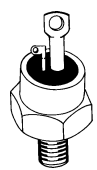
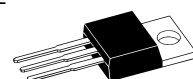
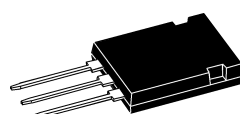
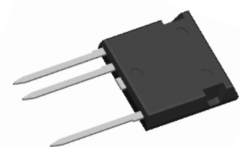
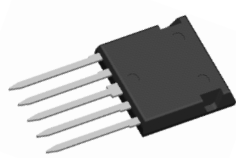


Contents

Package style		$I_{T(AV)M}$	V_{RRM}/V_{DRM} (V)					Type	Page			
			800	1200	1400	1600	2200					
1		2		1	16	●	●				CS 8-...io2	E1 - 2
3		2	19	●	●						CS 19-...ho1	E1 - 4
		3	19	●	●						CS 19-...ho1S	
4a ISOPLUS 247™		5	18					●			CS 20-22moF1 new	E1 - 7
		6	21	●							FCC 20-08io new	E1 - 9
5 ISOPLUS i4-PAC™		4	19		●	●	●				CS 20-...io1	E1 - 12
		1	32	●	●		●				CS 23	E1 - 15
		4	31		●	●	●				CS 30	E1 - 18
6 ISOPLUS i4-PAC™		1	69	●	●	●					CS 35	E1 - 21
		4 4a	48	●	●		●	●			CS 45-...io1 CS 45-...io1R new	E1 - 23
ISOPLUS... = isolated back surface												

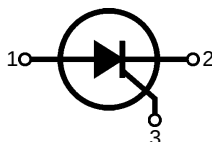
Phase Control Thyristors

$$V_{RRM} = 800-1200 \text{ V}$$

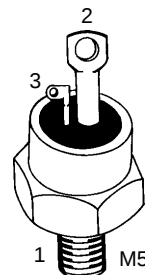
$$I_{T(RMS)} = 25 \text{ A}$$

$$I_{T(AV)M} = 16 \text{ A}$$

V_{RSM} V_{DSM} V	V_{RRM} V_{DRM} V	Type
900	800	CS 8-08io2
1300	1200	CS 8-12io2



TO-64



1 = Anode, 2 = Cathode, 3 = Gate

Symbol	Test Conditions	Maximum Ratings
$I_{T(RMS)}$	$T_{VJ} = T_{VJM}$	25 A
$I_{T(AV)M}$	$T_{case} = 85^{\circ}\text{C}; 180^{\circ}$ sine	16 A
I_{TSM}	$T_{VJ} = 45^{\circ}\text{C}; V_R = 0$	$t = 10 \text{ ms (50 Hz), sine}$ 250 A $t = 8.3 \text{ ms (60 Hz), sine}$ 270 A
	$T_{VJ} = T_{VJM}; V_R = 0$	$t = 10 \text{ ms (50 Hz), sine}$ 200 A $t = 8.3 \text{ ms (60 Hz), sine}$ 220 A
I^2t	$T_{VJ} = 45^{\circ}\text{C}; V_R = 0$	$t = 10 \text{ ms (50 Hz), sine}$ 310 A^2s $t = 8.3 \text{ ms (60 Hz), sine}$ 306 A^2s
	$T_{VJ} = T_{VJM}; V_R = 0$	$t = 10 \text{ ms (50 Hz), sine}$ 200 A^2s $t = 8.3 \text{ ms (60 Hz), sine}$ 200 A^2s
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}; f = 50 \text{ Hz}, t_p = 200 \mu\text{s}; V_D = 2/3 V_{DRM}; I_G = 0.2 \text{ A}; di_G/dt = 0.2 \text{ A}/\mu\text{s}$	repetitive, $I_T = 48 \text{ A}$ 150 $\text{A}/\mu\text{s}$ non repetitive, $I_T = I_{T(AV)M}$ 500 $\text{A}/\mu\text{s}$
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM}; R_{GK} = \infty; \text{method 1 (linear voltage rise)}$	$V_{DR} = 2/3 V_{DRM}$ 1000 $\text{V}/\mu\text{s}$
P_{GM}	$T_{VJ} = T_{VJM}; t_p = 30 \mu\text{s}$	10 W
$P_{G(AV)}$	$I_T = I_{T(AV)M}; t_p = 300 \mu\text{s}$	5 W 0.5 W
V_{RGM}		10 V
T_{VJ}		-40...+125 $^{\circ}\text{C}$
T_{VJM}		125 $^{\circ}\text{C}$
T_{stg}		-40...+125 $^{\circ}\text{C}$
M_d	Mounting torque	2.5 Nm 22 lb.in.
Weight		6 g

Features

- Thyristor for line frequencies
- International standard package JEDEC TO-64
- Planar glassivated chip
- Long-term stability of blocking currents and voltages

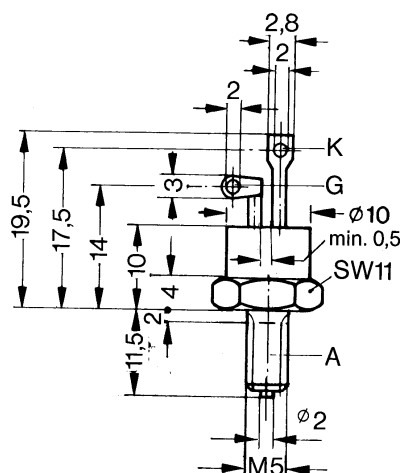
Applications

- Motor control
- Power converter
- AC power controller

Advantages

- Space and weight savings
- Simple mounting
- Improved temperature and power cycling

Dimensions in mm (1 mm = 0.0394")



Data according to IEC 60747
IXYS reserves the right to change limits, test conditions and dimensions

Symbol	Test Conditions	Characteristic Values
I_R, I_D	$T_{VJ} = T_{VJM}; V_R = V_{RRM}; V_D = V_{DRM}$	≤ 3 mA
V_T	$I_T = 33$ A; $T_{VJ} = 25^\circ\text{C}$	≤ 1.6 V
V_{T0}	For power-loss calculations only ($T_{VJ} = 125^\circ\text{C}$)	1.0 V
r_T		18 mΩ
V_{GT}	$V_D = 6$ V; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = -40^\circ\text{C}$	≤ 2.5 V ≤ 3.5 V
I_{GT}	$V_D = 6$ V; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = -40^\circ\text{C}$	≤ 30 mA ≤ 50 mA
V_{GD}	$T_{VJ} = T_{VJM}; V_D = 2/3 V_{DRM}$	≤ 0.2 V
I_{GD}		≤ 1 mA
I_L	$T_{VJ} = 25^\circ\text{C}; t_p = 10$ μs $I_G = 0.09$ A; $di_G/dt = 0.09$ A/μs	≤ 100 mA
I_H	$T_{VJ} = 25^\circ\text{C}; V_D = 6$ V; $R_{GK} = \infty$	≤ 80 mA
t_{gd}	$T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$ $I_G = 0.09$ A; $di_G/dt = 0.09$ A/μs	≤ 2 μs
t_q	$T_{VJ} = T_{VJM}; I_T = 16$ A, $t_p = 300$ μs; $di/dt = -20$ A/μs $V_R = 100$ V; $dv/dt = 20$ V/μs; $V_D = 2/3 V_{DRM}$	typ. 60 μs
R_{thJC}	DC current	1.5 K/W
R_{thJH}	DC current	2.5 K/W
d_s	Creepage distance on surface	1.55 mm
d_A	Strike distance through air	1.55 mm
a	Max. acceleration, 50 Hz	50 m/s ²

Accessories:

Nut M5 DIN 439/SW8

Lock washer A5 DIN 128

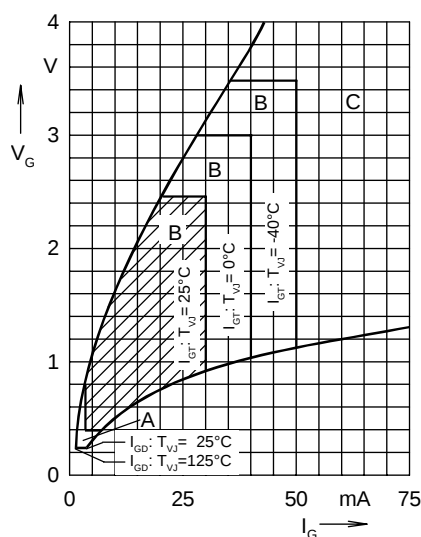


Fig. 1 Gate voltage and gate current
Triggering:
A = no; B = possible; C = safe

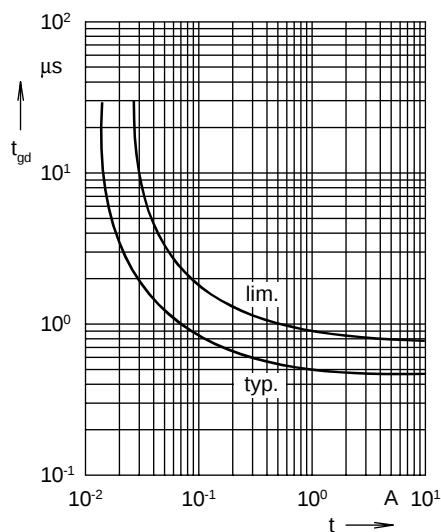


Fig. 2 Gate controlled delay time t_{gd}

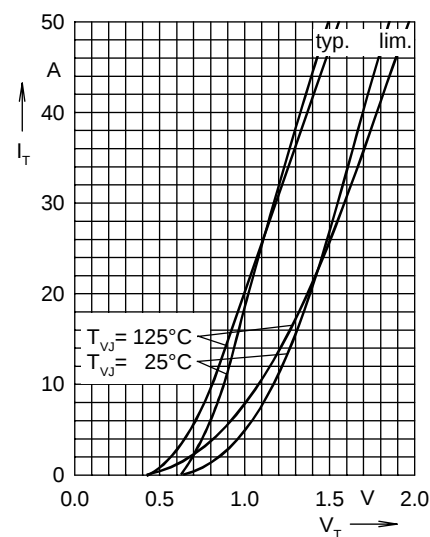


Fig. 3 On-state characteristics

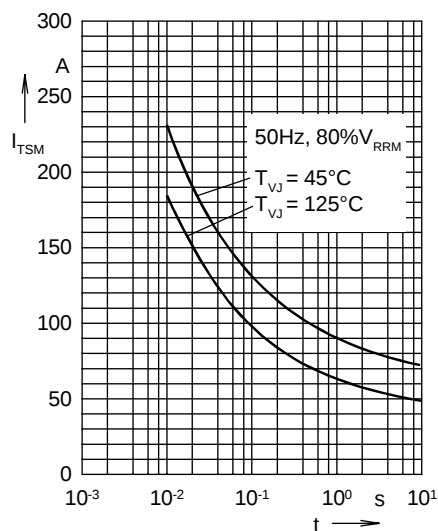


Fig. 4 Surge overload current
 I_{TSM} : crest value, t : duration

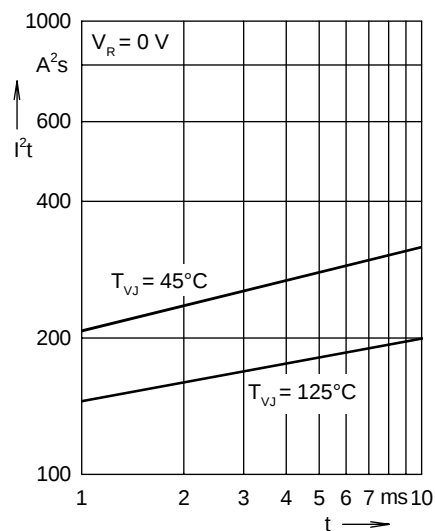


Fig. 5 I^2t versus time (1-10 ms)

