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256K x 8 CMOS FLASH MEMORY
WITH LPC INTERFACE

GENERAL DESCRIPTION

The W49V002 is a 2-megabit, 3.3V-volt only CMOS flash memory organized as 256K × 8 bits. The device can be programmed and erased in-system with a standard 3.3V power supply. A 12-volt V_{PP} is not required. The unique cell architecture of the W49V002 results in fast program/erase operations with extremely low current consumption. This device can operate at two modes, Programmer bus interface mode and LPC bus interface mode. As in the Programmer interface mode, it acts like the traditional flash but with a multiplexed address inputs. But in the LPC interface mode, this device complies with the Intel LPC specification 1.0. The device can also be programmed and erased using standard EPROM programmers.

FEATURES

- Single 3.3-volt operations:
  - 3.3-volt Read
  - 3.3-volt Erase
  - 3.3-volt Program
- Fast Program operation:
  - Byte-by-Byte programming: 50 μS (typ.)
- Fast Erase operation: 150 mS (typ.)
- Endurance: 10K cycles (typ.)
- Twenty-year data retention
- Hardware data protection
- One 16K bytes Boot Block with lockout protection
- Two 8K bytes Parameter Blocks
- Four Main Memory Blocks (with 32K bytes, 64K bytes, 64K bytes, 64K bytes each)
- Low power consumption
  - Active current: 25 mA (typ.)
  - Standby current: 20 μA (typ.)
- Automatic program and erase timing with internal V_{PP} generation
- End of program or erase detection
  - Toggle bit
  - Data polling
- Latched address and data
- TTL compatible I/O
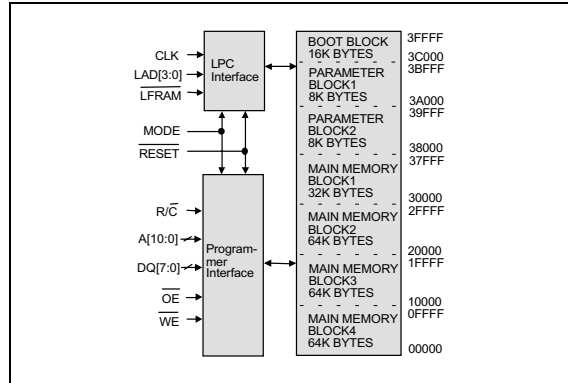- Available packages: 32-pin DIP and 32-pin TSOP and 32-pin-PLCC

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PIN CONFIGURATIONS
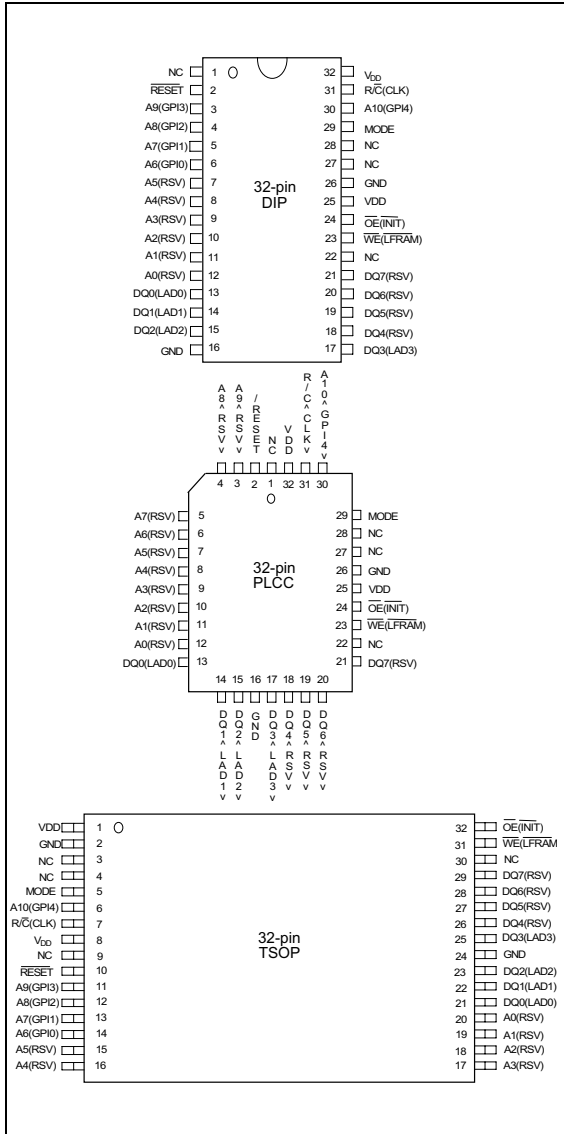
BLOCK DIAGRAM

PIN DESCRIPTION

SYMB	INTERFACE		PIN NAME
	PGM	LPC	
MODE	*	*	Interface Mode Selection
$\overline{\text{RESET}}$	*	*	Reset
$\overline{\text{INIT}}$		*	Initialize
CLK		*	CLK Input
GPI[4:0]		*	General Purpose Inputs
LAD[3:0]		*	Address/Data Inputs
$\overline{\text{LFRAM}}$		*	LPC Cycle Initial
R/$\overline{\text{C}}$	*		Row/Column Select
A[10:0]	*		Address Inputs
DQ[7:0]	*		Data Inputs/Outputs
$\overline{\text{OE}}$	*		Output Enable
$\overline{\text{WE}}$	*		Write Enable
V$_{DD}$	*	*	Power Supply
GND	*	*	Ground
RSV	*	*	Reserve Pins
NC	*	*	No Connection

FUNCTIONAL DESCRIPTION

Interface Mode Selection And Description

This device can be operated in two interface modes, one is Programmer interface mode, the other is LPC interface mode. The MODE pin of the device provides the control between these two interface modes. These interface modes need to be configured before power up or return from $\overline{RESET}$. When MODE pin is set to high state, the device is in the Programmer mode; while the MODE pin is set to low state(or leaved no connection), it is in the LPC mode. In Programmer mode, this device just behaves like traditional flash parts with 8 data lines. But the row and column address inputs are multiplexed. The row address are mapped to the higher internal address A[17:11]. And the column address are mapped to the lower internal address A[10:0]. For LPC mode, It complies with the LPC Interface Specification Revision 1.0. Through the LAD[3:0] and $\overline{LFRAM}$ to communicate with the system chipset .

Read(Write) Mode

In Programmer interface mode, the read(write) operation of the W49V002 is controlled by $\overline{OE}(\overline{WE})$. The $\overline{OE}(\overline{WE})$ is held low for the host to obtain(write) data from(to) the outputs(inputs). $\overline{OE}$ is the output control and is used to gate data from the output pins. The data bus is in high impedance state when $\overline{OE}$ is high. As in the LPC interface mode, the read or write is determined by the "bit 1 of CYCLE TYPER+DIR". Refer to the timing waveforms for further details.

Reset Operation

The $\overline{RESET}$ input pin can be used in some application. When $\overline{RESET}$ pin is at high state, the device is in normal operation mode. When $\overline{RESET}$ pin is at low state, it will halt the device and all outputs will be at high impedance state. As the high state re-asserted to the $\overline{RESET}$ pin, the device will return to read or standby mode, it depends on the control signals.

Boot Block Operation

There is a 16K-byte boot block in this device, which can be used to store boot codes. It is located in the first 16K bytes of the memory with the address range from 3C000(hex) to 3FFFF(hex).

See Command Codes for Boot Block Lockout Enable for the specific code. Once this feature is set the data for the designated block cannot be erased or programmed (programming lockout), other memory locations can be changed by the regular programming method.

In order to detect whether the boot block feature is set on the 16K-bytes block or not, users can perform software command sequence: enter the product identification mode (see Command Codes for Identification/Boot Block Lockout Detection for specific code), and then read from address 0002(hex). If the DQ0 of output data is "1," the boot block programming lockout feature will be activated; if the DQ0 of output data is "0," the lockout feature will be inactivated and the block can be erased/programmed.

