



MX27L4000

4M-BIT [512K x8] LOW VOLTAGE OPERATION CMOS EPROM

FEATURES

- 512K x 8 organization
- Wide voltage range, 2.7V to 3.6V
- +12.5V programming voltage
- Fast access time: 200/250ns
- Totally static operation
- Completely TTL compatible
- Operating current: 20mA @ 3.6V, 5MHz
- Standby current: 50uA
- Package type:
 - 32 pin plastic DIP
 - 32 pin PLCC/SOP
 - 32pin TSOP

GENERAL DESCRIPTION

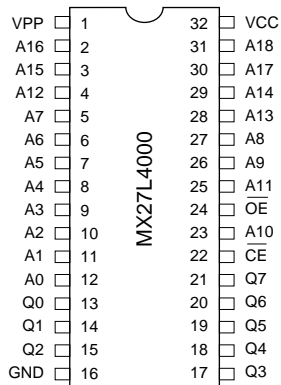
The MX27L4000 is a 4M-bit, ultraviolet Erasable Programmable Read Only Memory. It is organized as 512K words by 8 bits per word, operates from a single +3 volt supply, has a static standby mode, and features fast single address location programming. All programming signals are TTL levels, requiring a single pulse. For programming outside from the system, existing EPROM

programmers may be used. The MX27L4000 supports a intelligent fast programming algorithm which can result in programming time of less than two minutes.

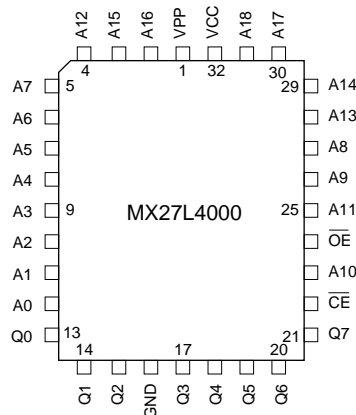
This EPROM is packaged in industry standard 32 pin dual-in-line packages, 32 lead PLCC, 32 lead SOP, and 32 lead TSOP(I) packages.

PIN CONFIGURATIONS

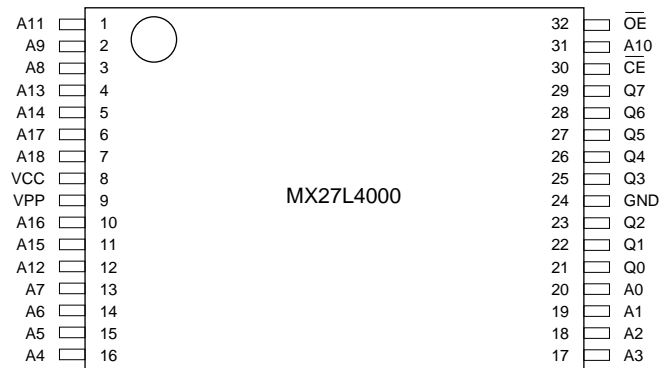
32 PDIP/SOP



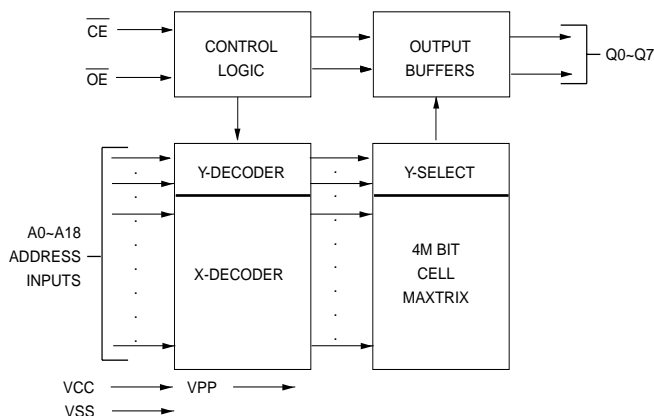
32 PLCC



32TSOP



BLOCK DIAGRAM



PIN DESCRIPTION

SYMBOL	PIN NAME
A0-A18	Address Input
Q0-Q7	Data Input/Output
CE	Chip Enable Input
OE	Output Enable Input
VPP	Program Supply Voltage
VCC	Power Supply Pin
GND	Ground Pin

FUNCTIONAL DESCRIPTION

THE PROGRAMMING OF THE MX27L4000

When the MX27L4000 is delivered, or it is erased, the chip has all 4M bits in the "ONE" or HIGH state. "ZEROS" are loaded into the MX27L4000 through the procedure of programming.

For programming, the data to be programmed is applied with 8 bits in parallel to the data pins.

VCC must be applied simultaneously or before VPP, and removed simultaneously or after VPP. When programming an MXIC EPROM, a 0.1uF capacitor is required across Vpp and ground to suppress spurious voltage transients which may damage the device.

