

# 2SK1967

## Silicon N-Channel Power F-MOS

### ■ Features

- Low-voltage drive possible
- High-speed switching :  $t_f = 180\text{ns}$
- No secondary breakdown

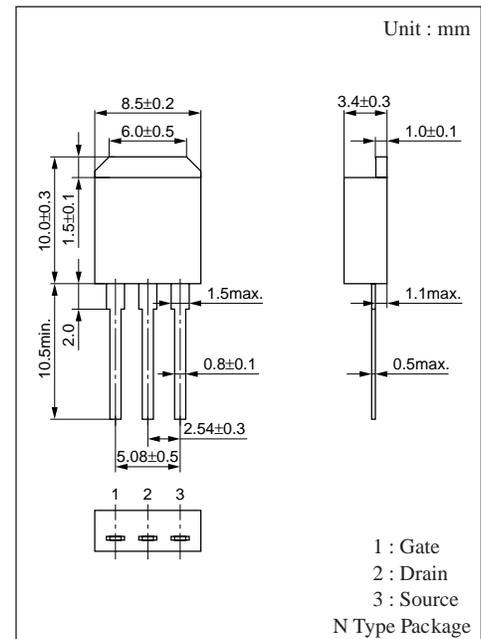
### ■ Applications

- Solenoid drive
- Motor drive
- Control equipment
- Switching mode regulator

### ■ Absolute Maximum Ratings ( $T_c = 25^\circ\text{C}$ )

Parameter	Symbol	Rating	Unit	
Drain-Source breakdown voltage	$V_{DSS}$	60	V	
Gate-Source voltage	$V_{GSS}$	$\pm 20$	V	
Drain current	DC	$I_D^*$	$\pm 12$	A
		$I_D$	$\pm 20$	A
	Pulse	$I_{DP}$	$\pm 40$	A
Allowable power dissipation	$T_c = 25^\circ\text{C}$	$P_D$	30	W
	$T_a = 25^\circ\text{C}$		1.3	
Channel temperature	$T_{ch}$	150	$^\circ\text{C}$	
Storage temperature	$T_{stg}$	-55 to +150	$^\circ\text{C}$	

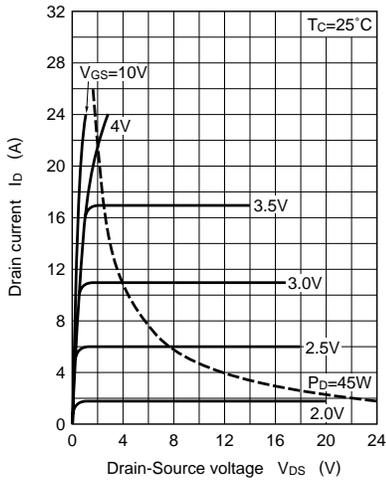
\* 1 Max  $I_D$  value at 4V drive



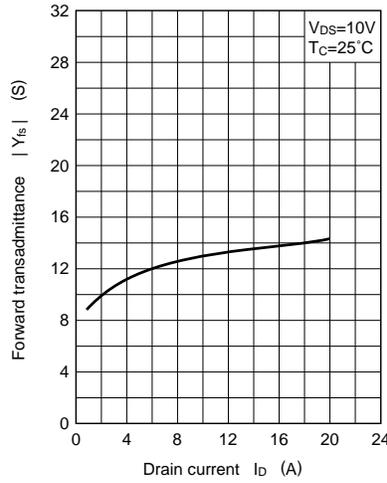
### ■ Electrical Characteristics ( $T_c = 25^\circ\text{C}$ )

Parameter	Symbol	Condition	Min	Typ	Max	Unit
Drain-Source cut-off current	$I_{DSS}$	$V_{DS} = 50\text{V}, V_{GS} = 0$			10	$\mu\text{A}$
Gate-Source leakage current	$I_{GSS}$	$V_{GS} = \pm 20\text{V}, V_{DS} = 0$			$\pm 1$	$\mu\text{A}$
Drain-Source breakdown voltage	$V_{DSS}$	$I_D = 1\text{mA}, V_{GS} = 0$	60			V
Gate threshold voltage	$V_{th}$	$V_{DS} = 10\text{V}, I_D = 1\text{mA}$	1		2.5	V
Drain-Source ON-resistance	$R_{DS(on)1}$	$V_{GS} = 10\text{V}, I_D = 10\text{A}$		45	70	$\text{m}\Omega$
	$R_{DS(on)2}$	$V_{GS} = 4\text{V}, I_D = 6\text{A}$		65	100	$\text{m}\Omega$
Forward transadmittance	$ Y_{fs} $	$V_{DS} = 10\text{V}, I_D = 10\text{A}$	8	13		S
Diode forward voltage	$V_{DSF}$	$I_{DR} = 10\text{A}, V_{GS} = 0$			-1.7	V
Input capacitance	$C_{iss}$	$V_{DS} = 10\text{V}, V_{GS} = 0, f = 1\text{MHz}$		1550		pF
Output capacitance	$C_{oss}$			680		pF
Feedback capacitance	$C_{rss}$			300		pF
Turn-on time	$t_{on}$	$V_{GS} = 10\text{V}, I_D = 10\text{A}$ $V_{DD} = 30\text{V}, R_L = 3\Omega$		90		ns
Fall time	$t_f$			180		ns
Turn-off time (delay time)	$t_{d(off)}$			360		ns

