

# CLC5622

## Dual, High Output, Video Amplifier

### General Description

The National CLC5622 has a new output stage that delivers high output drive current (130mA), but consumes minimal quiescent supply current (3.0mA/ch) from a single 5V supply. Its current feedback architecture, fabricated in an advanced complementary bipolar process, maintains consistent performance over a wide range of gains and signal levels, and has a linear-phase response up to one half of the -3dB frequency.

The CLC5622 offers 0.1dB gain flatness to 30MHz and differential gain and phase errors of 0.05% and 0.03°. These features are ideal for professional and consumer video applications.

The CLC5622 offers superior dynamic performance with a 160MHz small-signal bandwidth, 370V/ $\mu$ s slew rate and 4.4ns rise/fall times ( $2V_{step}$ ). The combination of low quiescent power, high output current drive, and high-speed performance make the CLC5622 well suited for many battery-powered personal communication/computing systems.

The ability to drive low-impedance, highly capacitive loads, makes the CLC5622 ideal for single ended cable applications. It also drives low impedance loads with minimum distortion. The CLC5622 will drive a 100 $\Omega$  load with only -95/-95dBc second/third harmonic distortion ( $A_v = +2$ ,  $V_{out} = 2V_{pp}$ ,  $f = 1$ MHz). With a 25 $\Omega$  load, and the same conditions, it produces only -72/-77dBc second/third harmonic distortion.

The CLC5622 can also be used for driving differential-input step-up transformers for applications such as Asynchronous Digital Subscriber Lines (ADSL) or High-Bit-Rate Digital Subscriber Lines (HDSL).

When driving the input of high-resolution A/D converters, the CLC5622 provides excellent -90/-97dBc second/third harmonic distortion ( $A_v = +2$ ,  $V_{out} = 2V_{pp}$ ,  $f = 1$ MHz,  $R_L = 1k\Omega$ ) and fast settling time.

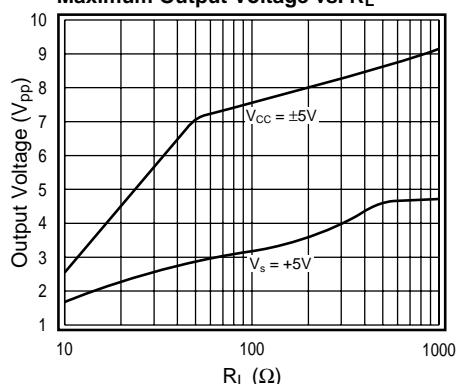
### Features

- 130mA output current
- 0.05%, 0.03° differential gain, phase
- 3.0mA/ch supply current
- 160MHz bandwidth ( $A_v = +2$ )
- -90/-97dBc HD2/HD3 (1MHz)
- 18ns settling to 0.05%
- 370V/ $\mu$ s slew rate
- Stable for capacitive loads up to 1000pf
- Single 5V or  $\pm 5$ V supplies

### Applications

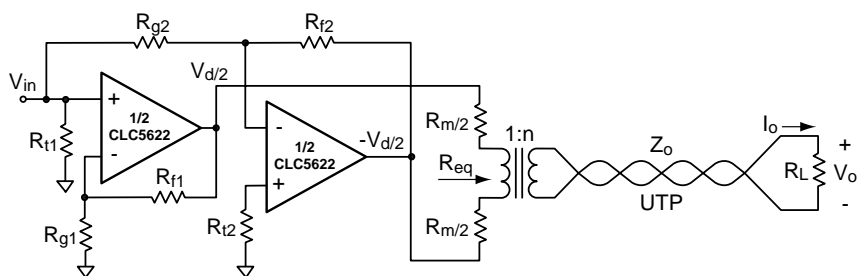
- Video line driver
- ADSL/HDSL driver
- Coaxial cable driver
- UTP differential line driver
- Transformer/coil driver
- High capacitive load driver
- Portable/battery-powered applications
- Differential A/D driver

Maximum Output Voltage vs.  $R_L$



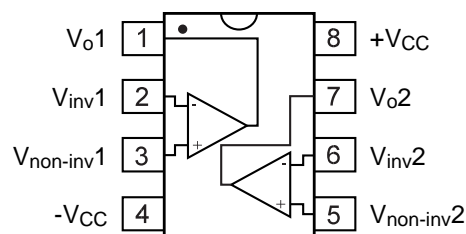
### Typical Application

#### Differential Line Driver with Load Impedance Conversion



### Pinout

#### DIP & SOIC



## +5V Electrical Characteristics ( $A_v = +2$ , $R_f = 750\Omega$ , $R_L = 100\Omega$ , $V_s = +5V^1$ , $V_{cm} = V_{EE} + (V_s/2)$ , $R_L$ tied to $V_{cm}$ , unless specified)

PARAMETERS	CONDITIONS	TYP	MIN/MAX RATINGS			UNITS	NOTES
Ambient Temperature	CLC5622IN/IM	+25°C	+25°C	0 to 70°C	-40 to 85°C		
<b>FREQUENCY DOMAIN RESPONSE</b>							
-3dB bandwidth	$V_o = 0.5V_{pp}$	130	100	90	85	MHz	
	$V_o = 2.0V_{pp}$	95	80	77	75	MHz	
-0.1dB bandwidth	$V_o = 0.5V_{pp}$	30	25	20	20	MHz	
gain peaking	<200MHz, $V_o = 0.5V_{pp}$	0	0.5	0.9	1.3	dB	
gain rolloff	<30MHz, $V_o = 0.5V_{pp}$	0.1	0.4	0.6	0.6	dB	
linear phase deviation	<30MHz, $V_o = 0.5V_{pp}$	0.15	0.3	0.4	0.4	deg	
differential gain	NTSC, $R_L = 150\Omega$ to -1V	0.03	—	—	—	%	
differential phase	NTSC, $R_L = 150\Omega$ to -1V	0.07	—	—	—	deg	
<b>TIME DOMAIN RESPONSE</b>							
rise and fall time	2V step	4.5	6.0	6.4	6.8	ns	
settling time to 0.05%	1V step	17	25	40	60	ns	
overshoot	2V step	11	15	18	18	%	
slew rate	2V step	280	195	165	150	V/ $\mu$ s	
<b>DISTORTION AND NOISE RESPONSE</b>							
2 <sup>nd</sup> harmonic distortion	$2V_{pp}$ , 1MHz	-79	-76	-73	-73	dBc	
	$2V_{pp}$ , 1MHz; $R_L = 1k\Omega$	-80	-78	-75	-75	dBc	
	$2V_{pp}$ , 5MHz	-66	-60	-58	-58	dBc	
3 <sup>rd</sup> harmonic distortion	$2V_{pp}$ , 1MHz	-85	-82	-79	-79	dBc	
	$2V_{pp}$ , 1MHz; $R_L = 1k\Omega$	-83	-81	-78	-78	dBc	
	$2V_{pp}$ , 5MHz	-65	-62	-60	-60	dBc	
equivalent input noise							
voltage ( $e_{ni}$ )	>1MHz	3.4	4.4	4.9	4.9	nV/ $\sqrt{Hz}$	
non-inverting current ( $i_{bn}$ )	>1MHz	6.3	8.2	9.0	9.0	pA/ $\sqrt{Hz}$	
inverting current ( $i_{bi}$ )	>1MHz	8.7	11.3	12.4	12.4	pA/ $\sqrt{Hz}$	
crosstalk (input referred)	10MHz, $1V_{pp}$	-72	—	—	—	dB	
<b>STATIC DC PERFORMANCE</b>							
input offset voltage		1	4	6	6	mV	A
average drift		8	—	—	—	$\mu$ V/ $^{\circ}$ C	
input bias current (non-inverting)		6	18	22	24	$\mu$ A	A
average drift		40	—	—	—	nA/ $^{\circ}$ C	
input bias current (inverting)		6	14	16	17	$\mu$ A	A
average drift		25	—	—	—	nA/ $^{\circ}$ C	
power supply rejection ratio	DC	48	45	43	43	dB	
common-mode rejection ratio	DC	47	45	43	43	dB	
supply current per channel	$R_L = \infty$	3.0	3.4	3.6	3.6	mA	A
<b>MISCELLANEOUS PERFORMANCE</b>							
input resistance (non-inverting)		0.36	0.26	0.23	0.23	M $\Omega$	
input capacitance (non-inverting)		1.8	2.75	2.75	2.75	pF	
input voltage range, High		4.2	4.1	4.1	4.0	V	
input voltage range, Low		0.8	0.9	0.9	1.0	V	
output voltage range, High	$R_L = 100\Omega$	4.0	3.9	3.9	3.8	V	
output voltage range, Low	$R_L = 100\Omega$	1.0	1.1	1.1	1.2	V	
output voltage range, High	$R_L = \infty$	4.1	4.0	4.0	3.9	V	
output voltage range, Low	$R_L = \infty$	0.9	1.0	1.0	1.1	V	
output current		100	80	65	40	mA	B
output resistance, closed loop	DC	70	105	105	140	m $\Omega$	

