	5	
		The backup SRAM is turned on, and the RTC is turned off	0.926	1.116	5	10	
		The backup SRAM is turned off, and the RTC is turned off	0.02	0.128	2	4	

Note: (1) The data are obtained from a comprehensive evaluation and are not tested in production.

5.8 Wake-up time in low-power mode

The measurement of wake-up time in low-power mode is from the start of wake-up event to the time when the user program reads the first instruction, in which V_{DD}=V_{DDA}.

Table 34 Wake-up Time in Low-power Mode

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
t _{WUSLEEP}	Wake-up from sleep mode	-	39.00	59	61.20	ns

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
t _{WUSTOP}	Wake up from the stop mode	The regulator is in run mode, and Flash is in stop state	12.51	13.602	14.99	μs
		The regulator is in low-power mode, and Flash is in stop state	15.51	19.552	22.93	
		The regulator is in run mode, and Flash is in deep power-down mode	125.63	133.156	135.16	
		The regulator is in low-power mode, and Flash is in deep power-down mode	133.52	136.956	139.60	
t _{WUSTDBY}	Wake up from standby mode	-	173.03	214.056	227.96	

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

5.9 I/O port characteristics

Table 35 DC Characteristics (T_A=-40°C-105°C, V_{DD}=2~3.6V)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V _{IL}	Low-level input voltage	STD and STDA I/O	-	-	0.3V _{DD} -0.04	V
		5T and 5Tf I/O	-	-	0.3V _{DD}	
		Boot0 pin	-	-	0.1V _{DD} +0.1	
V _{IH}	High-level input voltage	STD and STDA I/O	0.45V _{DD} +0.3	-	-	V
		5T and 5Tf I/O	0.7V _{DD}	-	-	
		Boot0 pin	0.17V _{DD} +0.7	-	-	
V _{hys}	Schmidt trigger hysteresis	STD, STDA and 5T, 5Tf I/O	10% V _{DD}	-	-	mV
		Boot0 pin	0.1	-	-	
I _{Ikg}	Input leakage current	STDA in digital mode, V _{DDIOx} ≤V _{IN} ≤V _{DDA}	-	-	±1	μA
		5T and 5Tf I/O, V _{DDIOx} ≤V _{IN} ≤5V	-	-	3	
R _{PU}	Weak pull-up equivalent resistance	Except PA10 and PB12, V _{IN} =V _{SS}	30	40	50	kΩ
		PA10 and PB12	7	10	14	
R _{PD}	Weak pull-down equivalent resistance	Except PA10 and PB12, V _{IN} =V _{DD}	30	40	50	
		PA10 and PB12	7	10	14	
C _{IO}	I/O pin capacitance	-	-	5	-	pF

Table 36 AC Characteristics (T_A=25°C)

SPEED[1:0]	Symbol	Parameter	Conditions	Min	Max	Unit
00	f _{max(IO)out}	Maximum frequency	CL=50pF, V _{DD} >2.7V	-	4	MHz
			CL=50pF, V _{DD} >1.8V	-	2	
			CL=10pF, V _{DD} >2.7V	-	8	
			CL=10pF, V _{DD} >1.8V	-	4	
	t _{f(IO)out} /t _{r(IO)out}	Fall time of output from high to low level and rise time of output from low to high level	C _L =50 pF, V _{DD} =1.8 V-3.6V	-	100	ns
01	f _{max(IO)out}	Maximum frequency	CL=50pF, V _{DD} >2.7V	-	25	MHz
			CL=50pF, V _{DD} >1.8V	-	12.5	
			CL=10pF, V _{DD} >2.7V	-	50	
			CL=10pF, V _{DD} >1.8V	-	20	
	t _{f(IO)out} /t _{r(IO)out}	Fall time of output from high to low level and rise time of output from low to high level	CL=30pF, V _{DD} >2.7V	-	10	ns
			CL=30pF, V _{DD} >1.8V	-	20	
			CL=10pF, V _{DD} >2.7V	-	6	
			CL=10pF, V _{DD} >1.8V	-	10	
10	f _{max(IO)out}	Maximum frequency	CL=30pF, V _{DD} >2.7V	-	50	MHz
			CL=30pF, V _{DD} >1.8V	-	25	
			CL=10pF, V _{DD} >2.7V	-	100	
			CL=10pF, V _{DD} >1.8V	-	50	
	t _{f(IO)out} /t _{r(IO)out}	Fall time of output from high to low level and rise time of output from low to high level	CL=30pF, V _{DD} >2.7V	-	6	ns
			CL=30pF, V _{DD} >1.8V	-	10	
			CL=10pF, V _{DD} >2.7V	-	4	
			CL=10pF, V _{DD} >1.8V	-	6	
11	f _{max(IO)out}	Maximum frequency	CL=30pF, V _{DD} >2.7V	-	100	MHz
			CL=30pF, V _{DD} >1.8V	-	50	
			CL=10pF, V _{DD} >2.7V	-	180	
			CL=10pF, V _{DD} >1.8V	-	100	
	t _{f(IO)out} /t _{r(IO)out}	Fall time of output from high to low level and rise time of output from low to high level	CL=30pF, V _{DD} >2.7V	-	4	ns
			CL=30pF, V _{DD} >1.8V	-	6	
			CL=10pF, V _{DD} >2.7V	-	2.5	

SPEED[1:0]	Symbol	Parameter	Conditions	Min	Max	Unit
			$CL=10pF, V_{DD}>1.8V$	-	4	
-	$t_{EINTipw}$	Pulse width of external signal detected by EINT controller	-	10	-	

Figure 12 I/O AC Characteristics Definition

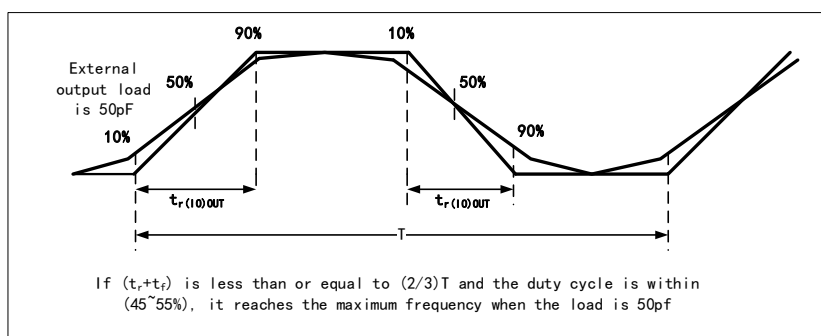


Table 37 Output Drive Voltage Characteristics ($T_A=25^\circ C$)

Symbol	Parameter	Conditions	Min	Max	Unit
V_{OL}	I/O pin outputs low voltage	CMOS port, $ I_{IO} =8mA$, $2.7V < V_{DD} < 3.6V$	-	0.4	V
V_{OH}	I/O pin outputs high voltage		$V_{DD}-0.4$	-	
V_{OL}	I/O pin outputs low voltage	TTL port, $ I_{IO} =20mA$, $2.7V < V_{DD} < 3.6V$	-	0.4	
V_{OH}	I/O pin outputs high voltage		2.4	-	
V_{OL}	I/O pin outputs low voltage	$ I_{IO} =20mA$, $2.7V < V_{DD} < 3.6V$	-	1.3	V
V_{OH}	I/O pin outputs high voltage		$V_{DD}-1.3$	-	
V_{OL}	I/O pin outputs low voltage	$ I_{IO} =6mA$, $2.7V < V_{DD} < 3.6V$	-	0.4	
V_{OH}	I/O pin outputs high voltage		$V_{DD}-0.4$	-	

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

5.10 NRST pin characteristics

The NRST pin input drive adopts CMOS process, which is connected with a permanent pull-up resistor RPU.

Table 38 NRST Pin Characteristics ($T_A=-40\sim105^\circ C$, $V_{DD}=2\sim3.6V$)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{IL(NRST)}$	NRST low-level input voltage	TTL port, $2.7V \leq V_{DD} \leq 3.6V$	-	-	0.8	V
$V_{IH(NRST)}$	NRST high-level input voltage		2	-	-	

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{IL(NRST)}$	NRST low-level input voltage	CMOS port, $1.8V \leq V_{DD} \leq 3.6V$	-	-	$0.3V_{DD}$	
$V_{IH(NRST)}$	NRST high-level input voltage		$0.7V_{DD}$	-	-	
$V_{hys(NRST)}$	NRST Schmidt trigger voltage hysteresis	-	-	200	-	mV
R_{PU}	Weak pull-up equivalent resistance	$V_{IN}=V_{SS}$	30	40	50	k Ω
$V_{F(NRST)}$	NRST input filter pulse	-	-	-	100	ns
$V_{NF(NRST)}$	NRST input unfiltered pulse	$V_{DD} > 2.7V$	300	-	-	
T_{NRST_OUT}	Generated reset pulse duration	Reset internal source	20	-	-	μs

