

TOSCATM INTEGRATED ADSL CMOS ANALOG FRONT-END CIRCUIT

- FULLY INTEGRATED AFE FOR ADSL
- OVERALL 12 BIT RESOLUTION, 1.1MHz SIGNAL BANDWIDTH
- 8.8MS/s ADC
- 8.8MS/s DAC
- THD: -60dB @FULL SCALE
- 4-BIT DIGITAL INTERFACE TO/FROM THE DMT MODEM
- 1V FULL SCALE INPUT
- DIFFERENTIAL ANALOG I/O
- ACCURATE CONTINUOUS-TIME CHANNEL FILTERING
- 3rd & 4th ORDER TUNABLE CONTINUOUS TIME LP FILTERS
- 0.5 WATT AT 3.3V
- 0.5µm HCMOS5 LA TECHNOLOGY
- 64 PIN TQFP PACKAGE

DESCRIPTION

STLC60134S is the Analog Front End of the STMicroelectronics Tosca $^{\rm TM}$ ADSL chipset and when coupled with STLC60135 (DTM modem) al-



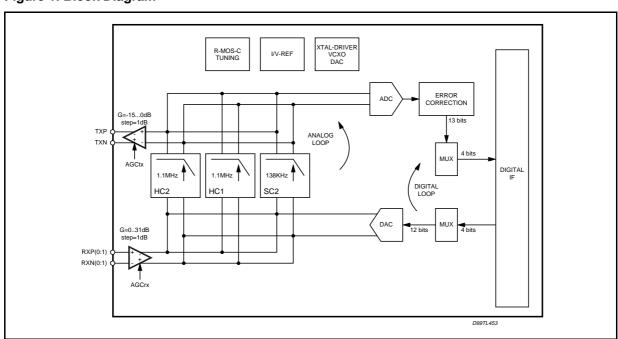
lows to get a T1.413 Issue 2 compliant solution.

The STLC60134S analog front end handles 2 transmission channels on a balanced 2 wire interconnection; a 16 to 640Kbit/s upstream channel and a 1.536 to 8.192Mbit/s downstream channel.

A 256 carrier DMT coding (frequency spacing 4.3125kHz) transforms the downstream channel to a 1MHz bandwidth analog signal (tones 32-255) and the upstream channel (tones 8-31) to a 100kHz bandwidth signal on the line.

This asymmetrical data transmission system uses high resolution, high speed analog to digital and digital to analog conversion and high order analog filtering to reduce the echo and noise in both

Figure 1. Block Diagram



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the ATU-C/ATU-R receivers and transmitters. External low noise driver and input stage used with STLC60134S guarantee low noise performances.

The STLC60134S chip can be used at ATU-C and ATU-R ends (behaviour set by LTNT pin). The selection consists mainly of a filter interchange between the RX and TX path. The filters (with a programmable cutoff frequency) use automatic Continuous Time Tuning to avoid time varying phase characteristic which can be of dramatic consequence for DMT modem. It requires few external components, uses a 3.3V supply (a separate 3.0V supply of the digital part is possible) and is packaged in a 64-pin TQFP in order to reduce PCB area.

The Receiver (RX) part

The DMT signal coming from the line to the STLC60134S is first filtered by the two following external filters:

POTS HP filter: Attenuation of speech and POTS

signalling

Channel filter: Attenuation of echo signal to

improve RX dynamic

An analog multiplexer allows the selection between two input ports which can be used to select an attenuated (0, 10dB for ex.) version of the signal in case of short loop or large echo. The signal is amplified by a low noise gain stage (0-31dB) then low-pass filtered to avoid anti-aliasing and to ease further digital processing by removing unwanted high frequency out-of-band noise. A 12-bit A/D converter samples the data at 8.832MS/s (or 4.416MS/s in alternative mode), transforms the signal into a digital representation and sends it to the DMT signal processor via the digital interface.

The Transmitter (TX) part

The 12-bit data words at 8.832MS/s (or 4.416MS/s) coming from the DMT signal processor through the digital interface are transformed by D/A converter into a analog signal.

This signal is then filtered to decrease DMT sidelobes level and meet the ANSI transmitter spectral response but also to reduce the out-of-band noise (which can be echoed to the RX path) to an acceptable level. The pre-driver buffers the signal for the external line driver and in case of short loop provide attenuation (-15...0dB).

The VCXO part

The VCXO is divided in a XTAL driver and a auxiliary 8 bits DAC for timing recovery.

The XTAL driver is able to operate at 35.328MHz and provides an amplitude regulation mechanism to avoid temperature / supply / technology de-

pendent frequency pulling.

The DAC which is driven by the CTRLIN pin provides a current output with 8-bit resolution and can be used to tune the XTAL frequency with the help of external components. A time constant between DAC input and VCXO output can be introduced (via the CTLIN interface) and programmed with the help of an external capacitor (on VCOC pin).

See chapter 'VCXO' for the external circuit related to the VCXO.

The Digital Interface part

The digital part of the STLC60134S can be divided in 3 sections:

- The data interface converts the multiplexed data from/to the DMT signal processor into valid representation for the TX DAC and RX ADC. It performs also the error correction mechanism needed at the (redundant) ADC output.
- The control interface allows the board processor to configure the STLC60134S paths (RX/TX gains, filter band, ...) or settings (OSR, vcodac enable, digital / analog loopback,...).
- The test interface to enable digital (Full Scan, nandtree, loop backs, functional,...) or analog (TIN, TOUT assignation) tests to be performed.

DMT Signal

A DMT signal is basically the sum of N independently QAM modulated signals, each carried over a distinct carrier. The frequency separation of each carrier is 4.3125kHz with a total number of 256 carriers (ANSI). For N large, the signal can be modelled by a gaussian process with a certain amplitude probability density function. Since the maximum amplitude is expected to arise very rarely, we decide to clip the signal and to tradeoff the resulting SNR loss against AD/DA dynamic. A clipping factor (Vpeak/Vrms = "crest factor") of 5 will be used resulting in a maximum SNR of 75dB.

ADSL DMT signals are nominally sent at -40dBm/Hz ±3dB (-3.65dBm/carrier) with a maximal power of 100mW for down link transmitter and 15.7mW for uplink transmitter.

DMT symbols are transmitted without 'windowing' causing sin (x)/x like sidelobes. For spectral response shaping, the 1st sidelobe level is assumed to be 13dB under the carrier level with an attenuation of -20dB/dec.

