

**MX27L2048****2M-BIT(256K x 8/128K x 16) CMOS EPROM****FEATURES**

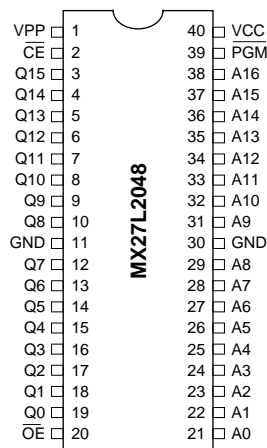
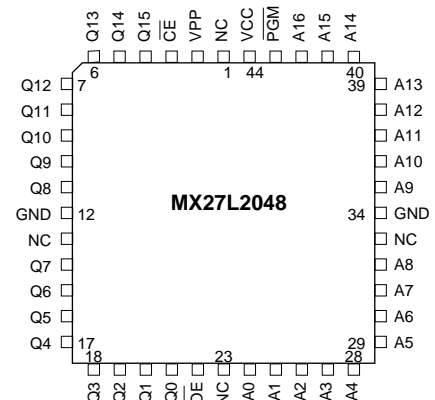
- 128K x 16 organization(MX27C2048, JEDEC pin out)
- +12.5V programming voltage
- Fast access time: 150/200/250 ns
- Totally static operation
- Completely TTL compatible
- Operating current: 20mA @ 3.6V, 5MHz
- Standby current: 20μA
- Package type:
 - 40 pin ceramic DIP
 - 40 pin plastic DIP
 - 44 pin PLCC
 - 40 pin TSOP(I)

GENERAL DESCRIPTION

The MX27L2048 is a 3V only, 2M-bit, ultraviolet Erasable Programmable Read Only Memory. It is organized as 128K words by 16 bits per word(MX27L2048), operates from a single + 3 volt supply, has a static standby mode, and features fast single address location programming. All programming signals are TTL levels, requiring a single pulse. For programming outside from the system, existing EPROM programmers may be used. The MX27L2048

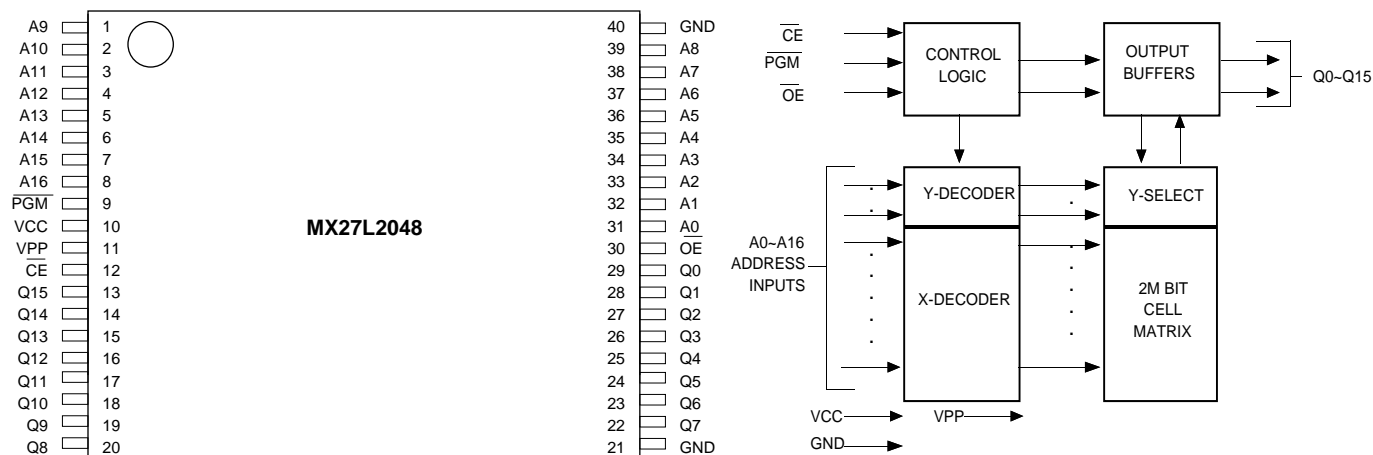
supports a intelligent quick pulse programming algorithm which can result in programming times of less than one minute.

This EPROM is packaged in industry standard 40 pin dual-in-line ceramic packages or 40 pin plastic packages, 44-lead PLCC, 40-lead TSOP(I).

PIN CONFIGURATIONS**CDIP/PDIP****PLCC**

10 x 40mm 40-TSOP(I)

BLOCK DIAGRAM



PIN DESCRIPTION(MX27C2048)

| SYMBOL | PIN NAME |
|------------------|------------------------|
| A0~A16 | Address Input |
| Q0~Q15 | Data Input/Output |
| \overline{CE} | Chip Enable Input |
| \overline{OE} | Output Enable Input |
| \overline{PGM} | Program Enable Input |
| VPP | Program Supply Voltage |
| VCC | Power Supply Pin (+5V) |
| GND | Ground Pin |

FUNCTIONAL DESCRIPTION

THE ERASURE OF THE MX27L2048

The MX27L2048 is erased by exposing the chip to an ultraviolet light source. A dosage of 15 W seconds/cm² is required to completely erase a MX27L2048. This dosage can be obtained by exposure to an ultraviolet lamp — wavelength of 2537 Angstroms (Å) — with intensity of 12,000 μW/cm² for 15 to 20 minutes. The MX27L2048 should be directly under and about one inch from the source and all filters should be removed from the UV light source prior to erasure.

It is important to note that the MX27L2048, and similar devices, will be cleared for all bits of their programmed states with light sources having wavelengths shorter than 4000 Å. Although erasure times will be much longer than that with UV sources at 2537Å, nevertheless the exposure to fluorescent light and sunlight will eventually erase the MX27L2048 and exposure to them should be prevented to realize maximum system reliability. If used in such an environment, the package window should be covered by an opaque label or substance.

THE PROGRAMMING OF THE MX27L2048

When the MX27L2048 is delivered, or it is erased, the chip has all 2M bits in the “ONE”, or HIGH state. “ZEROS” are loaded into the MX27L2048 through the procedure of programming.

The programming mode is entered when $12.5 \pm 0.5V$ is applied to the VPP pin, \overline{OE} is at VIH and \overline{PGM} is at VIL.

For programming, the data to be programmed is applied with 16 bits in parallel to the data pins.