5.11 Communication peripherals

5.11.1 I2C peripheral characteristics

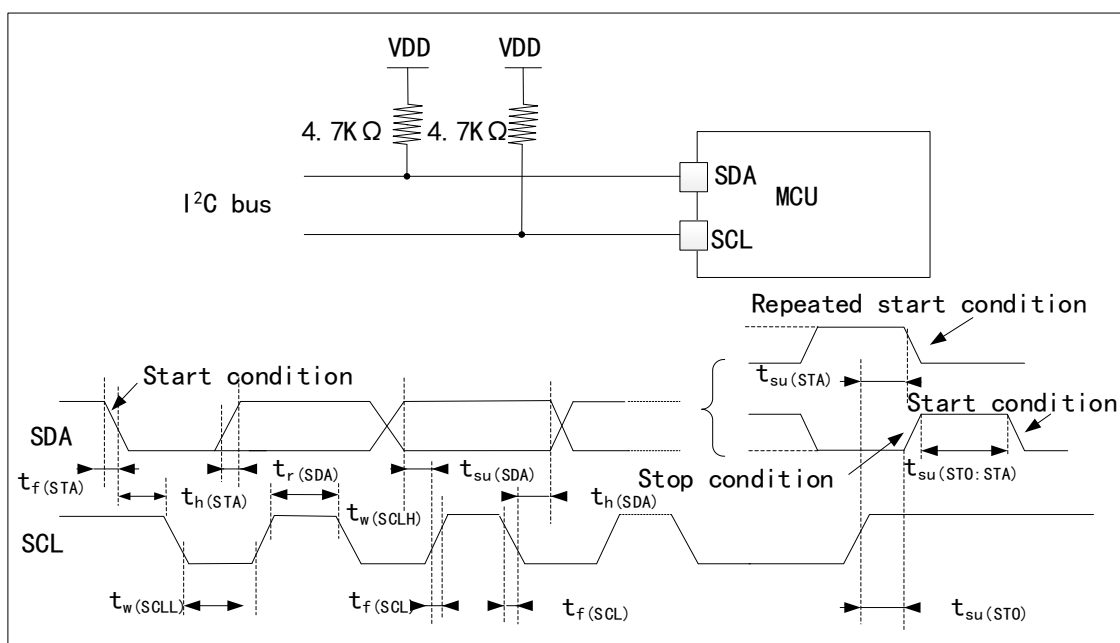
To achieve maximum frequency of I2C in standard mode, f_{PCLK1} must be greater than 2MHz. To achieve maximum frequency of I2C in fast mode, f_{PCLK1} must be greater than 4MHz.

Table 39 I2C Interface Characteristics ($T_A=25^{\circ}C$, $V_{DD}=3.3V$)

Symbol	Parameter	Standard I2C		Fast I2C		Unit
		Min	Max	Min	Max	
$t_{w(SCLL)}$	SCL clock low time	4.7	-	1.3	-	μs
$t_{w(SCLH)}$	SCL clock high time	4.0	-	0.6	-	
$t_{su(SDA)}$	SDA setup time	250	-	100	-	ns
$t_h(SDA)$	SDA data hold time	0	-	0	900	
$t_r(SDA)/t_r(SCL)$	SDA and SCL rise time	-	1000	$20+0.1C_b$	300	
$t_f(SDA)/t_f(SCL)$	SDA and SCL fall time	-	300	-	300	μs
$t_h(STA)$	Start condition hold time	4.0	-	0.6	-	
$t_{su(STA)}$	Setup time of repeated start condition	4.7	-	0.6	-	
$t_{su(STO)}$	Setup time of stop condition	4.0	-	0.6	-	
$t_{w(STO:STA)}$	Time from stop condition to start condition (the bus is idle)	4.7	-	1.3	-	pF
C_b	Capacitive load of each bus	-	400	-	400	

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

Figure 13 Bus AC Waveform and Measurement Circuit



Note: The measuring points are set at CMOS levels: $0.3V_{DD}$ and $0.7V_{DD}$.

5.11.2 SPI peripheral characteristics

Table 40 SPI Characteristics ($T_A=25^\circ\text{C}$, $V_{DD}=3.3\text{V}$)

Symbol	Parameter	Conditions	Min	Max	Unit
f_{SCK} $1/t_{c(SCK)}$	SPI clock frequency	Master mode	-	18	MHz
		Slave mode	-	18	
$t_{r(SCK)}$ $t_{f(SCK)}$	SI clock rise and fall time	Load capacitance: $C=15\text{pF}$	-	6	ns
$t_{su(NSS)}$	NSS setup time	Slave mode	$4T_{PCLK}$	-	
$t_{h(NSS)}$	NSS hold time	Slave mode	$2T_{PCLK} + 10$	-	
$t_{w(SCKH)}$ $t_{w(SCKL)}$	SCK high and low time	Master mode, $f_{PCLK}=36\text{MHz}$, Prescaler factor=4	$T_{PCLK}/2-2$	$T_{PCLK}/2+1$	
$t_{su(MI)}$ $t_{su(SI)}$	Data input setup time	Master mode	4	-	
		Slave mode	5	-	
$t_{h(MI)}$ $t_{h(SI)}$	Data input hold time	Master mode	4	-	
		Slave mode	5	-	
$t_{a(SO)}$	Data output access time	Slave mode, $f_{PCLK}=20\text{MHz}$	0	$3T_{PCLK}$	
$t_{dis(SO)}$	Disable time of data output	Slave mode	0	18	
$t_{v(SO)}$	Effective time of data output	Slave mode (after enabling the edge)	-	22.5	

Symbol	Parameter	Conditions	Min	Max	Unit
$t_{V(MO)}$	Effective time of data output	Master mode (after enabling the edge)	-	6.97	
$t_{h(SO)}$	Data output hold time	Slave mode (after enabling the edge)	11.5	-	
$t_{h(MO)}$		Master mode (after enabling the edge)	1	-	
$DuCy_{(SCK)}$	SPI clock frequency duty cycle	Slave mode	25	75	%

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

Figure 14 SPI Timing Diagram - Slave Mode and CPHA=0

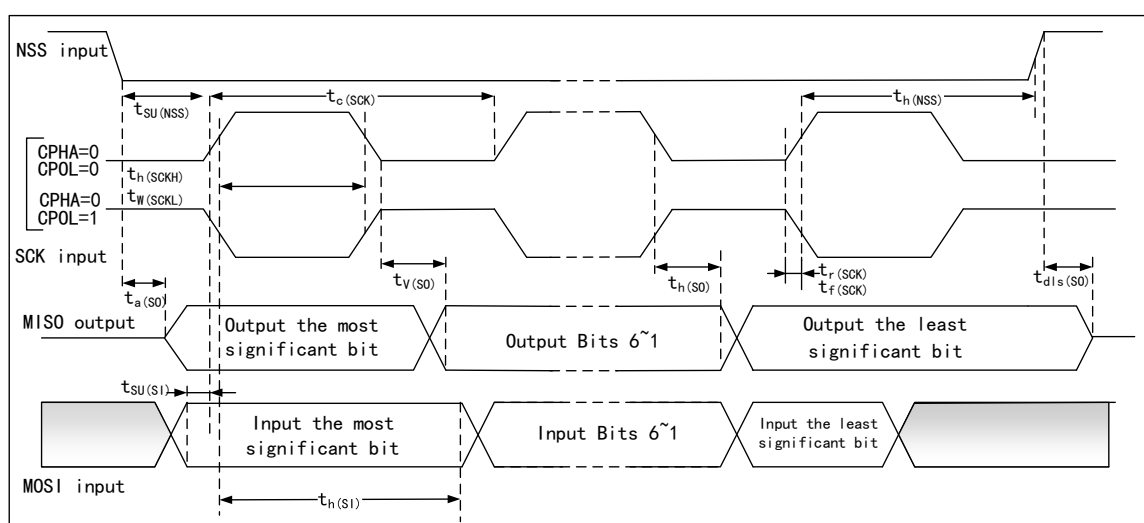
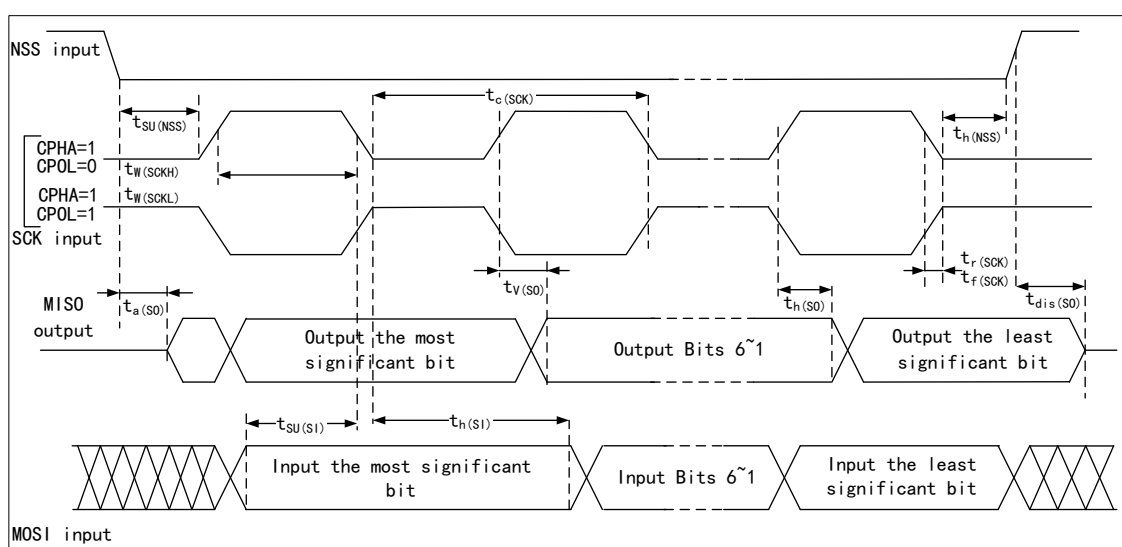
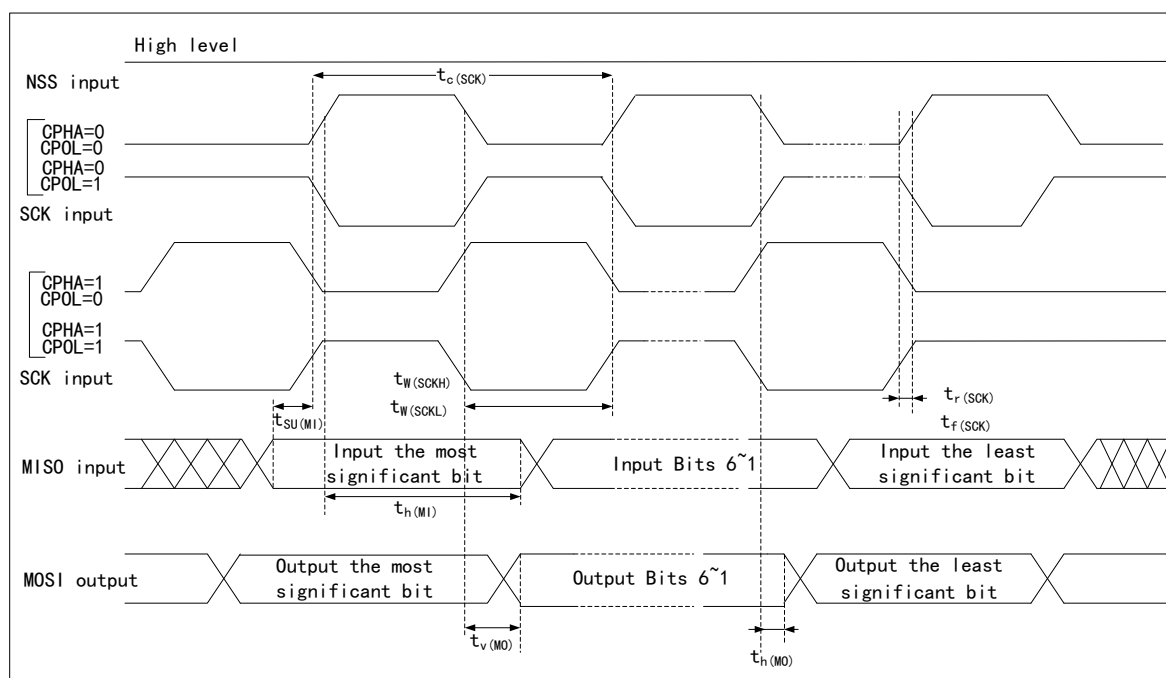