FAST PROGRAMMING

The device is set up in the fast programming mode when the programming voltage $VPP = 12.75V$ is applied, with $VCC = 6.25V$ and $OE = VIH$ (Algorithm is shown in Figure 1). The programming is achieved by applying a single TTL low level 100us pulse to the CE input after addresses and data line are stable. If the data is not verified, an additional pulse is applied for a maximum of 25 pulses. This process is repeated while sequencing through each address of the device. When the programming mode is completed, the data in all address is verified at $VCC = VPP = 5V \pm 10\%$.

PROGRAM INHIBIT MODE

Programming of multiple MX27L4000s in parallel with different data is also easily accomplished by using the Program Inhibit Mode. Except for CE and OE, all like inputs of the parallel MX27L4000 may be common. A TTL low-level program pulse applied to an MX27L4000 CE input with $VPP = 12.5 \pm 0.5V$ and CE LOW will program that MX27L4000. A high-level CE input inhibits the other MX27L4000s from being programmed.

PROGRAM VERIFY MODE

Verification should be performed on the programmed bits to determine that they were correctly programmed. The verification should be performed with OE and CE at VIL, and VPP at its programming voltage.

AUTO IDENTIFY MODE

The auto identify mode allows the reading out of a binary code from an EPROM that will identify its manufacturer and device type. This mode is intended for use by programming equipment for the purpose of automatically matching the device to be programmed with its corresponding programming algorithm. This mode is functional in the $25^{\circ}C \pm 5^{\circ}C$ ambient temperature range that is required when programming the MX27L4000.

To activate this mode, the programming equipment must force $12.0 \pm 0.5V$ on address line A9 of the device. Two identifier bytes may then be sequenced from the device outputs by toggling address line A0 from VIL to VIH. All other address lines must be held at VIL during auto identify mode.

Byte 0 (A0 = VIL) represents the manufacturer code, and byte 1 (A0 = VIH), the device identifier code. For the MX27L4000, these two identifier bytes are given in the Mode Select Table. All identifiers for manufacturer and device codes will possess odd parity, with the MSB (Q7) defined as the parity bit.

READ MODE

The MX27L4000 has two control functions, both of which must be logically satisfied in order to obtain data at the outputs. Chip Enable (CE) is the power control and should be used for device selection. Output Enable (OE) is the output control and should be used to gate data to the output pins, independent of device selection. Assuming that addresses are stable, address access time (tACC) is equal to the delay from CE to output (tCE). Data is available at the outputs tOE after the falling edge of OE's, assuming that CE has been LOW and addresses have been stable for at least tACC - tOE.

STANDBY MODE

The MX27L4000 has a CMOS standby mode which reduces the maximum VCC current to 50 uA. It is placed in CMOS standby when CE is at $VCC \pm 0.3V$. The MX27L4000 also has a TTL-standby mode which reduces the maximum VCC current to 0.25 mA. It is placed in TTL-standby when CE is at VIH. When in standby mode, the outputs are in a high-impedance state, independent of the OE input.

TWO-LINE OUTPUT CONTROL FUNCTION

To accommodate multiple memory connections, a two-line control function is provided to allow for:

1. Low memory power dissipation,
2. Assurance that output bus contention will not occur.

It is recommended that \overline{CE} be decoded and used as the primary device-selecting function, while \overline{OE} be made a common connection to all devices in the array and connected to the READ line from the system control bus. This assures that all deselected memory devices are in their low-power standby mode and that the output pins are only active when data is desired from a particular memory device.

SYSTEM CONSIDERATIONS

During the switch between active and standby conditions, transient current peaks are produced on the rising and falling edges of Chip Enable. The magnitude of these transient current peaks is dependent on the output capacitance loading of the device. At a minimum, a 0.1 μ F ceramic capacitor (high frequency, low inherent inductance) should be used on each device between VCC and GND to minimize transient effects. In addition, to overcome the voltage drop caused by the inductive effects of the printed circuit board traces on EPROM arrays, a 4.7 μ F bulk electrolytic capacitor should be used between VCC and GND for each eight devices. The location of the capacitor should be close to where the power supply is connected to the array.

