

FEATURES

- Sampling Rates from 1 kHz to 2.5 MHz
- DNL better than 1/2 LSB (typ) up to 3 MHz
- Low Power CMOS 75 mW at 5 V
- Monotonic; No Missing Codes
- Interface to any Analog Input Range between GND and V_{DD}
- No S/H needed for CCD Outputs or Input Signals less than100 kHz
- Single Power Supply
- ESD Protection to 2000 Volts

BENEFITS

- Reduced Board Space (Small Package)
- Reduced External Parts, No Sample/Hold Needed
- Suitable for Battery & Power Critical Applications
- Designer can Adapt Input Range & Scaling

APPLICATIONS

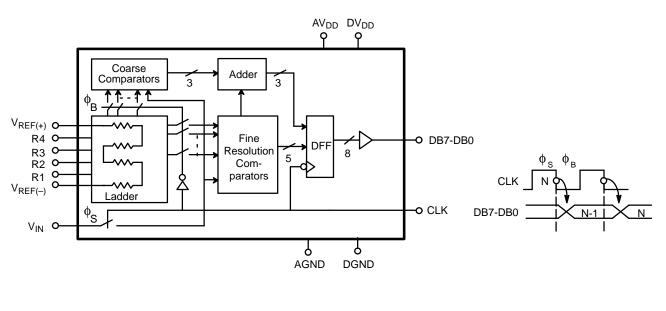
- Low Power A/D Applications
- High Resolution Imaging
- Multiplexed Data Acquisition
- Radar Pulse Analysis

Latch-Up Free

GENERAL DESCRIPTION

The MP7693 is an 8-bit monolithic CMOS Analog-to-Digital Converter designed for precision applications demanding low power consumption and fast conversion. The input architecture of the MP7693 allows direct interface to any analog input range between AGND and AVDD (0 to 2 V, 1 to 4 V, 0 to 5 V, etc.). The user simply sets VREF(+) and VREF(-) to encompass the desired input range. The MP7693 uses a two-step flash technique. The first segment converts the 3 MSBs and consists of 7 autobalanced comparators, latches, an encoder, and buffer storage registers. The second segment converts the remaining 5 LSBs.

With 75 mW typical and 100 mW maximum power dissipation, the MP7693 achieves its excellent performance due to the inherent high speed of a proprietary CMOS Process.

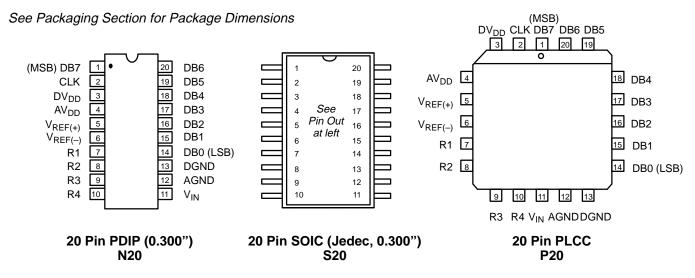


SIMPLIFIED BLOCK AND TIMING DIAGRAM

ORDERING INFORMATION

Package Type	Temperature Range	Part No.	DNL (LSB)	INL (LSB)
Plastic Dip	-40 to +85°C	MP7693BN	±3/4	3/4
PLCC	–40 to +85°C	MP7693BP	±3/4	3/4
SOIC	–40 to +85°C	MP7693BS	±3/4	3/4

PIN CONFIGURATIONS



PIN OUT DEFINITIONS

PIN NO.	NAME	DESCRIPTION		
1	DB7	Data Output Bit 7 (MSB)		
2	CLK	Clock Input		
3	DV_DD	Power Supply		
4	AV _{DD}	Analog Power Supply		
5	V _{REF(+)}	Upper Ref. Voltage		
6	V _{REF(-)}	Lower Ref. Voltage		
7	R1	Ref. Ladder Tap		
8	R2	Ref. Ladder Tap		
9	R3	Ref. Ladder Tap		
10	R4	Ref. Ladder Tap		

PIN NO.	NAME	DESCRIPTION		
11	V _{IN}	Analog Signal Input		
12	AGND	Analog Ground		
13	DGND	Digital Ground		
14	DB0	Data Output Bit 0 (LSB)		
15	DB1	Data Output Bit 1		
16	DB2	Data Output Bit 2		
17	DB3	Data Output Bit 3		
18	DB4	Data Output Bit 4		
19	DB5	Data Output Bit 5		
20	DB6	Data Output Bit 6		





