



The Infinite Bandwidth Company™

## MIC38C42A/43A/44A/45A

### BiCMOS Current-Mode PWM Controllers

#### Final Information

### General Description

The MIC38C4xA are fixed frequency, high performance, current-mode PWM controllers. Micrel's BiCMOS devices are pin compatible with 384x bipolar devices but feature several improvements.

Undervoltage lockout circuitry allows the '42 and '44 versions to start up at 14.5V and operate down to 9V, and the '43 and '45 versions start at 8.4V with operation down to 7.6V. All versions operate up to 20V.

When compared to bipolar 384x devices operating from a 15V supply, start-up current has been reduced to 50μA typical and operating current has been reduced to 4.0mA typical. Decreased output rise and fall times drive larger MOSFETs, and rail-to-rail output capability increases efficiency, especially at lower supply voltages. The MIC38C4xA also features a trimmed oscillator discharge current and bandgap reference.

The MIC38C4xA family is available in 8-pin SOIC and MSOP-8 (MM8) package options

*For fast rise and fall times and higher output drive, refer to the MIC38HC4x.*

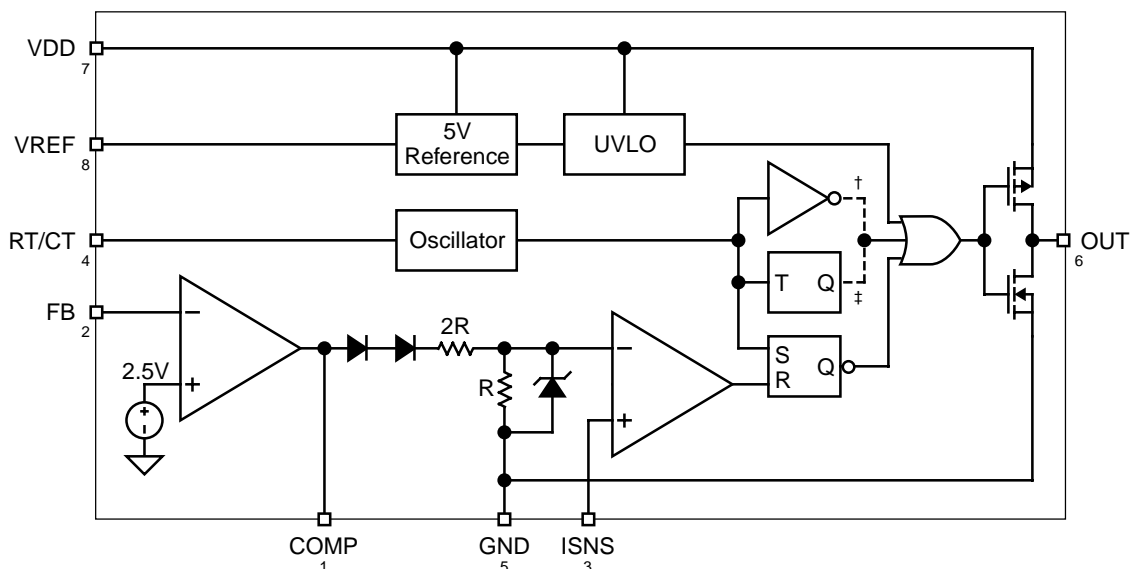
### Features

- Fast 40ns output rise and 30ns output fall times
- -40°C to +85°C temperature range meets UC284x specifications
- High-performance, low-power BiCMOS Process
- Ultralow start-up current (100μA typical)
- Low operating current (4mA typical)
- CMOS outputs with rail-to-rail swing
- ≥ 500kHz current-mode operation
- Trimmed 5V bandgap reference
- Pin-for-pin compatible with UC3842/3843/3844/3845
- Trimmed oscillator discharge current
- UVLO with hysteresis
- Low cross-conduction currents

### Applications

- Current-mode, off-line, switched-mode power supplies
- Current-mode, dc-to-dc converters.
- Step-down "buck" regulators
- Step-up "boost" regulators
- Flyback, isolated regulators
- Forward converters
- Synchronous FET converters

