

# SURFACE MOUNT 1.5 AMP HIGH VOLTAGE POSITIVE AND NEGATIVE ADJUSTABLE REGULATOR



**Dual Positive And Negative Adjustable  
High Voltage Regulators In Isolated  
Hermetic Surface Mount Package**

## FEATURES

- Similar To Industry Standard LT117AHV And LT137AHV
- Adjustable Output Voltage
- Built In Thermal Overload Protection
- Short Circuit Current Limiting
- Hermetic 6-Pin Metal Surface Mount Package
- Maximum Output Voltage Tolerance Is Guaranteed To  $\pm 1\%$
- Available Hi-Rel Screened

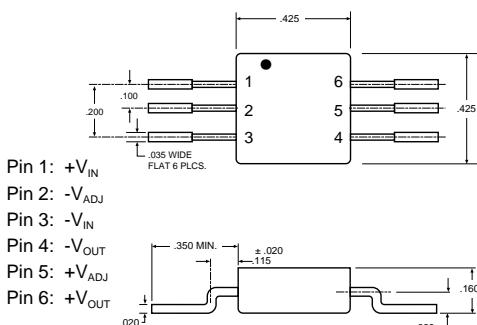
## DESCRIPTION

This device offers a positive and negative adjustable regulator in one hermetically sealed 6-pin surface mount package. All protective features are designed into the circuit, including thermal shutdown, current limiting, and safe-area control. With heat sinking, these devices can deliver up to 1.5 amps of output current. This device is ideally suited for military applications where small size and high reliability is required.

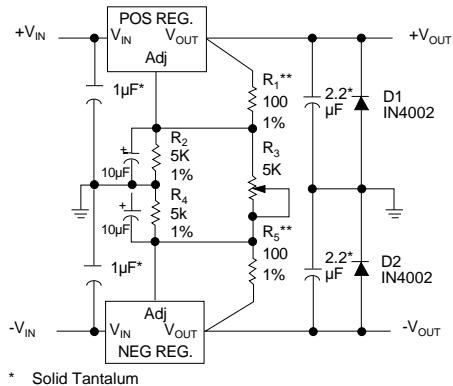
## ABSOLUTE MAXIMUM RATINGS

Input - Output Voltage Differential - LT117AHV Positive Regulator .....	+ 60 V
Input - Output Voltage Differential - LT137AHV Negative Regulator .....	- 50 V
Power Dissipation ( $P_d$ ) (Internally Limited) .....	20 W
Operating Junction Temperature Range .....	- 55°C to + 150°C
Storage Temperature Range .....	- 65°C to + 150°C
Lead Temperature (Soldering 10 seconds) .....	300°C
Thermal Resistance:	
$\theta_{JC}$ .....	4.2°C/W
$\theta_{JA}$ .....	42°C/W
Maximum Output Current .....	1.5 A

## MECHANICAL OUTLINE



## DUAL TRACKING SUPPLY $\pm 1.25V$ TO $\pm 20V$



3.5

**ELECTRICAL CHARACTERISTICS** Positive Regulator -55°C T<sub>A</sub> 125°C, I<sub>L</sub> = 8mA (unless otherwise specified)