Min/max ratings are based on product characterization and simulation. Individual parameters are tested as noted. Outgoing quality levels are determined from tested parameters.

### Notes

- A) J-level: spec is 100% tested at +25°C.  
 B) The short circuit current can exceed the maximum safe output current.  
 1)  $V_s = V_{CC} - V_{EE}$

### Absolute Maximum Ratings

supply voltage ( $V_{CC} - V_{EE}$ )	+14V
output current (see note C)	140mA
common-mode input voltage	$V_{EE}$ to $V_{CC}$
maximum junction temperature	+175°C
storage temperature range	-65°C to +150°C
lead temperature (soldering 10 sec)	+300°C
ESD rating (human body model)	1000V

### Reliability Information

Transistor Count	98
MTBF (based on limited test data)	300Mhr

# ±5V Electrical Characteristics (A<sub>v</sub> = +2, R<sub>f</sub> = 750Ω, R<sub>L</sub> = 100Ω, V<sub>CC</sub> = ±5V, unless specified)

PARAMETERS	CONDITIONS	TYP	GUARANTEED MIN/MAX				UNITS	NOTES
Ambient Temperature	CLC5622IN/IM	+25°C	+25°C	0 to 70°C	-40 to 85°C			
<b>FREQUENCY DOMAIN RESPONSE</b>								
-3dB bandwidth	V <sub>o</sub> = 1.0V <sub>pp</sub>	160	135	120	115		MHz	
	V <sub>o</sub> = 4.0V <sub>pp</sub>	75	60	57	55		MHz	
-0.1dB bandwidth	V <sub>o</sub> = 1.0V <sub>pp</sub>	30	25	20	20		MHz	
gain peaking	<200MHz, V <sub>o</sub> = 1.0V <sub>pp</sub>	0	0.5	0.9	1.3		dB	
gain rolloff	<30MHz, V <sub>o</sub> = 1.0V <sub>pp</sub>	0.1	0.2	0.3	0.3		dB	
linear phase deviation	<30MHz, V <sub>o</sub> = 1.0V <sub>pp</sub>	0.15	0.3	0.4	0.4		deg	
differential gain	NTSC, R <sub>L</sub> =150Ω	0.05	0.1	—	—		%	
differential phase	NTSC, R <sub>L</sub> =150Ω	0.03	0.06	—	—		deg	
<b>TIME DOMAIN RESPONSE</b>								
rise and fall time	2V step	4.4	5.8	6.2	6.8		ns	
settling time to 0.05%	2V step	18	25	40	60		ns	
overshoot	2V step	19	21	23	24		%	
slew rate	2V step	370	280	260	240		V/μs	
<b>DISTORTION AND NOISE RESPONSE</b>								
2 <sup>nd</sup> harmonic distortion	2V <sub>pp</sub> , 1MHz	-95	-88	-85	-85		dBc	
	2V <sub>pp</sub> , 1MHz; R <sub>L</sub> = 1kΩ	-90	-88	-85	-85		dBc	
	2V <sub>pp</sub> , 5MHz	-74	-66	-64	-64		dBc	
3 <sup>rd</sup> harmonic distortion	2V <sub>pp</sub> , 1MHz	-95	-91	-88	-88		dBc	
	2V <sub>pp</sub> , 1MHz; R <sub>L</sub> = 1kΩ	-97	-93	-90	-90		dBc	
	2V <sub>pp</sub> , 5MHz	-73	-64	-62	-62		dBc	
equivalent input noise								
voltage (e <sub>ni</sub> )	>1MHz	3.4	4.4	4.9	4.9		nV/√Hz	
non-inverting current (i <sub>bn</sub> )	>1MHz	6.3	8.2	9.0	9.0		pA/√Hz	
inverting current (i <sub>bi</sub> )	>1MHz	8.7	11.3	12.4	12.4		pA/√Hz	
crosstalk (input referred)	10MHz, 1V <sub>pp</sub>	-72	—	—	—		dB	
<b>STATIC DC PERFORMANCE</b>								
input offset voltage		1	6	7	8		mV	
average drift		10	—	—	—		μV/°C	
input bias current (non-inverting)		8	18	23	25		μA	
average drift		40	—	—	—		nA/°C	
input bias current (inverting)		9	24	28	28		μA	
average drift		30	—	—	—		nA/°C	
power supply rejection ratio	DC	48	45	43	43		dB	
common-mode rejection ratio	DC	48	46	44	44		dB	
supply current (per channel)	R <sub>L</sub> = ∞	3.2	3.8	4.0	4.0		mA	
<b>MISCELLANEOUS PERFORMANCE</b>								
input resistance (non-inverting)		0.48	0.34	0.31	0.31		MΩ	
input capacitance (non-inverting)		1.45	2.15	2.15	2.15		pF	
common-mode input range		±4.2	±4.1	±4.1	±4.0		V	
output voltage range	R <sub>L</sub> = 100Ω	±3.8	±3.6	±3.6	±3.5		V	
output voltage range	R <sub>L</sub> = ∞	±4.0	±3.8	±3.8	±3.7		V	
output current		130	100	80	50		mA	
output resistance, closed loop	DC	60	90	90	120		mΩ	B

## Notes

B) The short circuit current can exceed the maximum safe output current.