### Functional Diagram



† MIC38C42A, MIC38C43A (96% max. duty cycle) versions only

‡ MIC38C44A, MIC38C45A (50% max. duty cycle) versions only

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## Ordering Information

Part Number	Temperature Range	Package
MIC38C42ABM	–40°C to +85°C	8-pin SOIC
MIC38C43ABM	–40°C to +85°C	8-pin SOIC
MIC38C44ABM	–40°C to +85°C	8-pin SOIC
MIC38C45ABM	–40°C to +85°C	8-pin SOIC
MIC38C42ABMM	–40°C to +85°C	8-pin MM8™
MIC38C43ABMM	–40°C to +85°C	8-pin MM8™
MIC38C44ABMM	–40°C to +85°C	8-pin MM8™
MIC38C45ABMM	–40°C to +85°C	8-pin MM8™

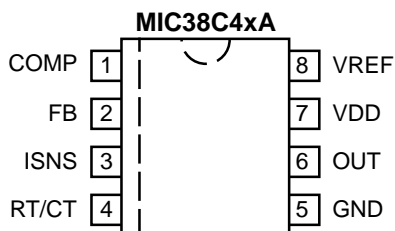
Refer to the Part Number Cross Reference for a listings of Micrel devices equivalent to UC284x and UC384x devices.

## Selection Guide

	UVLO Thresholds	
Duty Cycle	Startup 8.4V Minimum Operating 7.6V	Startup 14.5V Minimum Operating 9V
	MIC38C43A	MIC38C42A
0% to 96%		
0% to 50%	MIC38C45A	MIC38C44A



## Pin Configuration



**8-Lead SOIC (M)**  
**8-Lead MM8™ (MM)**

## Pin Description

Pin Number	Pin Name	Pin Function
1	COMP	Compensation: Connect external compensation network to modify the error amplifier output.
2	FB	Feedback (Input): Error amplifier input. Feedback is 2.5V at desired output voltage.
3	ISNS	Current Sense (Input): Current sense comparator input. Connect to current sensing resistor or current transformer.
4	RT/CT	Timing Resistor/Timing Capacitor: Connect external RC network to select switching frequency.
5	GND	Ground: Combined analog and power ground.
6	OUT	Power Output: Totem-pole output.
7	VDD	Analog Supply (Input): Controller circuitry supply input. Return to analog ground (AGND).
8	VREF	5V Reference (Output): Connect external RC network.



**Absolute Maximum Ratings**

Supply Voltage ( $V_{DD}$ )	20V
Switch Supply Voltage ( $V_D$ )	20V
Current Sense Voltage ( $V_{ISNS}$ )	-0.3V to 5.5V
Feedback Voltage ( $V_{FB}$ )	-0.3V to 5.5V
Output Current ( $I_{OUT}$ )	0.5A
Storage Temperature ( $T_A$ )	-65°C to +150°C

**Operating Ratings**

Junction Temperature ( $T_J$ )	150°C
Package Thermal Resistance	
8-Pin MM8™ ( $\theta_{JA}$ )	250°C/W
8-Pin SOIC ( $\theta_{JA}$ )	170°C/W

**Electrical Characteristics**(Note 6)

$V_{DD} = 15V$ , **Note 4**;  $R_T = 11.0k$ ;  $C_T = 3.3nF$ ;  $-40^\circ C \leq T_A \leq 85^\circ C$ ; unless noted

Parameter	Test Conditions	Min	Typ	Max	Units
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**Reference Section**

Output Voltage	$T_A = 25^\circ C$ , $I_O = 1mA$	4.90	5.00	5.10	V
Line Regulation	$12V \leq V_{DD} \leq 18V$ , $I_O = 5\mu A$		2	20	mV
Load Regulation	$1 \leq I_O \leq 20mA$		1	25	mV
Temp. Stability	<b>Note 1</b>		0.2		mV/°C
Total Output Variation	Line, Load, Temp., <b>Note 1</b>	4.82		5.18	V
Output Noise Voltage	$10Hz \leq f \leq 10kHz$ , $T_A = 25^\circ C$ , <b>Note 1</b>		50		$\mu V$
Long Term Stability	$T_A = 125^\circ C$ , 1000 hrs., <b>Note 1</b>		5	25	mV
Output Short Circuit		-30	-80	-180	mA

**Oscillator Section**

Initial Accuracy	$T_A = 25^\circ C$ , <b>Note 5</b>	47	53	59	kHz
Voltage Stability	$12 \leq V_{DD} \leq 18V$		0.2	1.0	%
Temp. Stability	$T_{MIN} \leq T_A \leq T_{MAX}$ , <b>Note 1</b>		0.04		%/°C
Clock Ramp Reset Current	$T_A = 25^\circ C$ , $V_{RT/CT} = 2V$ , <b>Note 1</b>	7.7	8.4	9.0	mA
Amplitude	$V_{RT/CT}$ peak to peak		1.9		Vp-p