Parameter	Symbol	Test Conditions	Min.	Max.	Unit
Reference Voltage	V <sub>REF</sub>	V <sub>DIFF</sub> = 3.0V, T <sub>A</sub> = 25°C V <sub>DIFF</sub> = 3.3V V <sub>DIFF</sub> = 40V V <sub>DIFF</sub> = 60V	• 1.238 • 1.225 • 1.225 • 1.225	1.262 1.270 1.270 1.270	V
Line Regulation (Note 1)	R <sub>LINE</sub>	3.0V V <sub>DIFF</sub> 40V, V <sub>out</sub> = V <sub>ref</sub> , T <sub>A</sub> = 25°C 3.3V V <sub>DIFF</sub> 40V, V <sub>out</sub> = V <sub>ref</sub> 40V V <sub>DIFF</sub> 60V, V <sub>out</sub> = V <sub>ref</sub> , T <sub>A</sub> = 25°C 40V V <sub>DIFF</sub> 60V, V <sub>out</sub> = V <sub>ref</sub>	• -4.5 • -9 • -5 • -10	4.5 -9 5 10	mV
Load Regulation (Note 1)	R <sub>LOAD</sub>	V <sub>DIFF</sub> = 3.0V, 10mA I <sub>L</sub> 1.5A, T <sub>A</sub> = 25°C V <sub>DIFF</sub> = 3.3V, 10mA I <sub>L</sub> 1.5A V <sub>DIFF</sub> = 40V, 10mA I <sub>L</sub> 300mA, T <sub>A</sub> = 25°C V <sub>DIFF</sub> = 40V, 10mA I <sub>L</sub> 195mA V <sub>DIFF</sub> = 60V, 10mA I <sub>L</sub> 30mA	• -15 • -15 • -15 • -15	15 15 15 15	mV
Thermal Regulation	V <sub>RTH</sub>	V <sub>in</sub> = 14.6V, I <sub>L</sub> = 1.5A P <sub>d</sub> = 20 Watts, t = 20 ms, T <sub>A</sub> = 25°C		-5 5	mV
Ripple Rejection (Note 2)	R <sub>N</sub>	f = 120 Hz, V <sub>out</sub> = V <sub>ref</sub> C <sub>Adj</sub> = 10 μF, I <sub>out</sub> = 100 mA	• 66		dB
Adjustment Pin Current	I <sub>Adj</sub>	V <sub>DIFF</sub> = 3.0V, T <sub>A</sub> = 25°C V <sub>DIFF</sub> = 3.3V V <sub>DIFF</sub> = 40V V <sub>DIFF</sub> = 60V	• 100 • 100 • 100 • 100	100 100 100 100	μA
Adjustment Pin	I <sub>Adj</sub>	V <sub>DIFF</sub> = 3.0V, 10mA I <sub>L</sub> 1.5A, T <sub>A</sub> = 25°C		-5 5	
Current Change	I <sub>L</sub>	V <sub>DIFF</sub> = 3.3V, 10mA I <sub>L</sub> 1.5A V <sub>DIFF</sub> = 40V, 10mA I <sub>L</sub> 300mA, T <sub>A</sub> = 25°C V <sub>DIFF</sub> = 40V, 10mA I <sub>L</sub> 195mA 3.0V V <sub>DIFF</sub> 40V, T <sub>A</sub> = 25°C 3.3V V <sub>DIFF</sub> 40V 3.3V V <sub>DIFF</sub> 60V	• -5 • -5 • -5 • -5	5 5 5 5	μA
Minimum Load Current	I <sub>Lmin</sub>	V <sub>DIFF</sub> = 3.0V, V <sub>out</sub> = 1.4V (forced) V <sub>DIFF</sub> = 3.3V, V <sub>out</sub> = 1.4V (forced) V <sub>DIFF</sub> = 40V, V <sub>out</sub> = 1.4V (forced) V <sub>DIFF</sub> = 60V, V <sub>out</sub> = 1.4V (forced)	• 5.0 • 5.0 • 5.0 • 7.0	5.0 5.0 5.0 7.0	mA
Current Limit (Note 2)	I <sub>CL</sub>	V <sub>DIFF</sub> = 5V V <sub>DIFF</sub> = 40V, T <sub>A</sub> = 25°C V <sub>DIFF</sub> = 60V, T <sub>A</sub> = 25°C	• 1.5 • 0.3 • 0.05	3.5 1.5 0.50	A

**ELECTRICAL CHARACTERISTICS** Positive Regulator -55°C T<sub>A</sub> 125°C, I<sub>L</sub> = 8mA (unless otherwise specified)

