



MX27L4100/27L4096

4M-BIT(512K x 8/256K x 16) CMOS EPROM

FEATURES

- 256K x 16 organization(MX27L4096, JEDEC pin out)
- 512K x 8 or 256K x 16 organization(MX27L4100, ROM pin out compatible)
- Wide voltage range, 2.7V to 3.6V
- +12.5V programming voltage
- Fast access time: 200/250 ns
- Totally static operation
- Completely TTL compatible
- Operating current: 20mA @3.6V, 5MHz
- Standby current: 50μA
- Package type:
 - 40 pin ceramic DIP
 - 40 pin plastic DIP
 - 44 pin PLCC
 - 40 pin SOP
 - 40 pin TSOP(I)

GENERAL DESCRIPTION

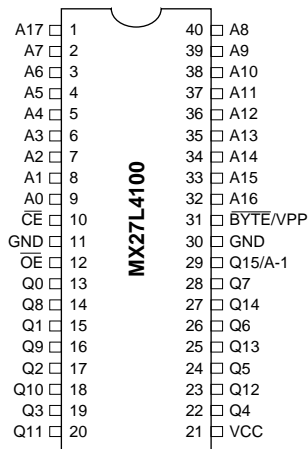
The MX27L4100/4096 is a 4M-bit, ultraviolet Erasable Programmable Read Only Memory. It is organized as 256K words by 16 bits per word(MX27L4096), 512K x 8 or 256K x 16(MX27L4100), operates from a single +3 volt supply, has a static standby mode, and features fast single address location programming. All programming signals are TTL levels, requiring a single pulse. For programming outside from the system, existing EPROM

programmers may be used. The MX27L4100/4096 supports a intelligent fast programming algorithm which can result in programming time of less than two minutes.

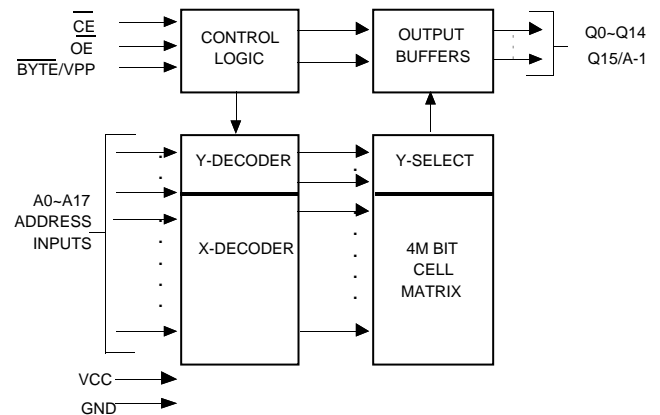
This EPROM is packaged in industry standard 40 pin dual-in-line packages, 40 lead SOP, and 44 lead PLCC packages.

PIN CONFIGURATIONS

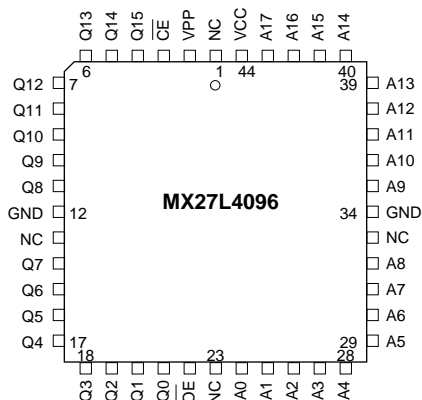
SOP/CDIP/PDIP(MX27L4100)



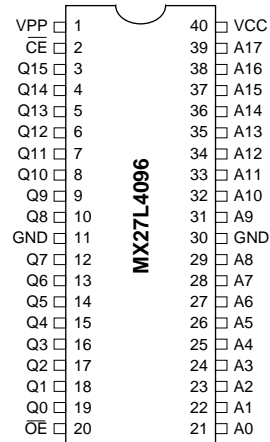
BLOCK DIAGRAM (MX27L4100)



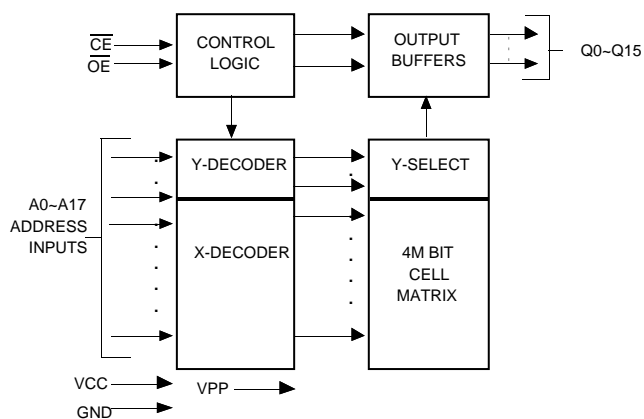
PIN CONFIGURATIONS

PLCC(MX27L4096)

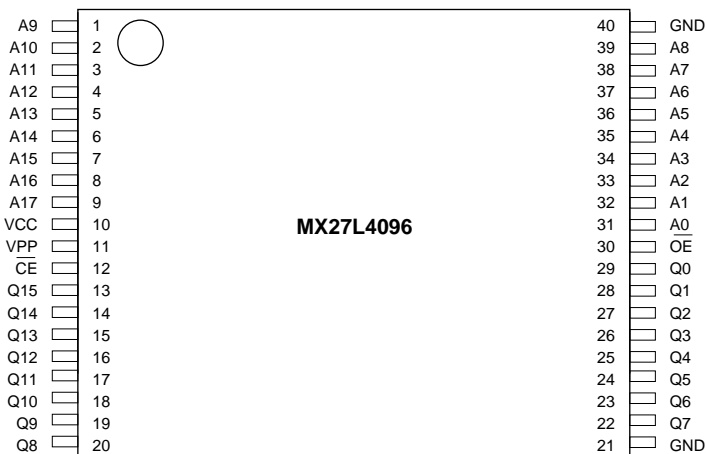
PIN CONFIGURATIONS

CDIP/PDIP(MX27L4096)

BLOCK DIAGRAM (MX27L4096)



10 x 14mm 40-TSOP(I)



PIN DESCRIPTION(MX27L4100)

SYMBOL	PIN NAME
A0~A17	Address Input
Q0~Q14	Data Input/Output
\overline{CE}	Chip Enable Input
\overline{OE}	Output Enable Input
BYTE/VPP	Word/Byte Selection /Program Supply Voltage
Q15/A-1	Q15(Word mode)/LSB addr. (Byte mode)
VCC	Power Supply Pin
GND	Ground Pin

PIN DESCRIPTION(MX27L4096)

SYMBOL	PIN NAME
A0~A17	Address Input
Q0~Q15	Data Input/Output
\overline{CE}	Chip Enable Input
\overline{OE}	Output Enable Input
VPP	Program Supply Voltage
VCC	Power Supply Pin
GND	Ground Pin

TRUTH TABLE OF BYTE FUNCTION(MX27L4100)

