

# LMH6704

# 650 MHz Programmable Gain Buffer with Disable

## **General Description**

The LMH™6704 is a very wideband, DC coupled programmable gain buffer designed specifically for wide dynamic range systems requiring exceptional signal fidelity. The LMH6704 includes on chip feedback and gain set resistors, simplifying PCB layout while providing user programmable gains of +1, +2 and −1 V/V. The LMH6704 provides a disable pin, which places the amplifier in a high output impedance, low power mode. The Disable pin may be allowed to float high.

With a 650 MHz Small Signal Bandwidth ( $A_V = +1$ ), full power gain flatness to 200 MHz, and excellent Differential Gain and Phase, the LMH6704 is optimized for video applications. High resolution video systems will benefit from the LMH6704's ability to drive multiple video loads at low levels of differential gain or differential phase distortion.

The LMH6704 is constructed with National's proprietary high speed complementary bipolar process using National's proven current feedback circuit architectures. It is available in 8-Pin SOIC and 6-Pin SOT23 packages.

#### **Features**

■ Wideband operation

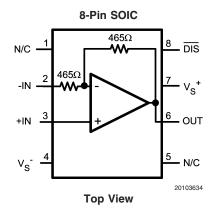
| $-A_V = +1, V_O = 0.5 V_{PP}$ | 650 MHz |
|-------------------------------|---------|
| $-A_V = +2, V_O = 0.5 V_{PP}$ | 450 MHz |
| $-A_V = +2, V_O = 2 V_{PP}$   | 400 MHz |
| ■ High output current         | ±90 mA  |

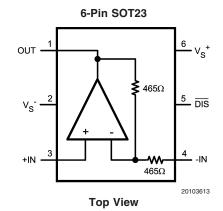
- Very low distortion
  - $-2^{\text{nd}}/3^{\text{rd}}$  harmonics (10 MHz, R<sub>L</sub> = 100 $\Omega$ ): -62/-78- Differential gain/Differential phase: 0.02%/0.02°
- Low noise 2.3nV/ $\sqrt{\text{Hz}}$  High slew rate 3000 V/ $\mu$ s
- Supply current 11.5 mA

# **Applications**

- HDTV, NTSC & PAL video systems
- Video switching and distribution
- ADC driver
- DAC buffer
- RGB driver
- High speed multiplexer

## **Connection Diagram**





# **Ordering Information**

| Package      | Part Number | Package Marking | Transport Media          | NSC Drawing |  |
|--------------|-------------|-----------------|--------------------------|-------------|--|
| 8-Pin SOIC   | LMH6704MA   | LMH6704MA       | 95 Units Rail            | M08A        |  |
| 6-PIII 50IC  | LMH6704MAX  | LIVINO704IVIA   | 2.5k Units Tape and Reel | IVIUOA      |  |
| 6-Pin SOT23  | LMH6704MF   | B07A            | 1k Units Tape and Reel   | MF06A       |  |
| 0-7111 30123 | LMH6704MFX  | DU/A            | 3k Units Tape and Reel   | MIFUOA      |  |

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# **Absolute Maximum Ratings** (Note 1)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

Supply Voltage 13.5V  $I_{OUT}$  (Note 3) Common-Mode Input Voltage  $V_S^-$  to  $V_S^+$  Maximum Junction Temperature 150°C Storage Temperature Range  $-65^{\circ}\text{C}$  to  $150^{\circ}\text{C}$ 

Soldering Information

Infrared or Convection (20 sec.) 235°C Wave Soldering (10 sec.) 260°C Lead Temp. (soldering 10 sec.) 300°C

ESD Tolerance (Note 4)
Human Body Model
Machine Model

# **Operating Ratings** (Note 1)

Nominal Supply Voltage  $\pm 4V$  to  $\pm 6V$ Operating Temperature  $-40^{\circ}$ C to  $85^{\circ}$ C

2000V

200V

Thermal Resistance

 Package
 ( $θ_{JC}$ )
 ( $θ_{JA}$ )