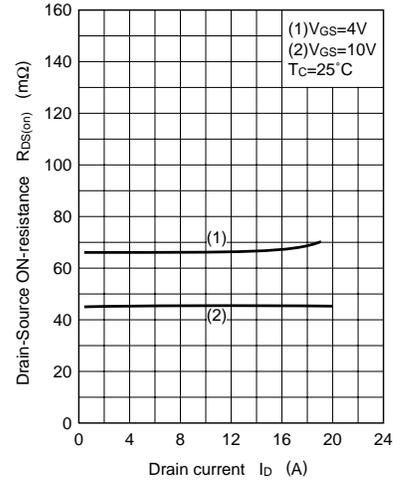
$I_D - V_{DS}$



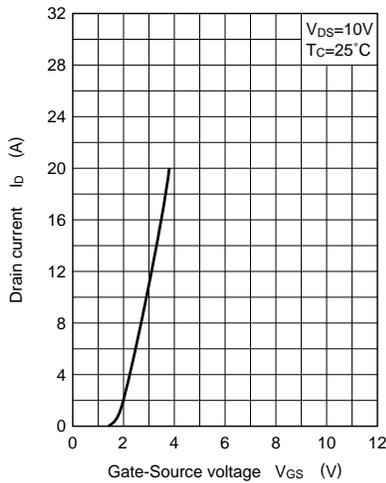
$|Y_{fs}| - I_D$



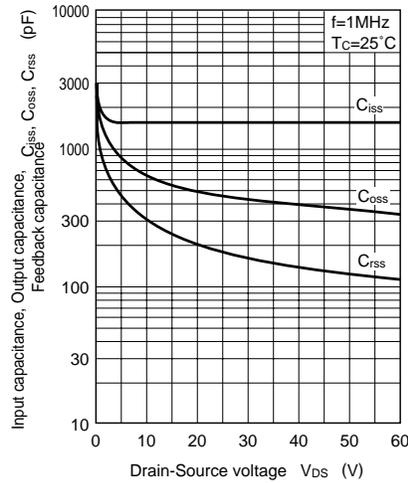
$R_{DS(on)} - I_D$



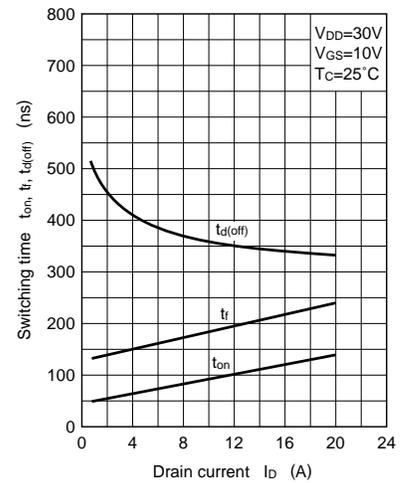
$I_D - V_{GS}$



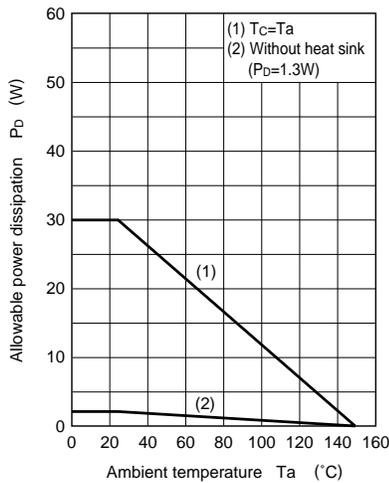
$C_{iss}, C_{oss}, C_{rss} - V_{DS}$



$t_{on}, t_f, t_d(off) - I_D$



$P_D - T_a$



Area of safe operation (ASO)