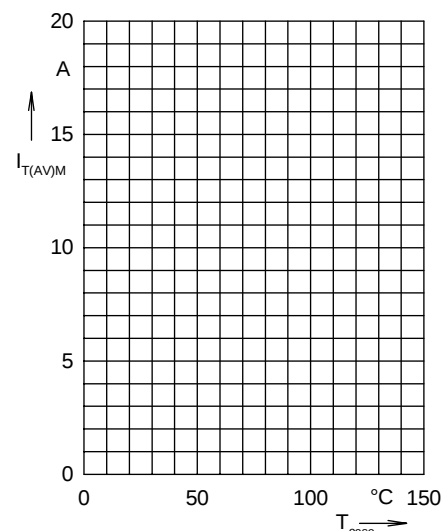


Fig. 6 Maximum forward current at case temperature 180° sine

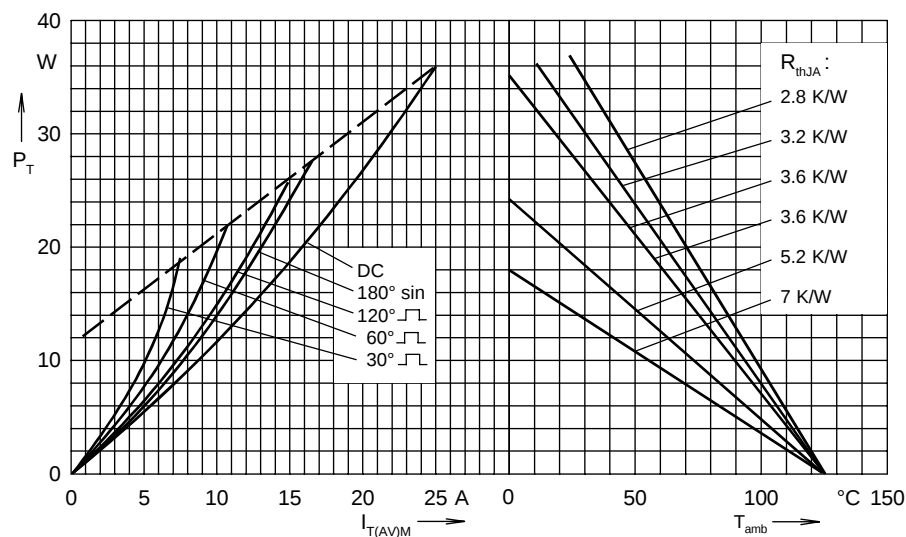


Fig. 7 Power dissipation versus on-state current and ambient temperature

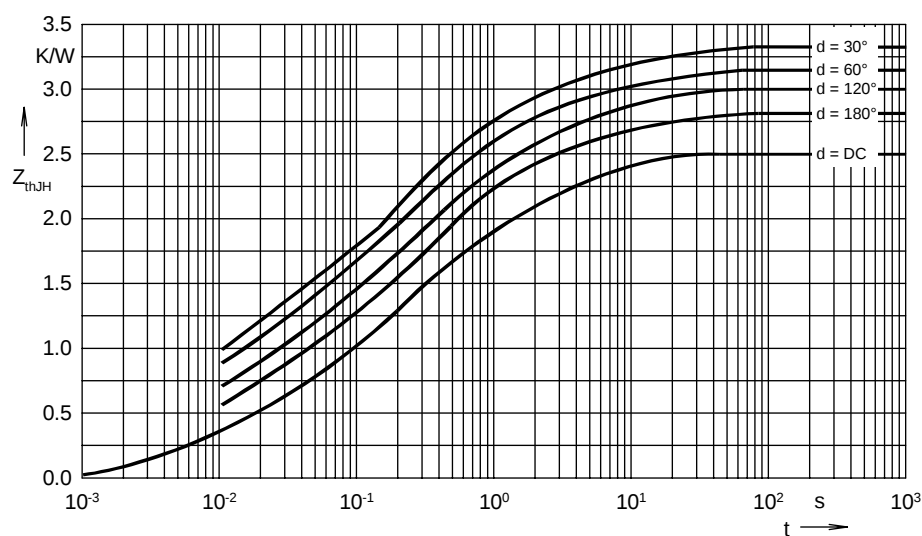


Fig. 8 Transient thermal impedance junction to heatsink

R_{thJH} for various conduction angles d :

d	R_{thJH} (K/W)
DC	2.5
180°	2.79
120°	2.95
60°	3.17
30°	3.32

Constants for Z_{thJH} calculation:

i	R_{thi} (K/W)	t_i (s)
1	0.252	0.005
2	0.333	0.0225
3	0.5	0.145
4	0.833	0.43
5	0.416	2.75
6	0.166	23

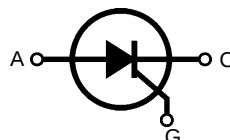
Phase Control Thyristors

$$V_{RRM} = 800-1200 \text{ V}$$

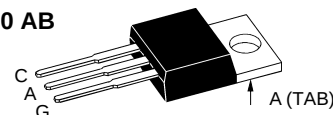
$$I_{T(RMS)} = 29 \text{ A}$$

$$I_{T(AV)M} = 19 \text{ A}$$

V_{RSM} V_{DSM}	V_{RRM} V_{DRM}	Type	Type
V	V	TO 220	TO 263
800	800	CS 19-08ho1	CS 19-08ho1S
1200	1200	CS 19-12ho1	CS 19-12ho1S



TO-220 AB



TO-263 AA



A = Anode, C = Cathode, G = Gate

Symbol	Test Conditions	Maximum Ratings	
$I_{T(RMS)}$	$T_{VJ} = T_{VJM}$	29	A
$I_{T(AV)M}$	$T_C = 85^\circ\text{C}; 180^\circ \text{ sine}$	19	A
I_{TSM}	$T_{VJ} = 45^\circ\text{C};$ $V_R = 0 \text{ V}$	$t = 10 \text{ ms (50 Hz), sine}$	160 A
		$t = 8.3 \text{ ms (60 Hz), sine}$	180 A
	$T_{VJ} = T_{VJM}$ $V_R = 0 \text{ V}$	$t = 10 \text{ ms (50 Hz), sine}$	140 A
		$t = 8.3 \text{ ms (60 Hz), sine}$	160 A
I^2t	$T_{VJ} = 45^\circ\text{C}$ $V_R = 0 \text{ V}$	$t = 10 \text{ ms (50 Hz), sine}$	128 A ² s
		$t = 8.3 \text{ ms (60 Hz), sine}$	134 A ² s
	$T_{VJ} = T_{VJM}$ $V_R = 0 \text{ V}$	$t = 10 \text{ ms (50 Hz), sine}$	100 A ² s
		$t = 8.3 \text{ ms (60 Hz), sine}$	105 A ² s
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}$ $f = 50 \text{ Hz}, t_p = 200 \mu\text{s}$ $V_D = 2/3 V_{DRM}$ $I_G = 0.15 \text{ A}$ $di_G/dt = 0.15 \text{ A}/\mu\text{s}$	repetitive, $I_T = 20 \text{ A}$	100 A/ μs
		non repetitive, $I_T = I_{T(AV)M}$	500 A/ μs
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM};$ $R_{GK} = \infty; \text{ method 1 (linear voltage rise)}$	$V_{DR} = 2/3 V_{DRM}$	500 V/ μs
P_{GM}	$T_{VJ} = T_{VJM}$ $I_T = I_{T(AV)M}$	$t_p = 30 \mu\text{s}$	5 W
P_{GAV}		$t_p = 300 \mu\text{s}$	2.5 W
			0.5 W
V_{RGM}			10 V
T_{VJ}		-40...+125	$^\circ\text{C}$
T_{VJM}		125	$^\circ\text{C}$
T_{stg}		-40...+125	$^\circ\text{C}$
M_d	Mounting torque with screw M3; TO220	0.45/4	Nm/lb.in.
	Mounting torque with screw M3.5; TO220	0.55/5	Nm/in.
Weight		2	g

Features

- SCR for frequency up to 400Hz
- International standard package
- High performance glass passivated chip
- Long-term stability of leakage current and blocking voltage
- Epoxy meets UL 94V-0

Applications

- Motor control
- Power converter
- AC power controller
- Light and temperature control
- SCR for inrush current limiting in power supplies or AC drive

Advantages

- Space and weight savings
- Simple mounting

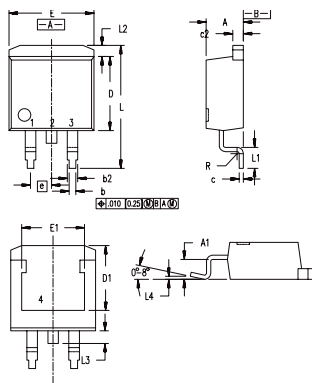
Data according to IEC 60747

IXYS reserves the right to change limits, test conditions and dimensions

Symbol	Test Conditions	Characteristic Values		
I_R, I_D	$T_{VJ} = T_{VJM}; V_R = V_{RRM}; V_D = V_{DRM}$	$\leq$	5	mA
V_T	$I_T = 20 \text{ A}; T_{VJ} = 25^\circ\text{C}$	$\leq$	1.6	V
V_{T0}	For power-loss calculations only ($T_{VJ} = 125^\circ\text{C}$)		0.85	V
r_T			27	m Ω
V_{GT}	$V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$	$\leq$	1.5	V
	$T_{VJ} = -40^\circ\text{C}$	$\leq$	2.5	V
I_{GT}	$V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$	$\leq$	25	mA
	$T_{VJ} = -40^\circ\text{C}$	$\leq$	50	mA
V_{GD}	$T_{VJ} = T_{VJM}; V_D = 2/3 V_{DRM}$	$\leq$	0.2	V
I_{GD}		$\leq$	3	mA
I_L	$T_{VJ} = 25^\circ\text{C}; t_p = 10 \mu\text{s}$ $I_G = 0.1 \text{ A}; di_G/dt = 0.1 \text{ A}/\mu\text{s}$	$\leq$	75	mA
I_H	$T_{VJ} = 25^\circ\text{C}; V_D = 6 \text{ V}; R_{GK} = \infty$	$\leq$	50	mA
t_{gd}	$T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$ $I_G = 0.1 \text{ A}; di_G/dt = 0.1 \text{ A}/\mu\text{s}$	$\leq$	2	μs
R_{thJC}	DC current		1.0	K/W
R_{thCK}	DC current		typ 0.25	K/W
a	Max. acceleration, 50 Hz		50	m/s ²

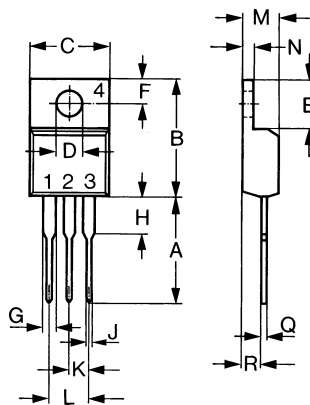
Dimensions in mm (1 mm = 0.0394")

TO 263 AA



Dim.	Millimeter		Inches	
	Min.	Max.	Min.	Max.
A	4.06	4.83	.160	.190
A1	2.03	2.79	.080	.110
b	0.51	0.99	.020	.039
b2	1.14	1.40	.045	.055
c	0.46	0.74	.018	.029
c2	1.14	1.40	.045	.055
D	8.64	9.65	.340	.380
D1	7.11	8.13	.280	.320
E	9.65	10.29	.380	.405
E1	6.86	8.13	.270	.320
e	2.54	BSC	.100	BSC
L	14.61	15.88	.575	.625
L1	2.29	2.79	.090	.110
L2	1.02	1.40	.040	.055
L3	1.27	1.78	.050	.070
L4	0	0.38	0	.015
R	0.46	0.74	.018	.029

TO 220 AB

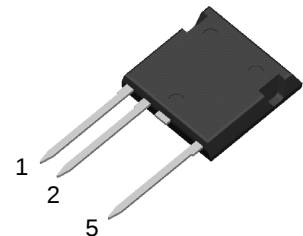
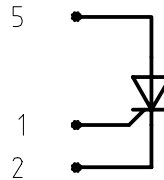


Dim.	Millimeter		Inches	
	Min.	Max.	Min.	Max.
A	12.70	13.97	0.500	0.550
B	14.73	16.00	0.580	0.630
C	9.91	10.66	0.390	0.420
D	3.54	4.08	0.139	0.161
E	5.85	6.85	0.230	0.270
F	2.54	3.18	0.100	0.125
G	1.15	1.65	0.045	0.065
H	2.79	5.84	0.110	0.230
J	0.64	1.01	0.025	0.040
K	2.54	BSC	0.100	BSC
M	4.32	4.82	0.170	0.190
N	1.14	1.39	0.045	0.055
Q	0.35	0.56	0.014	0.022
R	2.29	2.79	0.090	0.110

High Voltage Phase Control Thyristor

in High Voltage
ISOPLUS i4-PAC™

V_{RSM}	V_{RRM}	Type
V_{DSM}	V_{DRM}	
V	V	
2200	2200	CS 20-22moF1



$$\begin{aligned} V_{DRM} &= V_{RRM} = 2200 \text{ V} \\ I_{T(AV)} &= 18 \text{ A} \\ I_{TSM} &= 200 \text{ A} \end{aligned}$$

Thyristors

Symbol	Conditions	Maximum Ratings	
V_{DRM}, V_{RRM}		2200	V
$I_{T(AV)}$	sine 180°; $T_C = 90^\circ\text{C}$	18	A
$I_{T(AV)}$	square; $d = 1/3$; $T_C = 90^\circ\text{C}$	16	A
I_{TSM}	sine 180°; $t = 10 \text{ ms}$; $V_R = 0 \text{ V}$; $T_{VJ} = 25^\circ\text{C}$	200	A
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}$ repetitive, $I_T = 40 \text{ A}$ $f = 50 \text{ Hz}$, $t_p = 200 \mu\text{s}$ $V_D = 2/3 V_{DRM}$ $I_G = 0.45 \text{ A}$ $di_G/dt = 0.45 \text{ A}/\mu\text{s}$	100	A/ μs
	non repetitive, $I_T = 20 \text{ A}$	250	A/ μs
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM}$; $V_{DR} = 2/3 V_{DRM}$ $R_{GK} = \infty$; method 1 (linear voltage rise)	2500	V/ μs

Symbol	Conditions	Characteristic Values ($T_{VJ} = 25^\circ\text{C}$, unless otherwise specified)		
		min.	typ.	max.
V_T	$I_T = 20 \text{ A}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		1.3 1.3	1.5 V V
V_{GT} I_{GT}	$V_D = 6 \text{ V}$			2.3 V 250 mA
V_{GD} I_{GD}	$T_{VJ} = T_{VJM}$; $V_D = 2/3 V_{DRM}$			0.2 V 5 mA
I_L	$t_p = 10 \mu\text{s}$; $V_D = 6 \text{ V}$ $I_G = 0.45 \text{ A}$; $di_G/dt = 0.45 \text{ A}/\mu\text{s}$			500 mA
I_H	$V_D = 6 \text{ V}$; $R_{GK} = \infty$			150 mA
t_{gd}	$V_D = 1/2 V_{DRM}$ $I_G = 0.45 \text{ A}$; $di_G/dt = 0.45 \text{ A}/\mu\text{s}$			2 μs
I_R, I_D	$V_R = V_{RRM}$; $V_D = V_{DRM}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		2	50 μA mA
R_{thJC}	DC current			0.92 K/W

Features

- high voltage thyristor
 - for line frequency
 - chip technology for long term stability
- ISOPLUS i4-PAC™ high voltage package
 - isolated back surface
 - enlarged creepage towards heatsink
 - enlarged creepage between high voltage pins
 - application friendly pinout
 - high reliability
 - industry standard outline