ELECTRICAL CHARACTERISTICS TABLE

Unless Otherwise Specified: $AV_{DD} = DV_{DD} = 5 V$, $F_S = 2.5 MHz$ (50% Duty Cycle), $V_{REF(+)} = 4.1$, $V_{REF(-)} = GND$, $T_A = 25^{\circ}C$

		L T.	a = 25°C	Tmin to	Tmax		
Parameter	Symbol	Min	Тур Мах	Min	Max	Units	Test Conditions/Comments
KEY FEATURES							
Resolution	_	8		8		Bits	
Sampling Rate ¹	F _S	.001	3	.001	3	MHz	
ACCURACY ²							
Differential Non-Linearity	DNL		±3/4		\pm 3/4	LSB	
Integral Non-Linearity	INL		⊥3/4 ±3/4		$\pm 3/4$ $\pm 3/4$	LSB	Best Fit Line
(Relative Accuracy)							(Max INL – Min INL) / 2
Zero Scale Error	EZS		10			mV	
Full Scale Error	EFS		10			mV	
REFERENCE VOLTAGES							
Positive Ref. Voltage	V _{REF(+)}		V _{DD}		V _{DD}	v	
Negative Ref. Voltage	$V_{REF(-)}$	GND	.00	GND	•00	v	
Differential Ref. Voltage ⁵	V _{REF}	2.0	V _{DD}	2.0	V_{DD}	V	
Ladder Resistance	RL	500	1500	300	1950	Ω	
Ladder Temp. Coefficient ¹	R _{TCO}				3000	ppm/°C	
ANALOG INPUT ¹							
Input Voltage Range ⁷	V _{IN}	V _{REF(-)}	V _{REF(+)}		V _{REF(+)}	v	
Input Capacitance ³	C _{IN}	KEI()	50		KEI (1)	pF	
Aperture Delay ¹	t _{AP}		55			ns	
DIGITAL INPUTS							
Logical "1" Voltage	VIH	3.5		3.5		v	
Logical "0" Voltage	VIL	0.0	1.5	0.0	1.5	v	
Leakage Currents	I _{IN}						V _{IN} =GND to V _{DD}
CLK		-10	10	-10	10	μA	
Input Capacitance			5			pF	
Clock Timing (See Figure 1.) ¹ Clock Period	ta	333		333		ns	
Rise & Fall Time ⁴	t _S t _R , t _F	000	10	000	10	ns	
"High" Time ⁶	t _S	166	500,000	250	500,000	ns	
"Low" Time ⁶	t _B	166	500,000	250	500,000	ns	
DIGITAL OUTPUTS							C _{OUT} =15 pF
Logical "1" Voltage	Vou	V _{DD} -0.5		V _{DD} -0.5		v	I _{LOAD} = 1 mA
Logical "0" Voltage	VOH V _{OL}	0.000	0.4		0.4	v	$I_{LOAD} = 2 \text{ mA}$
Data Hold Time	t _{HLD}	10		10		ns	(See Figure 1.) (1)
Data Valid Delay ¹	t _{DL}		55			ns	
POWER SUPPLIES ⁸							
Operating Voltage (AV _{DD} , DV _{DD})	V _{DD}	4	56	4	6	v	(1)
Current ($AV_{DD} + DV_{DD}$)	I _{DD}		15 20		35	mA	$V_{IN} = 2 V$

Rev. 1.00 T⊙M

MP7693



ELECTRICAL CHARACTERISTICS TABLE (CONT'D)

NOTES

¹ Guaranteed by Design. Not production tested.

- ² Tester measures code transitions by dithering the voltage of the analog input (V_{IN}). The difference between the measured code width and the ideal value (V_{REF}/256) is the DNL error (*Figure 2.*). The INL error is the maximum distance (in LSB's) from the best fit line to any transition voltage (*Figure 3.*).
- ³ See V_{IN} input equivalent circuit (*Figure 4.*).
- ⁴ Clock specification to meet aperture specification (t_{AP}). Actual rise/fall time can be less stringent with no loss of accuracy.

- ⁵ Specified values guarantee functionality. Refer to other parameters for accuracy.
- ⁶ System can clock MP7693 with any duty cycle as long as all timing conditions are met.
- ⁷ Input range where input is converted correctly into binary code. Input voltage outside specified range converts to zero or full scale output.
- ⁸ DV_{DD} and AV_{DD} are connected through the silicon substrate. Connect together at the package.