The flowchart in Figure 1 shows MXIC's interactive algorithm. Interactive algorithm reduces programming time by using short programming pulses and giving each address only as many pulses as is necessary in order to reliably program the data. After each pulse is applied to a given address, the data in that address is verified. If the data is not verified, additional pulses are given until it is verified or the maximum is reached. This process is repeated while sequencing through each address of the MX27L2048. This part of the algorithm is done at VCC = 6.0V to assure that each EPROM bit is programmed to a sufficiently high threshold voltage. After the interactive programming is completed, an overprogram pulse is

given to each memory location; this ensures that all bits have sufficient margin. After the final address is completed, the entire EPROM memory is verified at VCC = $5V \pm 10\%$.

FAST PROGRAMMING

The device is set up in the fast programming mode when the programming voltage VPP = 12.75V is applied, with VCC = 6.25 V and PGM = VIH (Algorithm is shown in Figure 2). The programming is achieved by applying a single TTL low level 100μs pulse to the \overline{PGM} input after addresses and data line are stable. If the data is not verified, an additional pulse is applied for a maximum of 25 pulses. This process is repeated while sequencing through each address of the device. When the programming mode is completed, the data in all address is verified at VCC = VPP = $5V \pm 10\%$.

PROGRAM INHIBIT MODE

Programming of multiple MX27L2048's in parallel with different data is also easily accomplished by using the Program Inhibit Mode. Except for \overline{CE} and \overline{OE} , all like inputs of the parallel MX27L2048 may be common. A TTL low-level program pulse applied to an MX27L2048 \overline{CE} input with VPP = $12.5 \pm 0.5 V$ will program the MX27L2048. A high-level \overline{CE} input inhibits the other MX27L2048s from being programmed.

PROGRAM VERIFY MODE

Verification should be performed on the programmed bits to determine that they were correctly programmed. The verification should be performed with \overline{OE} and \overline{CE} , at VIL, and VPP at its programming voltage.

AUTO IDENTIFY MODE

The auto identify mode allows the reading out of a binary code from an EPROM that will identify its manufacturer and device type. This mode is intended for use by programming equipment for the purpose of automatically matching the device to be programmed with its corresponding programming algorithm. This mode is functional in the $25^{\circ}C \pm 5^{\circ}C$ ambient temperature range that is required when programming the MX27L2048.

To activate this mode, the programming equipment must

force 12.0 ± 0.5 V on address line A9 of the device. Two identifier bytes may then be sequenced from the device outputs by toggling address line A0 from VIL to VIH. All other address lines must be held at VIL during auto identify mode.

Byte 0 (A0 = VIL) represents the manufacturer code, and byte 1 (A0 = VIH), the device identifier code. For the MX27L2048, these two identifier bytes are given in the Mode Select Table. All identifiers for manufacturer and device codes will possess odd parity, with the MSB (DQ15) defined as the parity bit.

READ MODE

The MX27L2048 has two control functions, both of which must be logically satisfied in order to obtain data at the outputs. Chip Enable (\overline{CE}) is the power control and should be used for device selection. Output Enable (\overline{OE}) is the output control and should be used to gate data to the output pins, independent of device selection. Assuming that addresses are stable, address access time (t_{ACC}) is equal to the delay from \overline{CE} to output (t_{CE}). Data is available at the outputs t_{OE} after the falling edge of \overline{OE} 's, assuming that \overline{CE} has been LOW and addresses have been stable for at least $t_{ACC} - t_{OE}$.

WORD-WIDE MODE

With \overline{BYTE}/VPP at $VCC \pm 0.2V$ outputs Q0-7 present data D0-7 and outputs Q8-15 present data D8-15, after \overline{CE} and \overline{OE} are appropriately enabled.

BYTE-WIDE MODE

With \overline{BYTE}/VPP at $GND \pm 0.2V$, outputs Q8-15 are tri-stated. If Q15/A-1 = VIH, outputs Q0-7 present data bits D8-15. If Q15/A-1 = VIL, outputs Q0-7 present data bits D0-7.

STANDBY MODE

The MX27L2048 has a CMOS standby mode which reduces the maximum VCC current to 20 μA . It is placed in CMOS standby when \overline{CE} is at $VCC \pm 0.3$ V. The MX27L2048 also has a TTL-standby mode which reduces the maximum VCC current to 1.5 mA. It is placed in TTL-standby when \overline{CE} is at VIH. When in standby mode, the

outputs are in a high-impedance state, independent of the \overline{OE} input.

TWO-LINE OUTPUT CONTROL FUNCTION

To accommodate multiple memory connections, a two-line control function is provided to allow for:

1. Low memory power dissipation,
2. Assurance that output bus contention will not occur.

It is recommended that \overline{CE} be decoded and used as the primary device-selecting function, while \overline{OE} be made a common connection to all devices in the array and connected to the READ line from the system control bus. This assures that all deselected memory devices are in their low-power standby mode and that the output pins are only active when data is desired from a particular memory device.

SYSTEM CONSIDERATIONS

During the switch between active and standby conditions, transient current peaks are produced on the rising and falling edges of Chip Enable. The magnitude of these transient current peaks is dependent on the output capacitance loading of the device. At a minimum, a 0.1 μF ceramic capacitor (high frequency, low inherent inductance) should be used on each device between VCC and GND to minimize transient effects. In addition, to overcome the voltage drop caused by the inductive effects of the printed circuit board traces on EPROM arrays, a 4.7 μF bulk electrolytic capacitor should be used between VCC and GND for each eight devices. The location of the capacitor should be close to where the power supply is connected to the array.

MODE SELECT TABLE

| MODE | PINS | | | | | | OUTPUTS |
|-------------------|----------|-----|-----|-----|----|-----|---------|
| | CE | OE | PGM | A0 | A9 | VPP | |
| Read | VIL | VIL | VIH | X | X | VCC | DOUT |
| Output Disable | VIL | VIH | VIH | X | X | VCC | High Z |
| Standby (TTL) | VIH | X | X | X | X | VCC | High Z |
| Standby (CMOS) | VCC±0.3V | X | X | X | X | VCC | High Z |
| Program | VIL | VIH | VIL | X | X | VPP | DIN |
| Program Verify | VIL | VIL | VIH | X | X | VPP | DOUT |
| Program Inhibit | VIH | X | X | X | X | VPP | High Z |
| Manufacturer Code | VIL | VIL | X | VIL | VH | VCC | 00C2H |
| Device Code | VIL | VIL | X | VIH | VH | VCC | 0122H |

NOTES: 1. VH = 12.0 V ± 0.5 V
 2. X = Either VIH or VIL(For auto select)