Applications

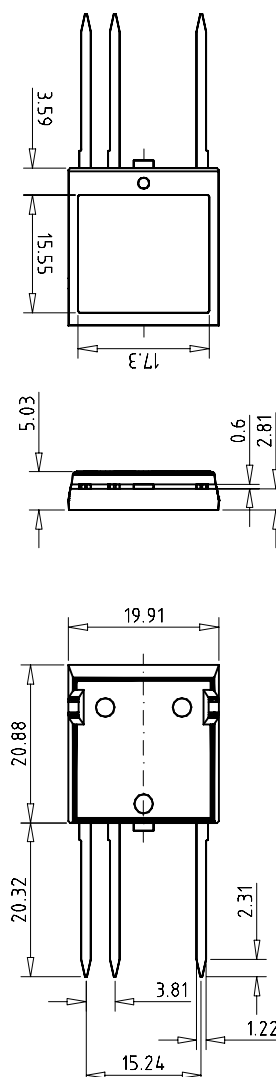
- controlled rectifiers
 - power supplies
 - drives
- AC switches
- capacitor discharge control
 - flash tubes
 - x ray and laser generators

Component

Symbol	Conditions	Maximum Ratings	
T_{VJ}		-40...+125	°C
T_{stg}		-55...+125	°C
V_{ISOL}	$I_{ISOL} \leq 1 \text{ mA}; 50/60 \text{ Hz}$	2500	V~
F_C	mounting force with clip	20...120	N

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
d_S, d_A	A pin - K pin	7		mm
d_S, d_A	pin - backside metal	5.5		mm
R_{thCH}	with heatsink compound	0.15		K/W
Weight		9		g

Dimensions in mm (1 mm = 0.0394")

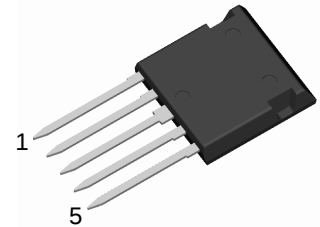
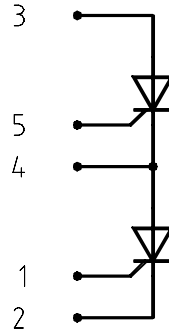


Phase Control Thyristors

-Phaseleg Topology-
in ISOPLUS i4-PAC™

$$\begin{aligned} V_{\text{DRM}} = V_{\text{RRM}} &= 800 \text{ V} \\ I_{\text{T(AV)}} &= 21 \text{ A} \\ I_{\text{TSM}} &= 300 \text{ A} \end{aligned}$$

V_{RSM}	V_{RRM}	Type
V_{DSM}	V_{DRM}	
V	V	
900	800	FCC 21-08io



Thyristors

Symbol	Conditions	Maximum Ratings	
$V_{\text{DRM}}, V_{\text{RRM}}$		800	V
$I_{\text{T(AV)}}$	sine 180°; $T_{\text{C}} = 90^{\circ}\text{C}$	21	A
$I_{\text{T(AV)}}$	square; $d = 1/3$; $T_{\text{C}} = 90^{\circ}\text{C}$	20	A
I_{TSM}	sine 180°; $t = 10 \text{ ms}$; $V_{\text{R}} = 0 \text{ V}$; $T_{\text{VJ}} = 25^{\circ}\text{C}$	300	A
$(di/dt)_{\text{cr}}$	$T_{\text{VJ}} = T_{\text{VJM}}$ repetitive, $I_{\text{T}} = 40 \text{ A}$ $f = 50 \text{ Hz}$, $t_{\text{p}} = 200 \mu\text{s}$ $V_{\text{D}} = 2/3 V_{\text{DRM}}$ $I_{\text{G}} = 0.3 \text{ A}$ non repetitive, $I_{\text{T}} = 30 \text{ A}$ $di_{\text{G}}/dt = 0.3 \text{ A}/\mu\text{s}$	150	A/ μs
$(dv/dt)_{\text{cr}}$	$T_{\text{VJ}} = T_{\text{VJM}}$; $V_{\text{DR}} = 2/3 V_{\text{DRM}}$ $R_{\text{GK}} = \infty$; method 1 (linear voltage rise)	1000	V/ μs

Symbol	Conditions	Characteristic Values ($T_{\text{VJ}} = 25^{\circ}\text{C}$, unless otherwise specified)		
		min.	typ.	max.
V_{T}	$I_{\text{T}} = 30 \text{ A}$; $T_{\text{VJ}} = 25^{\circ}\text{C}$ $T_{\text{VJ}} = 125^{\circ}\text{C}$		1.3	1.3 V V
V_{GT} I_{GT}	$V_{\text{D}} = 6 \text{ V}$			1.4 V 55 mA
V_{GD} I_{GD}	$T_{\text{VJ}} = T_{\text{VJM}}$; $V_{\text{D}} = 2/3 V_{\text{DRM}}$			0.2 V 5 mA
I_{L}	$t_{\text{p}} = 10 \mu\text{s}$; $V_{\text{D}} = 6 \text{ V}$ $I_{\text{G}} = 0.3 \text{ A}$; $di_{\text{G}}/dt = 0.3 \text{ A}/\mu\text{s}$			150 mA
I_{H}	$V_{\text{D}} = 6 \text{ V}$; $R_{\text{GK}} = \infty$			100 mA
t_{gd}	$V_{\text{D}} = 1/2 V_{\text{DRM}}$; $V_{\text{D}} = 6 \text{ V}$ $I_{\text{G}} = 0.3 \text{ A}$; $di_{\text{G}}/dt = 0.3 \text{ A}/\mu\text{s}$			2 μs
$I_{\text{R}}, I_{\text{D}}$	$V_{\text{R}} = V_{\text{RRM}}$; $V_{\text{D}} = V_{\text{DRM}}$; $T_{\text{VJ}} = 25^{\circ}\text{C}$ $T_{\text{VJ}} = 125^{\circ}\text{C}$		0.5	50 μA mA
R_{thJC}	DC current			1.0 K/W

Features

- Thyristor
 - for line frequency
 - chip technology for long term stability
- ISOPLUS i4-PAC™ package
 - isolated back surface
 - enlarged creepage towards heatsink
 - application friendly pinout
 - high reliability
 - industry standard outline

Applications

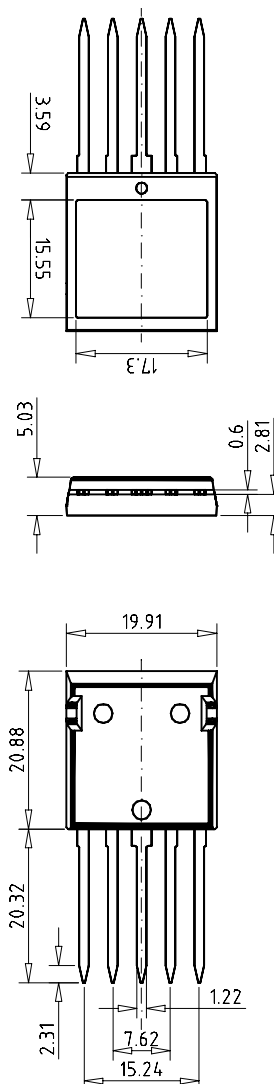
- controlled rectifiers
 - power supplies
 - drives
- AC switches

Component

Symbol	Conditions	Maximum Ratings	
T_{VJ}		-40...+125	°C
T_{stg}		-55...+125	°C
V_{ISOL}	$I_{ISOL} \leq 1 \text{ mA}; 50/60 \text{ Hz}$	2500	V~
F_C	mounting force with clip	20...120	N

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
d_S, d_A	pin - pin	1.7		mm
d_S, d_A	pin - backside metal	5.5		mm
R_{thCH}	with heatsink compound		0.15	K/W
Weight			9	g

Dimensions in mm (1 mm = 0.0394")



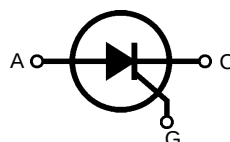
Phase Control Thyristor

$$V_{RRM} = 1200-1600 \text{ V}$$

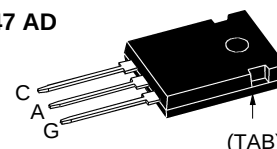
$$I_{T(RMS)} = 30 \text{ A}$$

$$I_{T(AV)M} = 19 \text{ A}$$

V_{RSM} V_{DSM} V	V_{RRM} V_{DRM} V	Type
1200	1200	CS 20-12io1
1400	1400	CS 20-14io1
1600	1600	CS 20-16io1



TO-247 AD



C = Cathode, A = Anode, G = Gate
TAB = Anode

Symbol	Test Conditions	Maximum Ratings
$I_{T(RMS)}$	$T_{VJ} = T_{VJM}$	30 A
$I_{T(AV)M}$	$T_{case} = 85^{\circ}\text{C}; 180^{\circ}$ sine	19 A
I_{TSM}	$T_{VJ} = 45^{\circ}\text{C};$ $V_R = 0 \text{ V}$	$t = 10 \text{ ms (50 Hz), sine}$ 200 A
		$t = 8.3 \text{ ms (60 Hz), sine}$ 215 A
	$T_{VJ} = T_{VJM}$	$t = 10 \text{ ms (50 Hz), sine}$ 180 A
	$V_R = 0 \text{ V}$	$t = 8.3 \text{ ms (60 Hz), sine}$ 195 A
I^2t	$T_{VJ} = 45^{\circ}\text{C}$	$t = 10 \text{ ms (50 Hz), sine}$ 200 A ² s
	$V_R = 0 \text{ V}$	$t = 8.3 \text{ ms (60 Hz), sine}$ 195 A ² s
	$T_{VJ} = T_{VJM}$	$t = 10 \text{ ms (50 Hz), sine}$ 162 A ² s
	$V_R = 0 \text{ V}$	$t = 8.3 \text{ ms (60 Hz), sine}$ 158 A ² s
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}$ $f = 50 \text{ Hz}, t_p = 200 \mu\text{s}$ $V_D = 2/3 V_{DRM}$ $I_G = 0.3 \text{ A}$ $di_G/dt = 0.3 \text{ A}/\mu\text{s}$	repetitive, $I_T = 40 \text{ A}$ 150 A/ μs
		non repetitive, $I_T = I_{T(AV)M}$ 500 A/ μs
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM};$ $R_{GK} = \infty; \text{method 1 (linear voltage rise)}$	$V_{DR} = 2/3 V_{DRM}$ 1000 V/ μs
P_{GM}	$T_{VJ} = T_{VJM}$	$t_p = 30 \mu\text{s}$ 10 W
P_{GAV}	$I_T = I_{T(AV)M}$	$t_p = 300 \mu\text{s}$ 5 W
		0.5 W
V_{RGM}		10 V
T_{VJ}		-40...+125 $^{\circ}\text{C}$
T_{VJM}		125 $^{\circ}\text{C}$
T_{stg}		-40...+125 $^{\circ}\text{C}$
M_d	Mounting torque M3	0.8...1.2 Nm
Weight		6 g

Features

- Thyristor for line frequency
- International standard package JEDEC TO-247
- Planar passivated chip
- Long-term stability of blocking currents and voltages
- Epoxy meets UL 94V-0

Applications

- Motor control
- Power converter
- AC power controller
- Switch-mode and resonant mode power supplies
- Light and temperature control

Advantages

- Easy to mount with 1 screw (isolated mounting screw hole)
- Space and weight savings
- Simple mounting
- Improved temperature and power cycling

Data according to IEC 60747
IXYS reserves the right to change limits, test conditions and dimensions

Symbol	Test Conditions	Characteristic Values
I_R, I_D	$T_{VJ} = T_{VJM}; V_R = V_{RRM}; V_D = V_{DRM}$	≤ 10 mA
V_T	$I_T = 25$ A; $T_{VJ} = 25^\circ\text{C}$	≤ 2.1 V
V_{T0}	For power-loss calculations only ($T_{VJ} = 125^\circ\text{C}$)	1.1 V
r_T		40 mΩ
V_{GT}	$V_D = 6$ V; $T_{VJ} = 25^\circ\text{C}$	≤ 1.0 V
	$T_{VJ} = -40^\circ\text{C}$	≤ 1.2 V
I_{GT}	$V_D = 6$ V; $T_{VJ} = 25^\circ\text{C}$	≤ 65 mA
	$T_{VJ} = -40^\circ\text{C}$	≤ 80 mA
	$T_{VJ} = 125^\circ\text{C}$	≤ 50 mA
V_{GD}	$T_{VJ} = T_{VJM}; V_D = 2/3 V_{DRM}$	≤ 0.2 V
I_{GD}		≤ 5 mA
I_L	$T_{VJ} = 25^\circ\text{C}; t_p = 10$ μs $I_G = 0.3$ A; $di_G/dt = 0.3$ A/μs	≤ 150 mA
I_H	$T_{VJ} = 25^\circ\text{C}; V_D = 6$ V; $R_{GK} = \infty$	≤ 100 mA
t_{gd}	$T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$ $I_G = 0.3$ A; $di_G/dt = 0.3$ A/μs	≤ 2 μs
R_{thJC}	DC current	0.62 K/W
R_{thJH}	DC current	0.82 K/W
a	Max. acceleration, 50 Hz	50 m/s ²