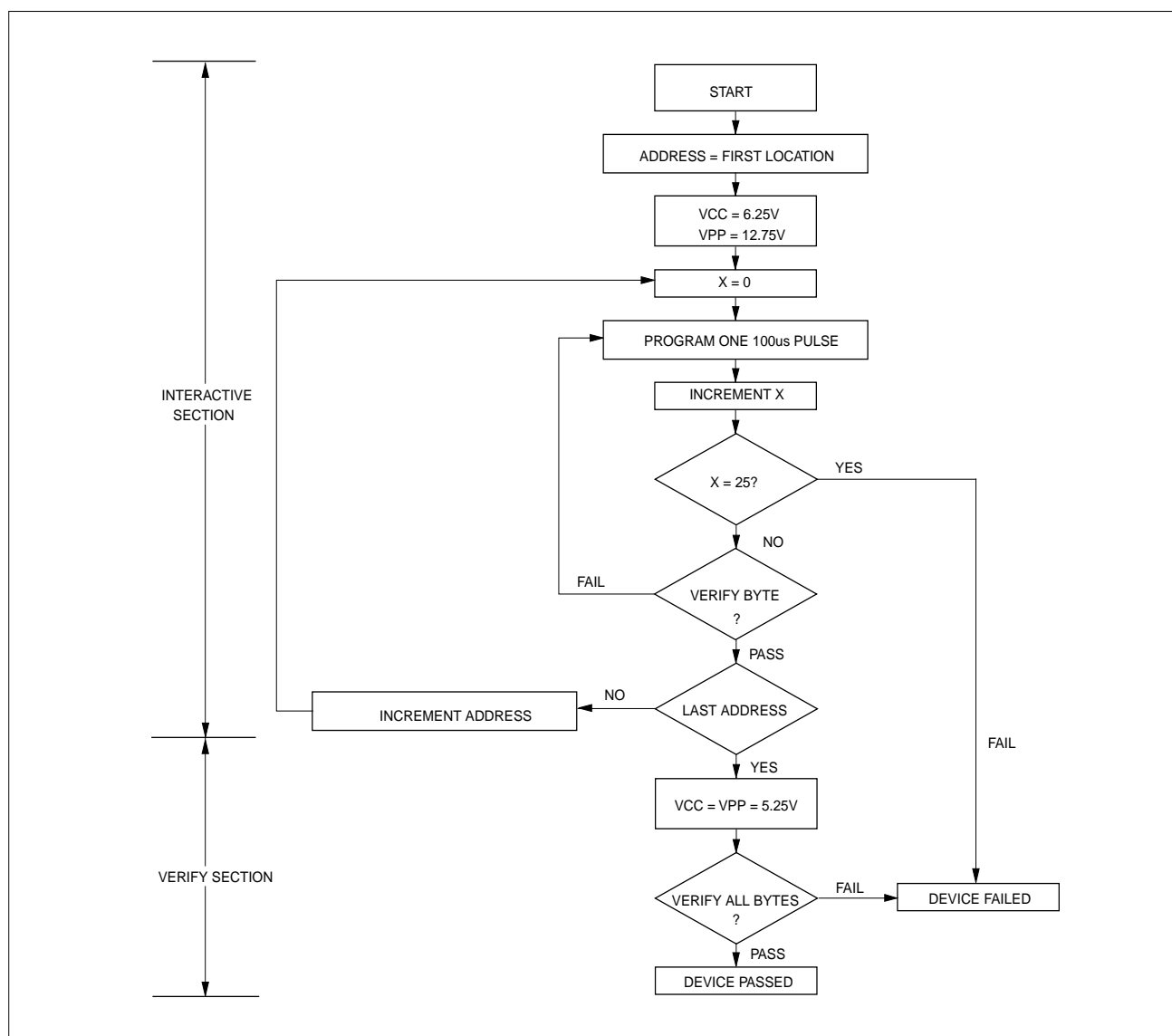
MODE SELECT TABLE

MODE	PINS					
	\overline{CE}	\overline{OE}	A0	A9	VPP	OUTPUTS
Read	VIL	VIL	X	X	VCC	DOUT
Output Disable	VIL	VIH	X	X	VCC	High Z
Standby (TTL)	VIH	X	X	X	VCC	High Z
Standby (CMOS)	VCC \pm 0.3V	X	X	X	VCC	High Z
Program	VIL	VIH	X	X	VPP	DIN
Program Verify	VIH	VIL	X	X	VPP	DOUT
Program Inhibit	VIH	VIH	X	X	VPP	High Z
Manufacturer Code(3)	VIL	VIL	VIL	VH	VCC	C2H
Device Code(3)	VIL	VIL	VIH	VH	VCC	40H