Figure 15 SPI Timing Diagram - Slave Mode and CPHA=1



Note: The measuring points are set at CMOS levels: 0.3V_{DD} and 0.7V_{DD}.

Figure 16 SPI Timing Diagram - Master Mode



Note: The measuring points are set at CMOS levels: $0.3V_{DD}$ and $0.7V_{DD}$.

5.12 Analog peripherals

5.12.1 ADC

Test parameter description:

- Sampling rate: the number of conversion of analog quantity to digital quantity by ADC per second
- Sample rate=ADC clock/(number of sampling periods + number of conversion periods)

5.12.1.1 12-bit ADC characteristics

Table 41 12-bit ADC Characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{DDA}	Power supply voltage	-	1.8	-	3.6	V
I_{DDA}	ADC power consumption	-	-	1.6	1.8	mA
f_{ADC}	ADC frequency	$V_{DDA}=1.8\sim 2.4V$	0.6	15	18	MHz
		$V_{DDA}=2.4\sim 3.6V$	0.6	30	36	
C_{ADC}	Internal sampling and holding capacitance	-	-	4	-	pF
R_{ADC}	Sampling resistor	-	-	-	6000	Ω
t_s	Sampling time	$f_{ADC}=30MHz$	0.1		16	μs

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
		-	3		480	1/f _{ADC}
T _{CONV}	Sampling and conversion time	f _{ADC} =30MHz 12-bit resolution	0.50	-	16.40	μs
		f _{ADC} =30MHz 10-bit resolution	0.43	-	16.34	μs
		f _{ADC} =30MHz 8-bit resolution	0.37	-	16.27	μs
		f _{ADC} =30MHz 6-bit resolution	0.30	-	16.20	μs

Table 42 12-bit ADC Accuracy

Symbol	Parameter	Conditions	Typ	Max	Unit
E _T	Composite error	f _{PCLK} =56MHz, f _{ADC} =14MHz, V _{DDA} =2.4V-3.6V T _A =-40°C~105°C	±2	±5	LSB
E _O	Offset error		±1.5	±2.5	
E _G	Gain error		±1.5	±3	
E _D	Differential linear error		±1	±2	
E _L	Integral linear error		±1.5	±3	

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

5.12.1.2 Test of Built-in Reference Voltage Characteristics

Table 43 Built-in Reference Voltage Characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V _{REFINT}	Built-in Reference Voltage	-40°C < T _A < +105°C	1.19	1.20	1.20	V
T _{S_vrefint}	Sampling time of ADC when reading out internal reference voltage	-	10	-	-	μs
V _{RERINT}	Built-in reference voltage extends to temperature range	V _{DD} =3V	-	3	5	mV
T _{coeff}	Temperature coefficient	-	-	30	50	ppm/°C

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

5.12.2 DAC

Test parameter description:

- DNL differential non-linear error: the deviation between two consecutive codes is -1LSB
- INL integral non-linear error: the difference between the measured value at code i and the value at code i on the connection between code 0 and the last code 4095

Table 44 DAC Characteristics

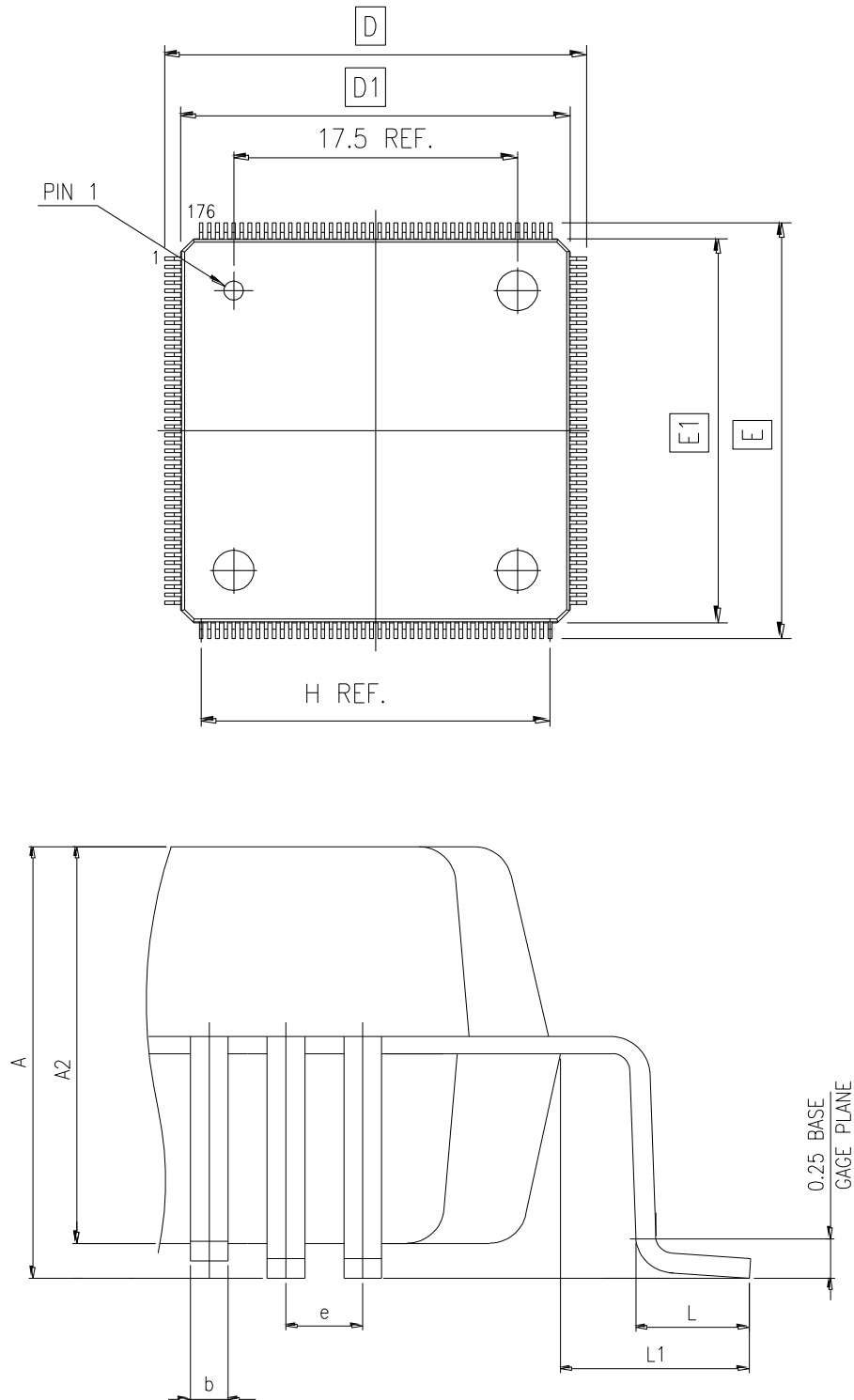
Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V _{DDA}	Analog power supply voltage	-	1.8	-	3.6	V
R _{LOAD}	Resistive load	The buffer is turned on	5	-	-	kΩ
R _O	Output impedance	The resistive load between DAC_OUT and V _{SS} is 1.5MΩ with buffer off	-	-	15	kΩ
C _{LOAD}	Capacitive load	Maximum capacitive load at DAC_OUT pin with buffer on	-	-	50	pF
DAC_OUT min	Low DAC_OUT voltage with buffer	Maximum output offset of DAC, (0x0E0) corresponding to 12-bit input code to V _{REF+} (0xF1C) at 3.6V and V _{REF+} (0x1C7) at 1.8V and (0xE38)	0.2	-	-	V
DAC_OUT max	Higher DAC_OUT voltage with buffer		-	-	V _{DDA} -0.2	V
DAC_OUT min	Low DAC_OUT voltage without buffer	Maximum output offset of DAC	-	0.5	-	mV
DAC_OUT max	Higher DAC_OUT voltage without buffer		-	-	V _{REF+} -1LSB	V
DNL	Differential non-linear error	Configured with 12-bit DAC	-	-	±2	LSB
INL	Integral non-linear error	Configured with 12-bit DAC	-	-	±4	LSB
Offset	Offset error	V _{REF+} =3.6V, configuring 12-bit DAC	-	-	±12	LSB
Gain error	Gain error	Configured with 12-bit DAC	-	-	±0.5	%