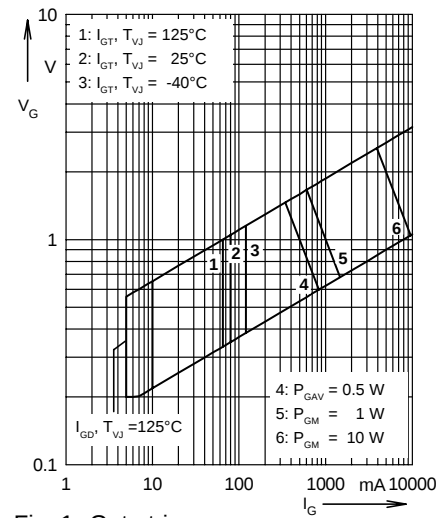


Fig. 1 Gate trigger range

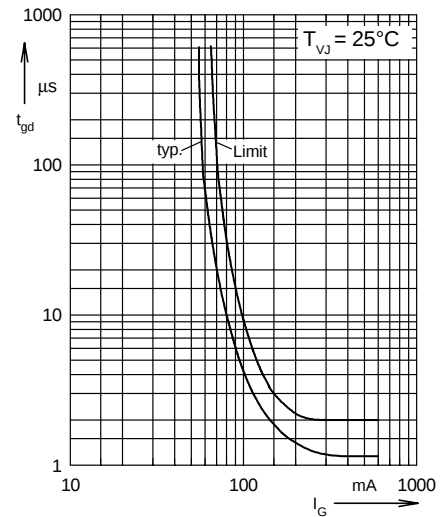
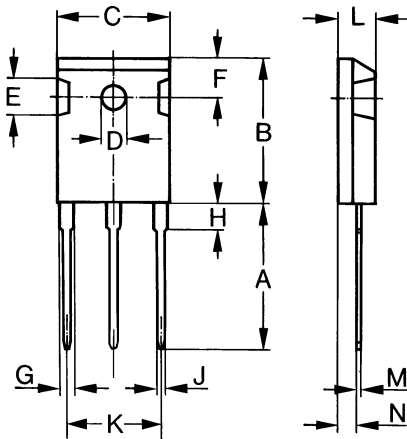


Fig. 2 Gate controlled delay time t_{gd}

TO-247 AD and ISOPLUS 247™



Dim.	Millimeter Min. Max.	Inches Min. Max.
A	19.81 20.32	0.780 0.800
B	20.80 21.46	0.819 0.845
C	15.75 16.26	0.610 0.640
D*	3.55 3.65	0.140 0.144
E	4.32 5.49	0.170 0.216
F	5.4 6.2	0.212 0.244
G	1.65 2.13	0.065 0.084
H	- 4.5	- 0.177
J	1.0 1.4	0.040 0.055
K	10.8 11.0	0.426 0.433
L	4.7 5.3	0.185 0.209
M	0.4 0.8	0.016 0.031
N	1.5 2.49	0.087 0.102

* ISOPLUS 247™ without hole

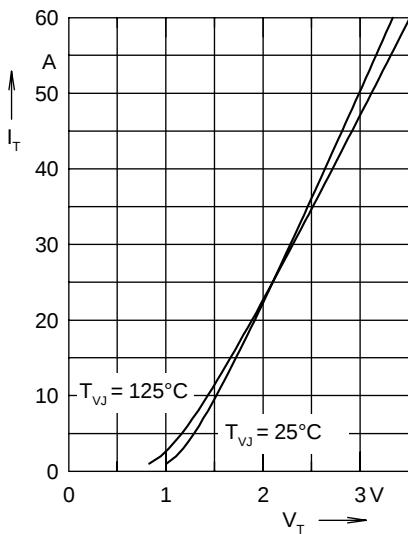


Fig. 3 Forward characteristics

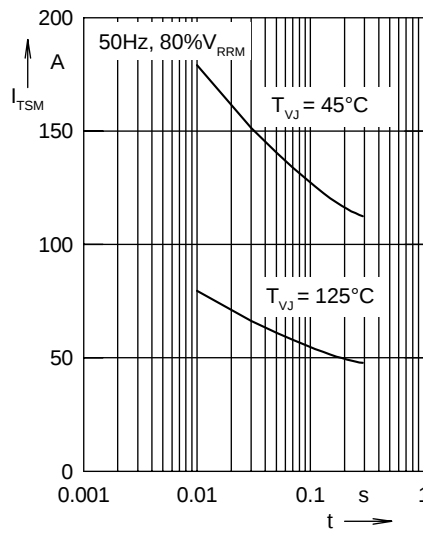


Fig. 4 Surge overload current
 I_{TSM} : crest value, t : duration

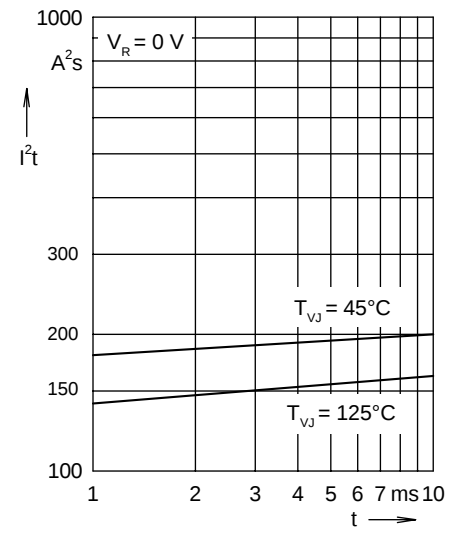


Fig. 5 I^2t versus time (1-10 ms)

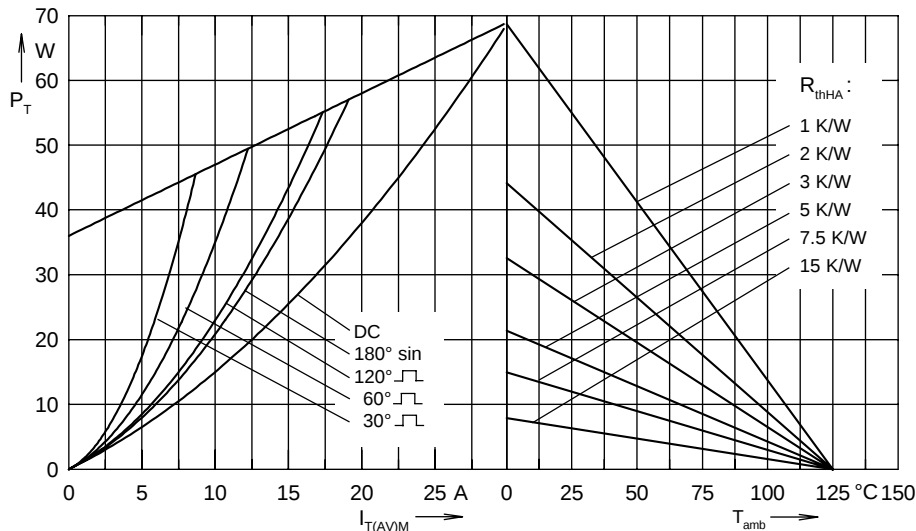


Fig. 6 Power dissipation versus forward current and ambient temperature

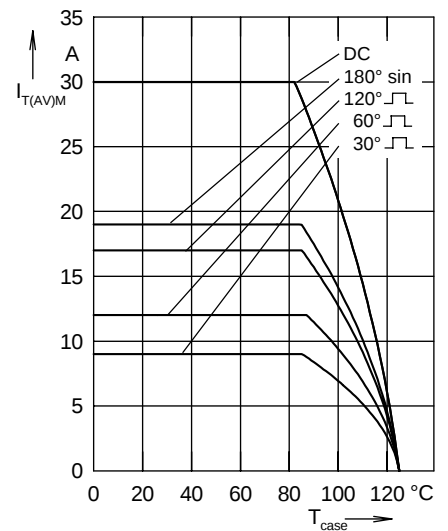


Fig. 7 Max. forward current at case temperature

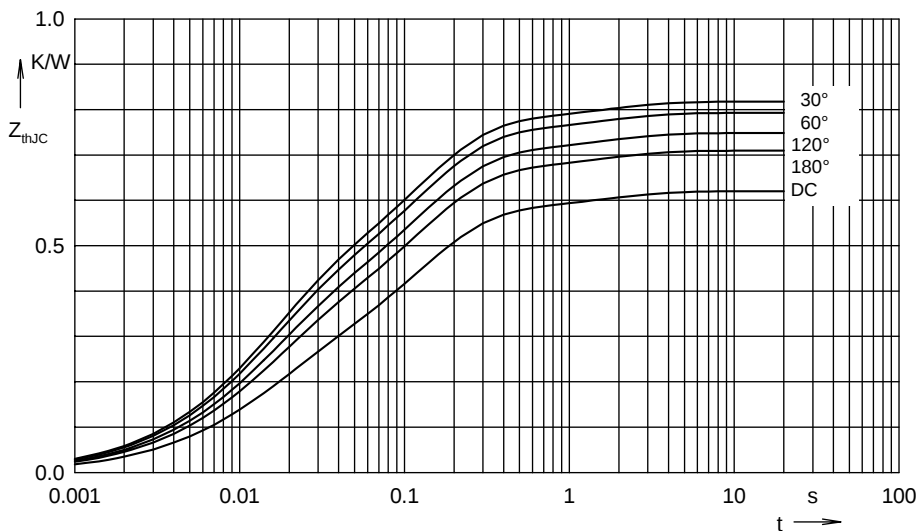


Fig. 8 Transient thermal impedance junction to case

R_{thJC} for various conduction angles d :

d	R_{thJC} (K/W)
DC	0.62
180°	0.71
120°	0.748
60°	0.793
30°	0.817

Constants for Z_{thJC} calculation:

i	R_{thi} (K/W)	t_i (s)
1	0.206	0.013
2	0.362	0.118
3	0.052	1.488

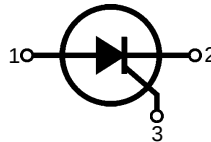
Phase Control Thyristors

$$V_{RRM} = 800-1600 \text{ V}$$

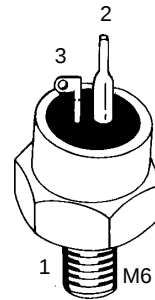
$$I_{T(RMS)} = 50 \text{ A}$$

$$I_{T(AV)M} = 32 \text{ A}$$

V_{RSM} V_{DSM} V	V_{RRM} V_{DRM} V	Type
900	800	CS 23-08io2
1300	1200	CS 23-12io2
1700	1600	CS 23-16io2



TO-208AA
(TO-48)



1 = Anode, 2 = Cathode, 3 = Gate

Symbol	Test Conditions	Maximum Ratings
$I_{T(RMS)}$ $I_{T(AV)M}$	$T_{VJ} = T_{VJM}$ $T_{case} = 85^{\circ}\text{C}; 180^{\circ}$ sine $T_{case} = 69^{\circ}\text{C}; 180^{\circ}$ sine	50 A 25 A 32 A
I_{TSM}	$T_{VJ} = 45^{\circ}\text{C};$ $V_R = 0$ $t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$ $T_{VJ} = T_{VJM}$ $V_R = 0$ $t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$	450 A 480 A 400 A 430 A
I^2t	$T_{VJ} = 45^{\circ}\text{C}$ $V_R = 0$ $t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$ $T_{VJ} = T_{VJM}$ $V_R = 0$ $t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$	1010 A^2s 970 A^2s 800 A^2s 770 A^2s
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}$ $f = 50 \text{ Hz}, t_p = 200 \mu\text{s}$ $V_D = 2/3 V_{DRM}$ $I_G = 0.3 \text{ A}$ $di_G/dt = 0.3 \text{ A}/\mu\text{s}$	repetitive, $I_T = 75 \text{ A}$ 150 $\text{A}/\mu\text{s}$ non repetitive, $I_T = I_{T(AV)M}$ 500 $\text{A}/\mu\text{s}$
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM};$ $R_{GK} = \infty; \text{method 1 (linear voltage rise)}$ $V_{DR} = 2/3 V_{DRM}$	1000 $\text{V}/\mu\text{s}$
P_{GM}	$T_{VJ} = T_{VJM}$ $I_T = I_{T(AV)M}$	$t_p = 30 \mu\text{s}$ 10 W $t_p = 300 \mu\text{s}$ 5 W
$P_{G(AV)}$		0.5 W
V_{RGM}		10 V
T_{VJ} T_{VJM} T_{stg}		-40...+125 $^{\circ}\text{C}$ 125 $^{\circ}\text{C}$ -40...+125 $^{\circ}\text{C}$
M_d	Mounting torque	2.7-3.3 Nm 24-29 lb.in.
Weight		12 g

Features

- Thyristor for line frequencies
- International standard package JEDEC TO-208AA
- Planar glassivated chip
- Long-term stability of blocking currents and voltages

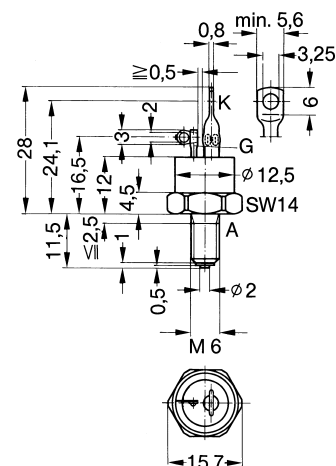
Applications

- Motor control
- Power converter
- AC power controller

Advantages

- Space and weight savings
- Simple mounting
- Improved temperature and power cycling

Dimensions in mm (1 mm = 0.0394")



Data according to IEC 60747
IXYS reserves the right to change limits, test conditions and dimensions