The minimum SNR + D needed for DMT carrier demodulation is about $(3 \cdot N + 20)$ dB with a minimum of 38dB were N is the constellation size of a carrier (in bits).

Maximum / minimum signal levels

The following table gives the transmitted and received signal levels for both ATU-R and ATU-C sides. All the levels are referred to the line voltages (i.e. after hybrid and transformers in TX direction, before hybrid and transformer in RX direction).

Note that signal amplitudes shown below are for illustration purpose and depending on the trans-

mit power and line impedance signal amplitudes can differ from these values.

The reference line impedance for all power calculations is 100Ω .

PACKAGE

The STLC60134S is packaged in a 64-pin TQFP package (body size 10x10mm, pitch 0.5mm).

Table 1. Target Signal Levels (on the line).

Parameter		ATU - C		ATU - R	
	RX	TX	RX	TX	
Max level	839 mVpdif	15.8 Vpdif	3.95 Vpdif	3.4 Vpdif	
Max RMS level	168 mVrms	3.16 Vrms	791 mVrms	671 mVrms	
Min level	54 mVpdif	3.95 Vpdif	42 mVpdif	839 mVpdif	
Min RMS level	11 mVrms	791 mVrms	8 mVrms	168 mVrms	

Table 2. Total Signal Level (on the line).

Parameter	ATU - C		Parameter ATU - C ATU - R		J - R
	RX	TX	RX	TX	
Max level for receiver	4 Vpdif (Long line)		4.2 Vpdif (Short line)		

Figure 2. Pin Connection

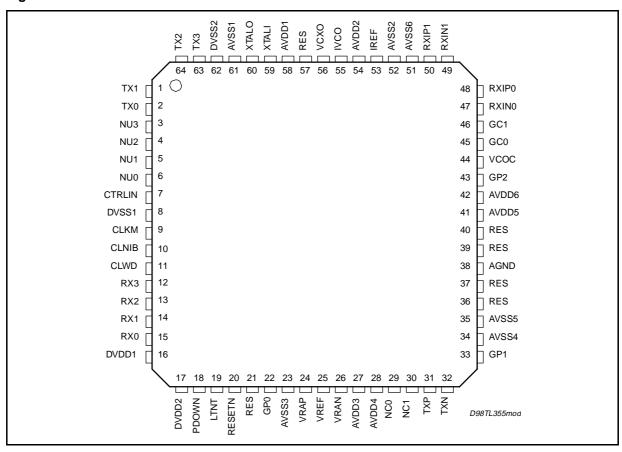


Table 3. Pin Functions.

N.	Name	Function	PCB connection	Supply
ANALO	G INTERF	ACE		
24	VRAP	positive voltage reference ADC	Decoupling network	AVDD3
25	VREF	ground reference ADC	Decoupling network	
26	VRAN	negative voltage reference ADC	Decoupling network	
31	TXP	pre driver output	Line driver input	AVDD4
32	TXN	pre driver output	Line driver input	AVDD4
38	AGND	virtual analog ground (AVDD/2 = 1.65V)	Decoupling network	
44	VCOC	VCODAC time constant capacitor	VCODAC cap.	AVDD5
45	GC0	External gain control output LSB		AVDD5
46	GC1	External gain control output MSB		AVDD5
47	RXN0	analog receive negative input Gain 0	Echo filter output	AVDD5
48	RXP0	analog receive positive input Gain 0	Echo filter output	AVDD5
49	RXN1	analog receive negative input Gain 1 (most sensitive input)	Echo filter output	AVDD5
50	RXP1	analog receive positive input Gain 1 (most sensitive input)	Echo filter output	AVDD5
53	IREF	current reference TX DAC/DACE	Decoupling network	
55	IVCO	current reference VCO DAC	VCO bias network	AVDD1
56	VCXO	VXCO control current	VCXO filter	AVDD1
59	XTALI	XTAL oscillator input pin	Crystal + varicap	AVDD1
60	XTALO	XTAL oscillator output pin	Crystal + varicap	AVDD1
	L INTERFA			
1	TX1	digital transmit input, parallel data		DVDD2
2	TX0	digital transmit input, parallel data		DVDD2
7	CTRLIN	serial data input (settings)	Async Interface	DVDD2
9	CLKM	master clock output, f = 35.328MHz	Load = CL<30pF	DVDD2
10	CLNIB	nibble clock output, f = 17.664MHz (OSR = 2) or ground (OSR = 4)	Load = CL<30pF	DVDD2
11	CLWD	word clock output, f = 8.832/4.416MHz	Load = CL<30pF	DVDD2
12	RX3	digital receive output, parallel data	Load = CL<30pF	DVDD2
13	RX2	digital receive output, parallel data	Load = CL<30pF	DVDD2
14	RX1	digital receive output, parallel data	Load = CL<30pF	DVDD2
15	RX0	digital receive output, parallel data	Load = CL<30pF	DVDD2
18	PDOWN	power down select, "1" = power down	Power down input	DVDD2
19	LTNT	ATU-R / ATU-C select pin ¹ , ATU-R = 0 /ATU-C = 1 / test mode MSB	VDD in ATU-C mode	
20	RESETN	reset pin (active low)	RC- reset	DVDD2
22	GP0	General purpose output 0 (on AVDD 1)	Echo filter output	AVDD
33	GP1	General purpose output 1 (on AVDD 1)	Echo filter output	AVDD
43	GP2	General purpose output 2 (on AVDD 1)	Echo filter output	AVDD
63	TX3	digital transmit input, parallel data	Load = CL<30pF	DVDD2
64	TX2	digital transmit input, parallel data	Load = CL<30pF	DVDD2
21	RES	RESERVED	Must be connected to DVSS (input)	
36, 37, 39, 40, 57	RES	RESERVED	Must be connected to AVSS (input)	
SUPPL	Y VOLTAG	ES		
8	DVSS1		DVSS	
16	DVDD1	Digital I/O supply voltage	DVDD	
17	DVDD2	digital internal supply voltage	DVDD	
		 - 		
23	AVSS3		AVSS	

