

MN86072

Image Processing LSI

■ Overview

The MN86072 enhances image quality by applying various imaging processing techniques to the analog signal from an image sensor. It reproduces halftone images with 64-gradation using two-dimensional MTF correction and a user-programmable gamma curve.

■ Features

- Image processing that yields top image quality
 - White and black shading correction using overall pixel correction
 - Error dispersion processing that reproduces halftone images with 64-gradation
 - User-programmable gamma curve
 - Multivalue smoothing for diagonal lines to eliminate unsightly "jaggies," artifacts resulting from enlargement or line density conversion
 - Enlargement/reduction (line density conversion) with a user-specified scaling factor without introducing moire patterns
- High-speed processing of only 1 ms per line for an A3 page at 400 dpi with an image processing frequency of 6 MHz
- Built-in analog processing circuits: offset correction circuit, gain correction circuit, and analog-to-digital converter

■ Applications

- Facsimile equipment

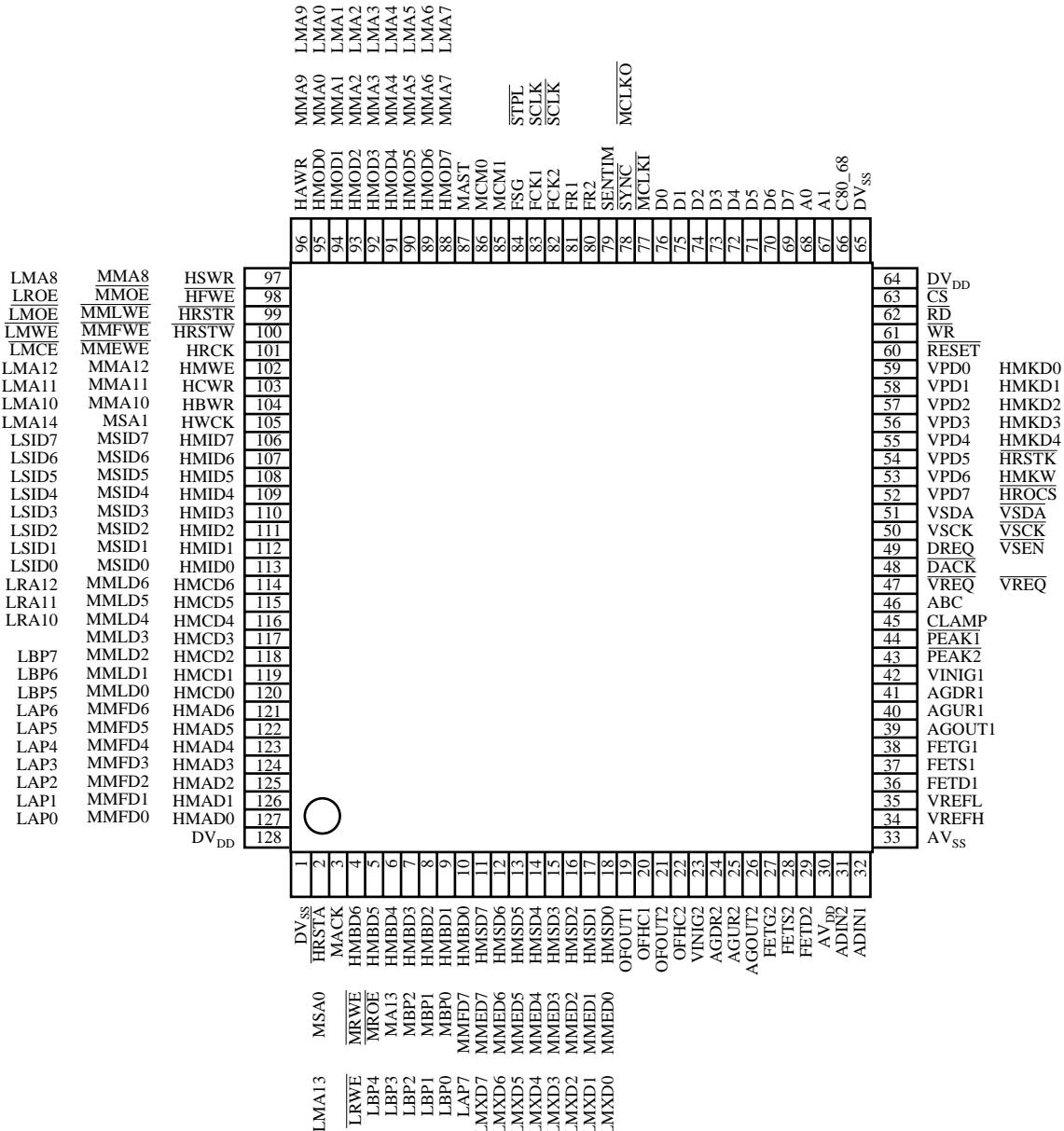
- Drive signal generator for CCDs, CISs, and other
- Memory interfaces that cover a wide variety of applications
 - Standard G3 operation (L mode) (200 dpi, 3 ms/line)
 B4 readout: 64-Kbit SRAM × 1
 A3 readout: 256-Kbit pseudo-SRAM × 1
 - High-speed G3 operation (M mode)
 (200 dpi, 1 ms/line)
 B4 and A3 readout: 64-Kbit SRAM × 2
 - High-resolution G3 operation (M mode)
 (400 dpi, 2 ms/line)
 B4 readout: 64-Kbit SRAM × 2
 A3 readout: 256-Kbit SRAM × 2
 +SRAM (16-Kbit) × 2
 or
 256-Kbit SRAM × 2
 - Ultra-high-speed G4 (H mode) (400 dpi, 1 ms/line)
 B4 and A3 readout: 64-Kbit SRAM × 4
 + 5K × 8-bit FIFO × 1