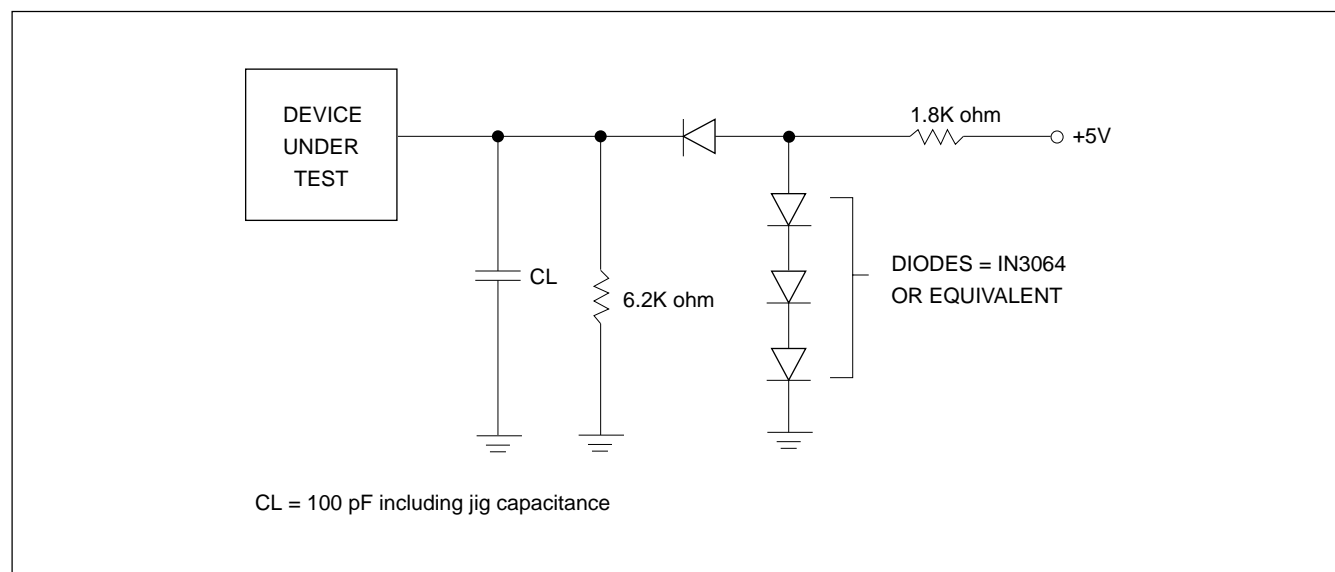
NOTES: 1. VH = 12.0 V \pm 0.5 V
2. X = Either VIH or VIL

3. A1 - A8 = A10 - A18 = VIL(For auto select)
4. See DC Programming Characteristics for VPP voltage during programming.

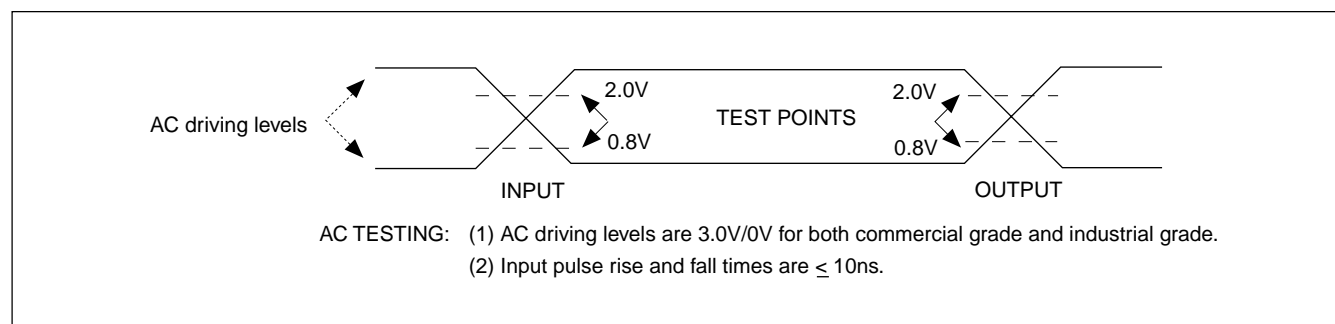
FIGURE 1. FAST PROGRAMMING FLOW CHART



SWITCHING TEST CIRCUITS



SWITCHING TEST WAVEFORMS



ABSOLUTE MAXIMUM RATINGS

RATING	VALUE
Ambient Operating Temperature	-40°C to 85°C
Storage Temperature	-65°C to 125°C
Applied Input Voltage	-0.5V to 7.0V
Applied Output Voltage	-0.5V to VCC + 0.5V
VCC to Ground Potential	-0.5V to 7.0V
V9 & VPP	-0.5V to 13.5V

NOTICE:

Stresses greater than those listed under ABSOLUTE MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended period may affect reliability.

NOTICE:

Specifications contained within the following tables are subject to change.

DC/AC Operating Conditions for Read Operation

MX27L4000			
		-20	-25
Operating Temperature	Commercial	0°C to 70°C	0°C to 70°C
	Industrial	-40°C to 85°C	-40°C to 85°C
VCC Power Supply		2.7V to 3.6V	2.7V to 3.6V

DC CHARACTERISTICS

SYMBOL	PARAMETER	MIN.	MAX.	UNIT	CONDITIONS
VOH	Output High Voltage	VCC -0.3		V	IOH = -100uA, VCC = 3.0V
VOL	Output Low Voltage		0.3	V	IOL = 2.1mA, VCC = 3.0V
VIH	Input High Voltage	2.0	VCC + 0.5	V	
VIL	Input Low Voltage	-0.3	0.6	V	
ILI	Input Leakage Current	-10	10	uA	VIN = 0 to 3.6V
ILO	Output Leakage Current	-10	10	uA	VOU = 0 to 3.6V
ICC3	VCC Power-Down Current		50	uA	$\overline{CE} = VCC \pm 0.3V$
ICC2	VCC Standby Current		0.25	mA	$\overline{CE} = VIH$
ICC1	VCC Active Current		20	mA	$\overline{CE} = VIL$, f=5MHz, Iout = 0mA, VCC =3.6V
IPP	VPP Supply Current Read		10	uA	$\overline{CE} = \overline{OE} = VIL$, VPP = VCC