**Error Amp Section**

Input Voltage	$V_{COMP} = 2.5V$	2.4	2.50	2.58	V
Input Bias Current	$V_{FB} = 5.0V$		-0.1	-2	$\mu A$
$A_{VOL}$	$2 \leq V_O \leq 4V$	65	90		dB
Unity Gain Bandwidth	<b>Note 1</b>	0.7	1.0		MHz
PSRR	$12 \leq V_{DD} \leq 18V$	60			dB
Output Sink Current	$V_{FB} = 2.7V$ , $V_{COMP} = 1.1V$	2	14		mA
Output Source Current	$V_{FB} = 2.3V$ , $V_{COMP} = 5V$	-0.3	-1		mA
$V_{OUT}$ High	$V_{FB} = 2.3V$ , $R_L = 15k$ to ground	5	6.8		V
$V_{OUT}$ Low	$V_{FB} = 2.7V$ , $R_L = 15k$ to $V_{REF}$		0.1	1.1	V



Parameter	Test Conditions	Min	Typ	Max	Units
<b>Current Sense</b>					
Gain	Notes 2, 3	2.85	3.0	3.15	V/V
Maximum Threshold	$V_{COMP} = 5V$ , Note 2	0.9	1	1.1	V
PSRR	$12 \leq V_{DD} \leq 18V$ , Note 2		70		dB
Input Bias Current			-0.1	-2	$\mu A$
Delay to Output			120	250	ns
<b>Output</b>					
$R_{DS(ON)}$ High	$I_{SOURCE} = 200mA$		20		$\Omega$
$R_{DS(ON)}$ Low	$I_{SINK} = 200mA$		11		$\Omega$
Rise Time	$T_A = 25^\circ C$ , $C_L = 1nF$		40	80	ns
Fall Time	$T_A = 25^\circ C$ , $C_L = 1nF$		30	60	ns
<b>Undervoltage Lockout</b>					
Start Threshold	MIC38C42A/4A	13.5	14.5	15.5	V
	MIC38C43A/5A	7.8	8.4	9.0	V
Minimum Operating Voltage	MIC38C42A/4A	8	9	10	V
	MIC38C43A/5A	7.0	7.6	8.2	V
<b>Pulse Width Modulator</b>					
Maximum Duty Cycle	MIC38C42A/3A	94	96		%
	MIC38C44A/5A	46	50		%
Minimum Duty Cycle				0	%
<b>Total Standby Current</b>					
Start-Up Current	$V_{DD} = 13V$ for MIC38C42A/44A $V_{DD} = 7.5V$ for MIC38C43A/45A		100	230	$\mu A$
Operating Supply Current	$V_{FB} = V_{ISNS} = 0V$		4.0	6.0	mA