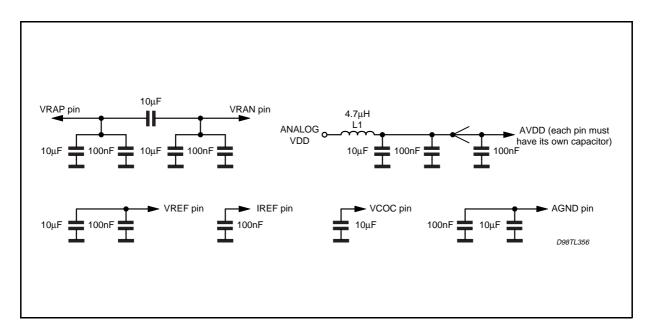
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Table 3. Pin Functions (continued)

28	AVDD4	TX pre - drivers supply	AVDD
34	AVSS4		AVSS
35	AVSS5		AVSS
41	AVDD5	CT filter supply	AVDD
42	AVDD6	LNA supply	AVDD
51	AVSS6		AVSS
52	AVSS2		AVSS
54	AVDD2	DAC and support circuit	AVDD
58	AVDD1	XTAL oscillator supply voltage	AVDD
61	AVSS1		AVSS
62	DVSS2		DVSS
SPARE	S		
3	NU3	Not used inputs	DVSS
4	NU2	Not used inputs	DVSS
5	NU1	Not used inputs	DVSS
6	NU0	Not used inputs	DVSS
29	NC0		
30	NC1		

 $^{^{1}}$ LT \leftrightarrow AUT-C; NT \leftrightarrow ATU-R

Figure 3. Grounding and Decoupling Networks.



ATU-C END: BLOCK DIAGRAM

The transformer at ATU-C side has 1:2 ratio. The termination resistors are 12.5 Ω in case of 100 Ω lines.

The hybrid bridge resistors should be < $2.5k\Omega$ for low-noise.

An HP filter must be used on the TX path to re-

duce DMT sidelobes and out of band noise influence on the receiver. On the RX path, a LP filter must be used in order to reduce the echo signal level and to avoid saturation of the input stage of the receiver.

The POTS filter is used in both directions to reduce crosstalk between STLC60134S signals and POTS speech and signalling.

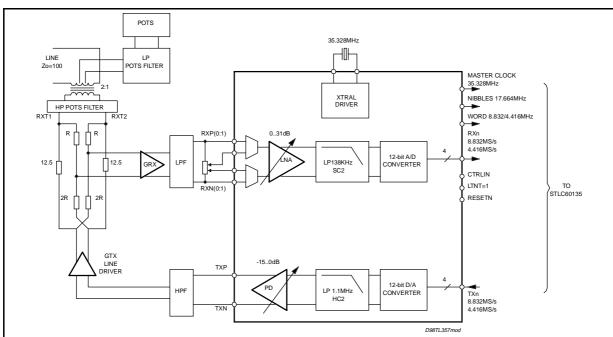


Figure 4. ATU-C END Block Diagram.

ATU-R END: BLOCK DIAGRAM

The ATU-R side block diagram is equal to the ATU-C side block diagram with the following differences:

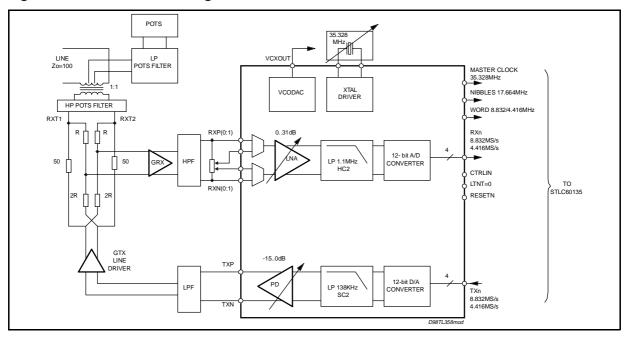
- The transformer ratio is 1:1
- Termination resistors are 50Ω for 100Ω lines.

An LP filter may be used on the TX path to re-

duce DMT sidelobes and out of band noise influence on the receiver. On the RX path, a HP filter must be used in order to reduce the echo signal level and to avoid saturation of the input stage of the receiver.

The POTS filter is used in both directions to reduce crosstalk between ADSL signals and POTS speech and signalling. Low pass POTS filter can be very simple for Lite - ADSL application

Figure 5. ATU-R END Block Diagram.



RX PATH

Speech filter

An external bi-directional LC filter for up and downstream POTS service splits the speech signal from the ADSL signal to the POTS circuits on ATU-C.

The ADSL analog front end integrated circuit does not contain any circuitry for the POTS service but it guarantees that bandwidth is not disturbed by spurious signals from the ADSL-spectrum.

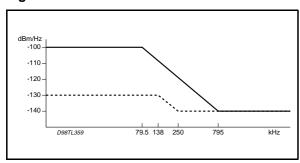
Channel Filters

The external analog circuits provide partial echo cancellation by an analog filtering of the receive signal for both ATU-R (Reception of downstream channel) and ATU-C (Reception of upstream channel). This is feasible because the upstream and the downstream data can be modulated on separate carriers (FDM).

Line Noise Model

The power spectral density of the crosstalk noise sources as described in ANSI document is given in the figure below (no HDB3 interferer signals). Also given in dotted line, is the noise model used in this document to specify the sensivity requirements which are stronger than the original ones.

Figure 6. Crosstalk PSD.



Signal to Noise Performance

RX- PATH SENSITIVITY AT MAXIMUM GAIN

The RX path sensitivity at the maximal RX-AGC of the ATU-R receiver is defined at -140dBm/Hz (for 100Ω ref) on the line. This figure corresponds to the equivalent input noise of $31\text{nVHz}^{-1/2}$ seen on the line.

The sensitivity at the maximal RX - gain of the ATU-C receiver is defined at -130dBm/Hz (for 100 Ω ref) on the line. The figure corresponds to the equivalent input noise of 100nVHz^{-1/2} seen on the line.

Both noise figures include the noise of the hybrid. It is the equivalent average thermal noise over

the frequency band of interest. The maximum noise density within the pass band can exceed the average value as follows:

ATU-R RX path (max AGC setting):

<100nVHz^{-1/2} @ 138kHz

 $<31 \text{nVHz}^{-1/2} \text{ for } 250 \text{kHz} < \text{f}$

ATU-C RX path (max AGC setting):

<100nVHz^{-1/2} for 34.5kHz < f <138kHz

RX-PATH NOISE AT MINIMUM GAIN

At the minimum AGC the total average thermal noise of the analog RX-path at the ADC input should be lower than the ADC quantisation noise. The maximum noise density within the pass band can exceed the average value as follows:

ATU-R RX path (min AGC setting):

<500nVHz^{-1/2} @ 138kHz < f

ATU-C RX path (min AGC setting):

 $<1.5\mu VHz^{-1/2}$ @ 34.5kHz < f < 138kHz

These noise specifications correspond with 10bit resolution of the complete RX-path.

