
HM6264BI Series

8,192-word $\times$ 8-bit High Speed CMOS Static RAM

HITACHI

ADE-203-492A (Z)

Rev. 1.0

Sep. 5, 1996

Description

The Hitachi HM6264BI is 64k-bit static RAM organized 8-kword $\times$ 8-bit. It realizes higher performance and low power consumption by 1.5 μ m CMOS process technology. The device, packaged in 450 mil SOP (foot print pitch width), 600 mil plastic DIP, is available for high density mounting.

Features

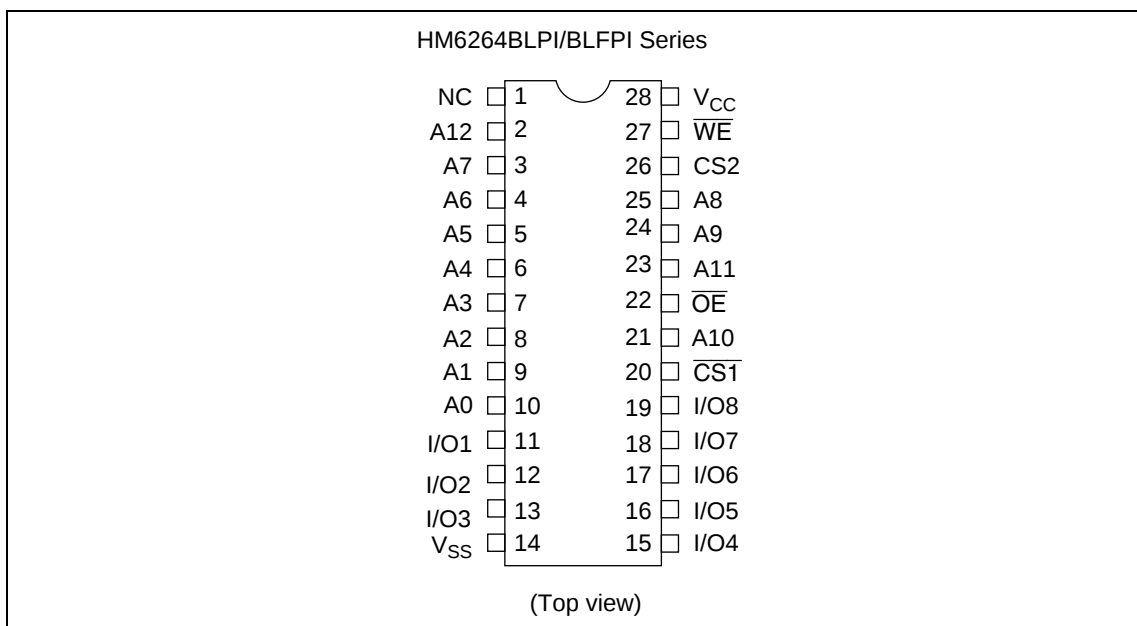
- High speed
 - Fast access time: 100/120 ns (max)
- Low power
 - Standby: 10 μ W (typ)
 - Operation: 15 mW (typ) (f = 1 MHz)
- Single 5 V supply
- Completely static memory
 - No clock or timing strobe required
- Equal access and cycle times
- Common data input and output
 - Three state output
- Directly TTL compatible
 - All inputs and outputs
- Battery backup operation capability
- Operating temperature range
 - -40°C to $+85^{\circ}\text{C}$

Ordering Information

Type No.	Access time	Package
HM6264BLPI-10	100 ns	600-mil, 28-pin plastic DIP (DP-28)
HM6264BLPI-12	120 ns	
HM6264BLFPI-10T	100 ns	450-mil, 28-pin plastic SOP(FP-28DA)
HM6264BLFPI-12T	120 ns	