 8-Pin SOIC
 75°C/W
 160°C/W

 6-Pin SOT23
 120°C/W
 187°C/W

### **Electrical Characteristics** (Note 2)

 $T_A = +25^{\circ}C$  ,  $A_V = +2,~V_S = \pm 5V,~R_L = 100\Omega;$  unless specified.

| Symbol              | Parameter  | eter Conditions                                   |                     | Min                 | Тур      | Max                 | Units   |
|---------------------|--|---|---------------------|---------------------|----------|---------------------|---------|
|                     |  |   |                     | (Note 6)            | (Note 6) | (Note 6)            |         |
| Dynamic I           | Performance                                      |   |                     |                     |          |                     |         |
| SSBW                | -3 dB Bandwidth $V_{OUT} = 0.5 V_{PP}, A_V = +1$ |   |                     | 650                 |          |                     |         |
| SSBW                |  | $V_{OUT} = 0.5 V_{PP}$                            |                     |                     | 450      |                     | MHz     |
| LSBW                |  | $V_{OUT} = 2 V_{PP}$                              |                     |                     | 400      |                     |         |
| GF <sub>0.1dB</sub> | 0.1 dB Gain Bandwidth                            | V <sub>OUT</sub> = 2 V <sub>PP</sub>              |                     |                     | 200      |                     | MHz     |
| SR                  | Slew Rate  | $V_{OUT} = 4 V_{PP}, 40\% \text{ to } 60^{\circ}$ | % (Note 5)          |                     | 3000     |                     | V/µs    |
| TRS/TRL             | Rise and Fall Time (10% to 90%)                  | 2V Step   |                     |                     | 0.9      |                     | ns      |
| t <sub>s</sub>      | Settling Time to 0.1%                            | 2V Step   |                     |                     | 10       |                     | ns      |
| Distortion          | and Noise Response                               |   |                     | •                   | •        | •                   |         |
| HD2L                | 2 <sup>nd</sup> Harmonic Distortion              | V <sub>OUT</sub> = 2.0 V <sub>PP</sub> , f = 10 M | Hz                  |                     | -62      |                     | -ID-    |
| HD2H                |  | $V_{OUT} = 2.0 V_{PP}, f = 40 M$                  | Hz                  |                     | -52      |                     | dBc     |
| HD3L                | 3 <sup>rd</sup> Harmonic Distortion              | V <sub>OUT</sub> = 2.0 V <sub>PP</sub> , f = 10 M | Hz                  |                     | -78      |                     | -ID-    |
| HD3H                |  | $V_{OUT} = 2.0 V_{PP}, f = 40 MHz$                |                     |                     | -65      |                     | dBc     |
| IMD                 | Two-Tone Intermodulation                         | f = 10 MHz, P <sub>OUT</sub> = 10 dE              | 3m/tone             |                     | -65      |                     | dBc     |
| V <sub>N</sub>      | Output Noise Voltage                             | f = 100 kHz                                       | A <sub>V</sub> = +2 |                     | 10.5     |                     | nV/ √Hz |
|                     |  |   | $A_V = +1$          |                     | 9.3      |                     |         |
|                     |  |   | $A_{V} = -1$        |                     | 10.5     |                     |         |
| I <sub>NN</sub>     | Non-Inverting Input Noise<br>Current             |   |                     |                     | 3        |                     | pA/ √Hz |
| DG                  | Differential Gain                                | $R_L = 150\Omega$ , $f = 4.43 \text{ MHz}$        |                     |                     | .02      |                     | %       |
| DP                  | Differential Phase                               | $R_L = 150\Omega$ , $f = 4.43 \text{ MHz}$        |                     |                     | 0.02     |                     | deg     |
| Static, DC          | Performance                                      |   |                     |                     |          |                     |         |
| A <sub>V</sub>      | Gain   |   |                     | 1.98<br><b>1.96</b> | 2.00     | 2.02<br><b>2.04</b> | V/V     |
|                     | Gain Error                                       |   |                     | -1<br>-2            |          | +1<br>+2            | %       |
| V <sub>IO</sub>     | Input Offset Voltage                             |   |                     |                     | 2        | ±7<br>±8.3          | mV      |
| DV <sub>IO</sub>    | Input Offset Voltage Average Drift               |   |                     |                     | 35       |                     | μV/°C   |
| I <sub>BN</sub>     | Input Bias Current                               | Non-Inverting (Note 7)                            |                     |                     | -5       | ±15<br><b>±18</b>   | μΑ      |
| I <sub>BI</sub>     | Input Bias Current                               | Inverting   |                     |                     | 5        | ±22<br><b>±31</b>   |         |