Note: The data are obtained from a comprehensive evaluation and are not tested in production.

6 Package information

6.1 LQFP176 package information

Figure 17 LQFP176 Package Diagram



- (1) The figure is not drawn to scale.
- (2) All pins should be soldered to the PCB.

Table 45 LQFP176 Package Data

S/N	SYM	DIMENSIONS	REMARKS
1	A	MAX. 1.600	OVERALL HEIGHT
2	A2	1.400±0.050	PKG THICKNESS
3	D	26.000±0.200	LEAD TIP TO TIP
4	D1	24.000±0.100	PKG LENGTH
5	E	26.000±0.200	LEAD TIP TO TIP
6	E1	24.000±0.100	PKG WIDTH
7	L	0.600±0.150	FOOT LENGTH
8	L1	1.000 REF	LEAD LENGTH
9	e	0.500 BASE	LEAD PITCH
10	H (REF)	(21.50)	CUM LEAD PITCH
11	b	0.22±0.050	LEAD WIDTH

Note: Dimensions are marked in millimeters.

Figure 18 LQFP176 -176 Pins, 24 x24mm Welding Layout Recommendations

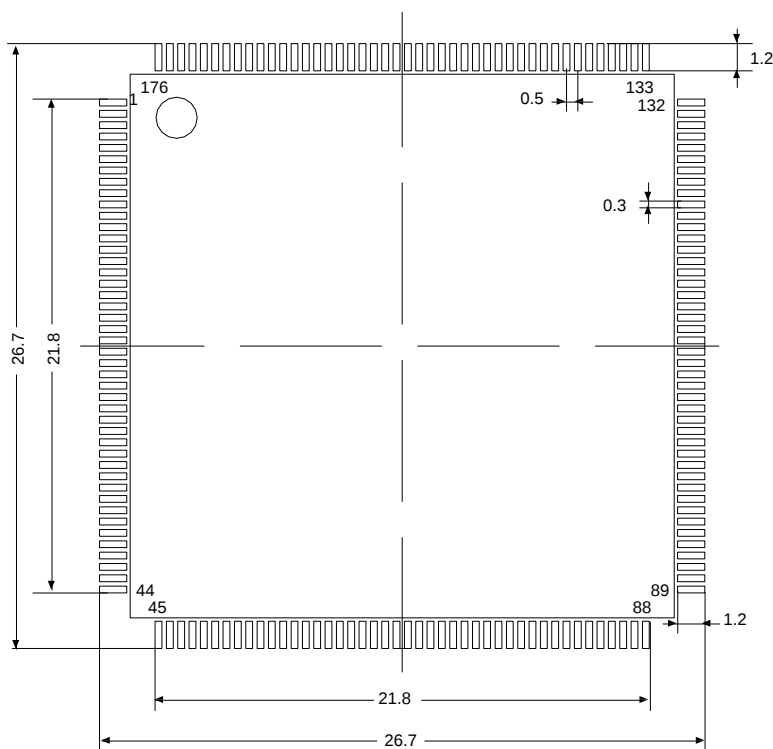
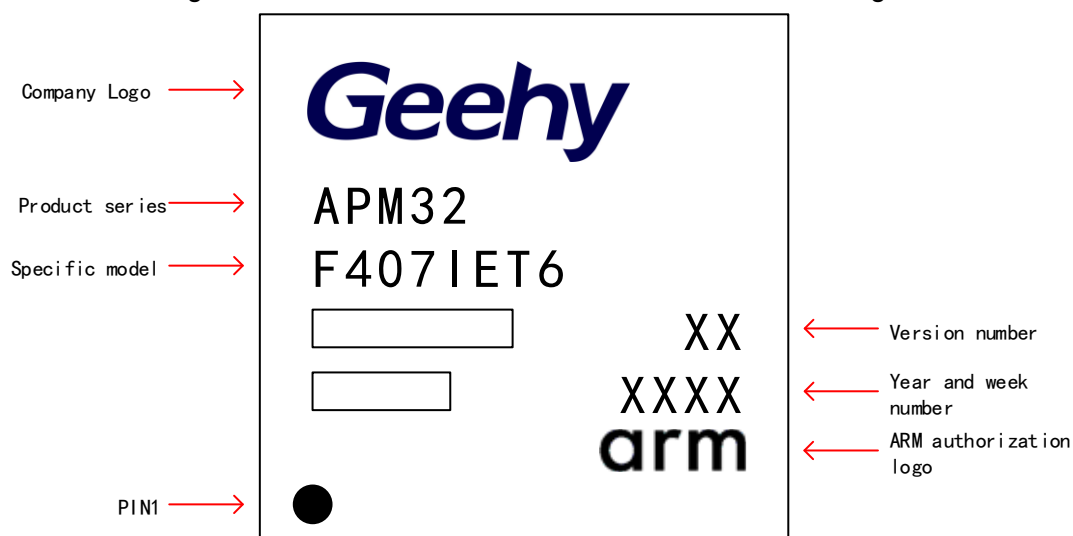
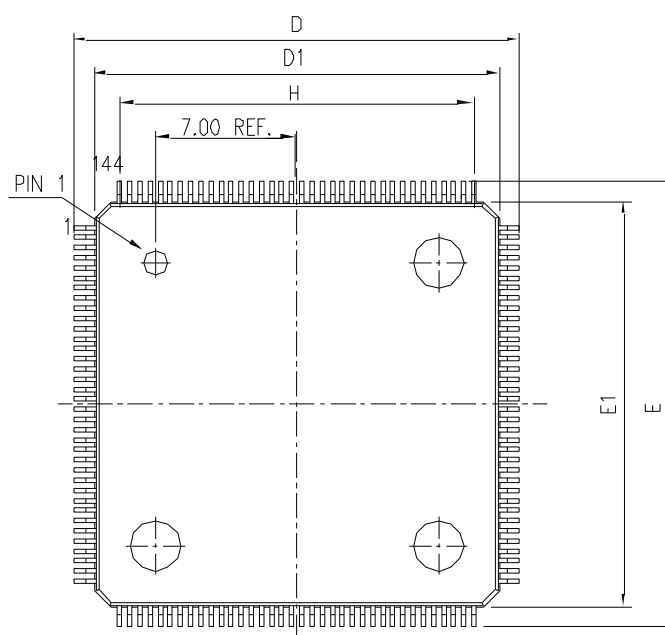


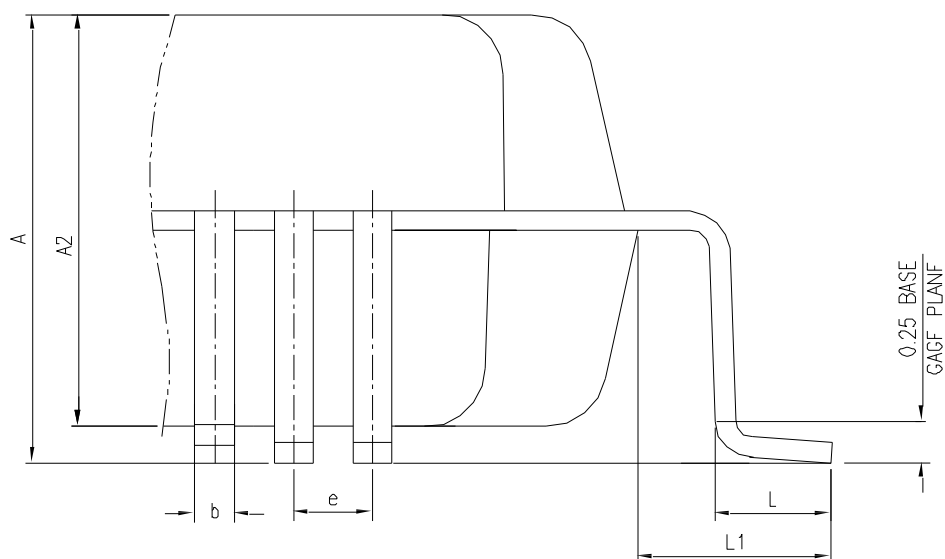
Figure 19 LQFP176 -176 Pins, 24 x24mm Schematic Diagram