CAPACITANCE TA = 25°C, f = 1.0 MHz (Sampled only)

SYMBOL	PARAMETER	TYP.	MAX.	UNIT	CONDITIONS
CIN	Input Capacitance	8	12	pF	VIN = 0V
COUT	Output Capacitance	8	12	pF	VOUT = 0V
CVPP	VPP Capacitance	18	25	pF	VPP = 0V

AC CHARACTERISTICS

SYMBOL	PARAMETER	27L4000-20		27CL4000-25		UNIT	CONDITIONS
		MIN.	MAX.	MIN.	MAX.		
tACC	Address to Output Delay		200		250	ns	$\overline{CE} = \overline{OE} = VIL$
tCE	Chip Enable to Output Delay		200		250	ns	$\overline{OE} = VIL$
tOE	Output Enable to Output Delay		100		120	ns	$\overline{CE} = VIL$
tDF	\overline{OE} High to Output Float, or \overline{CE} High to Output Float	0	60	0	70	ns	
tOH	Output Hold from Address, \overline{CE} or \overline{OE} which ever occurred first	0		0		ns	

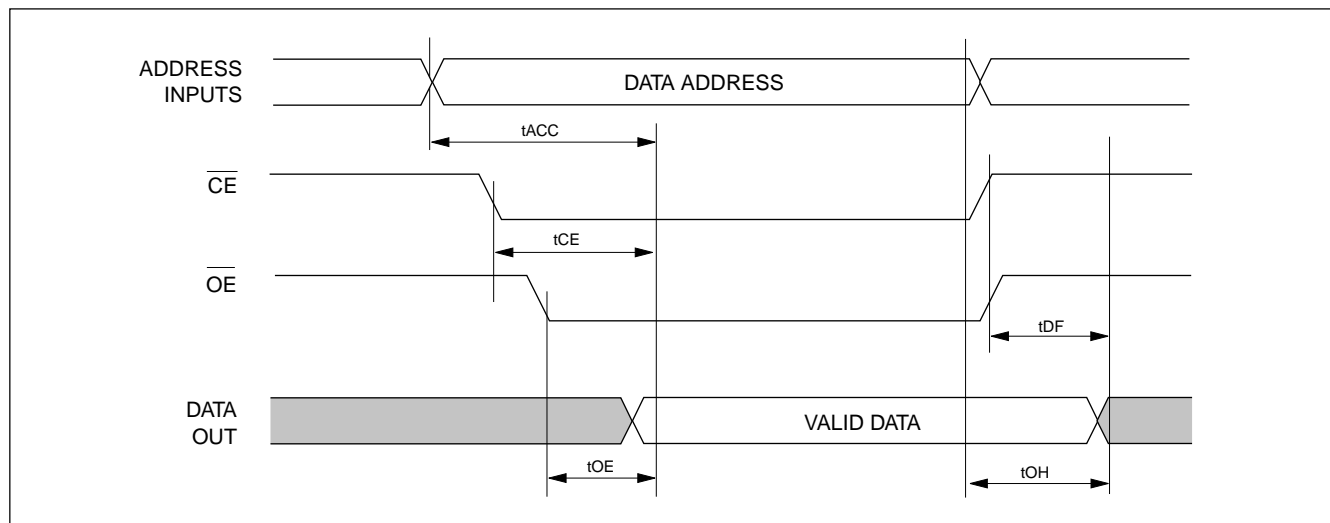
DC PROGRAMMING CHARACTERISTICS TA = 25°C ± 5°C

SYMBOL	PARAMETER	MIN.	MAX.	UNIT	CONDITIONS
VOH	Output High Voltage	2.4		V	IOH = -0.40mA
VOL	Output Low Voltage		0.4	V	IOL = 2.1mA
VIH	Input High Voltage	2.0	VCC + 0.5	V	
VIL	Input Low Voltage	-0.3	0.8	V	
ILI	Input Leakage Current	-10	10	uA	VIN = 0 to 3.6V
VH	A9 Auto Select Voltage	11.5	12.5	V	
ICC3	VCC Supply Current (Program & Verify)		50	mA	
IPP2	VPP Supply Current(Program)		30	mA	$\overline{CE} = VIL, \overline{OE} = VIH$
VCC1	Fast Programming Supply Voltage	6.00	6.50	V	
VPP1	Fast Programming Voltage	12.5	13.0	V	