Specifications are subject to change without notice

ABSOLUTE MAXIMUM RATINGS (TA = +25°C unless otherwise noted)^{1, 2}

V _{DD} (to GND)	+7 V
V _{REF(+)} & V _{REF(-)}	GND –0.5 to V _{DD} +0.5 V
V _{IN}	GND –0.5 to V_DD +0.5 V
All Inputs	GND –0.5 to V_DD +0.5 V
All Outputs	GND –0.5 to V_DD +0.5 V

Storage Temperature
Lead Temperature (Soldering 10 seconds) +300°C
Package Power Dissipation Rating to 75°C
PDIP, PLCC, SOIC 900mW
Derates above 75°C 12mW/°C

NOTES:

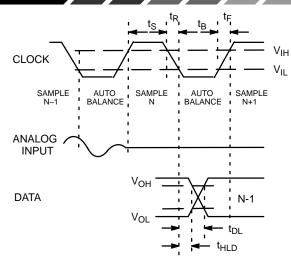
Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation at or above this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

² Any input pin which can see a value outside the absolute maximum ratings should be protected by Schottky diode clamps (HP5082-2835) from input pin to the supplies.

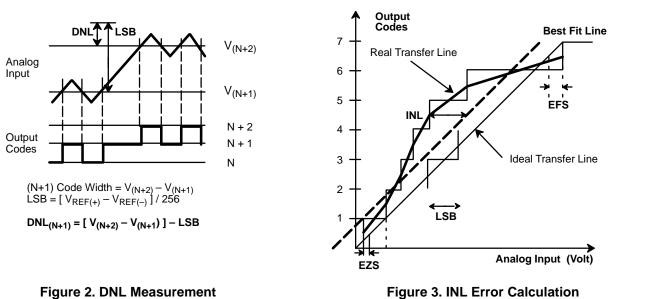




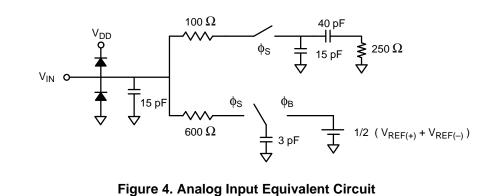








On Production Tester





THEORY OF OPERATION

MP7693

Analog-to-Digital Conversion

The MP7693 converts analog voltages into 256 digital codes by encoding the outputs of 7 coarse and 33 fine comparators. The conversion is synchronous with the clock and is accomplished in 2 clock periods.

The reference resistance ladder is a series of 257 resistors. The first and the last resistor of the ladder are half the value of the others so that the following relations apply:

 $R_{REF} = 256 * R$ $V_{REF} = V_{REF(+)} - V_{REF(-)} = 256 * LSB$

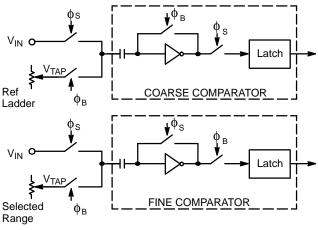


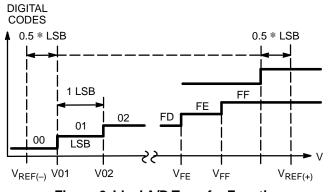
Figure 5. MP7693 Comparators

The clock signal generates the two internal phases, ϕ_B (CLK high) and ϕ_S (CLK low = sample) (*See Figure 5.*). The rising edge of the CLK input marks the end of the sampling phase (ϕ_S). Internal delay of the clock circuitry will delay the actual instant when ϕ_S disconnects the latches from the comparators. This delay is called aperture delay (t_{AP}).

The coarse comparators make the first pass conversion and select a ladder range for the fine comparators. The fine comparators are connected to the selected range during the next ϕ_B phase.

Accuracy of Conversion: DNL and INL

The transfer function for an ideal A/D converter is shown in *Figure 6.*



ZPEXAR

Figure 6. Ideal A/D Transfer Function

The first and the last transitions for the data bits take place at:

 $V_{IN} = V001 = V_{REF(-)} + 0.5 * LSB$ $V_{IN} = V_{FF} = V_{REF(+)} - 1.5 * LSB$ $LSB = V_{REF} / 256 = (V_{FF} - V01) / 254$

DIGITAL CODES 0.5 * LSB 1.5 * LSB E_{FS} E_{ZS} FF 02 01 00 V01 V02 V_{REF(-)} V_{FE} V_{FF} V_{REF(+)}

Figure 7. Real A/D Transfer Curve

In a "real" converter, the code-to-code transitions do not fall exactly every $V_{REF}/256$ volts.

