

Four-bit Single-Chip Microcontrollers On-Chip 4 K/6 K/8 K-byte ROM

Overview

The LC66354B, LC66356B and LC66358B are 42-pin package four-bit CMOS microcontrollers that integrate on a single chip all functions required in a control microcontroller, including ROM, RAM, I/O ports, serial interfaces, comparator inputs, three-value inputs, timers and an interrupt system. These products differ from the earlier LC66358A series in their power supply voltage range and operating speed specifications.

Features and Functions

- ROM (with 4 K-, 6 K- and 8 K-byte capacities) and RAM (512 4-bit digits) on chip
- LC66000 series compatible instruction set (128 instructions)
- A total of 36 I/O port pins
- Two eight-bit serial interfaces that can be connected in cascade to form a 16-bit interface
- Instruction cycle time: 0.92 to 10 µs (3 to 5.5 V)
 The earlier LC66358A series had instruction cycle times of from 1.96 to 10 µs (at 3 to 5.5 V) and from 3.92 to 10 µs (at 2.2 to 5.5 V).
- · Powerful timer and prescaler functions

Time limit timer, event counter, pulse width measurement and square wave output using a 12-bit timer.

Time limit timer, event counter, PWM output and square wave output using an 8-bit timer.

Time base function using a 12-bit prescaler.

Powerful interrupt system with eight interrupts and eight vector locations

External interrupts: three interrupts and three vector locations

Internal interrupts: five interrupts and five vector locations

- Flexible I/O functions
- Comparator inputs, three-value inputs, 20 mA drive outputs, 15 V withstand voltage, pull-up or open-drain option switching
- Runaway detection function (watchdog timer) option
- Eight-bit I/O function
- Power reduction functions using halt and hold modes
- Packages: DIP42S, OIP48E (OFP48E)
- Evaluation LSI: used together
 - LC66599 (evaluation chip) + EVA850/800-TB6630X
- LC66E308 (on-chip EPROM microcontroller)

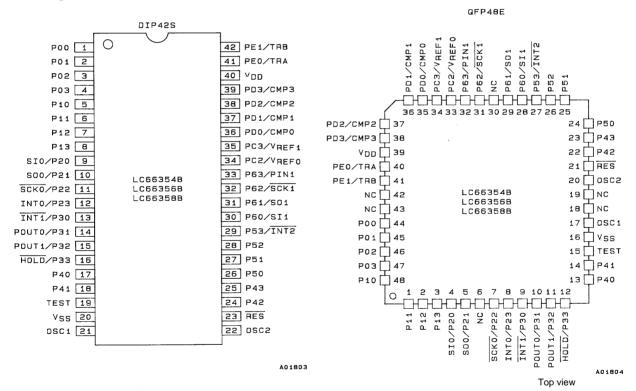
- Any and all SANYO products described or contained herein do not have specifications that can handle applications that require extremely high levels of reliability, such as life-support systems, aircraft's control systems, or other applications whose failure can be reasonably expected to result in serious physical and/or material damage. Consult with your SANYO representative nearest you before using any SANYO products described or contained herein in such applications.
- SANYO assumes no responsibility for equipment failures that result from using products at values that exceed, even momentarily, rated values (such as maximum ratings, operating condition ranges, or other parameters) listed in products specifications of any and all SANYO products described or contained herein.

Series Structure

Product name	Pins	ROM capacity	RAM capacity	Pacl	kage	Features
LC66304A/306A/308A	42, 48	4 K/6 K/8 K bytes	512 W	DIP42S	QFP48E	
LC66404A/406A/408A	42, 48	4 K/6 K/8 K bytes	512 W	DIP42S	QFP48E	Normal version 4.0 to 6.0 V/0.92 µs
LC66506B/508B/512B/516B	64	6 K/8 K/12 K/16 K bytes	512 W	DIP64S	QFP64A	4.0 to 0.0 770.02 μο
LC66354A/356A/358A	42, 48	4 K/6 K/8 K bytes	512 W	DIP42S	QFP48E	
LC66354S/356S/358S*	44	4 K/6 K/8 K bytes	512 W		QFP44M	Low-voltage version 2.2 to 5.5 V/3.92 µs
LC66556A/558A/562A/566A	64	6 K/8 K/12 K/16 K bytes	512 W	DIP64S	QFP64E	Σ.Σ το σ.σ ν/σ.σΣ μσ
LC66354B/356B/358B	42, 48	4 K/6 K/8 K bytes	512 W	DIP42S	QFP48E	Low-voltage, high-speed
LC66556B/558B*	64	6 K/8 K bytes	512 W	DIP64S	QFP64E	version
LC66562B/566B	64	12 K/16 K bytes	512 W	DIP64S	QFP64E	3.0 to 5.5 V/0.92 µs
LC66E308	42, 48	EPROM, 8 K bytes	512 W	DIC42S (window)	QFC48 (window)	
LC66P308	42, 48	OTPROM, 8 K bytes	512 W	DIP42S	QFP48E	
LC66E408	42, 48	EPROM, 8 K bytes	512 W	DIC42S (window)	QFC48 (window)	Evaluation window and OTP
LC66P408	42, 48	OTPROM, 8 K bytes	512 W	DIP42S	QFP48E	versions 4.5 to 5.5 V/0.92 µs
LC66E516	64	EPROM 16 K bytes	512 W	DIC64S (window)	QFC64 (window)	
LC66P516	64	OTPROM 16 K bytes	512 W	DIP64S	QFP64E	

Note: * Under development

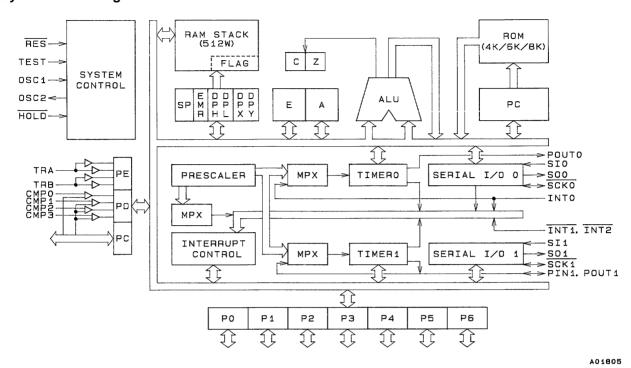
Pin Assignments



We recommend using reflow soldering methods to mount the QFP package version.

Contact your Sanyo sales representative to discuss process conditions if techniques in which the whole package is immersed in a solder bath (solder dip or spray techniques) are used.

System Block Diagram



Differences between the LC66354B, LC66356B and LC66358B and the LC6630X Series

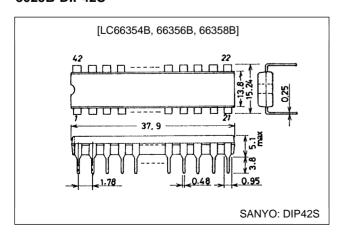
Parameter	LC6630X series (including the LC66599 evaluation chip)	LC6635XB series
System Differences Hardware wait time (number of cycles) when HOLD mode is cleared	65536 cycles At 4 MHz (Tcyc = 1 μs): About 64 ms	16384 cycles At 4 MHz (Tcyc = 1 μs): About 16 ms
Value of timer 0 on reset (including the value after HOLD mode is cleared)	The value FFO is loaded.	The value FFC is loaded.
Main differences in product characteristics • Operating power supply voltage/operating speed (cycle time)	LC66304A, 66306A, 66308A 4.0 to 6.0 V/0.92 to 10 μs LC66E308, 66P308 4.5 to 5.5 V/0.92 to 10 μs	3.0 to 5.5 V/0.92 to 10 μs LC6635XA, 2.2 to 5.5 V/3.92 to 10 μs, 3.0 to 5.5 V/1.96 to 10 μs

- Note: 1. An RC oscillator cannot be used with the LC66354B, LC66356B and LC66358B.
 - In addition, there are differences in the output currents, comparator input voltages and other aspects. For details, refer to the individual catalogs for the LC66308A, LC66E308 and the LC66P308.
 - 3. These points require care when using the LC66E308 or LC66P308 for evaluation purposes.

Package Dimensions

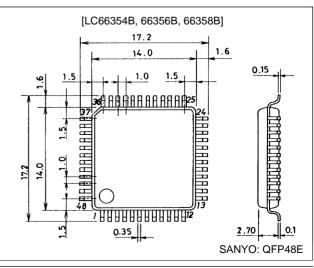
unit: mm

3025B-DIP42S



unit: mm

3156-QFP48E



Pin Function Overview

Pin	I/O	Overview	Output drive type	Option	Value on reset
P00 P01 P02 P03	I/O	I/O ports P00 to P03 • Input or output in 4-bit or 1-bit units • P00 to P03 have control functions in HALT mode.	P-channel: pull-up MOS type N-channel: intermediate sink current type	Either with pull-up MOS or n-channel OD output Reset output level	High or low level (option)
P10 P11 P12 P13	I/O	I/O ports P10 to P13 • Input or output in 4-bit or 1-bit units	P-channel: pull-up MOS type N-channel: intermediate sink current type	Either with pull-up MOS or n-channel OD output Reset output level	High or low level (option)
P20/SI0 P21/SO0 P22/SCK0 P23/INT0	I/O	I/O ports P20 to P23 Input or output in 4-bit or 1-bit units P20 is also used as the serial input S10 pin. P21 is also used as the serial output S00 pin. P22 is also used as the serial clock SCK0 pin. P23 is also used as the INT0 interrupt request, the timer 0 event counter and pulse width measurement input.	P-channel: CMOS type N-channel: intermediate sink current type (+15 V withstand voltage in OD)	Either CMOS or n-channel OD output	Н
P30/ĪNT1 P31/POUT0 P32/POUT1	I/O	I/O ports P30 to P32 Input or output in 3-bit or 1-bit units P30 is also used as the INT1 interrupt request. P31 is also used for square wave output from timer 0. P32 is also used for square wave output from timer 1 and PWM output.	P-channel: CMOS type N-channel: intermediate sink current type (+15 V withstand voltage in OD)	Either CMOS or n-channel OD output	Н
P33/HOLD	ı	Hold mode control input Hold mode is entered if a HOLD instruction is executed when HOLD is low. When in hold mode, the CPU is reactivated by setting HOLD to the high level. P33 can also be used as an input port along with P30 to P32. When P33/HOLD is low, the CPU will not be reset by a low level on RES. Therefore, RES cannot be used in applications that set P33/HOLD low when power is first applied.			
P40 P41 P42 P43	I/O	 I/O ports P40 to P43 Input or output in 3-bit or 1-bit units I/O in 8-bit units when used in conjunction with P50 to P53 Output of 8-bit ROM data when used in conjunction with P50 to P53 	P-channel: pull-up MOS type N-channel: intermediate sink current type (+15 V withstand voltage in OD)	Either with pull-up MOS or n-channel OD output	Н

Continued from preceding page.