Table 4. RX Common-mode Voltage

Description	Value/Unit	
Common mode signal V _{CM} at RXIN1 and RXIN2:	1.6V < V _{CM} <1.7V	

AGC of RX path

The AGC gain in the RX-path is controlled through a 5-bits digital code.

Four inputs are provided for RX input and the selection is made with the RXMUX bits of the CTRLIN interface. This can be used to make lower gain paths in case of high input signal.

Table 5. AGC Characteristics.

Description	Value/Unit
Input referred noise (max. gain)	20nVHz ^{-1/2}
Max. input level	1Vpd
Max. output level	1Vpd
Gain range	0 to 31dB with step = 1dB
Gain and step accuracy	± 0.3dB

RX Filters

The combination of the external filter (an LC ladder filter typically) with the integrated lowpass filter must provide:

- echo reduction to improve dynamic range
- DMT sidelobe and out of band (anti-aliasing) attenuation.
- Anti alias filter (60dB rejection @ image freq.)

ATU-R RX Filters

The integrated filter have the following characteristics:

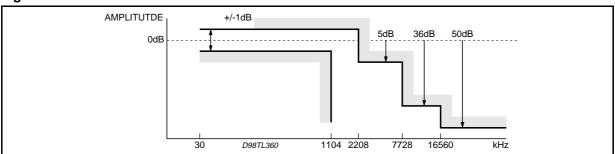
Table 6. Integrated HC Filter Characteristics

Description	Value/Unit
Input referred noise	100nVHz ^{-1/2}
Max. input level	1Vpd
Max. output level	1Vpd
Туре	3rd order butterworth
Frequency band	1.104MHz (0%setting, see below)
Frequency tuning	-43.75% -> +0%
Max. in-band ripple	1dB
Matlab Model Default cut off frequency @ -3dB Actual cut off @ -3dB HC Freq. selection register	[B, A] = butter (3, w0, 's') F0 = 1560KHz w0 = 2 * pi * F0/((20 + n)/16) n = -4,,3 see (AFE settings ,Table 22)

Table 7. Phase Characteristic

Description	Value/Unit
Total RX filter group delay	< 50μs @ 138kHz < f < 1.104MHz
Total RX filter group delay distortion	< 15μs @ 138kHz < f < 1.104MHz

Figure 7. HC Filter Mask for ATU-R RX and ATU-C TX



Note: The total ATU_R RX path (including ADC) group delay distortion is $16\mu s$ (i.e. = $15\mu s$ + $1\mu s$ of ADC)

ATU-C RX filter

This filter is the same as the one used for ATU-R TX.

Linearity of RX

Linearity of the RX analog path is defined by the IM3 product of two sinusoidal signals with frequencies f1 and f2 and each with 0.5Vpd amplitude (total \leq 1Vpd) at the output of the RX - AGC amplifier (i.e: before the ADC) for the case of minimal AGC setting.

The following tables 8 and 9 list the RX path intermodulation distortion (as S/IM3 ratio) in downstream and upstream bandwidth.

Table 8. Linearity of ATU-R RX

f1 (0.5Vpd)	300kHz	500kHz	700kHz
f2 (0.5Vpd)	200kHz	400kHz	600kHz
S/IM3 (AGC = 0dB)	59.5dB @ 100kHz 53.5dB @ 400kHz 43.5dB @ 700kHz 42.5dB @ 800kHz	59.5dB @ 300kHz 48.0dB @ 600kHz	48.0dB @ 500kHz 42.5dB @ 800kHz

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Table 9. Linearity of ATU-C RX

f1 (0.5Vpd)	80kHz
f2 (0.5Vpd)	70kHz
S/IM3 (AGC = 20 dB) 2f2 - 2f1 -	

Table 10. RX Filter to A/D Interface

	1
RX filter to A/D maximal level:	1Vpd = full scale of A/D

Table 11. A/D Convertors (A pipeline architecture is used for A/D convertors).

Numbers of bits:	12bits
Minimum resolution of the A/D convertor	11bits
Linearity error of the A/D convertor	<1LSB (out of 12bits)
Full scale input range:	1 Vpdif ±5%
Sampling rate:	8.832MHz (or 4.416MHz in OSR = 2 mode)
Maximum attenuation at 1.1MHz:	<0.5dB without in-band ripple
Maximum group delay:	<3μs
Maximum group delay distortion:	<1μs

Power Supply Rejection

The noise on the power supplies for the RX path must be lower than the following: <50mVrms in band white noise for any AVDD.

In this case, PSR (power supply rejection) of STLC60134S RX path is lower than -43dB.

TX PATH

Transmitter Spectral Response

The two figures below show the ANSI spectral response mask for ATU-C and ATU-R transmitters

Figure 8. ATU-C TX spectral response mask

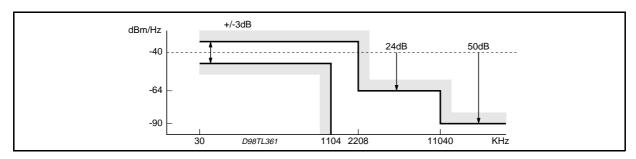


Figure 9. ATU-R TX spectral response mask

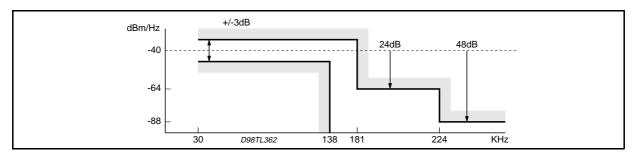


Table 12. AGC of TX Path (from filter output to TXP and TXN).

Output noise	25mVHz ^{-1/2}				
Input level (nominal)	1Vpd				
Output level nominal, full-scale	1.5Vpd				
Maximum Output Load	> 500Ω; <10pF				
AGC range:	-15dBdB				
AGC step:	1dB				
Gain and step accuracy	±0.3dB				

Minimum code (0000) stands for AGC = -15dB and maximum (1111 - MSB left) for AGC = 0dB (See Tx setting, Table22).