To return to normal operation, perform a three-byte command sequence (or an alternate single-byte command) to exit the identification mode. For the specific code, see Command Codes for Identification/Boot Block Lockout Detection.

Chip Erase Operation

The chip-erase mode can be initiated by a six-byte command sequence. After the command loading cycle, the device enters the internal chip erase mode, which is automatically timed and will be

completed within fast 100 mS (typical). The host system is not required to provide any control or timing during this operation. If the boot block programming lockout is activated, only the data in the other memory blocks will be erased to FF(hex) while the data in the boot block will not be erased (remains as the same state before the chip erase operation). The entire memory array will be erased to FF(hex) by the chip erase operation if the boot block programming lockout feature is not activated. The device will automatically return to normal read mode after the erase operation completed. Data polling and/or Toggle Bits can be used to detect end of erase cycle.

Sector Erase Operation

The six sectors, two main memory and four parameter blocks, can be erased individually by initiating a six-byte command sequence. Sector address is latched on the falling $\overline{\text{WE}}$ edge of the sixth cycle, while the 30(hex) data input command is latched at the rising edge of $\overline{\text{WE}}$. After the command loading cycle, the device enters the internal sector erase mode, which is automatically timed and will be completed within fast 100 mS (typical). The host system is not required to provide any control or timing during this operation. The device will automatically return to normal read mode after the erase operation completed. Data polling and/or Toggle Bits can be used to detect end of erase cycle.

Whether the boot block is locked or not, only the main memory and parameter blocks will be erased by the execution of sector erase operation. Boot block can only be erased by chip erase command under lock out feature inactivated.

Program Operation

The W49V002 is programmed on a byte-by-byte basis. Program operation can only change logical data "1" to logical data "0." The erase operation, which changed entire data in main memory and/or boot block from "0" to "1", is needed before programming.

The program operation is initiated by a 4-byte command cycle (see Command Codes for Byte Programming). The device will internally enter the program operation immediately after the byte-program command is entered. The internal program timer will automatically time-out (100 μS max. - T_{BP}) once it is completed and then return to normal read mode. Data polling and/or Toggle Bits can be used to detect end of program cycle.

Hardware Data Protection

The integrity of the data stored in the W49V002 is also hardware protected in the following ways:

(1) Noise/Glitch Protection: A $\overline{\text{WE}}$ pulse of less than 15 nS in duration will not initiate a write cycle.
(2) V_{DD} Power Up/Down Detection: The programming operation is inhibited when V_{DD} is less than 2.5V typical.
(3) Write Inhibit Mode: Forcing $\overline{\text{OE}}$ low or $\overline{\text{WE}}$ high will inhibit the write operation. This prevents inadvertent writes during power-up or power-down periods.
(4) V_{DD} power-on delay: When V_{DD} has reached its sense level, the device will automatically time-out 5 mS before any write (erase/program) operation.

Data Polling (DQ7)- Write Status Detection

The W49V002 includes a data polling feature to indicate the end of a program or erase cycle. When the W49V002 is in the internal program or erase cycle, any attempts to read DQ_7 of the last byte loaded will receive the complement of the true data. Once the program or erase cycle is completed, DQ_7 will show the true data. Note that DQ_7 will show logical "0" during the erase cycle, and when erase cycle has been completed it becomes logical "1" or true data.

Toggle Bit (DQ6)- Write Status Detection

In addition to data polling, the W49V002 provides another method for determining the end of a program cycle. During the internal program or erase cycle, any consecutive attempts to read DQ_6 will produce alternating 0's and 1's. When the program or erase cycle is completed, this toggling between 0's and 1's will stop. The device is then ready for the next operation.

Memory Address Map

There are 8M bytes space reserved for BIOS Addressing. The ROM will respond to 256K byte pages whenever the memory address rang is within the top 4M bytes and bottom 128K bytes.

The 32bit address space is as below:

Block	Address Range
4M Byte BIOS ROM	FFFF,FFFFh:FFC0,0000h
128K Byte BIOS ROM	000F,FFFFh:000E,0000h
Registers	FFBC,0100h

General Purpose Inputs Register

This register reads the GPI[4:0] pins on the W49V002.This is a pass-through register which can read via memory address FFBC0100(hex). Since it is pass-through register, there is no default value.

Bit	Function
7-5	Reserved
4	Read GPI4 pin status
3	Read GPI3 pin status
2	Read GPI2 pin status
1	Read GPI1 pin status
0	Read GPI0 pin status

Product Identification

The product ID operation outputs the manufacturer code and device code. Programming equipment automatically matches the device with its proper erase and programming algorithms.

The manufacturer and device codes can be accessed by software or hardware operation. In the software access mode, a six-byte (or JEDEC 3-byte) command sequence can be used to access the product ID. A read from address 0000(hex) outputs the manufacturer code, DA(hex). A read from address 0001(hex) outputs the device code, B0(hex)." The product ID operation can be terminated by a three-byte command sequence or an alternate one-byte command sequence (see Command Definition table).

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TABLE OF OPERATING MODES

Operating Mode Selection - Programmer Mode

($V_{HH} = 12V \pm 5\%$)

MODE	PINS				
	$\overline{OE}$	$\overline{WE}$	$\overline{RESET}$	ADDRESS	DQ.
Read	VIL	VIH	VIH	AIN	Dout
Write	VIH	VIL	VIH	AIN	Din
Standby	X	X	VIL	X	High Z
Write Inhibit	VIL	X	VIH	X	High Z/DOUT
	X	VIH	VIH	X	High Z/DOUT
Output Disable	VIH	X	VIH	X	High Z

Operating Mode Selection - LPC Mode

Operation modes in LPC interface mode are determined by "cycle type" when it is selected. When it is not selected, its outputs (LAD[3:0]) will be disable. Please reference to the "Standard LPC Memory Cycle Definition".

TABLE OF COMMAND DEFINITION

COMMAND DESCRIPTION	NO. OF Cycles	1ST CYCLE Addr. Data	2ND CYCLE Addr. Data	3RD CYCLE Addr. Data	4TH CYCLE Addr. Data	5TH CYCLE Addr. Data	6TH CYCLE Addr. Data
Read	1	A_{IN} D_{OUT}					
Chip Erase	6	5555 AA	2AAA 55	5555 80	5555 AA	2AAA 55	5555 10
Sector Erase	6	5555 AA	2AAA 55	5555 80	5555 AA	2AAA 55	SA 30
Byte Program	4	5555 AA	2AAA 55	5555 A0	A_{IN} D_{IN}		
Boot Block Lockout	6	5555 AA	2AAA 55	5555 80	5555 AA	2AAA 55	5555 40
Product ID Entry	3	5555 AA	2AAA 55	5555 90			
Product ID Exit [1]	3	5555 AA	2AAA 55	5555 F0			
Product ID Exit [1]	1	XXXX F0					

Note: 1. The cycle means the write command cycle not the LPC clock cycle.

2. The Column Address / Row Address are mapped to the Low / High order Internal Address. i.e. Column Address A[10:0] are mapped to the internal A[10:0], Row Address A[6:0] are mapped to the internal A[17:11]

3. Address Format: A14–A0 (Hex); Data Format: DQ7-DQ0 (Hex)

4. Either one of the two Product ID Exit commands can be used.

5. SA : Sector Address

  SA = 3A000h to 3BFFFh for Parameter Block1

  SA = 38000h to 39FFFh for Parameter Block2

  SA = 30000h to 37FFFh for Main Memory Block1

  SA = 2XXXXh for Main Memory Block2

  SA = 1XXXXh for Main Memory Block3

  SA = 0XXXXh for Main Memory Block4

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STANDARD LPC MEMORY CYCLE DEFINITION

FIELD	NO. OF CLOCKS	DESCRIPTION
Start	1	"0000b" appears on LPC bus to indicate the initial
Cycle Type & Dir	1	"010Xb" indicates memory read cycle; while "011xb" indicates memory write cycle. "X" mean don't have to care.
TAR	2	Turned Around Time
Addr.	8	Address Phase for Memory Cycle. LPC supports the 32 bits address protocol. The addresses transfer most significant nibble first and least significant nibble last. (i.e. Address[31:28] on LAD[3:0] first , and Address[3:0] on LAD[3:0] last.)
Sync.	N	Synchronous to add wait state. "0000b" means Ready, "0101b" means Short Wait, "0110b" means Long Wait, "1001b" for DMA only, "1010b" means error, and other values are reserved.
Data	2	Data Phase for Memory Cycle. The data transfer least significant nibble first and most significant nibble last. (i.e. DQ[3:0] on LAD[3:0] first , then DQ[7:4] on LAD[3:0] last.)