3. A1 - A8 = A10 - A16 = VIL(For auto select)
 4. See DC Programming Characteristics for VPP voltage during programming.

FIGURE 1. INTERACTIVE PROGRAMMING FLOW CHART

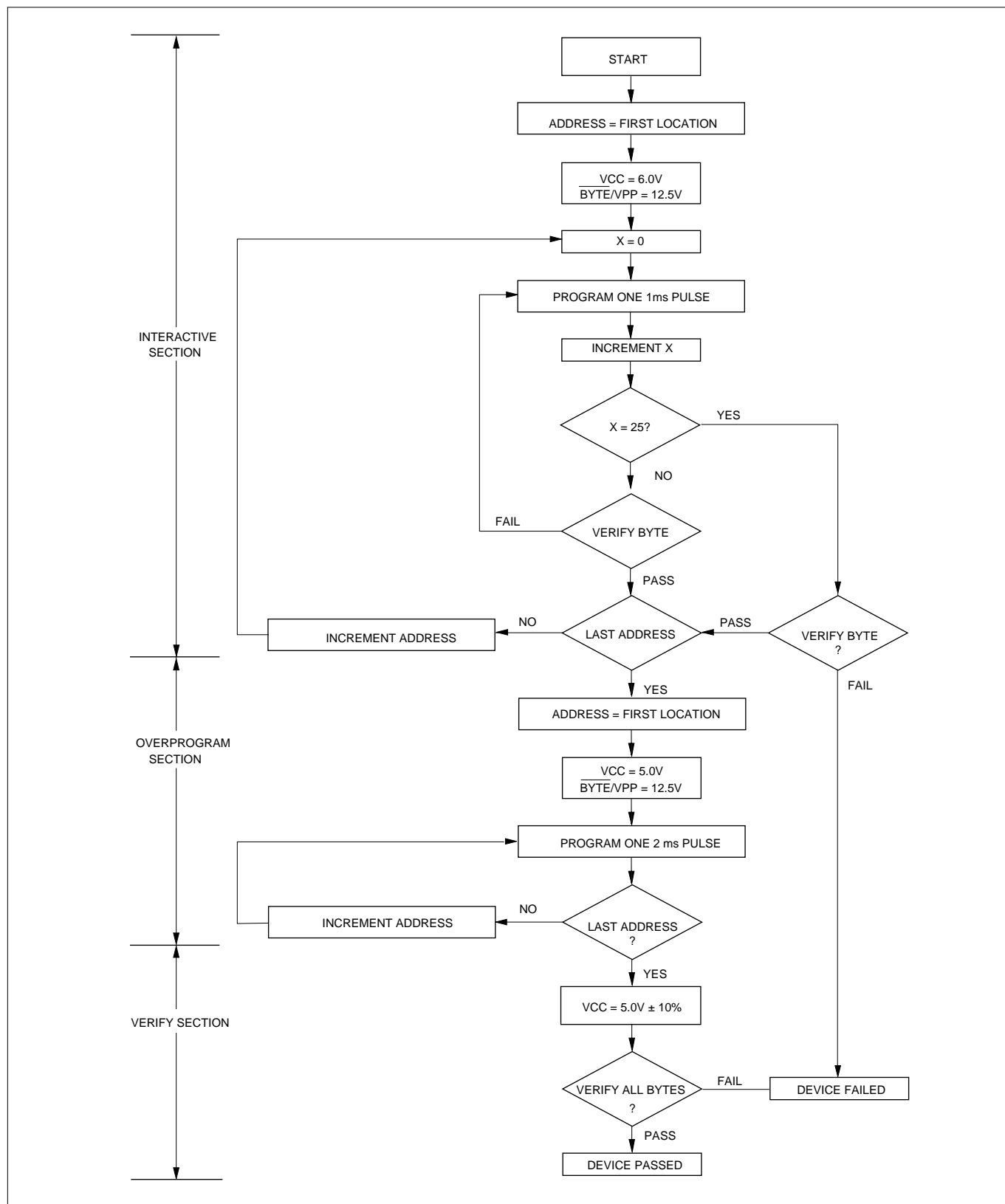
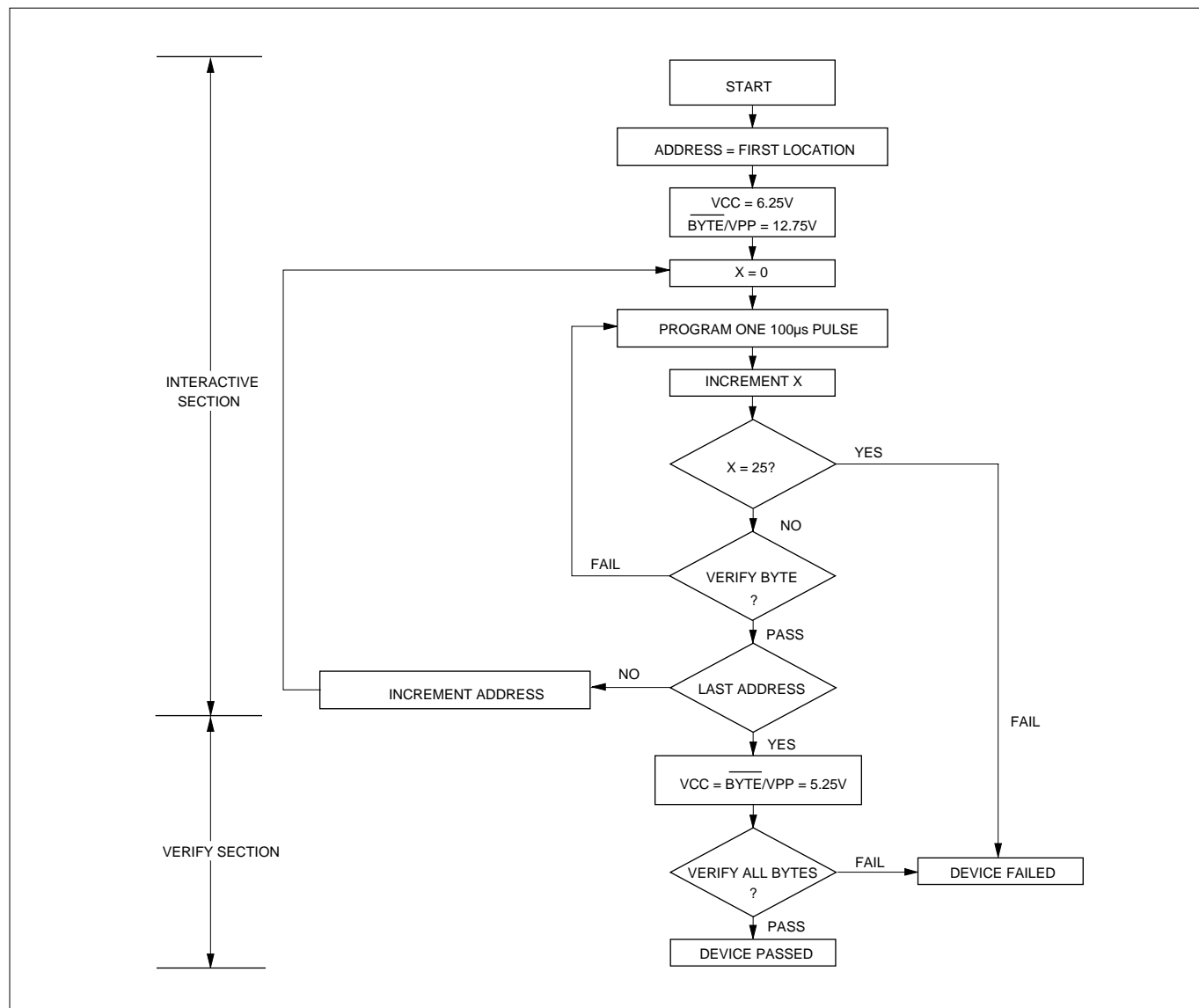
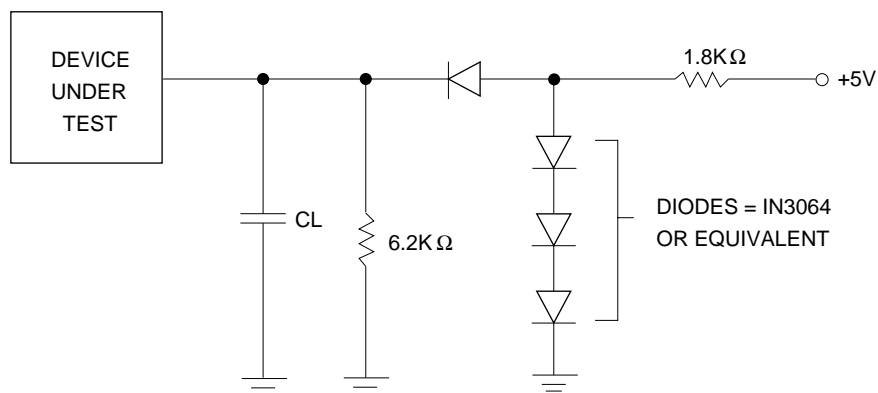
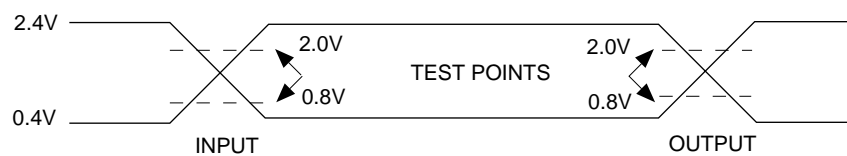