**Note 1:** These parameters, although guaranteed, are not 100% tested in production.

**Note 2:** Parameter measured at trip point of latch with  $V_{EA} = 0$ .

**Note 3:** Gain defined as:

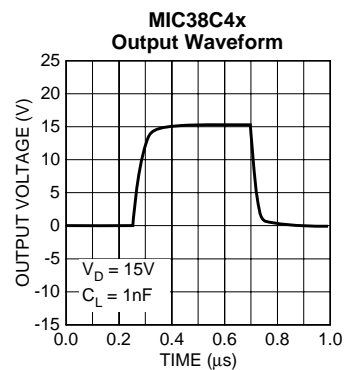
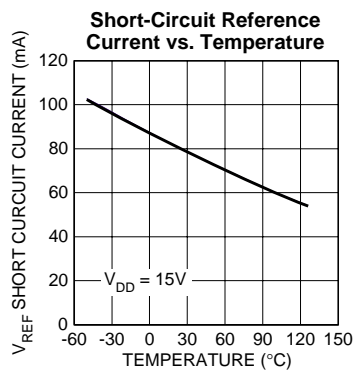
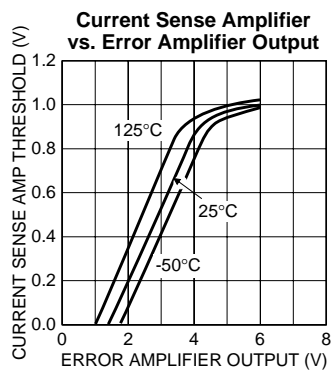
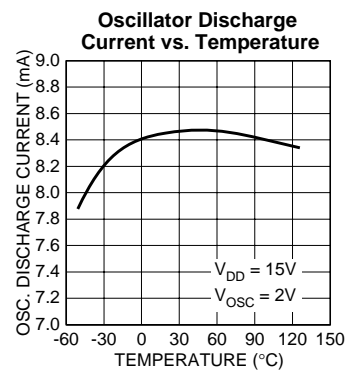
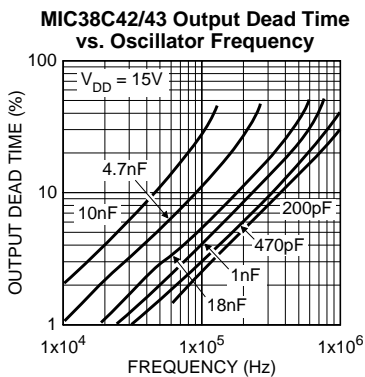
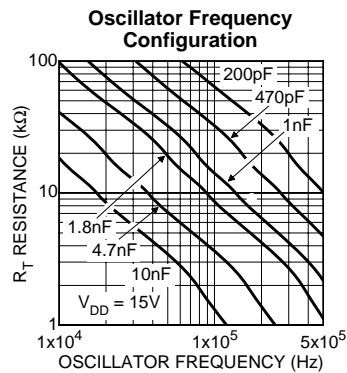
**Note 4:** Adjust  $V_{DD}$  above the start threshold before setting at 15V.

**Note 5:** Output frequency equals oscillator frequency for the MIC38C42 and MIC38C43. Output frequency for the MIC38C44A, and MIC38C45A equals one half the oscillator frequency.

**Note 6:** Specification for packaged product only.



## Typical Characteristics





## Application Information

Familiarity with 384x converter designs is assumed.

## MIC38C4x Advantages

### Start-up Current

Start-up current has been reduced to an ultra-low 50 $\mu$ A (typical) permitting higher-valued, lower-wattage, start-up resistors (powers controller during power supply start-up). The reduced resistor wattage reduces cost and printed circuit space.

### Operating Current

Operating current has been reduced to 4mA compared to 11mA for a typical bipolar controller. The controller runs cooler and the  $V_{DD}$  hold-up capacitance required during start-up may be reduced.

### Output Driver

Complementary internal P- and N-channel MOSFETs produce rail-to-rail output voltages for better performance driving external power MOSFETs. The driver transistor's low on-resistance and high peak current capability can drive gate capacitances of greater than 1000pF. The value of output capacitance which can be driven is determined only by the rise/fall time requirements. Within the restrictions of output capacity and controller power dissipation, maximum switching frequency can approach 500kHz.

## Design Precautions

When operating near 20V, circuit transients can easily exceed the 20V absolute maximum rating, permanently damaging the controller's CMOS construction. To reduce transients, use a 0.1μF low-ESR capacitor to next to the controller's supply  $V_{DD}$  (or  $V_D$  for '-1' versions) and ground connections. Film type capacitors, such as Wima MKS2, are recom-

mended.

When designing high-frequency converters, avoid capacitive and inductive coupling of the switching waveform into high-impedance circuitry such as the error amplifier, oscillator, and current sense amplifier. Avoid long printed-circuit traces and component leads. Locate oscillator and compensation circuitry near the IC. Use high frequency decoupling capacitors on  $V_{REF}$ , and if necessary, on  $V_{DD}$ . Return high  $di/dt$  currents directly to their source and use large area ground planes.