## Package Thermal Resistance

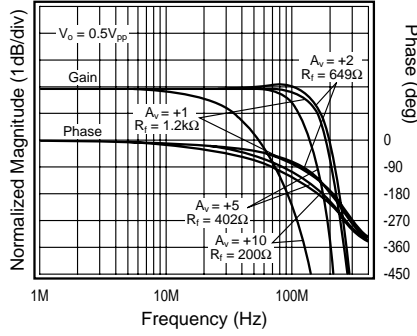
Package	θ <sub>JC</sub>	θ <sub>JA</sub>
Plastic (IN)	65°C/W	130°C/W
Surface Mount (IM)	50°C/W	145°C/W

## Ordering Information

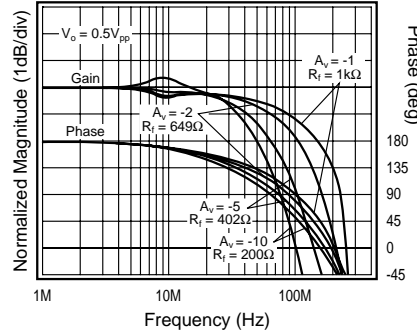
Model	Temperature Range	Description
CLC5622IN	-40°C to +85°C	8-pin PDIP
CLC5622IM	-40°C to +85°C	8-pin SOIC
CLC5622IMX	-40°C to +85°C	8-pin SOIC tape and reel

# **+5V Typical Performance** ( $A_v = +2$ , $R_f = 750\Omega$ , $R_L = 100\Omega$ , $V_s = +5V^1$ , $V_{cm} = V_{EE} + (V_s/2)$ , $R_L$ tied to $V_{cm}$ , unless specified)

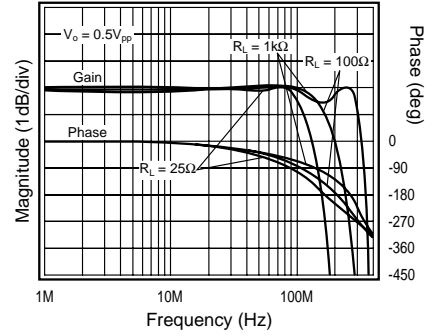
**Non-Inverting Frequency Response**



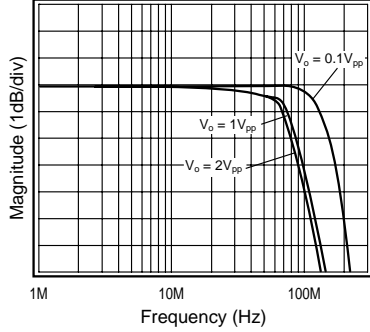
**Inverting Frequency Response**



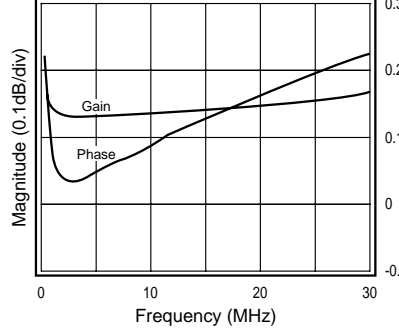
**Frequency Response vs.  $R_L$**



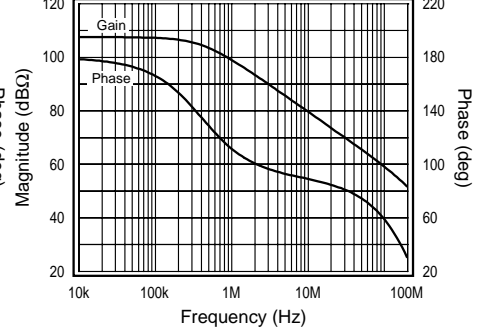
**Frequency Response vs.  $V_o$**



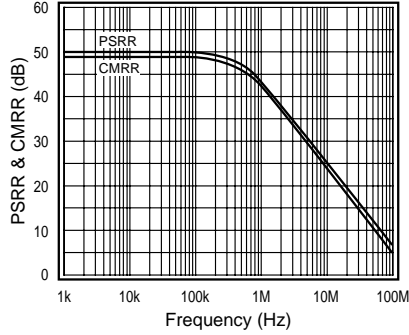
**Gain Flatness & Linear Phase**



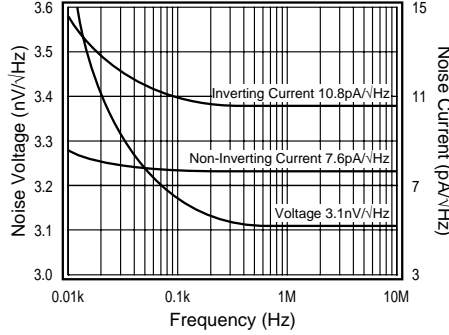
**Open Loop Transimpedance Gain,  $Z(s)$**



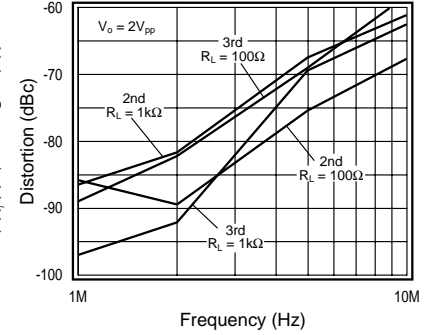
**PSRR & CMRR**



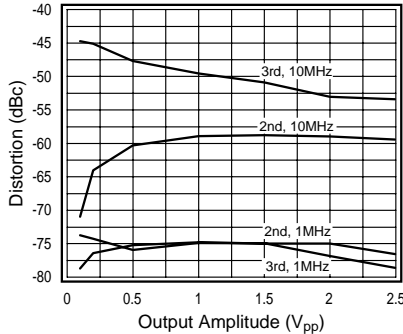
**Equivalent Input Noise**



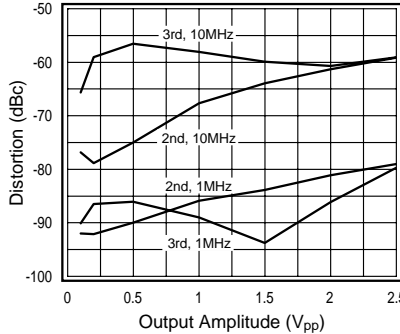
**2nd & 3rd Harmonic Distortion**



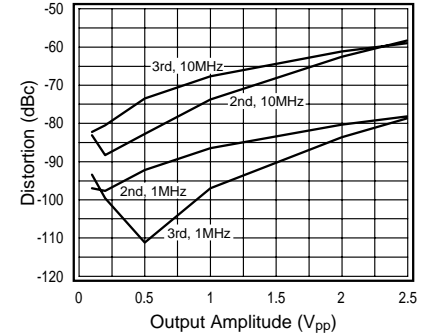
**2nd & 3rd Harmonic Distortion,  $R_L = 25\Omega$**



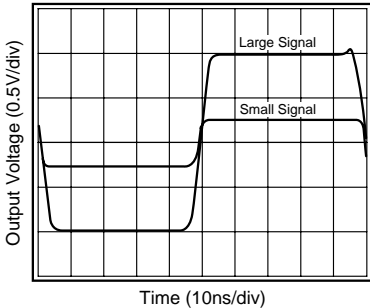
**2nd & 3rd Harmonic Distortion,  $R_L = 100\Omega$**