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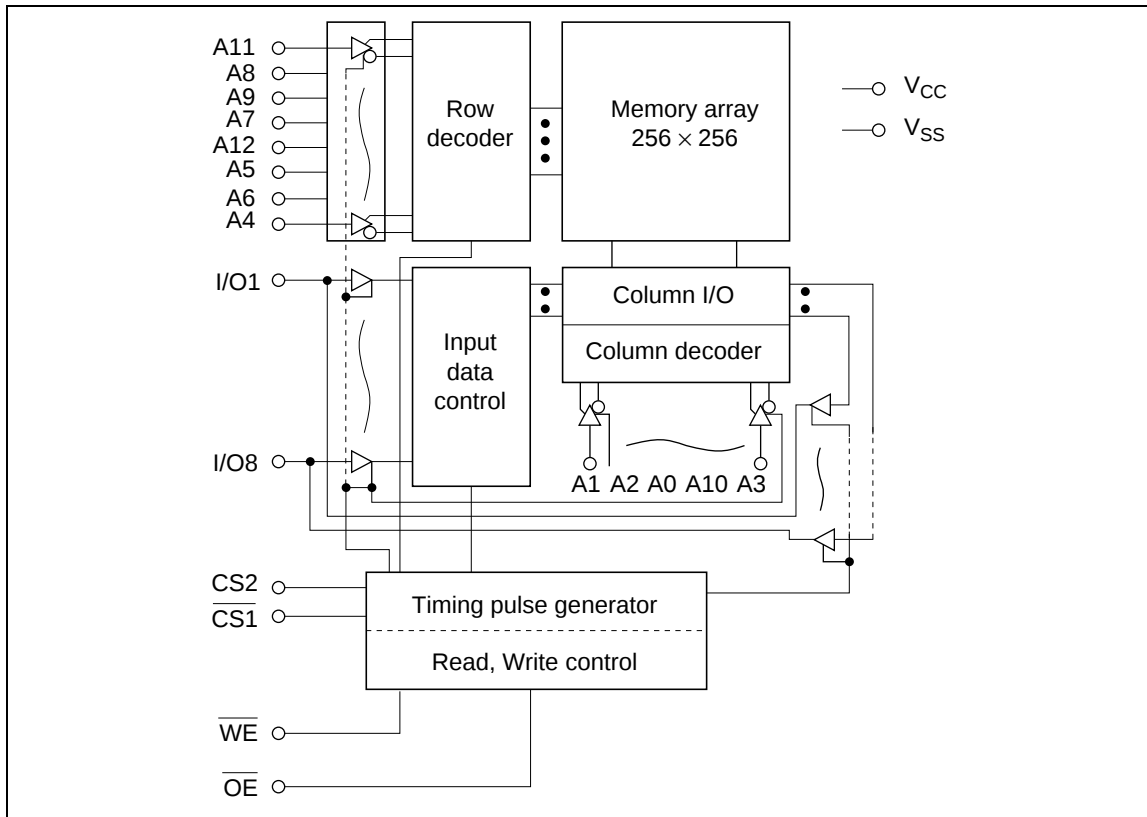
Pin Arrangement



Pin Description

Pin name	Function
A0 to A12	Address input
I/O1 to I/O8	Data input/output
CS1	Chip select 1
CS2	Chip select 2
WE	Write enable
OE	Output enable
NC	No connection
V _{CC}	Power supply
V _{SS}	Ground

Block Diagram



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Function Table

WE	CS1	CS2	OE	Mode	V _{CC} current	I/O pin	Ref. cycle
×	H	×	×	Not selected (power down)	I _{SB} , I _{SB1}	High-Z	—
×	×	L	×	Not selected (power down)	I _{SB} , I _{SB1}	High-Z	—
H	L	H	H	Output disable	I _{CC}	High-Z	—
H	L	H	L	Read	I _{CC}	Dout	Read cycle (1)–(3)
L	L	H	H	Write	I _{CC}	Din	Write cycle (1)
L	L	H	L	Write	I _{CC}	Din	Write cycle (2)