FIGURE 2. FAST PROGRAMMING FLOW CHART



SWITCHING TEST CIRCUITS


CL = 100 pF including jig capacitance

SWITCHING TEST WAVEFORMS


AC TESTING: Inputs are driven at 2.4V for a logic "1" and 0.4V for a logic "0".
Input pulse rise and fall times are <20ns.

ABSOLUTE MAXIMUM RATINGS

| RATING | VALUE |
|-------------------------------|---------------------|
| Ambient Operating Temperature | 0°C to 70°C |
| Storage Temperature | -65°C to 125°C |
| Applied Input Voltage | -0.5V to 7.0V |
| Applied Output Voltage | -0.5V to VCC + 0.5V |
| VCC to Ground Potential | -0.5V to 7.0V |
| A9 & Vpp | -0.5V to 13.5V |

NOTICE:

Stresses greater than those listed under ABSOLUTE MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended period may affect reliability.

NOTICE:

Specifications contained within the following tables are subject to change.

DC CHARACTERISTICS TA = 0°C to 70°C, VCC = 2.7 ~ 3.6V

| SYMBOL | PARAMETER | MIN. | MAX. | UNIT | CONDITIONS |
|--------|-------------------------|------|-----------|------|--|
| VOH | Output High Voltage | 2.4 | | V | IOH = -0.4mA, VCC=3.0V |
| VOL | Output Low Voltage | | 0.4 | V | IOL = 2.1mA, VCC=3.0V |
| VIH | Input High Voltage | 2.0 | VCC + 0.5 | V | |
| VIL | Input Low Voltage | -0.3 | 0.8 | V | 2.7V < VCC < 3.6V |
| ILI | Input Leakage Current | -10 | 10 | μA | VIN = 0 to 3.6V |
| ILO | Output Leakage Current | -10 | 10 | μA | VOUT = 0 to 3.6V |
| ICC3 | VCC Power-Down Current | | 20 | μA | CE = VCC ± 0.3V |
| ICC2 | VCC Standby Current | | 0.25 | mA | CE = VIH |
| ICC1 | VCC Active Current | | 20 | mA | CE = VIL, f=5MHz, Iout = 0mA, VCC=3.6V |
| IPP | VPP Supply Current Read | | 100 | μA | CE = OE = VIL, VPP = VCC |

CAPACITANCE TA = 25°C, f = 1.0 MHz (Sampled only)

| SYMBOL | PARAMETER | TYP. | MAX. | UNIT | CONDITIONS |
|--------|--------------------|------|------|------|------------|
| CIN | Input Capacitance | 8 | 12 | pF | VIN = 0V |
| COUT | Output Capacitance | 8 | 12 | pF | VOUT = 0V |
| CVPP | VPP Capacitance | 18 | 25 | pF | VPP = 0V |