BYTE MODE($\overline{BYTE} = \text{GND}$)

\overline{CE}	\overline{OE}	Q15/A-1	MODE	Q0-Q7	SUPPLY CURRENT
H	X	X	Non selected	High Z	Standby(ICC2)
L	H	X	Non selected	High Z	Operating(ICC1)
L	L	A-1 input	Selected	DOUT	Operating(ICC1)

WORD MODE($\overline{BYTE} = \text{VCC}$)

\overline{CE}	\overline{OE}	Q15/A-1	MODE	Q0-Q14	SUPPLY CURRENT
H	X	High Z	Non selected	High Z	Standby(ICC2)
L	H	High Z	Non selected	High Z	Operating(ICC1)
L	L	DOUT	Selected	DOUT	Operating(ICC1)

NOTE : X = H or L

FUNCTIONAL DESCRIPTION

THE ERASURE OF THE MX27L4100/4096

The MX27L4100/4096 is erased by exposing the chip to an ultraviolet light source. A dosage of 15 W seconds/cm² is required to completely erase a MX27L4100/4096. This dosage can be obtained by exposure to an ultraviolet lamp — wavelength of 2537 Angstroms (Å) — with intensity of 12,000 μW/cm² for 15 to 20 minutes. The MX27L4100/4096 should be directly under and about one inch from the source and all filters should be removed from the UV light source prior to erasure.

It is important to note that the MX27L4100/4096, and similar devices, will be cleared for all bits of their programmed states with light sources having wavelengths shorter than 4000 Å. Although erasure times will be much longer than that with UV sources at 2537Å, nevertheless the exposure to fluorescent light and sunlight will eventually erase the MX27L4100/4096 and exposure to them should be prevented to realize maximum system reliability. If used in such an environment, the package window should be covered by an opaque label or substance.

THE PROGRAMMING OF THE MX27L4100/4096

When the MX27L4100/4096 is delivered, or it is erased, the chip has all 4M bits in the “ONE”, or HIGH state. “ZEROS” are loaded into the MX27L4100/4096 through the procedure of programming.

For programming, the data to be programmed is applied with 16 bits in parallel to the data pins.

VCC must be applied simultaneously or before VPP, and removed simultaneously or after VPP. When programming an MXIC EPROM, a 0.1μF capacitor is required across VPP and ground to suppress spurious voltage transients which may damage the device.

FAST PROGRAMMING

The device is set up in the fast programming mode when the programming voltage VPP = 12.75V is applied, with VCC = 6.25 V and \overline{OE} = VIH (Algorithm is shown in Figure 1). The programming is achieved by applying a single TTL low level 100μs pulse to the \overline{CE} input after addresses and data line are stable. If the data is not verified, an

additional pulse is applied for a maximum of 25 pulses. This process is repeated while sequencing through each address of the device. When the programming mode is completed, the data in all address is verified at VCC = VPP = 5V ± 10%.

PROGRAM INHIBIT MODE

Programming of multiple MX27L4100/4096's in parallel with different data is also easily accomplished by using the Program Inhibit Mode. Except for \overline{CE} and \overline{OE} , all like inputs of the parallel MX27L4100/4096 may be common. A TTL low-level program pulse applied to an MX27L4100/4096 \overline{CE} input with VPP = 12.5 ± 0.5 V will program the MX27L4100/4096. A high-level \overline{CE} input inhibits the other MX27L4100/4096s from being programmed.

PROGRAM VERIFY MODE

Verification should be performed on the programmed bits to determine that they were correctly programmed. The verification should be performed with \overline{OE} and \overline{CE} at VIL (for MX27C4096), \overline{OE} at VIL and \overline{CE} at VIH (for MX27C4100) and VPP at its programming voltage.

AUTO IDENTIFY MODE

The auto identify mode allows the reading out of a binary code from an EPROM that will identify its manufacturer and device type. This mode is intended for use by programming equipment for the purpose of automatically matching the device to be programmed with its corresponding programming algorithm. This mode is functional in the 25°C ± 5°C ambient temperature range that is required when programming the MX27L4100/4096.

To activate this mode, the programming equipment must force 12.0 ± 0.5 V on address line A9 of the device. Two identifier bytes may then be sequenced from the device outputs by toggling address line A0 from VIL to VIH. All other address lines must be held at VIL during auto identify mode.

Byte 0 (A0 = VIL) represents the manufacturer code, and byte 1 (A0 = VIH), the device identifier code. For the MX27L4100/4096, these two identifier bytes are given in the Mode Select Table. All identifiers for manufacturer and device codes will possess odd parity, with the MSB (Q15) defined as the parity bit.

READ MODE

The MX27L4100/4096 has two control functions, both of which must be logically satisfied in order to obtain data at the outputs. Chip Enable (\overline{CE}) is the power control and should be used for device selection. Output Enable (\overline{OE}) is the output control and should be used to gate data to the output pins, independent of device selection. Assuming that addresses are stable, address access time (t_{ACC}) is equal to the delay from \overline{CE} to output (t_{CE}). Data is available at the outputs t_{OE} after the falling edge of \overline{OE} 's, assuming that \overline{CE} has been LOW and addresses have been stable for at least $t_{ACC} - t_{OE}$.

WORD-WIDE MODE

With \overline{BYTE}/VPP at $VCC \pm 0.2V$ outputs Q0-7 present data Q0-7 and outputs Q8-15 present data Q8-15, after \overline{CE} and \overline{OE} are appropriately enabled.

BYTE-WIDE MODE

With \overline{BYTE}/VPP at $GND \pm 0.2V$, outputs Q8-15 are tri-stated. If Q15/A-1 = VIH, outputs Q0-7 present data bits Q8-15. If Q15/A-1 = VIL, outputs Q0-7 present data bits Q0-7.

STANDBY MODE

The MX27L4100/4096 has a CMOS standby mode which reduces the maximum VCC current to 50 μA . It is placed in CMOS standby when \overline{CE} is at $VCC \pm 0.3 V$. The MX27L4100/4096 also has a TTL-standby mode which reduces the maximum VCC current to 1.5 mA. It is placed in TTL-standby when \overline{CE} is at VIH. When in standby mode, the outputs are in a high-impedance state, independent of the \overline{OE} input.

TWO-LINE OUTPUT CONTROL FUNCTION

To accommodate multiple memory connections, a two-line control function is provided to allow for:

1. Low memory power dissipation,
2. Assurance that output bus contention will not occur.

It is recommended that \overline{CE} be decoded and used as the primary device-selecting function, while \overline{OE} be made a common connection to all devices in the array and connected to the READ line from the system control bus. This assures that all deselected memory devices are in their low-power standby mode and that the output pins are only active when data is desired from a particular memory device.