TX Pre-driver Capability

The pre-driver drives an external line power amplifier which transmits the required power to the line.

Table 13. TX Pre-driver

TX drive level to the external line driver for max. AGC setting		1.5 Vpdif
External line driver input impedance:	resistive capacitive	> 500Ω < 30pF
Pre-driver characteristics:	•	•
closed loop gain:	-15dB0dB with step = 1dB	
ooutput impedance:		
output offset voltage (0dB)	< 10mV	
input noise voltage (0dB)	< 20nVHz ^{-1/2} @ f > 250kΩ $<$ 50nVHz ^{-1/2} @ 34.5K $<$ f $<$ 138kΩ	
output common mode voltage:	1.6V < Vcm < 1.7V	

TX Filter

The TX filters act not only to suppress the DMT sidebands but also as smoothing filters on the D/A convertor's output to suppress the image spectrum. For this reason they must be realized in a continuous time approach.

ATU-R TX Filter

The purpose of this filter is to remove out-of-band noise of the ATU-R TX path echoed to the ATU-R RX path. In order to meet the transmitter spectral response, an additional filtering must be (digitally) performed. The integrated filter has the following characteristics:

Table 14. Integrated SC Filter Characteristics

Description	Value/Unit				
Input referred noise	100nVHz ^{-1/2}				
Max. input level	1Vpd				
Max. output level	1Vpd				
Туре	4th order chebytchef				
Frequency band	138kHz (0% setting see below)				
Frequency tuning	-25% -> +25%				
Max. in-band ripple	1dB				
Matlab Model Default cut-off frequency @ -3dB Actual cut-off @ -3dB SC Freq. selection register	[B,A] = cheby1 (4,0.5,W0,'s') {ripple = 0.5} F0 = 151.8kHz W0 = 2*pi*F0/((17+n)/16) n = -4,,3 see (AFE settings, Table 22)				

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Table 15. Phase characteristics

Description	Value/Unit
Total TX filter group delay	<50μs @ 34.5kHz < f < 138kHz
Total TX filter group delay distortion	<20μs @ 34.5kHz < f < 138kHz

Note: The total ATU-R TX path (including DAC) group delay distortion is $16\mu s$ (i.e. = $15\mu s$ + $1\mu s$ of DAC)

Figure 10. SC Filter Mask for ATU-CRX and ATU-R TX

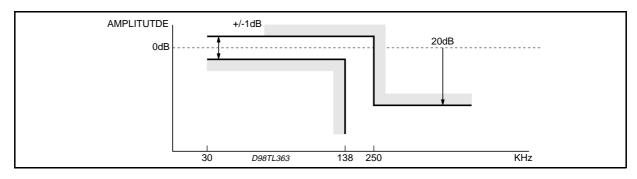


Table 16. D/A Convertor (A current steering architecture is used).

Description	Value/Unit
Numbers of bits:	12bits
Minimum resolution of the D/A convertors	11bits
Linearity error of the A/D convertor	<1LSB (out of 12bits)
Full scale input range:	1 Vpdif ±5%
Sampling rate:	8.832MHz (or 4.416MHz in compatible mode)
Maximum group delay:	<3μs
Maximum group delay distortion:	<1μs

Linearity of ATU-C TX

Linearity of the TX is defined by the IM3 product of two sinusoidal signals with frequencies f1 and f2 and each with 0.5Vpd amplitude (total \leq 1Vpd) at the output of the pre-driver for the case of a total AGC = 0dB.

Table 17. Linearity of ATU-C TX

f1 (0.5Vpd)	300kHz	500kHz	700kHz
f2 (0.5Vpd)	200kHz	400kHz	600kHz
S/IM3 (AGC = 0dB)	59.5dB @ 100kHz 53.5dB @ 400kHz 43.5dB @ 700kHz 42.5dB @ 800kHz	59.5dB @ 300kHz 48.0dB @ 600kHz	48.0dB @ 500kHz 42.5dB @ 800kHz

Linearity of ATU-R TX

Table 18. Linearity of ATU-R TX

f1 (0.5Vpd)	80kHz
f2 (0.5Vpd)	70kHz
S/IM3 (AGC = 0 dB)	59.5dB (@ 60KHz, 90KHz)

TX IDLE CHANNEL NOISE

ATU-C TX idle channel noise

The idle channel noise specifications correspond with 11bit resolution of the complete TX-path. ATU-C TX idle channel output noise on TX.

Table 19. ATU-C TX idle channel noise

For max AGC setting (0dB)								
In-band noise								
For min AGC setting (=-15dB)								
In-band noise	80nVHz ^{-1/2}	@ 138kHz -1.104MHz						

ATU-R TX idle channel noise

ATU-R TX idle channel output noise on TXP, TXN

Table 20. ATU-R TX idle channel noise

For max AGC setting (0dB)									
In-band noise Out-of-band noise	1.6μVHz ^{-1/2} 1.6μVHz ^{-1/2} 150nVHz ^{-1/2}	@ 34.5kHz -138kHz @ 138kHz @ 250kHz -1.104MHz							
For min AGC setting (=-15dB)									
In-band noise 500nVHz ^{-1/2} @ 34kHz -138kHz									

Power Supply Rejection

The noise on the power supplies for the TX-path must be lower than the following:

- < 50mVrms in-band white noise for AVDD.
- < 15mVrms in-band white noise for Pre-driver AVDD.

VCXO

A voltage controlled crystal oscillator driver is integrated in STLC60134S. The nominal frequency is 35.328MHz. The quartz crystal is connected between the pins XTALI and XTALO. The principle of the VCXO control is shown in figure 11.

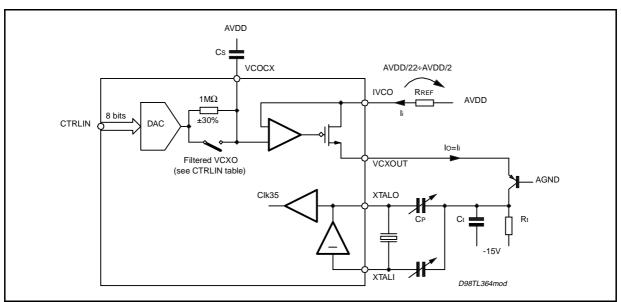
The information coming from the digital processor via the CTRLIN path is used to drive an 8-bit DAC which generates a control current. This current is externally converted and filtered to generate the required control voltage (range:-15V to 0.5V) for the varicap. The VCXO circuit characteristics are given in Table 21.