Symbol	Test Conditions	Characteristic Values
I_R, I_D	$T_{VJ} = T_{VJM}; V_R = V_{RRM}; V_D = V_{DRM}$	≤ 3 mA
V_T	$I_T = 80$ A; $T_{VJ} = 25^\circ\text{C}$	≤ 1.8 V
V_{T0}	For power-loss calculations only ($T_{VJ} = 125^\circ\text{C}$)	1.0 V
r_T		10 m Ω
V_{GT}	$V_D = 6$ V; $T_{VJ} = 25^\circ\text{C}$	≤ 2.5 V
	$T_{VJ} = -40^\circ\text{C}$	≤ 3.5 V
I_{GT}	$V_D = 6$ V; $T_{VJ} = 25^\circ\text{C}$	≤ 50 mA
	$T_{VJ} = -40^\circ\text{C}$	≤ 80 mA
V_{GD}	$T_{VJ} = T_{VJM}; V_D = 2/3 V_{DRM}$	≤ 0.2 V
I_{GD}		≤ 1 mA
I_L	$T_{VJ} = 25^\circ\text{C}; t_p = 10$ μs $I_G = 0.15$ A; $di_G/dt = 0.15$ A/ μs	≤ 200 mA
I_H	$T_{VJ} = 25^\circ\text{C}; V_D = 6$ V; $R_{GK} = \infty$	≤ 100 mA
t_{gd}	$T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$ $I_G = 0.15$ A; $di_G/dt = 0.15$ A/ μs	≤ 2 μs
t_q	$T_{VJ} = T_{VJM}; I_T = 25$ A; $t_p = 300$ μs ; $di/dt = -20$ A/ μs $V_R = 100$ V; $dv/dt = 20$ V/ μs ; $V_D = 2/3 V_{DRM}$	typ. 60 μs
R_{thJC}	DC current	1.0 K/W
R_{thJH}	DC current	1.61 K/W
d_s	Creepage distance on surface	1.5 mm
d_A	Strike distance through air	1.5 mm
a	Max. acceleration, 50 Hz	50 m/s ²

Accessories:

Nut M6 DIN 439/SW14

Lock washer A6 DIN 128

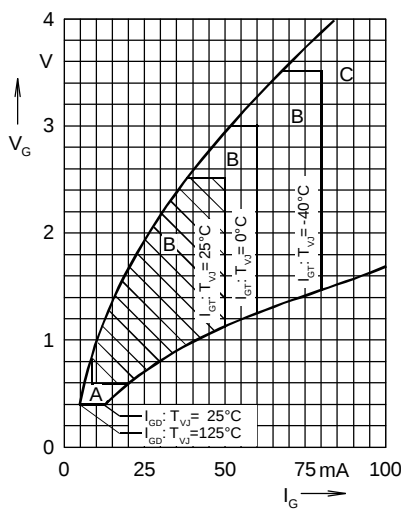


Fig. 1 Gate voltage and gate current

Triggering:

A = no; B = possible; C = safe

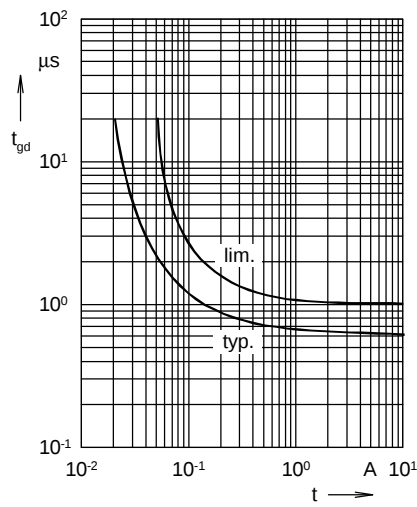


Fig. 2 Gate controlled delay time t_{gd}

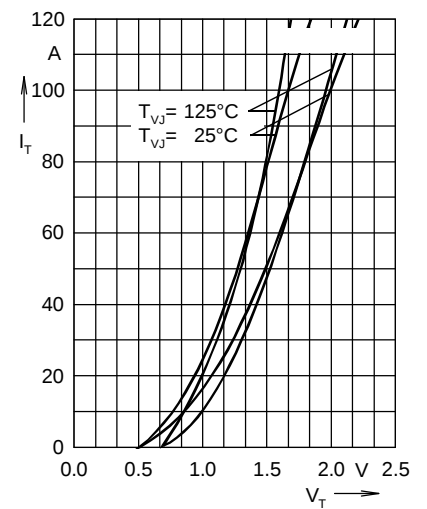


Fig. 3 On-state characteristics

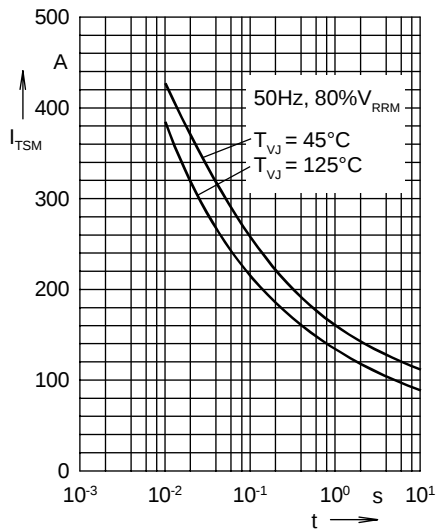


Fig. 4 Surge overload current
 I_{TSM} : crest value, t : duration

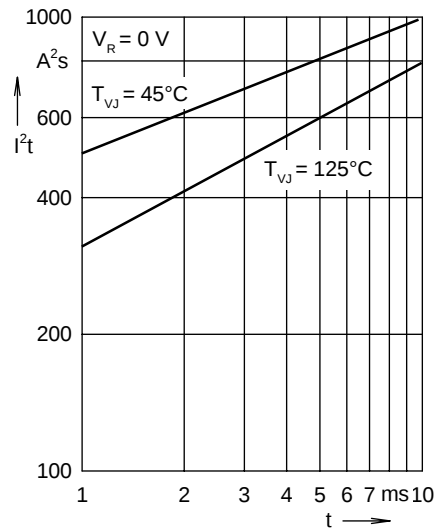


Fig. 5 I^2t versus time (1-10 ms)

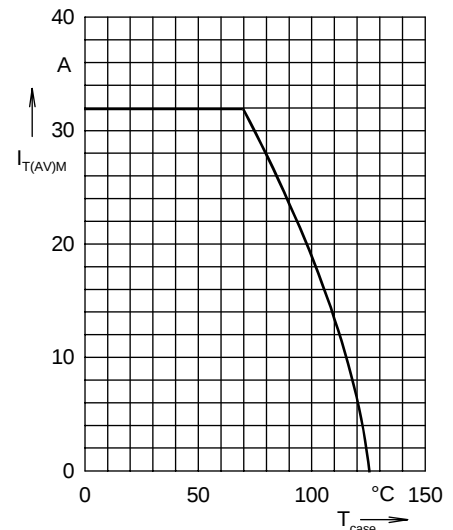


Fig. 6 Maximum forward current at case temperature 180° sine

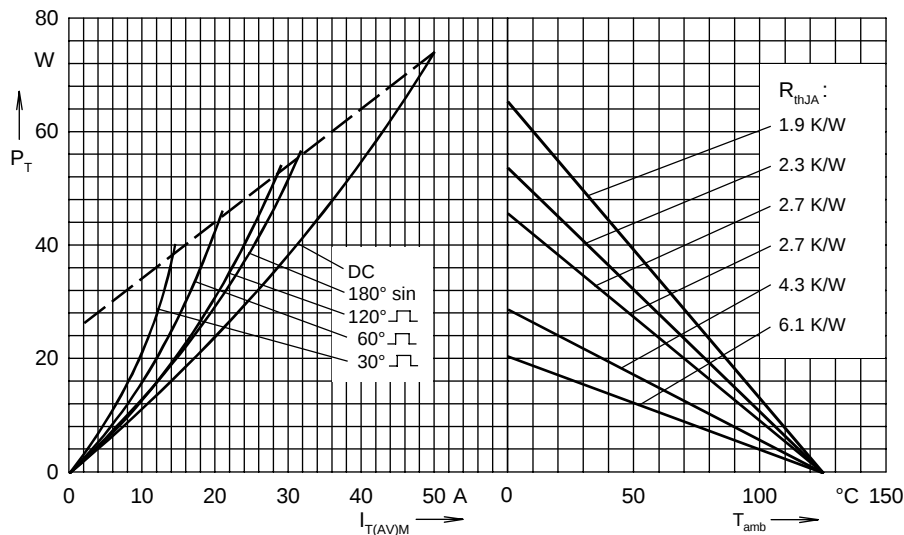


Fig. 7 Power dissipation versus on-state current and ambient temperature

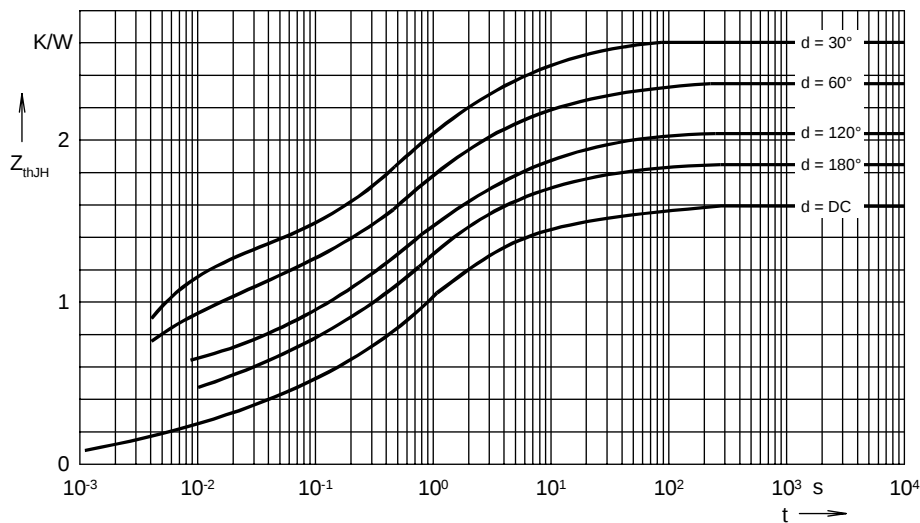


Fig. 8 Transient thermal impedance junction to heatsink

R_{thJH} for various conduction angles d :

d	R_{thJH} (K/W)
DC	1.61
180°	1.85
120°	2.03
60°	2.35
30°	2.60

Constants for Z_{thJH} calculation:

i	R_{thi} (K/W)	t_i (s)
1	0.224	0.003
2	0.132	0.028
3	0.321	0.216
4	0.522	1.1
5	0.249	4.2
6	0.162	43.2

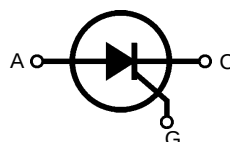
Phase Control Thyristor

$$V_{RRM} = 1200-1600 \text{ V}$$

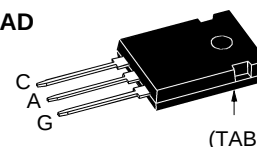
$$I_{T(RMS)} = 49 \text{ A}$$

$$I_{T(AV)M} = 31 \text{ A}$$

V_{RSM} V_{DSM} V	V_{RRM} V_{DRM} V	Type
1200	1200	CS 30-12io1
1400	1400	CS 30-14io1
1600	1600	CS 30-16io1



TO-247 AD



C = Cathode, A = Anode, G = Gate
TAB = Anode

Symbol	Test Conditions	Maximum Ratings
$I_{T(RMS)}$	$T_{VJ} = T_{VJM}$	49 A
$I_{T(AV)M}$	$T_{case} = 85^{\circ}\text{C}; 180^{\circ}$ sine	31 A
I_{TSM}	$T_{VJ} = 45^{\circ}\text{C};$ $V_R = 0 \text{ V}$	$t = 10 \text{ ms (50 Hz), sine}$ 300 A
		$t = 8.3 \text{ ms (60 Hz), sine}$ 320 A
	$T_{VJ} = T_{VJM}$ $V_R = 0 \text{ V}$	$t = 10 \text{ ms (50 Hz), sine}$ 270 A
		$t = 8.3 \text{ ms (60 Hz), sine}$ 290 A
I^2t	$T_{VJ} = 45^{\circ}\text{C}$ $V_R = 0 \text{ V}$	$t = 10 \text{ ms (50 Hz), sine}$ 450 A ² s
		$t = 8.3 \text{ ms (60 Hz), sine}$ 440 A ² s
	$T_{VJ} = T_{VJM}$ $V_R = 0 \text{ V}$	$t = 10 \text{ ms (50 Hz), sine}$ 365 A ² s
		$t = 8.3 \text{ ms (60 Hz), sine}$ 355 A ² s
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}$ $f = 50 \text{ Hz}, t_p = 200 \mu\text{s}$ $V_D = 2/3 V_{DRM}$ $I_G = 0.3 \text{ A}$ $di_G/dt = 0.3 \text{ A}/\mu\text{s}$	repetitive, $I_T = 40 \text{ A}$ 150 A/ μs
		non repetitive, $I_T = I_{T(AV)M}$ 500 A/ μs
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM};$ $R_{GK} = \infty$; method 1 (linear voltage rise)	$V_{DR} = 2/3 V_{DRM}$ 1000 V/ μs
P_{GM}	$T_{VJ} = T_{VJM}$ $I_T = I_{T(AV)M}$	$t_p = 30 \mu\text{s}$ 10 W
P_{GAV}		$t_p = 300 \mu\text{s}$ 5 W
		0.5 W
V_{RGM}		10 V
T_{VJ}		-40...+125 $^{\circ}\text{C}$
T_{VJM}		125 $^{\circ}\text{C}$
T_{stg}		-40...+125 $^{\circ}\text{C}$
M_d	Mounting torque M3	0.8...1.2 Nm
Weight		6 g

Features

- Thyristor for line frequency
- International standard package JEDEC TO-247
- Planar passivated chip
- Long-term stability of blocking currents and voltages
- Epoxy meets UL 94V-0

Applications

- Motor control
- Power converter
- AC power controller
- Switch-mode and resonant mode power supplies
- Light and temperature control

Advantages

- Easy to mount with 1 screw (isolated mounting screw hole)
- Space and weight savings
- Simple mounting
- Improved temperature and power cycling

Data according to IEC 60747
IXYS reserves the right to change limits, test conditions and dimensions

