

## **General Description**

The MAX9400 evaluation kit (EV kit) contains the MAX9400 low-skew quad buffer. The MAX9400 EV kit runs at PECL/ECL and LVPECL/LVECL supplies at clock rates up to 3.0GHz. The EV kit can be operated synchronously with an external clock or asynchronously.

The EV kit is designed with  $50\Omega$  controlled-impedance traces in a four-layer PC board. It can also be used to evaluate the MAX9401-MAX9405.

## **Component List**

DESIGNATION	QTY	DESCRIPTION	
C1, C2	2	10μF ±10%, 10V tantalum capacitors (case B) AVX TAJB106K010R Kemet T494B106010AS	
C3-C11	9	0.1µF ±10%, 16V X7R ceramic chip capacitors (0603) Murata GRM39X7R104K016A or Taiyo Yuden EMK107BJ104KA	
C12-C20	9	0.01µF ±10%, 16V X7R ceramic capacitors (0402) Taiyo Yuden EMK105BJ103KW or Murata GRM36X7R103K016AD	
INO-IN3, INO-IN3, OUTO-OUT3, OUTO- OUT3, CLK, CLK	18	SMA edge-mount connectors Johnson Components 142-0701-801	
JU1–JU4	4	3-pin jumpers	
R1, R2	0	Not installed resistor (0402)	
R3-R8	6	49.9Ω ±1% resistors (0402)	
R9-R36	28	100Ω ±1%, 1/8W resistors (1206)	
U1	1	MAX9400EHJ (32-pin 5mm x 5mm TQFP)	
SEL, <u>SEL</u> , EN, EN	0	Not installed, SMA edge-mount connectors	
None	4	Shunts	
None	1	MAX9400 PC board	
None	1	MAX9400 EV kit data sheet	
None	1	MAX9400 data sheet	

#### Features

- ♦ Controlled 50Ω Coplanar Traces
- ♦ Input Trace Lengths Matched to <2mils</p>
- ♦ Output Trace Lengths Matched to <1mil
- ♦ Frequency Range

Up to 3.0GHz (MAX9400/MAX9402/MAX9403/ MAX9405)

Up to 2.0GHz (MAX9401/MAX9405)

- **♦ PECL/ECL or LVPECL/LVECL Supply**
- ♦ 32-Pin TQFP Package
- Fully Assembled and Tested

## **Ordering Information**

PART	TEMP RANGE	IC PACKAGE
MAX9400EVKIT	0°C to +70°C	32 TQFP

Note: To evaluate the MAX9401-MAX9405, request a MAX9401EHJ/MAX9402EHJ/MAX9403EHJ/MAX9404EHJ/ MAX9405EHJ free sample with the MAX9400EVKIT.

#### Quick Start

The MAX9400 EV kit is fully assembled and tested. Do not turn on the power supplies until all connections are completed.

### **Recommended Equipment**

- One 3GHz (min) differential signal generator (e.g., Agilent 8133A)
- One 12GHz (min) bandwidth oscilloscope with internal  $50\Omega$  input termination (e.g., Tektronix 11801C digital sampling oscilloscope with SD-24 sampling head)
- Two power supplies:
  - a) One 2.0V with 500mA current capability
  - b) One adjustable -3.5V to -0.375V with 500mA current capability
- Matched male-SMA-to-male-SMA  $50\Omega$  coax cables:
  - a) Matched SMA  $50\Omega$  coax cables for inputs IN1 and IN1
  - b) Matched SMA  $50\Omega$  coax cables for outputs OUT1 and OUT1

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## **Component Suppliers**

SUPPLIER	PHONE	FAX	WEBSITE
AVX	843-946-0238	843-626-3123	www.avxcorp.com
Kemet	864-963-6300	864-963-6322	www.kemet.com
Murata	770-436-1300	770-436-3030	www.murata.com
Taiyo Yuden	800-348-2496	847-945-0899	www.t-yuden.com

Note: Please indicate that you are using the MAX9400–MAX9405 when contacting these component suppliers.

### **Asynchronous Operation**

- Verify that shunts are across pins 1 and 2 of jumpers JU1 (SEL) and JU3 (EN) and pins 2 and 3 of jumpers JU2 (SEL) and JU4 (EN).
- Connect two matched coax cables to the oscilloscope. Then connect the other end of the cables to OUT1 and OUT1 on the MAX9400 EV kit board.
- Connect the 2.0V power supply to the VCC pad. Set the supply to 2.00V. Connect the supply ground to the GND pad closest to VCC.
- 4) Connect the -0.375V to -3.5V power supply to the VEE pad. Set the supply to -1.3V. Connect the supply ground to the GND closest to VEE.
- 5) Connect two matched coax cables to the differential signal generator that provides differential square waves with the following setting:
  - a) Frequency = 2GHz
  - b)  $V_{IH} = 1.5V$
  - c)  $V_{IL} = 1.0V$
  - d) Duty cycle = 50%
- 6) Connect the other end of the cables to IN1 and  $\overline{\text{IN1}}$ .
- 7) Turn on the two power supplies, enable the function generator, and verify the differential output signal (VOUT1 VOUT1) is greater than 500mV.