Table 21. VCXO circuit Characteristics

Symbol	Parameter	Min.	Nominal	Max.	Note
f _{abs}	Absolute frequency accuracy	-15ppm	35.328MHz	+15ppm	
frange	Frequency Tuning Range		±50ppm		
lo	VCXO Output Current		100μΑ		Rref = $16.5k\Omega$ AVDD = $3.3V$
li	Reference Input Current	100μΑ		1mA	AVDD = 3.3V

N.B: frequency tuning range is proportional to the crystal dynamic capacitance C_m.

Figure 11. Principle of VCXO control



The tuning must be monotonic with 8-bit resolution with the worst-case tuning step of <2ppm/LSB (8-bit). The time constant of the tuning must be variable from 5s to 10s through an external capacitor C_s (R = 1M Ω ±30%). This determines the speed of the VCXO in normal operation (slow speed in "show time") with filtered VCXO. For faster tracking, the previous filter is not used and the speed depends on CtRt.

DIGITAL INTERFACE

Control Interface

The digital setting codes for the STLC60134S configuration are sent over a serial line (CTRLIN) using the word clock (CLWD).

The data burst is composed of 16 bits from which the first bit is used as start bit ('0'), the three LSBs being used to identify the data contained in the 12 remaining bits. Test related data are overruled by the normal settings if the TEST pin is low.

Table 22. Control Interface Bit Mapping

M S B	
b b b b b b b b b b	
5 4 3 2 1 0	
0 x 0 0 0 External Gain Control GC1	(init = 0)
0 x 0 0 0 External Gain Control GC0	(init = 0)
0 0 0 Rx input selected = RXIN0, RXIP0	(init)
0 1 0 0 0 Rx input selected = RXIN1, RXIP1	
0 0 0 0 0 0 0 0 AGC RX Gain setting 0dB	(init)
0 0 0 0 1 0 0 0 AGC RX Gain setting 1dB	
0 x x x x x x	
0 1 1 1 1 1 1 0 0 0 AGC RX Gain setting 31dB	
0 0 0 Normal mode Filter selection see L	TNT pin (init)
0 1 0 0 0 In ATU-C conf, force HC2 for RX pa	ath, TX grounded
0 1 0 0 0 0 In ATU-C conf, force HC1 for RX pa	ath
0 1 1 1 0 0 0 Normal mode Filter selection see L'	TNT pin
b b b b b b b b b b	
1 1 1 1 1 9 8 7 6 5 4 3 2 1 0 TX SETTINGS	
0 0 0 0 0 0 Transmit TX - AGC setting -15dB	(init)
0 0 0 1 0 1 0 1 Transmit TX - AGC setting -14dB	
0 x x x x x	dB
0 1 1 1 1 1 0 0 0 1 Transmit TX - AGC setting 0dB	
0 0 0 0 0 0 1 Not used	(init)
0 0 0 0 0 0 1 Not used	(init)
0 0 0 0 0 0 1 Not used	(init)
0 0 0 0 0 0 1 Not used	(init)
0	ting (init = 000)
b b b b b b b b b b b b b b b b b b b	
b b	(init)
b b	\ ',
b b	RX - DAC not used)
b b	RX - DAC not used)
b b	RX - DAC not used)
b b	RX - DAC not used)
b b	RX - DAC not used) not used) 1) (init)

¹⁾ After initialization, this bit has to be cleared (0) to make the device properly operate.

Table 22. Control Interface Bit Mapping (continued)

b 1 5	b 1 4	b 1 3	b 1 2	b 1 1	b 1 0	b 9	b 8	b 7	b 6	b 5	b 4	b 3	b 2	b 1	b 0	AFE SETTINGS
0					0								0	1	0	OSR set to 4 (init)
0					1								0	1	0	OSR set to 2
0						1	1	1					0	1	0	SC freq. selection: Fc = 138kHz (init) (*)
0						0	1	1					0	1	0	SC freq. selection: Fc ~ 110kHz (*)
0						1	0	1					0	1	0	SC freq. selection: Fc ~ 170kHz (*)
0									1	0	0		0	1	0	HC freq. selection: Fc = 1.104MHz (init) (*)
0									0	1	1		0	1	0	HC freq. selection: Fc ~ 768kHz (*)
0												0	0	1	0	VCXO output NOT filtered ("show-time") (init)
0												1	0	1	0	VCXO output filtered
b 1 5	b 1 4	b 1 3	b 1 2	b 1	b 1 0	b 9	b 8	b 7	b 6	b 5	b 4	b 3	b 2	b 1	b 0	VCO DAC VALUE SETTINGS
0	0	0	0	0	0	0	0	0					0	1	1	VCO DAC CURRENT value @ MINIMUM
0	Х	Х	Х	Х	Х	Х	Х	Х					0	1	1	VCO DAC CURRENT value @ X
0	1	1	1	1	1	1	1	1					0	1	1	VCO DAC CURRENT value @ MAXIMUM
b 1 5	b 1 4	b 1 3	b 1 2	b 1	b 1 0	b 9	b 8	b 7	b 6	b 5	b 4	b 3	b 2	b 1	b 0	POWER DOWN ANALOG BLOCK SETTINGS
0	0												1	0	0	TXD Active (init)
0	1												1	0	0	TXD in powerdown
0		0											1	0	0	N.U. (init)
0		1											1	0	0	N.U.
0			0										1	0	0	ADC Active (init)
0			1										1	0	0	ADC in powerdown
0				0									1	0	0	HFC2 Active (init)
0				1									1	0	0	HFC2 in powerdown
0					0								1	0	0	HFC1 Active (init)
0					1								1	0	0	HFC1 in powerdown
0						0							1	0	0	SCF2 Active (init)
0						1							1	0	0	SCF2 in powerdown
0							0						1	0	0	SCF1 Active (init)
0							1						1	0	0	SCF1 in powerdown
0								0					1	0	0	LNA Active (init)
0								1					1	0	0	LNA in powerdown
0									0				1	0	0	DAC Active (init)
0									1				1	0	0	DAC in powerdown
0										0			1	0	0	DACE Active (init)
0										1			1	0	0	DACE in powerdown
0											0		1	0	0	VCODAC Active (init)
0											1		1	0	0	VCODAC in powerdown
0												0	1	0	0	XTAL Active (init)
0												1	1	0	0	XTAL in powerdown
b 1 5	b 1 4	b 1 3	b 1 2	b 1 1	b 1 0	b 9	b 8	b 7	b 6	b 5	b 4	b 3	b 2	b 1	b 0	RESERVED
0	Х	Х	Х	Х	Х	Х	Х	х	х	х	Х	Х	1	0	1	RESERVED
0	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	1	1	0	RESERVED
0	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	1	1	1	RESERVED