■ Brief Specifications

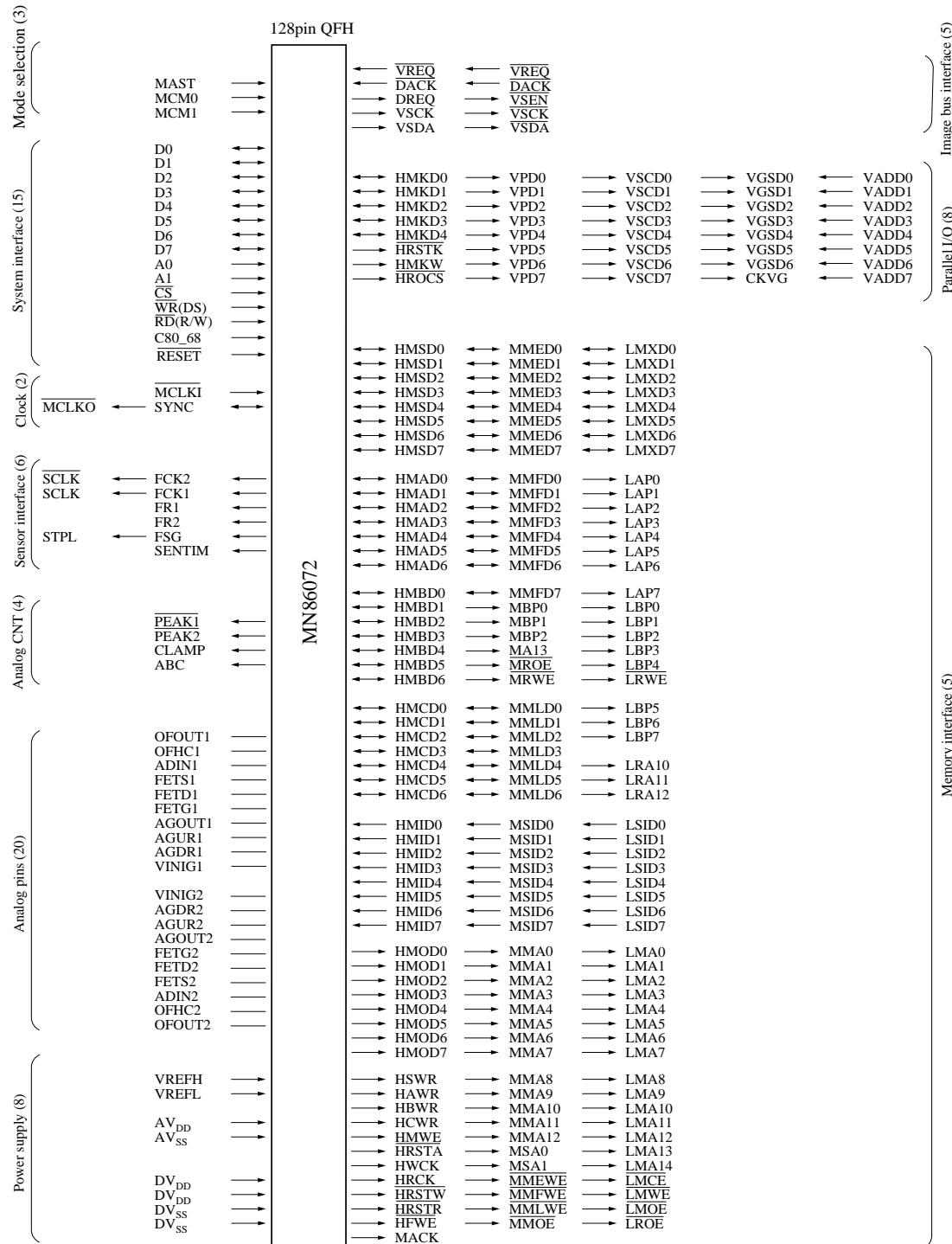
- Image processing speed:
 - 0.1 to 6 million pixels per second
- Pixels per line:
 - max. 16,384 pixels in the primary scanning direction
- Offset correction:
 - negative feedback preamplifier
 - The chip controls the feedback voltage using A/D conversion data from black pixel sections
 - Built-in circuits: Feedback voltage control circuit + source follower circuit × 2
 - (Support for channel-separated CCDs included)
- Gain control:
 - Analog control using an external operational amplifier and the built-in field effect transistor (FET)
 - An external resistor determines the control range.
 - (The standard range is from +6 dB to -12 dB.)
 - Built-in circuits: Gain control circuit + FET × 2
 - (Support for channel-separated CCDs included)
- A/D converter:
 - Half flash converter
 - Number of bits: 8
 - Conversion speed: 0.1 to 6 MHz
 - Input range: min. 3 V_{p-p}
 - Input channels: Support for odd/even separation
- White shading correction:
 - Overall pixel correction
 - Distortion correction level: max. 75% (or max. 50%) of A/D converter's input range
- Black shading correction:
 - Overall pixel correction
 - Distortion correction level: 25% of A/D converter's input range
- MTF correction:
 - Laplacian transforms (processing for text images)
 - Reference to five pixels, max. coefficient of -1.875
 - Support for edge direction-specific processing and processing from preceding history
- Halftone processing:
 - Error dispersion processing: Reproduction of 64-gradation using 6-bit processing
 - Dither pattern: Mesh (4×4 or 8×8 pixels)
Bayer (4×4 pixels)
- Gamma correction:
 - User-definable by loading a conversion curve
 - Conversion levels: 7 bits to 6
- Binary coded:
 - Fixed slice
 - Slice level: User-specified 5-bit value
- Enlargement/reduction (line density conversion):
 - Decimation with image clock or line enable
 - Scaling factor in primary scanning direction: 0.78% to 200% (in 0.78% increments)
 - Scaling factor in subscanning direction: 0.39% to 200% (in 0.39% increments)
- Enlargement/reduction (line density conversion) correction:
 - Multivalue smoothing (for enlargement in primary direction or line density enhancement)
 - Black pixel preservation (for reduction in primary or subscanning direction or line density reduction)
 - OR processing (for line density conversion in subscanning direction from 7.7 line/mm to 3.85)
- Sensor interfaces:
 - CCD sensor
 - Supports both channel-composite and channel-separated CCDs.
 - Generates the following drive signals using user settings: FSG (SH), FCK1, FCK2 ($\phi 1$ and $\phi 2$), FR1, FR2 (RS1 and RS2)
 - Contacting bipolar image sensor
 - Generates SCLK and ST signals.