AC CHARACTERISTICS TA = 0°C to 70°C, VCC = 2.7 ~ 3.6V

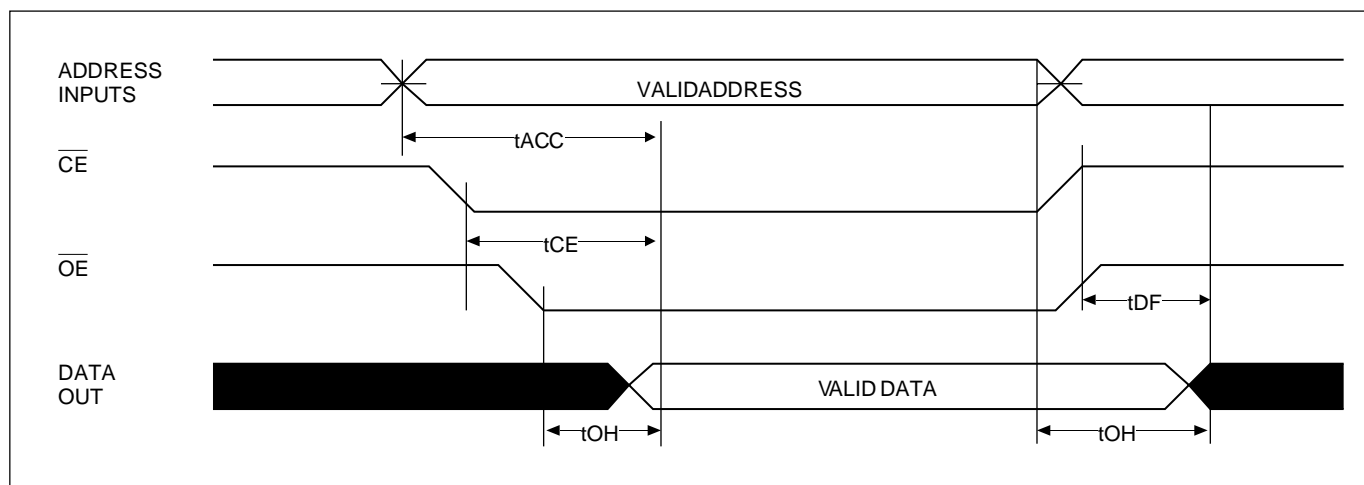
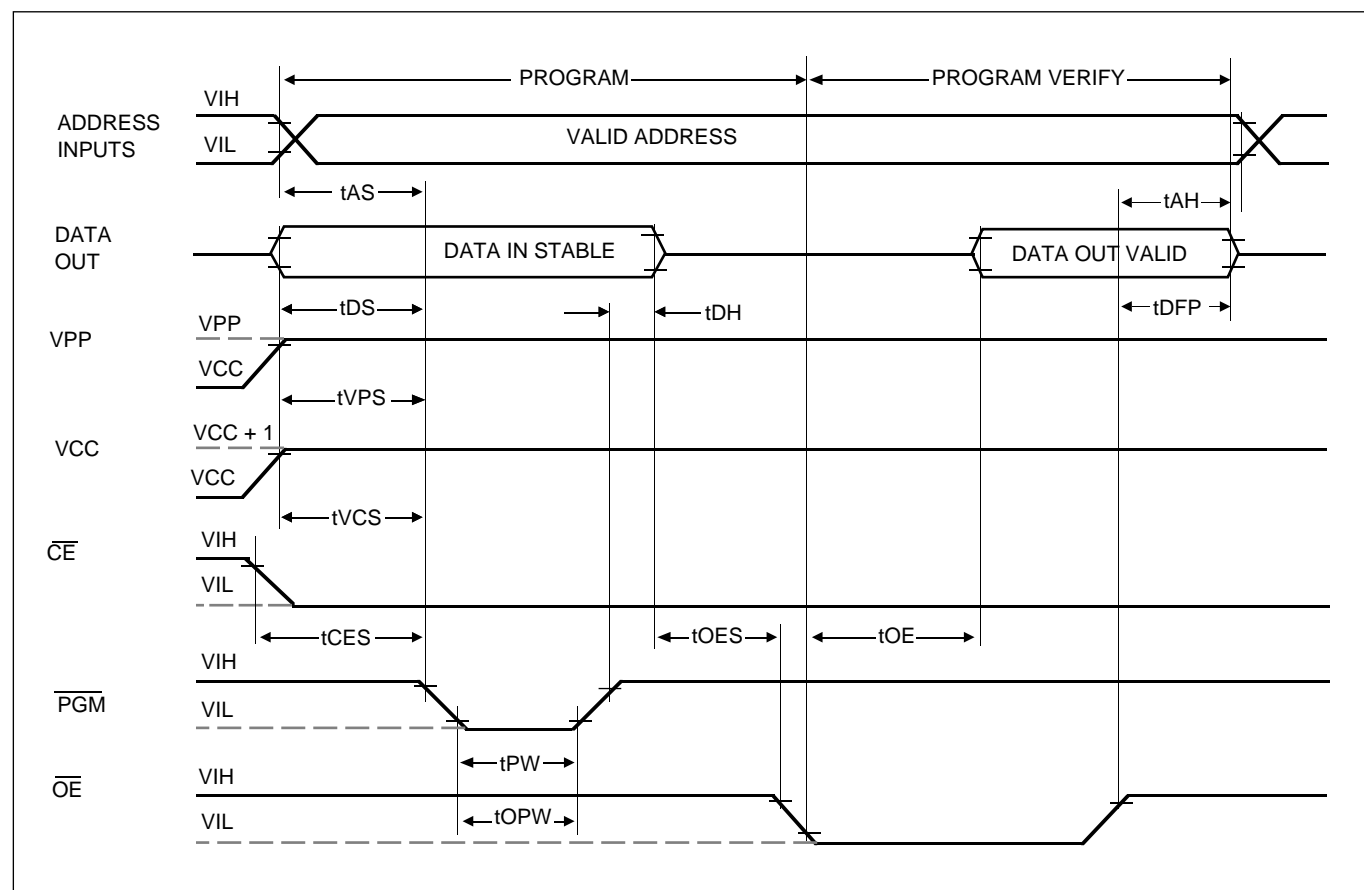
| SYMBOL | PARAMETER | 27L2048-15 | | 27L2048-20 | | 27L2048-25 | | UNIT | CONDITIONS |
|--------|---|------------|------|------------|------|------------|------|------|---------------|
| | | MIN. | MAX. | MIN. | MAX. | MIN. | MAX. | | |
| tACC | Address to Output Delay | | 150 | | 200 | | 250 | ns | CE = OE = VIL |
| tCE | Chip Enable to Output Delay | | 150 | | 200 | | 250 | ns | OE = VIL |
| tOE | Output Enable to Output Delay | | 70 | | 100 | | 120 | ns | CE = VIL |
| tDF | OE High to Output Float, or CE High to Output Float | 0 | 50 | 0 | 60 | 0 | 70 | ns | |
| tOH | Output Hold from Address, CE or OE which ever occurred first | 0 | | 0 | | 0 | | ns | |