## Buck Converter

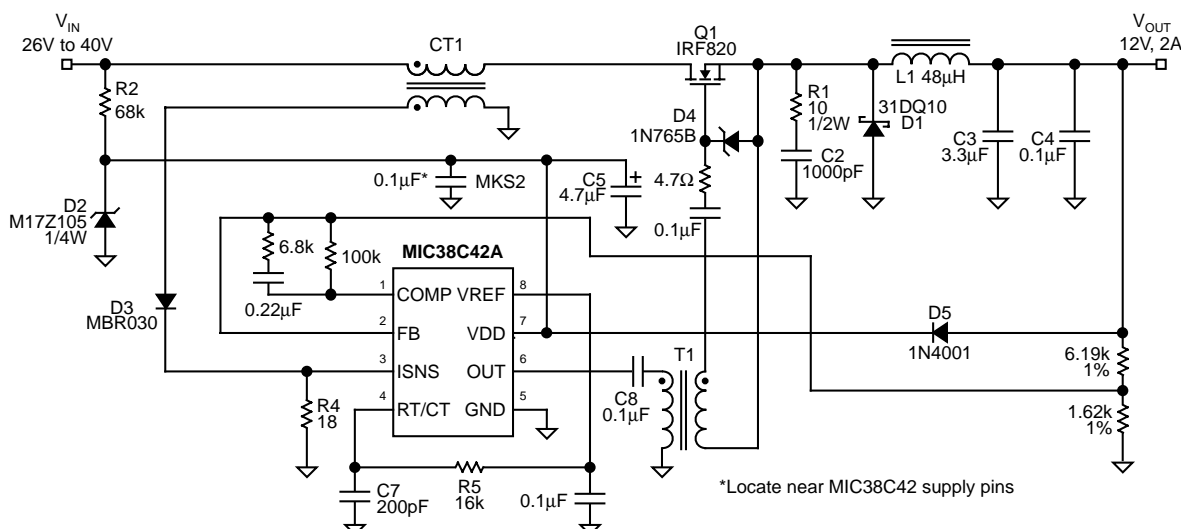
Refer to figure 1. When at least 26V is applied to the input, C5 is charged through R2 until the voltage  $V_{DD}$  is greater than 14.5V (the undervoltage lockout value of the MIC38C42). Output switching begins when Q1 is turned on by the gate drive transformer T1, charging the output filter capacitor C3 through L1. D5 supplies a regulated +12V to  $V_{DD}$  once the circuit is running.

Current sense transformer CT1 provides current feedback to ISNS for current-mode operation and cycle-by-cycle current limiting. This is more efficient than a high-power sense resistor and provides the required ground-referenced level shift.

When Q1 turns off, current flow continues from ground through D1 and L1 until Q1 is turned on again.

The 100V Schottky diode D1 reduces the forward voltage drop in the main current path, resulting in higher efficiency than could be accomplished using an ultra-fast-recovery diode. R1 and C2 suppress parasitic oscillations from D1.

Using a high-value inductance for L1 and a low-ESR capacitor for C3 permits small capacitance with minimum output ripple. This inductance value also improves circuit efficiency by reducing the flux swing in L1.



### Figure 1. 500kHz, 25W, Buck Converter



Magnetic components are carefully chosen for minimal loss at 500kHz. CT1 and T1 are wound on Magnetics, Inc. P-type material toroids. L1 is wound on a Siemens N49 EFD core.

Test	Conditions	Results
Line Regulation	$V_{IN} = 26V$ to $80V$ , $I_O = 2A$	0.5%
Load Regulation	$V_{IN} = 48V$ , $I_O = 0.2A$ to $2A$	0.6%
Efficiency	$V_{IN} = 48V$ , $I_O = 2A$	90%
Output Ripple	$V_{IN} = 48V$ , $I_O = 2A$ (20MHz BW)	100mV

Symbol	Custom Coil <sup>1</sup>	ETS <sup>2</sup>
CT1	4923	ETS 92420
T1	4924	ETS 92419
L1	4925	ETS 92421

1. Custom Coils, Alcester, SD tel: (605) 934-2460

2. Energy Transformation Systems, Inc. tel: (415) 324-4949.

## Synchronous Buck Converter

Refer to figure 2. This MIC38C43 synchronous buck converter uses an MIC5022 half-bridge driver to alternately drive the PWM switch MOSFET (driven by GATEH, or high-side output) and a MOSFET which functions as a synchronous rectifier (driven by the GATEL, or low-side output).

The low-side MOSFET turns on when the high-side MOSFET is off, allowing current to return from ground. Current flows through the low-side MOSFET in the source to drain direction.

The on-state voltage drop of the low-side MOSFET is lower than the forward voltage drop of an equivalent Schottky rectifier. This lower voltage drop results in higher efficiency.

A sense resistor ( $5m\Omega$ ) is connected to the driver's high-side current sense inputs to provide overcurrent protection. Refer to the MIC5020, MIC5021, and MIC5022 data sheets for more information.