Pin	I/O	Overview	Output drive type	Option	Value on reset
P50 P51 P52 P53/INT2	I/O	 I/O ports P50 to P53 Input or output in 4-bit or 1-bit units I/O in 8-bit units when used in conjunction with P40 to P43 Output of 8-bit ROM data when used in conjunction with P40 to P43 P53 is also used for the INT2 interrupt request. 	P-channel: pull-up MOS type N-channel: intermediate sink current type (+15 V withstand voltage in OD)	Either with pull-up MOS or n-channel OD output	н
P60/SI1 P61/SO1 P62/SCK1 P63/PIN1	I/O	I/O ports P60 to P63 Input or output in 4-bit or 1-bit units P60 is also used as the serial input S11 pin. P61 is also used as the serial output SO1 pin. P62 is also used as the serial clock SCK1 pin. P63 is also used as the timer 1 event counter input.	P-channel: CMOS type N-channel: intermediate sink current type (+15 V withstand voltage in OD)	Either CMOS or n-channel OD output	Н
PC2/VREF0 PC3/VREF1	I/O	I/O ports PC2 and PC3 Output in 4-bit or 1-bit units PC2 is also used as the VREF0 comparator comparison voltage pin. PC3 is also used as the VREF1 comparator comparison voltage pin.	P-channel: CMOS type N-channel: intermediate sink current type	Either CMOS or n-channel OD output	н
PD0/CMP0 PD1/CMP1 PD2/CMP2 PD3/CMP3	I	Dedicated input ports PD0 to PD3 Can be switched to use as comparator inputs under program control. The PD0 comparison voltage is VREF0. The PD1 to PD3 comparison voltage is VREF1. Comparisons can be specified in units of PD0, PD2, and PD2 and PD3 together.			Normal input
PE0/TRA PE1/TRB	I	Dedicated input ports Can be switched to function as three-value inputs under program control.			Normal input
OSC1 OSC2	0	System clock oscillator external connection When an external clock is used, leave OSC2 open and input the clock signal to OSC1.		Selection of either ceramic oscillator or external clock input.	
RES	I	System reset input The CPU is initialized if a low level is input to RES when the P33/HOLD pin is high.			
TEST	ı	CPU test pin This pin must be connected to V _{SS} during normal operation.			
V _{DD} V _{SS}		Power supply connections			

Note: Pull-up MOS output:......A pull-up MOS transistor is connected to the output circuit.

CMOS output:Complementary output

OD output:......Open drain output

User Option Types

1. Port 0 and 1 reset time output level option

The output levels of ports 0 and 1 can be selected from the following two options in 4-bit units.

Option	Conditions and notes					
High level output at reset time	Ports 0 and/or 1 in 4-bit sets					
Low level output at reset time	Ports 0 and/or 1 in 4-bit sets					

2. Oscillator circuit option

Option	Circuit	Conditions and notes
External clock	OSC1 Z	This input is a Schmitt specification input.
Ceramic oscillator	C1 OSC1 Ceramic resonator OSC2 OSC2 A01807	

Note: There is no RC oscillator option.

3. Watchdog timer option

The presence or absence of a watchdog timer can be selected as an option.

4. Port output type option

• One of the following two output circuit options can be selected for each bit in ports P0, P1, P2, P3 (except for the P33/HOLD pin), P4, P5. P6 and PC.

Option	Circuit	Conditions and notes
Open drain output	Output data Input data DSB A01808	P2, P3, P5 and P6 are Schmitt inputs.
Built-in pull-up resistor output	Output data Input data A01809	P2, P3, P5 and P6 are Schmitt inputs. CMOS outputs (P2, P3, P6 and PC) and pull-up MOS outputs (P0, P1, P4 and P5) are differentiated according to the drive capacity of the p-channel transistor.

• The PD comparator inputs and the PE three-value inputs are selected in software.

Specifications

Absolute Maximum Ratings at $Ta = 25^{\circ}C$, $V_{SS} = 0$ V

Parameter	Symbol	Applicable pins, notes	Conditions	Ratings	Unit	Note
Maximum supply voltage	V _{DD} max	V _{DD}		-0.3 to +7.0	V	
Input voltage	V _{IN} (1)	P2, P3 (except for the P33/HOLD pin), P4, P5, P6		-0.3 to +15.0	V	1
Input voltage	V _{IN} (2)	Other inputs		-0.3 to $V_{DD} + 0.3$	V	2
Output voltage	V _{OUT} (1)	P2, P3 (except for the P33/HOLD pin), P4, P5, P6		-0.3 to +15.0	V	1
Output voltage	V _{OUT} (2)	Other outputs		-0.3 to $V_{DD} + 0.3$	V	2
Output current per pin	I _{ON}	P0, P1, P2, P3 (except for the P33/ HOLD pin), P4, P5, P6, PC		20	mA	3
	-I _{OP} (1)	P0, P1, P4, P5		2	mA	4
	-I _{OP} (2)	P2, P3 (except for the P33/HOLD pin), P6, PC		4	mA	4
	Σl _{ON} (1)	P0, P1, P2, P3, (except for the P33/HOLD pin), P40, P41		75	mA	3
Total pip ourrant	ΣI _{ON} (2)	P5, P6, P42, P43, PC		75	mA	3
Total pin current	Σl _{OP} (1)	P0, P1, P2, P3 (except for the P33/HOLD pin), P40, P41		25	mA	4
	Σl _{OP} (2)	P5, P6, P42, P43, PC		25	mA	4
Allowable power dissination	Pd max	Ta = -30 to +70°C	DIP42S	600	mW	
Allowable power dissipation	ru max	1a = -30 to +70 C	QFP48E	430	mW	5
Operating temperature	Topr			-30 to +70	°C	
Storage temperature	Tstg			-55 to +125	°C	

- Note: 1. Applies to open drain output specification pins. The rating from the "other pin" entry applies for specifications other than the open drain output specification.
 - 2. Levels up to the free-running oscillation level are allowed for the oscillator input and output pins.
 - 3. Inflow current
 - 4. Outflow current (Applies to the pull-up output specification and CMOS output specification pins.)
 - 5. We recommend using reflow soldering methods to mount the QFP package version.

 Contact your Sanyo sales representative to discuss process conditions if techniques in which the whole package is immersed in a solder bath (solder dip or spray techniques) are used.

Allowable Operating Ranges at $Ta = -30 \text{ to} + 70^{\circ}\text{C}$, $V_{SS} = 0 \text{ V}$, $V_{DD} = 3.0 \text{ to} 5.5 \text{ V}$ unless otherwise specified

Danasatas	Oh!	A li l i	Conditions		Unit	Nata		
Parameter	Symbol	Applicable pins	Conditions	min	typ	max	Unit	Note
Operating supply voltage	V _{DD}	V _{DD}	0.92 ≤ Tcyc ≤ 10 µs	3.0		5.5	V	
Memory hold supply voltage	V _{DD} (H)	V _{DD}	In HOLD mode	1.8		5.5	V	
	V _{IH} (1)	P2, P3 (except for the P33/HOLD pin), P4, P5, P6	With the output n-channel transistor off	0.8 V _{DD}		13.5	V	1
Input high level Voltage	V (2)		With the output n-channel transistor off	0.8 V _{DD}		V _{DD}	V	2
	V _{IH} (3)	P0, P1, PC, PD, PE	With the output n-channel transistor off	0.75 V _{DD}		V _{DD}	V	3
	V _{IH} (4)	PE	Using three-value input	0.8 V _{DD}		V _{DD}	V	
Middle level input voltage	V _{IM}	PE	Using three-value input	0.4 V _{DD}		0.6 V _{DD}	V	
Common mode input	V _{CMM} (1)	PD0, PC2	Using comparator input	1.5		V _{DD}	V	
voltage range	V _{CMM} (2)	PD1, PD2, PD3, PC3	Osing comparator input	V _{SS}		V _{DD} – 1.5	V	
	V _{IL} (1)	P2, P3 (except for the P33/HOLD pin), P5, P6, RES, OSC1	With the output n-channel transistor off			0.2 V _{DD}	V	1
Input low level voltage	V _{IL} (2)	P33/HOLD	V _{DD} = 1.8 to 5.5 V			0.2 V _{DD}	V	
	V _{IL} (3)	P0, P1, P4, PC, PD, PE, TEST	With the output n-channel transistor off	V _{SS}		0.25 V _{DD}	V	3
	V _{IL} (4)	PE	Using comparator input	V _{SS}		0.2 V _{DD}	V	
Operating frequency (instruction cycle time)	f _{OP} (T _{CYC})			0.4 (10)		4.35 (0.92)	MHz (µs)	

Note: 1. Applies to open drain specification pins. However, the rating for V_{IH} (2) applies to the P33/HOLD pin. Ports P2, P3 and P6 cannot be used as input pins when CMOS output specifications are used.