To evaluate other channels, make sure the corresponding output termination resistors on the EV kit board are removed and the unused outputs are terminated.

To eliminate signal distortion, use the matched samelength input cables, and use the matched same-length output cables.

## **Detailed Description**

The MAX9400 EV kit contains an extremely fast, low-skew quad LVECL/LVPECL or ECL/PECL buffer. The EV kit demonstrates ultra-low propagation delay and channel-to-channel skew. The four channels can be operated synchronously with an external clock, or in asynchronous mode, depending on the state of the SEL input.

### **Power Supply**

The MAX9400/MAX9402/MAX9403/MAX9405 are specified with outputs terminated with  $50\Omega$  to  $V_{CC}$  - 2V. In order to terminate the outputs with  $50\Omega$  to  $V_{CC}$  - 2V using the  $50\Omega$  oscilloscope input termination,  $V_{CC}$  is set to 2.0V. The MAX9401/MAX9404 are specified with outputs terminated with  $50\Omega$  to  $V_{CC}$  - 3.3V, and with double swing outputs. In order to terminate the outputs with  $50\Omega$  to  $V_{CC}$  - 3.3V,  $V_{CC}$  is set to 3.3V. Table 1 lists the supply ranges for  $V_{CC}$  and  $V_{EE}$ . In an actual application,  $V_{CC}$  and  $V_{EE}$  can have different supplies (refer to the MAX9400/MAX9402/MAX9403/MAX9405 data sheet or the MAX9401/MAX9404 data sheet).

#### **Enable and Select**

EN, EN, SEL, and SEL can be controlled by either jumpers or external signals. The MAX9400 EV kit can provide internal DC logic signals to EN, EN, SEL, and SEL by using jumpers JU1, JU2, JU3, and JU4. Table 2 lists jumper JU3 and jumper JU4 functions. Table 3 lists jumper JU1 and jumper JU2 functions. The EV kit can also be controlled by external signals using EN, EN, SEL, and SEL connectors. Before connecting external signals to the EN, EN, SEL, SEL connectors, verify there are no shunts across jumpers JU1–JU4.

Table 1. VCC and VEE Range

DEVICE	V <sub>CC</sub> (V)	VEE RANGE (V)
MAX9400	2.0	-3.5 to -0.375
MAX9401	3.3	-2.2 to +0.3
MAX9402	2.0	-3.5 to -0.375
MAX9403	2.0	-3.5 to -0.375
MAX9404	3.3	-2.2 to +0.3
MAX9405	2.0	-3.5 to -0.375

## Table 2. Jumper JU3 and JU4 Functions

JU3 LOCATION	EN PIN	JU4 LOCATION	EN PIN	ОИТРИТ
1 and 2	Connected to VCC	2 and 3	Connected to GND	Enabled
2 and 3	Connected to GND	1 and 2	Connected to VCC	Disabled
All other combinations (not driven externally)				Undefined

## Table 3. Jumpers JU1 and JU2 Functions

JU1 LOCATION	SEL PIN	JU2 LOCATION	SEL PIN	OPERATING MODE
1 and 2	Connected to V <sub>CC</sub>	2 and 3	Connected to GND	Asynchronous mode
2 and 3	Connected to GND	1 and 2	Connected to VCC	Synchronous mode
All other combinations (not driven externally)				Undefined

### **Evaluating the MAX9401-MAX9405**

The MAX9400 EV kit is a four-layer PC board with  $50\Omega$  controlled-impedance input traces with  $50\Omega$  termination (two parallel  $100\Omega$  resistors). All output signal traces are also  $50\Omega$  controlled-impedance traces (with  $49.9\Omega$  termination resistors).

The MAX9400 EV kit can be used to evaluate the MAX9401–MAX9405 after modification. Table 4 lists onchip input and output termination to the corresponding Maxim IC:

- To evaluate the MAX9401, replace the MAX9400EHJ with a MAX9401EHJ.
- To evaluate the MAX9402, replace the MAX9400EHJ with a MAX9402EHJ and remove output termination resistors R1 to R8. The output is half-amplitude compared to an open output because of the voltage-divider formed by the on-chip series 50Ω and the 50Ω oscilloscope input.
- To evaluate the MAX9403/MAX9404, replace the MAX9400EHJ with a MAX9403EHJ/MAX9404EHJ and remove input termination resistors R9 to R36.
- To evaluate the MAX9405, replace the MAX9400EHJ with a MAX9405EHJ and remove input and output termination resistors R1 to R36. The output is half-amplitude compared to an open output because of the voltage-divider formed by the on-chip series 50Ω and the 50Ω oscilloscope input.