- CdS sensor
Generates SCLK and STPL signals.
- Memory interfaces:
 - L mode (max. 1 MHz)
 - : 256-Kbit pseudo-SRAM × 1
 - or
 - : 256-Kbit SRAM × 1
 - or, if enlargement and black shading are disabled and the lines are not more than 2048 pixels long, 64-Kbit SRAM × 1
 - M mode(max.3MHz)
 - : 64-Kbit SRAM × 2
 - or, if there is enlargement or black shading
 - : 64-Kbit SRAM × 3
 - H mode (max. 6 MHz)
 - : 64-Kbit SRAM × 4
 - + 5K × 8-bit FIFO × 1
 - Shading memory function (Common in L, M, and H modes)"
 - : Support for fixed ROM shading
 - : Support for automatic data transfers between shading memory and EEROM
 - : Shading memory accessible from microprocessor for read/write operations
- Image bus interface:
 - Parallel mode (DMA slave operation)
 - : 8-bit mode
 - : 16-bit mode (requires external circuitry)
 - Serial mode with request ($\overline{\text{VREQ}}$) input and enable ($\overline{\text{VSEN}}$), clock ($\overline{\text{VSCK}}$), and data ($\overline{\text{VSDA}}$) outputs
- Scanning modes:
 - Free Scan
 - Cycle scan (normal drive)
 - Cycle scan (trapezoidal drive)
 - Trigger scan
- System interface:
 - Interface to 8-bit microprocessors
(Choice of Intel or Motorola formats)
- Video data register readout function:
 - Image data after A/D conversion or shading correction
 - : Maximum value for ABC interval
 - : Minimum value for offset correction interval
 - : Data at user's choice of position
- Image data I/O function:
 - Image data output after shading correction (8 bits)
 - Image data output after multivalue smoothing (7 bits)
 - Image data input sent from external A/D converter (8 bits)
- Output ports:
 - 16 pins (memory interface for L mode)
 - 3 pins (memory interface for M mode)
- Power supply:
 - Digital circuits DV_{DD} : 5.0V
 - Analog circuits AV_{DD} : 5.0V
 - A/D converter reference voltages V_{REFH} : 5.0 to 3.0 V
 V_{REFL} : 0.0 to 2.0 V

■ Pin Assignment



■ Pin Function Chart



■ Pin Descriptions

1. Mode Selection Pins

Pin No.	Symbol	I/O	Function Description	
87	MAST	O	Clock synchronization selection H: Master mode. The chip synchronizes operation with its internal SYNC signal and feeds this signal to the SYNC pin. L: Slave mode. The chip synchronizes operation with the external SYNC signal from the SYNC pin.	
86	MCM0	I	Memory interface mode selection	
85	MCM1	I	These inputs select the mode for the memory interface pins, which determine the multiplier applied to master clock frequency (from the MCLKI pin).	
MAST	MCM1	MCM0	Memory Interface Mode	Clock Mode
L	L	L	L mode	Slave $f_{CKVD} \times 16$
L	L	H	M mode	Slave $f_{CKVD} \times 8$
L	H	L	H mode	Slave $f_{CKVD} \times 2$
L	H	H	T mode	Slave $f_{CKVD} \times 2$
H	L	L	L mode	Master $f_{CKVD} \times 16$
H	L	H	M mode	Master $f_{CKVD} \times 8$
H	H	L	H mode	Master $f_{CKVD} \times 2$
H	H	H	DCTEST	—
			L mode (Low-speed mode) 256-Kbit pseudo-SRAM × 1 or 256-Kbit SRAM × 1 Recommended image signal frequency (f_{CKVD}): max. 1 MHz Master clock frequency (f_{MCLKI}): $f_{CKVD} \times 16$	
			M mode (Medium-speed mode) 64-Kbit SRAM × 3 If enlargement and black shading are disabled 64-Kbit SRAM × 2 Recommended image signal frequency (f_{CKVD}): max. 3 MHz Master clock frequency (f_{MCLKI}): $f_{CKVD} \times 8$	
			H mode (High-speed mode) 64-Kbit SRAM × 4 + 5K × 8-bit FIFO × 1 Recommended image signal frequency (f_{CKVD}): max. 6 MHz Master clock frequency (f_{MCLKI}): $f_{CKVD} \times 2$	