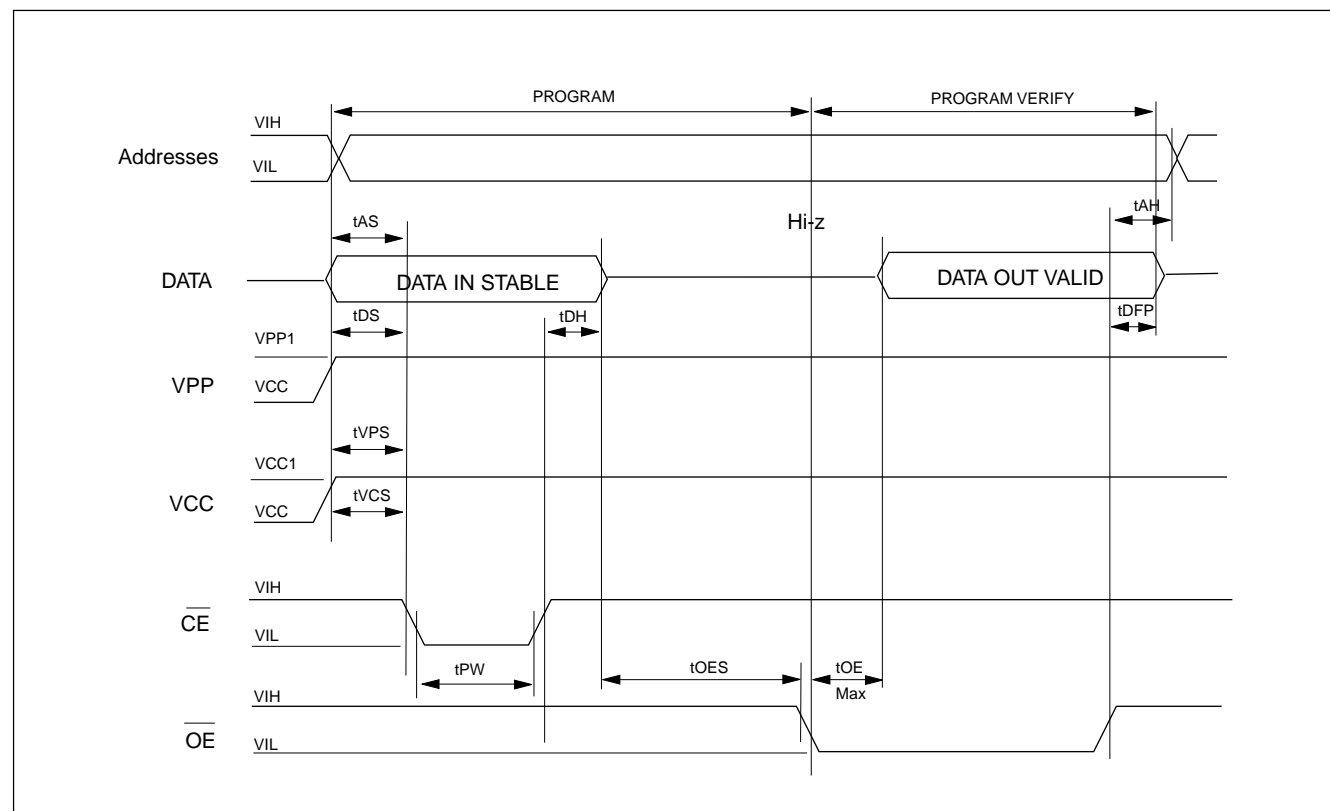
AC PROGRAMMING CHARACTERISTICS TA = 25°C ± 5°C

SYMBOL	PARAMETER	MIN.	MAX.	UNIT	CONDITIONS
tAS	Address Setup Time	2.0		us	
tOES	\overline{OE} Setup Time	2.0		us	
tDS	Data Setup Time	2.0		us	
tAH	Address Hold Time	0		us	
tDH	Data Hold Time	2.0		us	
tDFP	Output Enable to Output Float Delay	0	130	ns	
tVPS	VPP Setup Time	2.0		us	
tPW	PGM Program Pulse Width	95	105	us	
tVCS	VCC Setup Time	2.0		us	
tOE	Data valid from \overline{OE}		150	ns	