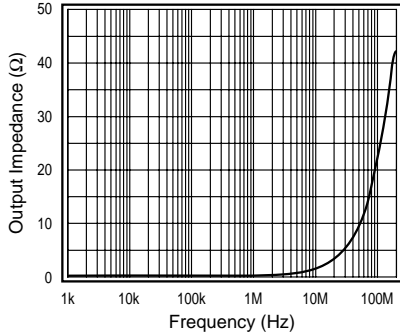
**2nd & 3rd Harmonic Distortion,  $R_L = 1k\Omega$**



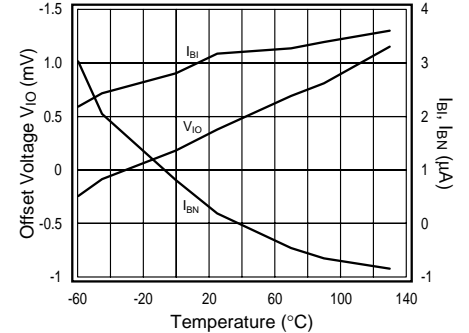
**Large & Small Signal Pulse Response**



**Output Impedance vs. Frequency**

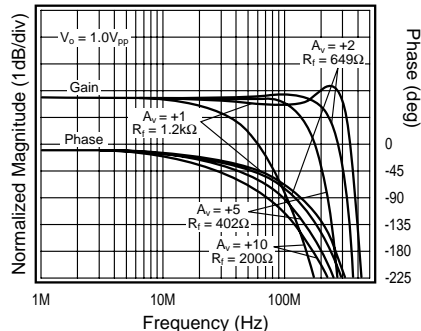


**$I_{BI}$ ,  $I_{BN}$ ,  $V_{IO}$  vs. Temperature**

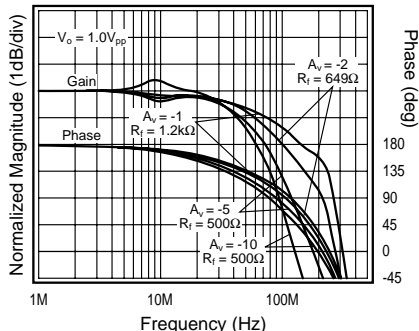


# ±5V Typical Performance ( $A_v = +2$ , $R_f = 750\Omega$ , $R_L = 100\Omega$ , $V_{CC} = \pm 5V$ , unless specified)

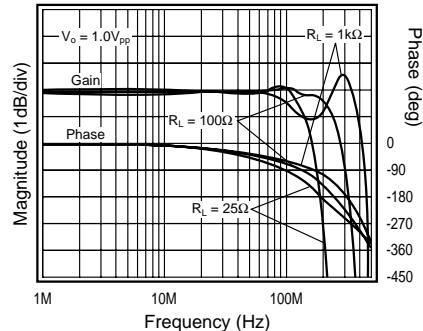
**Frequency Response**



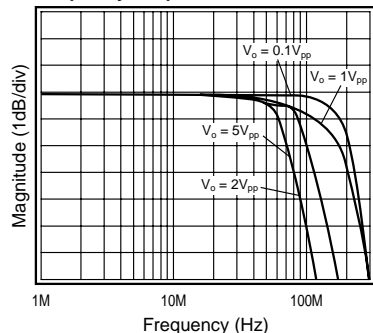
**Inverting Frequency Response**



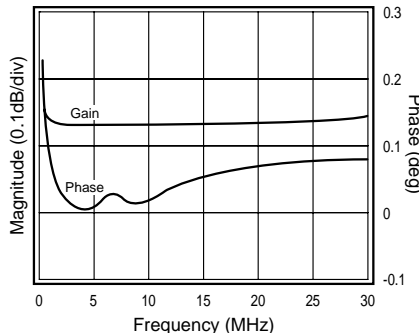
**Frequency Response vs.  $R_L$**



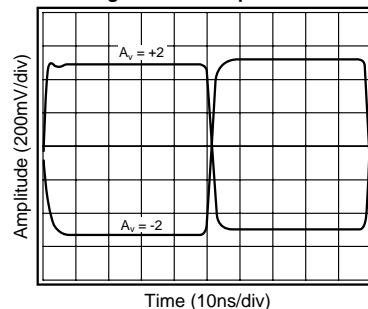
**Frequency Response vs.  $V_o$**



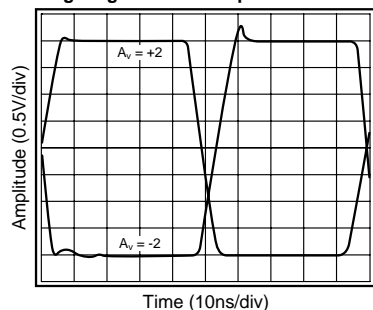
**Gain Flatness & Linear Phase**



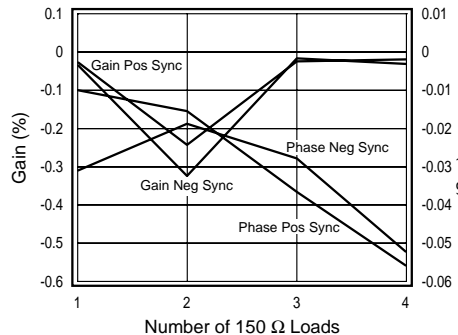
**Small Signal Pulse Response**



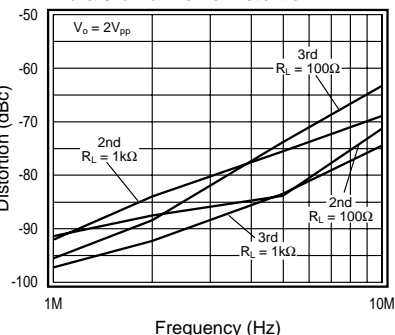
**Large Signal Pulse Response**



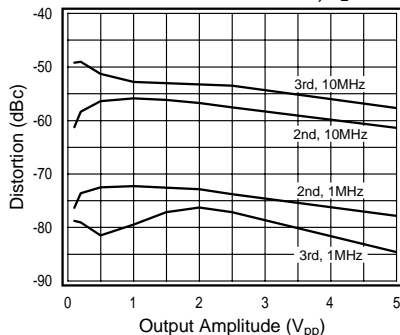
**Differential Gain & Phase**



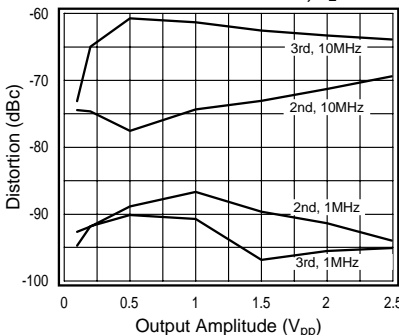
**2nd & 3rd Harmonic Distortion**



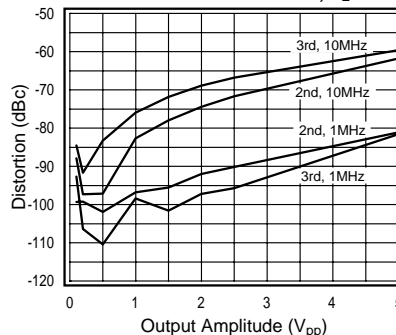
**2nd & 3rd Harmonic Distortion,  $R_L = 25\Omega$**