SYSTEM CONSIDERATIONS

During the switch between active and standby conditions, transient current peaks are produced on the rising and falling edges of Chip Enable. The magnitude of these transient current peaks is dependent on the output capacitance loading of the device. At a minimum, a 0.1 μF ceramic capacitor (high frequency, low inherent inductance) should be used on each device between VCC and GND to minimize transient effects. In addition, to overcome the voltage drop caused by the inductive effects of the printed circuit board traces on EPROM arrays, a 4.7 μF bulk electrolytic capacitor should be used between VCC and GND for each eight devices. The location of the capacitor should be close to where the power supply is connected to the array.

MODE SELECT TABLE (MX27L4096)

MODE	PINS				VPP	OUTPUTS
	\overline{CE}	\overline{OE}	A0	A9		
Read	VIL	VIL	X	X	VCC	DOUT
Output Disable	VIL	VIH	X	X	VCC	High Z
Standby (TTL)	VIH	X	X	X	VCC	High Z
Standby (CMOS)	VCC±0.3V	X	X	X	VCC	High Z
Program	VIL	VIH	X	X	VPP	DIN
Program Verify	VIH	VIL	X	X	VPP	DOUT
Program Inhibit	VIH	VIH	X	X	VPP	High Z
Manufacturer Code(3)	VIL	VIL	VIL	VH	VCC	00C2H
Device Code(3)	VIL	VIL	VIH	VH	VCC	0151H

NOTES:1. VH = 12.0 V ± 0.5 V
2. X = Either VIH or VIL

3. A1 - A8 = A10 - A17 = VIL(For auto select)
4. See DC Programming Characteristics for VPP voltage during programming.

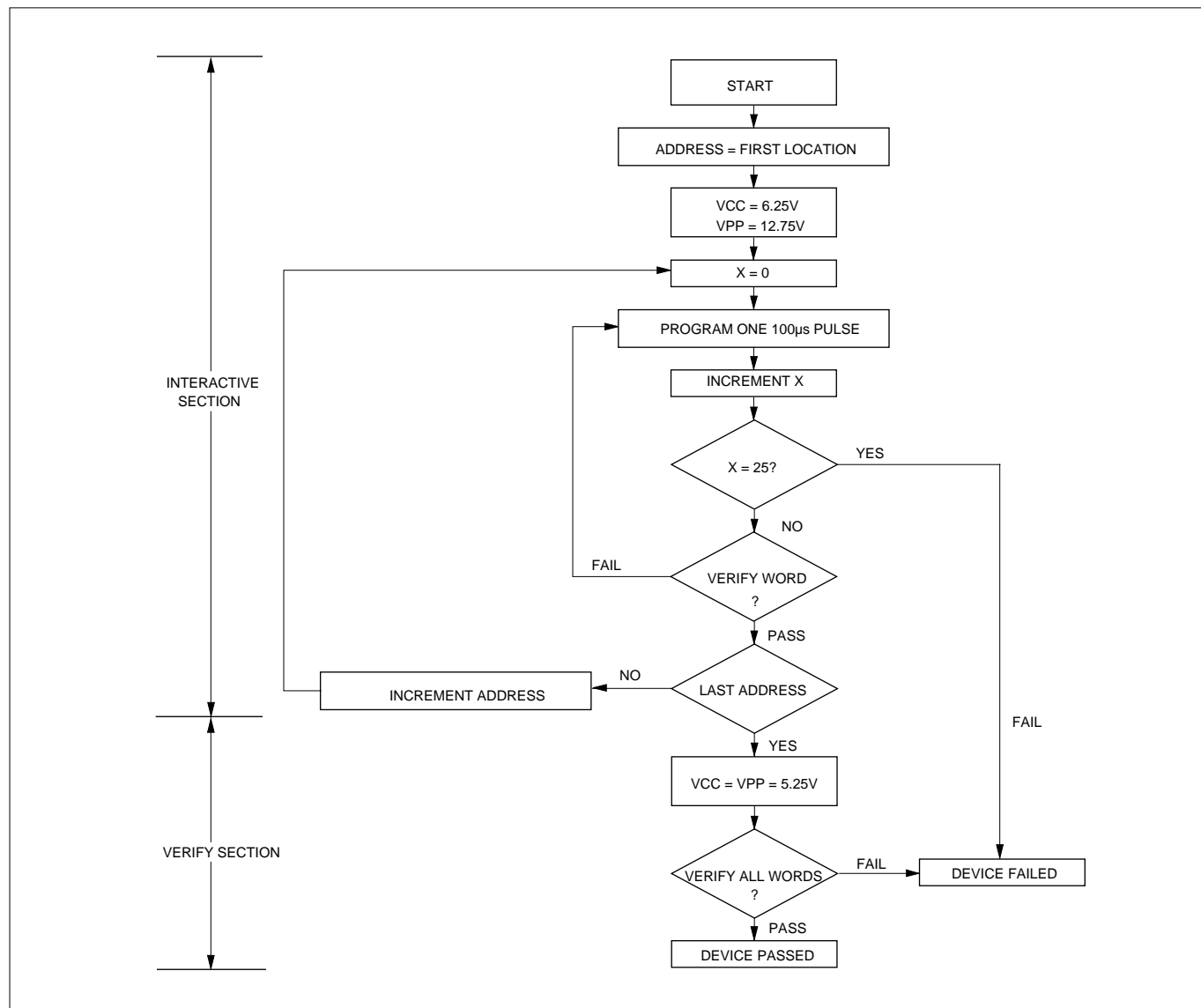
MODE SELECT TABLE (MX27L4100)

MODE	\overline{CE}	\overline{OE}	A17	A0	Q15/A-1	BYTE/	Q8-14	Q0-7
						VPP(5)		
Read (Word)	VIL	VIL	X	X	Q15 Out	VCC	Q8-14 Out	Q0-7 Out
Read (Upper Byte)	VIL	VIL	X	X	VIH	GND	High Z	Q8-15 Out
Read (Lower Byte)	VIL	VIL	X	X	VIL	GND	High Z	Q0-7 Out
Output Disable	VIL	VIH	X	X	High Z	X	High Z	High Z
Standby	VIH	X	X	X	High Z	X	High Z	High Z
Program	VIL	VIH	X	X	Q15 In	VPP	Q8-14 In	Q0-7 In
Program Verify	VIH	VIL	X	X	Q15 Out	VPP	Q8-14 Out	Q0-7 Out
Program Inhibit	VIH	VIH	X	X	High Z	VPP	High Z	High Z
Manufacturer Code(3)	VIL	VIL	VH	VIL	0B	VCC	00H	C2H
Device Code(3)	VIL	VIL	VH	VIH	1B	VCC	38H	00H