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# Electrical Characteristics (Note 2) (Continued)

 $T_A = +25^{\circ}C$  ,  $A_V = +2$ ,  $V_S = \pm 5V$ ,  $R_L = 100\Omega$ ; unless specified.

| Symbol           | Parameter                                  | Conditions   | Min      | Тур      | Max      | Units     |
|------------------|--|--|----------|----------|----------|-----------|
|                  |  |  | (Note 6) | (Note 6) | (Note 6) |           |
| CMIR             | Common Mode Input Range                    | $V_{IO} \le 15 \text{ mV}$                                 | ±1.9     | ±2       |          | V         |
| PSRR             | Power Supply Rejection Ratio               | DC   | 48       | 52       |          | dB        |
|                  |  |  | 47       |          |          |           |
| $V_O$            | Output Voltage Swing                       | R <sub>L</sub> = ∞   | ±3.3     | ±3.5     |          |           |
|                  |  |  | ±3.18    |          |          | V         |
|                  |  | $R_L = 100\Omega$  | ±3.2     | ±3.5     |          | V         |
|                  |  |  | ±3.12    |          |          |           |
| $I_{O}$          | Linear Output Current                      | V <sub>OUT</sub> ≤ 80 mV                                   | ±55      | ±90      |          | mA        |
| $I_S$            | Supply Current (Enabled)                   | $\overline{\text{DIS}} = 2\text{V}, R_{\text{L}} = \infty$ |          | 11.5     | 12.5     |           |
|                  |  |  |          |          | 13.7     | mA        |
|                  | Supply Current (Disabled)                  | $\overline{\rm DIS}$ = 0.8V, R <sub>L</sub> = $\infty$     |          | 0.25     | 0.9      | ША        |
|                  |  |  |          |          | 0.925    |           |
| $R_F \& R_G$     | Internal R <sub>F</sub> and R <sub>G</sub> |  | 375      | 465      | 563      | Ω         |
| $R_{\text{OUT}}$ | Closed Loop Output Resistance              | DC   |          | 0.05     |          | Ω         |
| $R_{\text{IN+}}$ | Input Resistance                           |  |          | 1        |          | $M\Omega$ |
| C <sub>IN+</sub> | Input Capacitance                          |  |          | 1        |          | pF        |
| Enable/Dis       | sable Performance (Disabled Low            | ·)   | •        |          |          |           |
| T <sub>ON</sub>  | Enable Time                                |  |          | 10       |          | ns        |
| T <sub>OFF</sub> | Disable Time                               |  |          | 10       |          | ns        |
|                  | Output Glitch                              |  |          | 50       |          | $mV_{PP}$ |
| V <sub>IH</sub>  | Enable Voltage                             | DIS ≥ V <sub>IH</sub>                                      | 2.0      |          |          | V         |
| V <sub>IL</sub>  | Disable Voltage                            | <del>DIS</del> ≤ V <sub>IL</sub>                           |          |          | 0.8      |           |
| I <sub>IH</sub>  | Disable Input Bias Current, High           | DIS = V <sup>+</sup> , (Note 7)                            |          | -1       | ±50      | μA        |
| I <sub>IL</sub>  | Disable Input Bias Current, Low            | DIS = 0V (Note 7)  | 0        | -100     | -350     | μA        |
| l <sub>oz</sub>  | Disabled Output Leakage                    | $A_V = +1, V_{OUT} = \pm 1.8V$                             |          | 0.2      | ±25      | μA        |
|                  | Current                                    |  |          |          | ±50      |           |

**Note 1:** Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not guaranteed. For guaranteed specifications, see the Electrical Characteristics tables.