- 2. Applies to open drain specification pins.
- 3. When PE is used as a three-value input, V_{IH} (4), V_{IM} and V_{IL} (4) apply. Port P3 cannot be used as input pins when CMOS output specifications are used.

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Para	meter	Symbol	Applicable pins	Conditions	Ratings			Unit	Note
i diameter		Symbol	принавно рина	Conditions	min	typ	max	Offic	Note
External clock input conditions	Frequency f _{ext}			See Figure 1. With the signal input to OSC1 and with OSC2 open (with external clock input selected for the oscillator circuit option)	0.4		4.35	MHz	
	Pulse width	t _{ext} H t _{ext} L	OSC1	See Figure 1. With the signal input to OSC1 and with OSC2 open (with external clock input selected for the oscillator circuit option)	100			ns	
	Rise/fall times	t _{ext} R t _{ext} F		See Figure 1. With the signal input to OSC1 and with OSC2 open (with external clock input selected for the oscillator circuit option)			30	ns	

Electrical Characteristics at Ta = -30 to $+~70^{\circ}C$, $V_{SS} = 0~V$, $V_{DD} = 3.5$ to 5.5~V unless otherwise specified

Dove		Cumbal	Applicable pine	Canditions		Ratings		Linia	Note
Para	ımeter	Symbol	Applicable pins	Conditions	min	typ	max	Unit	Note
		I _{IH} (1)	P2, P3 (except for the P33/HOLD pin), P4, P5, P6	V _{IN} = 13.5, With the output n-channel transistor off			5.0	μА	1
Input high level current		I _{IH} (2)	P0, P1, PC, OSC1, RES, P33/HOLD	$V_{IN} = V_{DD}$, With the output n-channel transistor off			1.0	μA	1
		I _{IH} (3)	PD, PE, PC2, PC3	V _{IN} = V _{DD} , With the output n-channel transistor off			1.0	μA	1
Input low level current		I _{IL} (1)	Inputs other than PD, PE, PC2 and PC3	V _{IN} = V _{SS} , With the output n-channel transistor off	-1.0			μА	2
		I _{IL} (2)	PC2, PC3, PD, PE	V _{IN} = V _{SS} , With the output n-channel transistor off	-1.0			μA	2
Output high level voltage		P2, P3 (except for		I _{OH} = -1 mA	V _{DD} – 1.0			.,	
		V _{OH} (1)	the P33/HOLD pin) P6, PC	I _{OH} = -0.1 mA	V _{DD} – 0.5			· V	3
Output high lev	Output high level voltage		Do D. D. D.	I _{OH} = -50 μA	V _{DD} – 1.0			.	١.
		V _{OH} (2)	P0, P1, P4, P5	I _{OH} = -30 μA	V _{DD} – 0.5			V	4
Output pull-up	current	I _{PO}	P0, P1, P4, P5	$V_{IN} = V_{SS}, V_{DD} = 5.5 \text{ V}$	-1.6			mA	4
Output law lava	Lucitore	V _{OL} (1)	P0, P1, P2, P3, P4, P5, P6, PC (except for the P33/HOLD pin)	I _{OL} = 1.6 mA			0.4	V	5
Output low leve	er voltage	V _{OL} (2)	P0, P1, P2, P3, P4, P5, P6, PC (except for the P33/HOLD pin)	I _{OL} = 8 mA			1.5	V	
Output off looks		I _{OFF} (1)	P2, P3, P4, P5, P6	V _{IN} = 13.5 V			5.0	μA	5
Output off leaka	age current	I _{OFF} (2)	P0, P1, PC	$V_{IN} = V_{DD}$			1.0	μΑ	5
Comparator off	not voltage	V _{OFF} (1)	PD1, PD2, PD3	$V_{IN} = V_{SS}$ to $V_{DD} - 1.5$ V		±50	±300	mV	
Comparator off	ser voltage	V _{OFF} (2)	PD0	V_{IN} = 1.5 to V_{DD}		±50	±300	mV	
	Hysteresis voltage	V _{HIS}				0.1 V _{DD}		V	
Schmitt characteristics	High level thresHOLD voltage	VtH	P2, P3, P5, P6, OSC1 (EXT), RES		0.5 V _{DD}		0.8 V _{DD}	V	
	Low level thresHOLD voltage	evel HOLD VtL			0.2 V _{DD}		0.5 V _{DD}	V	

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Dor	ameter		Symbol	Applicable	o nino	Conditions		Ratings		Unit	Note
Faic	anietei		Symbol	Applicable	e piris	Conditions	min	typ	max	Offic	Note
Ceramic	Oscillat frequer		f _{CF}	OSC1, OSC2		Figure 2, 4 MHz		4.0		MHz	
oscillator	Oscillat stabiliza time		f _{CFS}			Figure 3, 4 MHz			10	ms	
	Cycle	Input	t _{CKCY}				0.9			μs	
	time	Output	CRCT	_			2.0			Tcyc	-
	Low level/ high	Input	t _{CKL}			The timing from Figure 4	0.4			μs	
Serial clock	level pulse widths	Output	t _{CKH}	SCKO, SCK1		and the test load from Figure 5	1.0			Тсус	
	Rise/ fall times	Output	^t CKR ^t CKF						0.1	μs	
Contabliance	Data se	tup time	t _{ICK}	010 014		Stipulated with respect to the rising edge timing for				μs	
Serial input	Data hold time		t _{CKI}	SI0, SI1		SCK0 and SCK1 from Figure 4	0.3			μs	
Serial output	Output time	delay	^t cko	SO0, SO1		Stipulated with respect to the rising edge timing for SCK0 and SCK1 from Figure 4 and the test load shown in Figure 5			0.3	μs	
	INT0 high/low level pulse widths		^t IOH ^t IOL	INTO		Conditions such that the INTO interrupt is accepted Conditions such that timer 0 event counter and pulse width measurement inputs are accepted.	2			Тсус	
Pulse conditions	interrup	w level vidths for ot inputs nan INT0	t _{IIH} t _{IIL}	INT1, INT2	Figure 6	Conditions such that all interrupts are accepted	2			Тсус	
	PIN1 hi level pu widths		t _{PINH} t _{PINL}	PIN1		Conditions such that timer 1 event counter inputs are accepted.	2			Тсус	
	RES his	gh/low ılse	t _{RSH} t _{RSL}	RES		Conditions such that reset occurs	3			Тсус	
Comparator res	sponse s	peed	T _{RS}	PD	Figure 7				20	ms	
0		-li-				Using a 4 MHz ceramic oscillator		3.0	5.0	mA	
Operating mode current drain		I _{DD OP}	D OP V _{DD}		Using a 4 MHz external clock		3.0	5.0	mA	8	
UAI T mada	rront de-			V		Using a 4 MHz ceramic oscillator		1.0	2.0	mA	
HALT mode cu	neni arai	"	I _{DDHALT}	V _{DD}		Using a 4 MHz external clock		1.0	2.0	mA	
Hold-mode cur	rent drair	1	I _{DDHOLD}	V _{DD}		V _{DD} = 1.8 to 5.5 V		0.01	10	μA	

Note: 1. Common input and output ports with open-drain output specifications are specified for the state with the output n-channel transistor turned off. These pins cannot be used for input when the CMOS output specification option is selected.

- 4. Stipulated for pull-up output specifications with the output n-channel transistor in the off state.
- 5. Stipulated for open-drain output specifications with the output n-channel transistor in the off state.
- 6. In the reset state

^{2.} Common input and output ports with open-drain output specifications are specified for the state with the output n-channel transistor turned off. Ratings for pull-up output specification pins are stipulated for the output pull-up current IPO. These pins cannot be used for input when the CMOS output specification option is selected.

3. Stipulated for CMOS output specifications with the output n-channel transistor in the off state.

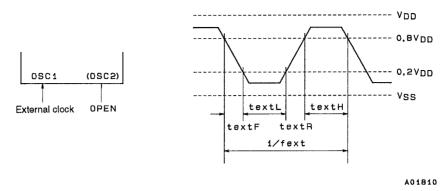


Figure 1 External Clock Input Waveform

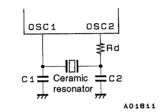


Figure 2 Ceramic Oscillator Circuit

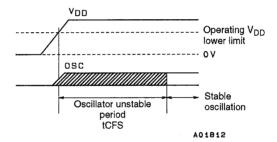


Figure 3 Oscillator Stabilization Time

Table 1 Ceramic Oscillator Guaranteed Constants

		C1 = 33 pF ± 10%		C1 = 47 pF ± 10%
	2 MHz (Murata) CSA2.00MG	C2 = 33 pF ± 10%	2 MHz (Kyocera) KBR2.0MS	C2 = 47 pF ± 10%
External		$Rd = 0 \Omega$		$Rd = 0 \Omega$
capacitance type		C1 = 33 pF ± 10%		C1 = 33 pF ± 10%
	4 MHz (Murata) CSA4.00MG	C2 = 33 pF ± 10%	4 MHz (Kyocera) KBR4.0MS	C2 = 33 pF ± 10%
		$Rd = 0 \Omega$		$Rd = 0\Omega$