6.2 LQFP144 package information

Figure 20 LQFP144 Package Diagram





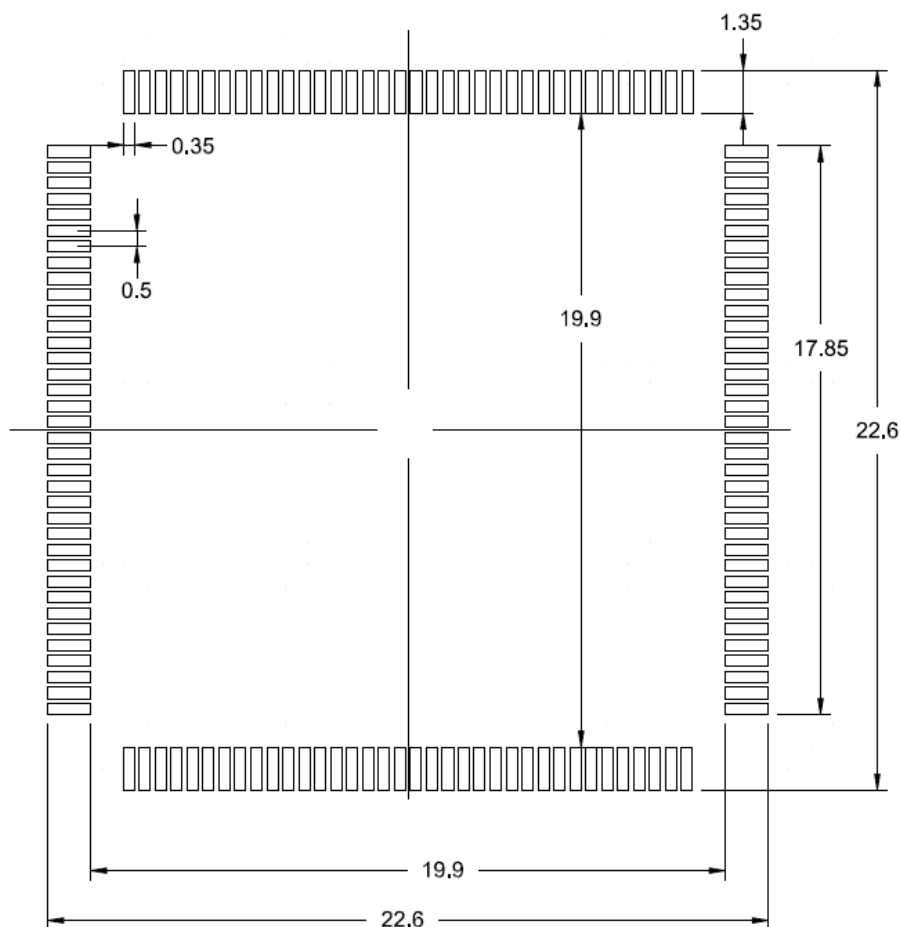
- (1) The figure is not drawn to scale.
- (2) All pins should be soldered to the PCB.

Table 46 LQFP144 Package Data

S/N	SYM	DIMENSIONS	REMARKS
1	A	MAX. 1.600	OVERALL HEIGHT
2	A2	1.400±0.050	PKG THICKNESS
3	D	22.000±0.200	LEAD TIP TO TIP
4	D1	20.000±0.100	PKG LENGTH
5	E	22.000±0.200	LEAD TIP TO TIP
6	E1	20.000±0.100	PKG WIDTH
7	L	0.600±0.150	FOOT LENGTH
8	L1	1.000 REF	LEAD LENGTH
9	e	0.500 BASE	LEAD PITCH
10	H (REF)	(17.50)	CUM LEAD PITCH
11	b	0.22±0.050	LEAD WIDTH

Note: Dimensions are marked in millimeters.

Figure 21 LQFP144-144 Pins, 20 x 20mm Welding Layout Recommendations



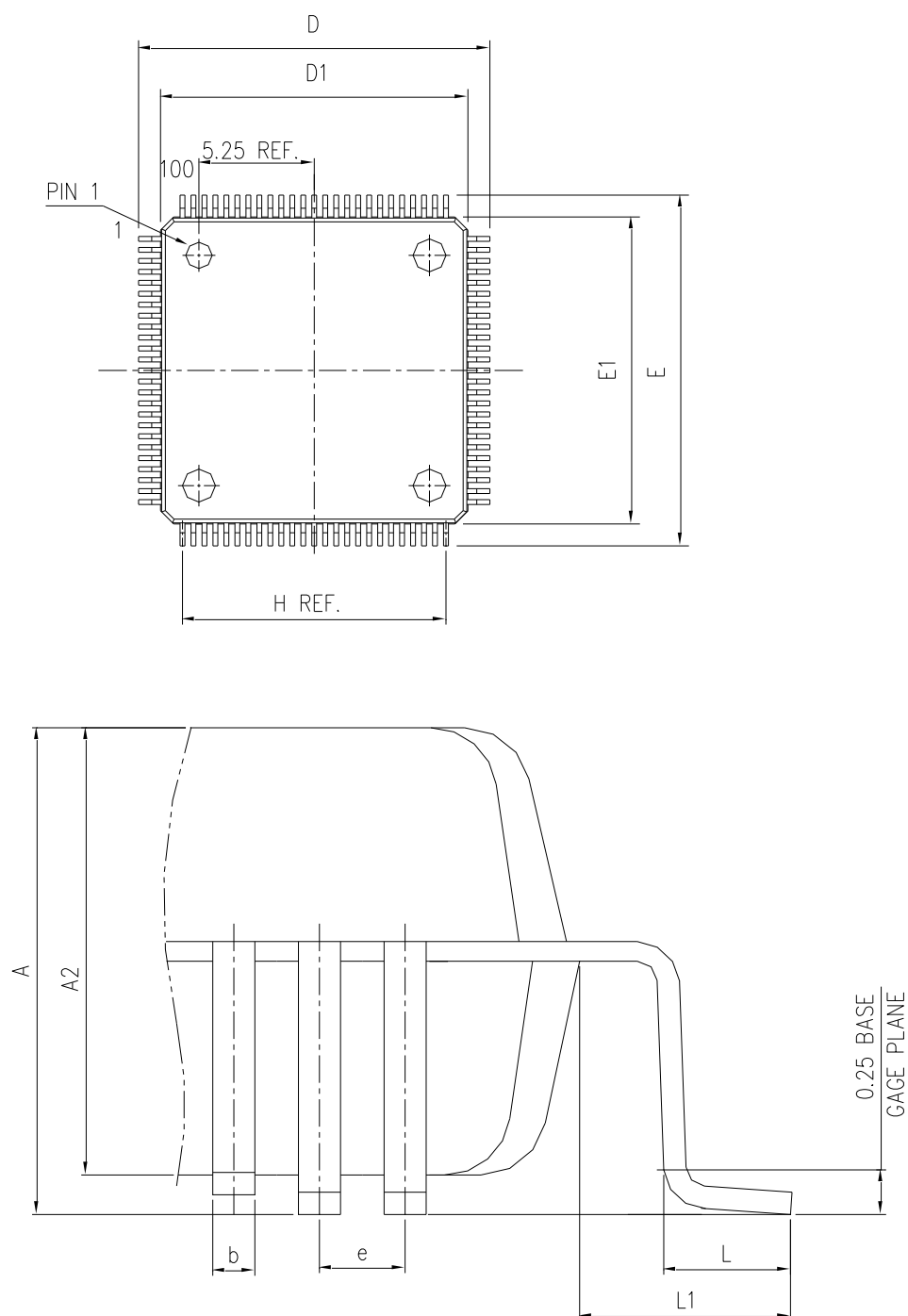
Note: Dimensions are marked in millimeters.

Figure 22 LQFP144 -144 Pins, 20 x20mm Schematic Diagram



6.3 LQFP100 package information

Figure 23 LQFP100 Package Diagram



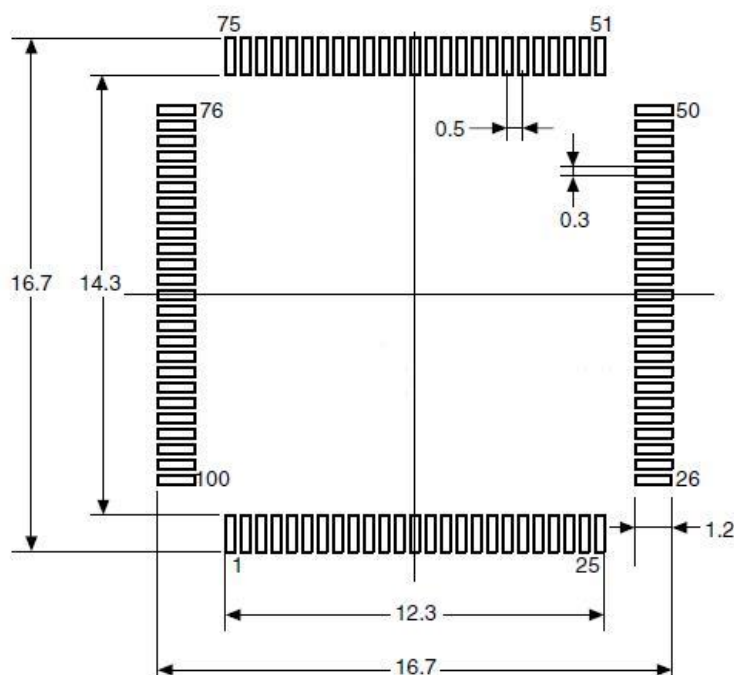
- (1) The figure is not drawn to scale.
- (2) All pins should be soldered to the PCB.

