

AN6607NS

DC Motor Forward/Reverse Dual Speed Electronic Governor

■ Overview

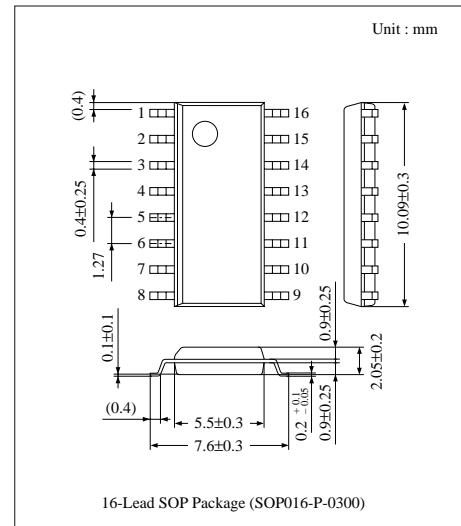
The AN6607NS is an electronic governor which incorporates the forward/reverse rotation and double speed controls of the DC motors used for radio/cassette tape recorder, and the functions such as fast forward, rewind, brake, and pause.

■ Features

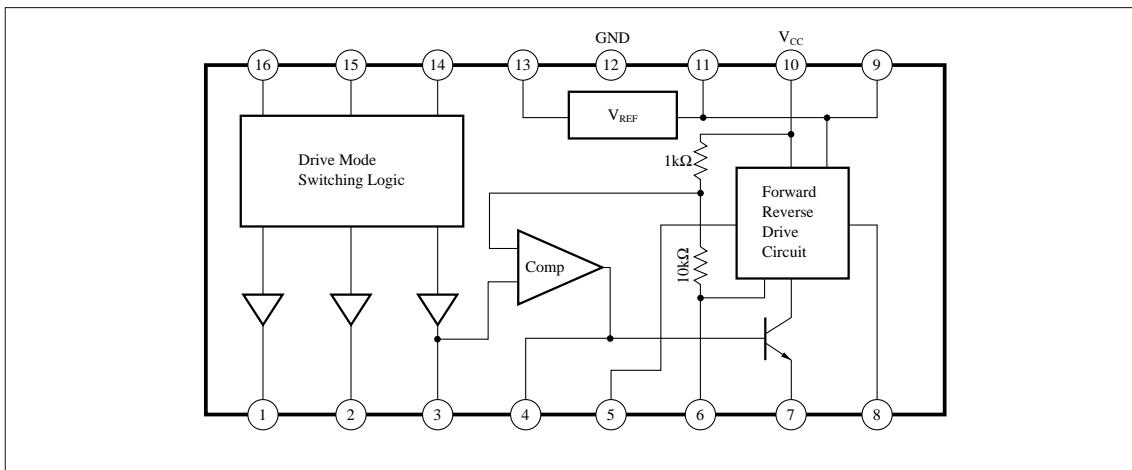
- Operating supply voltage range ; V_{CC} = 8V to 16V
- Stable reference voltage (1.27V) and easy speed adjustment
- Large starting torque and maximum control torque
- Good secular drift because of external power transistor
- High-density mounting allowed by the SO package
- Forward/reverse constant speed and double speed controls, and fast forward, brake, and pause functions available by 3-bit input

■ Applications

Cassette decks, radio/cassette tape recorders, car cassette tape players, DC motor control such as DAT, tape loading motor control.



■ Block Diagram



■ Absolute Maximum Ratings (Ta = 25°C)

| Parameter | Symbol | Rating | Unit |
|-------------------------------|------------------|------------|------|
| Supply Voltage | V _{CC} | 18 | V |
| Supply Current | I _{CC} | 20 | mA |
| Power Dissipation | P _D | 450 | mW |
| Operating Ambient Temperature | T _{opr} | -20 ~ +70 | °C |
| Storage Temperature | T _{stg} | -55 ~ +125 | °C |

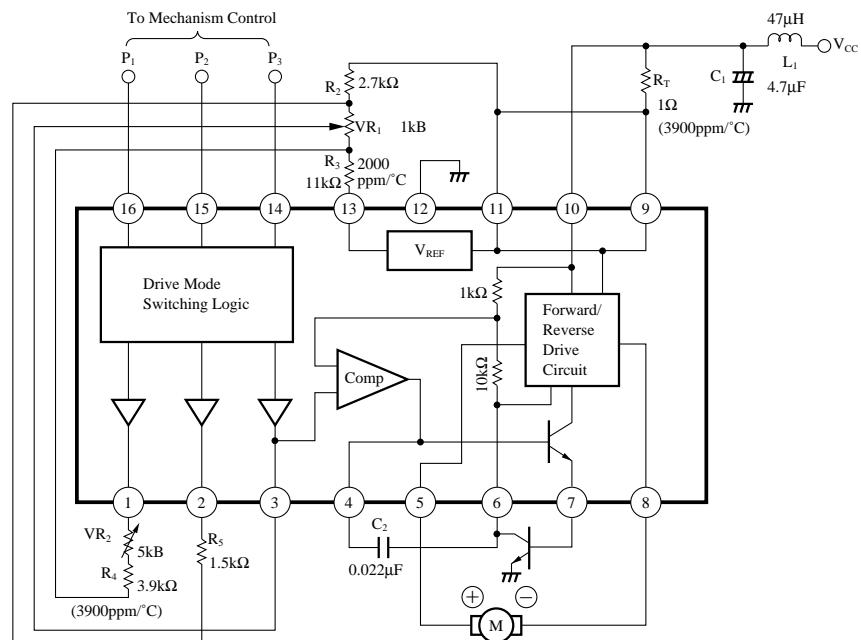
■ Recommended Operating Range (Ta = 25°C)

| Parameter | Symbol | Range |
|--------------------------------|-----------------|----------|
| Operating Supply Voltage Range | V _{CC} | 8V ~ 16V |