Note: 1. For detail related LPC specification, please refer to Intel LPC spec. 1.0 or later.

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Command Codes for Byte Program

BYTE SEQUENCE	ADDRESS	DATA
0 Write	5555H	AAH
1 Write	2AAAH	55H
2 Write	5555H	A0H
3 Write	Programmed-Address	Programmed-Data

Byte Program Flow Chart

Byte Program
Command Flow

```
┌─────────────────┐
│  Load data AA   │
│       to        │
│  address 5555   │
└─────────────────┘
         │
         ▼
┌─────────────────┐
│  Load data 55   │
│       to        │
│  address 2AAA   │
└─────────────────┘
         │
         ▼
┌─────────────────┐
│  Load data A0   │
│       to        │
│  address 5555   │
└─────────────────┘
         │
         ▼
┌─────────────────┐
│  Load data Din  │
│       to        │
│  programmed-    │
│    address      │
└─────────────────┘
         │
         ▼
┌─────────────────┐
│   Pause $T_{BP}$ │
└─────────────────┘
         │
         ▼
┌─────────────────┐
│      Exit       │
└─────────────────┘
```
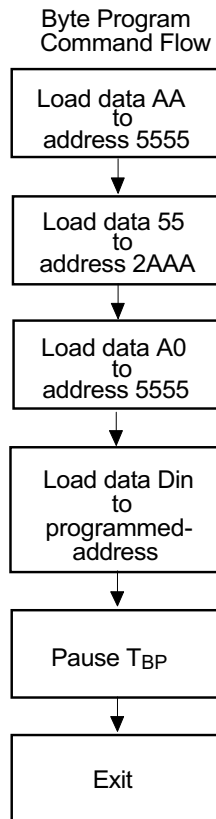
Notes for software program code:

Data Format: DQ7–DQ0 (Hex); XX = Don't Care

Address Format: A14–A0 (Hex)

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Command Codes for Chip Erase

BYTE SEQUENCE	ADDRESS	DATA
1 Write	5555H	AAH
2 Write	2AAAH	55H
3 Write	5555H	80H
4 Write	5555H	AAH
5 Write	2AAAH	55H
6 Write	5555H	10H

Chip Erase Acquisition Flow
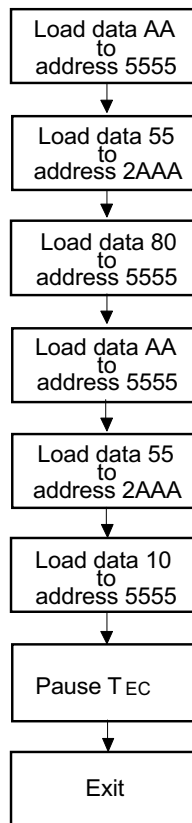
```
        ┌─────────────────┐
        │  Load data AA   │
        │       to        │
        │  address 5555   │
        └─────────────────┘
                 │
                 ▼
        ┌─────────────────┐
        │  Load data 55   │
        │       to        │
        │  address 2AAA   │
        └─────────────────┘
                 │
                 ▼
        ┌─────────────────┐
        │  Load data 80   │
        │       to        │
        │  address 5555   │
        └─────────────────┘
                 │
                 ▼
        ┌─────────────────┐
        │  Load data AA   │
        │       to        │
        │  address 5555   │
        └─────────────────┘
                 │
                 ▼
        ┌─────────────────┐
        │  Load data 55   │
        │       to        │
        │  address 2AAA   │
        └─────────────────┘
                 │
                 ▼
        ┌─────────────────┐
        │  Load data 10   │
        │       to        │
        │  address 5555   │
        └─────────────────┘
                 │
                 ▼
        ┌─────────────────┐
        │   Pause T EC    │
        └─────────────────┘
                 │
                 ▼
        ┌─────────────────┐
        │      Exit       │
        └─────────────────┘
```

Notes for chip erase:
Data Format: DQ7–DQ0 (Hex)
Address Format: A14–A0 (Hex)

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Command Codes for Sector Erase

BYTE SEQUENCE	ADDRESS	DATA
1 Write	5555H	AAH
2 Write	2AAAH	55H
3 Write	5555H	80H
4 Write	5555H	AAH
5 Write	2AAAH	55H
6 Write	SA*	30H

Sector Erase Acquisition Flow

```
┌─────────────────┐
│  Load data AA   │
│       to        │
│ address 5555    │
└────────┬────────┘
         ▼
┌─────────────────┐
│  Load data 55   │
│       to        │
│ address 2AAA    │
└────────┬────────┘
         ▼
┌─────────────────┐
│  Load data 80   │
│       to        │
│ address 5555    │
└────────┬────────┘
         ▼
┌─────────────────┐
│  Load data AA   │
│       to        │
│ address 5555    │
└────────┬────────┘
         ▼
┌─────────────────┐
│  Load data 55   │
│       to        │
│ address 2AAA    │
└────────┬────────┘
         ▼
┌─────────────────┐
│  Load data 30   │
│       to        │
│ address SA*     │
└────────┬────────┘
         ▼
┌─────────────────┐
│   Pause T_EC    │
└────────┬────────┘
         ▼
┌─────────────────┐
│      Exit       │
└─────────────────┘
```
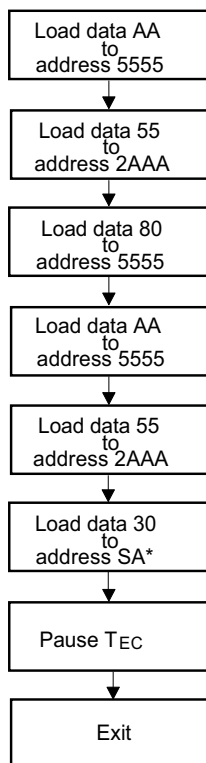
Notes for chip erase:

Data Format: DQ7–DQ0 (Hex)

Address Format: A14–A0 (Hex)

SA : Sector Address

SA = 3A000 to 3BFFF for Parameter Block1   SA = 2XXXX for Main Memory Block2

SA = 38000 to 39FFF for Parameter Block2   SA = 1XXXX for Main Memory Block3

SA = 30000 to 37FFF for Main Memory Block1   SA = 0XXXX for Main Memory Block4

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Command Codes for Product Identification and Boot Block Lockout Detection