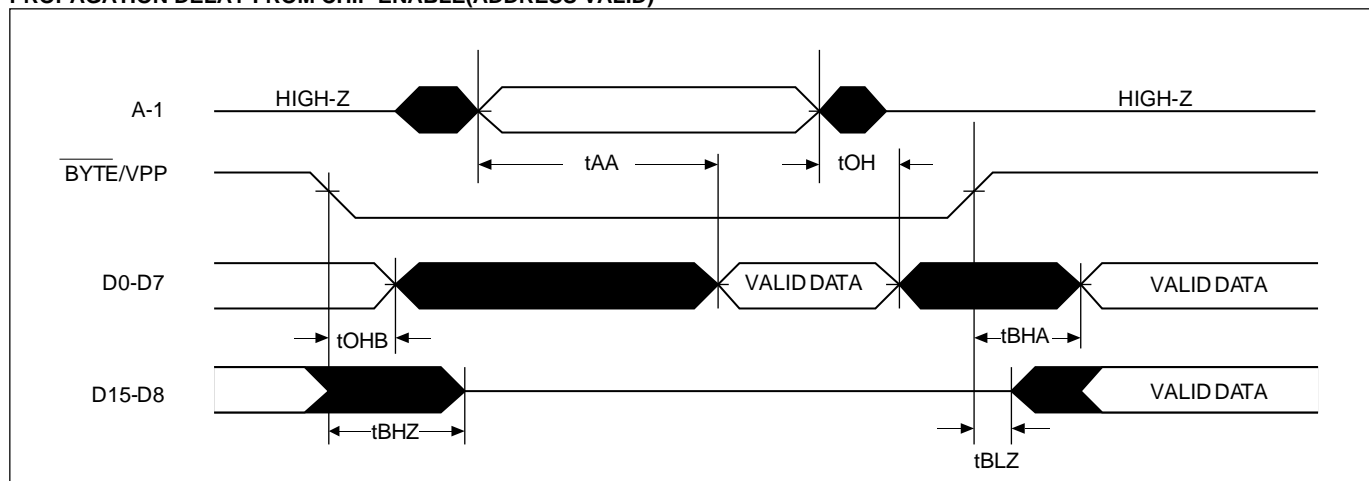
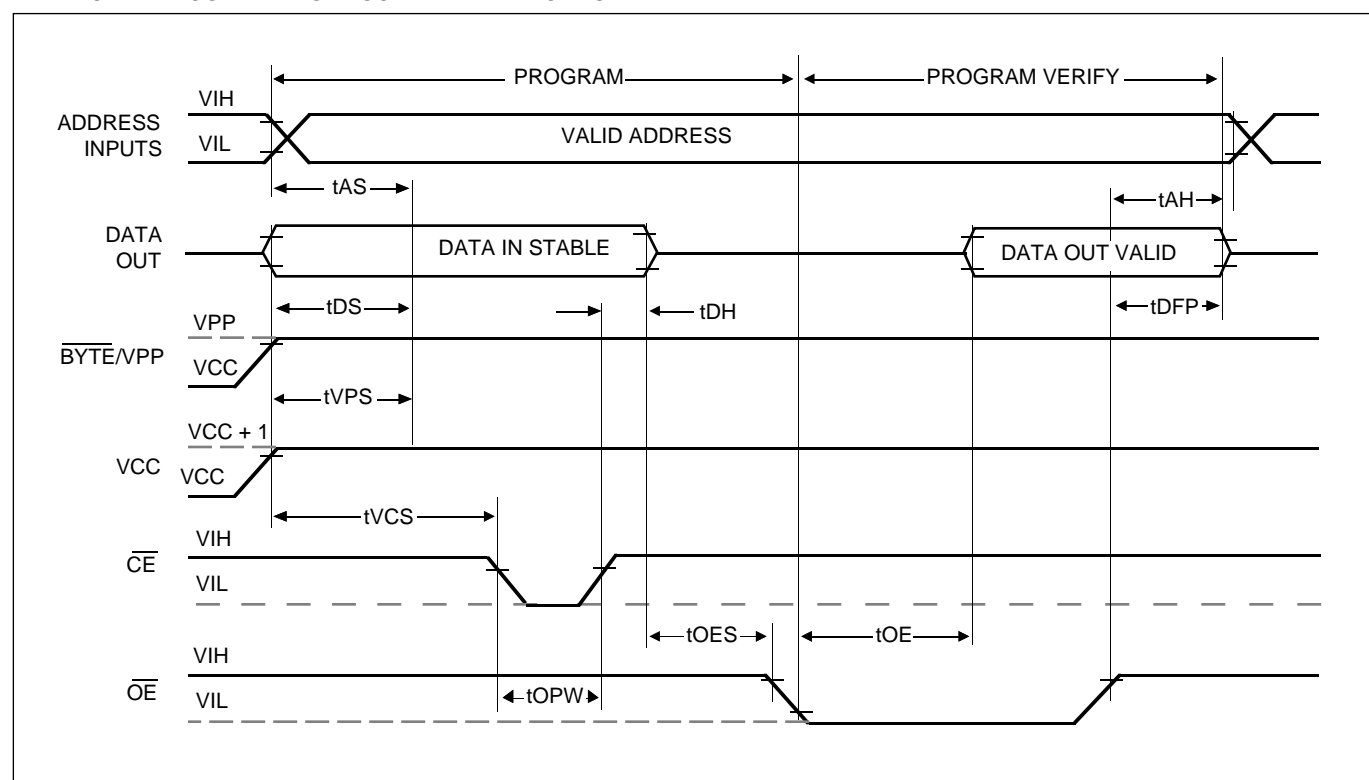
DC PROGRAMMING CHARACTERISTICS $T_A = 25^\circ\text{C} \pm 5^\circ\text{C}$

| SYMBOL | PARAMETER | MIN. | MAX. | UNIT | CONDITIONS |
|--------|---------------------------------------|------|-----------|---------------|--------------------|
| VOH | Output High Voltage | 2.4 | | V | IOH = -0.40mA |
| VOL | Output Low Voltage | | 0.4 | V | IOL = 2.1mA |
| VIH | Input High Voltage | 2.0 | VCC + 0.5 | V | |
| VIL | Input Low Voltage | -0.3 | 0.8 | V | |
| ILI | Input Leakage Current | -10 | 10 | μA | VIN = 0 to 3.6V |
| VH | A9 Auto Select Voltage | 11.5 | 12.5 | V | |
| ICC3 | VCC Supply Current (Program & Verify) | | 50 | mA | |
| IPP2 | VPP Supply Current(Program) | | 30 | mA | CE = VIL, OE = VIH |
| VCC1 | Interactive Supply Voltage | 5.75 | 6.25 | V | |
| VPP1 | Interactive Programming Voltage | 12.0 | 13.0 | V | |
| VCC2 | Fast Programming Supply Voltage | 6.00 | 6.50 | V | |
| VPP2 | Fast Programming Voltage | 12.5 | 13.0 | V | |