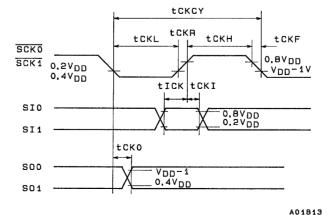


Figure 4 Serial I/O Timing

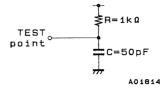


Figure 5 Timing Load

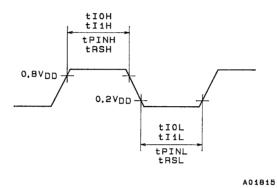


Figure 6 Input Timing for INT0, INT1, INT2, PIN1 and RES

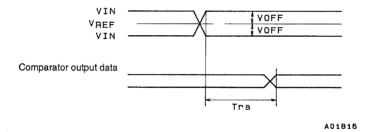
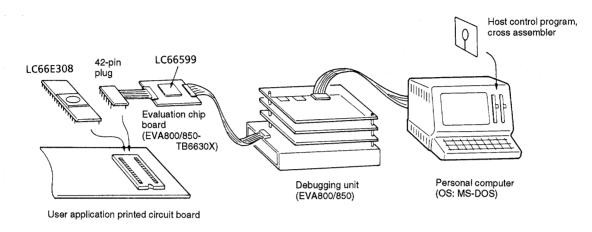


Figure 7 Comparator Response Speed Trs Timing

Application Development Tools

Programs for the LC66354B, LC66356B and LC66358B microcontrollers are developed on an IBM-PC compatible personal computer running the MS-DOS operating system. A cross assembler and other tools are available. To make application development more convenient, Sanyo also provides a program debugging unit (EVA800/850), an evaluation board (EVA800/850-TB6630X), an evaluation chip (LC66599) and an on-chip EPROM microprocessor (LC66E308).



Structure of the Application Development Tools

1. Program debugging unit (EVA800/850)

This is an emulator that provides functions for EPROM writing and serial data communications with external equipment (such as a host computer). It supports application development in machine language and program modification. Its main debugging functions include breaking, stepping and tracing. (The MPM6630X is used for the EVA800/850 monitor ROM.)

2. Evaluation chip board (EVA800/850-TB6630X)

The evaluation chip signals and ports are output to the 42-pin connector and when the output cable is connected, the evaluation chip board converts these signals to the same pin assignments as those on the mass production chip. The evaluation chip board includes jumpers for setting options and other states, and these jumper settings allow the evaluation chip to implement the same I/O circuit types and functions as the mass production chip. However, there are differences in the HOLD mode clear timing and the electrical characteristics.

Jumper

Туре		OSC		Reset method	Power s	supply to the user application board
Jumper		Jumper 1 (J1)		Jumper 2 (J2: RES)		Jumper 3 (J3: V _{DD})
	EXT	External oscillator (external clock)	INT (a)	Reset by a RUN instruction from the host computer.	ON (a)	V _{DD} is supplied to the user application printed circuit board
Jumper setting	RC	RC oscillator		the nost computer.		through the evaluation chip board.
and mode	CF	CF oscillator	EXT (b)	Reset by the reset circuit on the user application printed circuit board.	OFF (b)	Separate power supplies on the user application printed circuit board and the evaluation chip board.

Switches (SW9, SW10 and SW11)

Туре		Port 0 and 1 outp	ut levels	on reset	Watchd	og timer presence or absence setting
Switch		SW11: P0HL		SW10: P1HL		SW9: WDC
Switch setting	ON	Port 0 high	ON	Port 1 highPort 1 low	ON	Watchdog timer present
and mode	OFF	Port 0 low	OFF		OFF	Watchdog timer absent

Switches SW1 to SW8: Pull-up resistor option settings

- Set the corresponding switch to the on position for built-in pull-up resistors, and set the switch to the off position for open drain output.
- These settings can be specified for individual pins.

3. Cross Assembler

Cross assembler (file name)	Object microprocessors	Limitat	tions on program creation
LC66S. EXE	LC66354B, 66356B, 66358B (LC66E308, 66P308) (LC66599)	SB instruction limitation • LC66354B • LC66356B, 66358B (LC66E308, 66P308)	: Only SB0 can be used. : Only SB0 and SB1 can be used.
	(200000)	• LC66599	: SB0, SB1, SB2 and SB3 can be used.

4. Simulation chip (See the LC66E308 individual product catalog for more details.)

The LC66E308 simulation chip is an on-chip EPROM microprocessor. Mounted configuration operation can be confirmed in the application product by using a dedicated conversion board (the W66EP308D/408D for DIP products and the W66EP308Q/408Q for QFP products) and writing programs with a commercial PROM writer.

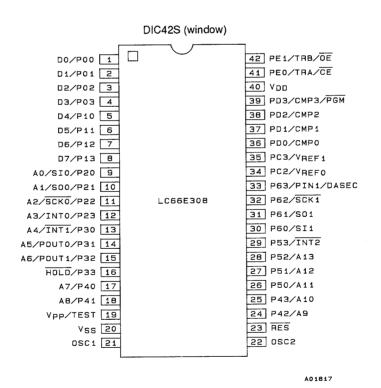
• Form

The LC66E308 has a pin arrangement and functions identical to those of the LC66354B, LC66356B and LC66358B. However, there are differences in the HOLD mode clear timing and the electrical characteristics. The figure below shows the pin assignment.

• Options

The options (the port 0 and 1 level at reset, the watchdog timer and the port output circuit types) for the microprocessor to be evaluated can be specified by EPROM data. (The next item describes the option data area and definitions.) This allows evaluation with the same peripheral circuits as those that will be used in the mass production product.

Pin Assignment



Option Data Area and Definitions

ROM area	Bit		Option item	Relation between option and data
	7			
	6	Unused		Must be set to zeros.
	5			
200011	4	Oscillato	r option	1 = ceramic oscillator 0 = external clock
2000H	3	Unused		Must be set to zero.
	2	P1		1 = high level
	1	P0	Level of reset	0 = low level
	0	Watchdo	g timer option	1 = present, 0 = absent
	7	P13		
	6	P12		
	5	P11		
	4	P10	1	
2001H	3	P03	Output circuit type	1 = PU, 0 = OD
	2	P02		
	1	P01		
	0	P00		
	7	Unused	1	Must be set to zero.
	6	P32		
	5	P31		
	4	P30	Output circuit type	1 = PU, 0 = OD
2002H	3	P23		
	2	P22		
	1	P21		
	0	P20		
	7	P53		
	6	P52		
	5	P51		
	4	P50	1	
2003H	3	P43	Output circuit type	1 = PU, 0 = OD
	2	P42		
	1	P41		
	0	P40		
	7 to 4	Unused		
	3	P63		
2004H	2	P62	1	. 50.0
	1	P61	Output circuit type	1 = PU, 0 = OD
	0	P60		
2005H	7 to 0	Unused		Must be set to zero.
2006H	7 to 0	Unused		Must be set to zero.
	7 to 4	Unused		Must be set to zero.
	3	PC3		
2007H	2	PC2	Output circuit type	1 = PU, 0 = OD
	1		1	Must be set to zero
	0	Unused		Must be set to zero.

LC663XX Series Instruction Table (by function)

Abbreviations:

AC: Accumulator
E: E register
CF: Carry flag
ZF: Zero flag

HL: Data pointer DPH, DPL XY: Data pointer DPX, DPY

M: Data memory

M (HL): Data memory pointed to by the DPH, DPL data pointer M (XY): Data memory pointed to by the DPX, DPY data pointer

M2 (HL): Two words of data memory (starting on an even address) pointed to by the DPH, DPL data pointer

SP: Stack pointer

M2 (SP): Two words of data memory pointed to by the stack pointer M4 (SP): Four words of data memory pointed to by the stack pointer

in: n bits of immediate data

t2: Bit specification

t2	11	10	01	00
Bit	2 ³	22	21	20

PCh: Bits 8 to 11 in the PC
PCm: Bits 4 to 7 in the PC
PCl: Bits 0 to 3 in the PC
Fn: User flag, n = 0 to 15

