DS04-29101-4E

## **ASSP**

# **Bidirectional Motor Driver**

## **MB3763**

#### DESCRIPTION

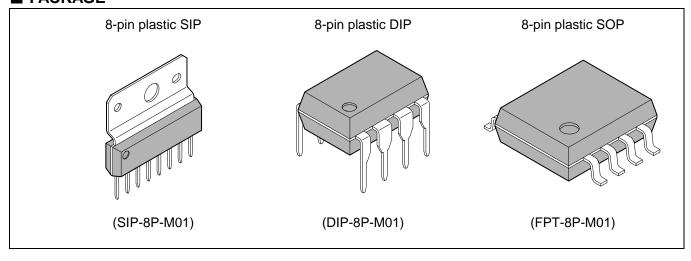
Fujitsu's MB3763 Motor Driver with forward/reverse control capability, is used in applications such as the front-loading mechanism in video tape, or the auto-reverse tape deck, driven by a TTL signal. The MB3763 has 300 mA drive units and braking capability with TTL control.

#### **■ FEATURES**

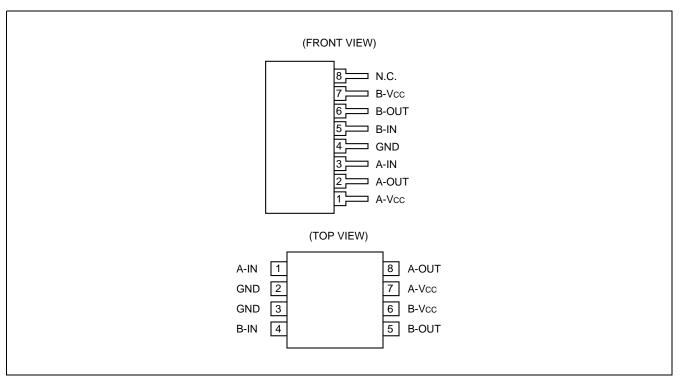
- Motor Drive Current: 300 mA maximum in a SIP Package
  - : 150 mA maximum in a DIP/FTP Package
- Wide Power Supply Voltage Range: 4V to 18V
- · TTL-control capability
- · Standby capability when input is off.
- Brake capability at motor stop mode.
- Built-in diode for surge absorption
- Package: 8-pin plastic SIP package (Suffix: –PS)

8-pin plastic DIP package (Suffix: –P) 8-pin plastic SOP package (Suffix: –PF)

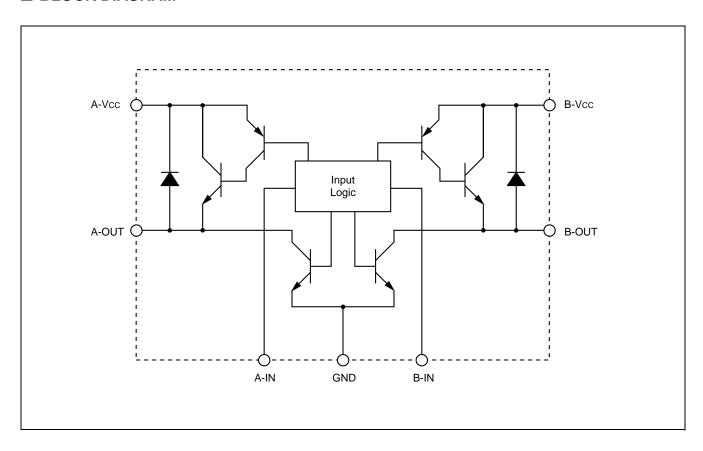
### ■ PACKAGE



## **■ PIN ASSIGNMENT**



### **■ BLOCK DIAGRAM**



#### ■ ABSOLUTE MAXIMUM RATINGS

 $(Ta = +25^{\circ}C)$ 

Parameter	Symbol	Rating			
rarameter		DIP/SOP (Plastic)	SIP (Plastic)	Unit	
Power supply voltage	Vcc	20	20	V	
Output current	lo	180 (330*1)	330	mA	
Maximum output current	IOMAX*3	1.2	1.2	Α	
Power Dissipation	PD	560*2	1000	mW	
Operating temperature	Tc	−20 to +75	-20 to +75	°C	
Storage temperature	Тѕтс	-55 to +125	-55 to +125	°C	