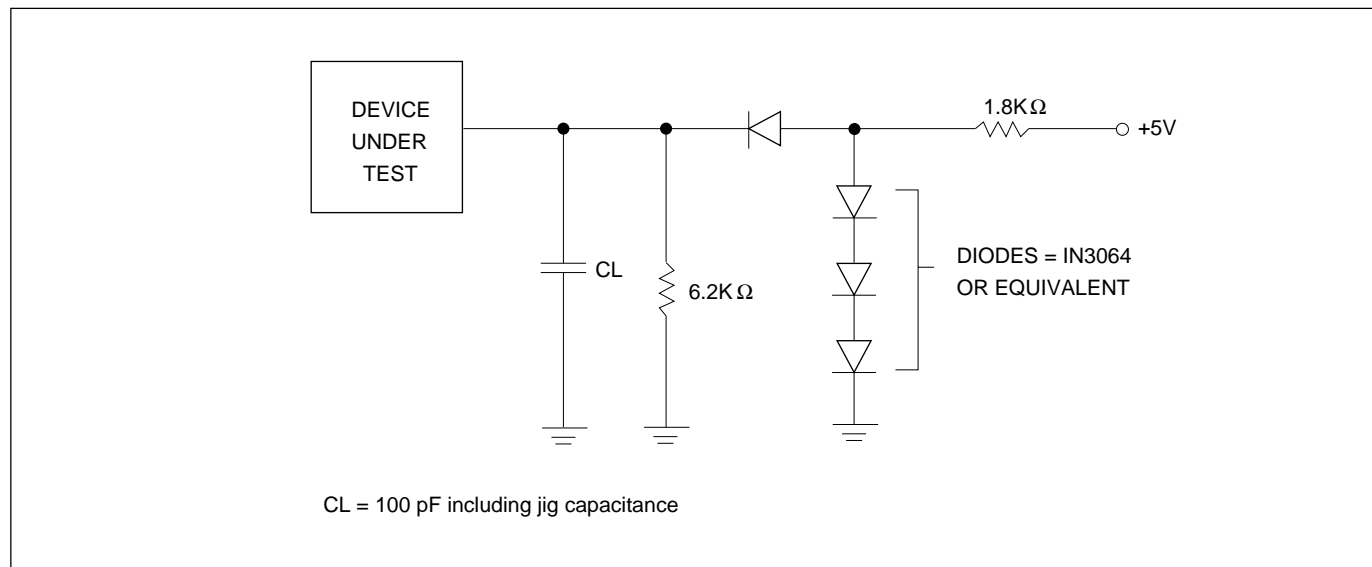
NOTES:1. VH = 12.0V ± 0.5V
2. X can be VIL or VIH.
3. A1 - A8, A10 - A17 = VIL (for auto select)

4. See DC Programming Characteristics for VPP voltages.
5. BYTE/VPP is intended for operation under DC Voltage conditions only.
6. Manufacture code = 00C2H
Device code = B800H

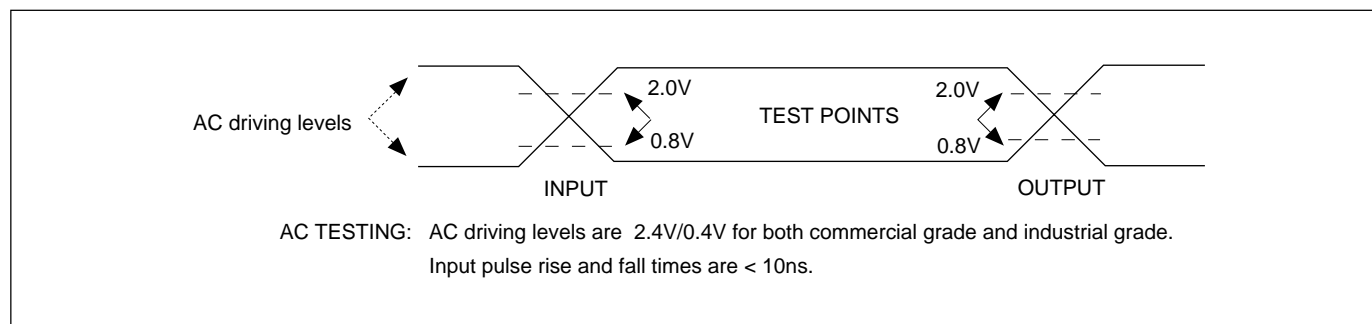
FIGURE 1. FAST PROGRAMMING FLOW CHART



SWITCHING TEST CIRCUITS



SWITCHING TEST WAVEFORMS



ABSOLUTE MAXIMUM RATINGS

RATING	VALUE
Ambient Operating Temperature	-40°C to 85°C
Storage Temperature	-65°C to 125°C
Applied Input Voltage	-0.5V to 7.0V
Applied Output Voltage	-0.5V to VCC + 0.5V
VCC to Ground Potential	-0.5V to 7.0V
A9 & VPP	-0.5V to 13.5V

NOTICE:

Stresses greater than those listed under ABSOLUTE MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended period may affect reliability.

NOTICE:

Specifications contained within the following tables are subject to change.

DC/AC Operating Conditions for Read Operation

MX27L4100/4096			
		-20	-25
Operating Temperature	Commercial	0°C to 70°C	0°C to 70°C
	Industrial	-40°C to 85°C	-40°C to 85°C
VCC Power Supply		2.7V to 3.6V	2.7V to 3.6V

DC CHARACTERISTICS

SYMBOL	PARAMETER	MIN.	MAX.	UNIT	CONDITIONS
VOH	Output High Voltage	Vcc-0.3		V	IOH = -100μA, Vcc=3.0V
VOL	Output Low Voltage		0.3	V	IOL = 2.1mA
VIH	Input High Voltage	2.0	VCC + 0.5	V	
VIL	Input Low Voltage	-0.3	0.6	V	
ILI	Input Leakage Current	-10	10	μA	VIN = 0 to 3.6V
ILO	Output Leakage Current	-10	10	μA	VOUT = 0 to 3.6V
ICC3	VCC Power-Down Current		50	μA	$\overline{CE} = VCC \pm 0.3V$
ICC2	VCC Standby Current		0.25	mA	$\overline{CE} = VIH$
ICC1	VCC Active Current		20	mA	$\overline{CE} = VIL$, f=5MHz, Iout=0mA, Vcc=3.0V
IPP	VPP Supply Current Read		10	μA	$\overline{CE} = \overline{OE} = VIL$, VPP = VCC

CAPACITANCE TA = 25°C, f = 1.0 MHz (Sampled only)

SYMBOL	PARAMETER	TYP.	MAX.	UNIT	CONDITIONS
CIN	Input Capacitance	8	12	pF	VIN = 0V
COUT	Output Capacitance	8	12	pF	VOUT = 0V
CVPP	VPP Capacitance	18	25	pF	VPP = 0V

AC CHARACTERISTICS

SYMBOL	PARAMETER	27L4100/4096-20				27L4100/4096-25	
		MIN.	MAX.	MIN.	MAX.	UNIT	CONDITIONS
tACC	Address to Output Delay		200		250	ns	$\overline{CE} = \overline{OE} = VIL$
tCE	Chip Enable to Output Delay		200		250	ns	$\overline{OE} = VIL$
tOE	Output Enable to Output Delay		100		120	ns	$\overline{CE} = VIL$
tDF	\overline{OE} High to Output Float, or \overline{CE} High to Output Float	0	60	0	70	ns	
tOH	Output Hold from Address, \overline{CE} or \overline{OE} which ever occurred first	0		0		ns	