TIMER0: Timer 0
TIMER1: Timer 1
SIO: Serial register

P: Port

P (i4): Port indicated by 4 bits of immediate data

INT: Interrupt enable flag

(), []: Indicates the contents of a location

←: Transfer direction, result

∀: Exclusive or
∀: Logical and
∧: Logical or
+: Addition
-: Subtraction

—: Taking the one's complement

Instructions

Instruction group	,	Mnemonic			Instr	ucti	on co	de			Number of bytes	Number of cycles	Operation	Description	Affected	Note
Instruc group	'	viriemonic	D ₇	D_6	D ₅	D ₄	D_3	D ₂	D ₁	D_0	Num bytes	Num cycle	Operation	Description	status bits	Note
	CLA	Clear AC	1	0	0	0	0	0	0	0	1	1	AC ← 0 (Equivalent to LAI0.)	Clear AC.	ZF	1
	DAA	Decimal adjust AC in addition	1 0	1 0		0	1 0	1 1	1 1	1 0	2	2	AC ← (AC) + 6 (Equivalent to ADI6.)	Add six to AC.	ZF	
Su	DAS	Decimal adjust AC in subtraction	1 0	1		0 0	1 1	1	1	1	2	2	AC ← (AC) + 10 (Equivalent to ADIOAH.)	Add 10 to AC.	ZF	
ctio	CLC	Clear CF	0	0	0	1	1	1	1	0	1	1	CF ← 0	Clear CF to 0.	CF	
ıstru	STC	Set CF	0	0	0	1	1	1	1	1	1	1	CF ← 1	Set CF to 1.	CF	
ation ir	СМА	Complement AC	0	0	0	1	1	0	0	0	1	1	$AC \leftarrow (\overline{AC})$	Take the one's complement of AC.	ZF	
Indic	IA	Increment AC	0	0	0	1	0	1	0	0	1	1	AC ← (AC) + 1	Increment AC.	ZF, CF	
mar	DA	Decrement AC	0	0	1	0	0	1	0	0	1	1	AC ← (AC) – 1	Decrement AC.	ZF, CF	
Accumulator manipulation instructions	RAR	Rotate AC right through CF	0	0	0	1	0	0	0	0	1	1	$\begin{array}{l} AC_3 \leftarrow (CF), \\ ACn \leftarrow (ACn + 1), \\ CF \leftarrow (AC_0) \end{array}$	Shift AC (including CF) right.	CF	
Acc	RAL	Rotate AC left through CF	0	0	0	0	0	0	0	1	1	1	$\begin{aligned} &AC_0 \leftarrow (CF), \\ &ACn + 1 \leftarrow (ACn), \\ &CF \leftarrow (AC_3) \end{aligned}$	Shift AC (including CF) left.	CF, ZF	
	TAE	Transfer AC to E	0	1	0	0	0	1	0	1	1	1	E ← (AC)	Move the contents of AC to E.		
	TEA	Transfer E to AC	0	1	0	0	0	1	1	0	1	1	AC ← (E)	Move the contents of E to AC.	ZF	
	XAE	Exchange AC with E	0	1	0	0	0	1	0	0	1	1	$(AC) \leftrightarrow (E)$	Exchange the contents of AC and E.		
ion	IM	Increment M	0	0	0	1	0	0	1	0	1	1	M (HL) ← [M (HL)] + 1	Increment M (HL).	ZF, CF	
nstruct	DM	Decrement M	0	0	1	0	0	0	1	0	1	1	M (HL) ← [M (HL)] – 1	Decrement M (HL).	ZF, CF	
lation i	IMDR i8	Increment M direct	1 I ₇	1 I ₆		0 I ₄	0 I ₃	1 I ₂	1 I ₁	1 I ₀	2	2	M (i8) ← [M (i8)] + 1	Increment M (i8).	ZF, CF	
nanipu	DMDR i8	Decrement M direct	1 I ₇	1 I ₆		0 I ₄	0	0	1 I ₁	1 I ₀	2	2	M (i8) ← [M (i8)] – 1	Decrement M (i8).	ZF, CF	
Memory manipulation instruction	SMB t2	Set M data bit	0	0	0	0	1	1	t ₁	t ₀	1	1	[M (HL), t2] ← 1	Set the bit in M (HL) specified by t0 and t1 to 1.		
M	RMB t2	Reset M data bit	0	0	1	0	1	1	t ₁	t ₀	1	1	[M (HL), t2] ← 0	Clear the bit in M (HL) specified by t0 and t1 to 0.	ZF	
	AD	Add M to AC	0	0	0	0	0	1	1	0	1	1	$AC \leftarrow (AC) + [M\ (HL)]$	Add the contents of AC and M (HL) as two's complement values and store the result in AC.	ZF, CF	
instructions	ADDR i8	Add M direct to AC	1 I ₇	1 I ₆	0 I ₅	0 I ₄	1 I ₃	0 I ₂	0 I ₁	1 I ₀	2	2	AC ← (AC) + [M (i8)]	Add the contents of AC and M (i8) as two's complement values and store the result in AC.	ZF, CF	
comparison	ADC	Add M to AC with CF	0	0	0	0	0	0	1	0	1	1	AC ← (AC) + [M (HL)] + (CF)	Add the contents of AC, M (HL) and C as two's complement values and store the result in AC.	ZF, CF	
Arithmetic, logic and comparison instructions	ADI i4	Add immediate data to AC	1 0	1	0		1 I ₃	1 I ₂	1 I ₁	1 I ₀	2	2	$AC \leftarrow (AC) + I_3, I_2, I_1, I_0$	Add the contents of AC and the immediate data as two's complement values and store the result in AC.	ZF	
Arithme	SUBC	Subtract AC from M with CF	0	0	0	1	0	1	1	1	1	1	$\begin{array}{c} AC \leftarrow [M \ (HL)] - (AC) \\ - \ (\overline{CF}) \end{array}$	Subtract the contents of AC and \overline{CF} from M (HL) as two's complement values and store the result in AC.	ZF, CF	2
	ANDA	And M with AC then store AC	0	0	0	0	0	1	1	1	1	1	$\begin{array}{c} AC \leftarrow (AC) \ \ \forall \\ [M \ (HL)] \end{array}$	Take the logical and of AC and M (HL) and store the result in AC.	ZF	

Note: 1. Has a vertical skip function.

2. CF will be zero if there was a borrow and one otherwise.

Continued from preceding page.

Instruction group					Inst	ructi	on c	ode			Number of bytes	Number of cycles		2	Affected	
Instruc group	ſ	Mnemonic	D ₇	D ₆	D ₅	D ₄	D ₃	D ₂	D ₁	D ₀	Numb bytes	Numb	Operation	Description	status bits	Note
	ORA	Or M with AC then store AC	0	0	0	0	0	1	0	1	1	1	AC ← (AC) ∨ [M (HL)]	Take the logical or of AC and M (HL) and store the result in AC.	ZF	
	EXL	Exclusive or M with AC then store AC	0	0	0	1	0	1	0	1	1	1	AC ← (AC) ∀ [M (HL)]	Take the logical exclusive or of AC and M (HL) and store the result in AC.	ZF	
	ANDM	And M with AC then store M	0	0	0	0	0	0	1	1	1	1	M (HL) ← (AC) ↑ [M (HL)]	Take the logical and of AC and M (HL) and store the result in M (HL).	ZF	
	ORM	Or M with AC then store M	0	0	0	0	0	1	0	0	1	1	M (HL) ← (AC) ∨ [M (HL)]	Take the logical or of AC and M (HL) and store the result in M (HL).	ZF	
structions	OM.	Compare AC		0	0	4		4	4	0			<u> </u>	Compare the contents of AC and M (HL) and set or clear CF and ZF according to the result.	75.05	
d comparison in	СМ	with M	0	0	U	1	0	1	1	U	1	1	[M (HL)] + (AC) + 1	Magnitude CF ZF Comparison CF ZF CM CM CM CM CM CM CM C	ZF, CF	
Arithmetic, logic and comparison instructions	CI i4	Compare AC wiht	1	1	0	0	1	1	1	1	2	2	13 12 11 10 + (AC) +1	Compare the contents of AC and the immediate data I ₃ I ₂ I ₁ I ₀ and set or clear CF and ZF according to the result.	ZF, CF	
A	0114	immediate data	1	0	1	0	I ₃	l ₂	I ₁	I ₀			13.12.11.10.1 (1.0)	comparison CF ZF	21,01	
	CLI i4	Compare DP _L with immediate data	1	1	0			1 I ₂		1 I ₀	2	2	$ \begin{aligned} & ZF \leftarrow 1 \\ & if \; (DP_L) = I_3 \; I_2 \; I_1 \; I_0 \\ & ZF \leftarrow 0 \\ & if \; (DP_L) = I_3 \; I_2 \; I_1 \; I_0 \end{aligned} $	Compare the contents of DP _L with the immediate data. Set ZF if identical and clear ZF if not.	ZF	
	CMB t2	Compare AC bit with M data bit	1	1	0	0	1 0	1 0	1 t ₁	1 t ₀	2	2	$ZF \leftarrow 1$ if (AC, t2) = [M (HL), t2] $ZF \leftarrow 0$ if (AC, t2) = [M (HL), t2]	Compare the corresponding bits specified by t ₀ and t ₁ in AC and M(HL). Set ZF if identical and clear ZF if not.	ZF	
	LAE	Load AC and E from M2 (HL)	0	1	0	1	1	1	0	0	1	1	AC ← M (HL) E ← M (HL +1)	Load the contents of M2 (HL) into AC, E.		
	LAI i4	Load AC with immediate data	1	0	0	0	I ₃	I ₂	I ₁	I ₀	1	1	AC ← I ₃ I ₂ I ₁ I ₀	Load the immediate data into AC.	ZF	3
ions	LADR i8	Load AC from M	1 I ₇	1 I ₆	0 I ₅			0 I ₂			2	2	AC ← [M (i8)]	Load the contents of M (i8) into AC.	ZF	
nstructi	S	Store AC to M		1		0		1			1	1	M (HL) ← (AC)	Store the contents of AC into M (HL).		
store	SAE	Store AC and E to M2 (HL)	0	1	0	1	1	1	1	0	1	1	M (HL) ← (AC) M (HL + 1) ← (E)	Store the contents of AC, E into M2(HL).		
Load and store instructions		Load AC from												Load the contents of M (reg) into AC. The reg is either HL or XY depending on t0.		
	LA reg	M (reg)	0	1	0	0	1	0	t ₀	0	1	1	AC ← [M (reg)]	reg t ₀	ZF	
														HL 0 XY 1		

Note: 3. Has a vertical skip function.

Continued from preceding page.