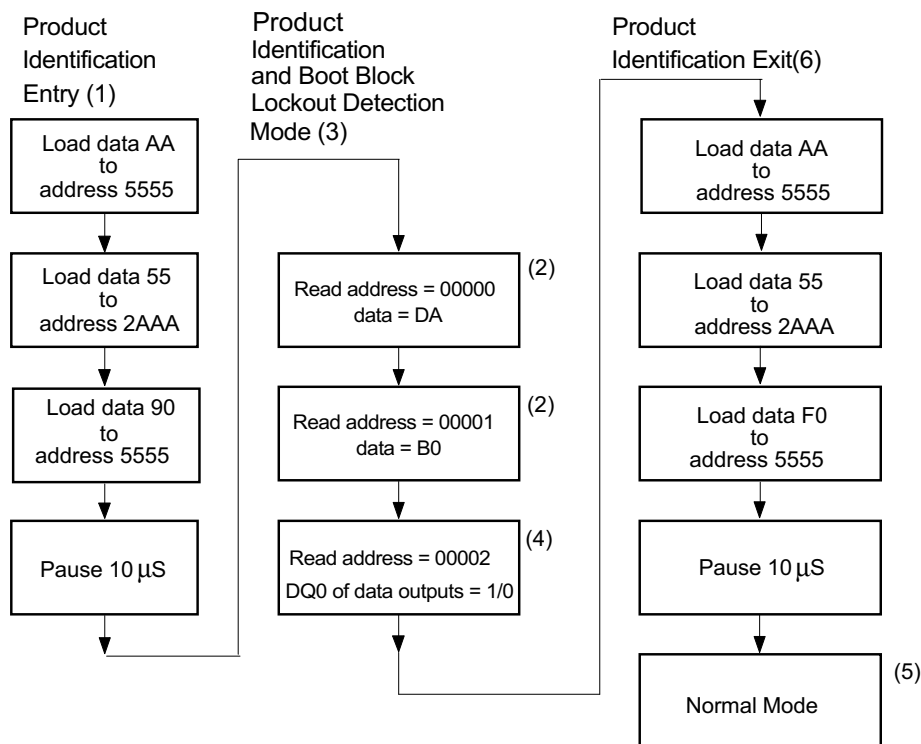| BYTE SEQUENCE	SOFTWARE PRODUCT IDENTIFICATION / BOOT BLOCK LOCKOUT DETECTION ENTRY		SOFTWARE PRODUCT IDENTIFICATION / BOOT BLOCK LOCKOUT DETECTION EXIT (6)	
	ADDRESS	DATA	ADDRESS	DATA
1 Write	5555	AA	5555H	AAH
2 Write	2AAA	55	2AAAH	55H
3 Write	5555	90	5555H	F0H
	Pause 10µS		Pause 10µS	

Software Product Identification and Boot Block Lockout Detection Acquisition Flow

Product Identification Entry (1)

Load data AA to address 5555

↓

Load data 55 to address 2AAA

↓

Load data 90 to address 5555

↓

Pause 10 µS

Product Identification and Boot Block Lockout Detection Mode (3)

Read address = 00000 data = DA (2)

↓

Read address = 00001 data = B0 (2)

↓

Read address = 00002 DQ0 of data outputs = 1/0 (4)

Product Identification Exit(6)

Load data AA to address 5555

↓

Load data 55 to address 2AAA

↓

Load data F0 to address 5555

↓

Pause 10 µS

↓

Normal Mode (5)

Notes for software product identification/boot block lockout detection:

(1) Data Format: DQ7−DQ0 (Hex); Address Format: A14−A0 (Hex)

(2) A1−A17 = V$_{IL}$; manufacture code is read for A0 = V$_{IL}$; device code is read for A0 = V$_{IH}$.

(3) The device does not remain in identification and boot block lockout detection mode if power down.

(4) If the DQ0 of output data is "1," the boot block programming lockout feature is activated; if the DQ0 of output data "0," the lockout feature is inactivated and the block can be programmed.

(5) The device returns to standard operation mode.

(6) Optional 1-write cycle (write F0 hex at XXXX address) can be used to exit the product identification/boot block lockout detection.

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Command Codes for Boot Block Lockout Enable

BYTE SEQUENCE	BOOT BLOCK LOCKOUT FEATURE SET	
	ADDRESS	DATA
1 Write	5555H	AAH
2 Write	2AAAH	55H
3 Write	5555H	80H
4 Write	5555H	AAH
5 Write	2AAAH	55H
6 Write	5555H	40H
Pause = T_{BP}		

Boot Block Lockout Enable Acquisition Flow

Boot Block Lockout
Feature Set Flow

Load data AA
to
address 5555

Load data 55
to
address 2AAA

Load data 80
to
address 5555

Load data AA
to
address 5555

Load data 55
to
address 2AAA

Load data 40
to
address 5555

Pause T_{BP}

Exit
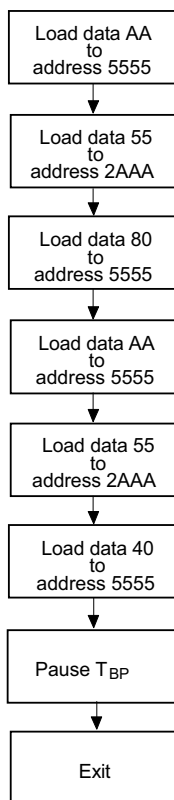
Notes for boot block lockout enable:
Data Format: DQ7−DQ0 (Hex)
Address Format: A14−A0 (Hex)

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DC CHARACTERISTICS

Absolute Maximum Ratings

PARAMETER	RATING	UNIT
Power Supply Voltage to V$_{SS}$ Potential	-0.5 to +4.1	V
Operating Temperature	0 to +70	°C
Storage Temperature	-65 to +150	°C
D.C. Voltage on Any Pin to Ground Potential	-0.5 to V$_{DD}$ +0.5	V
Transient Voltage (<20 nS) on Any Pin to Ground Potential	-1.0 to V$_{DD}$ +0.5	V

Note: Exposure to conditions beyond those listed under Absolute Maximum Ratings may adversely affect the life and reliability of the device.

DC Operating Characteristics

(V$_{DD}$ = 3.3V ±10%, V$_{GND}$= 0V, T$_A$ = 0 to 70° C)

PARAMETER	SYM.	TEST CONDITIONS	LIMITS			UNIT
			MIN.	TYP.	MAX.	
Power Supply Current	I$_{CC}$	In Read or Write mode, all DQs open Address inputs = 3.0V/0V, at f = 3 MHz	-	20	30	mA
Input Leakage Current	I$_{LI}$	V$_{IN}$ = GND to V$_{DD}$	-	-	10	μA
Output Leakage Current	I$_{LO}$	V$_{OUT}$ = GND to V$_{DD}$	-	-	10	μA
Input Low Voltage	V$_{IL}$	-	-0.3	-	0.8	V
Input High Voltage	V$_{IH}$	-	2.0	-	V$_{DD}$ +0.5	V
Output Low Voltage	V$_{OL}$	I$_{OL}$ = 2.1 mA	-	-	0.45	V
Output High Voltage	V$_{OH}$	I$_{OH}$ = -0.1mA	2.4	-	-	V

AC CHARACTERISTICS

AC Test Conditions

PARAMETER	CONDITIONS
Input Pulse Levels	0V to 0.9VDD
Input Rise/Fall Time	< 5 nS
Input/Output Timing Level	1.5V/1.5V
Output Load	1 TTL Gate and C$_L$ = 30 pF

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AC Test Load and Waveform

+3.3V

1.8KΩ

D_{OUT}

30 pF
(Including Jig and
Scope)

1.3KΩ

Input

3V

0V

1.5V

Test Point

Output

1.5V

Test Point

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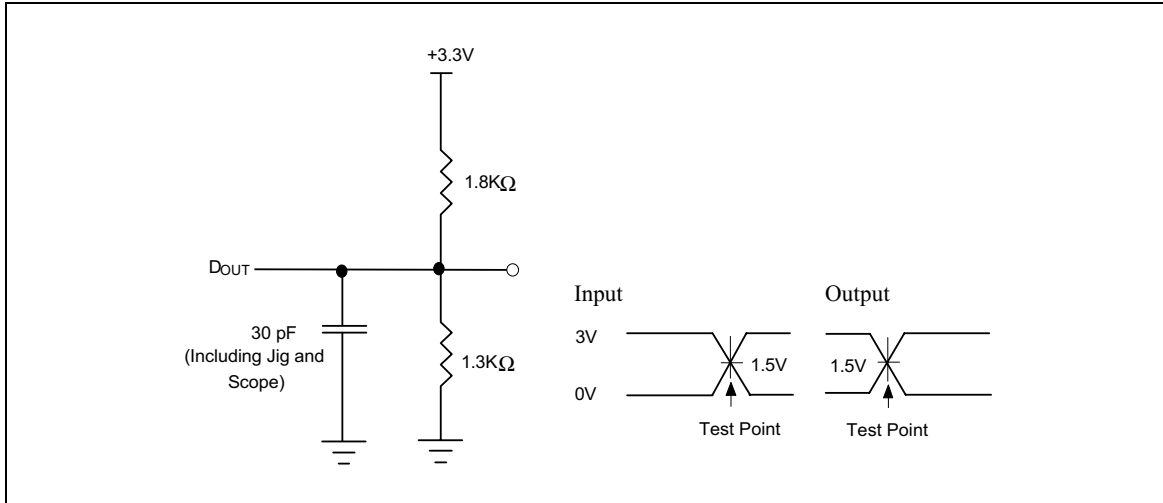
AC Characteristics, continued