AC CHARACTERISTICS(Continued)

SYMBOL	PARAMETER	27L4100-20		27L4100-25		UNIT	CONDITIONS
		MIN.	MAX.	MIN.	MAX.		
tBHA	\overline{BYTE} Access Time		200		250	ns	
tOH \overline{B}	\overline{BYTE} Output Hold Time	0		0		ns	
tBHZ	\overline{BYTE} Output Delay Time		100		120	ns	
tBLZ	\overline{BYTE} Output Set Time	20		20		ns	

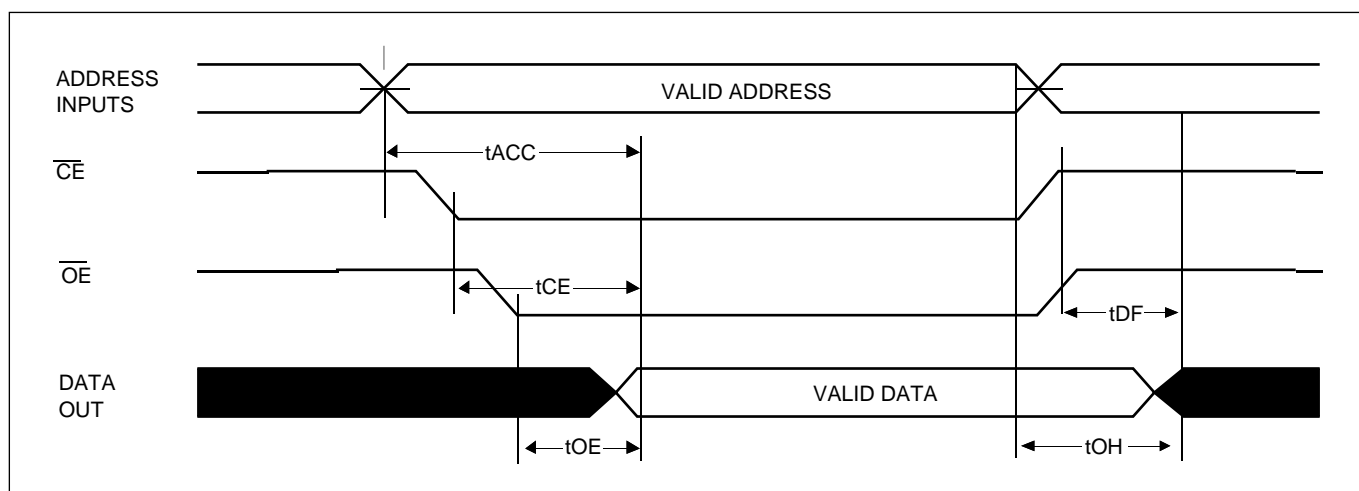
DC PROGRAMMING CHARACTERISTICS TA = 25°C ± 5°C

SYMBOL	PARAMETER	MIN.	MAX.	UNIT	CONDITIONS
VOH	Output High Voltage	2.4		V	IOH = -0.40mA
VOL	Output Low Voltage		0.4	V	IOL = 2.1mA
VIH	Input High Voltage	2.0	VCC + 0.5	V	
VIL	Input Low Voltage	-0.3	0.8	V	
ILI	Input Leakage Current	-10	10	μA	VIN = 0 to 3.6V
VH	A9 Auto Select Voltage	11.5	12.5	V	
ICC3	VCC Supply Current (Program & Verify)		50	mA	
IPP2	VPP Supply Current(Program)		30	mA	$\overline{CE} = VIL, \overline{OE} = VIH$
VCC1	Fast Programming Supply Voltage	6.00	6.50	V	
VPP1	Fast Programming Voltage	12.5	13.0	V	