Instruction group					Inst	ructi	on c	ode			Number of bytes	Number of cycles	0 "	B	Affected	
Instru		Mnemonic	D ₇	D_6	D_5	D_4	D_3	D ₂	D ₁	D_0	Num! bytes	Num! cycle	Operation	Description	status bits	Note
	LA reg, I	Load AC from M (reg) then increment reg	0	1	0	0	1	0	t ₀	1	1	2	$\begin{aligned} & AC \leftarrow [M \text{ (reg)}] \\ & DP_L \leftarrow (DP_L) + 1 \\ & \text{or } DP_Y \leftarrow (DP_Y) + 1 \end{aligned}$	Load the contents of M (reg) into AC. (The reg is either HL or XY.) Then increment the contents of either DP _L or DP _Y . The relationship between t0 and reg is the same as that for the LA reg instruction.	ZF	4
	LA reg, D	Load AC from M (reg) then decrement reg	0	1	0	1	1	0	t ₀	1	1	2	$\begin{aligned} & AC \leftarrow [M \text{ (reg)}] \\ & DP_L \leftarrow (DP_L) - 1 \\ & \text{or } DP_Y \leftarrow (DP_Y) - 1 \end{aligned}$	Load the contents of M (reg) into AC. (The reg is either HL or XY.) Then decrement the contents of either DP _L or DP _Y . The relationship between t ₀ and reg is the same as that for the LA reg instruction.	ZF	5
SI	XA reg	Exchange AC with M (reg)	0	1	0	0	1	1	t ₀	0	1	1	$(AC) \leftrightarrow [M (reg)]$	Exchange the contents of M (reg) and AC. The reg is either HL or XY depending on t ₀ . reg t ₀ HL 0 XY 1		
Load and store instructions	XA reg, I	Exchange AC with M (reg) then increment reg	0	1	0	0	1	1	t ₀	1	1	2	$ \begin{aligned} & (AC) \leftrightarrow [M \; (reg)] \\ & DP_L \leftarrow (DP_L) + 1 \\ & or \; DP_Y \leftarrow (DP_Y) + 1 \end{aligned} $	Exchange the contents of M (reg) and AC. (The reg is either HL or XY.) Then increment the contents of either DP _L or DP _Y . The relationship between t0 and reg is the as that for the XA reg instruction.	ZF	6
	XA reg, D	Exchange AC with M (reg) then decrement reg	0	1	0	1	1	1	t ₀	1	1	2	$ \begin{aligned} & (AC) \leftrightarrow [M \ (reg)] \\ & DP_L \leftarrow (DP_L) - 1 \\ & \text{or } DP_Y \leftarrow (DP_Y) - 1 \end{aligned} $	Exchange the contents of M (reg) and AC. (The reg is either HL or XY.) Then decrement the contents of either DP _L or DP _Y . The relationship between t0 and reg is the as that for the XA reg instruction.	ZF	7
	XADR i8	Exchange AC with M direct	1 I ₇	1 I ₆	0 I ₅	0 I ₄	1 I ₃	0 I ₂	0 I ₁	0 I ₀	2	2	(AC) ↔ [M (i8)]	Exchange the contents of AC with M (i8).		
	LEAI i8	Load E & AC with immediate data	1 I ₇	1 I ₆	0	0 I ₄	0	1 I ₂	1 I ₁	0 I ₀	2	2	$\begin{array}{c} E \leftarrow I_7 I_6 I_5 I_4 \\ AC \leftarrow I_3 I_2 I_1 I_0 \end{array}$	Load the immediate data i8 into E, AC.		
	RTBL	Read table data from program ROM	0	1	0	1	1	0	1	0	1	2	E, AC ← [ROM (PCh, E, AC)]	Load into E, AC the ROM data at the location determined by replacing the lower 8 bits of the PC with E, AC.		
	RTBLP	Read table data from program ROM then output to P4, 5	0	1	0	1	1	0	0	0	1	2	Port 4, 5 ← [ROM (PCh, E, AC)]	Output from ports 4 and 5 the ROM data at the location determined by replacing the lower 8 bits of the PC with E, AC.		

Note: 4. ZF is set according to the result of incrementing DP_L or DP_Y.
5. ZF is set according to the result of decrementing DP_L or DP_Y.
6. ZF is set according to the result of incrementing DP_L or DP_Y.
7. ZF is set according to the result of decrementing DP_L or DP_Y.

Continued from preceding page.

Instruction group					Inst	ructi	on c	ode			Number of bytes	oer of		5	Affected	
Instrugroup		Mnemonic	D ₇	D ₆	D_5	D_4	D ₃	D ₂	D ₁	D ₀	Num! bytes	Number o	Operation	Description	status bits	Note
	LDZ i4	Load DP _H with zero and DP _L with immediate data respectively	0	1	1	0	l ₃	l ₂	I ₁	I ₀	1	1	$\begin{array}{c} DP_H \leftarrow 0 \\ DP_L \leftarrow I_3 I_2 I_1 I_0 \end{array}$	Load zero into DP _H and the immediate data i4 into DP _L .		
	LHI i4	Load DP _H with immediate data	1 0	1 0	0 0		1 I ₃	1 I ₂	1 I ₁	1 I ₀	2	2	$DP_H \leftarrow I_3 I_2 I_1 I_0$	Load the immediate data i4 into DP _H .		
	LLI i4	Load DP _L with immediate data	1 0	1	0	0	1 I ₃	1 I ₂	1 I ₁	1 I ₀	2	2	$DP_L \leftarrow I_3I_2I_1I_0$	Load the immediate data i4 into DP _L .		
	LHLI i8	Load DP _H , DP _L with immediate data	1 I ₇	1 I ₆	0 I ₅	0 I ₄	0 I ₃	0 I ₂	0 I ₁	0 I ₀	2	2	$\begin{array}{c} DP_H \leftarrow I_7 \; I_6 \; I_5 \; I_4 \\ DP_L \leftarrow I_3 \; I_2 \; I_1 \; I_0 \end{array}$	Load the immediate data into DL _H , DP _L .		
	LXYI i8	Load DP _X , DP _Y with immediate data	1 I ₇	1 I ₆	0 I ₅	0 I ₄	0 I ₃	0 I ₂	1 I ₁	0 I ₀	2	2	$DP_X \leftarrow I_7 I_6 I_5 I_4$ $DP_Y \leftarrow I_3 I_2 I_1 I_0$	Load the immediate data into DL_X , DP_Y .		
	IL	Increment DP _L	0	0	0	1	0	0	0	1	1	1	$DP_L \leftarrow (DP_L) + 1$	Increment the contents . of DP _L	ZF	
Si	DL	Decrement DP _L	0	0	1	0	0	0	0	1	1	1	$DP_L \leftarrow (DP_L) - 1$	Decrement the contents of DP _L .	ZF	
Data pointer manipulation instructions	IY	Increment DP _Y	0	0	0	1	0	0	1	1	1	1	$DP_Y \leftarrow (DP_Y) + 1$	Increment the contents of DP _Y .	ZF	
ion inst	DY	Decrement DP _Y	0	0	1	0	0	0	1	1	1	1	$DP_Y \leftarrow (DP_Y) - 1$	Decrement the contents of DP _Y .	ZF	
ınipulat	TAH	Transfer AC to DP _H	1	1	0	0	1	1 0	1 0	1 0	2	2	DP _H ← (AC)	Transfer the contents of AC to DP _H .		
nter ma	THA	Transfer DP _H to AC	1	1	0 1	0	1 0	1 0	1 0	1 0	2	2	$AC \leftarrow (DP_H)$	Transfer the contents of DP _H to AC	ZF	
ata poir	ХАН	Exchange AC with DP _H	0	1	0	0	0	0	0	0	1	1	$(AC) \leftrightarrow (DP_H)$	Exchange the contents of AC and DP _H .		
۵	TAL	Transfer AC to DP _L	1	1	0	0	1 0	1 0	1 0	1	2	2	$DP_L \leftarrow (AC)$	Transfer the contents of AC to DP _L .		
	TLA	Transfer DP _L to AC	1	1	0	0	1 0	1 0	1 0	1	2	2	$AC \leftarrow (DP_L)$	Transfer the contents of DP _L to AC.	ZF	
	XAL	Exchange AC with DP _L	0	1	0	0	0	0	0	1	1	1	$(AC) \leftrightarrow (DP_L)$	Exchange the contents of AC and DP _L .		
	TAX	Transfer AC to DP _X	1	1	0	0	1 0	0	1	1 0	2	2	$DP_X \leftarrow (AC)$	Transfer the contents of AC to DP _X .		
	TXA	Transfer DP _X to AC	1	1	0	0	0	0	1	1 0	2	2	$AC \leftarrow (DP_X)$	Transfer the contents of DP _X to AC.	ZF	
	XAX	Exchange AC with DP _X		1	0	0	0	0	1	0	1	1	$(AC) \leftrightarrow (DP_X)$	Exchange the contents of AC and DP _X .		
	TAY	Transfer AC to DP _Y	1	1	0	0	1 0	0	1	1	2	2	$DP_Y \leftarrow (AC)$	Transfer the contents of AC to DP _Y .		
	TYA	Transfer DP _Y to AC	1	1	0		1 0		1	1	2	2	$AC \leftarrow (DP_Y)$	Transfer the contents of DP _Y to AC.	ZF	
	XAY	Exchange AC with DP _Y	0	1	0	0	0	0	1	1	1	1	$(AC) \leftrightarrow (DP_Y)$	Exchange the contents of AC and DP _Y		
pulation 1S	SFB n4	Set flag bit	0	1	1	1	n ₃	n ₂	n ₁	n ₀	1	1	Fn ← 1	Set the flag specified by n4 to 1.		
Flag manipulation instructions	RFB n4	Reset flag bit	0	0	1	1	n ₃	n ₂	n ₁	n ₀	1	1	Fn ← 0	Clear the flag specified by n4 to 0.	ZF	

Continued from preceding page.