AC PROGRAMMING CHARACTERISTICS $T_A = 25^\circ\text{C} \pm 5^\circ\text{C}$

| SYMBOL | PARAMETER | MIN. | MAX. | UNIT | CONDITIONS |
|--------|-----------------------------------|--------------------|------|---------------|---------------|
| tAS | Address Setup Time | 2.0 | | μS | |
| tOES | OE Setup Time | 2.0 | | μS | |
| tDS | Data Setup Time | 2.0 | | μS | |
| tAH | Address Hold Time | 0 | | μS | |
| tDH | Data Hold Time | 2.0 | | μS | |
| tDFP | CE to Output Float Delay | 0 | 130 | nS | |
| tVPS | VPP Setup Time | 2.0 | | μS | |
| tPW | CE Program Pulse Width | <i>Fast</i> | 95 | 105 | μS |
| | | <i>Interactive</i> | 0.95 | 1.05 | mS |
| tOPW | CE Overprogram Pulse(Interactive) | 1.95 | 2.05 | mS | |
| tVCS | VCC Setup Time | 2.0 | | μS | |
| tDV | Data Valid from CE | | 250 | nS | |
| tCES | CE Setup Time | 2.0 | | μS | |
| tOE | Data valid from OE | | 150 | nS | |

WAVEFORMS(MX27C2048)
READ CYCLE

INTERACTIVE PROGRAMMING ALGORITHM WAVEFORMS


WAVEFORMS(MX27C2100)
PROPAGATION DELAY FROM CHIP ENABLE(ADDRESS VALID)

INTERACTIVE PROGRAMMING ALGORITHM WAVEFORMS


ORDERING INFORMATION**CERAMIC PACKAGE**

| PART NO. | ACCESS TIME (ns) | OPERATING CURRENT MAX.(mA) | STANDBY CURRENT MAX.(μA) | PACKAGE |
|----------------|---------------------|-------------------------------|-----------------------------|---------------------------|
| MX27L2048DC-15 | 150 | 20 | 20 | 40 Pin DIP(JEDEC pin out) |
| MX27L2048DC-20 | 200 | 20 | 20 | 40 Pin DIP(JEDEC pin out) |
| MX27L2048DC-25 | 250 | 20 | 20 | 40 Pin DIP(JEDEC pin out) |

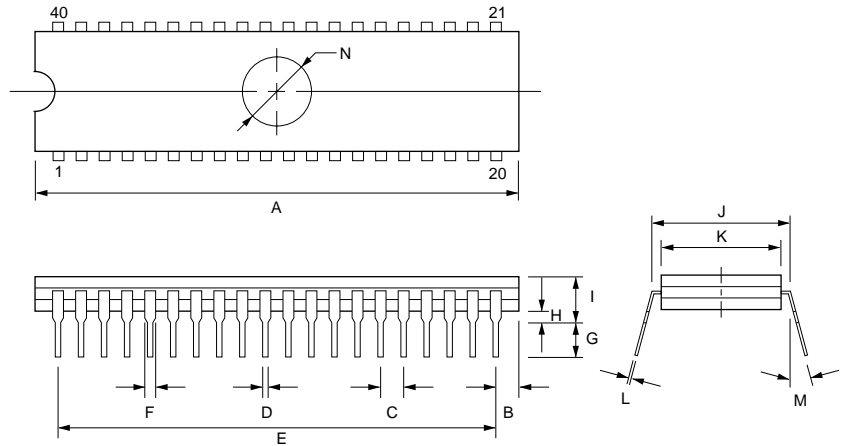
PLASTIC PACKAGE

| PART NO. | ACCESS TIME (ns) | OPERATING CURRENT MAX.(mA) | STANDBY CURRENT MAX.(μA) | PACKAGE |
|----------------|---------------------|-------------------------------|-----------------------------|---------------------------|
| MX27L2048PC-15 | 150 | 20 | 20 | 40 Pin DIP(JEDEC pin out) |
| MX27L2048PC-20 | 200 | 20 | 20 | 40 Pin DIP(JEDEC pin out) |
| MX27L2048PC-25 | 250 | 20 | 20 | 40 Pin DIP(JEDEC pin out) |
| MX27L2048QC-15 | 150 | 20 | 20 | 44 Pin PLCC |
| MX27L2048QC-20 | 2000 | 20 | 20 | 44 Pin PLCC |
| MX27L2048QC-25 | 250 | 20 | 20 | 44 Pin PLCC |
| MX27L2048TC-15 | 150 | 20 | 20 | 40 Pin TSOP(I) |
| MX27L2048TC-20 | 200 | 20 | 20 | 40 Pin TSOP(I) |
| MX27L2048TC-25 | 250 | 20 | 20 | 40 Pin TSOP(I) |

PACKAGE INFORMATION
40-PIN CERDIP(MSI) WITH WINDOW(600 mil)