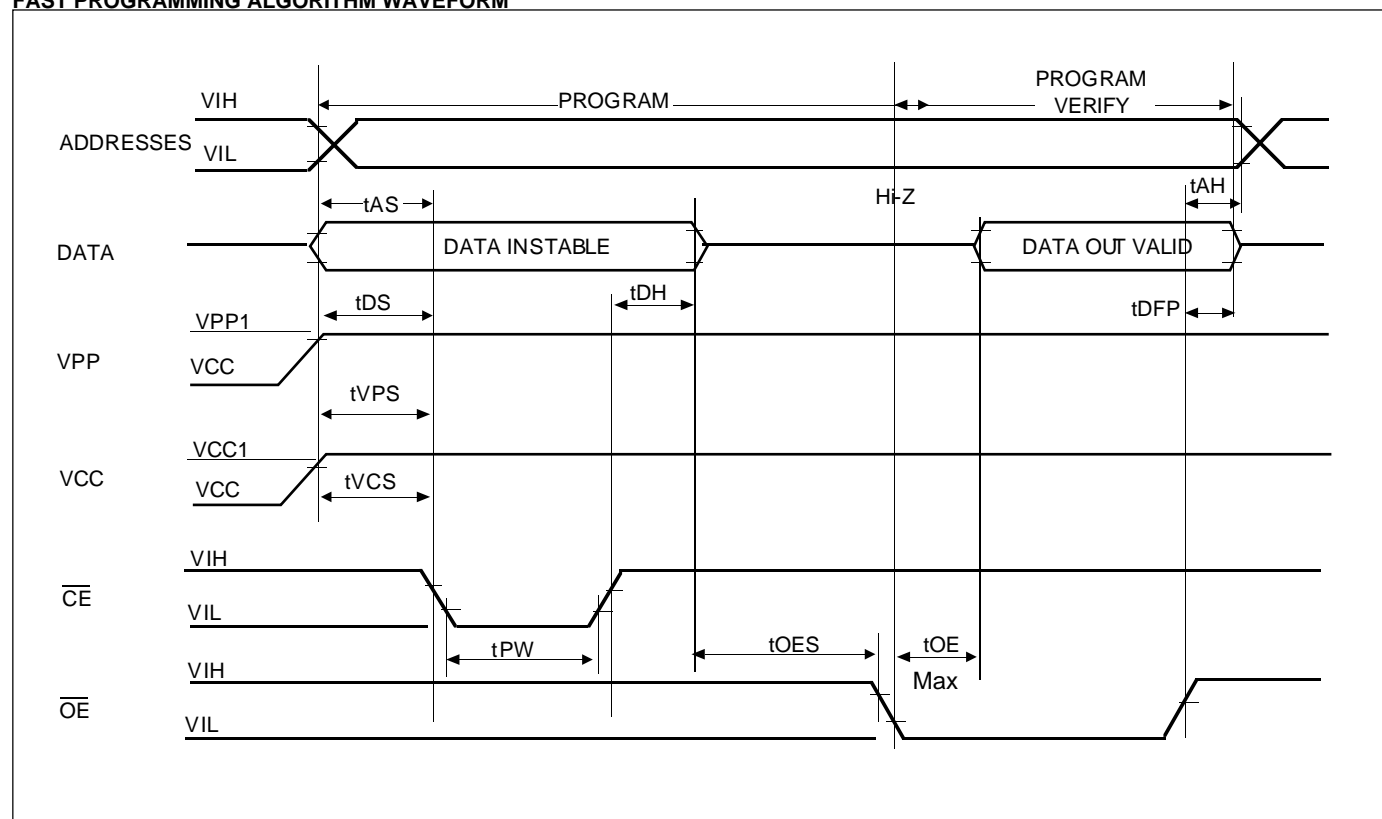
AC PROGRAMMING CHARACTERISTICS TA = 25°C ± 5°C

SYMBOL	PARAMETER	MIN.	MAX.	UNIT	CONDITIONS
tAS	Address Setup Time	2.0		μS	
tOES	\overline{OE} Setup Time	2.0		μS	
tDS	Data Setup Time	2.0		μS	
tAH	Address Hold Time	0		μS	
tDH	Data Hold Time	2.0		μS	
tDFP	Output Enable to Output Float Delay	0	130	nS	
tVPS	VPP Setup Time	2.0		μS	
tPW	\overline{PGM} Program Pulse Width	95	105	μS	
tVCS	VCC Setup Time	2.0		μS	
tOE	Data valid from \overline{OE}		150	nS	

READ CYCLE

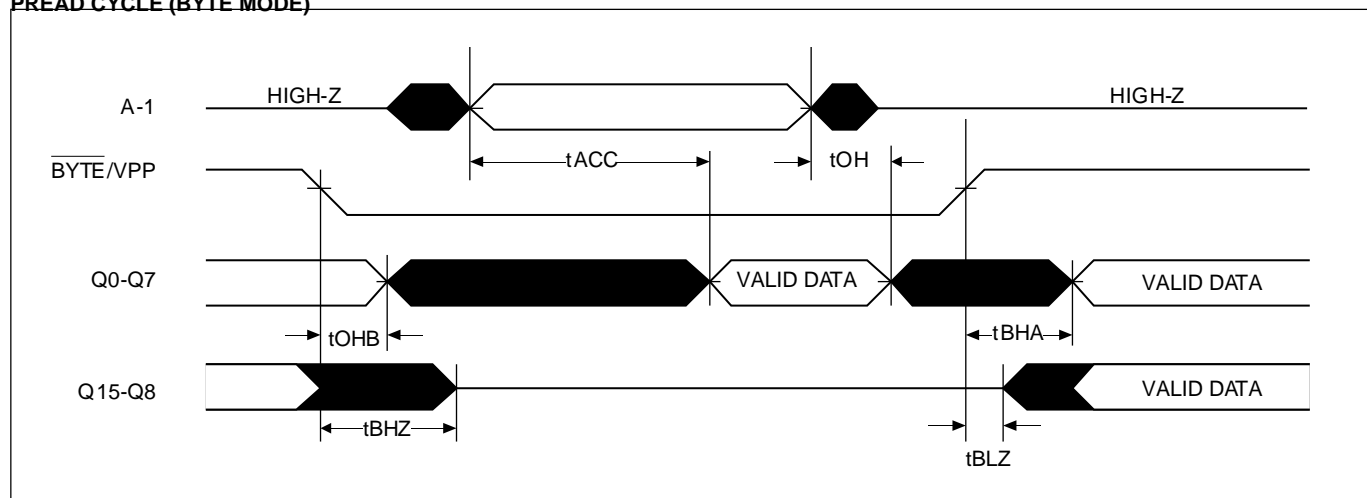


FAST PROGRAMMING ALGORITHM WAVEFORM

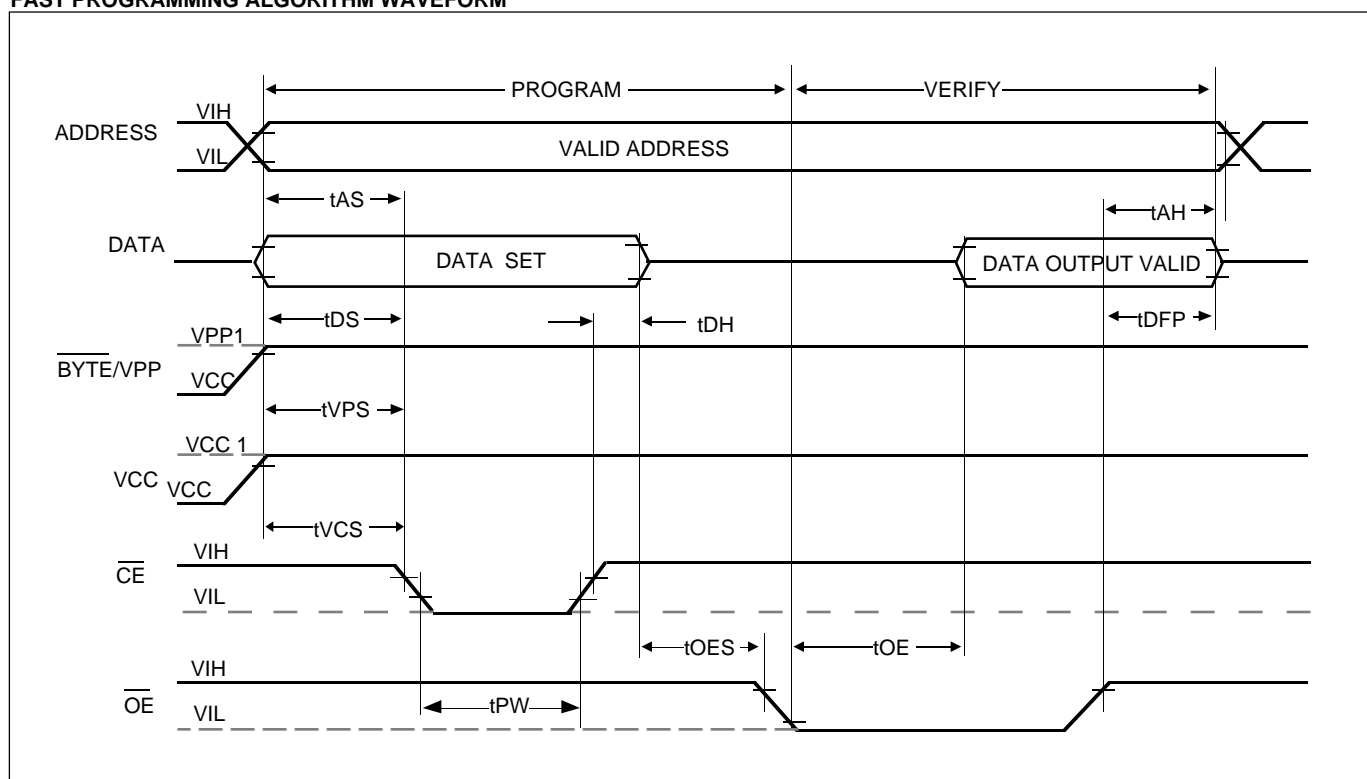


WAVEFORMS(MX27L4100)