Table 47 LQFP100 Package Data

DIMENSION LIST (FOOTPRINT: 2.00)			
S/N	SYM	DIMENSIONS	REMARKS
1	A	MAX. 1.600	OVERALL HEIGHT
2	A2	1.400±0.050	PKG THICKNESS
3	D	16.000±0.200	LEAD TIP TO TIP
4	D1	14.000±0.100	PKG LENGTH
5	E	16.000±0.200	LEAD TIP TO TIP
6	E1	14.000±0.100	PKG WIDTH
7	L	0.600±0.150	FOOT LENGTH
8	L1	1.000 REF	LEAD LENGTH
9	e	0.500 BASE	LEAD PITCH
10	H (REF)	(12.00)	CUM LEAD PITCH
11	b	0.22±0.050	LEAD WIDTH

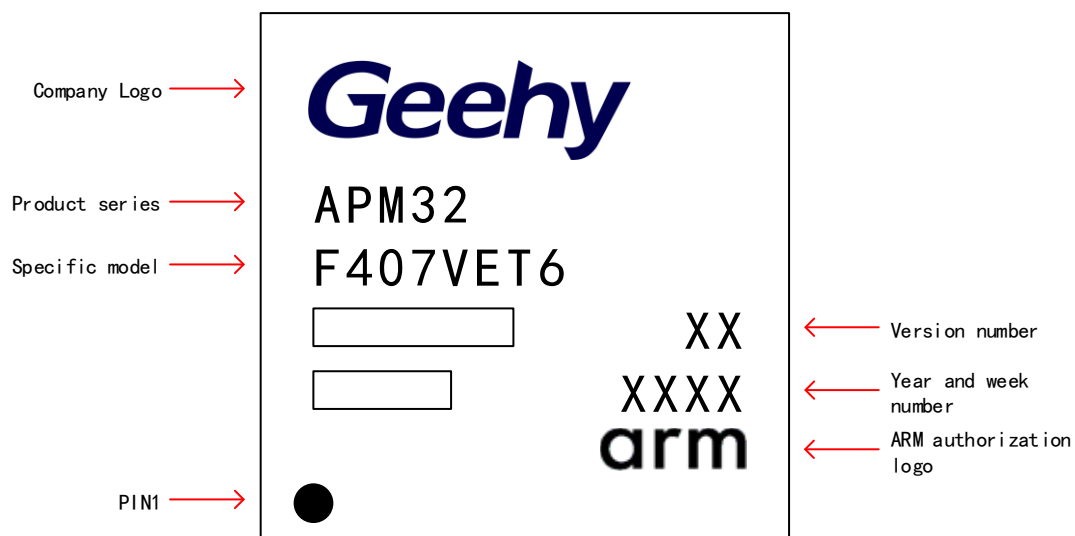
Note: Dimensions are marked in millimeters.

Figure 24 LQFP100 - 100 Pins, 14 x 14mm Welding Layout Recommendations



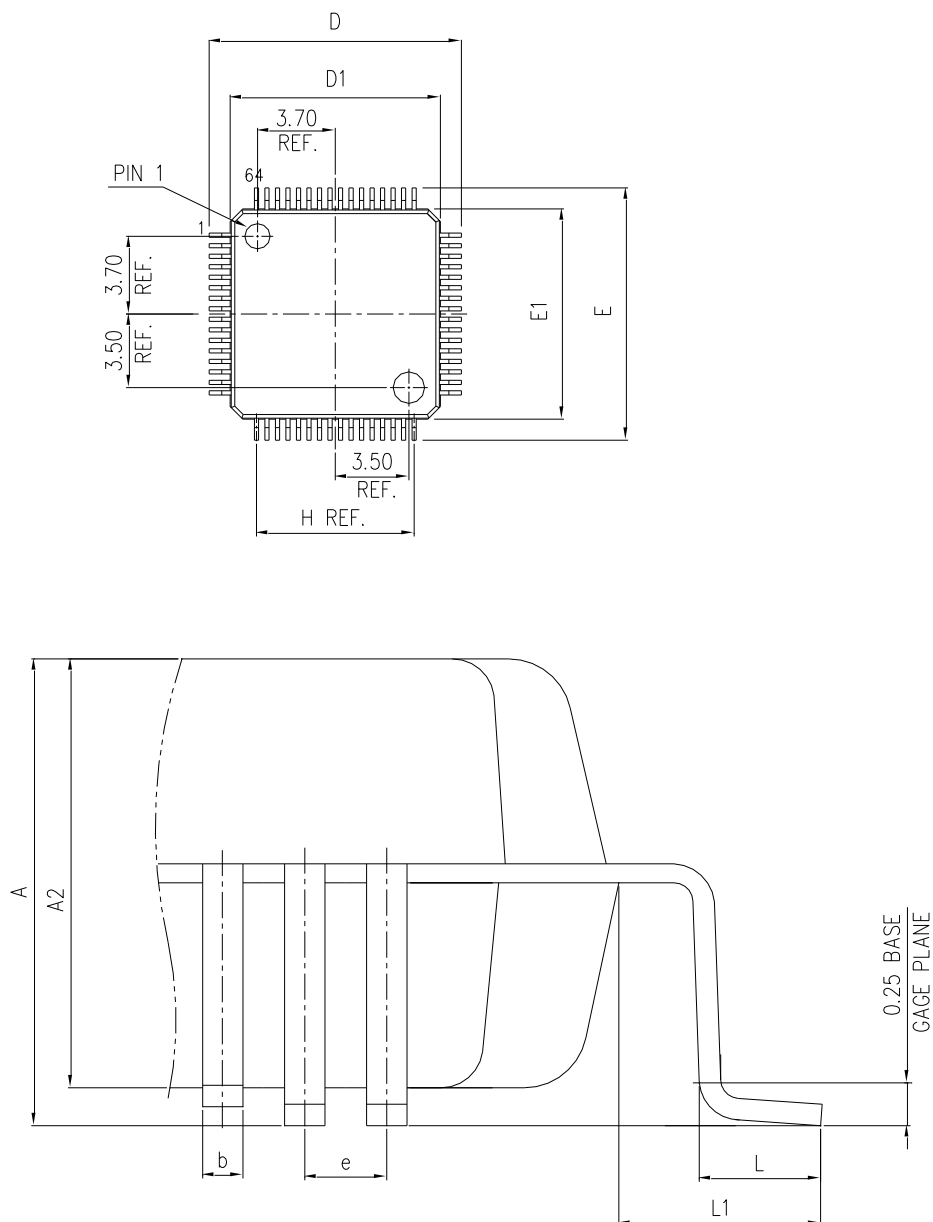
Note: Dimensions are marked in millimeters.

Figure 25 LQFP100 - 100 Pins, 14 x 14mm Package Schematic Diagram



6.4 LQFP64 package information

Figure 26 LQFP64 Package Diagram



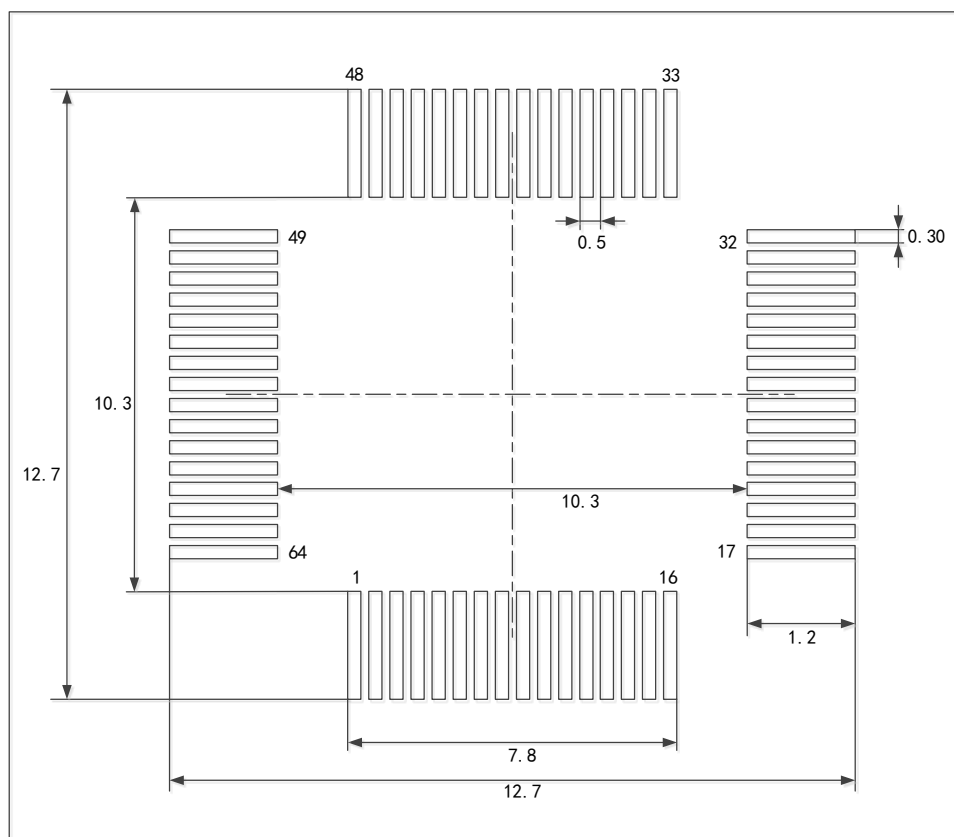
- (1) The figure is not drawn to scale.
- (2) All pins should be soldered to the PCB.