Note: ×: H or L

Absolute Maximum Ratings

Parameter	Symbol	Value	Unit
Power supply voltage* ¹	V _{CC}	−0.5 to +7.0	V
Terminal voltage* ¹	V _T	−0.5* ² to V _{CC} + 0.3* ³	V
Power dissipation	P _T	1.0	W
Operating temperature	T _{opr}	−40 to +85	°C
Storage temperature	T _{stg}	−55 to +125	°C
Storage temperature under bias	T _{bias}	−40 to +85	°C

Notes: 1. Relative to V_{SS}
 2. V_T min: −3.0 V for pulse half-width ² 50 ns
 3. Maximum voltage is 7.0 V

Recommended DC Operating Conditions (T_a = −40 to +85°C)

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V _{CC}	4.5	5.0	5.5	V
	V _{SS}	0	0	0	V
Input high voltage	V _{IH}	2.4	—	V _{CC} + 0.3	V
Input low voltage	V _{IL}	−0.3* ¹	—	0.6	V

Note: 1. V_{IL} min: −3.0 V for pulse half-width ² 50 ns

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DC Characteristics (Ta = -40 to +85°C, V_{CC} = 5 V ±10%, V_{SS} = 0 V)

Parameter	Symbol	Min	Typ* ¹	Max	Unit	Test conditions
Input leakage current	I _{LI}	—	—	2	μA	V _{in} = V _{SS} to V _{CC}
Output leakage current	I _{LO}	—	—	2	μA	CS1 = V _{IH} or CS2 = V _{IL} or OE = V _{IH} or WE = V _{IL} , V _{I/O} = V _{SS} to V _{CC}
Operating power supply current	I _{CCDC}	—	7	20	mA	CS1 = V _{IL} , CS2 = V _{IH} , I _{I/O} = 0 mA others = V _{IH} /V _{IL}
Average operating power supply current	I _{CC1}	—	30	50	mA	Min cycle, duty = 100%, CS1 = V _{IL} , CS2 = V _{IH} , I _{I/O} = 0 mA others = V _{IH} /V _{IL}
	I _{CC2}	—	3	8	mA	Cycle time = 1 μs, duty = 100%, I _{I/O} = 0 mA CS1 ² 0.2 V, CS2 ³ V _{CC} - 0.2 V, V _{IH} ³ V _{CC} - 0.2 V, V _{IL} ² 0.2 V
Standby power supply current	I _{SB}	—	1	3	mA	CS1 = V _{IH} , CS2 = V _{IL}
	I _{SB1} ^{*2}	—	2	200	μA	CS1 ³ V _{CC} - 0.2 V, CS2 ³ V _{CC} - 0.2 V or 0 V ² CS2 ² 0.2 V, 0 V ² V _{in}
Output low voltage	V _{OL}	—	—	0.4	V	I _{OL} = 2.1 mA
Output high voltage	V _{OH}	2.4	—	—	V	I _{OH} = -1.0 mA

Notes: 1. Typical values are at V_{CC} = 5.0 V, Ta = +25°C and not guaranteed.

2. V_{IL} min = -0.3V

Capacitance (Ta = 25°C, f = 1.0 MHz)

Parameter	Symbol	Min	Typ	Max	Unit	Test conditions
Input capacitance* ¹	C _{in}	—	—	5	pF	V _{in} = 0 V
Input/output capacitance* ¹	C _{I/O}	—	—	7	pF	V _{I/O} = 0 V

Note: 1. This parameter is sampled and not 100% tested.

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AC Characteristics ($T_a = -40$ to $+85^\circ\text{C}$, $V_{CC} = 5\text{ V} \pm 10\%$, unless otherwise noted.)