\*1:  $ton \le 1 s$ , Duty = 50%

\*2: Ta ≤ 60°C \*3: t ≤ 5 ms

WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

#### ■ RECOMMENDED OPERATING CONDITIONS

Parameter	Cumbal	Va	Unit	
Farameter	Symbol	DIP/SOP (Plastic)	SIP (Plastic)	- Offic
Power supply voltage	Vcc	4 to 18	4 to 18	V
Output current	lo	0 to 150 (300*1)	0 to 300	mA
Input high voltage	VIH*2	2.4 to Vcc + 0.3	2.4 to Vcc + 0.3	V
Input low voltage	VIL	0 to 0.4	0 to 0.4	V

\*1:  $ton \le 1 s$ , Duty = 50%

\*2: When  $V_{IH} \ge V_{CC}$ ,  $I_{IH} \le V_{CC} \times 0.2$  mA

WARNING: The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated within these ranges.

Always use semiconductor devices within their recommended operating conditionranges. Operation outside these ranges may adversely affect reliability and could result in device failure.

No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their FUJITSU representatives beforehand.

## **■ ELECTRICAL CHARACTERISTICS**

 $(Vcc = 12 \text{ V}, Io = 150/300 \text{ mA}, Ta = +25^{\circ}C)$ 

Parameter	Symbol	Condition		Value			Unit
Parameter	Syllibol			Min.	Тур.	Max.	Offic
Standby supply current	Icco	Vcc = 18 V, VIA = VIB = 0 V		_	_	1.0	mA
	Icc1	Io = 0 mA		_	10	20	mA
Power supply current	Icc2	lo=150/300 mA	Plastic DIP/SOP	_	10	_	mA
			Plastic SIP	_	15	_	
	Іссз	Io = 0 mA, VIA = VIB = 2.4 V		_	15	_	mA
Output high voltage	Vон	Plastic DIP/SOP		11.0	11.2	_	V
		Plastic SIP		10.8	11.1	_	
Output low voltage	Vol	Plastic DIP/SOP		_	0.1	0.2	V
		Plastic SIP		_	0.2	0.5	
0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	Vsat	Plastic DIP/SOP		_	0.9	1.2	V
Output saturation voltage		Plastic SIP		_	1.1	1.7	
Input current	Іін	VIN = 2.4 V		_	250	400	μΑ
Input switching prohibition time	Toff	_		10	_	_	μs

DIP: Dual in line package SIP: Single in line package SOP: Small outline I-leaded package

### **■ FUNCTIONAL DESCRIPTIONS**

### FORWARD/REVERSE MODE (MODE B& C)

In this mode, the transistor pairs Q2-Q3 and Q1-Q4 work alternatively, changing the output current direction. When the mode B is selected, Q2 and Q3 are active and Q1 and Q4 are inactive. Therefore A-OUT is at low level and B-OUT is at high level, with the current flowing from B-OUT to A-OUT through the motor. On the other hand, when the mode C is selected, the current flows in the reverse direction.

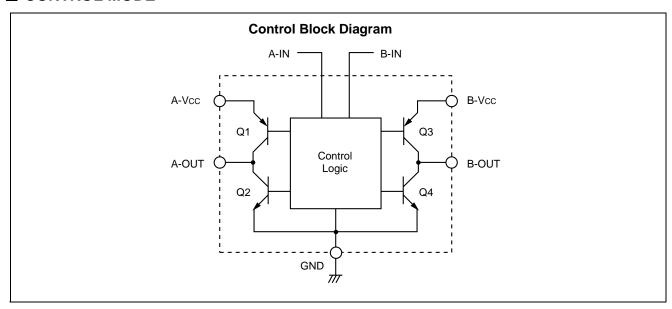
#### **BRAKE/STOP MODE (MODE A)**

When the mode A is selected, Q1 and Q3 are inactive and Q2 and Q4 are active. A-OUT and B-OUT are stuck at low-level; terminals of motor are shorted and the motor is forced to stop.