■ Pin Descriptions (continued)

1. Mode Selection Pins (continued)

Pin No.	Symbol	I/O	Function Description												
			<p>T mode (Test data input mode) This mode is for testing internal functions. Master clock frequency (f_{MCLKI}): $f_{CKVD} \times 2$</p> <p>DCTEST mode This mode configures the output and I/O pins for DC testing.</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <th>HMID0</th><th>HMID1</th><th>DC Test Function</th></tr> <tr> <td>0</td><td>—</td><td>Output high-impedance test</td></tr> <tr> <td>1</td><td>0</td><td>"L" level output test</td></tr> <tr> <td>1</td><td>1</td><td>"H" level output test</td></tr> </table>	HMID0	HMID1	DC Test Function	0	—	Output high-impedance test	1	0	"L" level output test	1	1	"H" level output test
HMID0	HMID1	DC Test Function													
0	—	Output high-impedance test													
1	0	"L" level output test													
1	1	"H" level output test													

2. System Interface Pins

Pin No.	Symbol	I/O	Function Description	
76 to 69	D0 to D7	I/O	Microprocessor data I/O bus	
68, 67	A0, A1	I	Microprocessor address input	
63	\overline{CS}	I	Microprocessor chip select input	
61	$\overline{WR}(DS)$	I	Microprocessor data write input Microprocessor data strobe input	(Set C80_68 pin at "H" level) (Set C80_68 pin at "L" level)
62	$\overline{RD}(R/W)$	I	Microprocessor data read input Microprocessor data read/write input	(Set C80_68 pin at "H" level) (Set C80_68 pin at "L" level)
66	C80_68	I	Microprocessor selection input L: Motorola H: Intel	
60	\overline{RESET}	I	System reset input	

■ Pin Descriptions (continued)

3. Clock Pins

Pin No.	Symbol	I/O	Function Description									
77	$\overline{\text{MCLKI}}$	I	<p>Master clock input</p> <p>Clock frequency:</p> <ul style="list-style-type: none"> Image signal frequency × 2 (H mode memory interface) Image signal frequency × 8 (M mode memory interface) Image signal frequency × 16 (L mode memory interface) <p>Clock duty: 50%</p>									
	$\overline{\text{SYNC}}$	I/O	<p>Clock synchronization signal I/O</p> <p>Start timing pulse for individual lines</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <th>MAST</th><th>SYSL (TIM2 REG)</th><th>Remarks</th></tr> <tr> <td>L</td><td>—</td><td>SYNC input</td></tr> <tr> <td>H</td><td>1</td><td>SYNC output</td></tr> </table>	MAST	SYSL (TIM2 REG)	Remarks	L	—	SYNC input	H	1	SYNC output
MAST	SYSL (TIM2 REG)	Remarks										
L	—	SYNC input										
H	1	SYNC output										
78	$\overline{\text{MCLKO}}$	O	<p>Internal master clock output. This pin provides the internal master clock, the signal from the $\overline{\text{MCLKI}}$ pin.</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <th>MAST</th><th>SYSL (TIM2 REG)</th><th>Remarks</th></tr> <tr> <td>H</td><td>0</td><td>MCLK output</td></tr> </table>	MAST	SYSL (TIM2 REG)	Remarks	H	0	MCLK output			
MAST	SYSL (TIM2 REG)	Remarks										
H	0	MCLK output										

■ Pin Descriptions (continued)

4. Sensor Interface Pins

Pin No.	Symbol	I/O	Function Description															
83	FCK1 SCLK	O O	CCD: 1 (TIM 1 REG) Reduced CCD sensor. $\phi 1$ clock: CKVD/2. CCD: 0 (TIM 1 REG) CdS or bipolar image sensor. SCLK clock: CKVD															
82	FCK2 SCLK	O O	CCD: 1 (TIM 1 REG) Reduced CCD sensor. $\phi 2$ clock: CKVD/2. CCD: 0 (TIM 1 REG) CdS or bipolar image sensor. SCLK clock: CKVD															
84	FSG ST STPL	O O O	CCD: 1, CONTA: — (TIM 1 REG) Reduced CCD sensor. ϕSG CCD: 0, CONTA: 0 (TIM 1 REG) Bipolar image sensor. ST = Start puls CCD: 0, CONTA: 0 (TIM 1 REG) CdS sensor. STPL = Start pulse															
81	FR1	O	FRM2: 0 Reduced CCD sensor. $\phi R1$ clock (parallel mode) FRM2: 1 Reduced CCD sensor. ϕR clock (serial mode)															
80	FR2	O	FRM2: 0 Reduced CCD sensor. $\phi R2$ clock (parallel mode) FRM2: 1 Reduced CCD sensor. ϕSP clock (serial mode)															
79	SENTIM	O	Sensor timing output pin <table border="1" data-bbox="620 1351 1362 1573"> <thead> <tr> <th>STM1 (TIM2 REG)</th> <th>STM0 (TIM2 REG)</th> <th>SETIM output signal</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>Offset enable</td> </tr> <tr> <td>0</td> <td>1</td> <td>ABC enable</td> </tr> <tr> <td>1</td> <td>0</td> <td>User-defined timing (for all lines read)</td> </tr> <tr> <td>1</td> <td>1</td> <td>User-defined timing (for valid lines only)</td> </tr> </tbody> </table>	STM1 (TIM2 REG)	STM0 (TIM2 REG)	SETIM output signal	0	0	Offset enable	0	1	ABC enable	1	0	User-defined timing (for all lines read)	1	1	User-defined timing (for valid lines only)
STM1 (TIM2 REG)	STM0 (TIM2 REG)	SETIM output signal																
0	0	Offset enable																
0	1	ABC enable																
1	0	User-defined timing (for all lines read)																
1	1	User-defined timing (for valid lines only)																