Note 2: Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that  $T_J = T_A$ . No guarantee of parametric performance is indicated in the electrical tables under conditions of internal self-heating where  $T_J > T_A$ . Min/Max ratings are based on production testing unless otherwise specified.

Note 3: The maximum output current ( $I_{OUT}$ ) is determined by device power dissipation limitations.

Note 4: Human body model: 1.5 k $\Omega$  in series with 100 pF. Machine model: 0 $\Omega$  in series with 200 pF.

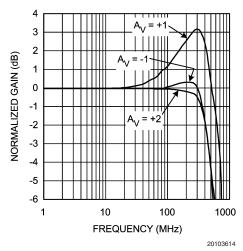
Note 5: Slew Rate is the average of the rising and falling edges.

Note 6: Typical numbers are the most likely parametric norm. Bold numbers refer to over temperature limits.

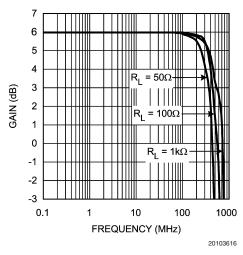
Note 7: Negative current implies current flowing out of the device.

# **Typical Performance Characteristics** $(T_A = 25^{\circ}C, V_S = \pm 5V, R_L = 100\Omega, A_V = +2, V_{OUT} = 0.5 V_{PP};$ Unless Specified).

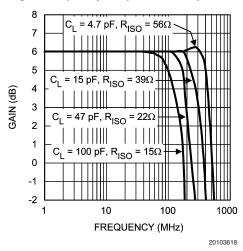
#### Small Signal Frequency Response vs. Gain



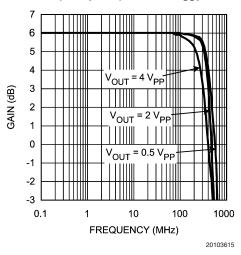
#### Small Signal Frequency Response vs. R<sub>LOAD</sub>



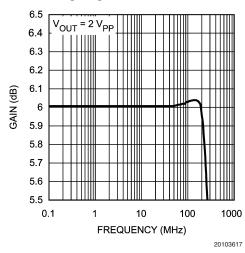
#### Small Signal Frequency Response vs. Capacitive Load



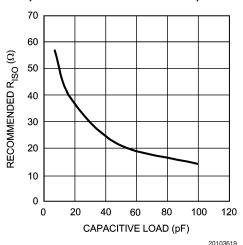
#### Frequency Response vs. V<sub>OUT</sub>



#### Large Signal Gain Flatness

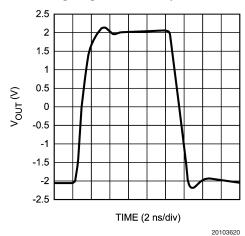


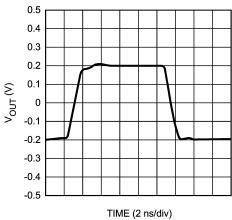
#### Series Output Isolation Resistance vs. Capacitive Load



# **Typical Performance Characteristics** ( $T_A = 25^{\circ}C$ , $V_S = \pm 5V$ , $R_L = 100\Omega$ , $A_V = +2$ , $V_{OUT} = 0.5 V_{PP}$ ; Unless Specified). (Continued)



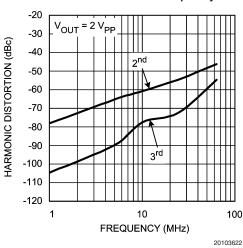




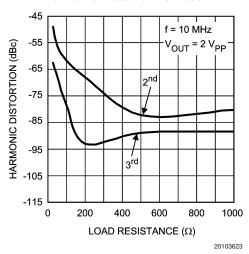
**Small Signal Pulse Response** 

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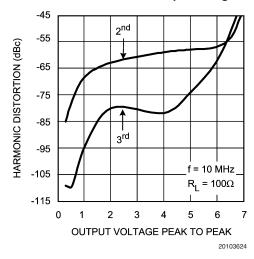
#### Harmonic Distortion vs. Frequency