Symbol	Test Conditions	Characteristic Values
I_R, I_D	$T_{VJ} = T_{VJM}; V_R = V_{RRM}; V_D = V_{DRM}$	≤ 5 mA
V_T	$I_T = 45$ A; $T_{VJ} = 25^\circ\text{C}$	≤ 1.6 V
V_{T0}	For power-loss calculations only ($T_{VJ} = 125^\circ\text{C}$)	0.9 V
r_T		15 m Ω
V_{GT}	$V_D = 6$ V; $T_{VJ} = 25^\circ\text{C}$	≤ 1.0 V
	$T_{VJ} = -40^\circ\text{C}$	≤ 1.2 V
I_{GT}	$V_D = 6$ V; $T_{VJ} = 25^\circ\text{C}$	≤ 65 mA
	$T_{VJ} = -40^\circ\text{C}$	≤ 80 mA
	$T_{VJ} = 125^\circ\text{C}$	≤ 50 mA
V_{GD}	$T_{VJ} = T_{VJM}; V_D = 2/3 V_{DRM}$	≤ 0.2 V
I_{GD}		≤ 5 mA
I_L	$T_{VJ} = 25^\circ\text{C}; t_p = 10$ μs $I_G = 0.3$ A; $di_G/dt = 0.3$ A/ μs	≤ 150 mA
I_H	$T_{VJ} = 25^\circ\text{C}; V_D = 6$ V; $R_{GK} = \infty$	≤ 100 mA
t_{gd}	$T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$ $I_G = 0.3$ A; $di_G/dt = 0.3$ A/ μs	≤ 2 μs
R_{thJC}	DC current	0.62 K/W
R_{thJH}	DC current	0.82 K/W
a	Max. acceleration, 50 Hz	50 m/s ²

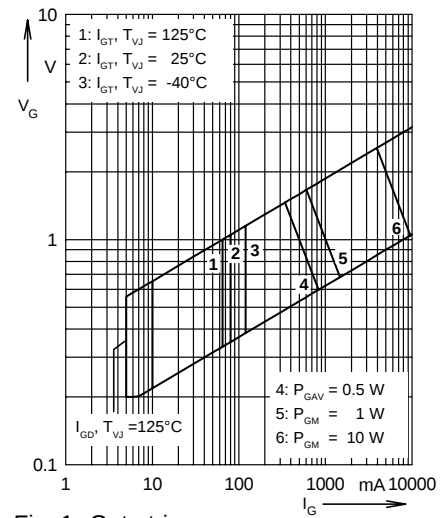


Fig. 1 Gate trigger range

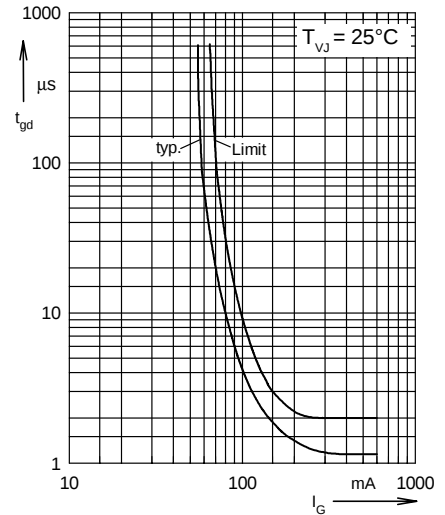
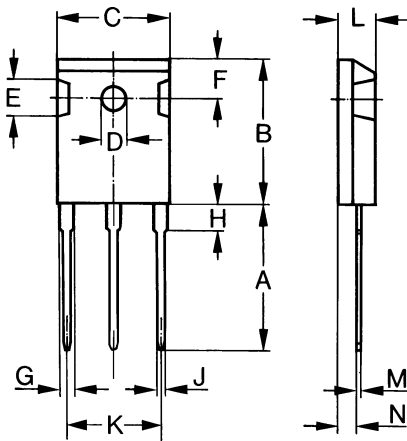


Fig. 2 Gate controlled delay time t_{gd}

TO-247 AD and ISOPLUS 247™



Dim.	Millimeter Min. Max.	Inches Min. Max.
A	19.81 20.32	0.780 0.800
B	20.80 21.46	0.819 0.845
C	15.75 16.26	0.610 0.640
D*	3.55 3.65	0.140 0.144
E	4.32 5.49	0.170 0.216
F	5.4 6.2	0.212 0.244
G	1.65 2.13	0.065 0.084
H	- 4.5	- 0.177
J	1.0 1.4	0.040 0.055
K	10.8 11.0	0.426 0.433
L	4.7 5.3	0.185 0.209
M	0.4 0.8	0.016 0.031
N	1.5 2.49	0.087 0.102

* ISOPLUS 247™ without hole

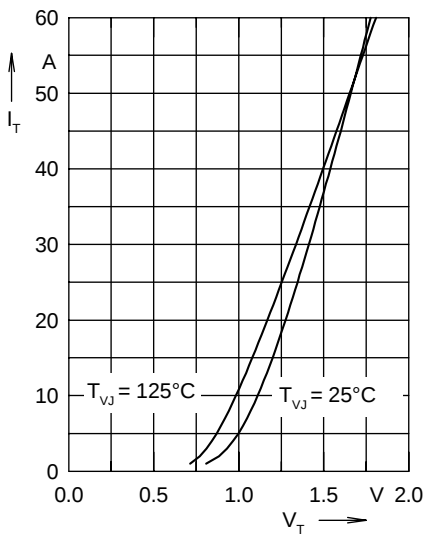


Fig. 3 Forward characteristics

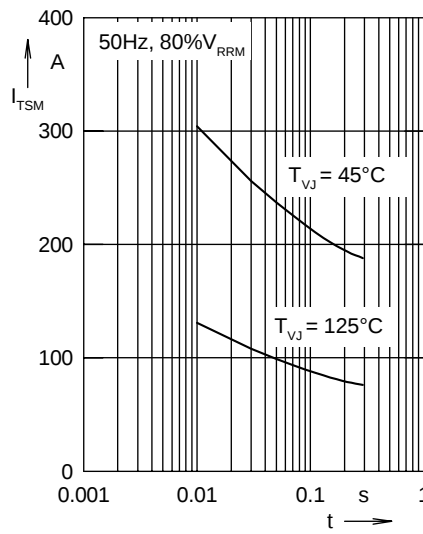


Fig. 4 Surge overload current
 I_{TSM} : crest value, t : duration

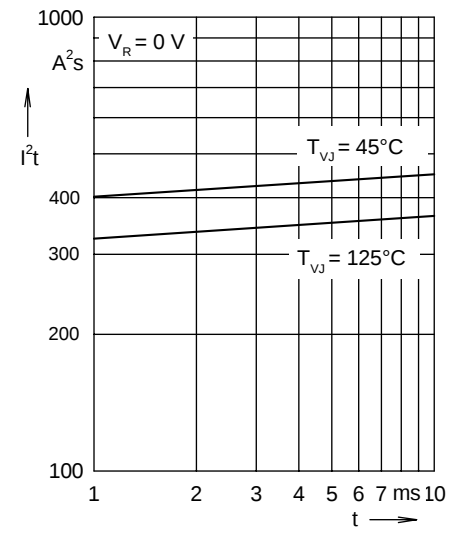


Fig. 5 I^2t versus time (1-10 ms)

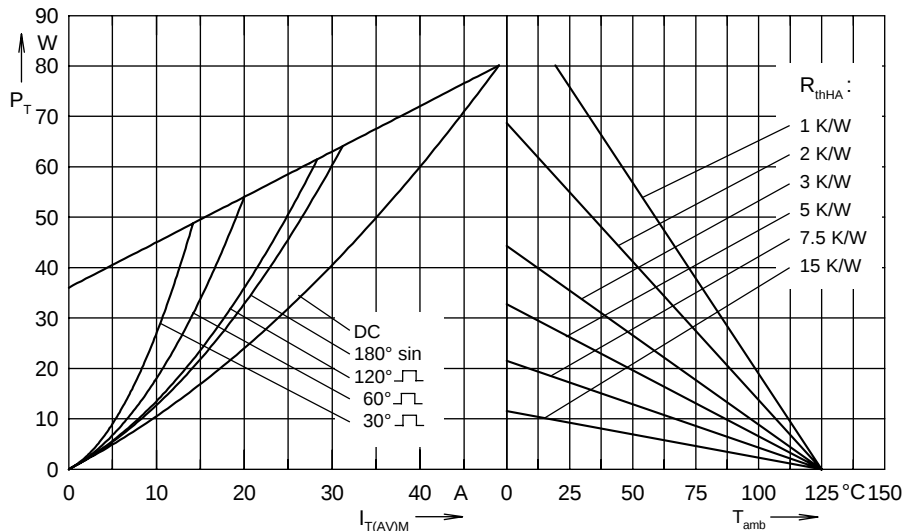


Fig. 6 Power dissipation versus forward current and ambient temperature

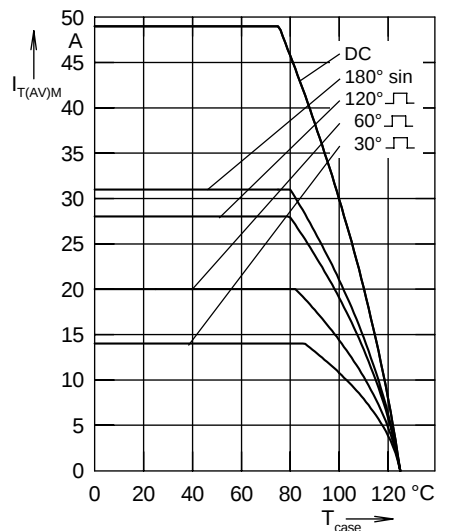


Fig. 7 Max. forward current at case temperature

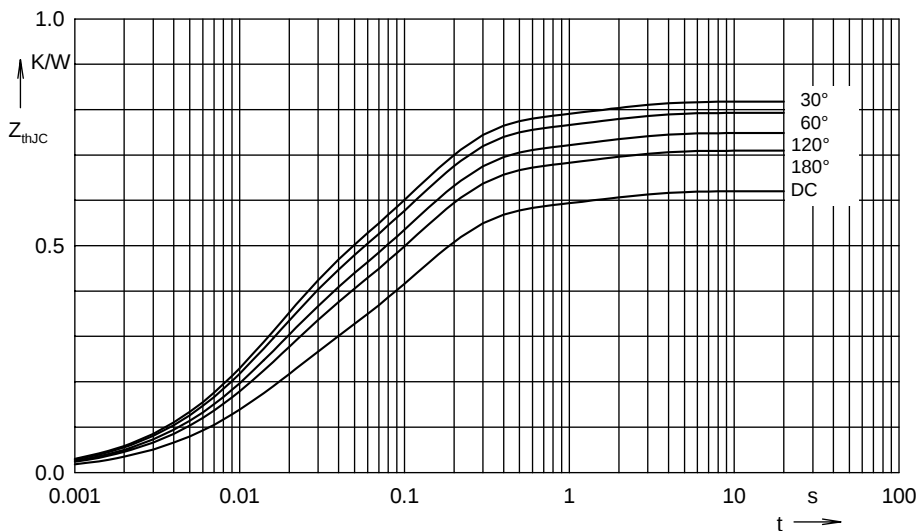


Fig. 8 Transient thermal impedance junction to case

R_{thJC} for various conduction angles d :

d	R_{thJC} (K/W)
DC	0.62
180°	0.71
120°	0.748
60°	0.793
30°	0.817

Constants for Z_{thJC} calculation:

i	R_{thi} (K/W)	t_i (s)
1	0.206	0.013
2	0.362	0.118
3	0.052	1.488

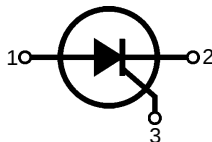
Phase Control Thyristors

$$V_{RRM} = 800-1400 \text{ V}$$

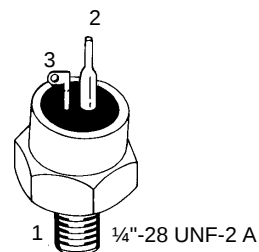
$$I_{T(RMS)} = 120 \text{ A}$$

$$I_{T(AV)M} = 69 \text{ A}$$

V_{RSM}	V_{RRM}	Type
V_{DSM}	V_{DRM}	
V	V	
900	800	CS 35-08io4
1300	1200	CS 35-12io4
1500	1400	CS 35-14io4



TO-208AC
(TO-65)



1 = Anode, 2 = Cathode, 3 = Gate

Symbol	Test Conditions	Maximum Ratings
$I_{T(RMS)}$	$T_{VJ} = T_{VJM}$	120 A
$I_{T(AV)M}$	$T_{case} = 85^{\circ}\text{C}; 180^{\circ}$ sine	63 A
	$T_{case} = 80^{\circ}\text{C}; 180^{\circ}$ sine	69 A
I_{TSM}	$T_{VJ} = 45^{\circ}\text{C}; V_R = 0$	$t = 10 \text{ ms (50 Hz), sine}$ 1200 A $t = 8.3 \text{ ms (60 Hz), sine}$ 1340 A
	$T_{VJ} = T_{VJM}; V_R = 0$	$t = 10 \text{ ms (50 Hz), sine}$ 1100 A $t = 8.3 \text{ ms (60 Hz), sine}$ 1250 A
I^2t	$T_{VJ} = 45^{\circ}\text{C}; V_R = 0$	$t = 10 \text{ ms (50 Hz), sine}$ 7200 A ² s $t = 8.3 \text{ ms (60 Hz), sine}$ 7550 A ² s
	$T_{VJ} = T_{VJM}; V_R = 0$	$t = 10 \text{ ms (50 Hz), sine}$ 6050 A ² s $t = 8.3 \text{ ms (60 Hz), sine}$ 6500 A ² s
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}; f = 50 \text{ Hz}, t_p = 200 \mu\text{s}; V_D = 2/3 V_{DRM}; I_G = 0.5 \text{ A}$	repetitive, $I_T = 150 \text{ A}$ 150 A/ μs non repetitive, $I_T = I_{T(AV)M}$ 400 A/ μs
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM}; R_{GK} = \infty; \text{method 1 (linear voltage rise)}$	$V_{DR} = 2/3 V_{DRM}$ 1000 V/ μs
P_{GM}	$T_{VJ} = T_{VJM}; t_p = 30 \mu\text{s}$	10 W
$P_{G(AV)}$	$I_T = I_{T(AV)M}; t_p = 500 \mu\text{s}$	5 W 0.5 W
V_{RGM}		10 V
T_{VJ}		-40...+125 $^{\circ}\text{C}$
T_{VJM}		125 $^{\circ}\text{C}$
T_{stg}		-40...+125 $^{\circ}\text{C}$
M_d	Mounting torque	2.5 Nm 22 lb.in.
Weight		20 g