■ Pin Descriptions (continued)**5. Sensor Drive Pins**

Pin No.	Symbol	I/O	Function Description
44	<u>PEAK1</u>	O	Gain control signal 1 (Overflow 1) "L" level: Reduce gain. "H" level: Increase gain.
43	<u>PEAK2</u>	O	Gain control signal 2 (Overflow 2) "L" level: Reduce gain. "H" level: Increase gain.
45	CLAMP	O	Clamp (offset correction) interval signal. "L" level: Hold. "H" level: Sample (offset adjustment operation).
46	ABC	O	ABC effective interval signal. "L" level: Hold gain. "H" level: Adjust gain.

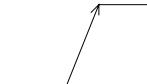
■ Pin Descriptions (continued)

6. Image Bus Interface Pins

Pin No.	Symbol	I/O	Function Description
47	<u>VREQ</u>	I	<p>Video request.</p> <p>This pin accepts image data transfer requests from the controlled device. "L" level: Transfer request enable. "H" level: Transfer request disable.</p> <p>In the trigger scan mode, pulling this pin to "L" level forces the sensor start (STPL) pin to "L" level to start sensor readout. After image-processing a line of data, the image data are outputted at the VSDA pin.</p> <p>In the cycle scan mode, pulling this pin to "L" level enables the next readout line. After image-processing a line of data, the image data are outputted at the VSDA pin.</p> <p>In the free scan mode, the chip ignores this pin, sensor readout starts at the interval specified with the timing settings, and the image data are outputted at the VSDA pin after processing each line of data.</p>
49	DREQ	O	<p>Parallel mode (IPARA (IBCNT REGI): 1)</p> <p>Parallel data transfer request. "L" level: Transfer request enable. "H" level: Transfer request disable.</p> <p>Serial mode (IPARA (IBCNT REGI): 0)</p>
	<u>VSEN</u>	O	<p>Video enable "L" level: Image data enable. "H" level: Image data disable.</p>
48	<u>DACK</u>	I	<p>Parallel data acknowledge.</p> <p>Data transfer acknowledge signal in response to DREQ. "L" level: Data transfer enable. "H" level: Data transfer disable.</p>

■ Pin Descriptions (continued)

6. Image Bus Interface Pins (continued)

Pin No.	Symbol	I/O	Function Description
50	VSCK	O	Parallel mode (IPARA (IBCNT REGI): 1) Video serial clock (signal for external circuitry).  Timing for reading VSDA data.
	- - - VSCK - - -	O	Serial mode (IPARA (IBCNT REGI): 0) Video serial clock.  Timing for reading VSDA data.
51	VSDA	O	Parallel mode (IPARA (IBCNT REGI): 1) Video serial data. (signal for external circuitry). Binary image data output. "L" level: Black. "H" level: White.
	- - - VSDA - - -	O	Serial mode (IPARA (IBCNT REGI): 0) Video serial data. Binary image data output. "L" level: Black. "H" level: White.

■ Pin Descriptions (continued)