Test Conditions

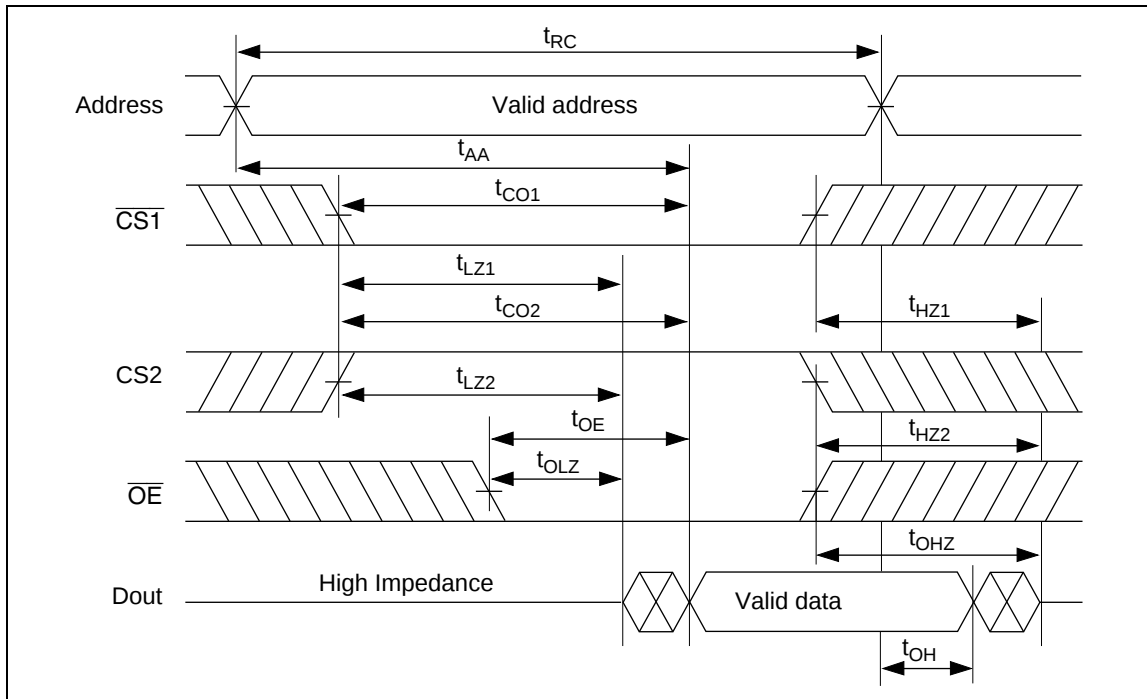
- Input pulse levels: 0.6 V to 2.4 V
- Input and output timing reference level: 1.5 V
- Input rise and fall time: 10 ns
- Output load: 1 TTL Gate + C_L (100 pF) (Including scope & jig)

Read Cycle

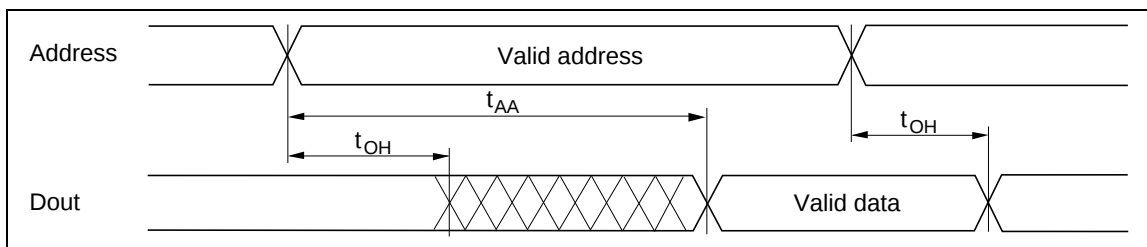
Parameter	Symbol	HM6264BI-10		HM6264BI-12		Unit	Notes
		Min	Max	Min	Max		
Read cycle time	t_{RC}	100	—	120	—	ns	
Address access time	t_{AA}	—	100	—	120	ns	
Chip select access time	CS1 t_{CO1}	—	100	—	120	ns	
	CS2 t_{CO2}	—	100	—	120	ns	
Output enable to output valid	t_{OE}	—	50	—	60	ns	
Chip selection to output in low-Z	CS1 t_{LZ1}	10	—	10	—	ns	2
	CS2 t_{LZ2}	10	—	10	—	ns	2
Output enable to output in low-Z	t_{OLZ}	5	—	5	—	ns	2
Chip deselection in to output in high-Z	CS1 t_{HZ1}	0	35	0	40	ns	1, 2
	CS2 t_{HZ2}	0	35	0	40	ns	1, 2
Output disable to output in high-Z	t_{OHZ}	0	35	0	40	ns	1, 2
Output hold from address change	t_{OH}	10	—	10	—	ns	