A positive DNL (Differential-Non-Linearity) error means that the real width of a particular code is larger than 1 LSB. This error is measured in fractions of LSBs.

A Max DNL specification guarantees that ALL code widths (DNL errors) are within the stated value. A specification of Max DNL = ± 0.5 LSB means that all code widths are within 0.5 and 1.5 LSB. If V_{REF} = 4.096 V then 1 LSB = 16.0 mV and every code width is within 8 and 24 mV.

The formulas for Differential Non-linearity (DNL), Integral Non-Linearity (INL) and zero and full scale errors (EZS, EFS) are:

DNL (01) = V02 - V01 - LSB

 $DNL (FE) = V_{FF} - V_{FE} - LSB$

 E_{FS} (full scale error) = $V_{FF} - [V_{REF(+)} - 1.5 * LSB]$

 E_{ZS} (zero scale error) = $V_{01} - [V_{REF(-)} + 0.5 * LSB]$

Figure 7. shows the zero scale and full scale error terms. *Figure 3.* gives a visual definition of the INL error. The chart shows a 3 bit converter transfer curve with greatly exaggerated







DNL errors to show the deviation of the real transfer curve from the ideal one.

After all transition voltages are measured, a best straight line is drawn (*see Figure 3.*) so that the positive INL error equals the negative INL error in magnitude., i.e. best fit line INL = (maximum positive – maximum negative) / 2.

Clock and Conversion Timing

A system will clock the MP7693 continuously or it will give clock pulses intermittently when a conversion is desired. The timing of *Figure 8a* shows normal operation, while the timing of *Figure 8b* keeps the MP7693 in balance and ready to sample the analog input.

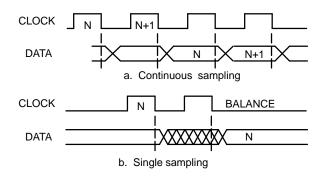


Figure 8. Relationship of Data to Clock

Analog Input

The MP7693 has very flexible input range characteristics. The user may set $V_{REF(+)}$ and $V_{REF(-)}$ to two fixed voltages and then vary the input DC and AC levels to match the V_{REF} range. Another method is to first design the analog input circuitry and then adjust the reference voltages for the analog input range. One advantage is that this approach may eliminate the need for external gain and offset adjust circuitry which may be required by fixed input range A/Ds.

The MP7693's performance is optimized by using analog input circuitry that is capable of driving the A_{IN} input. *NO TAG* shows the equivalent circuit for A_{IN} .

Reference Voltages

The input/output relationship is a function of V_{REF}:

$$A_{IN} = V_{IN} - V_{REF(-)}$$
$$V_{REF} = V_{REF(+)} - V_{REF(-)}$$
$$DATA = 255 * (A_{IN}/V_{REF})$$

A system can increase total gain by reducing V_{REF}.

Digital Interfaces

The logic encodes the outputs of the comparators into a binary code and latches the data in a D-type flip-flop for output.

The functional equivalent of the MP7693 (*Figure 9.*) is composed of:

- 1) Delay stage (t_{AP}) from the clock to the sampling phase (ϕ_S) .
- 2) An ideal analog switch which samples V_{IN}.
- An ideal A/D which tracks and converts V_{IN} with no delay.
- A series of two DFF's with specified hold (t_{HLD}) and delay (t_{DL}) times.

 $t_{\text{AP}}, t_{\text{HLD}}$ and t_{DL} are specified in the Electrical Characteristics table.