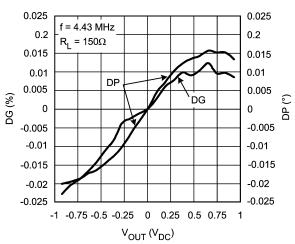
#### Harmonic Distortion vs. Load



#### Harmonic Distortion vs. Output Voltage

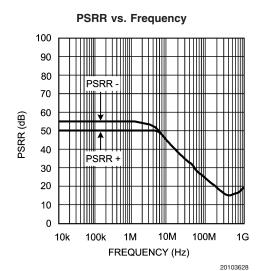


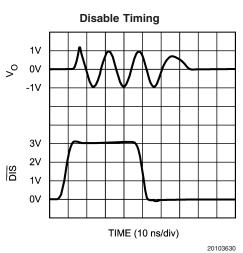
#### DG/DP



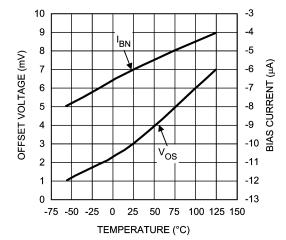
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# **Typical Performance Characteristics** ( $T_A = 25^{\circ}C$ , $V_S = \pm 5V$ , $R_L = 100\Omega$ , $A_V = +2$ , $V_{OUT} = 0.5 V_{PP}$ ; Unless Specified). (Continued)





#### DC Errors vs. Temperature (A Typical Unit, (Note 7))



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# Disable Output Glitch 20 mV -20 mV -40 mV 3V 2V 1V 0V TIME (10 ns/div)

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# **Application Section**

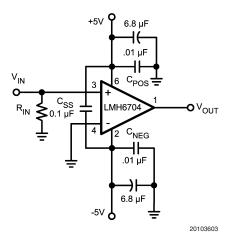


FIGURE 1. Recommended Gain of +2 Circuit

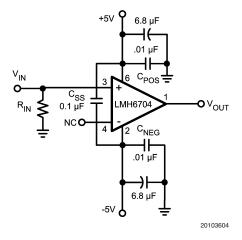


FIGURE 2. Recommended Gain of +1 Circuit

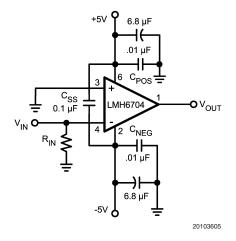


FIGURE 3. Recommended Gain of -1 Circuit

#### **GENERAL INFORMATION**

The LMH6704 is a high speed current feedback Programmable Gain Buffer (PGB), optimized for very high speed and low distortion. With its internal feedback and gain-setting resistors the LMH6704 offers excellent AC performance while simplifying board layout and minimizing the affects of layout related parasitic components. The LMH6704 has no internal ground reference so single or split supply configurations are both equally useful.

#### SETTING THE CLOSED LOOP GAIN

The LMH6704 is a current feedback amplifier with on-chip  $R_F=R_G=465\Omega$ . As such it can be configured with an  $A_V=+2$ ,  $A_V=+1$ , or an  $A_V=-1$  by connecting pins 3 and 4 as described in the chart below.

| GAIN A <sub>v</sub> | Input Connections     |                   |  |  |
|---------------------|-----------------------|-------------------|--|--|
| GAIN A <sub>V</sub> | Non-Inverting (Pin 3) | Inverting (Pin 4) |  |  |
| -1 V/V              | Ground                | Input Signal      |  |  |
| +1 V/V              | Input Signal          | NC (Open)         |  |  |
| +2 V/V              | Input Signal          | Ground            |  |  |

The gain accuracy of the LMH6704 is accurate and guaranteed over temperature to within  $\pm 1\%$ . The internal gain setting resistors,  $R_{\text{F}}$  and  $R_{\text{G}}$ , match very well. The LMH6704 architecture takes advantage of the fact that the internal gain setting resistors track each other well over a wide range of temperature and process variation to keep the overall gain constant, despite the fact that the individual resistors have nominal temperature drifts. Therefore, using external resistors in series with  $R_{\text{G}}$  to change the gain will result in poor gain accuracy over temperature.