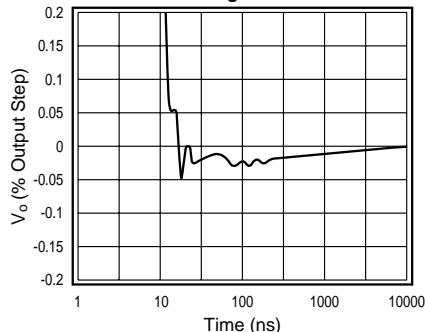
**2nd & 3rd Harmonic Distortion,  $R_L = 100\Omega$**



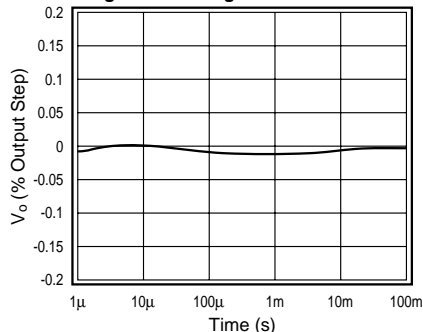
**2nd & 3rd Harmonic Distortion,  $R_L = 1k\Omega$**



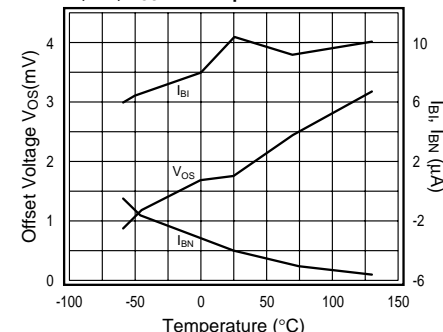
**Short Term Settling Time**



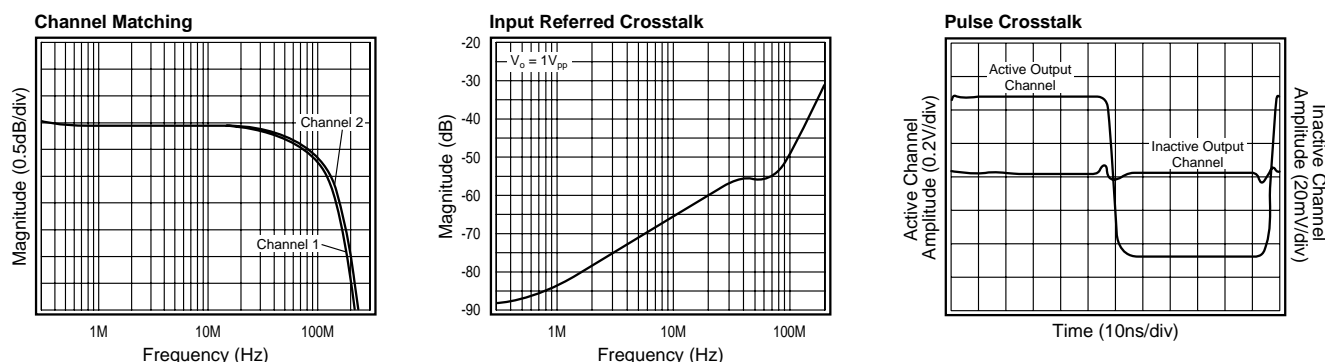
**Long Term Settling Time**



**$I_{BI}$ ,  $I_{BN}$ ,  $V_{OS}$  vs. Temperature**



## ±5V Typical Channel Matching Performance ( $A_v = +2$ , $R_f = 750\Omega$ , $R_L = 100\Omega$ , $V_{CC} = \pm 5V$ , unless specified)



## CLC5622 OPERATION

The CLC5622 is a current feedback amplifier built in an advanced complementary bipolar process. The CLC5622 operates from a single 5V supply or dual  $\pm 5V$  supplies. Operating from a single supply, the CLC5622 has the following features:

- Provides 100mA of output current while consuming 15mW of power
- Offers low -80/-83dB 2nd and 3rd harmonic distortion
- Provides BW > 80MHz and 1MHz distortion < -75dBc at  $V_o = 2V_{pp}$

The CLC5622 performance is further enhanced in  $\pm 5V$  supply applications as indicated in the **±5V Electrical Characteristics** table and **±5V Typical Performance** plots.

### Current Feedback Amplifiers

Some of the key features of current feedback technology are:

- Independence of AC bandwidth and voltage gain
- Inherently stable at unity gain
- Adjustable frequency response with feedback resistor
- High slew rate
- Fast settling

Current feedback operation can be described using a simple equation. The voltage gain for a non-inverting or inverting current feedback amplifier is approximated by Equation 1.

$$\frac{V_o}{V_{in}} = \frac{A_v}{1 + \frac{R_f}{Z(j\omega)}} \quad \text{Equation 1}$$

where:

- $A_v$  is the closed loop DC voltage gain
- $R_f$  is the feedback resistor
- $Z(j\omega)$  is the CLC5622's open loop transimpedance gain
- $\frac{Z(j\omega)}{R_f}$  is the loop gain

The denominator of Equation 1 is approximately equal to 1 at low frequencies. Near the -3dB corner frequency, the interaction between  $R_f$  and  $Z(j\omega)$  dominates the circuit performance. The value of the feedback resistor has a large affect on the circuits performance. Increasing  $R_f$  has the following affects:

- Decreases loop gain
- Decreases bandwidth
- Reduces gain peaking
- Lowers pulse response overshoot
- Affects frequency response phase linearity

Refer to the **Feedback Resistor Selection** section for more details on selecting a feedback resistor value.

## CLC5622 DESIGN INFORMATION

### Single Supply Operation ( $V_{CC} = +5V$ , $V_{EE} = \text{GND}$ )

The specifications given in the **±5V Electrical Characteristics** table for single supply operation are measured with a common mode voltage ( $V_{cm}$ ) of 2.5V.  $V_{cm}$  is the voltage around which the inputs are applied and the output voltages are specified.

Operating from a single +5V supply, the Common Mode Input Range (CMIR) of the CLC5622 is typically +0.8V to

+4.2V. The typical output range with  $R_L = 100\Omega$  is +1.0V to +4.0V.

For single supply DC coupled operation, keep input signal levels above 0.8V DC. For input signals that drop below 0.8V DC, AC coupling and level shifting the signal are recommended. The non-inverting and inverting configurations for both input conditions are illustrated in the following 2 sections.



## DC Coupled Single Supply Operation

Figures 1 and 2 show the recommended non-inverting and inverting configurations for input signals that remain above 0.8V DC.