7. Parallel I/O Pins

Pin No.	Symbol	I/O	Function Description
52	VADD7	I	PSD2: 0, PSD1: 0, PSD0: — (IBCNT REGI) External A/D converter signal input
	HROCS	O	PSD2: 0, PSD1: 1, PSD0: — (IBCNT REGI) Shading ROM chip select
	VPD7	O/Hi-z	PSD2: 1, PSD1: 0, PSD0: 0 (IBCNT REGI) Binary parallel image output (parallel interface) DACK: L Output.
			DACK: H High-impedance.
	VSCD7	O	PSD2: 1, PSD1: 0, PSD0: 1 (IBCNT REGI) Output pin for image signal after shading correction
	CKVG	O	PSD2: 1, PSD1: 1, PSD0: 0 (IBCNT REGI) Multivalue image signal synchronization clock output
53	SBUS7	O	PSD2: 1, PSD1: 1, PSD0: 1 (IBCNT REGI) Internal DBUS data output
	VADD6	I	PSD2: 0, PSD1: 0, PSD0: — (IBCNT REGI) External A/D converter input
	HKWR	O	PSD2: 0, PSD1: 1, PSD0: — (IBCNT REGI) HMKD write/read output
	VPD6	O/Hi-z	PSD2: 1, PSD1: 0, PSD0: 0 (IBCNT REGI) Binary parallel image output (parallel interface) DACK: L Output.
	VSCD6	O	PSD2: 1, PSD1: 0, PSD0: 1 (IBCNT REGI) Output pin for image signal after shading correction
	VGSD6	O	PSD2: 1, PSD1: 1, PSD0: 0 (IBCNT REGI) Multivalue image signal output
54	SBUS6	O	PSD2: 1, PSD1: 1, PSD0: 1 (IBCNT REGI) Internal DBUS data output
	VADD5	I	PSD2: 0, PSD1: 0, PSD0: — (IBCNT REGI) External A/D converter input
	HRSTK	O	PSD2: 0, PSD1: 1, PSD0: — (IBCNT REGI) External address control clear for black shading
	VPD5	O/Hi-z	PSD2: 1, PSD1: 0, PSD0: 0 (IBCNT REGI) Binary parallel image output (parallel interface) DACK: L Output.
	VSCD5	O	PSD2: 1, PSD1: 0, PSD0: 1 (IBCNT REGI) Output pin for image signal after shading correction

■ Pin Descriptions (continued)

7. Parallel I/O Pins (continued)

Pin No.	Symbol	I/O	Function Description
54	VGSD5	O	PSD2: 1, PSD1: 1, PSD0: 0 (IBCNT REGI) Multivalue image signal output
	SBUSS	O	PSD2: 1, PSD1: 1, PSD0: 1 (IBCNT REGI) Internal DBUS data output
55 to 59	VADD4 VADD0 HMKD4 to HMKD0	I I/O	PSD2: 0, PSD1: 0, PSD0: — (IBCNT REGI) External A/D converter output PSD2: 0, PSD1: 1, PSD0: — (IBCNT REGI) Black shading correction data I/O. HKWR: L Input. HKWR: H High-impedance.
	VPD4 to VPD0	O/Hi-z	PSD2: 1, PSD1: 0, PSD0: 0 (IBCNT REGI) Binary parallel image signal output (parallel interface) DACK: L Output. DACK: H High-impedance.
	VSCD4 to VSCD0	O	PSD2: 1, PSD1: 0, PSD0: 1 (IBCNT REGI) Shading correction data I/O.
	VGSD4 to VGSD0	O	PSD2: 1, PSD1: 1, PSD0: 0 (IBCNT REGI) Multivalue image signal output
	SBUS4 to SBUS0	O	PSD2: 1, PSD1: 1, PSD0: 1 (IBCNT REGI) Internal DBUS data output

*1 VPD0 to 7
1: Black Data direction: MSB first
0: White

*2 VPD0 to 7
X'FF' to X'00': "White" to "Black"

*3 VGSD 0 to 6
X'7F' to X'00': "White" to "Black"

*4 VADD0 to 7
X'FF' to X'00': "White" to "Black"

■ Pin Descriptions (continued)

8. Memory interface pins

Function is selected by the memory control register (MECR) and mode pins of MCM0 (Pin No. 86) and of MCM1 (Pin No. 85).

Mode	Mode pins		MECR		Image processing functions			Notes	
	MCM1	MCM0	RSH	MAG	Shading		Enlarge- ment		
					White Correc- tion	Black Correc- tion			
L	L	L		0	0	●	×	×	Image signal frequency: Max. 625kHz to 1MHz
				0	1	●	●	●	Memory selection bit, STK. 0: SRAM or PSRAM 1: PSRAM
				1	0	Fixed in ROM	×	×	EXSCD *1 0: Internal SCD processing. 1: External SCD input.
				1	1	Fixed in ROM	●	●	
M	L	H		0	-	●	●	●	Image signal frequency: Max. 3 MHz EXSCD *1 0: Internal SCD processing. 1: External SCD input.
				1	1	Fixed in ROM	●	●	STK:- Disabling black correction and enlargement reduces memory requirements to two SRAMs.
H	H	L	-	-	●	●	●	Image signal frequency: Max. 6 MHz EXSCD *1 0: Internal SCD processing. 1: External SCD input. STK:-	

Note*1: SCD is the data after shading correction.

■ Pin Descriptions (continued)

8.1 L Mode

Pin No.	Symbol	I/O	Function Description
18 to 11	LMXD0 to LMXD7	I/O	RAM data I/O bus. I/O data bus for white shading data, black shading data, error dispersion processing error data, and 2-line image data."
95 to 88 97 96 104 103 102 2 105	LMA0 to LMA7 LMA8 LMA9 LMA10 LMA11 LMA12 LMA13 LMA14	O	RAM address
99	<u>LMOE</u>	O	RAM OE control
100	<u>LMWE</u>	O	RAM WE control
101	<u>LMCE</u>	O	Pseudo-SRAM chip select control
103 to 106	LSID0 to LSID7	I	White shading ROM data input. Input for data after external shading correction.
98	<u>LROE</u>	O	White shading ROM OE control.
4	<u>LRWE</u>	O	EEROM WE control
116 to 114	LRA10 to LRA12	O	Upper address of EEROM (The lower bits use LMA0–LMA9.)
127 to 121 10	LAP0 to LAP6 LAP7	O	Output port A (8 bits)
9 to 5 120 119 118	LBP0 to LBP4 LBP5 LBP6 LBP7	O	Output port B (8 bits)

