

## KA9258D

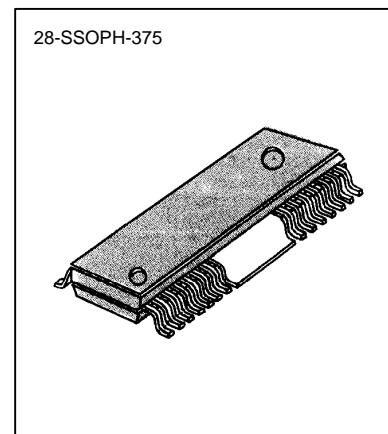
## MOTOR DRIVER

### INTRODUCTION

The KA9258D is a quad power operational amplifier to drive spindle motor, sled motor, focus actuator and tracking actuator.

### FEATURES

- 4-channel BTL driver
- Built in 5V regulator
- Built-in thermal shut down circuit
- Operating supply voltage: 6 ~ 13V



### ORDERING INFORMATION

Device	Package	Operating Temperature
KA9258D	28-SSOPH-375	-25°C~ +75°C

### BLOCK DIAGRAM

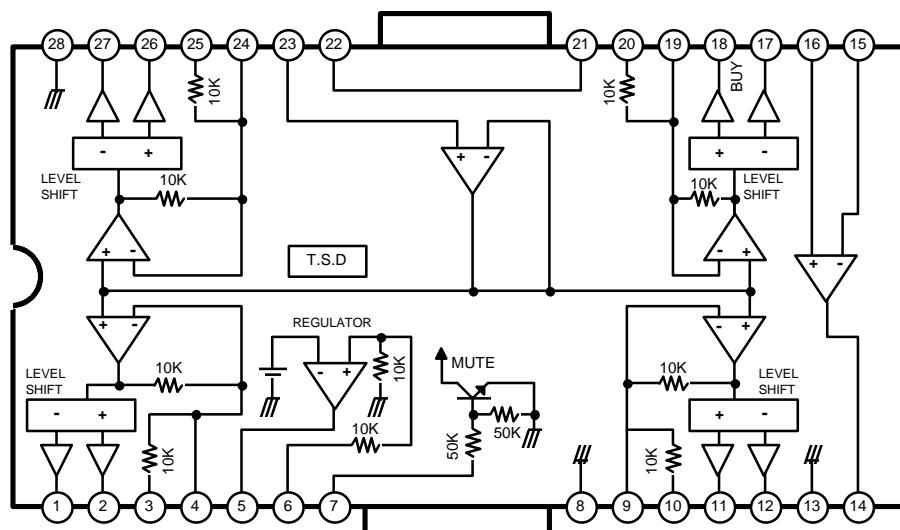


Fig. 1



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**KA9258D****MOTOR DRIVER****PIN DESCRIPTION**

Pin No.	Symbol	I/O	Description
1	DO1.1	O	DRIVE OUTPUT
2	DO1.2	O	DRIVE OUTPUT
3	DI1.1	I	DRIVE INPUT
4	DI1.2	I	DRIVE INPUT
5	REG		REGULATOR
6	REO	O	REGULATOR OUTPUT
7	MUTE	I	MUTE
8	GND1	-	GROUND
9	DI2.1	I	DRIVE INPUT
10	DI2.2	I	DRIVE INPUT
11	DO2.1	O	DRIVE OUTPUT
12	DO2.2	O	DRIVE OUTPUT
13	GND2	-	GROUND
14	OPOUT	O	OPAMP OUTPUT
15	OPIN (-)	I	OPAMP INPUT (-)
16	OPIN (+)	I	OPAMP INPUT (+)
17	DO3.1	O	DRIVE OUTPUT
18	DO3.2	O	DRIVE OUTPUT
19	DI3.1	I	DRIVE INPUT
20	DI3.2	I	DRIVE INPUT
21	VCC1	-	SUPPLY VOLTAGE
22	VCC2	-	SUPPLY VOLTAGE
23	VREF	I	2.5V BIAS VOLTAGE
24	DI4.1	I	DRIVE INPUT
25	DI4.2	I	DRIVE INPUT
26	DO4.1	O	DRIVE OUTPUT
27	DO4.2	O	DRIVE OUTPUT
28	GND3	-	GROUND