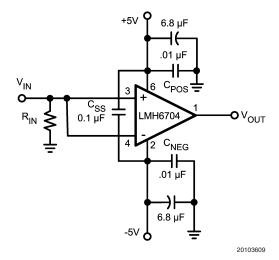


FIGURE 4. Alternate Unity Gain Configuration

# **Application Section** (Continued)

#### **UNITY GAIN COMPENSATION**

With a current feedback PGB like the LMH6704, the feedback resistor is a compromise between the value needed for stability at unity gain and the optimized value needed at a gain of two. In standard open-loop current feedback operational amplifiers the feedback resistor,  $R_{\rm F}$ , is external and its value can be adjusted to match the required gain. Since the feedback resistor is integrated in the LMH6704, it is not possible to adjust it's value. However, we can employ the circuit shown in *Figure 4*. This circuit modifies the noise gain of the amplifier to eliminate the peaking associated with using the circuit shown in *Figure 2*. The frequency response is shown in *Figure 5*. The decreased peaking does come at a price as the output referred voltage noise density increases by a factor of 1.1.

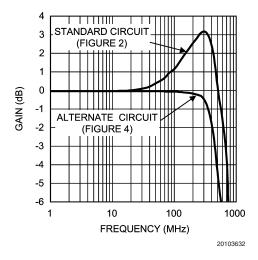


FIGURE 5. Unity Gain Frequency Response

#### **OUTPUT VOLTAGE NOISE**

Open-loop operational amplifiers specify three input referred noise parameters: input voltage noise, non-inverting input current noise, and inverting input current noise. These specifications are used to calculate the total voltage noise produced at the output of the amplifier. The LMH6704 is a closed loop amplifier with internal resistors, thus only the non-inverting input current noise flows through external components. All other noise sources are internal to the part. There are four possible values for the noise at the output depending on the gain configuration as shown in *Table 1*. For more information on calculating noise in current feedback amplifiers see Application Notes OA-12 and AN104 available at www.national.com.

The total noise voltage at the output can be calculated using the following formula:

For example, if an  $A_V=+2$  configuration is used with a source impedance of  $37.5\Omega$  (parallel combination of  $75\Omega$  source and  $75\Omega$  termination impedances), where "I $_{BN}$ " is  $18.5 p A/\sqrt{Hz}$  and the output referred voltage noise (excluding non-inverting input noise current) can be found in Table 1 below. The total noise (E $_O$ ) at the output can be calculated as:

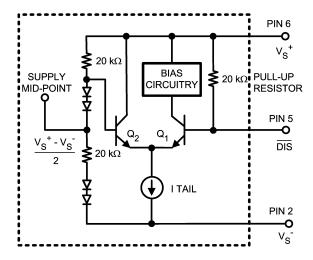
 $E_0 = \sqrt{(16E-21*37.5 + (18.5 \text{ pA}*37.5)^2)*2^2 + (10.5 \text{ nV})^2} = 10.6 \text{ nV}/\sqrt{\text{Hz}}$ 

TABLE 1. Measured Output Noise Voltage

| Gain (A <sub>V</sub> ) | Output Referred Voltage Noise (nV/ √Hz ), excluding non-inverting noise current |
|------------------------|---|
| +2                     | 10.5  |
| +1                     | 9.3   |
| +1, alternate          | 10.5  |
| method shown in        |   |
| Figure 4               |   |
| -1                     | 10.5  |

Note: f ≥ 100 kHz

#### **ENABLE/DISABLE**



NOTE: PINS 2, 5, 6 ARE EXTERNAL

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FIGURE 6. DIS Pin Simplified Schematic

The LMH6704 has a TTL logic compatible disable function. Apply a logic low (<.8V) to the DS pin and the LMH6704 is disabled. Apply a logic high (>2.0V), or let the pin float and the LMH6704 is enabled. Voltage, not current, at the Disable pin (DS) determines the enable/disable state. Care must be exercised to prevent the disable pin voltage from going more than .8V below the midpoint of the supply voltages (0V with split supplies, V+/2 with single supply biasing). Doing so could cause transistor Q1 to Zener resulting in damage to the disable circuit (See *Figure 6* or the simplified internal schematic diagram). The core amplifier is unaffected by this, but the disable operation could become permanently slower as a result.