- Notes: 1. t_{HZ} is defined as the time at which the outputs achieve the open circuit conditions and are not referred to output voltage levels.
2. At any given temperature and voltage condition, t_{HZ} maximum is less than t_{LZ} minimum both for a given device and from device to device.
3. Address must be valid prior to or simultaneously with CS1 going low or CS2 going high.

Read Timing Waveform (1) ($\overline{WE} = V_{IH}$)

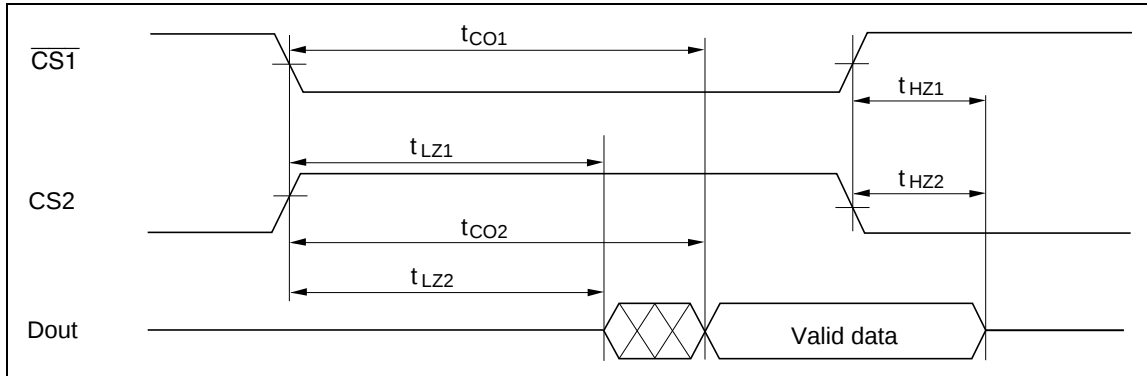


Read Timing Waveform (2) ($\overline{WE} = V_{IH}$, $\overline{OE} = V_{IL}$)



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Read Timing Waveform (3) ($\overline{WE} = V_{IH}$, $\overline{OE} = V_{IL}$)*³