WAVEFORMS READ CYCLE



FAST PROGRAMMING ALGORITHM WAVEFORM



ORDERING INFORMATION**PLASTIC PACKAGE**

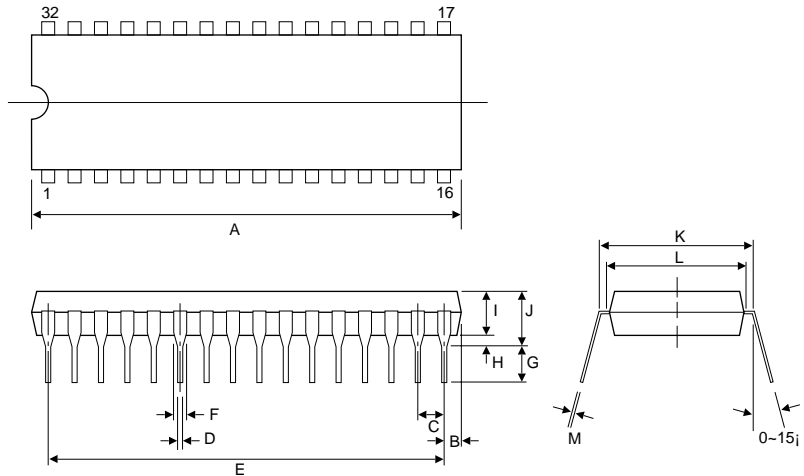
PART NO.	ACCESS TIME(ns)	OPERATING CURRENT MAX.(mA)	STANDBY CURRENT MAX.(uA)	OPERATING TEMPERATURE	PACKAGE
MX27L4000PC-25	250	20	50	0°C to 70°C	32 Pin DIP
MX27L4000PC-20	200	20	50	0°C to 70°C	32 Pin DIP
MX27L4000QC-25	250	20	50	0°C to 70°C	32 Pin PLCC
MX27L4000QC-20	200	20	50	0°C to 70°C	32 Pin PLCC
MX27L4000MC-25	250	20	50	0°C to 70°C	32 Pin SOP
MX27L4000MC-20	200	20	50	0°C to 70°C	32 Pin SOP
MX27L4000TC-25	250	20	50	0°C to 70°C	32 Pin TSOP
MX27L4000TC-20	200	20	50	0°C to 70°C	32 Pin TSOP
MX27L4000PI-25	250	20	50	-40°C to 85°C	32 Pin DIP
MX27L4000PI-20	200	20	50	-40°C to 85°C	32 Pin DIP
MX27L4000QI-25	250	20	50	-40°C to 85°C	32 Pin PLCC
MX27L4000QI-20	200	20	50	-40°C to 85°C	32 Pin PLCC
MX27L4000MI-25	250	20	50	-40°C to 85°C	32 Pin SOP
MX27L4000MI-20	200	20	50	-40°C to 85°C	32 Pin SOP
MX27L4000TI-25	250	20	50	-40°C to 85°C	32 Pin TSOP
MX27L4000TI-20	200	20	50	-40°C to 85°C	32 Pin TSOP

PACKAGE INFORMATION

32-PIN PLASTIC DIP(600 mil)

ITEM	MILLIMETERS	INCHES
A	42.13 max.	1.660 max.
B	1.90 [REF]	.075 [REF]
C	2.54 [TP]	.100 [TP]
D	.46 [Typ.]	.018 [Typ.]
E	38.07	1.500
F	1.27 [Typ.]	.050 [Typ.]
G	3.30 ± .25	.130 ± .010
H	.51 [REF]	.020 [REF]
I	3.94 ± .25	.155 ± .010
J	5.33 max.	.210 max.
K	15.22 ± .25	.600 ± .010
L	13.97 ± .25	.550 ± .010
M	.25 [Typ.]	.010 [Typ.]

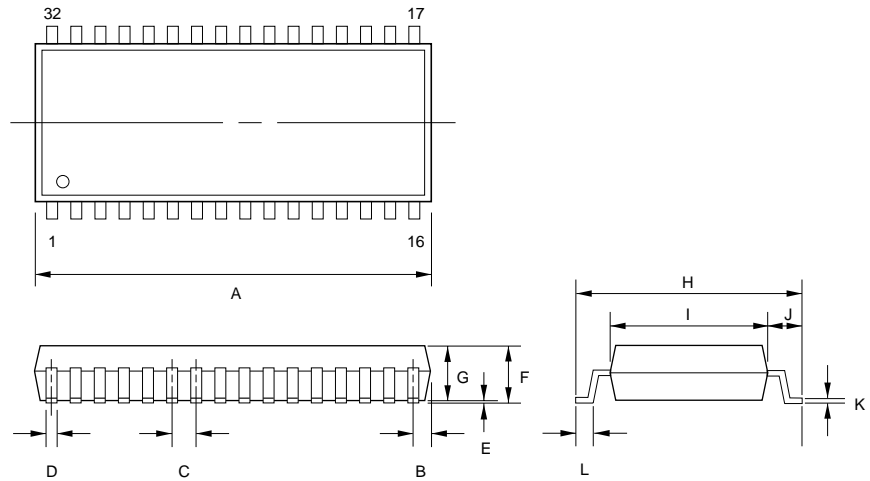
NOTE: Each lead centerline is located within .25 mm[.01 inch] of its true position [TP] at maximum material condition.



32-PIN PLASTIC SOP (450 mil)

ITEM	MILLIMETERS	INCHES
A	20.95 max.	.825 max.
B	1.00 [REF]	.039 [REF]
C	1.27 [TP]	.050 [TP]
D	.40 [Typ.]	.016 [Typ.]
E	.05 min.	.002 min.
F	3.05 max.	.120 max.
G	2.69 ± .13	.106 ± .005
H	14.12 ± .25	.556 ± .010
I	11.30 ± .13	.445 ± .005
J	1.42	.056
K	.20 [Typ.]	.008 [Typ.]
L	.79	.031

NOTE: Each lead centerline is located within .25 mm[.01 inch] of its true position [TP] at maximum material condition.