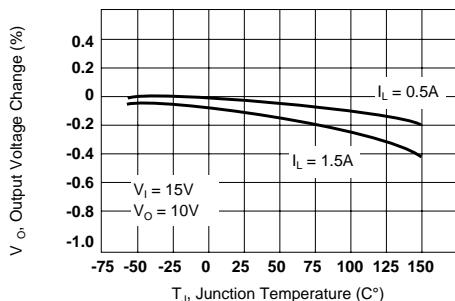
Parameter	Symbol	Test Conditions	Min.	Max.	Unit
Reference Voltage	V <sub>REF</sub>	V <sub>DIFF</sub> = 3.0V, T <sub>A</sub> = 25°C V <sub>DIFF</sub> = 3.0V V <sub>DIFF</sub> = 50V, T <sub>A</sub> = 25°C V <sub>DIFF</sub> = 50V	• -1.262 • -1.28 • -1.28 • -1.28	-1.238 -1.22 -1.22 -1.22	V
Line Regulation (Note 1)	R <sub>LINE</sub>	3.0V V <sub>DIFF</sub> 50V, T <sub>A</sub> = 25°C	• -6 • -20	6 20	mV
Load Regulation (Note 1)	R <sub>LOAD</sub>	V <sub>DIFF</sub> = 50V, 8mA I <sub>L</sub> 110mA, T <sub>A</sub> = 25°C V <sub>DIFF</sub> = 5V, 8mA I <sub>L</sub> 1.5A, T <sub>A</sub> = 25°C	• -25 • -25 • -50	25 25 50	mV
Thermal Regulation	V <sub>RTH</sub>	V <sub>in</sub> = -14.6V, I <sub>L</sub> = 1.5A P <sub>d</sub> = 20 Watts, t = 10 ms, T <sub>A</sub> = 25°C		-5 5	mV
Ripple Rejection (Note 2)	R <sub>N</sub>	f = 120 Hz, V <sub>out</sub> = V <sub>ref</sub> C <sub>Adj</sub> = 10 μF, I <sub>out</sub> = 100 mA	• 66		dB
Adjustment Pin Current	I <sub>Adj</sub>	V <sub>DIFF</sub> = 3.0V V <sub>DIFF</sub> = 40V V <sub>DIFF</sub> = 50V	• 100 • 100 • 100	100 100 100	μA
Adjustment Pin Current Change	I <sub>Adj</sub>	V <sub>DIFF</sub> = 5V, 8mA I <sub>out</sub> 1.5A 3V V <sub>DIFF</sub> 50V, I <sub>L</sub> 8mA	• -5 • -6	5 6	μA
Minimum Load Current	I <sub>Lmin</sub>	V <sub>DIFF</sub> = 3.0V, V <sub>out</sub> = -1.4V (forced) V <sub>DIFF</sub> = 10V, V <sub>out</sub> = -1.4V (forced) V <sub>DIFF</sub> = 40V, V <sub>out</sub> = -1.4V (forced) V <sub>DIFF</sub> = 50V, V <sub>out</sub> = -1.4V (forced)	• 3.0 • 3.0 • 5.0 • 5.0	3.0 3.0 5.0 5.0	mA
Current Limit (Note 2)	I <sub>CL</sub>	V <sub>DIFF</sub> = 5V V <sub>DIFF</sub> = 50V, T <sub>A</sub> = 25°C	• 1.5 • 0.2	3.5 1.0	A

**Notes for both Positive and Negative Regulators Characteristics:**

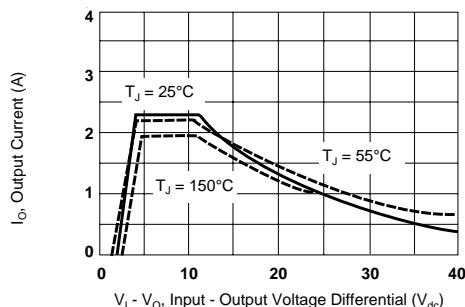
- Load and Line Regulation are specified at a constant junction temperature. Pulse testing with low duty cycle is used. Changes in output voltage due to heating effects must be taken into account separately.
- If not tested, shall be guaranteed to the specified limits.
- The • denotes the specifications which apply over the full operating temperature range.