### **STANDBY MODE (MODE D)**

In this mode, all transistors are inactive and the current through the motor does not flow. When the power supply voltage is applied to A-Vcc and B-Vcc, the supply current is still less than or equal to 1 mA.

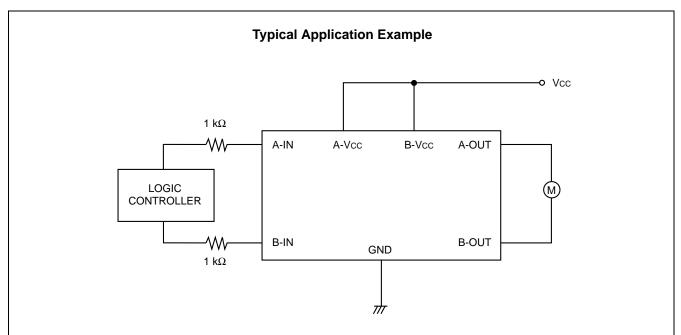
#### **■ CONTROL MODE**



Mode	Input mode		Output mode		Operation	
Ivioue	A-IN	A-IN B-IN A-OUT		B-OUT	Operation	
А	1	1	L	L	short (Brake)	
В	1	0	L	Н	Forward	
С	0	1	Н	L	Reverse	
D	0	0	_	_	Open (Standby)	

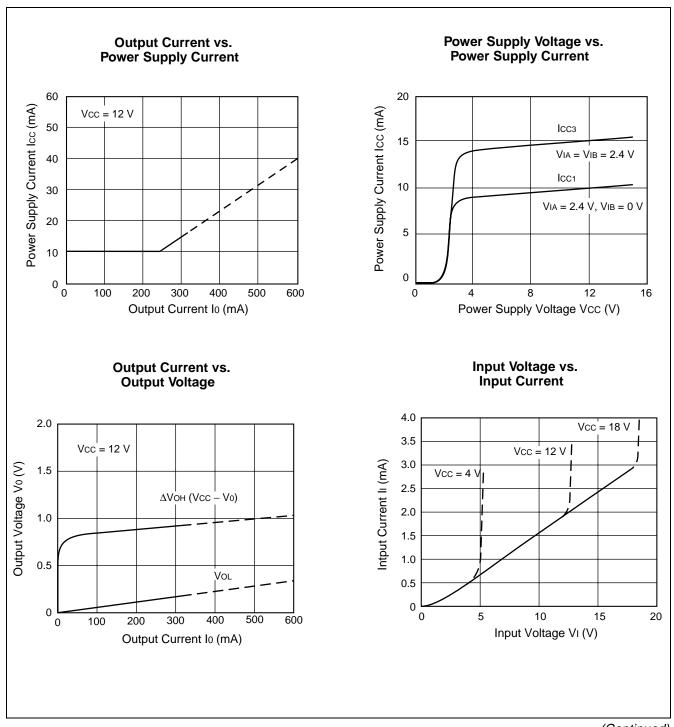
Notes:  $1: \ge 2.4V$  $0: \le 0.4V$ 

## **■ TYPICAL APPLICATION**



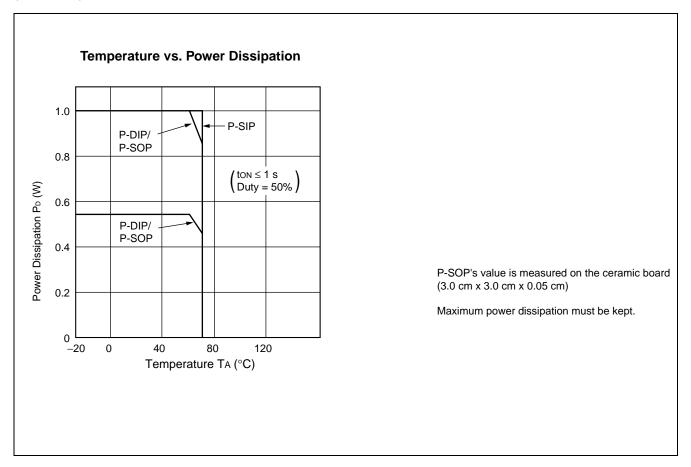
Note: In the case the control voltage is input when the power supply voltage is not applied because of the time lag between those two voltages, excess current flows into IC from the input terminals. In this case, please connect a resistor ( $\geq$  1 k $\Omega$ ) serially to input pin in order to prevent excess current flow.