Table 4. On-Chip Input and Output Termination

NAME	INPUT TERMINATION RESISTOR	OUTPUT TERMINATION RESISTOR
MAX9400	Open	Open
MAX9401	Open	Open
MAX9402	Open	50Ω
MAX9403	100Ω	Open
MAX9404	100Ω	Open
MAX9405	100Ω	50Ω

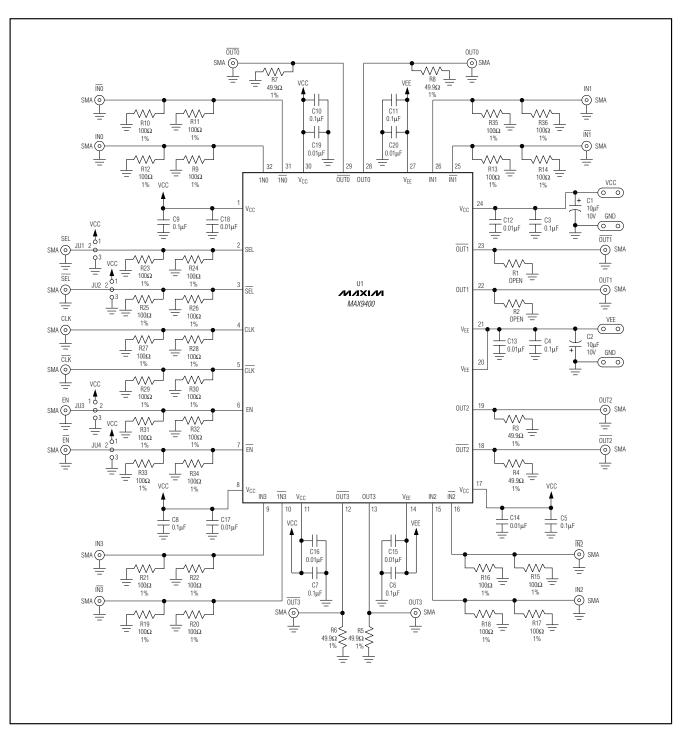


Figure 1. MAX9400 EV Kit Schematic

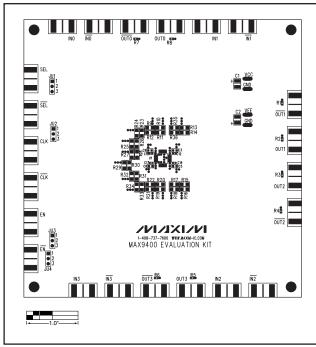


Figure 2. MAX9400 EV Kit Component Placement Guide—Component Side

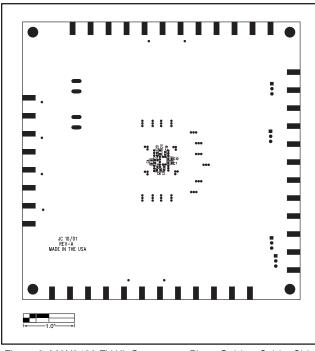


Figure 3. MAX9400 EV Kit Component Place Guide—Solder Side

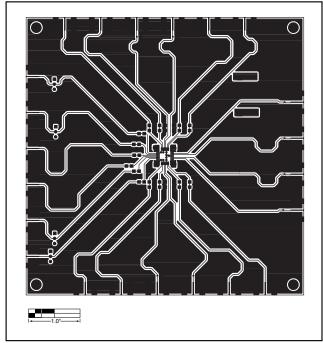


Figure 4. MAX9400 EV Kit PC Board Layout—Component Side

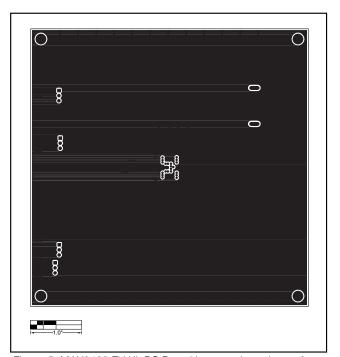


Figure 5. MAX9400 EV Kit PC Board Layout—Inner Layer 2 (GND Layer)

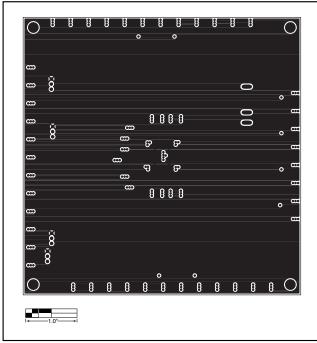


Figure 6. MAX9400 EV Kit PC Board Layout—Inner Layer 3 (VCC Layer)

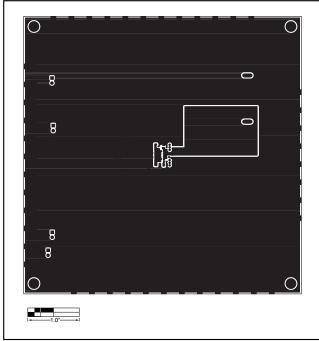


Figure 7. MAX9400 EV Kit PC Board Layout—Solder Side

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