## POSITIVE REGULATOR - TYPICAL PERFORMANCE CHARACTERISTICS

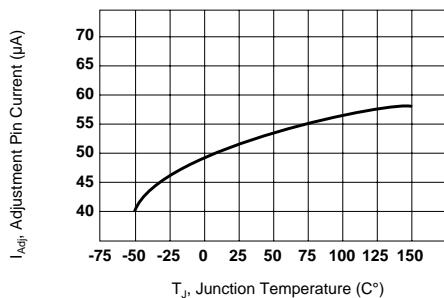
## LOAD REGULATION



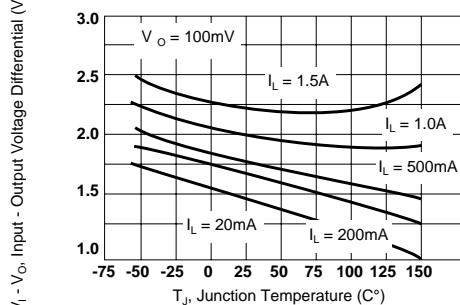
## CURRENT LIMIT



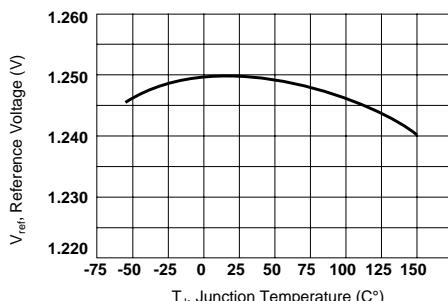
## ADJUSTMENT PIN CURRENT



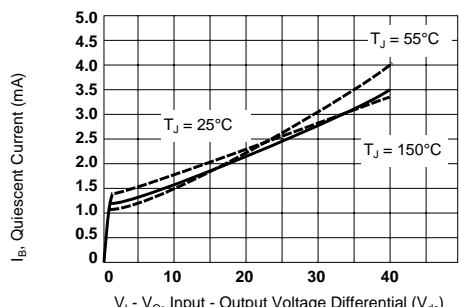
## DROPOUT VOLTAGE



## TEMPERATURE STABILITY



## MINIMUM OPERATING CURRENT



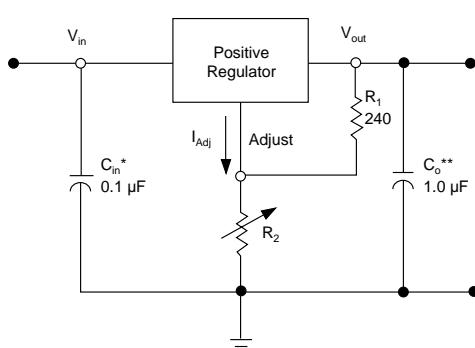
## STANDARD APPLICATION

\* C<sub>in</sub> is required if regulator is located an appreciable distance from power supply filter.

\*\* C<sub>o</sub> is not needed for stability, however it does improve transient response.

$$V_{out} = 1.25 V \left(1 + \frac{R_2}{R_1}\right) + I_{Adj} R_2$$

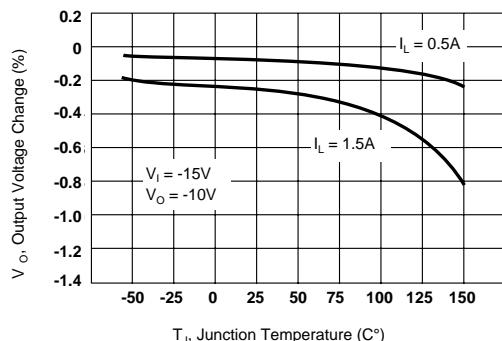
Since I<sub>Adj</sub> is controlled to less than 100 μA, the error associated with this term is negligible in most applications.