**KA9258D****MOTOR DRIVER****ABSOLUTE MAXIMUM RATINGS (Ta = 25°C)**

Characteristic	Symbol	Value	Unit
Supply Voltage	V <sub>CC</sub>	18	V
Power Dissipation	P <sub>D</sub>	1.7	W
Operating Temperature	T <sub>OPR</sub>	-25 ~ + 75	°C
Storage Temperature	T <sub>STG</sub>	-55 ~ + 150	°C

(NOTE) Power Dissipation value: at V<sub>CC</sub> = 8V.**ELECTRICAL CHARACTERISTICS**(Ta = 25°C, V<sub>CC</sub> = 8V, Unless Otherwise Specified)

## A. REGULATOR PART

Characteristic	Symbol	Test Conditions	Min	Typ	Max	Unit
Regulator Output Voltage	V <sub>REG</sub>	I <sub>L</sub> = 100mA	4.75	5	5.25	V
Load Regulation	ΔV <sub>RL</sub>	I <sub>L</sub> = 0mA to 200mA	-40.0	0	10.0	mV
Line Regulation	ΔV <sub>CC</sub>	I <sub>L</sub> = 200mA, V <sub>CC</sub> = 6 to 9V	-10.0	0	20.0	mV

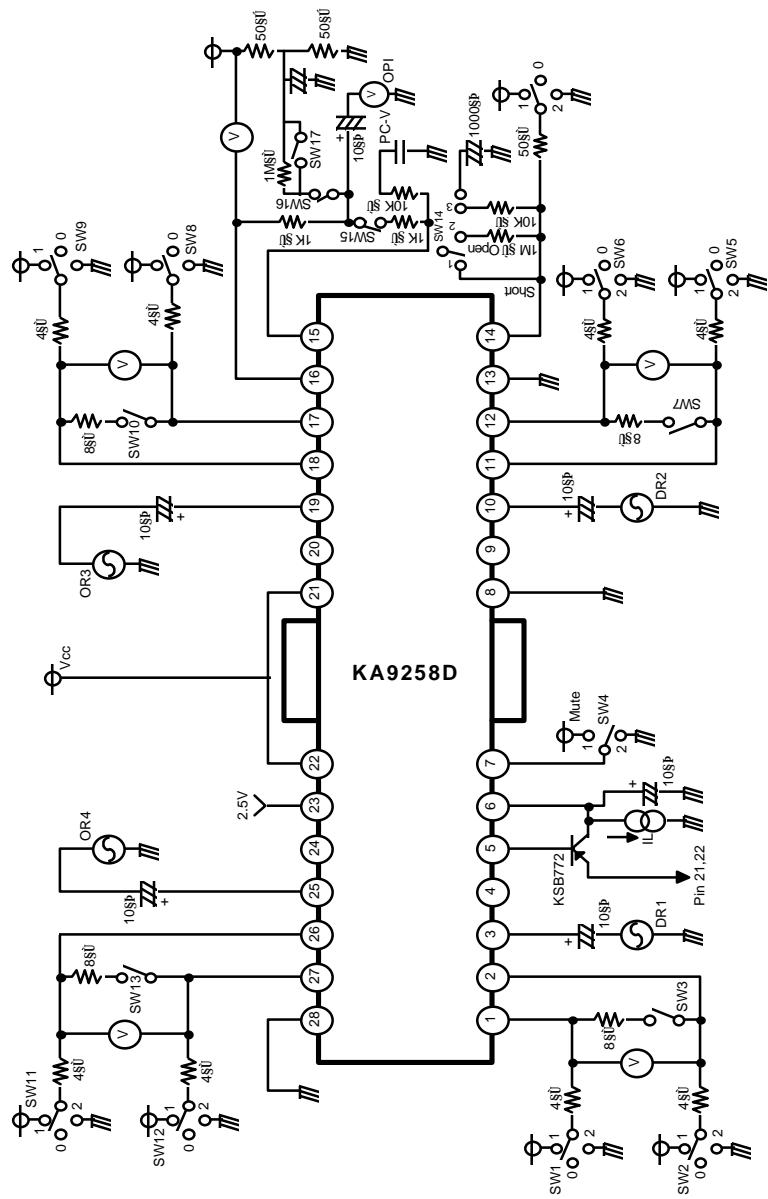
## B. DRIVER PART

Characteristic	Symbol	Test Conditions	Min	Typ	Max	Unit
Quiescent Circuit Current	I <sub>CCQ</sub>	V <sub>I</sub> = 0	5.5	9.5	13.5	mA
Input Bias Current	I <sub>BOP</sub>	V <sub>I</sub> = 0			300	nA
Input offset voltage	V <sub>OFOP</sub>		-5.0	0	5.0	mV
Output offset voltage	V <sub>OO</sub>		-3.0	0	30	