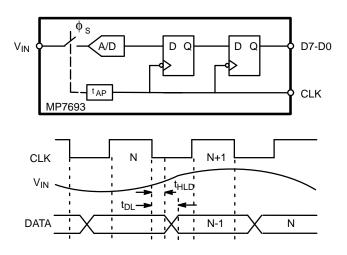


Figure 9. MP7693 Functional Equivalent Circuit and Interface Timing





APPLICATION NOTES

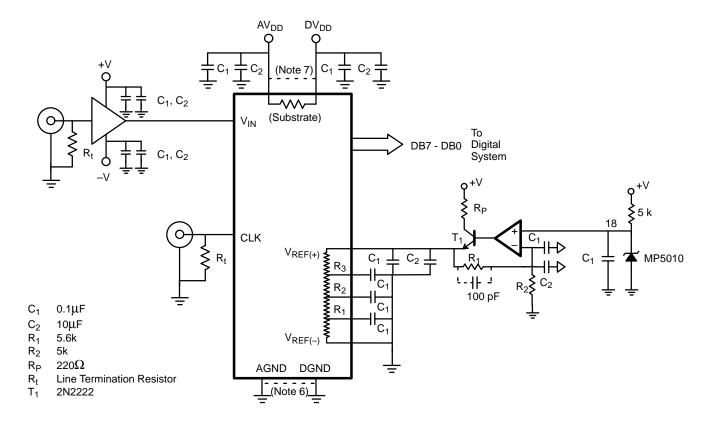


Figure 10. Typical Circuit Connections

The following information will be useful in maximizing the performance of the MP7693.

- 1. All signals should not exceed AV_{DD} +0.5 V or AGND –0.5 V or DV_{DD} +0.5 V or DGND –0.5 V.
- 2. Any input pin which can see a value outside the absolute maximum ratings (AV_{DD} or DV_{DD} +0.5 V or AGND -0.5 V) should be protected by diode clamps (HP5082-2835) from input pin to the supplies. All MP7684A inputs have input protection diodes which will protect the device from short transients outside the supply ranges.
- 3. The design of a PC board will affect the accuracy of MP7693. Use of wire wrap is not recommended.
- 4. The analog input signal (V_{IN}) is quite sensitive and should be properly routed and terminated. It should be shielded from the clock and digital outputs so as to minimize cross coupling and noise pickup.
- 5. The analog input should be driven by a low impedance (less than 50 Ω).

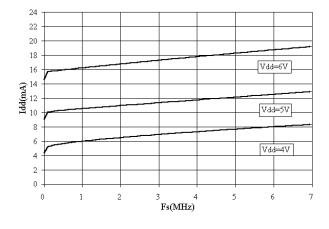
- 6. Analog and digital ground planes should be substantial and common at one point only. The ground plane should act as a shield for parasitics and not a return path for signals. Separate low impedance ground paths will reduce noise levels. *DGND should not be shared with other digital circuitry.* DGND should be connected to AGND next to the MP7693.
- DV_{DD} should not be shared with other digital circuitry to avoid conversion errors caused by digital supply transients. DV_{DD} should be connected to AV_{DD} next to the MP7693.
- 8. DV_{DD} and AV_{DD} are connected inside the MP7693 through the N – doped silicon substrate. Any DC voltage difference between DV_{DD} and AV_{DD} will cause undesirable internal currents.
- 9. Each power supply and reference voltage pin should be decoupled with a ceramic $(0.1\mu F)$ and a tantalum $(10\mu F)$ capacitor as close to the device as possible.
- 10. The digital output should not be driving long wires as the capacitative coupling and reflection will contribute noise to the conversion. When driving distant loads, buffers should be used.



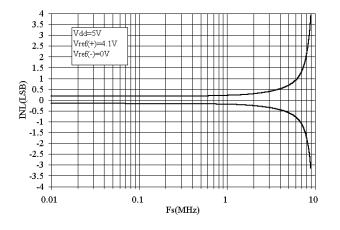




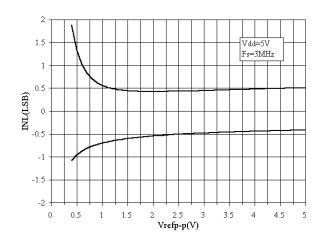
PERFORMANCE CHARACTERISTICS



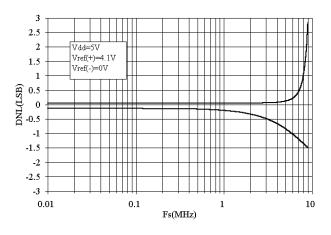
Graph 1. Supply Current vs. Sampling Frequency