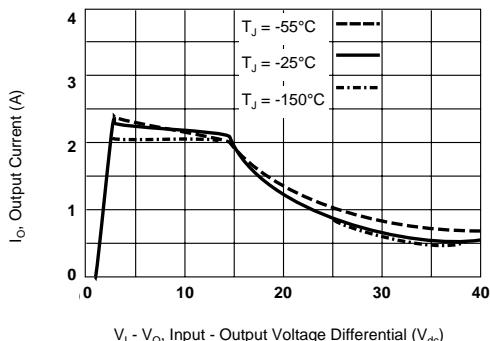
3.5

## NEGATIVE REGULATOR - TYPICAL PERFORMANCE CHARACTERISTICS

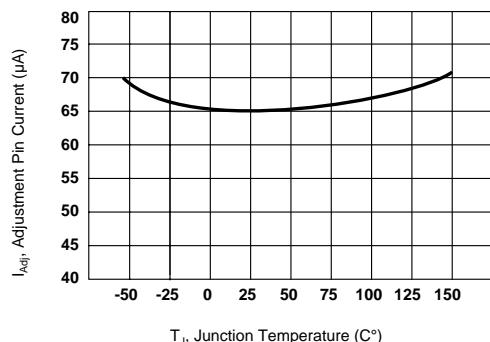
## LOAD REGULATION



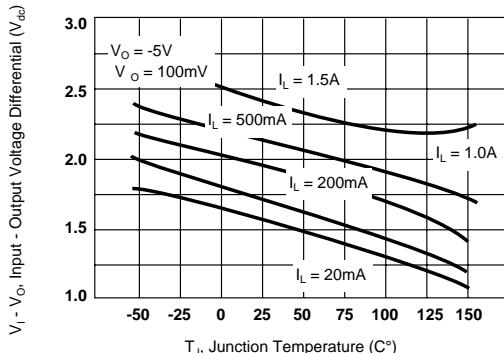
## CURRENT LIMIT



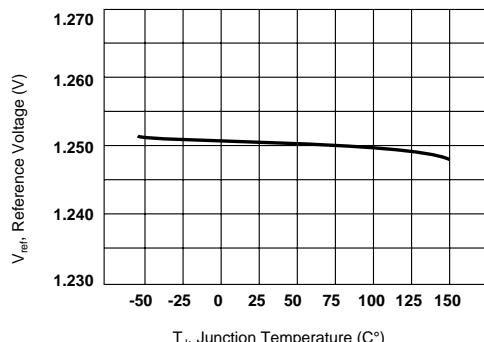
## ADJUSTMENT PIN CURRENT



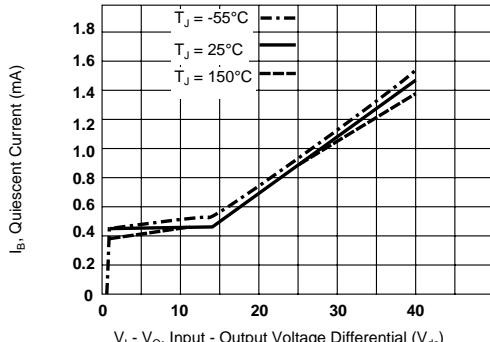
## DROPOUT VOLTAGE



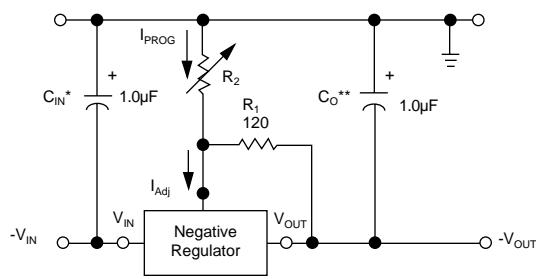
## TEMPERATURE STABILITY



## MINIMUM OPERATING CURRENT



3.5



## STANDARD APPLICATION

\*  $C_{\text{in}}$  is required if regulator is located an appreciable distance from power supply filter.

\*\*  $C_{\text{o}}$  is not needed for stability, however it does improve transient response.

$$V_{\text{out}} = -1.25 \text{ V} \left( 1 + \frac{R_2}{R_1} \right) + I_{\text{Adj}} R_2$$

Since  $I_{\text{Adj}}$  is controlled to less than 100  $\mu\text{A}$ , the error associated with this term is negligible in most applications.