Table 48 LQFP64 Package Data

S/N	SYM	DIMENSIONS	REMARKS
1	A	MAX.1.600	OVERALLHEIGHT
2	A2	1.400±0.050	PKGTHICKNESS
3	D	12.000±0.200	LEADTIPTOTIP
4	D1	10.000±0.100	PKGLENGTH
5	E	12.000±0.200	LEADTIPTOTIP
6	E1	10.000±0.100	PKGWIDTH
7	L	0.600±0.150	FOOTLENGTH
8	L1	1.000REF.	LEADLENGTH
9	e	0.500BASE	LEADPITCH
10	H(REF.)	(7.500)	GUM.LEADPITCH
11	b	0.220±0.050	LEADWIDTH

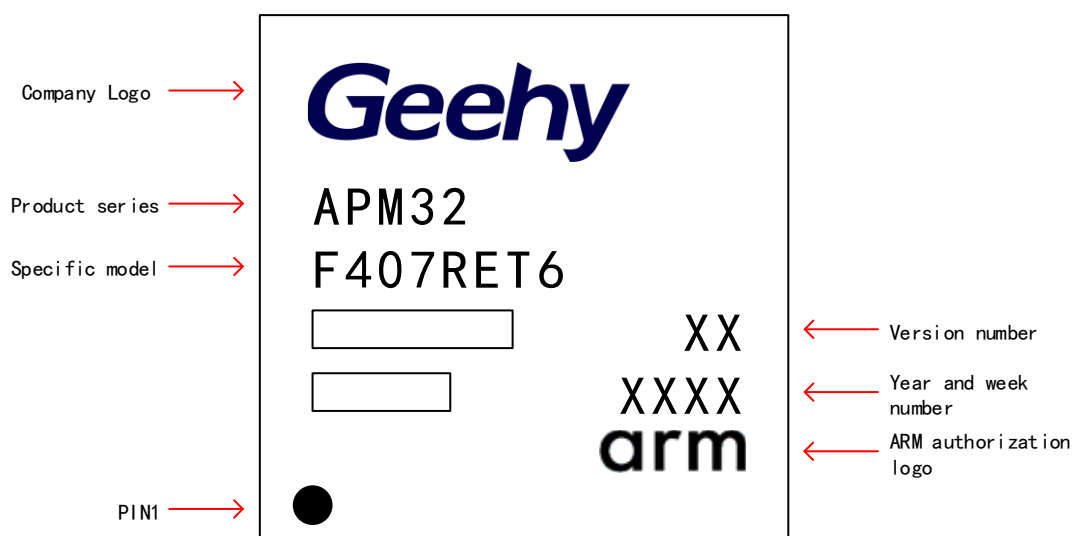
Note: Dimensions are marked in millimeters.

Figure 27 LQFP64 Welding Layout Recommendations



Note: Dimensions are marked in millimeters.

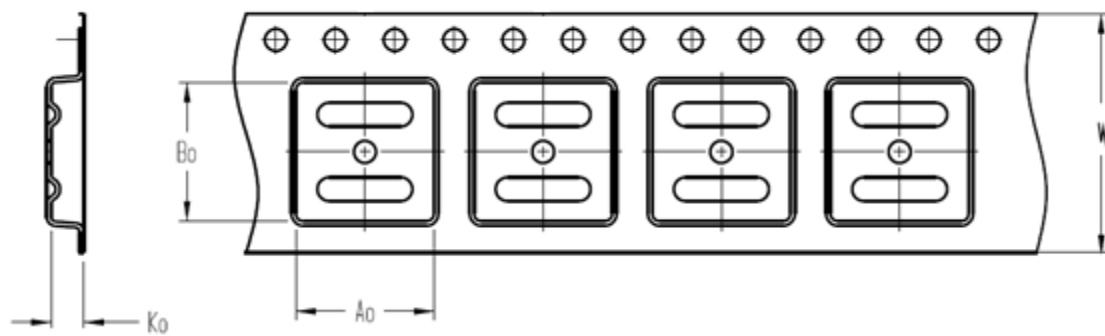
Figure 28 LQFP64 - 64 Pins, 10 x 10mm Package Schematic Diagram



7 Packaging Information

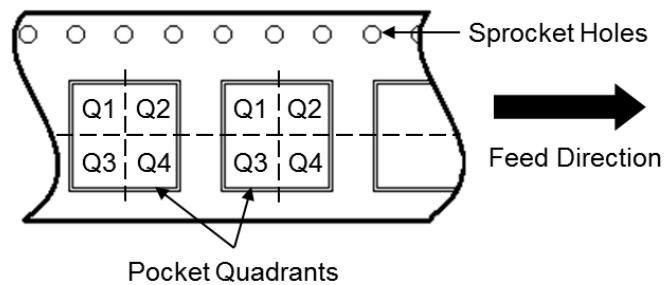
7.1 Reel Packaging

Figure 29 Specification Drawing of Reel Packaging

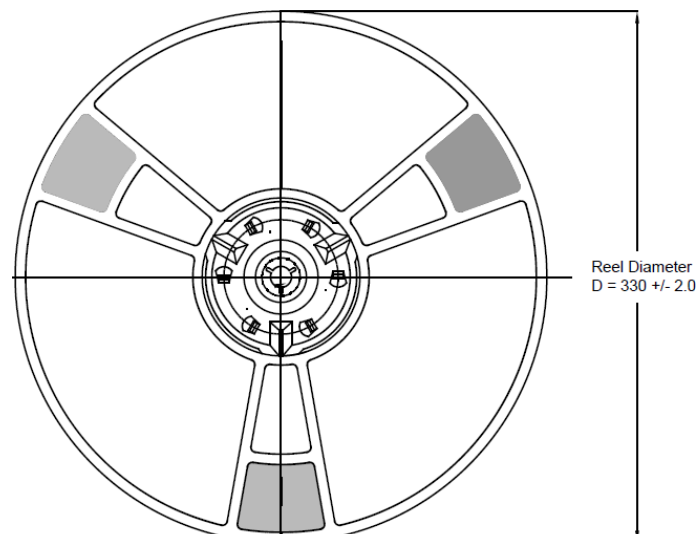


A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape

Quadrant Assignments for PIN1 Orientation in Tape



Reel Dimensions



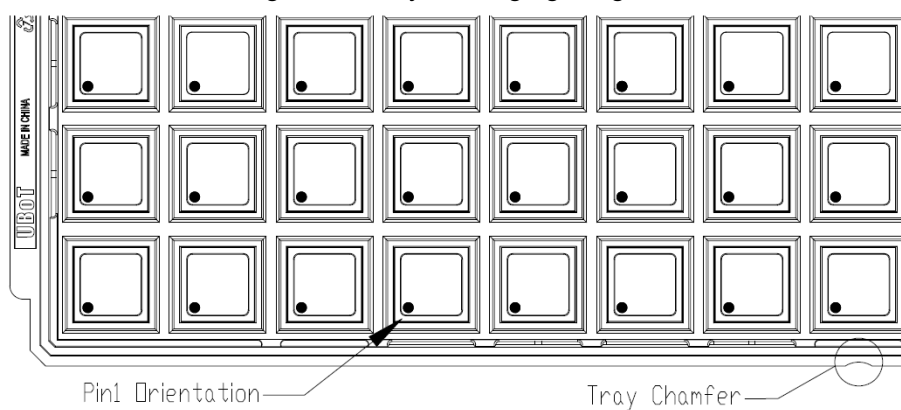
All photos are for reference only, and the appearance is subject to the product.