### **■ TYPICAL PERFORMANCE CHARACTERISTICS**



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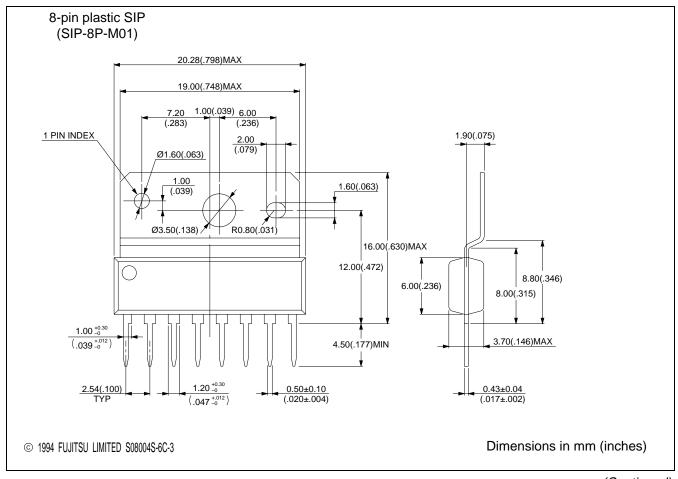
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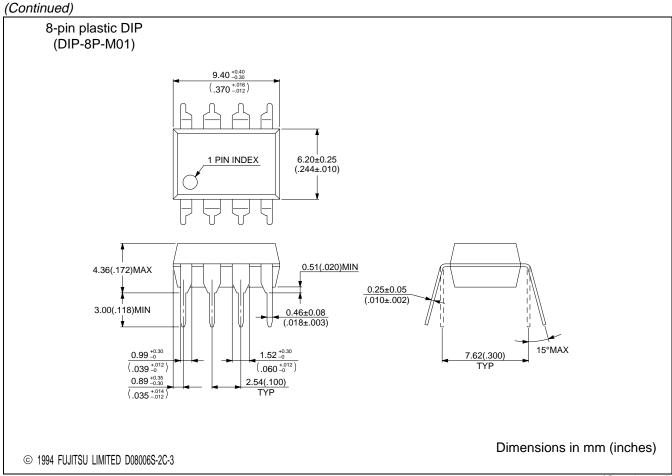
### **■** ORDERING INFORMATION

Part number	Package	Remarks		
MB3763	8-pin plastic DIP (DIP-8P-M01)			
MB3763PS	8-pin plastic SIP (SIP-8P-M01)			
MB3763PF	8-pin plastic SOP (FPT-8P-M01)			

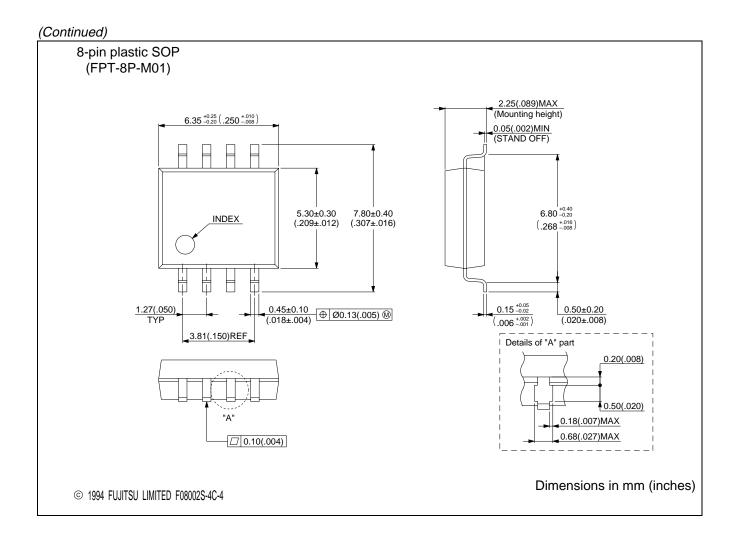
### **■ PACKAGE DIMENSIONS**



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