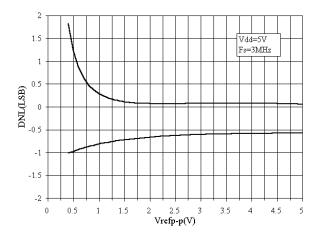
Graph 3. INL vs. Sampling Frequency



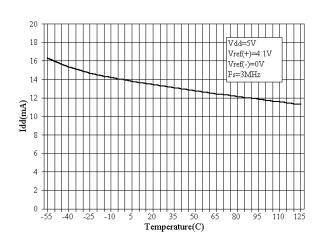




Graph 2. DNL vs. Sampling Frequency

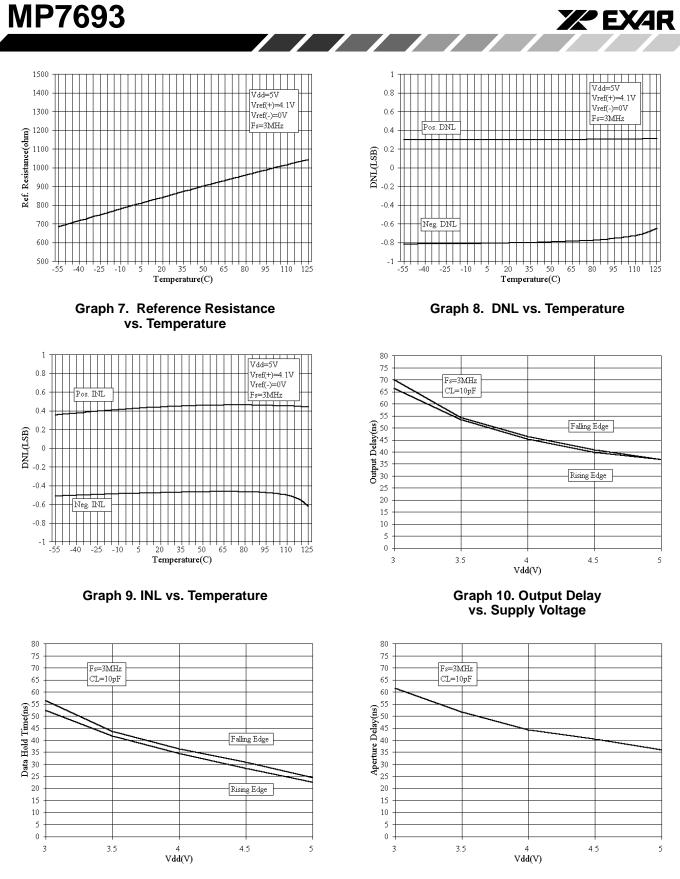


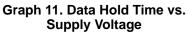
Graph 4. DNL vs. Reference Voltage



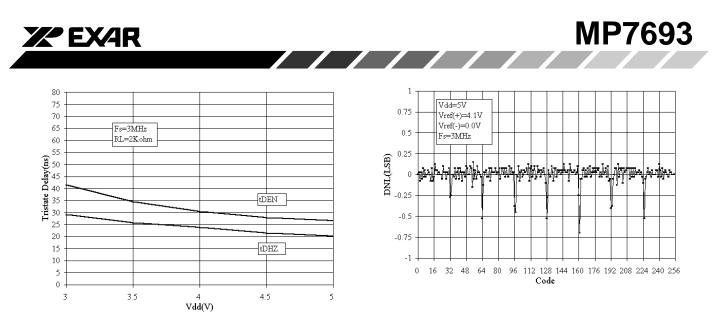
Graph 6. Supply Current vs. Temperature

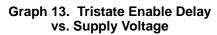




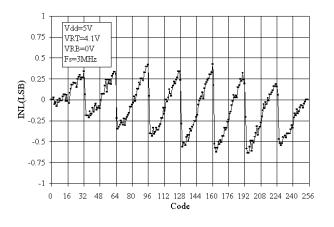


Graph 12. Aperture Delay vs. Supply Voltage





Graph 14. DNL Error Plot







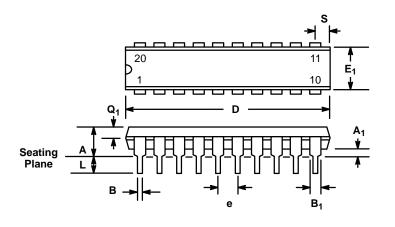


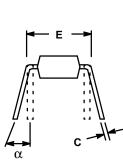
This page left blank











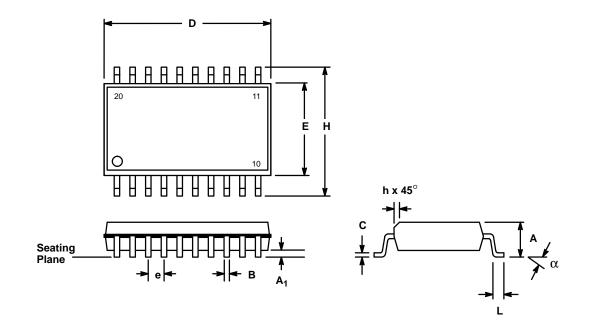
	INC	HES	MILLIN	IETERS	
SYMBOL	MIN	MAX	MIN	МАХ	
А		0.200		5.08	
A ₁	0.015		0.38	-	
В	0.014	0.023	0.356	0.584	
B ₁ (1)	0.038	0.065	0.965	1.65	
С	0.008	0.015	0.203	0.381	
D	0.945	1.060	24.0	26.92	
E	0.295	0.325	7.49	8.26	
E ₁	0.220	0.310	5.59	7.87	
е	0.1	00 BSC	2.54 BSC		
L	0.115	0.150	2.92	3.81	
α	0°	15°	0°	15°	
Q ₁	0.055	0.070	1.40	1.78	
S	0.040	0.080	1.02	2.03	

Note: (1) The minimum limit for dimensions B1 may be 0.023" (0.58 mm) for all four corner leads only.





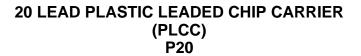


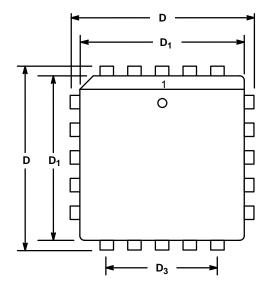


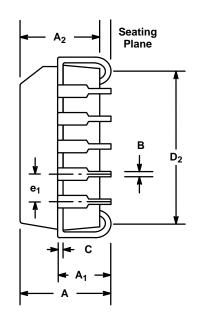
	INC	CHES	MILLIN	METERS
SYMBOL	MIN	МАХ	MIN	MAX
А	0.097	0.104	2.464	2.642
A ₁	0.0050	0.0115	0.127	0.292
В	0.014	0.019	0.356	0.483
С	0.0091	0.0125	0.231	0.318
D	0.500	0.510	12.70	12.95
E	0.292	0.299	7.42	7.59
е	0.0	50 BSC	1.2	7 BSC
н	0.400	0.410	10.16	10.41
h	0.010	0.016	0.254	0.406
L	0.016	0.035	0.406	0.889
α	0°	8°	0°	8°











	INC	CHES	MILLIMETERS	
SYMBOL	MIN	MAX	MIN	MAX
А	0.165	0.180	4.19	4.57
A ₁	0.100	0.110	2.54	2.79