Table 49 Reel Packaging Parameter Specification Table

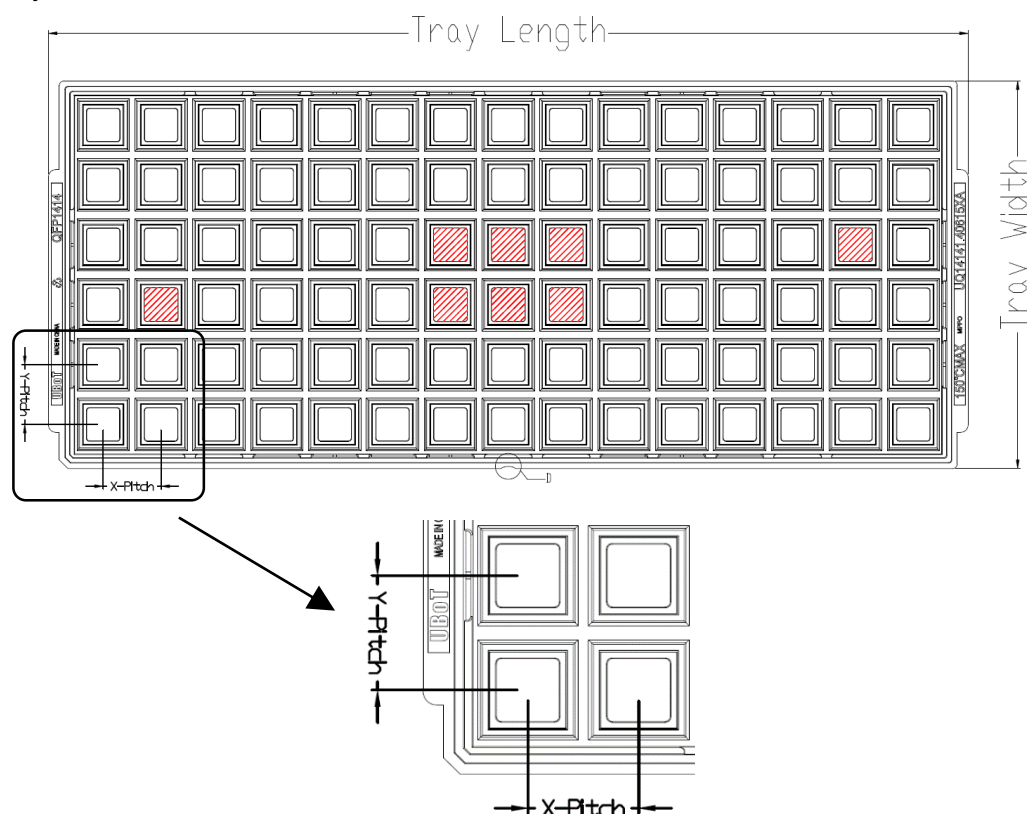
Device	Package Type	Pins	SPQ	Reel Diameter (mm)	A0 (mm)	B0 (mm)	K0 (mm)	W (mm)	Pin1 Quadrant
APM32F407RET6	LQFP	64	1000	330	12.35	12.35	2.2	24	Q1
APM32F407RGT6	LQFP	64	1000	330	12.35	12.35	2.2	24	Q1

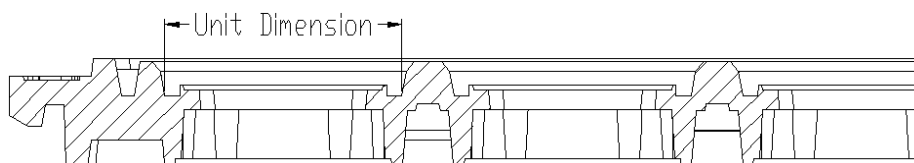
7.2 Tray packaging

Figure 30 Tray Packaging Diagram



Tray Dimensions





All photos are for reference only, and the appearance is subject to the product

Table 50 Tray Packaging Parameter Specification Table

Device	Package Type	Pins	SPQ	X-Dimension (mm)	Y-Dimension (mm)	X-Pitch (mm)	Y-Pitch (mm)	Tray Length (mm)	Tray Width (mm)
APM32F407IET6	LQFP	176	400	27	27	30.4	31.5	322.6	135.9
APM32F407IGT6	LQFP	176	400	27	27	30.4	31.5	322.6	135.9
APM32F407ZET6	LQFP	144	600	22.06	22.06	25.4	25.2	322.6	135.9
APM32F407ZGT6	LQFP	144	600	22.06	22.06	25.4	25.2	322.6	135.9
APM32F407VET6	LQFP	100	900	16.6	16.6	20.3	21	322.6	135.9
APM32F407VGT6	LQFP	100	900	16.6	16.6	20.3	21	322.6	135.9
APM32F407RET6	LQFP	64	1600	12.3	12.3	15.2	15.7	322.6	135.9
APM32F407RGT6	LQFP	64	1600	12.3	12.3	15.2	15.7	322.6	135.9

8 Ordering Information

Figure 31 APM32F407xExG Series Ordering Information Diagram

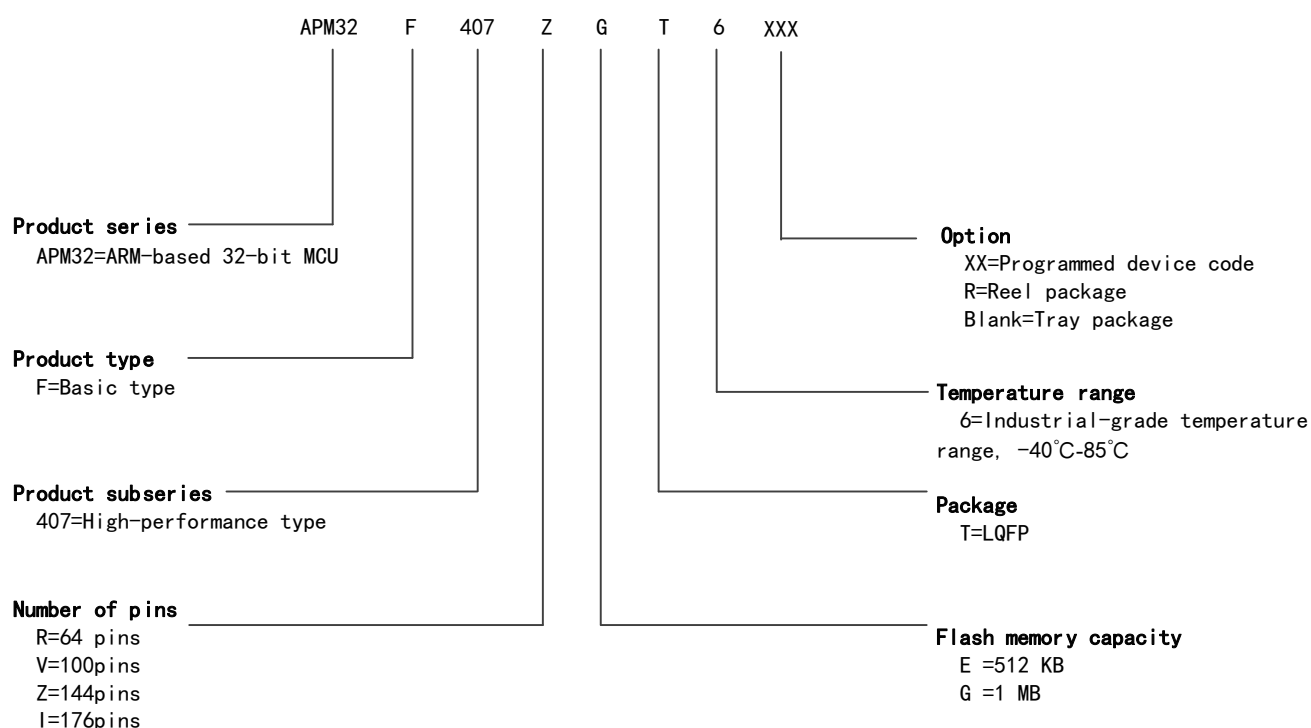


Table 51 Ordering Information Table

Order code	FLASH (KB)	SRAM (KB)	Package	SPQ	Range of temperature
APM32F407IGT6	1024	192+4	LQFP176	400	Industrial grade -40°C~85°C
APM32F407IET6	512	192+4	LQFP176	400	Industrial grade -40°C~85°C
APM32F407ZGT6	1024	192+4	LQFP144	600	Industrial grade -40°C~85°C
APM32F407ZET6	512	192+4	LQFP144	600	Industrial grade -40°C~85°C
APM32F407VGT6	1024	192+4	LQFP100	900	Industrial grade -40°C~85°C
APM32F407VET6	512	192+4	LQFP100	900	Industrial grade -40°C~85°C
APM32F407RGT6	1024	192+4	LQFP64	1600	Industrial grade -40°C~85°C
APM32F407RET6	512	192+4	LQFP64	1600	Industrial grade -40°C~85°C
APM32F407RGT6R	1024	192+4	LQFP64	1000	Industrial grade -40°C~85°C
APM32F407RET6R	512	192+4	LQFP64	1000	Industrial grade -40°C~85°C

9 Commonly Used Function Module Denomination

Table 52 Commonly Used Function Module Denomination

Chinese description	Abbreviations
Reset management unit	RMU
Clock management unit	CMU
Reset and clock management	RCM
External interrupt	EINT
General-purpose IO	GPIO
Multiplexing IO	AFIO
Wake-up controller	WUPT
Buzzer	BUZZER
Independent watchdog timer	IWDT
Window watchdog timer	WWDT
Timer	TMR
CRC controller	CRC
Power Management Unit	PMU
DMA controller	DMA
Analog-to-digital converter	ADC
Real-time clock	RTC
External memory controller	EMMC
Controller local area network	CAN
I2C Interface	I2C
Serial peripheral interface	SPI
Universal asynchronous transmitter receiver	UART
Universal synchronous and asynchronous transmitter receiver	USART
Flash interface control unit	FMC

10 Revision History

Table 53 Document Revision History

Date	Revision	Change
2021.10	1.0	New creation