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# 10-2500 GHz, Linear-in-dB Variable Gain Amplifier

## RF/IF Concept

## AD8365

### FEATURES

**“Linear-in-dB” Gain Control**

**40dB Control Range**

**20dB Gain, 20dB Attenuation**

**Performance from 10 to 2500 GHz**

**+3dBm Output Drive Capability**

**Open Collector Option to +10dBm**

**50 ohm Input/Output Impedance**

**5 dB Noise Figure (at max gain)**

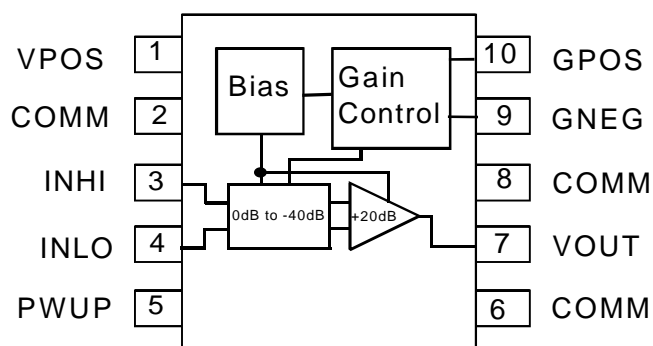
**+/-1 dB Gain Control Accuracy**

**Power-Down Feature**

### APPLICATIONS

**RF/IF AGC Amplifier**

**Power Amplifier Pre-Driver**



10 Pin Micro-SO Package

### PRODUCT DESCRIPTION

The AD8365 is a variable gain amplifier for use in RF AGC systems. It provides accurate performance from 10 to 2500 MHz. The decibel gain and attenuation is Linear-in-dB, accurately calibrated and stable over temperature and supply voltage. The device offers 40 dB control range, with 20 dB gain and 20 dB attenuation.

The differential control interface allows a positive or negative gain control transfer function. Single-ended gain control is easily implemented by grounding either GPOS or GNEG.

The output drivers are capable, in full bias operation, of providing +3 dBm output power into a 50 ohm load. An open collector option is offered which enables drive levels up to +10dBm. Noise figure is targeted at 5 dB at maximum gain. Output IP3 design goal is +25 dBm. The device operates from a single supply over a 2.7 to 5.5 volt range, requiring a nominal 20 mA of quiescent current.

This RF VGA is useful as a predriver and gain control device for RF transmitter power amplifiers up to 2500 MHz. It can also be used as receiver AGC amplifier. Cellular base stations and terminals, microwave radios, CATV, Wireless LAN and other systems can benefit from the Linear-in-dB performance at high frequencies.

The AD8365 uses a proprietary circuit topology- the X-AMP™. The X-AMP comprises a variable attenuator, followed by a fixed gain amplifier. The front end attenuator allows the fixed gain stage to avoid coping with large input signal levels. A proprietary interpolation technique provides a continuous gain control function which is Linear-in-dB.

The AD8365 is specified for operation from -40°C to +85°C and is available in an 8 pin micro-SO package. It is fabricated on an Analog Devices proprietary high Ft silicon bipolar process.

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<b>SPECIFICATIONS</b> (@25°C, Vs=+5V, RL=50Ω, Pwr <sub>dn</sub> = (N.C.), T <sub>min</sub> = -40°C, T <sub>max</sub> = +85°C, unless otherwise noted)					
AD8365	Conditions	Min	Typ	Max	Units
<b>DYNAMIC PERFORMANCE</b>					
–3 dB Small Signal Bandwidth	G=+1, V <sub>out</sub> = 0.5 V p-p	TBD	350		MHz
	G=+5, V <sub>out</sub> = 0.5 V p-p		175		MHz
Bandwidth for 0.1 dB Flatness	V <sub>out</sub> = 0.2 V p-p	TDB	TDB		MHz
Large Signal Bandwidth	V <sub>out</sub> = 4Vp-p		2		MHz
Peaking	V <sub>out</sub> = 0.2Vp-p, <50MHz		TBD		dB
Slew Rate	V <sub>out</sub> = 2 Vp-p, G=+2		900		V/μs
Rise and Fall time	V <sub>out</sub> = 2 V p-p		2		ns
Settling Time	0.1%, V <sub>out</sub> = 2Vp-p		TBD		ns
Input Overdrive recovery time	V <sub>in</sub> < 150% of V <sub>s</sub>		TBD		ns
<b>NOISE/DISTORTION PERFORMANCE</b>					
Distortion	V <sub>out</sub> = 2 V p-p				
2 <sup>nd</sup> Harmonic	f <sub>c</sub> = 1 MHz, R <sub>L</sub> = 100Ω/ 25Ω		-66/TBD		dBc
	10 MHz		TBD		dBc
3 <sup>rd</sup> Harmonic	f <sub>c</sub> = 1 MHz, R <sub>L</sub> = 100Ω/ 25Ω		-67/TBD		dBc
	10 MHz		TBD		dBc
Multitone Input Power Ratio	26kHz to 1.1MHz, R <sub>L</sub> = 100Ω/ 25Ω		-65/TBD		dBc
IMD	10MHz, Delta f=50kHz, R <sub>L</sub> = 100Ω/ 25Ω		TBD		MHz
IP3	5MHz, R <sub>L</sub> = 100Ω/ 25Ω		TBD		MHz
Voltage Noise (RTI)	f = 100 kHz		4.6		nV/√Hz
Input Current Noise	f = 100 kHz		17		pA/√Hz
Differential Gain	NTSC, R <sub>L</sub> =150 Ω		TBD		%
Differential Phase	NTSC, R <sub>L</sub> =150 Ω		TBD		Degrees
<b>INPUT CHARACTERISTICS</b>					
RTI Offset Voltage	T <sub>min</sub> to T <sub>max</sub>		TBD	TBD	mV
Input Bias Current	T <sub>min</sub> to T <sub>max</sub>		TBD	TBD	μA
Input Resistance			TBD	TBD	μA
Input Capacitance			2		MΩ
Input Common Mode Voltage Range		TBD		TBD	pF
<b>OUTPUT CHARACTERISTICS</b>					
Output Voltage Swing	Single Ended, R <sub>L</sub> =25Ω	-10		+10	V
Linear Output Current	T <sub>min</sub> to T <sub>max</sub>	400	500		mA
Turn on output Glitch	1VDC input		TBD		mV
Capacitive Load Drive	R <sub>s</sub> = 10Ω		TBD		pF
<b>POWER SUPPLY</b>					
Operating Range	T <sub>min</sub> to T <sub>max</sub>	+5	12.5	+/-13	V
Quiescent Current	Shutdown		4.5	TBD	mA/Amp
Turn off time	To rated shutdown current		TBD	TBD	mA
Turn on time	To 0.1% of final output, 1VDC input		TBD		μs
Power Supply Rejection Ratio	Delta V <sub>s</sub> = +/-1V		TBD		us
<b>OPERATING TEMPERATURE RANGE</b>		-40		+85	°C