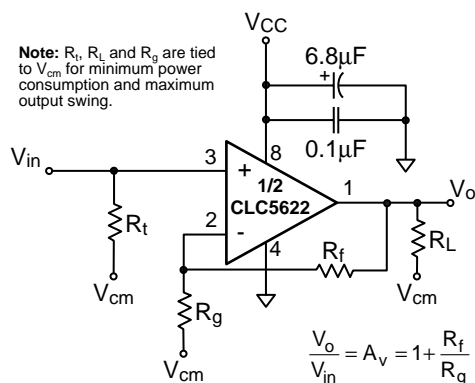


Figure 1: Non-Inverting Configuration

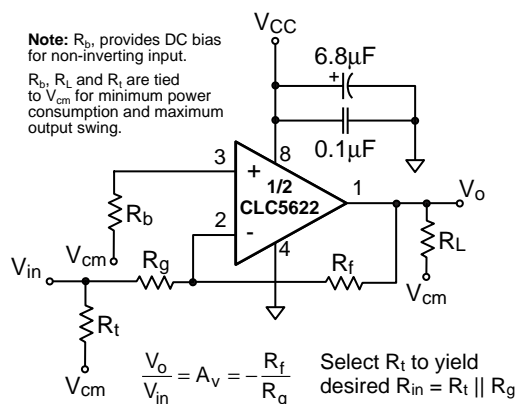


Figure 2: Inverting Configuration

## AC Coupled Single Supply Operation

Figures 3 and 4 show possible non-inverting and inverting configurations for input signals that go below 0.8V DC. The input is AC coupled to prevent the need for level shifting the input signal at the source. The resistive voltage divider biases the non-inverting input to  $V_{CC} \div 2 = 2.5V$  (For  $V_{CC} = +5V$ ).

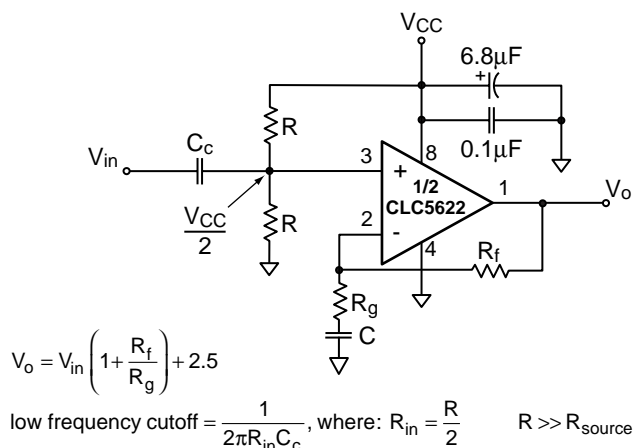


Figure 3: AC Coupled Non-Inverting Configuration

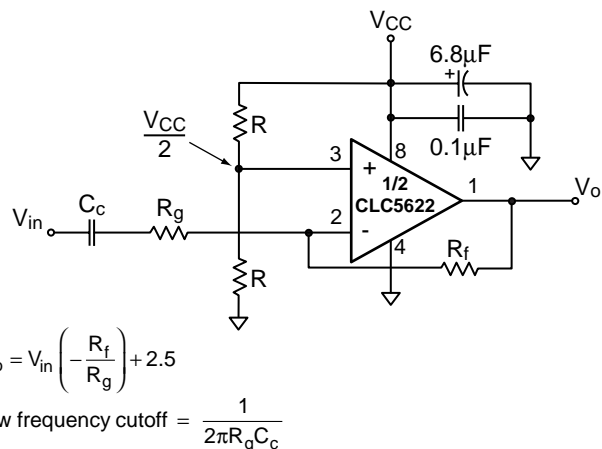


Figure 4: AC Coupled Inverting Configuration

## Dual Supply Operation

The CLC5622 operates on dual supplies as well as single supplies. The non-inverting and inverting configurations are shown in Figures 5 and 6.

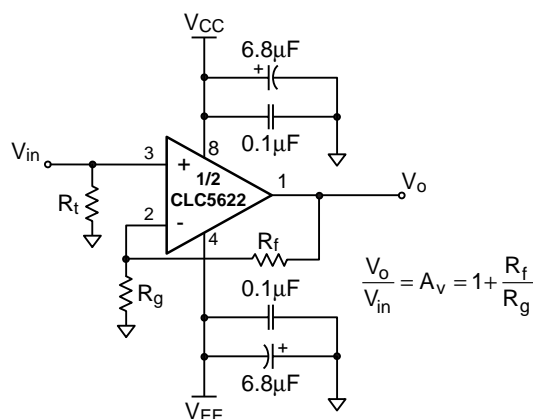


Figure 5: Dual Supply Non-Inverting Configuration

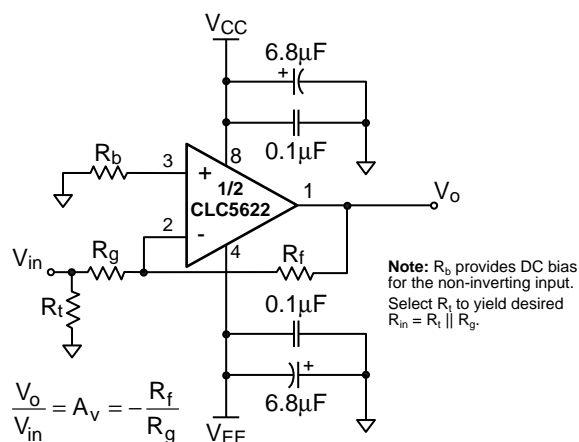


Figure 6: Dual Supply Inverting Configuration

## Feedback Resistor Selection

The feedback resistor,  $R_f$ , affects the loop gain and frequency response of a current feedback amplifier. Optimum performance of the CLC5622, at a gain of +2V/V, is achieved with  $R_f$  equal to 750 $\Omega$ . The frequency response plots in the **Typical Performance** sections illustrate the recommended  $R_f$  for several gains. These recommended values of  $R_f$  provide the maximum bandwidth with minimal peaking. Within limits,  $R_f$  can be adjusted to optimize the frequency response.

- Decrease  $R_f$  to peak frequency response and extend bandwidth
- Increase  $R_f$  to roll off frequency response and compress bandwidth

As a rule of thumb, if the recommended  $R_f$  is doubled, then the bandwidth will be cut in half.

## Unity Gain Operation

The recommended  $R_f$  for unity gain (+1V/V) operation is 1.2k $\Omega$ .  $R_g$  is left open. Parasitic capacitance at the inverting node may require a slight increase in  $R_f$  to maintain a flat frequency response.

## Load Termination

The CLC5622 can source and sink near equal amounts of current. For optimum performance, the load should be tied to  $V_{cm}$ .

## Driving Cables and Capacitive Loads

When driving cables, double termination is used to prevent reflections. For capacitive load applications, a small series resistor at the output of the CLC5622 will improve stability and settling performance. The **Frequency Response vs.  $C_L$**  plot, shown below in Figure 7, gives the recommended series resistance value for optimum flatness at various capacitive loads.

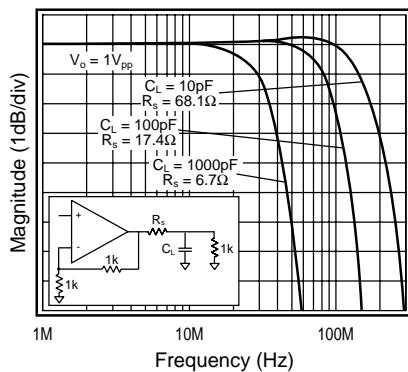


Figure 7: Frequency Response vs.  $C_L$

## Transmission Line Matching

One method for matching the characteristic impedance ( $Z_0$ ) of a transmission line or cable is to place the appropriate resistor at the input or output of the amplifier.

Figure 8 shows typical inverting and non-inverting circuit configurations for matching transmission lines.