■ Pin Descriptions (continued)

8.2 M Mode

Pin No.	Symbol	I/O	Function Description
18 to 11	MMED0 to MMED7	I/O	RAM data I/O. White shading data and error dispersion processing error data.
127 to 121 10	MMFD0 to MMFD6 MMFD7	I/O	RAM data I/O. Black shading data and error dispersion processing error data (for use in enlargement).
120 to 114	MMLD0 to MMLD6	I/O	RAM data I/O. 2-line image data.
113 to 106	MSID0 to MSID7	I	White shading ROM data input, or input for data after external shading correction.
95 to 88 97 96 104 to 102 6	MMA0 to MMA7 MMA8 MMA9 MMA10 to MMA12 MMA13	O	RAM address
2 105	MSA0 MSA1	O	Upper address of RAM
101 100 99	<u>MMEWE</u> <u>MMFWE</u> <u>MMLWE</u>	O	RAM WE control
98	<u>MMOE</u>	O	RAM OE control
5	<u>MROE</u>	O	White shading ROM and EEROM OE control
4	<u>MRWE</u>	O	EEROM WE control
9 to 7	MBP0 to MBP2	O	Output port B (3 bits)

■ Pin Descriptions (continued)

8.3 H Mode

Pin No.	Symbol	I/O	Function Description
18 to 11	HMSD0 to HMSD7	I/O	RAM data I/O. White shading data.
127 to 121	MMAD0 to MMAD6	I/O	RAM data I/O. One-line image data.
10 to 4	MMBD0 to MMBD6	I/O	RAM data I/O. One-line image data.
120 to 114	MMCD0 to MMCD6	I/O	RAM data I/O. One-line image data.
113 to 106	HMID0 to HMID7	I	FIFO data input. Error dispersion processing error data.
95 to 88	HMOD0 to HMOD7	O	FIFO data input. Error dispersion processing error data.
97 96 104 103	HMSWR HMAWR HMBWR HMCWR	O	RAM OE control
102	HMWE	O	RAM WE control (needs NAND gate)
105	HWCK	O	FIFO WCK
101	HRCK	O	FIFO RCK
100	<u>HRSTW</u>	O	FIFO RSTW
99	<u>HRSTR</u>	O	FIFO RSTR
98	<u>HFWE</u>	O	FIFO WE
3	MACK	O	RAM address counter clock
2	<u>HRSTA</u>	O	RAM address counter clear

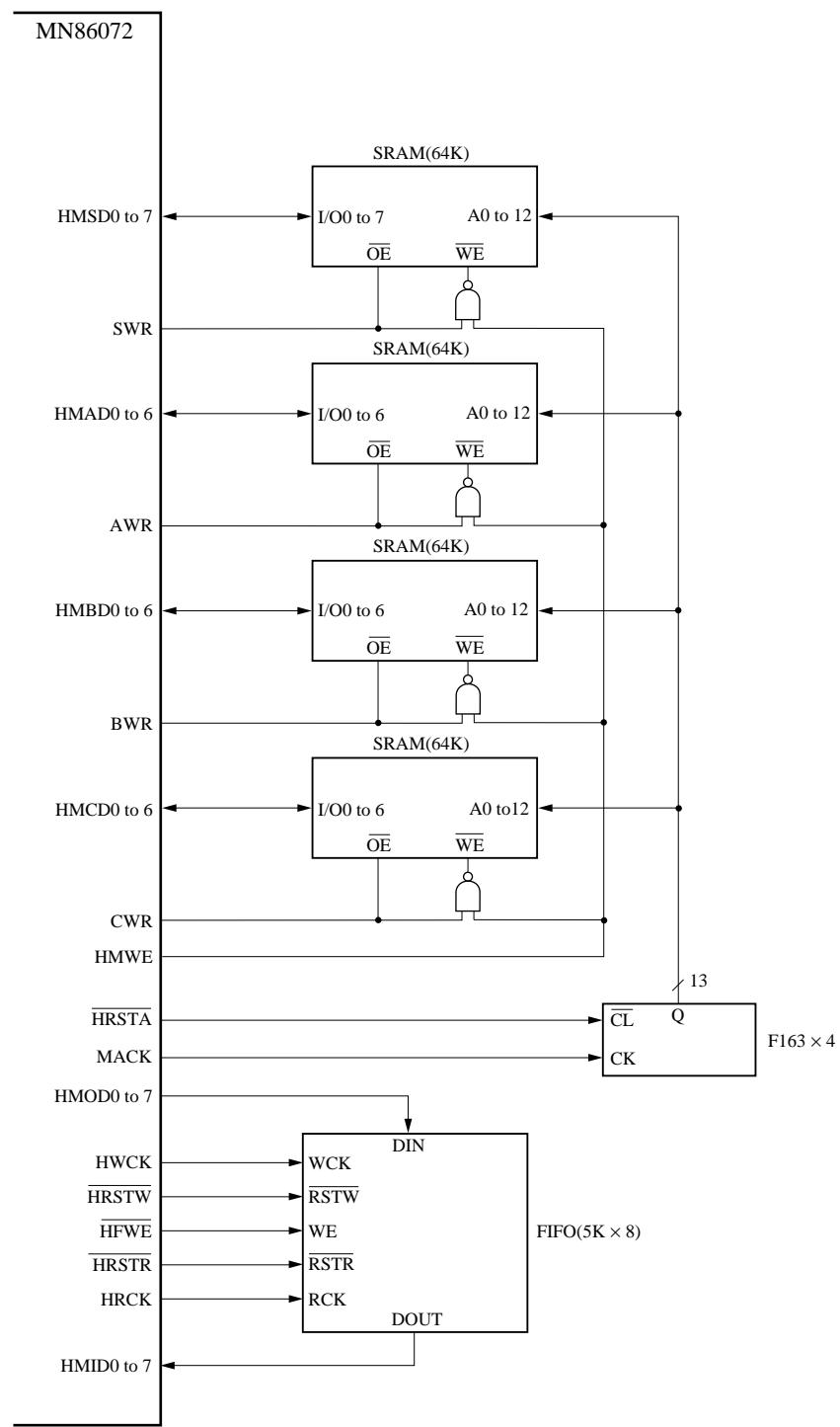
■ Application Circuit Example (1)