 $E_{\rm O} = \sqrt{(4kTR_{\rm SOURCE} + (I_{\rm BN} * R_{\rm SOURCE})^2)} * G_{\rm N}^2 + (0UTPUT\,REFERRED\,NOISE\,VOLTAGE)^2, Where \ G_{\rm N} = Noise Gain and 4kT = 16E-21 Joules @ Room Temperature$ 

# Application Section (Continued)

Disabled, the LMH6704 inputs and output become high impedances. While disabled the LMH6704 quiescent current is approximately 250  $\mu A.$  Because of the pull up resistor on the disable circuit, the  $I_{\rm CC}$  and  $I_{\rm EE}$  currents (positive and negative supply currents respectively) are not balanced in the disabled state. The positive supply current ( $I_{\rm CC}$ ) is approximately 350  $\mu A$  while the negative supply current ( $I_{\rm EE}$ ) is only 250  $\mu A.$  The remaining  $I_{\rm EE}$  current of 100  $\mu A$  flows through the disable pin.

The disable function can be used to create analog switches or multiplexers. Implement a single analog switch with one LMH6704 positioned between an input and output. Create an analog multiplexer with several LMH6704's. Use the circuit shown in for multiplexer applications because there is no RG to shunt signals to ground.

#### **EVALUATION BOARDS**

National Semiconductor provides the following evaluation boards as a guide for high frequency layout and as an aid in device testing and characterization. Many of the datasheet plots were measured with these boards.

| Device    | Package | <b>Evaluation Board</b> |
|-----------|---------|-------------------------|
|           |         | Part Number             |
| LMH6704MA | SOIC-8  | CLC730227               |
| LMH6704MF | SOT23-6 | CLC730216               |

An evaluation board is shipped upon request when a sample order is placed with National Semiconductor.

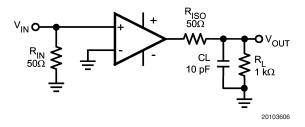


FIGURE 7. Decoupling Capacitive Loads

#### **DRIVING CAPACITIVE LOADS**

Capacitive output loading applications will benefit from the use of a series output resistor  $R_{\rm ISO}.$  Figure 7 shows the use of a series output resistor,  $R_{\rm ISO}.$  to stabilize the amplifier output under capacitive loading. Capacitive loads of 5 to 120 pF are the most critical, causing ringing, frequency response peaking and possible oscillation. The chart "Suggested  $R_{\rm ISO}$  vs. Cap Load" gives a recommended value for selecting a series output resistor for mitigating capacitive loads. The values suggested in the charts are selected for .5 dB or less of peaking in the frequency response. This gives a good compromise between settling time and bandwidth. For applications where maximum frequency response is needed and some peaking is tolerable, the value of  $R_{\rm ISO}$  can be reduced slightly from the recommended values.

#### LAYOUT CONSIDERATIONS

Whenever questions about layout arise, use the evaluation board as a guide. The CLC730216 is the evaluation board supplied with samples of the LMH6704. To reduce parasitic capacitances ground and power planes should be removed near the input and output pins. For long signal paths controlled impedance lines should be used, along with impedance matching elements at both ends. Bypass capacitors should be placed as close to the device as possible. Bypass capacitors from each rail to ground are applied in pairs. The larger electrolytic bypass capacitors can be located farther from the device, the smaller ceramic capacitors should be placed as close to the device as possible. In Figure 1, Figure 2, and Figure 3  $C_{\rm SS}$  is optional, but is recommended for best second order harmonic distortion. Another option to using  $C_{\rm SS}$  is to use pairs of 0.01  $\mu F$  and 0.1  $\mu F$  ceramic capacitors for each supply bypass.