Non-inverting gain applications:

- Connect  $R_g$  directly to ground.
- Make  $R_1$ ,  $R_2$ ,  $R_6$ , and  $R_7$  equal to  $Z_0$ .
- Use  $R_3$  to isolate the amplifier from reactive loading caused by the transmission line, or by parasitics.

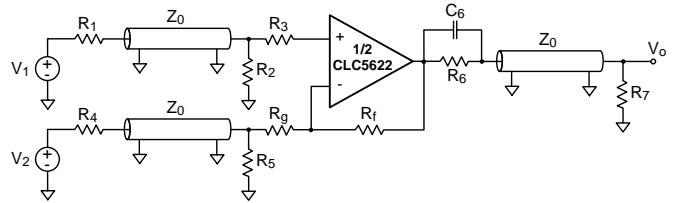


Figure 8: Transmission Line Matching

Inverting gain applications:

- Connect  $R_3$  directly to ground.
- Make the resistors  $R_4$ ,  $R_6$ , and  $R_7$  equal to  $Z_0$ .
- Make  $R_5 \parallel R_g = Z_0$ .

The input and output matching resistors attenuate the signal by a factor of 2, therefore additional gain is needed. Use  $C_6$  to match the output transmission line over a greater frequency range.  $C_6$  compensates for the increase of the amplifier's output impedance with frequency.

## Power Dissipation

Follow these steps to determine the power consumption of the CLC5622:

1. Calculate the quiescent (no-load) power:  

$$P_{amp} = I_{CC} (V_{CC} - V_{EE})$$
2. Calculate the RMS power at the output stage:  

$$P_o = (V_{CC} - V_{load}) (I_{load})$$
, where  $V_{load}$  and  $I_{load}$  are the RMS voltage and current across the external load.
3. Calculate the total RMS power:  

$$P_t = P_{amp} + P_o$$

The maximum power that the DIP and SOIC packages can dissipate at a given temperature is illustrated in Figure 9. The power derating curve for any CLC5622 package can be derived by utilizing the following equation:

$$\frac{(175^\circ - T_{amb})}{\theta_{JA}}$$

where

$T_{amb}$  = Ambient temperature ( $^\circ\text{C}$ )

$\theta_{JA}$  = Thermal resistance, from junction to ambient, for a given package ( $^\circ\text{C/W}$ )



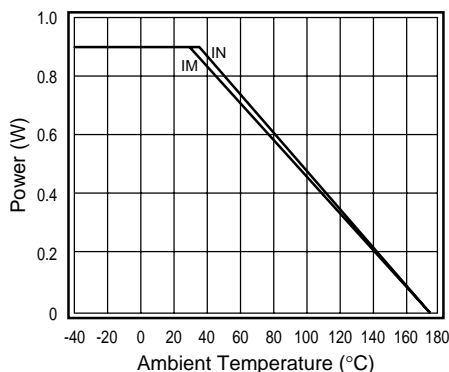


Figure 9: Power Derating Curves

### Layout Considerations

A proper printed circuit layout is essential for achieving high frequency performance. Comlinear provides evaluation boards for the CLC5622 (CLC730038-DIP, CLC730036-SOIC) and suggests their use as a guide for high frequency layout and as an aid for device testing and characterization.

General layout and supply bypassing play major roles in high frequency performance. Follow the steps below as a basis for high frequency layout:

- Include 6.8 $\mu$ F tantalum and 0.1 $\mu$ F ceramic capacitors on both supplies.
- Place the 6.8 $\mu$ F capacitors within 0.75 inches of the power pins.
- Place the 0.1 $\mu$ F capacitors less than 0.1 inches from the power pins.
- Remove the ground plane under and around the part, especially near the input and output pins to reduce parasitic capacitance.
- Minimize all trace lengths to reduce series inductances.
- Use flush-mount printed circuit board pins for prototyping, never use high profile DIP sockets.

### Evaluation Board Information

A data sheet is available for the CLC730038/ CLC730036 evaluation boards. The evaluation board data sheet provides:

- Evaluation board schematics
- Evaluation board layouts
- General information about the boards

The evaluation boards are designed to accommodate dual supplies. The boards can be modified to provide single supply operation. For best performance; 1) do not connect the unused supply, 2) ground the unused supply pin.

### SPICE Models

SPICE models provide a means to evaluate amplifier designs. Free SPICE models are available for National's monolithic amplifiers that:

- Support Berkeley SPICE 2G and its many derivatives
- Reproduce typical DC, AC, Transient, and Noise performance
- Support room temperature simulations

The **readme** file that accompanies the diskette lists released models, and provides a list of modeled parameters. The application note OA-18, Simulation SPICE Models for National's Op Amps, contains schematics and a reproduction of the readme file.

## Application Circuits

### Single Supply Cable Driver

The typical application shown below shows one of the CLC5622 amplifiers driving 10m of 75 $\Omega$  coaxial cable. The CLC5622 is set for a gain of +2V/V to compensate for the divide-by-two voltage drop at  $V_o$ .

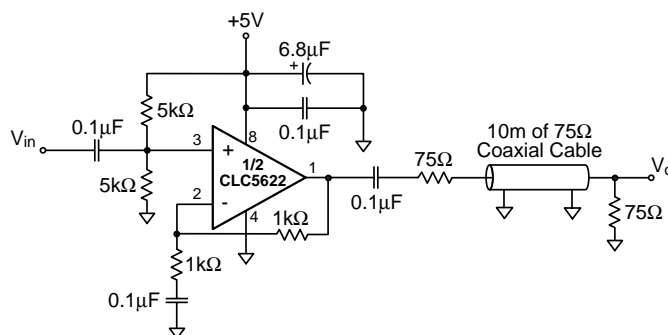


Figure 10: Single Supply Cable Driver

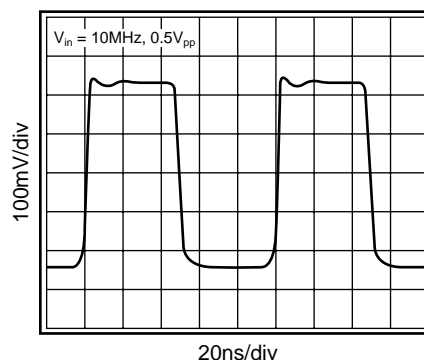
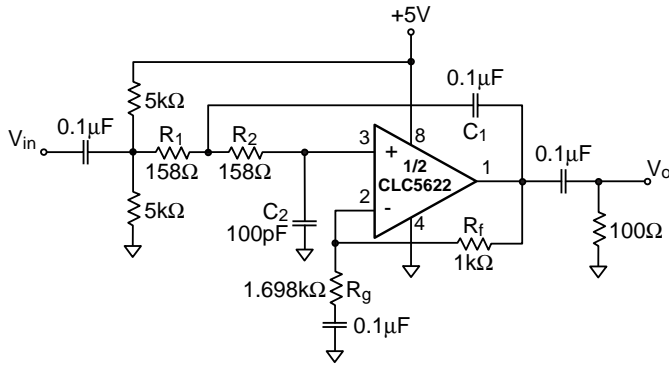


Figure 11: Response After 10m of Cable

### Single Supply Lowpass Filter

Figures 12 and 13 illustrate a lowpass filter and design equations. The circuit operates from a single supply of +5V. The voltage divider biases the non-inverting input to 2.5V. And the input is AC coupled to prevent the need for level shifting the input signal at the source. Use the design equations to determine  $R_1$ ,  $R_2$ ,  $C_1$ , and  $C_2$  based on the desired Q and corner frequency.