PREAD CYCLE (BYTE MODE)



FAST PROGRAMMING ALGORITHM WAVEFORM



ORDERING INFORMATION

CERAMIC PACKAGE

PART NO.	ACCESS TIME (ns)	OPERATING CURRENT MAX.(mA)	STANDBY CURRENT CURRENT MAX.(μA)	OPERATING TEMPERATURE	PACKAGE
MX27L4100DC-20	200	20	50	0°C to 70°C	40 Pin DIP(ROM pin out)
MX27L4100DC-25	250	20	50	0°C to 70°C	40 Pin DIP(ROM pin out)
MX27L4096DC-20	200	20	50	0°C to 70°C	40 Pin DIP(JEDEC pin out)
MX27L4096DC-25	250	20	50	0°C to 70°C	40 Pin DIP(JEDEC pin out)
MX27L4100DI-20	200	20	50	-40°C to 85°C	40 Pin DIP(ROM pin out)
MX27L4100DI-25	250	20	50	-40°C to 85°C	40 Pin DIP(ROM pin out)
MX27L4096DI-20	200	20	50	-40°C to 85°C	40 Pin DIP(JEDEC pin out)
MX27L4096DI-25	250	20	50	-40°C to 85°C	40 Pin DIP(JEDEC pin out)

PLASTIC PACKAGE

PART NO.	ACCESS TIME (ns)	OPERATING CURRENT MAX.(mA)	STANDBY CURRENT MAX.(μA)	OPERATING TEMPERATURE	PACKAGE
MX27L4100PC-20	200	20	50	0°C to 70°C	40 Pin DIP(ROM pin out)
MX27L4100PC-25	250	20	50	0°C to 70°C	40 Pin DIP(ROM pin out)
MX27L4100MC-20	200	20	50	0°C to 70°C	40 Pin SOP(ROM pin out)
MX27L4100MC-25	250	20	50	0°C to 70°C	40 Pin SOP(ROM pin out)
MX27L4096PC-20	200	20	50	0°C to 70°C	40 Pin DIP(JEDEC pin out)
MX27L4096PC-25	250	20	50	0°C to 70°C	40 Pin DIP(JEDEC pin out)
MX27L4096QC-20	200	20	50	0°C to 70°C	44 Pin PLCC
MX27L4096QC-25	250	20	50	0°C to 70°C	44 Pin PLCC
MX27L4100PI-20	200	20	50	-40°C to 85°C	40 Pin DIP(ROM pin out)
MX27L4100PI-25	250	20	50	-40°C to 85°C	40 Pin DIP(ROM pin out)
MX27L4100MI-20	200	20	50	-40°C to 85°C	40 Pin SOP(ROM pin out)
MX27L4100MI-25	250	20	50	-40°C to 85°C	40 Pin SOP(ROM pin out)
MX27L4096PI-20	200	20	50	-40°C to 85°C	40 Pin DIP(JEDEC pin out)
MX27L4096PI-25	250	20	50	-40°C to 85°C	40 Pin DIP(JEDEC pin out)
MX27L4096QI-20	200	20	50	-40°C to 85°C	44 Pin PLCC
MX27L4096QI-25	250	20	50	-40°C to 85°C	44 Pin PLCC

Revision History

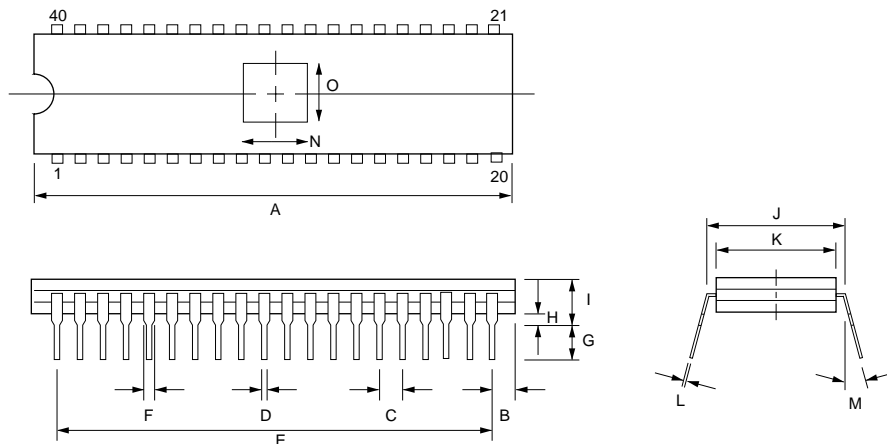
Revision No.	Description
2.0	1) Revise SWITCHING TEST WAVEFORM, the AC measurement level change from 2.0V/0.6V to 2.0V/0.8V. 2) 40-CDIP package quartz lens change to square shape. 3) Eliminate Interactive programming Mode.
2.1	IPP1 100μA to 10μA
7/17/1997	

PACKAGE INFORMATION

40-PIN CERDIP(MSI) WITH WINDOW(600 mil)

ITEM	MILLIMETERS	INCHES
A	53.34 max.	2.100 max.
B	1.85 ± .30	.073 ± .012
C	2.54 [TP]	.100 [TP]
D	.46 ± .05	.018 ± .002
E	48.22	1.900
F	1.40 ± .05	.055 ± .005
G	3.43 ± .38	.135 ± .015
H	.94 ± .41	.037 ± .016
I	5.00	.197
J	15.494 ± 1.27	.610 ± .005
K	14.6558 ± .254	.577 ± .001
L	.25 ± .13	.010 ± .005
M	0~15°	0~15°
N	10.668	.420
O	8.128	.320

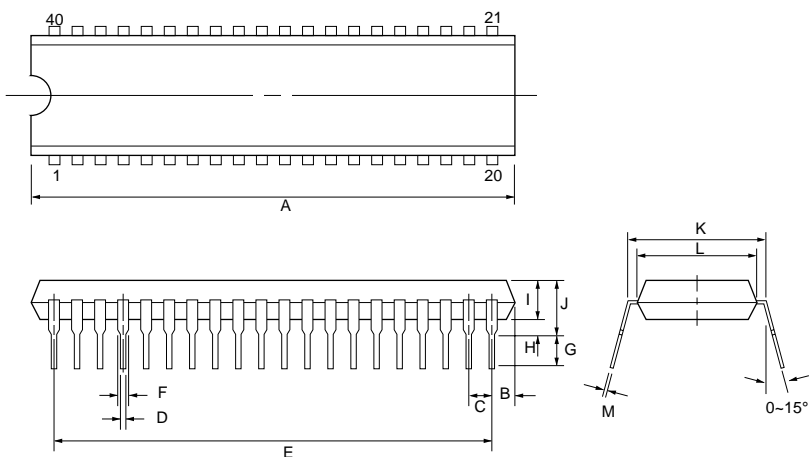
NOTE: Each lead centerline is located within .25 mm[.01 inch] of its true position [TP] at maximum material condition.