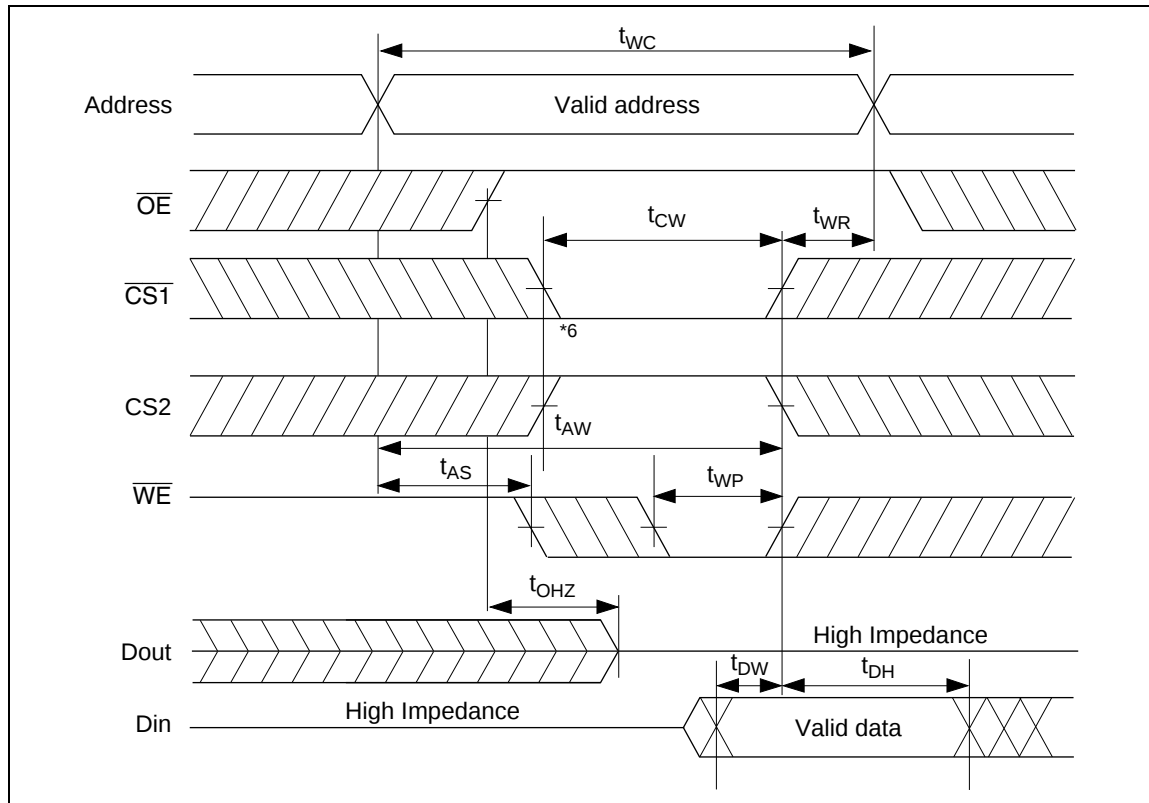
Write Cycle

Parameter	Symbol	HM6264BI-10		HM6264BI-12		Unit	Notes
		Min	Max	Min	Max		
Write cycle time	t_{WC}	100	—	120	—	ns	
Chip selection to end of write	t_{CW}	80	—	85	—	ns	2
Address setup time	t_{AS}	0	—	0	—	ns	3
Address valid to end of write	t_{AW}	80	—	85	—	ns	
Write pulse width	t_{WP}	60	—	70	—	ns	1, 9
Write recovery time	t_{WR}	0	—	0	—	ns	4
WE to output in high-Z	t_{WHZ}	0	35	0	40	ns	5
Data to write time overlap	t_{DW}	40	—	40	—	ns	
Data hold from write time	t_{DH}	0	—	0	—	ns	
Output active from end of write	t_{OW}	5	—	5	—	ns	
Output disable to output in high-Z	t_{OHZ}	0	35	0	40	ns	5

- Notes:
1. A write occurs during the overlap of a low $\overline{CS1}$, and high $\overline{CS2}$, and a high $\overline{WE}$. A write begins at the latest transition among $\overline{CS1}$ going low, $\overline{CS2}$ going high and $\overline{WE}$ going low. A write ends at the earliest transition among $\overline{CS1}$ going high, $\overline{CS2}$ going low and $\overline{WE}$ going high. Time t_{WP} is measured from the beginning of write to the end of write.
 2. t_{CW} is measured from the later of $\overline{CS1}$ going low or $\overline{CS2}$ going high to the end of write.
 3. t_{AS} is measured from the address valid to the beginning of write.
 4. t_{WR} is measured from the earliest of $\overline{CS1}$ or $\overline{WE}$ going high or $\overline{CS2}$ going low to the end of write cycle.
 5. During this period, I/O pins are in the output state, therefore the input signals of the opposite phase to the outputs must not be applied.
 6. If $\overline{CS1}$ goes low simultaneously with $\overline{WE}$ going low after $\overline{WE}$ goes low, the outputs remain in high impedance state.
 7. $Dout$ is the same phase of the written data in this write cycle.
 8. $Dout$ is the read data of the next address
 9. In the write cycle with $\overline{OE}$ low fixed, t_{WP} must satisfy the following equation to avoid a problem of data bus contention