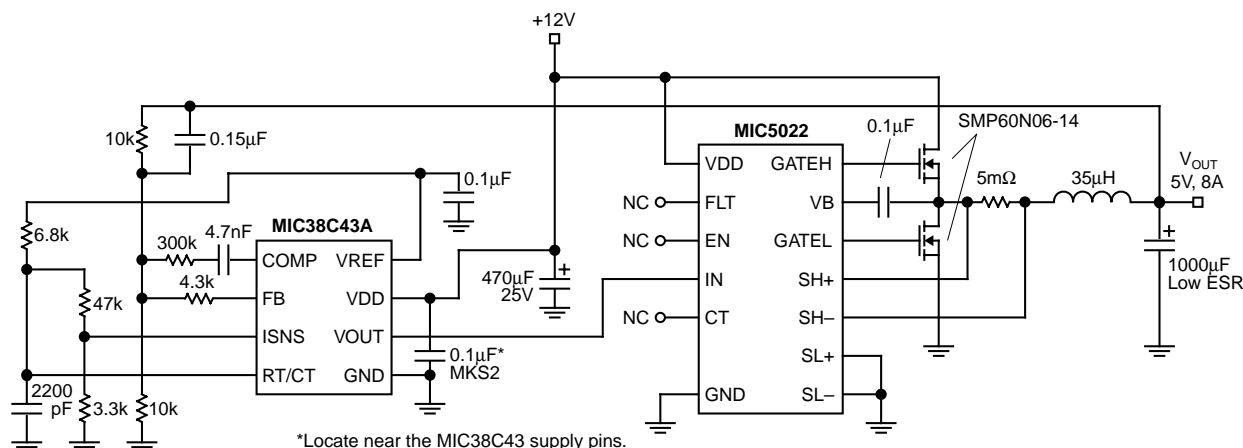
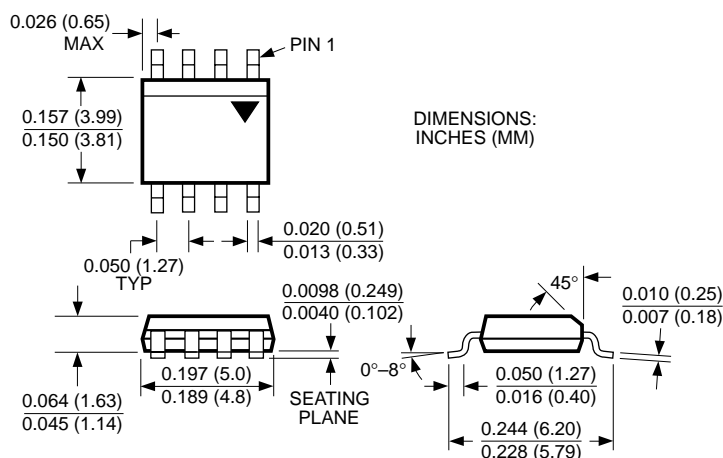


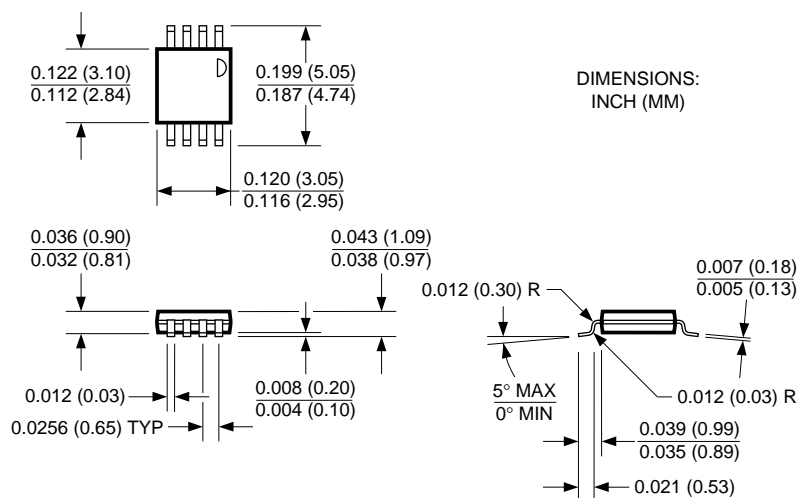
Figure 2. 100kHz, Synchronous Buck Converter



## Package Information



**8-Pin SOP (M)**



**8-Pin MSOP (MM)**

**MICREL INC. 1849 FORTUNE DRIVE SAN JOSE, CA 95131 USA**

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