Read Cycle Timing Parameters

(V_{DD} = 3.3V ±10%, V_{GND} = 0V, T_A = 0 to 70° C)

PARAMETER	SYM.	W49V002		UNIT
		MIN.	MAX.	
Read Cycle Time	T_{RC}	300	-	nS
Row / Column Address Set Up Time	T_{AS}	50	-	nS
Row / Column Address Hold Time	T_{AH}	50	-	nS
Address Access Time	T_{AA}	-	150	nS
Output Enable Access Time	T_{OE}	-	75	nS
$\overline{OE}$ Low to Active Output	T_{OLZ}	0	-	nS
$\overline{OE}$ High to High-Z Output	T_{OHZ}	-	35	nS
Output Hold from Address Change	T_{OH}	0	-	nS

Write Cycle Timing Parameters

PARAMETER	SYMBOL	MIN.	TYP.	MAX.	UNIT
Reset Time	T_{RST}	1	-	-	µS
Address Setup Time	T_{AS}	50	-	-	nS
Address Hold Time	T_{AH}	50	-	-	nS
$R/\overline{C}$ to Write Enable High Time	T_{CWH}	50	-	-	nS
$\overline{WE}$ Pulse Width	T_{WP}	100	-	-	nS
$\overline{WE}$ High Width	T_{WPH}	100	-	-	nS
Data Setup Time	T_{DS}	50	-	-	nS
Data Hold Time	T_{DH}	50	-	-	nS
$\overline{OE}$ Hold Time	T_{OEH}	0	-	-	nS
Byte programming Time	T_{BP}	-	50	100	µS
Erase Cycle Time	T_{EC}	-	0.15	0.2	S

Note: All AC timing signals observe the following guidelines for determining setup and hold times:
  (a) High level signal's reference level is input high and (b) low level signal's reference level is input low.
  Ref. to the AC testing condition.

Data Polling and Toggle Bit Timing Parameters

PARAMETER	SYM	W49V002		UNIT
		MIN.	MAX.	
$\overline{OE}$ to Data Polling Output Delay	T_{OEP}	-	40	nS
$\overline{OE}$ to Toggle Bit Output Delay	T_{OET}	-	40	nS

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TIMING WAVEFORMS FOR PROGRAMMER INTERFACE MODE

Read Cycle Timing Diagram
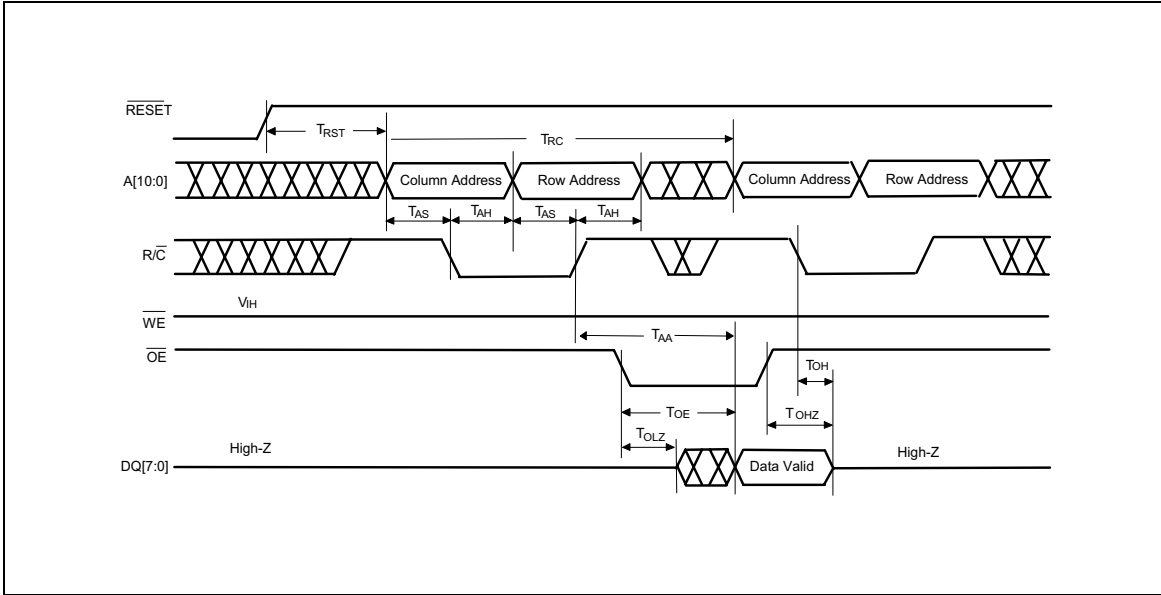
Write Cycle Timing Diagram

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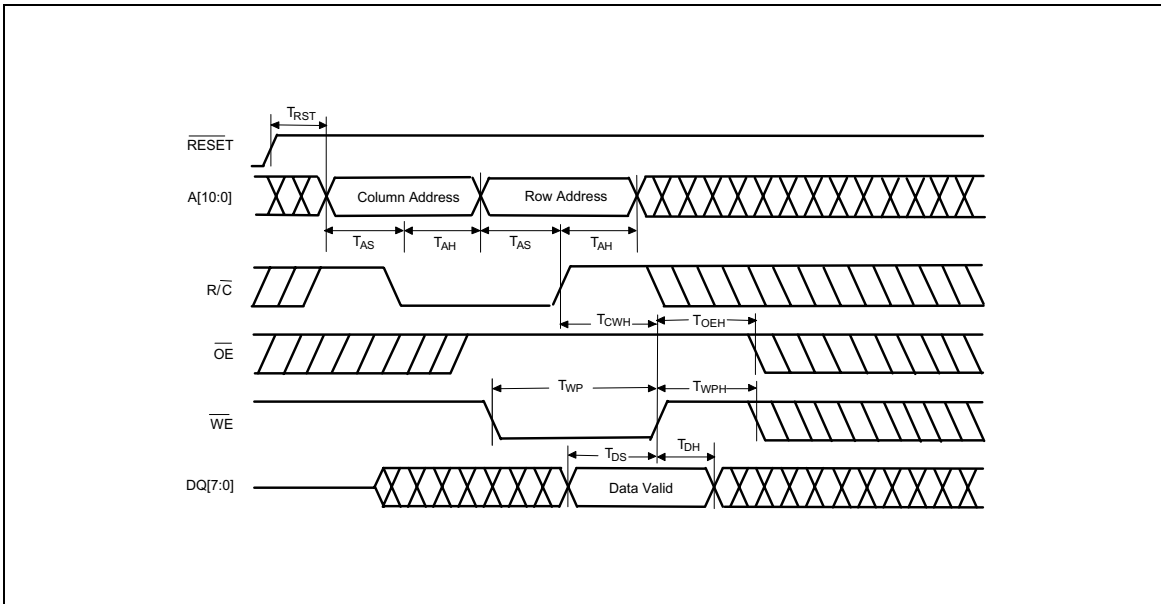
Timing Waveforms for Programmer Interface Mode, continued