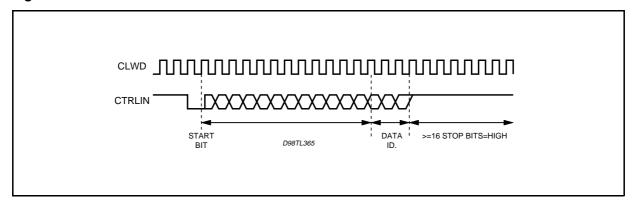
^(*) For each filter, 8 possible frequency values (see table 6 and table 14). Notation is 2's complement range from -4 = 100b +3 = 011b. Fc is the frequency band (-1dB)



Control Interface Timing

The word clock (CLWD) is used to sample at negative going edge the control information. The start bit b15 is transmitted first followed by bits b[14:0] and at least 16 stop bits need to be provided to validate the data.

Figure 12. Control Interface.



Data set-up and hold time versus falling edge CLWD must be greater than 10nsec.

Receive / Transmit Interface

RECEIVE / TRANSMIT PROTOCOL

The digital interface is based on 4 x 8.832MHz (35.328MHz) data lines in the following manner:

If OSR = 2 (OSR bit set to 1) is selected, CLKNIB is used as nibble clock (17.664MHz, disabled in normal mode), and all the RXi, TXi, CLKWD periods are twice as long as in normal mode. This ensures a compatibility with lower speed products.

TX Signal Dynamic

The dynamic of data signal for both TX DACs is 12 bits extracted from the available signed 16 bit representation coming from the digital processor.

The maximal positive number is 2¹⁴-1, the most negative number is -2¹⁴, the 3 LSBs are filled with '0'. Any signal exceeding these limits is clamped to the maximum value.

Table 23.

BIT MAP/NIBBLE	N0	N1	N2	N3
TXD0	not used	data bit 1	data bit 5	data bit 9
TXD1	not used	data bit 2	data bit 6	data bit 10
TXD2	not used	data bit 3	data bit 7	data SIGN
TXD3	d0 = data bit 0 (LSB)	data bit 4	data bit 8	data SIGN

Table 24. TX bit map

	N	13			N	12			N	1			N	0		
sian	sian	d10	49	d8	d7	d6	d5	d4	d3	d2	d1	d0	n u	nи	nи	1

The two sign bits must be identical.

RX Signal Dynamic

The dynamic of the signal from the ADC is limited to 13bits. Those bits are converted to a signed (2's complement) representation with a maximal positive number of 2^{14} -1 and a most negative number - 2^{14} . The 2 LSBs are filled with '0'.

Table 25.

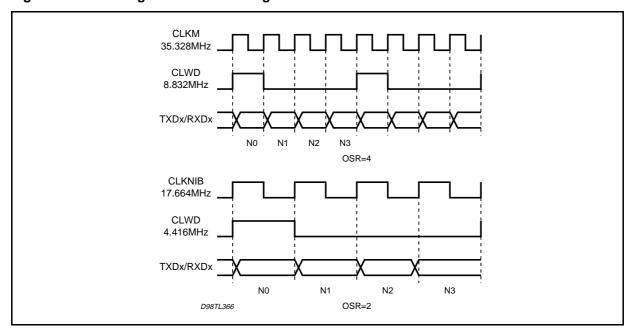
BIT MAP/NIBBLE	N0	N1	N2	N3
RXD0	0	data bit 2	data bit 6	data bit 10
RXD1	0	data bit 3	data bit 7	data bit 11
RXD2	d0 = data bit 0 (LSB)	data bit 4	data bit 8	data SIGN
RXD3	data bit 1	data bit 5	data bit 9	data SIGN

Table 26. RX bit map

	N	13			N	2			N	1			N	0		
sign	sign	d11	d10	d9	d8	d7	d6	d5	d4	d3	d2	d1	d0	0	0	

The two sign bits must be identical.

Figure 13. TX/ RX Digital Interface Timing



Receive / Transmit interface timing

The interface is a triple (RX, TX) nibble - serial interface running at 8.8 MHz sampling (normal mode). The data are represented in 16bits format, and transferred in groups of 4 bits (nibbles). The LSBs are transferred first. The STLC60134S generates a nibble clock (CLKM master clock in normal mode, CLKNIB in OSR = 2 mode) and word signals shared by the three interfaces.

Data is transmitted on the rising edge of the master clock (CLKM/CLKNIB) and sampled on the falling edge of CLKM/CLKNIB. This holds for the data stream from STLC60134S and from the digital processor

Data, CLWD setup and hold times are 5ns with reference to the falling edge of CLKM/CLKNIB. (not floating).

Data is transmitted on the rising edge of the master clock (CLKM/CLKNIB) and sampled on the low going edge of CLKM/CLKNIB. This holds for the data stream from STLC60134S and from the digital processor. Data, CLWD setup and hold times are 5ns with reference to the falling edge of CLKM/CLKNIB. (not floating).

POWER DOWN

When pin Pdown = "1", the chip is set in power down mode. As the Pdown signal is synchronously sampled, minimum duration is 2 periods of the 35MHz clock. In this mode all analog functional blocks are deactivated except: preamplifiers (TX), clock circuits for output clock CLKM. P_{down} will not affect the digital part of the chip. Anyway, after a Pdown transition, the digital part status, is updated after 3 clock periods (worst case)

The chip is activated when Pdown = "0".

In power down mode the following conditions hold:

- Output voltages at TXP/TXN = AGND
- Preamplifier is on with maximum gain setting (0dB), (digital gain setting coefficients are overruled)
- The XTAL output clock on pin CLKM keeps running.
- All digital setting are retained.
- Digital output on pins RXDx don't care (not floating).

In power-down mode the power consumption is 100mW.