**Figure 12: Lowpass Filter Topology**

$$\text{Gain} = K = 1 + \frac{R_f}{R_g}$$

$$\text{Corner frequency} = \omega_c = \sqrt{\frac{1}{R_1 R_2 C_1 C_2}}$$

$$Q = \frac{1}{\sqrt{\frac{R_2 C_2}{R_1 C_1} + \frac{R_1 C_2}{R_2 C_1} + (1-K) \sqrt{\frac{R_1 C_1}{R_2 C_2}}}}$$

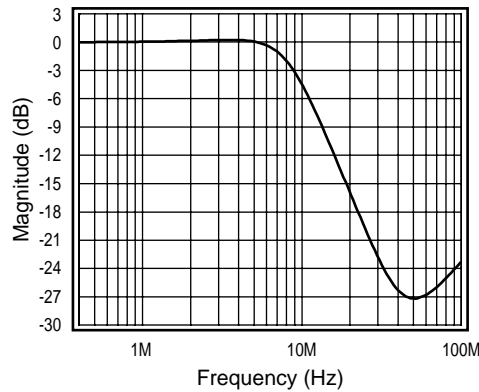
For  $R_1 = R_2 = R$  and  $C_1 = C_2 = C$

$$\omega_c = \frac{1}{RC}$$

$$Q = \frac{1}{(3-K)}$$

**Figure 13: Design Equations**

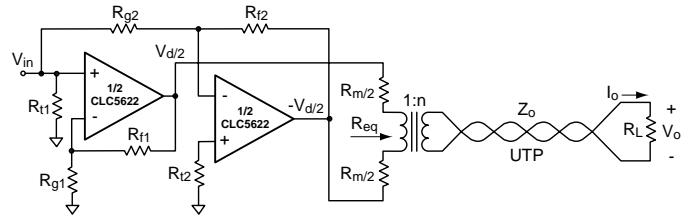
This example illustrates a lowpass filter with  $Q = 0.707$  and corner frequency  $f_c = 10\text{MHz}$ . A  $Q$  of 0.707 was chosen to achieve a maximally flat, Butterworth response. Figure 14 indicates the filter response.



**Figure 14: Lowpass Response**

## Differential Line Driver With Load Impedance Conversion

The circuit shown in the **Typical Application** schematic on the front page and in Figure 15, operates as a differential line driver. The transformer converts the load impedance to a value that best matches the CLC5622's output capabilities. The single-ended input signal is converted to a differential signal by the CLC5622. The line's characteristic impedance is matched at both the input and the output. The schematic shows Unshielded Twisted Pair for the transmission line; other types of lines can also be driven.



**Figure 15: Differential Line Driver with Load Impedance Conversion**

Set up the CLC5622 as a difference amplifier:

$$\frac{V_d}{V_{in}} = 2 \cdot \left( 1 + \frac{R_{f1}}{R_{g1}} \right) = 2 \cdot \frac{R_{f2}}{R_{g2}}$$

Make the best use of the CLC5622's output drive capability as follows:

$$R_m + R_{eq} = \frac{2 \cdot V_{max}}{I_{max}}$$

where  $R_{eq}$  is the transformed value of the load impedance,  $V_{max}$  is the Output Voltage Range, and  $I_{max}$  is the maximum Output Current.

Match the line's characteristic impedance:

$$R_L = Z_o$$

$$R_m = R_{eq}$$

$$n = \sqrt{\frac{R_L}{R_{eq}}}$$

Select the transformer so that it loads the line with a value very near  $Z_o$  over frequency range. The output impedance of the CLC5622 also affects the match. With an ideal transformer we obtain:

$$\text{Return Loss} = -20 \cdot \log_{10} \left| \frac{n^2 \cdot Z_{o(5622)}(j\omega)}{Z_o} \right|, \text{dB}$$

where  $Z_{o(5622)}(j\omega)$  is the output impedance of the CLC5622 and  $|Z_{o(5622)}(j\omega)| \ll R_{m1}$ .

The load voltage and current will fall in the ranges:

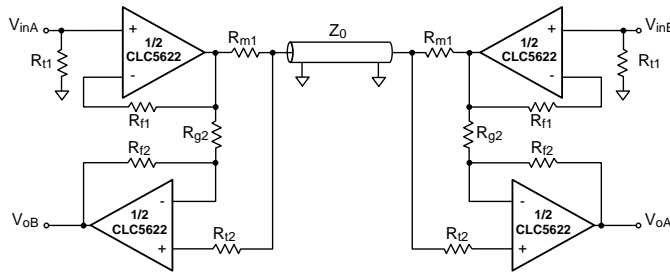
$$|V_o| \leq n \cdot V_{\max}$$

$$|I_o| \leq \frac{I_{\max}}{n}$$

The CLC5622's high output drive current and low distortion make it a good choice for this application.

### Full Duplex Cable Driver

The circuit shown in Figure 16 below, operates as a full duplex cable driver which allows simultaneous transmission and reception of signals on one transmission line. The circuit on either side of the transmission line uses are CLC5622 as a cable driver, and the second CLC5622 as a receiver.  $V_{oA}$  is an attenuated version of  $V_{inA}$ , while  $V_{oB}$  is an attenuated version of  $V_{inB}$ .



**Figure 16: Full Duplex Cable Driver**

$R_{m1}$  is used to match the transmission line.  $R_{f2}$  and  $R_{g2}$  set the DC gain of the CLC5622, which is used in a difference mode.  $R_{t2}$  provides good CMRR and DC offset. The transmitting CLC5622's are shown in a unity gain configuration because they consume the least power of any gain, for a given load. For proper operation we need  $R_{f2} = R_{g2}$ .

The receiver output voltages are:

$$V_{outA(B)} \approx V_{inA(B)} \cdot A + \frac{V_{inB(A)}}{2} \cdot \left( 1 - \frac{R_{f2}}{R_{g2}} + \frac{Z_{o(5622)}(j\omega)}{R_{m1}} \right)$$

where A is the attenuation of the cable,  $Z_{o(5622)}(j\omega)$  is the output impedance of the CLC5622 (see the **Closed-Loop Output Resistance** plot), and  $|Z_{o(5622)}(j\omega)| \ll R_{m1}$ .

We selected the component values as follows:

- $R_{f1} = 1.2k\Omega$ , the recommended value for CLC5622 at unity gain
- $R_{m1} = Z_0 = 50\Omega$ , the characteristic impedance of the transmission line
- $R_{f2} = R_{g2} = 750\Omega \geq R_{m1}$ , the recommended value for the CLC5622 at  $A_v = 2$
- $R_{t2} = (R_{f2} \parallel R_{g2}) - \frac{R_{m1}}{2} = 25\Omega$

These values give excellent isolation from the other input:

$$\frac{V_{oA(B)}}{V_{inB(A)}} \approx -38dB, f = 5.0MHz$$

The CLC5622 provides large output current drive, while consuming little supply current, at the nominal bias point. It also produces low distortion with large signal swings and heavy loads. These features make the CLC5622 an excellent choice for driving transmission lines.

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