Program Cycle Timing Diagram

Note: The internal address A[17:0] are converted from external Column/Row address.
Column/Row Address are mapped to the Low/High order internal address.
i.e. Column Address A[10:0] are mapped to the internal A[10:0],
Row Address A[6:0] are mapped to the internal A[17:11].
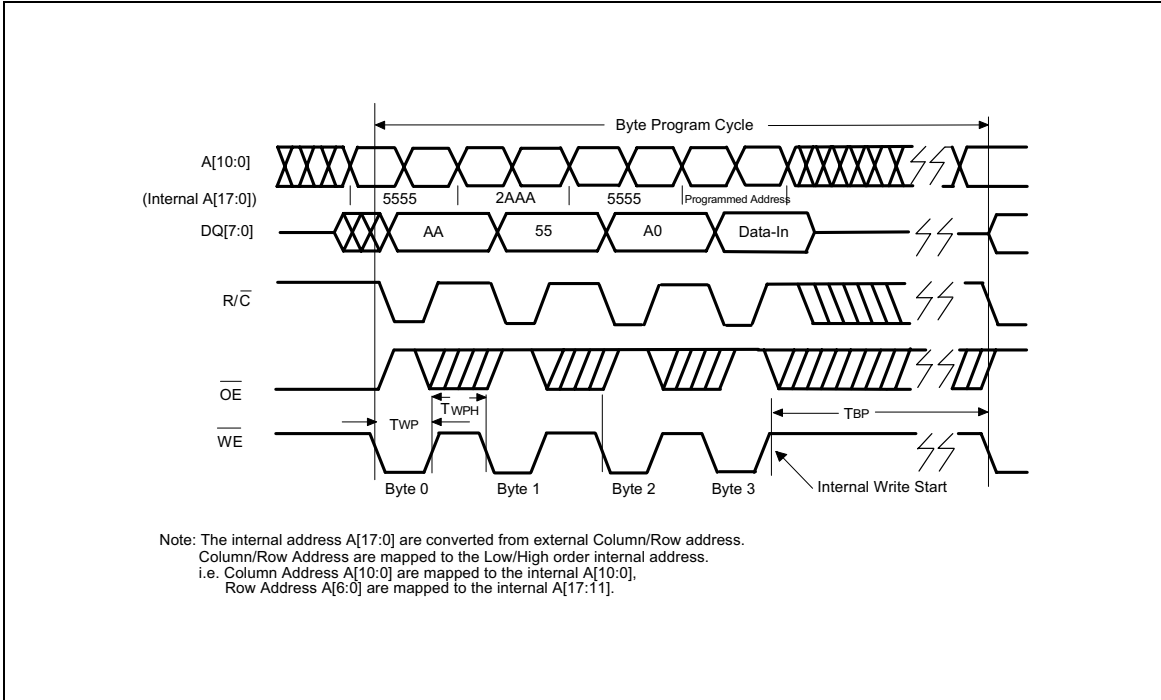
DATA Polling Timing Diagram

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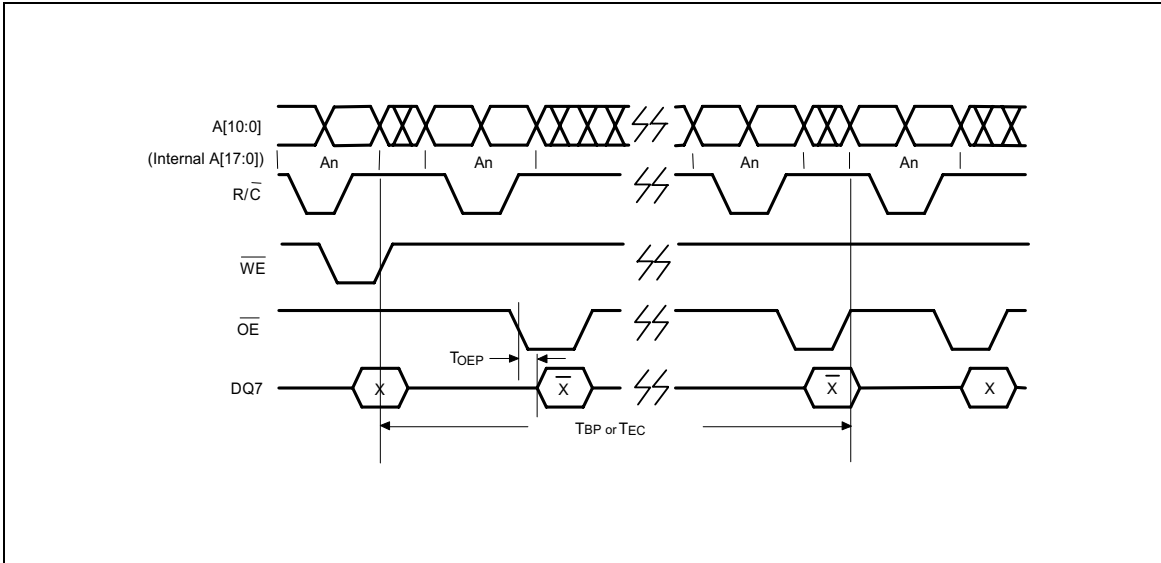
Timing Waveforms for Programmer Interface Mode, continued

Toggle Bit Timing Diagram
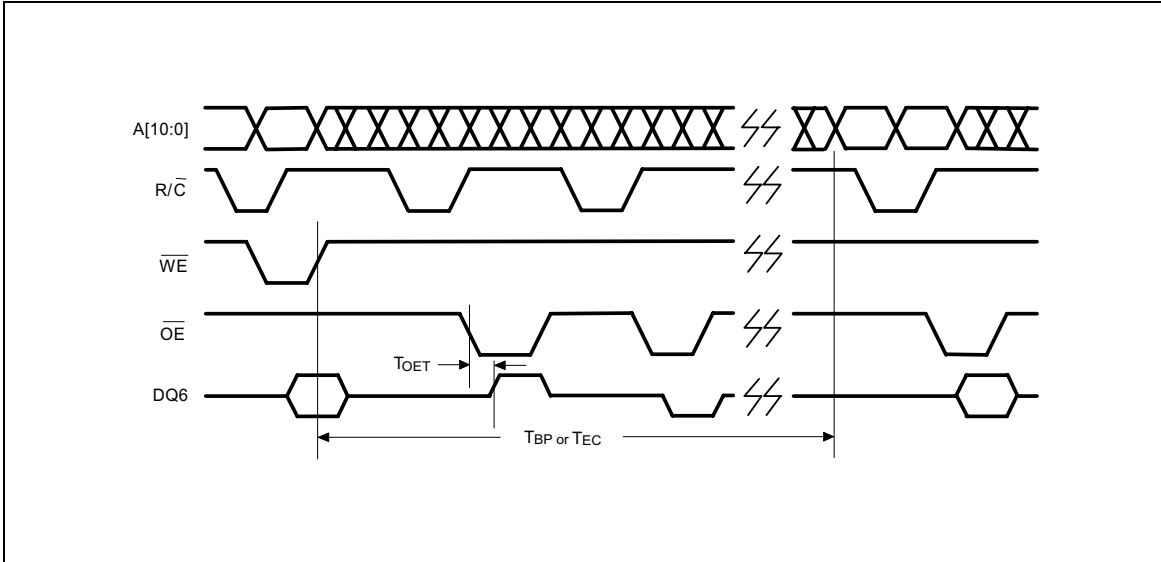
Boot Block Lockout Enable Timing Diagram