40-PIN PLASTIC DIP(600 mil)

ITEM	MILLIMETERS	INCHES
A	52.54 max.	2.070 max.
B	2.03 [REF]	.080 [REF]
C	2.54 [TP]	.100 [TP]
D	.46 [Typ.]	.018 [Typ.]
E	48.22	1.900
F	1.52 [Typ.]	.060 [Typ.]
G	3.30 ± .25	.130 ± .010
H	.51 [REF]	.020 [REF]
I	3.94 ± .25	.155 ± .010
J	5.33 max.	.210 max.
K	15.22 ± .25	.600 ± .010
L	13.97 ± .25	.550 ± .010
M	.25 [Typ.]	.010 [Typ.]

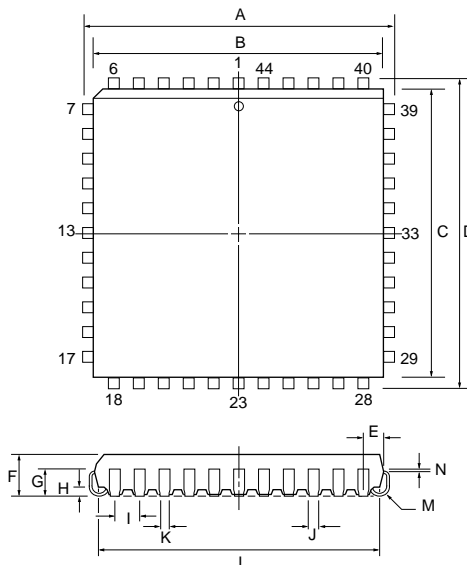
NOTE: Each lead centerline is located within .25 mm[.01 inch] of its true position [TP] at maximum material condition.



PACKAGE INFORMATION

44-PIN PLASTIC LEADED CHIP CARRIER (PLCC)

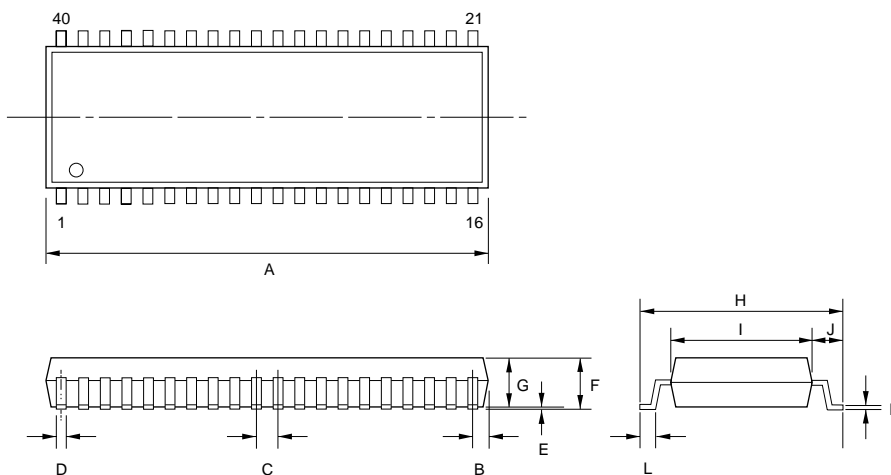
ITEM	MILLIMETERS	INCHES
A	17.53 ± .12	.690 ± .005
B	16.59 ± .12	.653 ± .005
C	16.59 ± .12	.653 ± .005
D	17.53 ± .12	.690 ± .005
E	1.95	.077
F	4.70 max.	.185 max
G	2.55 ± .25	.100 ± .010
H	.51 min.	.020 min.
I	1.27 [Typ.]	.050 [Typ.]
J	.71 ± .10	.028 ± .004
K	.46 ± .10	.018 ± .004
L	15.50 ± .51	.610 ± .020
M	.63 R	.025 R
N	.25 [Typ.]	.010 [Typ.]



40-PIN PLASTIC SOP(450 mil)

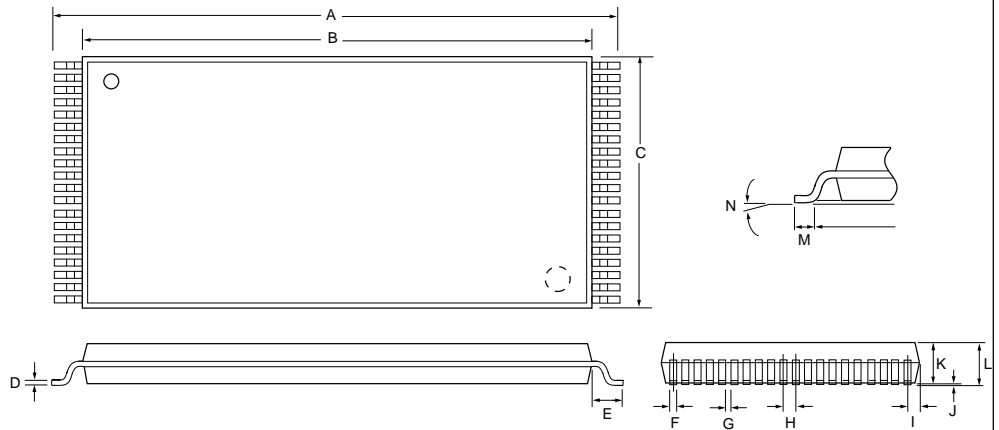
ITEM	MILLIMETERS	INCHES
A	26.16 max.	1.030 max.
B	1.00 [REF]	.038 [REF]
C	1.27 [TP]	.050 [TP]
D	.43 [Typ.]	.017 [Typ.]
E	.102 min.	.004 min.
F	2.54 max.	.100 max.
G	2.24 ± .05	.088 ± .002
H	14.22 ± .08	.560 ± .007
I	11.18 ± .12	.440 ± .005
J	1.52	.060
K	.15 [Typ.]	.006 [Typ.]
L	.79	.031

NOTE: Each lead centerline is located within .25 mm(.01 inch) of its true position [TP] at maximum material condition.



40-PIN PLASTIC TSOP

ITEM	MILLIMETERS	INCHES
A	14.0 ± .20	0.551 ± .008
B	12.4 ± .10	0.488 ± .004
C	10.1 max.	0.398 max.
D	0.125 [Typ.]	0.005 [Typ.]
E	.80 [Typ.]	.031 [Typ.]
F	.20 ± .10	.008 ± .004
G	.30 ± .10	.012 ± .004
H	.50 [Typ.]	.020 [Typ.]
I	.45 max.	0.18 max.
J	0 ~ .20	0 ~ .008
K	1.00 ± .10	.039 ± .004
L	1.2 max.	0.047 max.
M	.50	.020
N	0 ~ 10°	0 ~ 10°



NOTE: Each lead centerline is located within .25 mm[.01 inch] of its true position [TP] at maximum material condition.

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