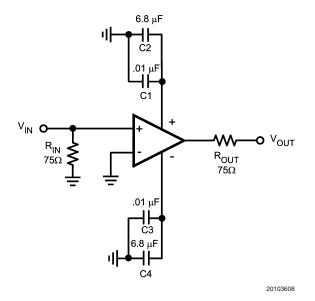


FIGURE 8. Typical Video Application

#### **VIDEO PERFORMANCE**

The LMH6704 has been designed to provide excellent performance with production quality video signals in a wide variety of formats such as HDTV and High Resolution VGA. NTSC and PAL performance is nearly flawless with DG of 0.02% and DP of 0.02°. Best performance will be obtained with back terminated loads. The back termination reduces reflections from the transmission line and effectively masks transmission line and other parasitic capacitances from the amplifier output stage. Figure 8 shows a typical configuration for driving a  $75\Omega$  Cable. The amplifier is configured for a gain of two to make up for the 6 dB of loss in  $R_{OUT}$ .

#### **POWER DISSIPATION**

Follow these steps to determine the Maximum power dissipation for the LMH6704:

- 1. Calculate the quiescent (no-load) power:  $P_{AMP} = I_{CC^*} (V_S)$ , where  $V_S = V^+ V^-$
- 2. Calculate the RMS power dissipated in the output stage:  $P_D$  (rms) = rms ( $(V_S V_{OUT})^*I_{OUT}$ ), where  $V_{OUT}$  and  $I_{OUT}$  are the voltage and current across the external load and  $V_S$  is the total supply current
- 3. Calculate the total RMS power:  $P_T = P_{AMP} + P_D$

The maximum power that the LMH6704, package can dissipate at a given temperature can be derived with the following equation:

# **Application Section** (Continued)

 $P_{MAX}=(150^{\circ}-T_{AMB})/~\theta_{JA},$  where  $T_{AMB}=$  Ambient temperature (°C) and  $\theta_{JA}=$  Thermal resistance, from junction to ambient, for a given package (°C/W). For the SOT23-6 package  $\theta_{JA}$  is 187°C/W.

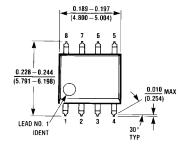
#### **ESD PROTECTION**

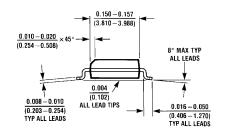
The LMH6704 is protected against electrostatic discharge (ESD) on all pins. The LMH6704 will survive 2000V Human Body model and 200V Machine model events. Input and Output pins have ESD diodes to either supply pin (V<sup>+</sup> and

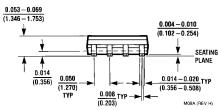
V<sup>-</sup>) which are reverse biased and essentially have no effect under most normal operating conditions. There are occasions, however, when the ESD diodes will be evident. If the LMH6704 is driven by a large signal while the device is powered down, the ESD diodes might enter forward operating region and conduct. The current that flows through the ESD diodes will either exit the chip through the supply pins or will flow through the device, hence it is possible to inadvertently power up the LMH6704 with a large signal applied to the input pins. Shorting the power pins to each other will prevent the chip from being powered up through the input.

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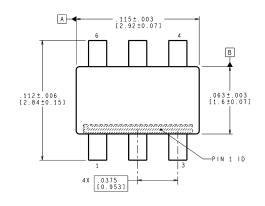
# **Physical Dimensions** inches (millimeters) unless otherwise noted

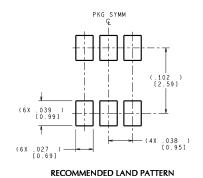


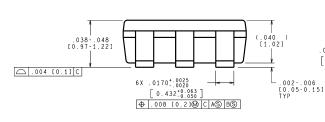


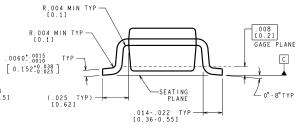


8-Pin SOIC **NS Package Number M08A** 









CONTROLLING DIMENSION IS INCH VALUES IN [ ] ARE MILLIMETERS

MF06A (Rev B)

6-Pin SOT23 **NS Package Number MF06A** 

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