Features

- Thyristor for line frequencies
- International standard package JEDEC TO-208AC
- Planar glassivated chip
- Long-term stability of blocking currents and voltages

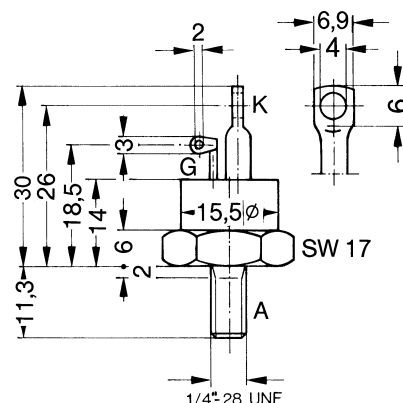
Applications

- Motor control
- Power converter
- AC power controller

Advantages

- Space and weight savings
- Simple mounting
- Improved temperature and power cycling

Dimensions in mm (1 mm = 0.0394")



Data according to IEC 60747
IXYS reserves the right to change limits, test conditions and dimensions

Symbol	Test Conditions	Characteristic Values
I_R, I_D	$T_{VJ} = T_{VJM}; V_R = V_{RRM}; V_D = V_{DRM}$	≤ 10 mA
V_T	$I_T = 150$ A; $T_{VJ} = 25^\circ\text{C}$	≤ 1.5 V
V_{T0}	For power-loss calculations only ($T_{VJ} = 125^\circ\text{C}$)	0.85 V
r_T		3.5 m Ω
V_{GT}	$V_D = 6$ V; $T_{VJ} = 25^\circ\text{C}$	≤ 1.5 V
	$T_{VJ} = -40^\circ\text{C}$	≤ 1.9 V
I_{GT}	$V_D = 6$ V; $T_{VJ} = 25^\circ\text{C}$	≤ 100 mA
	$T_{VJ} = -40^\circ\text{C}$	≤ 200 mA
V_{GD}	$T_{VJ} = T_{VJM}; V_D = 2/3 V_{DRM}$	≤ 0.2 V
I_{GD}		≤ 1 mA
I_L	$T_{VJ} = 25^\circ\text{C}; t_p = 30$ μs $I_G = 0.1$ A; $di_G/dt = 0.1$ A/ μs	≤ 100 mA
I_H	$T_{VJ} = 25^\circ\text{C}; V_D = 6$ V; $R_{GK} = \infty$	≤ 80 mA
t_{gd}	$T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$ $I_G = 0.1$ A; $di_G/dt = 0.1$ A/ μs	≤ 2 μs
t_q	$T_{VJ} = T_{VJM}; I_T = 50$ A, $t_p = 200$ μs ; $di/dt = -10$ A/ μs $V_R = 100$ V; $dv/dt = 10$ V/ μs ; $V_D = 2/3 V_{DRM}$	typ. 100 μs
R_{thJC}	DC current	0.4 K/W
R_{thJH}	DC current	0.6 K/W
d_s	Creepage distance on surface	1.7 mm
d_A	Strike distance through air	1.7 mm
a	Max. acceleration, 50 Hz	50 m/s ²

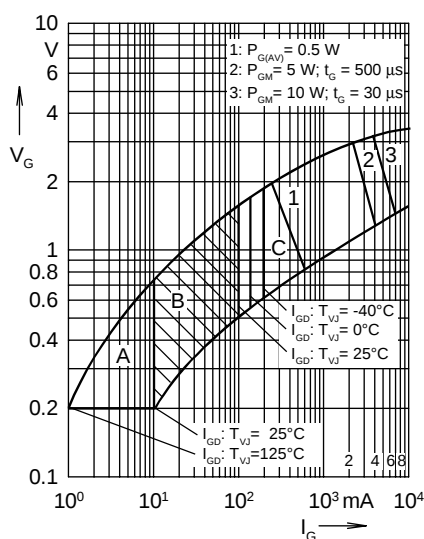


Fig. 1 Gate trigger range
Triggering:
A = no; B = possible, C = safe

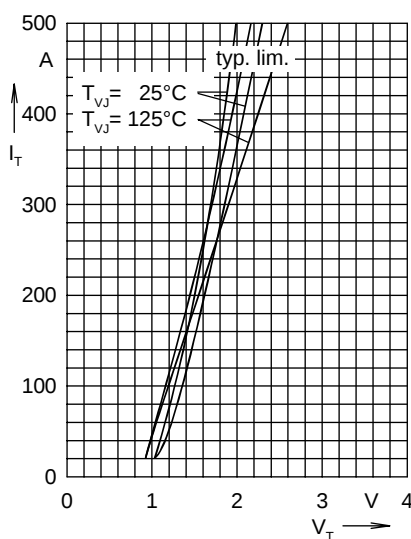


Fig. 2 On-state characteristics

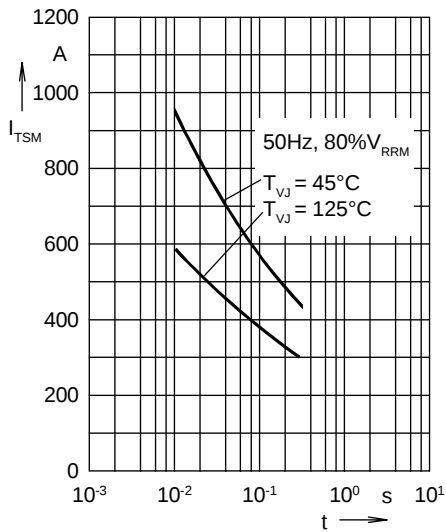


Fig. 3 Surge overload current
 I_{TSM} : crest value, t : duration

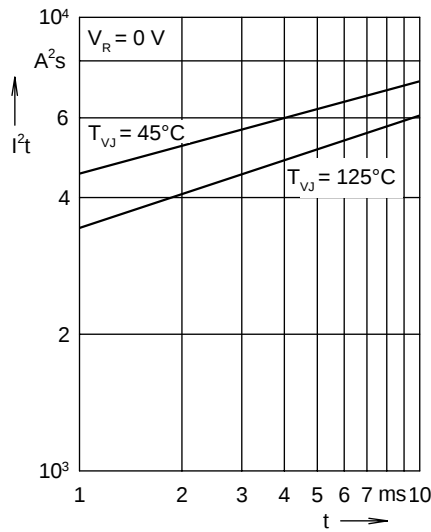


Fig. 4 I^2t versus time (1-10 ms)

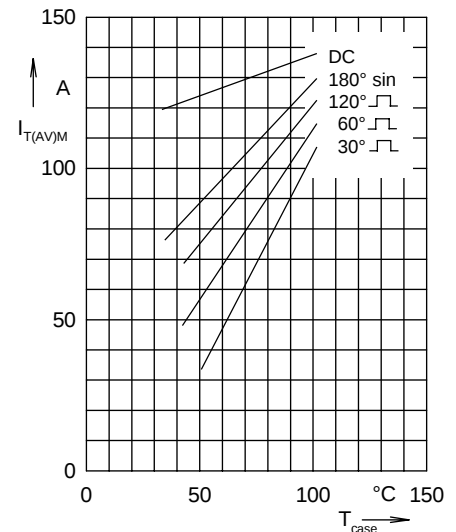


Fig. 5 Maximum forward current at case temperature

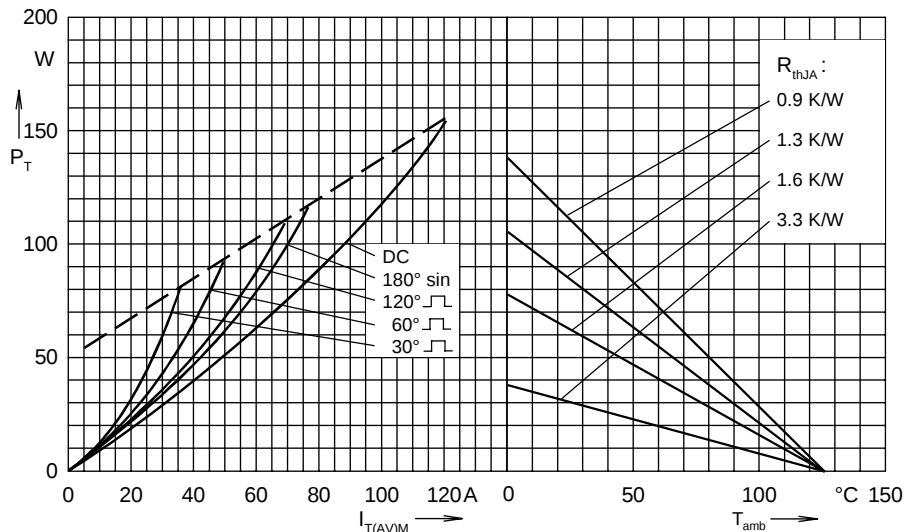


Fig. 6 Power dissipation versus on-state current and ambient temperature

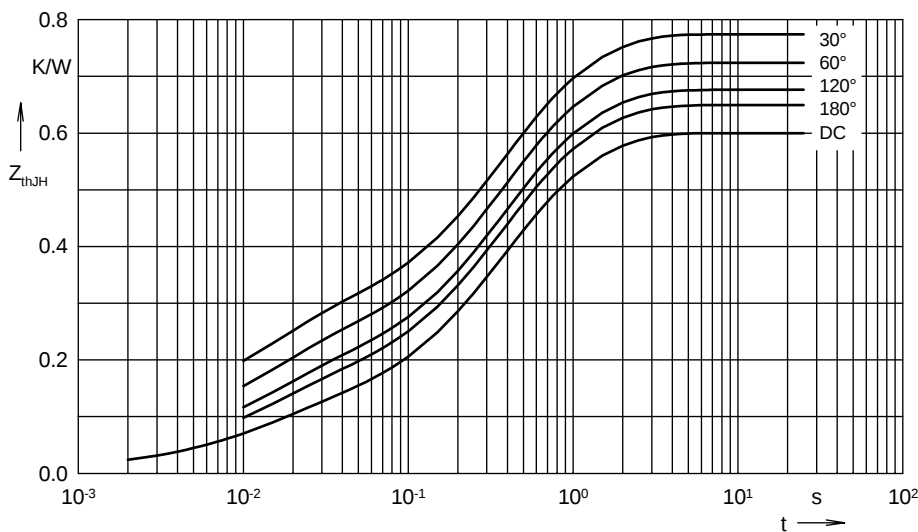


Fig. 7 Transient thermal impedance junction to heatsink

R_{thJH} for various conduction angles d :

d	R_{thJH} (K/W)
DC	0.6
180°	0.65
120°	0.677
60°	0.725
30°	0.775

Constants for Z_{thJH} calculation:

i	R_{thi} (K/W)	t_i (s)
1	0.01	0.001
2	0.09	0.013
3	0.30	0.3
4	0.20	0.9

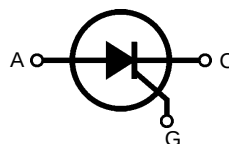
Phase Control Thyristor

$$V_{RRM} = 800-1600 \text{ V}$$

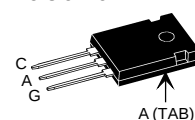
$$I_{T(RMS)} = 75 \text{ A}$$

$$I_{T(AV)M} = 48 \text{ A}$$

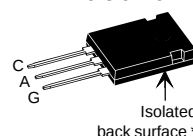
V_{RSM}	V_{RRM}	Type
V_{DSM}	V_{DRM}	
V	V	
900	800	CS 45-08io1
1300	1200	CS 45-12io1
1700	1600	CS 45-16io1 CS 45-16io1R