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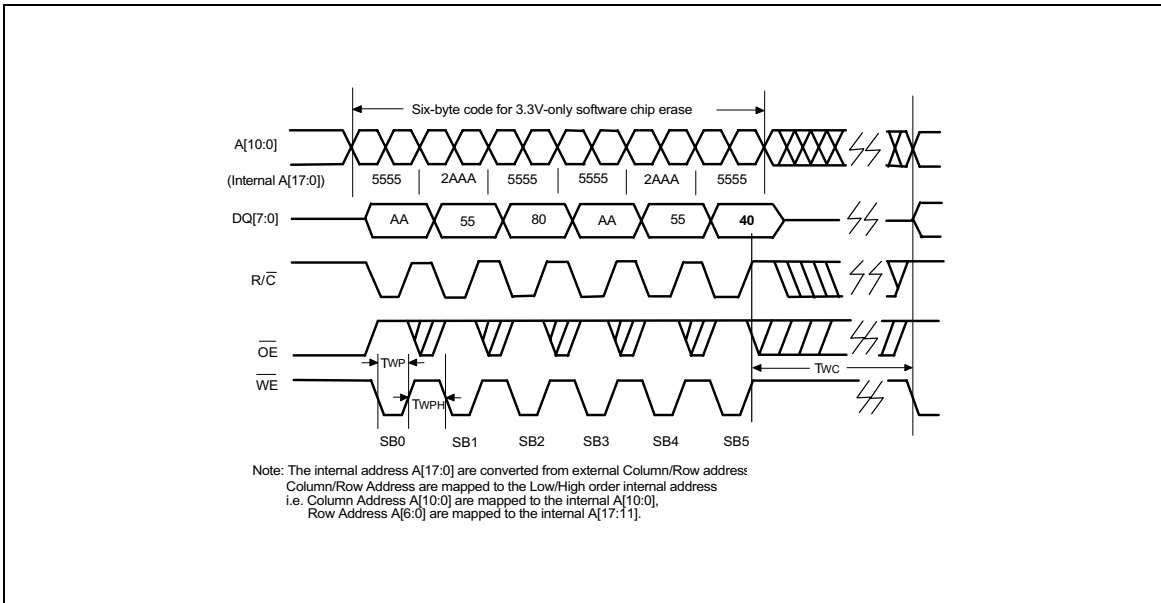
Timing Waveforms for Programmer Interface Mode, continued

Chip Erase Timing Diagram

Note: The internal address A[17:0] are converted from external Column/Row address
Column/Row Address are mapped to the Low/High order internal address.
i.e. Column Address A[10:0] are mapped to the internal A[10:0],
Row Address A[6:0] are mapped to the internal A[17:11].
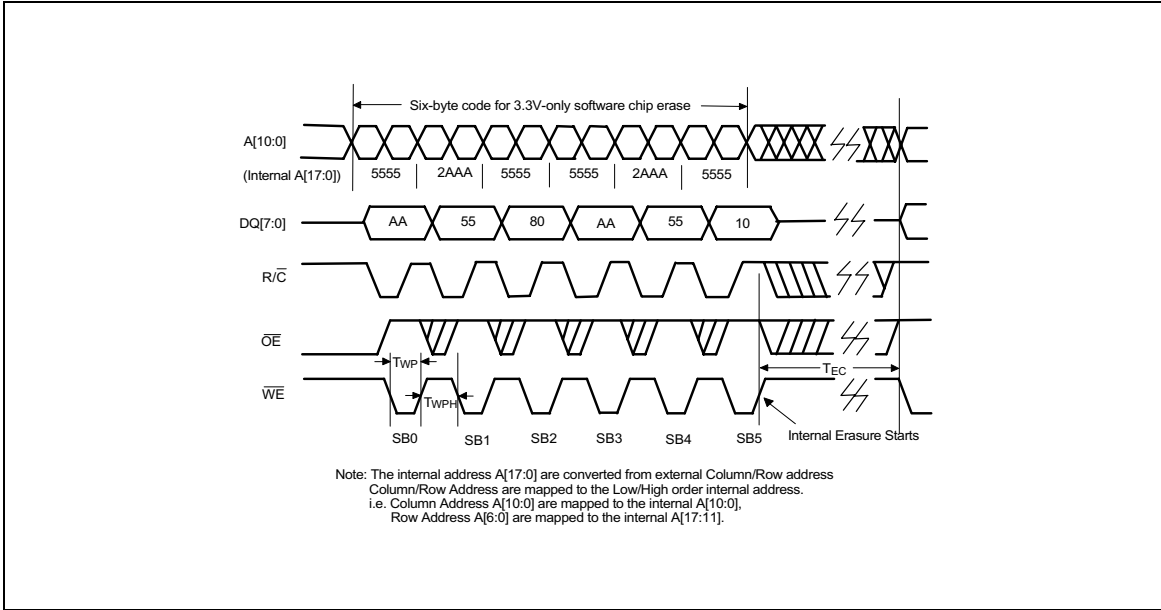
Sector Erase Timing Diagram

Note: The internal address A[17:0] are converted from external Column/Row address.
Column/Row Address are mapped to the Low/High order internal address.
i.e. Column Address A[10:0] are mapped to the internal A[10:0],
Row Address A[6:0] are mapped to the internal A[17:11].
SA = Sector Address, Please ref. to the "Table of Command Definition"

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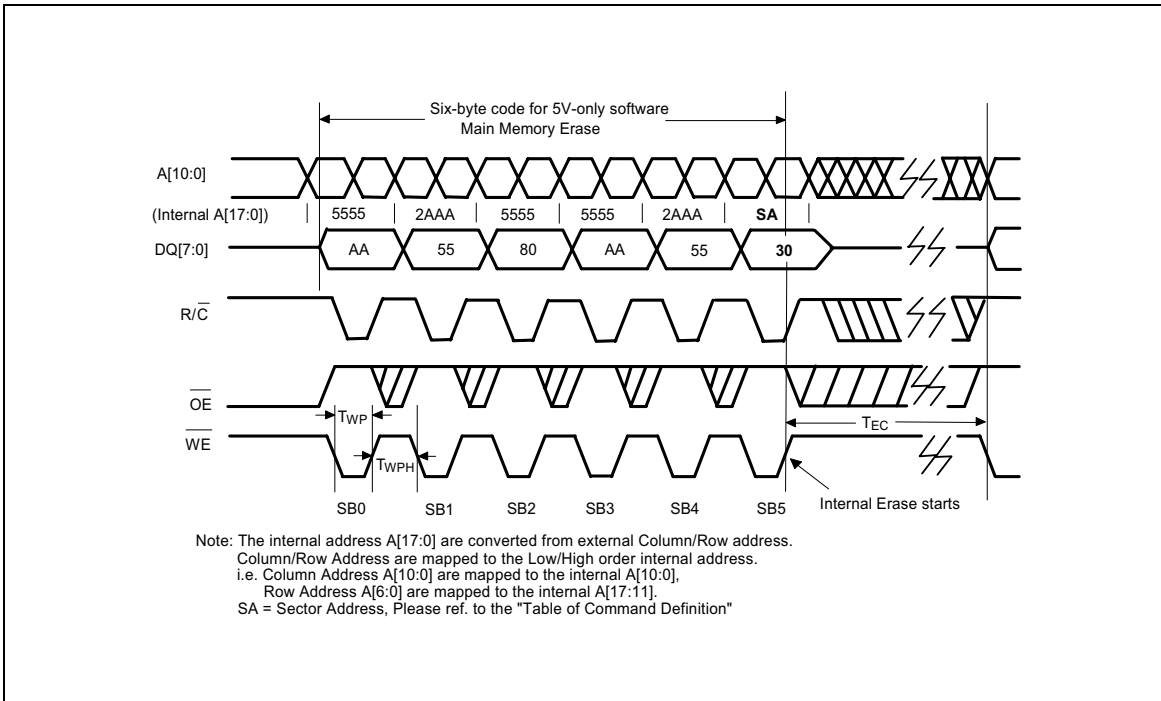
ORDERING INFORMATION

PART NO.	POWER SUPPLY CURRENT MAX. (mA)	STANDBY VDD CURRENT MAX. (μA)	PACKAGE
W49V002	25	20	32-pin DIP
W49V002P	25	20	32-pin PLCC
W49V002T	25	20	32-pin TSOP

Notes:

1. Winbond reserves the right to make changes to its products without prior notice.

2. Purchasers are responsible for performing appropriate quality assurance testing on products intended for use in applications where personal injury might occur as a consequence of product failure.