**SPECIFICATIONS (@25°C, Vs=+12V, RL=100Ω, Pwr<sub>dn</sub>= (N.C.), T<sub>min</sub> = -40°C, T<sub>max</sub> = +85°C, unless otherwise noted)**

<b>AD8016</b>	<b>Conditions</b>	<b>Min</b>	<b>Typ</b>	<b>Max</b>	<b>Units</b>
<b>DYNAMIC PERFORMANCE</b>					
–3 dB Small Signal Bandwidth	G=+1, V <sub>out</sub> = 0.5 V p-p	TBD	400		MHz
	G=+5, V <sub>out</sub> = 0.5 V p-p		175		MHz
Bandwidth for 0.1 dB Flatness	V <sub>out</sub> = 0.2 V p-p	TDB	TDB		MHz
Large Signal Bandwidth	V <sub>out</sub> = 4Vp-p		2		MHz
Peaking	V <sub>out</sub> = 0.2Vp-p, <50MHz		TBD		dB
Slew Rate	V <sub>out</sub> = 2 Vp-p, G=+2		1000		V/μs
Rise and Fall time	V <sub>out</sub> = 2 V p-p		2		ns
Settling Time	0.1%, V <sub>out</sub> = 2Vp-p		TBD		ns
Input Overdrive recovery time	V <sub>in</sub> < 150% of V <sub>s</sub>		TBD		ns
<b>NOISE/DISTORTION PERFORMANCE</b>					
Distortion	V <sub>out</sub> = 2 V p-p				
2 <sup>nd</sup> Harmonic	f <sub>c</sub> = 1 MHz, R <sub>L</sub> = 100Ω/ 25Ω		-66		dBc
	10 MHz		TBD		dBc
3 <sup>rd</sup> Harmonic	f <sub>c</sub> = 1 MHz, R <sub>L</sub> = 100Ω/ 25Ω		-67		dBc
	10 MHz		TBD		dBc
Multitone Input Power Ratio	26kHz to 1.1MHz, R <sub>L</sub> = 100Ω/ 25Ω		-65		dBc
IMD	10MHz, Delta f=50kHz, R <sub>L</sub> = 100Ω/ 25Ω		TBD		MHz
IP3	5MHz, R <sub>L</sub> = 100Ω/ 25Ω		TBD		MHz
Voltage Noise (RTI)	f = 100 kHz		4.6		nV/√Hz
Input Current Noise	f = 100 kHz		17		pA/√Hz
Differential Gain	NTSC, R <sub>L</sub> =150 Ω		TBD		%
Differential Phase	NTSC, R <sub>L</sub> =150 Ω		TBD		Degrees
<b>INPUT CHARACTERISTICS</b>					
RTI Offset Voltage	T <sub>min</sub> to T <sub>max</sub>		TBD	TBD	mV
Input Bias Current			TBD	TBD	mV
			TBD	TBD	μA
Input Resistance			TBD	TBD	μA
Input Capacitance			2		MΩ
Input Common Mode Voltage Range		TBD		TBD	pF
<b>OUTPUT CHARACTERISTICS</b>					
Output Voltage Swing	Single Ended, R <sub>L</sub> =25Ω	-10		+10	V
Linear Output Current	T <sub>min</sub> to T <sub>max</sub>	400	500		mA
Turn on output Glitch	1VDC input		TBD		mV
Capacitive Load Drive	R <sub>s</sub> = 10Ω		TBD		pF
<b>POWER SUPPLY</b>					
Operating Range	T <sub>min</sub> to T <sub>max</sub>	+5		+13	V
Quiescent Current			12.5	TBD	mA/Amp
				TBD	mA
Turn off time			4.5		mA/Amp
Turn on time			TBD		us
Power Supply Rejection Ratio	To 0.1% of final output, 1VDC input		TBD		us
	Delta V <sub>s</sub> = +/-1V		TBD		dB
<b>OPERATING TEMPERATURE RANGE</b>		-40		+85	°C

## **Applications:**