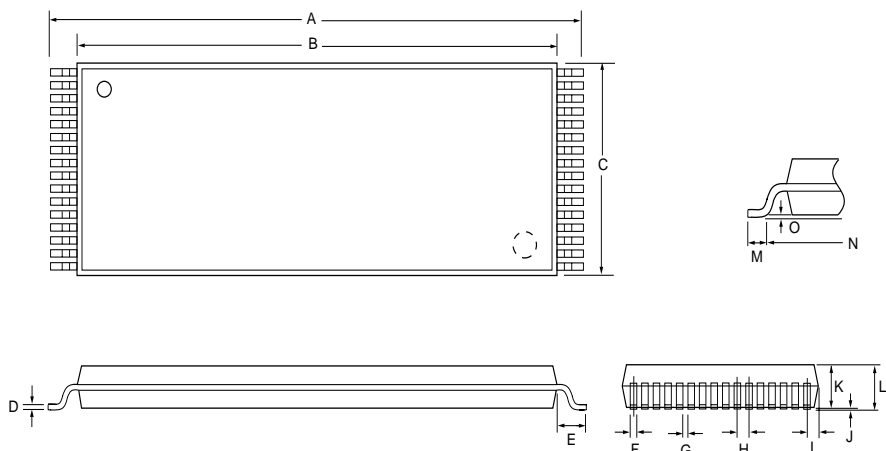


PACKAGE INFORMATION(Continued)

32-PIN PLASTIC TSOP

ITEM	MILLIMETERS	INCHES
A	20.0 ± .20	.078 ± .006
B	18.40 ± .10	.724 ± .004
C	8.20 max.	.323 max.
D	0.15 [Typ.]	.006 [Typ.]
E	.80 [Typ.]	.031 [Typ.]
F	.20 ± .10	.008 ± .004
G	.30 ± .10	.012 ± .004
H	.50 [Typ.]	.020 [Typ.]
I	.45 max.	.018 max.
J	0 ~ .20	0 ~ .008
K	1.00 ± .10	.039 ± .004
L	1.27 max.	.050 max.
M	.50	.020
N	0 ~ 5°	.500

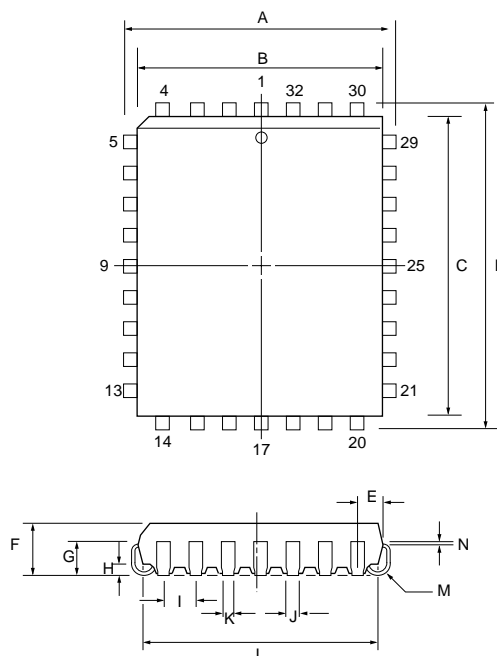
NOTE: Each lead centerline is located within .25 mm[.01 inch] of its true position [TP] at maximum material condition.



32-PIN PLASTIC LEADED CHIP CARRIER (PLCC)

ITEM	MILLIMETERS	INCHES
A	12.44 ± .13	.490 ± .005
B	11.50 ± .13	.453 ± .005
C	14.04 ± .13	.553 ± .005
D	14.98 ± .13	.590 ± .005
E	1.93	.076
F	3.30 ± .25	.130 ± .010
G	2.03 ± .13	.080 ± .005
H	.51 ± .13	.020 ± .005
I	1.27 [Typ.]	.050 [Typ.]
J	.71[REF]	.028[REF]
K	.46 [REF]	.018 [REF]
L	10.40/12.94 (W) (L)	.410/.510 (W) (L)
M	.89 R	.035 R
N	.25 (TYP.)	.010 (TYP.)

NOTE: Each lead centerline is located within .25 mm[.01 inch] of its true position [TP] at maximum material condition.



Revision History

Revision No.	Description	Page	Date
2.0	1) AC driving levels changed from 2.4V/0.3V to 3.0V/0V. 2) Change package type, from 12 x 20 mm 48TSOP(I) to 8 x 20mm 32TSOP(I) 3) Eliminate Interactive Programming Mode.		6/05/1997
2.1	IPP1 100uA ----> 10uA		7/17/1997
2.2	Change TSOP Orientation		4/09/1998
2.3	Cancel Ceramic DIP package type	P1,2,9,10	MAR/02/2000



MX27L4000

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