Maximum Sink Current	I <sub>SINK</sub>	R <sub>L</sub> = 4ohm, V <sub>CC</sub>	0.5	0.8		A
Maximum Source Current	I <sub>SOURCE</sub>	R <sub>L</sub> = 4ohm, GND	0.5	0.8		
Maximum Output Voltage	V <sub>MA</sub>	V <sub>I</sub> = 2V <sub>rms</sub> , 1KHz	2.5	3.0		V <sub>rms</sub>
Closed loop Voltage Gain	A <sub>VF</sub>	V <sub>I</sub> = 0.1V <sub>rms</sub> , 1KHz	4.5	6.5	7.5	dB
Ripple Rejection Ratio	RR	V <sub>I</sub> = -20dB, 120Hz	60 .0	80.0		
Slew Rate	SR	100Hz, Squarewave	1.0	2.0		V/us



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## Test Circuit



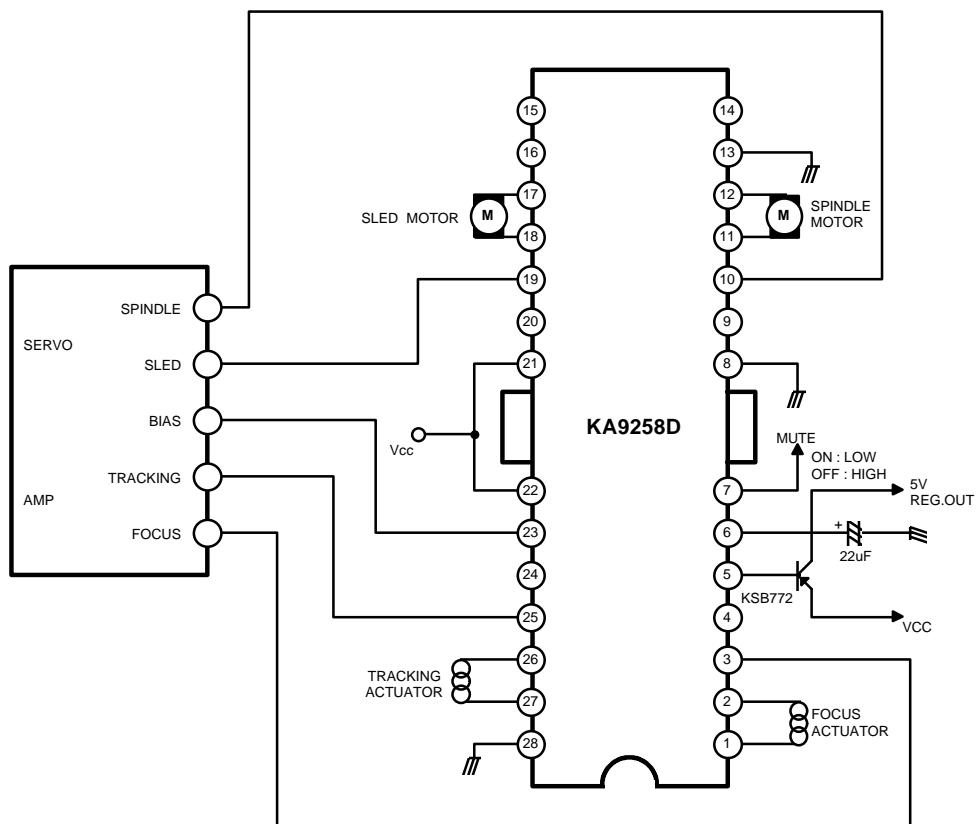
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## **KA9258D**

## **MOTOR DRIVER**

### **APPLICATION CIRCUIT**



\* THERMAL SHUT DOWN CIRCUIT

The IC is broken down by the heat when overload condition continues for a long time. So KA9258D has a thermal shutdown circuit to prevent this case. At that time the temperature of IC rises over 175°C, the circuit is operating and protects the IC against breakdown.

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