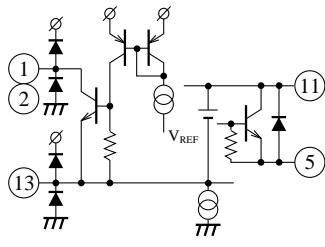
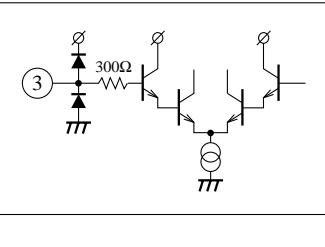
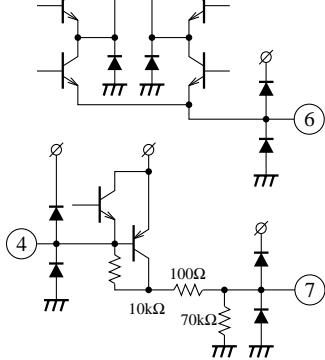
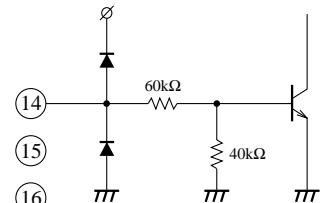
■ Electrical Characteristics (Ta = 25°C)

| Parameter | Symbol | Condition | min. | typ. | max. | Unit |
|--|---------------------|---|-------|------|------|--------|
| Bias Current at No Load | I _{bias} | V _{CC} = 12V | — | 7 | 15 | mA |
| Reference Voltage | V _{ref} | V _{CC} = 12V | 1.15 | 1.27 | 1.4 | mA |
| Rated Load Start Voltage | V _{CC(S)} | Supply voltage at which rotation starts | 6.5 | — | — | V |
| Rated r.p.m. | N _L | V _{CC} = 12V, N = 1600rpm | -8.75 | — | 8.75 | % |
| r.p.m. Characteristics on Load Change | ΔN _L | V _{CC} = 8V, I _L = 55mA ~ 120mA | -20 | — | 20 | rpm |
| r.p.m. Characteristics on Voltage Change | ΔN _V | V _{CC} = 8V ~ 16V, N = 1600rpm | -22 | 0 | 22 | rpm |
| FF/REW r.p.m. Difference | ΔN _{Logi} | V _{CC} = 12V, N = 5300rpm | -3 | 0 | 3 | % |
| Output Saturation Voltage 1 | V _{SAT(1)} | V _{CC} = 8V, I _O = 1A | — | — | 2 | V |
| Output Saturation Voltage 2 | V _{SAT(2)} | V _{CC} = 8V, I _O = 1A | — | — | 1.5 | V |
| r.p.m. Characteristics on Temperature Change | ΔN _A | V _{CC} = 12V, Ta = -10 ~ +60°C | — | 100 | — | ppm/°C |

■ Application Circuit



■ Pin Descriptions

| Pin No. | Pin Name | Pin Descriptions | I/O | Voltage | Equivalent Circuit |
|---------|------------------------------|--|-----|-----------------------|---|
| 1 | Double Speed Setting | Pin to connect the double speed r.p.m. setting resistor | I | V _{CC} -1.5V |  |
| 2 | FF Setting | Pin to connect the FF r.p.m. setting resistor | I | V _{CC} -1.5V |  |
| 3 | Speed Adjustment | Pin to control the rotating speed | I | — |  |
| 4 | Phase Compensation | Pin to connect the oscillation preventive phase compensation capacitor | I | — |  |
| 5 | Motor Drive \oplus | Pin to connect the motor \oplus pin | O | — |  |
| 6 | Collector Connection | Pin to connect the external NPN transistor's collector | O | — |  |
| 7 | Base Connection | Pin to connect the external NPN transistor's base | O | — |  |
| 8 | Motor Drive \ominus | Pin to connect the motor \ominus pin | O | — |  |
| 9 | Load Characteristics Setting | Pin to set the load characteristics of the motor torque | O | — |  |
| 10 | V _{CC} | V _{CC} Pin | I | — | — |
| 11 | To Pin 9 | Connect to Pin 9 | O | — | — |
| 12 | GND | GND pin | I | — | — |
| 13 | Reference Voltage \ominus | Reference voltage \ominus pin | O | V _{CC} -1.5V | — |
| 14 | Logic Input | Operating logic input pin P ₃ | I | — |  |
| 15 | Logic Input | Operating logic input pin P ₂ | I | — | — |
| 16 | Logic Input | Operating logic input pin P ₁ | I | — | — |

■ Supplementary Explanation

- Operating Logic

| Input | | | Output | | | | | |
|-------|-------|-------|--------|------|------|------|------------------------|--|
| Pin14 | Pin15 | Pin16 | Pin5 | Pin8 | Pin1 | Pin2 | Operating Mode | |
| H | H | H | H | L | OFF | ON | FF | |
| L | H | H | L | H | OFF | ON | REW | |
| H | L | H | H | L | OFF | OFF | Constant speed | |
| H | H | L | H | H | OFF | OFF | Brake | |
| L | L | H | H | L | ON | OFF | Double speed | |
| L | H | L | L | H | ON | OFF | Reverse double speed | |
| H | L | L | L | H | OFF | OFF | Reverse constant speed | |
| L | L | L | — | — | OFF | OFF | Pause | |

- Characteristics Curve