A ₂	0.148	0.156	3.76	3.96
В	0.013	0.021	0.330	0.533
С	0.008	0.012	0.203	0.305
D	0.385	0.395	9.78	10.03
D ₁ (1)	0.350	0.354	8.89	8.99
D ₂	0.290	0.330	7.37	8.38
D ₃	0.2	:00 Ref	5.0	8 Ref.
e ₁	0.0	50 BSC	1.2	7 BSC

Note: (1) Dimension D_1 does not include mold protrusion. Allowed mold protrusion is 0.254 mm/0.010 in.





NOTICE

EXAR Corporation reserves the right to make changes to the products contained in this publication in order to improve design, performance or reliability. EXAR Corporation assumes no responsibility for the use of any circuits described herein, conveys no license under any patent or other right, and makes no representation that the circuits are free of patent infringement. Charts and schedules contains here in are only for illustration purposes and may vary depending upon a user's specific application. While the information in this publication has been carefully checked; no responsibility, however, is assumed for inaccuracies.

EXAR Corporation does not recommend the use of any of its products in life support applications where the failure or malfunction of the product can reasonably be expected to cause failure of the life support system or to significantly affect its safety or effectiveness. Products are not authorized for use in such applications unless EXAR Corporation receives, in writing, assurances to its satisfaction that: (a) the risk of injury or damage has been minimized; (b) the user assumes all such risks; (c) potential liability of EXAR Corporation is adequately protected under the circumstances.

Copyright EXAR Corporation Datasheet April 1995 Reproduction, in part or whole, without the prior written consent of EXAR Corporation is prohibited.