Instruction group					Inst	ructi	on c	ode			Number of bytes	Number of cycles	0 "	B	Affected	
Instruc group	יי	Mnemonic	D ₇	D ₆	D ₅	D_4	D ₃	D ₂	D ₁	D ₀	Numb bytes	Numb cycle	Operation	Description	status bits	Note
	JMP addr	Jump in the current bank			1 P ₅	0 P ₄	P ₁₁ P ₃	P ₁₀	P ₉ P ₁	P ₈ P ₀	2	2	$\begin{array}{l} PC12 \leftarrow PC12 \\ PC11 \text{ to } 0 \leftarrow \\ P_{11} \text{ to } P_{0} \end{array}$	Jump to the location in the same bank specified by the immediate data P12.		8
	JPEA	Jump to the address stored at E and AC in the current page	0	0	1	0	0	1	1	1	1	1	PC12 to PC8 \leftarrow PC12 to PC8 PC7 to 4 \leftarrow (E) PC3 to 0 \leftarrow (AC)	Jump to the location determined by replacing the lower 8 bits of the PC by E, AC.		
	CAL addr	Call subroutine				1 P ₄	0 P ₃	P ₁₀ P ₂	P ₉ P ₁	P ₈ P ₀	2	2	$\begin{array}{l} \text{PC12, 11} \leftarrow 0 \\ \text{PC10 to 0} \leftarrow \\ \text{P}_{10} \text{ to P}_{0} \\ \text{M4 (SP)} \leftarrow \text{(CF, ZF,} \\ \text{PC12 to 0)} \\ \text{SP} \leftarrow \text{(SP)} - 4 \end{array}$	Call a subroutine.		
nstructions	CZP addr	Call subroutine in the zero page	1	0	1	0	P ₃	P ₂	P ₁	P ₀	1	2	$\begin{array}{l} \text{PC12 to 6,} \\ \text{PC1 to 0} \leftarrow 0 \\ \text{PC5 to 2} \leftarrow \text{P}_3 \text{ to P}_0 \\ \text{M4 (SP)} \leftarrow (\text{CF, ZF,} \\ \text{PC12 to 0)} \\ \text{SP} \leftarrow \text{SP} - 4 \end{array}$	Call a subroutine on page 0 in bank 0.		
utine ir	BANK	Change bank	0	0	0	1	1	0	1	1	1	1		Change the memory bank and register bank.		
Jump and subroutine instructions	PUSH reg	Push reg on M2 (SP)	1 1	1	0	0		1 i ₁		1 0	2	2	$M2 (SP) \leftarrow (reg)$ $SP \leftarrow (SP) - 2$	Store the contents of reg in M2 (SP). Subtract 2 from SP after the store. reg i ₁ i ₀ HL 0 0 XY 0 1		
														AE 1 0 Illegal setting 1 1		
	POP reg	Pop reg off M2 (SP)	1	1	0			1 i ₁		1 0	2	2	SP ← (SP) + 2 reg ← [M2 (SP)]	contents of M2 (SP) into reg. The relation between i ₁ i ₀ and reg is the same as that for the PUSH reg instruction.		
	RT	Return from subroutine	0	0	0	1	1	1	0	0	1	2	SP ← (SP) + 4 PC ← [M4 (SP)]	Return from a subroutine or interrupt handling routine. ZF and CF are not restored.		
	RTI	Return from interrupt routine	0	0	0	1	1	1	0	1	1	2	$\begin{array}{l} SP \leftarrow (SP) + 4 \\ PC \leftarrow [M4 \ (SP)] \\ CF, ZF \leftarrow [M4 \ (SP)] \end{array}$	Return from a subroutine or interrupt handling routine. ZF and CF are restored.	ZF, CF	
	BAt2 addr	Branch on AC bit	1 P ₇	1 P ₆	0 P ₅	1 P ₄	0 P ₃	0 P ₂	t ₁ P ₁	t ₀ P ₀	2	2	$P_4 P_3 P_2 P_1 P_0$	Branch to the location in the same page specified by P_0 to P_7 if the bit in AC specified by the immediate data t_1 t_0 is one.		
Branch instructions	MNAt2 addr	Branch on no AC bit	1 P ₇	0 P ₆	0 P ₅	1 P ₄	0 P ₃	0 P ₂	t ₁ P ₁	t ₀ P ₀	2	2	$\begin{array}{c} \text{PC7 to 0} \leftarrow \text{P}_7\text{P}_6\text{P}_5 \\ \text{P}_4\text{P}_3\text{P}_2 \\ \text{P}_1\text{P}_0 \\ \text{if (AC, t2)} \\ = 0 \end{array}$	Branch to the location in the same page specified by P_0 to P7 if the bit in AC specified by the immediate data t_1 t_0 is zero.		
Branch in	BMt2 addr	Branch on M bit	1 P ₇	1 P ₆	0 P ₅	1 P ₄	0 P ₃	1 P ₂	t ₁ P ₁	t ₀	2	2	t2] = 1	same page specified by P_0 to P_7 if the bit in M (HL) specified by the immediate data t_1 t_0 is one.		
	BNMt2 addr	Branch on no M bit	1 P ₇	0 P ₆	0 P ₅	1 P ₄	0 P ₃	1 P ₂	t ₁ P ₁	t ₀	2	2	$\begin{array}{c} \text{PC7 to 0} \leftarrow \text{P}_7\text{P}_6\text{P}_5 \\ \text{P}_4\text{P}_3\text{P}_2 \\ \text{P}_1\text{P}_0 \\ \text{if [M (HL),} \\ \text{t2] = 0} \end{array}$	Branch to the location in the same page specified by P_0 to P_7 if the bit in M (HL) specified by the immediate data t_1 t_0 is zero.		

Note: 8. This becomes PC12 + (PC12) immediately following a BANK instruction.

Continued from preceding page.

ction			Instructi	on code	er of	er of			Affected	
Instruction group	M	Mnemonic	D ₇ D ₆ D ₅ D ₄	D ₃ D ₂ D ₁ D ₀	Number of bytes	Number o	Operation	Description	status bits	Note
	BPt2 addr	Branch on port bit	1 1 0 1 P ₇ P ₆ P ₅ P ₄	1 0 t ₁ t ₀ P ₃ P ₂ P ₁ P ₀	2	2	$\begin{array}{c} \text{PC7 to 0} \leftarrow \text{P}_7 \text{P}_6 \text{P}_5 \\ \text{P}_4 \text{P}_3 \text{P}_2 \\ \text{P}_1 \text{P}_0 \\ \text{if [P]} \\ \text{(DPL), t2]} \\ = 1 \end{array}$	Branch to the location in the same page specified by P ₀ to P ₇ if the bit in port (DP _L) specified by the immediate data t ₁ t ₀ is one.		9
	BNPt2 addr	Branch on no port bit		1 0 t ₁ t ₀ P ₃ P ₂ P ₁ P ₀	2	2	$\begin{array}{c} \text{PC7 to } 0 \leftarrow P_7 P_6 P_5 \\ P_4 P_3 P_2 \\ P_1 P_0 \\ \text{if } [P \\ (DP_L), t2] \\ = 0 \end{array}$	Branch to the location in the same page specified by P ₀ to P ₇ if the bit in port (DP _L) specified by the immediate data t ₁ t ₀ is zero.		9
	BC addr	Branch on CF	1 1 0 1 P ₇ P ₆ P ₅ P ₄	1 1 0 0 P ₃ P ₂ P ₁ P ₀	2	2	$\begin{array}{c} \text{PC7 to 0} \leftarrow \text{P}_7 \text{P}_6 \text{P}_5 \\ \text{P}_4 \text{P}_3 \text{P}_2 \\ \text{P}_1 \text{P}_0 \\ \text{if (CF)} \\ = 1 \end{array}$	Branch to the location in the same page specified by P ₀ to P ₇ if CF is one.		
Branch instructions	BNC addr	Branch on no CF	1 0 0 1 P ₇ P ₆ P ₅ P ₄	1 1 0 0 P ₃ P ₂ P ₁ P ₀	2	2	$\begin{array}{c} \text{PC7 to 0} \leftarrow \text{P}_7 \text{P}_6 \text{P}_5 \\ \text{P}_4 \text{P}_3 \text{P}_2 \\ \text{P}_1 \text{P}_0 \\ \text{if (CF)} \\ = 0 \end{array}$	Branch to the location in the same page specified by P_0 to P_7 if CF is zero.		
Branch	BZ addr	Branch on ZF	1 1 0 1 P ₇ P ₆ P ₅ P ₄	1 1 0 1 P ₃ P ₂ P ₁ P ₀	2	2	$\begin{array}{c} \text{PC7 to 0} \leftarrow \text{P}_7 \text{P}_6 \text{P}_5 \\ \text{P}_4 \text{P}_3 \text{P}_2 \\ \text{P}_1 \text{P}_0 \\ \text{if (ZF)} \\ = 1 \end{array}$	Branch to the location in the same page specified by P ₀ to P ₇ if ZF is one.		
	BNZ addr	Branch on no ZF	1 0 0 1 P ₇ P ₆ P ₅ P ₄	1 1 0 1 P ₃ P ₂ P ₁ P ₀	2	2	$\begin{array}{c} \text{PC7 to 0} \leftarrow \text{P}_7 \text{P}_6 \text{P}_5 \\ \text{P}_4 \text{P}_3 \text{P}_2 \\ \text{P}_1 \text{P}_0 \\ \text{if (ZF)} \\ = 0 \end{array}$	Branch to the location in the same page specified by P ₀ to P ₇ if ZF is zero.		
	BFn4 addr	Branch on flag bit	1 1 1 1 P ₇ P ₆ P ₅ P ₄	n ₃ n ₂ n ₁ n ₀ P ₃ P ₂ P ₁ P ₀	2	2	$\begin{array}{c} \text{PC7 to 0} \leftarrow \text{P}_7 \text{P}_6 \text{P}_5 \\ \text{P}_4 \text{P}_3 \text{P}_2 \\ \text{P}_1 \text{P}_0 \\ \text{if (Fn)} \\ = 1 \end{array}$	Branch to the location in the same page specified by P_0 to P_7 if the flag (of the 16 user flags) specified by n_3 n_2 n_1 n_0 is one.		
	BNFn4 addr	Branch on no flag bit	1 0 1 1 P ₇ P ₆ P ₅ P ₄	n ₃ n ₂ n ₁ n ₀ P ₃ P ₂ P ₁ P ₀	2	2	$\begin{array}{c} \text{PC7 to 0} \leftarrow \text{P}_7 \text{P}_6 \text{P}_5 \\ \text{P}_4 \text{P}_3 \text{P}_2 \\ \text{P}_1 \text{P}_0 \\ \text{if (Fn)} \\ = 0 \end{array}$	Branch to the location in the same page specified by P_0 to P_7 if the flag (of the 16 user flags) specified by n_3 n_2 n_1 n_0 is zero.		
	IP0	Input port 0 to AC	0 0 1 0	0 0 0 0	1	1	AC ← (P0)	Input the contents of port 0 to AC.	ZF	
	IP	Input port to AC	0 0 1 0	0 1 1 0	1	1	$AC \leftarrow [P \ (DP_L)]$	Input the contents of port P (DP _L) to AC.	ZF	
	IPM	Input port to M	0 0 0 1	1 0 0 1	1	1	$M\;(HL) \leftarrow [P\;(DP_L)]$	Input the contents of port P (DP _L) to M (HL).		
s	IPDR i4	Input port to AC direct	1 1 0 0 0 1 1 0	1 1 1 1 I ₃ I ₂ I ₁ I ₀	2	2	AC ← [P (i4)]	Input the contents of P (i4) to AC.	ZF	
I/O instructions	IP45	Input port 4, 5 to E, AC respectively	1 1 0 0 1 1 0 1	1 1 1 1 0 0	2	2	$E \leftarrow [P (4)]$ $AC \leftarrow [P (5)]$	Input the contents of ports P (4) and P (5) to E and AC respectively.		
0/1	ОР	Output AC to port	0 0 1 0	0 1 0 1	1	1	$P (DP_L) \leftarrow (AC)$	Output the contents of AC to port P (DP _L).		
	ОРМ	Output M to port	0 0 0 1	1 0 1 0	1	1	$P\;(DP_L) \leftarrow [M\;(HL)]$	Output the contents of M (HL) to port P (DP _L).		
	OPDR i4	Output AC to port direct	1 1 0 0 0 1 1 1	1 1 1 1 1 1 1 ₃ 1 ₂ 1 ₁ 1 ₀	2	2	P (i4) ← (AC)	Output the contents of AC to P (i4).		
	OP45	Output E, AC to port 4, 5 respectively	1 1 0 0 1 1 0 1	1 1 1 1 0 1	2	2	P (4) ← (E) P (5) ← (AC)	Output the contents of E and AC to ports P (4) and P (5) respectively.		