Following external conditions are added:

- Clock pin CLW is running.
- CTRLIN signals can still be allowed.
- AGND remains at AVDD/2 (circuit is powered up)
- Input signal at TXDx inputs are not strobed.

The Pdown signal controls asynchronously the power-down of each analog module:

- After a few us the analog channel is functional
- After about 100ms the analog channel delivers full performance

RESET FUNCTION

The reset function is implied when the RESETN pin is at a low voltage input level. In this condition, the reset function can be easily used for power up reset conditions.

Detailed Description

During reset: (reset is asynchronous, tenths of ns are enough to put the IC in reset)

All clock outputs are deactivated and put to logical "1" (except for the XTAL and master clock CLKM)

After reset: (4 clock periods after reset transition, as worst case)

- -OSR = 4
- All analog gains (RX, TX) are set to minimum value
- Nominal filter frequency bands (138kHz, 1.104Hz)
- LNA input = "11" (max. attenuation)
- VCO dac disabled
- Depending of the LTNT pin value the following configuration is chosen:

'0' (ATU-R)

```
RX: LNA -> HC2 -> ADC
TX: DAC -> SC2 -> TX
```

'1' (ATU-C)

RX: LNA -> SC2 -> ADC TX: DAC -> HC2 -> TX Digital outputs are placed in don't care condition (non-floating).

N.B. If a Xtal oscillator is used, the RESET must be released at last 10μ s after power-on, to ensure a correct duty cycle for the clk35 clock signal.

ELECTRICAL RATINGS AND CHARACTERISTICS

Table 27. Absolute Maximum Ratings

Symbol	Parameter	Min	Max	Unit
Vdd	Any VDD Supply Voltage, related to substrate	- 0.5	5	V
Vin	Voltage at any input pin	-0.5	VDD +0.5	V
T _{stg}	Storage Temperature	-40	125	°C
TL	Lead Temperature (10 second soldering)		300	°C
llu	Latch - up current @80°C	100		mA
I _{AVDD}	Analog Supply Current @ 3.6V - normal operation		165	mA
I _{AVDD}	Analog Supply Current @ 3.6V - power down		30	mA
I _{DVDD}	Analog Supply Current @ 3.6V - normal operation		56	mA
I _{DVDD}	Analog Supply Current @ 3.6V - power down		50	mA

Table 28. Thermal Data

Symbol	Symbol Parameter		Unit
Rth j-amb	Thermal and Junction ambient	50	°C/W

Table 29. Operating Conditions

(Unless specified, the characteristic limits of 'Static Characteristics' in this document apply over an T_{op} = -40 to 80 °C; VDD within the range 3 to 3.6V ref. to substrate.

Symbol	Parameter	Min	Max	Unit
AVDD	AVDD Supply Voltage, related to substrate	3.0	3.6	V
DVDD	DVDD Supply Voltage, related to substrate	2.7	3.6	V
Vin /Vout	Voltage at any input and output pin	0	Vdd	V
Pd	Power Dissipation	0.4	0.6	W
T _{amb}	T _{amb} Ambient Temperature		80	°C
Tj	Junction Temperature	-40	110	°C

STATIC CHARACTERISTICS

Table 30. Digital Inputs

Schmitt-trigger inputs: TXi, CTRLIN, PDOWN, LTNT, RESETN, TEST

Symbol	Parameter	Test Condition	Min.	Тур.	Max.	Unit
V_{IL}	Low Level Input Voltage				0.3 · DVDD	V
V _{IH}	High Level Input Voltage		0.7 · DVDD			٧
V _H	Hysteresis		1.0		1.3	٧
C _{imp}	Input Capacitance				3	pF

Table 31. Digital Outputs

Hard Driven Outputs: RXi

Symbol	Parameter	Test Condition	Min.	Тур.	Max.	Unit
V_{OL}	Low Level Output Voltage	lout = -4mA			0.15 · DVDD	٧
V _{OH}	High Level Output Voltage	I _{out} = 4mA	0.85 · DVDD			V
C _{load}	Load Capacitance				30	pF

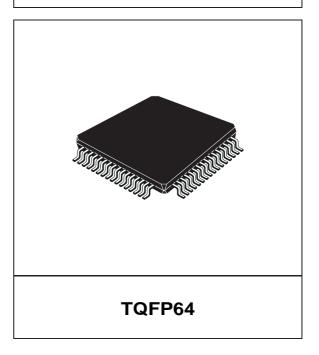
Clock Driver Output: CLKM, CLNIB, CLKWD

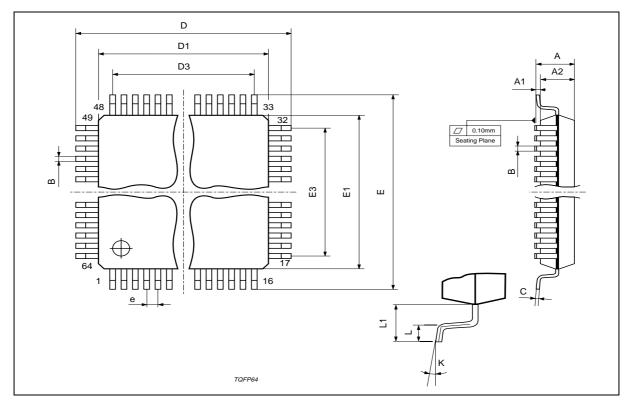
Symbol	Parameter	Test Condition	Min.	Тур.	Max.	Unit
V _{OL}	Low Level Output Voltage	lout = -4mA			0.15 · DVDD	V
V_{OH}	High Level Output Voltage	lout = 4mA	0.85 · DVDD			V
C _{load}	Load Capacitance				30	pF
DC	Duty Cycle		45		55	%

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DIM.		mm			inch			
Dill.	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.		
Α			1.60			0.063		
A1	0.05		0.15	0.002		0.006		
A2	1.35	1.40	1.45	0.053	0.055	0.057		
В	0.18	0.23	0.28	0.007	0.009	0.011		
С	0.12	0.16	0.20	0.0047	0.0063	0.0079		
D		12.00			0.472			
D1		10.00			0.394			
D3		7.50			0.295			
е		0.50			0.0197			
Е		12.00			0.472			
E1		10.00			0.394			
E3		7.50			0.295			
L	0.40	0.60	0.75	0.0157	0.0236	0.0295		
L1		1.00			0.0393			
K	0°(min.), 7°(max.)							

OUTLINE AND MECHANICAL DATA





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