H Mode

White correction (without SMA mode) with no black correction

Memory configuration: 64-Kbit SRAM × 4

5K × 8-bit FIFO × 1



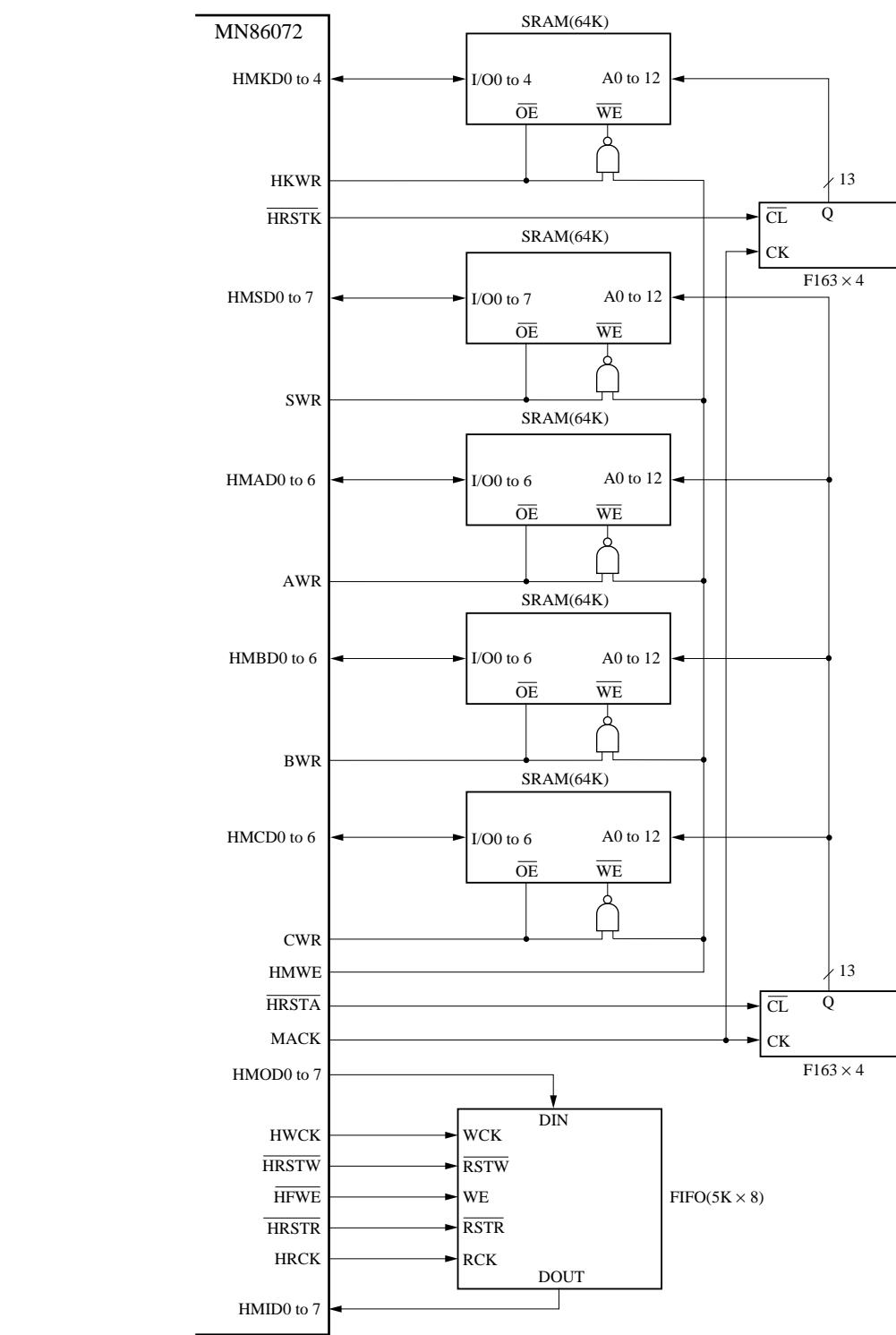
■ Application Circuit Example (2)

H Mode

White correction (without SMA mode) with black correction

Memory configuration: 64-Kbit SRAM × 4

5K × 8-bit FIFO × 1



■ Package Dimensions (Unit: mm)

QFH128-P-1818