Note: 9. Internal control registers can also be tested by executing this instruction immediately after a BANK instruction. However, this is limited to registers that can be read out.

Continued from preceding page.

Instruction group	retion			Instruction code								s s	0 1	Description	Affected	N-4-
Instrugroup	Mnemonic		D ₇	D ₆	D ₅	D ₄	D ₃	D ₂	D ₁	D ₀	Number of bytes	Number o	Operation	Description	status bits	Note
I/O instructions	SPB t2	Set port bit	0	0	0	0	1	0	t ₁	t ₀	1	1	[P (DP _L), t2] ← 1	Set to one the bit in port P (DP _L) specified by the immediate data t ₁ t ₀ .		
	RPB t2	Reset port bit	0	0	1	0	1	0	t ₁	t ₀	1	1	$[P (DP_L), t2] \leftarrow 0$	Clear to zero the bit in port P (DP _L) specified by the immediate data t ₁ t ₀ .	ZF	
	ANDPDR i4, p4	And port with immediate data then output	1 I ₃	1 I ₂	0 I ₁	0 I ₀	0 P ₃	1 P ₂	0 P ₁	1 P ₀	2	2	$P (P_3 \text{ to } P_0) \leftarrow [P (P_3 \text{ to } 0)] \lor I_{3 \text{ to } 0}$	Take the logical and of P (P_3 to P_0) and the immediate data I_3 I_2 I_1 I_0 and output the result to P (P_3 to P_0).	ZF	
	ORPDR i4, p4	Or port with immediate data then output	1 I ₃	1 I ₂	0 I ₁	0 I ₀	0 P ₃	1 P ₂	0 P ₁	0 P ₀	2	2	$P (P_3 \text{ to } P_0) \leftarrow [P (P_3 \text{ to } 0)] \lor I_{3 \text{ to } 0}$	Take the logical or of P (P_3 to P_0) and the immediate data $I_3 I_2 I_1 I_0$ and output the result to P (P_3 to P_0).	ZF	
Timer control instructions	WTTM0	Write timer 0	1	1	0	0	1	0	1	0	1	2	TIMER0 ← [M2 (HL)], (AC)	Write the contents of M2 (HL), AC into the timer 0 reload register.		
	WTTM1	Write timer 1	1 1	1	0 1	0	1 0	1	1 0	1 0	2	2	TIMER1 ← (E), (AC)	Write the contents of E, AC into the timer 1 reload register A.		
	RTIM0	Read timer 0	1	1	0	0	1	0	1	1	1	2	M2 (HL), AC ← (TIMER0)	Read out the contents of the timer 0 counter into M2 (HL), AC.		
	RTIM1	Read timer1	1 1	1 1	0 1	0 1	1 0	1 1	1 0	1 1	2	2	E, AC ← (TIMER1)	Read out the contents of the timer 1 counter into E, AC.		
	START0	Start timer 0	1	1	0	0	1 0	1	1	1 0	2	2	Start timer 0 counter	Start the timer 0 counter.		
	START1	Start timer 1	1	1	0	0	1	1	1	1	2	2	Start timer 1 counter	Start the timer 1 counter.		
	STOP1	Stop timer 0	1	1	0	0	1 0	1	1	1	2	2	Stop timer 0 counter	Stop the timer 0 counter.		
	STOP1	Stop timer 1	1	1	0	0	1 0	1	1	1	2	2	Stop timer 1 counter	Stop the timer 1 counter.		
Interrupt control instructions	MSET	Set interrupt master enable flag	1	1	0	0	1	1	0	1	2	2	MSE ← 1	Set the interrupt master enable flag to one.		
	MRESET	Reset interrupt master enable flag	1	1	0	0	1 0	1	0	1	2	2	MSE ← 0	Clear the interrupt master enable flag to zero.		
	EIH i4	Enable interrupt high	1 0	1	0	0	1 I ₃	1 I ₂	0 I ₁	1 I ₀	2	2	EDIH ← (EDIH) ∀ i4	Set the interrupt enable flag to one.		
	EIL i4	Enable interrupt low	1 0	1	0	0	1 I ₃	1 I ₂	0 I ₁	1 I ₀	2	2	EDIL ← (EDIL) ∨ i4	Set the interrupt enable flag to one.		
	DIH i4	Disable interrupt high	1 1	1	0	0	1 I ₃	1	0 I ₁	1 I ₀	2	2	$EDIH \leftarrow (EDIL) \land \ \overline{i4}$	Clear the interrupt enable flag to zero.	ZF	
	DIL i4	Disable interrupt low	1	1	0	0	1 I ₃	1 I ₂	0	1 I ₀	2	2	$EDIL \leftarrow (EDIL) \ \land \ \overline{i4}$	Clear the interrupt enable flag to zero.	ZF	
	WTSP	Write SP	1	1	0	0	1	1	1	1	2	2	SP ← (E), (AC)	Transfer the contents of E, AC to SP.		
	RSP	Read SP	1	1 1	0	0 1	1 1	1 0	1 1	1 1	2	2	$E,AC \leftarrow (SP)$	Transfer the contents of SP to E, AC.		
control	HALT	HALT	1	1	0	0	1	1	1	1	2	2	HALT	Enter halt mode.		
Standby control instructions	HOLD	HOLD	1	1	0	0	1	1	1	1 1	2	2	HOLD	Enter HOLD mode.		

Continued from preceding page.

Instruction group				Instruction code								oer of S		2	Affected	
Instruc	ľ	Mnemonic		D ₆	D ₅	D_4	D ₃	D ₂	D ₁	D ₀	Number bytes	Number cycles	Operation	Description	status bits	Note
Serial I/O control instructions	STARTS	Start serial IO	1 1	1 1	0 1	0	1 1	1 1	1 1	1 0	2	2	START SI O	Start SIO operation.		
	WTSIO	Write serial IO	1 1	1 1	0 1	0	1 1	1 1	1 1	1 1	2	2	SIO ← (E), (AC)	Write the contents of E, AC to SIO.		
	RSIO	Read serial IO	1 1	1 1	0	0	1	1 1	1 1	1 1	2	2	E, AC ← (SIO)	Read the contents of SIO into E, AC.		
Other instructions	NOP	No operation	0	0	0	0	0	0	0	0	1	1	No operation	Consume one machine cycle without performing any operation.		
	SB i2	Select bank	1 1	1 1	0	0	1	1 0	1 I ₁	1 I ₀	2	2	PC12 ← I ₁ I ₀	Specify the memory bank.		

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