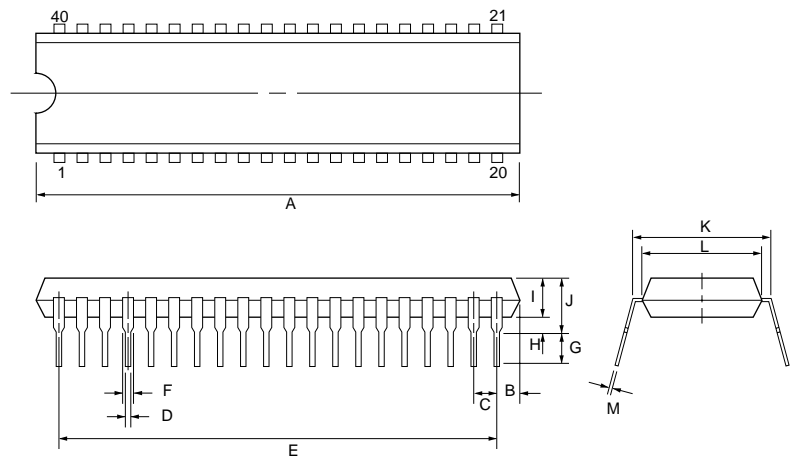
| ITEM | MILLIMETERS | INCHES |
|------|-------------|-------------|
| A | 53.34 max. | 2.100 max. |
| B | 1.85 ± .30 | .073 ± .012 |
| C | 2.54 [TP] | .100 [TP] |
| D | .46 ± .05 | .018 ± .002 |
| E | 48.22 | 1.900 |
| F | 1.40 ± .05 | .055 ± .002 |
| G | 3.43 ± .38 | .135 ± .015 |
| H | .94 ± .41 | .037 ± .016 |
| I | 5.00 | .197 |
| J | 15.51 ± .08 | .611 ± .003 |
| K | 14.82 ± .38 | .584 ± .015 |
| L | .25 ± .13 | .010 ± .005 |
| M | 0~15° | 0~15° |
| N | φ9.64 | φ.380 |

NOTE: Each lead centerline is located within .25 mm[.01 inch] of its true position [TP] at maximum material condition.


40-PIN PLASTIC DIP(600 mil)

| ITEM | MILLIMETERS | INCHES |
|------|-------------|-------------|
| A | 52.54 max. | 2.070 max. |
| B | 2.03 [REF] | .080 [REF] |
| C | 2.54 [TP] | .100 [TP] |
| D | .46 [Typ.] | .018 [Typ.] |
| E | 48.22 | 1.900 |
| F | 1.52 [Typ.] | .060 [Typ.] |
| G | 3.30 ± .25 | .130 ± .010 |
| H | .51 [REF] | .020 [REF] |
| I | 3.91 ± .25 | .154 ± .010 |
| J | 4.42 ± .25 | .174 ± .010 |
| K | 15.22 ± .25 | .600 ± .010 |
| L | 13.76 ± .25 | .542 ± .010 |
| M | .25 [Typ.] | .010 [Typ.] |

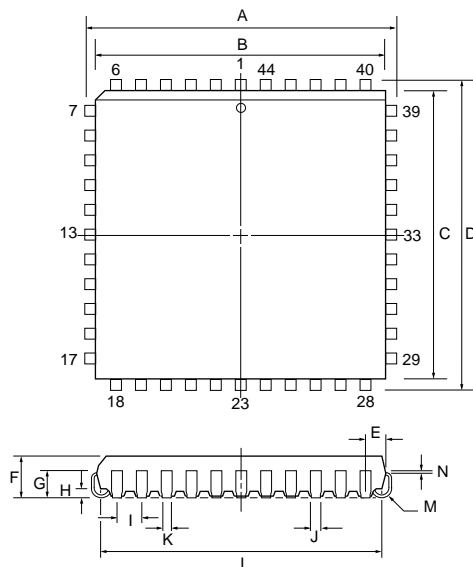
NOTE: Each lead centerline is located within .25 mm[.01 inch] of its true position [TP] at maximum material condition.



PACKAGE INFORMATION

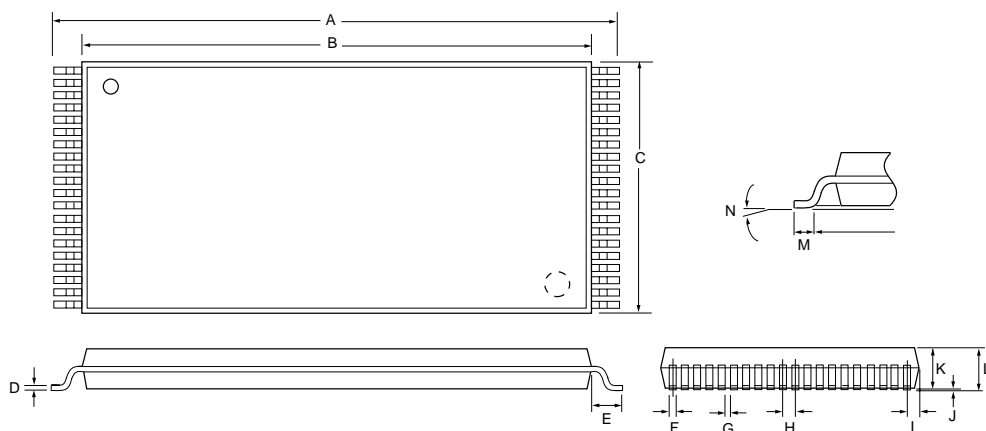
44-PIN PLASTIC LEADED CHIP CARRIER (PLCC)

| ITEM | MILLIMETERS | INCHES |
|------|-------------|-------------|
| A | 17.53 ± .12 | .690 ± .005 |
| B | 16.59 ± .12 | .653 ± .005 |
| C | 16.59 ± .12 | .653 ± .005 |
| D | 17.53 ± .12 | .690 ± .005 |
| E | 1.95 | .077 |
| F | 4.70 max. | .185 max |
| G | 2.55 ± .25 | .100 ± .010 |
| H | .51 min. | .020 min. |
| I | 1.27 [Typ.] | .050 [Typ.] |
| J | .71 ± .10 | .028 ± .004 |
| K | .46 ± .10 | .018 ± .004 |
| L | 15.50 ± .51 | .610 ± .020 |
| M | .63 R | .025 R |
| N | .25 [Typ.] | .010 [Typ.] |



40-PIN PLASTIC TSOP

| ITEM | MILLIMETERS | INCHES |
|------|--------------|--------------|
| A | 14.0 ± .20 | 0.551 ± .008 |
| B | 12.4 ± .10 | 0.488 ± .004 |
| C | 10.1 max. | 0.398 max. |
| D | 0.125 [Typ.] | 0.005 [Typ.] |
| E | .80 [Typ.] | .031 [Typ.] |
| F | .20 ± .10 | .008 ± .004 |
| G | .30 ± .10 | .012 ± .004 |
| H | .50 [Typ.] | .020 [Typ.] |
| I | .45 max. | 0.18 max. |
| J | 0 ~ .20 | 0 ~ .008 |
| K | 1.00 ± .10 | .039 ± .004 |
| L | 1.2 max. | 0.047 max. |
| M | .50 | .020 |
| N | 0 ~ 10° | 0 ~ 10° |



NOTE: Each lead centerline is located within .25 mm [.01 inch] of its true position [TP] at maximum material condition.

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