TO-247 AD
Version io1



ISOPLUS 247™
Version io1R



* Patent pending

C = Cathode, A = Anode, G = Gate

Symbol	Conditions	Maximum Ratings
$I_{T(RMS)}$	$T_{VJ} = T_{VJM}$	75 A
$I_{T(AV)M}$	$T_C = 75^\circ\text{C}; 180^\circ \text{ sine}$	48 A
I_{TSM}	$T_{VJ} = 45^\circ\text{C}$	$t = 10 \text{ ms (50 Hz), sine}$ 520 A
	$V_R = 0 \text{ V}$	$t = 8.3 \text{ ms (60 Hz), sine}$ 560 A
	$T_{VJ} = T_{VJM}$	$t = 10 \text{ ms (50 Hz), sine}$ 460 A
	$V_R = 0 \text{ V}$	$t = 8.3 \text{ ms (60 Hz), sine}$ 500 A
I^2t	$T_{VJ} = 45^\circ\text{C}$	$t = 10 \text{ ms (50 Hz), sine}$ 1350 A ² s
	$V_R = 0 \text{ V}$	$t = 8.3 \text{ ms (60 Hz), sine}$ 1300 A ² s
	$T_{VJ} = T_{VJM}$	$t = 10 \text{ ms (50 Hz), sine}$ 1050 A ² s
	$V_R = 0 \text{ V}$	$t = 8.3 \text{ ms (60 Hz), sine}$ 1030 A ² s
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}$ $f = 50 \text{ Hz}, t_p = 200 \mu\text{s}$	repetitive, $I_T = 40 \text{ A}$ 150 A/ μs
	$V_D = \frac{2}{3} V_{DRM}$ $I_G = 0.3 \text{ A}$ $di_G/dt = 0.3 \text{ A}/\mu\text{s}$	non repetitive, $I_T = I_{T(AV)M}$ 500 A/ μs
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM}$ $R_{GK} = \infty$; method 1 (linear voltage rise)	$V_{DR} = \frac{2}{3} V_{DRM}$ 1000 V/ μs
P_{GM}	$T_{VJ} = T_{VJM}$	$t_p = 30 \mu\text{s}$ 10 W
	$I_T = I_{T(AV)M}$	$t_p = 300 \mu\text{s}$ 5 W
$P_{G(AV)}$		0.5 W
V_{RGM}		10 V
T_{VJ}		-40...+140 °C
T_{VJM}		140 °C
T_{stg}		-40...+125 °C
M_d	Version io1: mounting torque M3	0.8...1.2 Nm
F_C	Version io1R: mounting force with clip	20...120 N
V_{ISOL}^*	50/60 Hz, RMS, $t = 1 \text{ minute}$, leads-to-tab	2500 V~
Weight		6 g

* Version io1R only

Data according to IEC 60747

IXYS reserves the right to change limits, test conditions and dimensions

Features

- Thyristor for line frequency
- International standard package JEDEC TO-247
- Planar passivated chip
- Long-term stability of blocking currents and voltages
- Version AR isolated and UL registered E153432
- Epoxy meets UL 94V-0

Applications

- Motor control
- Power converter
- AC power controller
- Switch-mode and resonant mode power supplies
- Light and temperature control

Advantages

- Easy to mount with 1 screw (isolated mounting screw hole)
- Space and weight savings
- Simple mounting
- Improved temperature and power cycling

Symbol	Conditions	Characteristic Values
I_R, I_D	$T_{VJ} = T_{VJM}; V_R = V_{RRM}; V_D = V_{DRM}$	≤ 5 mA
V_T	$I_T = 80$ A; $T_{VJ} = 25^\circ\text{C}$	≤ 1.64 V
V_{T0}	For power-loss calculations only ($T_{VJ} = 125^\circ\text{C}$)	0.85 V
r_T		11 m Ω
V_{GT}	$V_D = 6$ V; $T_{VJ} = 25^\circ\text{C}$	≤ 1.5 V
	$T_{VJ} = -40^\circ\text{C}$	≤ 1.6 V
I_{GT}	$V_D = 6$ V; $T_{VJ} = 25^\circ\text{C}$	≤ 100 mA
	$T_{VJ} = -40^\circ\text{C}$	≤ 200 mA
V_{GD}	$T_{VJ} = T_{VJM}; V_D = \frac{2}{3} V_{DRM}$	≤ 0.2 V
I_{GD}		≤ 10 mA
I_L	$T_{VJ} = 25^\circ\text{C}; t_p = 10$ μs $I_G = 0.3$ A; $di_G/dt = 0.3$ A/ μs	≤ 150 mA
I_H	$T_{VJ} = 25^\circ\text{C}; V_D = 6$ V; $R_{GK} = \infty$	≤ 100 mA
t_{gd}	$T_{VJ} = 25^\circ\text{C}; V_D = \frac{1}{2} V_{DRM}$ $I_G = 0.3$ A; $di_G/dt = 0.3$ A/ μs	≤ 2 μs
R_{thJC}	DC current	0.62 K/W
R_{thJH}	DC current	0.82 K/W
a	Max. acceleration, 50 Hz	50 m/s ²

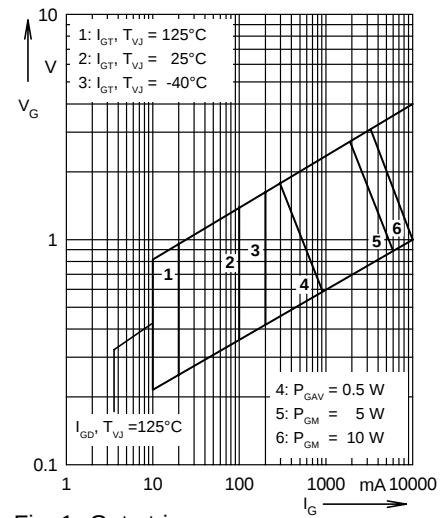


Fig. 1 Gate trigger range

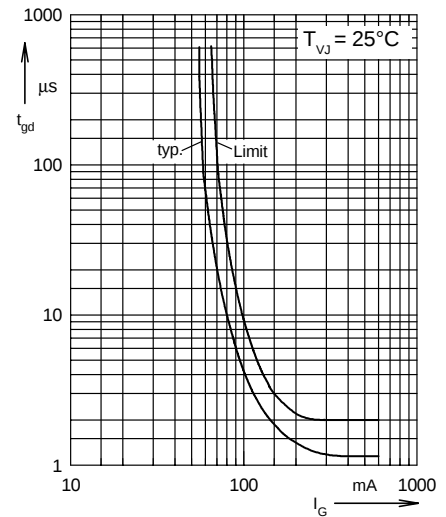
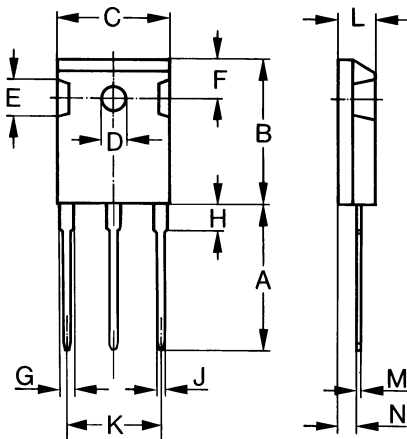


Fig. 2 Gate controlled delay time t_{gd}

TO-247 AD and ISOPLUS 247™



Dim.	Millimeter		Inches	
	Min.	Max.	Min.	Max.
A	19.81	20.32	0.780	0.800
B	20.80	21.46	0.819	0.845
C	15.75	16.26	0.610	0.640
D*	3.55	3.65	0.140	0.144
E	4.32	5.49	0.170	0.216
F	5.4	6.2	0.212	0.244
G	1.65	2.13	0.065	0.084
H	-	4.5	-	0.177
J	1.0	1.4	0.040	0.055
K	10.8	11.0	0.426	0.433
L	4.7	5.3	0.185	0.209
M	0.4	0.8	0.016	0.031
N	1.5	2.49	0.087	0.102

* ISOPLUS 247™ without hole

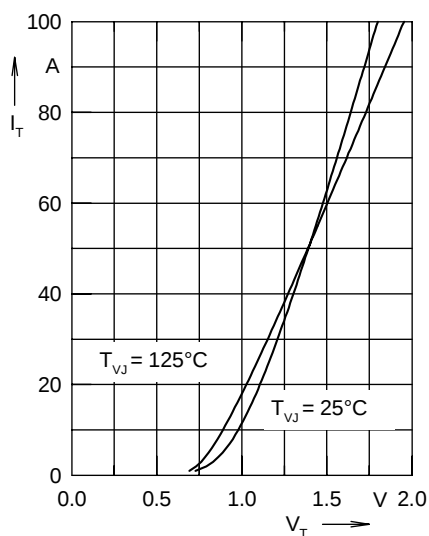


Fig. 3 Forward characteristics

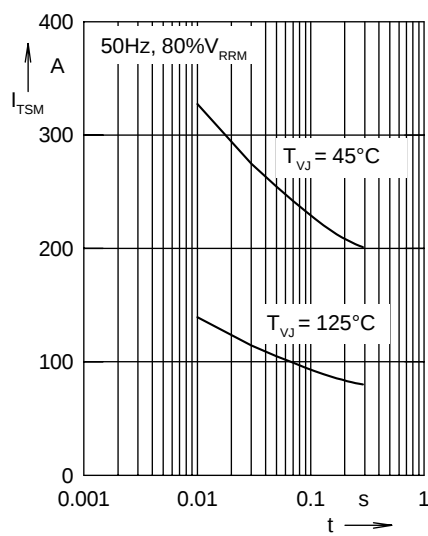


Fig. 4 Surge overload current
 I_{TSM} : crest value, t : duration

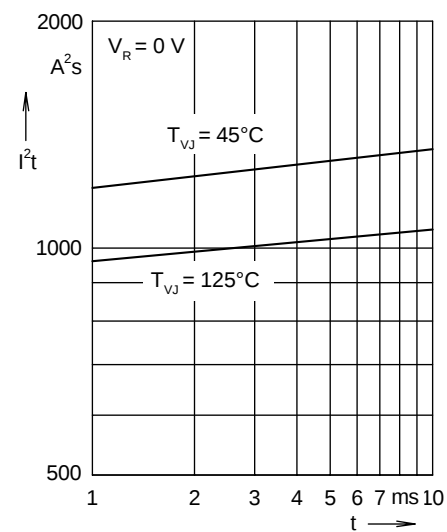


Fig. 5 I^2t versus time (1-10 ms)

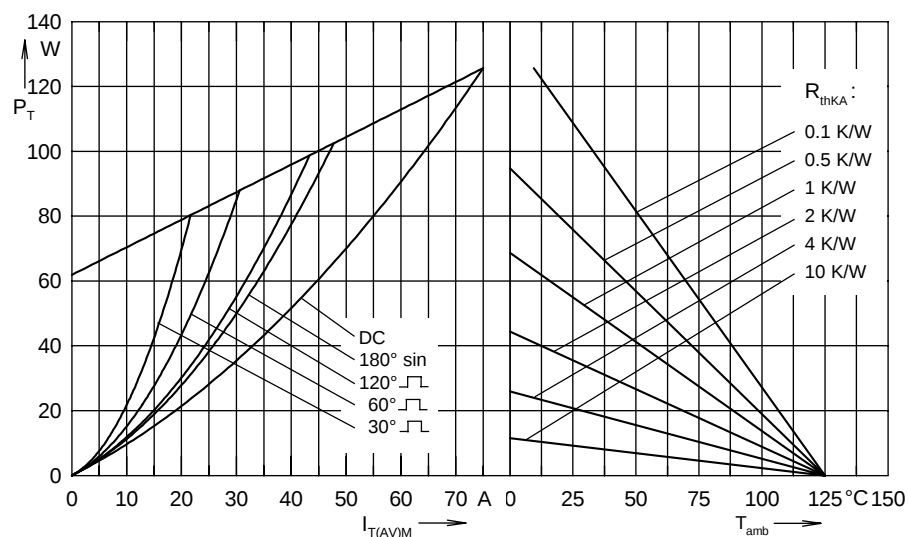


Fig. 6 Power dissipation versus forward current and ambient temperature

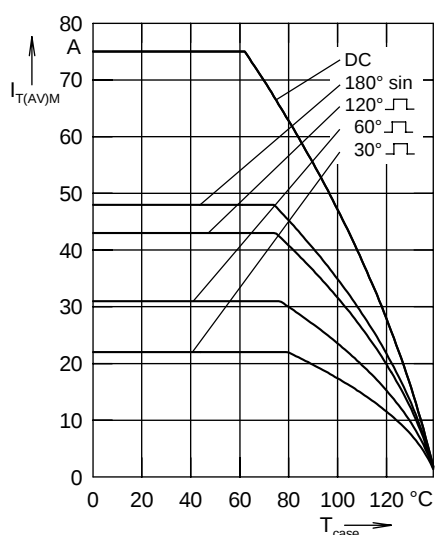


Fig. 7 Max. forward current at case temperature

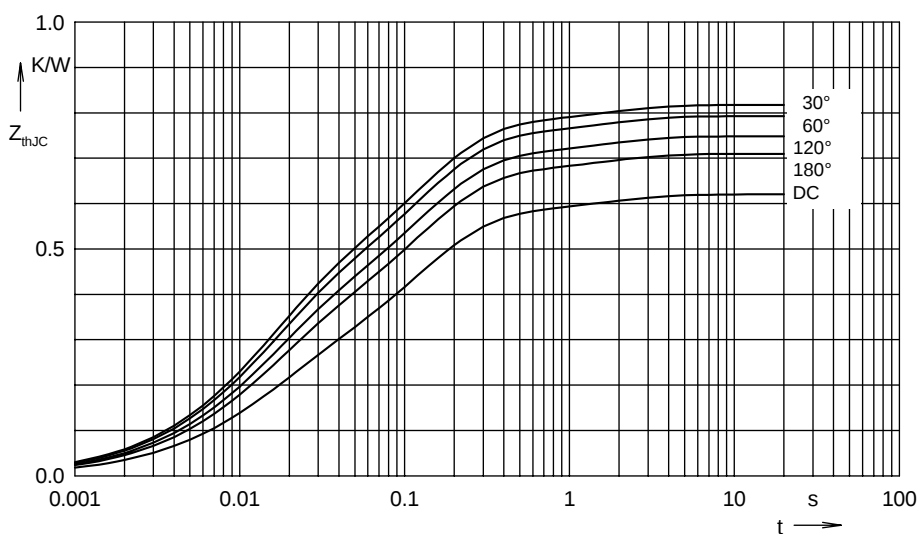


Fig. 8 Transient thermal impedance junction to case

R_{thJC} for various conduction angles d :

d	R_{thJC} (K/W)
DC	0.62
180°	0.71
120°	0.748
60°	0.793
30°	0.817

Constants for Z_{thJC} calculation:

i	R_{thi} (K/W)	t_i (s)
1	0.206	0.013
2	0.362	0.118
3	0.052	1.488