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PACKAGE DIMENSIONS

32-pin P-DIP

Symbol	Dimension in inches			Dimension in mm		
	Min.	Nom.	Max.	Min.	Nom.	Max.
A	—	—	0.210	—	—	5.33
A₁	0.010	—	—	0.25	—	—
A₂	0.150	0.155	0.160	3.81	3.94	4.06
B	0.016	0.018	0.022	0.41	0.46	0.56
B₁	0.048	0.050	0.054	1.22	1.27	1.37
c	0.008	0.010	0.014	0.20	0.25	0.36
D	—	1.650	1.660	—	41.91	42.16
E	0.590	0.600	0.610	14.99	15.24	15.49
E₁	0.545	0.550	0.555	13.84	13.97	14.10
e₁	0.090	0.100	0.110	2.29	2.54	2.79
L	0.120	0.130	0.140	3.05	3.30	3.56
a	0	—	15	0	—	15
e A	0.630	0.650	0.670	16.00	16.51	17.02
S	—	—	0.085	—	—	2.16

Notes:
1. Dimensions D Max. & S include mold flash or tie bar burrs.
2. Dimension E1 does not include interlead flash.
3. Dimensions D & E1 include mold mismatch and are determined at the mold parting line.
4. Dimension B1 does not include dambar protrusion/intrusion.
5. Controlling dimension: Inches
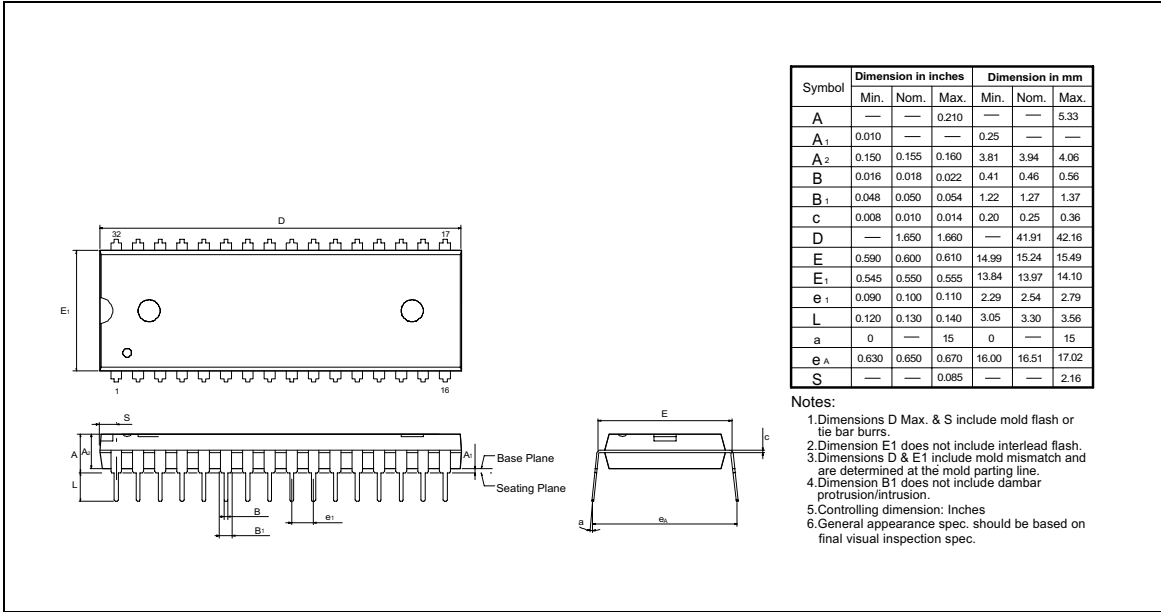6. General appearance spec. should be based on final visual inspection spec.

32-pin PLCC

Symbol	Dimension in Inches			Dimension in mm		
	Min.	Nom.	Max.	Min.	Nom.	Max.
A	—	—	0.140	—	—	3.56
A₁	0.020	—	—	0.50	—	—
A₂	0.105	0.110	0.115	2.67	2.80	2.93
b ₁	0.026	0.028	0.032	0.66	0.71	0.81
b	0.016	0.018	0.022	0.41	0.46	0.56
c	0.008	0.010	0.014	0.20	0.25	0.35
D	0.547	0.550	0.553	13.89	13.97	14.05
E	0.447	0.450	0.453	11.35	11.43	11.51
e	0.044	0.050	0.056	1.12	1.27	1.42
G D	0.490	0.510	0.530	12.45	12.95	13.46
G E	0.390	0.410	0.430	9.91	10.41	10.92
H D	0.585	0.590	0.595	14.86	14.99	15.11
H E	0.485	0.490	0.495	12.32	12.45	12.57
L	0.075	0.090	0.095	1.91	2.29	2.41
y	—	—	0.004	—	—	0.10
θ	0	—	10	0	—	10

Notes:
1. Dimensions D & E do not include interlead flash.
2. Dimension b1 does not include dambar protrusion/intrusion
3. Controlling dimension: Inches
4. General appearance spec. should be based on final visual inspection sepc.

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Package Dimensions, continued

32-pin TSOP

Symbol	Dimension in Inches			Dimension in mm		
	Min.	Nom.	Max.	Min.	Nom.	Max.
A	—	—	0.047	—	—	1.20
A_1	0.002	—	0.006	0.05	—	0.15
A_2	0.037	0.039	0.041	0.95	1.00	1.05
b	0.007	0.008	0.009	0.17	0.20	0.23
c	0.005	0.006	0.007	0.12	0.15	0.17
D	0.720	0.724	0.728	18.30	18.40	18.50
E	0.311	0.315	0.319	7.90	8.00	8.10
H_D	0.780	0.787	0.795	19.80	20.00	20.20
e	—	0.020	—	—	0.50	—
L	0.016	0.020	0.024	0.40	0.50	0.60
L_1	—	0.031	—	—	0.80	—
Y	0.000	—	0.004	0.00	—	0.10
θ	1	3	5	1	3	5

Note:

Controlling dimension: Millimeters
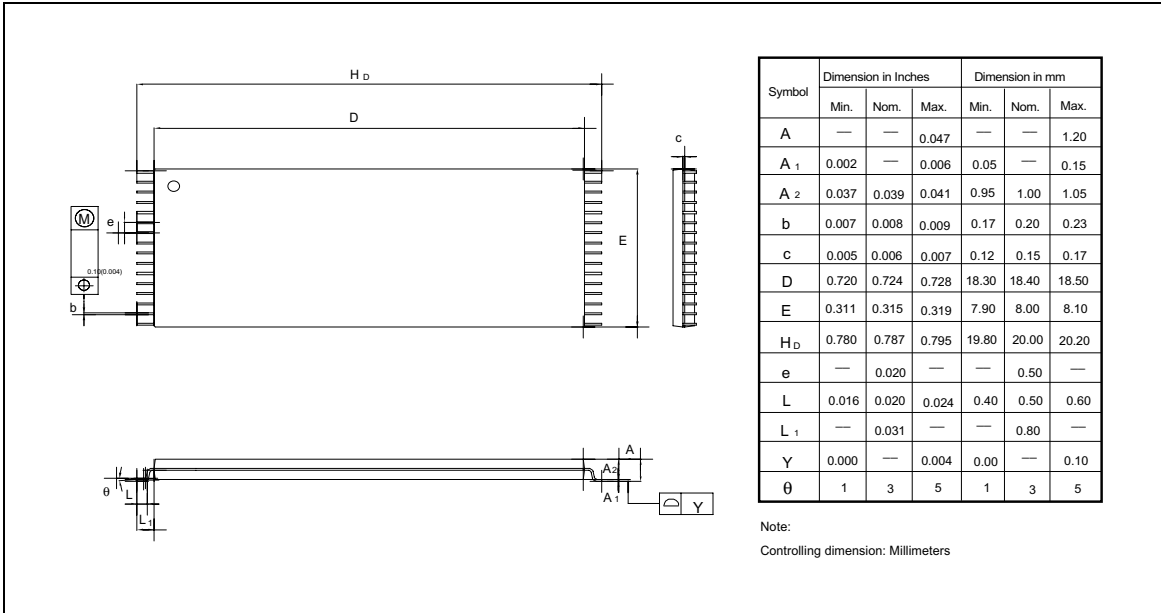
VERSION HISTORY

VERSION	DATE	PAGE	DESCRIPTION
A1	Mar. 2000	-	Initial Issued

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