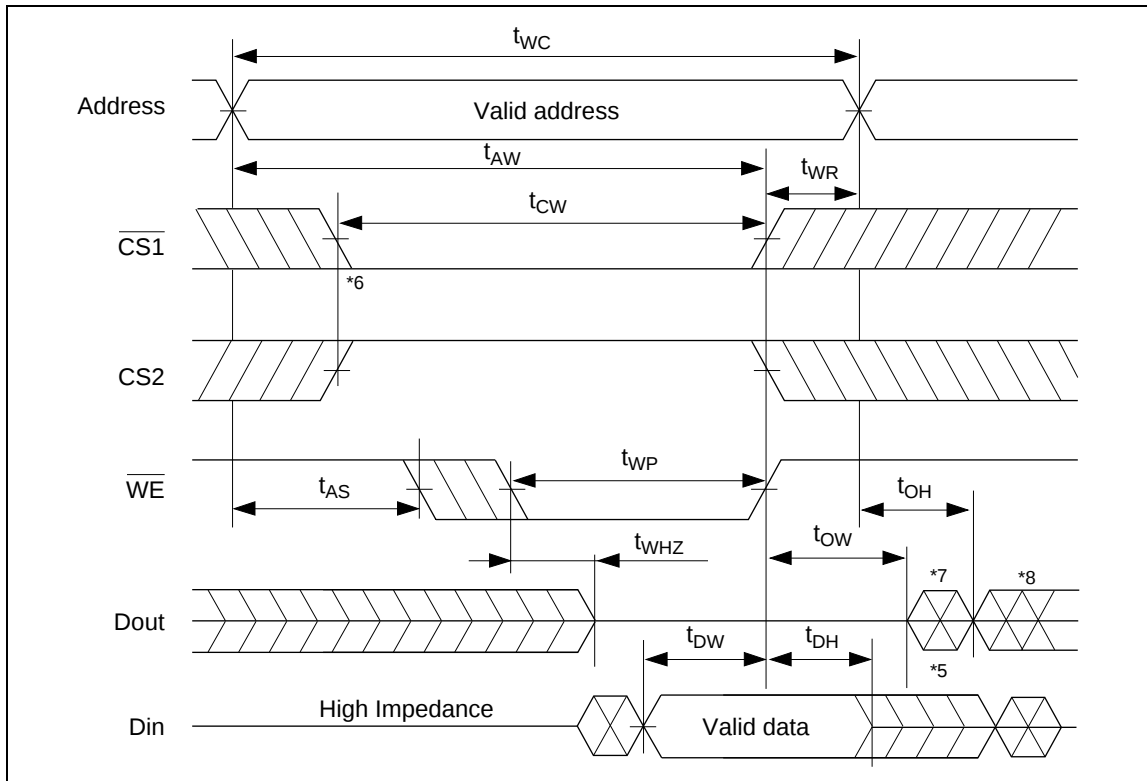
$$t_{WP} \geq t_{WHZ} \max + t_{DW} \min.$$

Write Timing Waveform (1) ($\overline{\text{OE}}$ Clock)



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Write Timing Waveform (2) ($\overline{OE}$ Low Fixed) ($\overline{OE} = V_{IL}$)



Low V_{CC} Data Retention Characteristics ($T_a = -40$ to $+85^\circ\text{C}$)

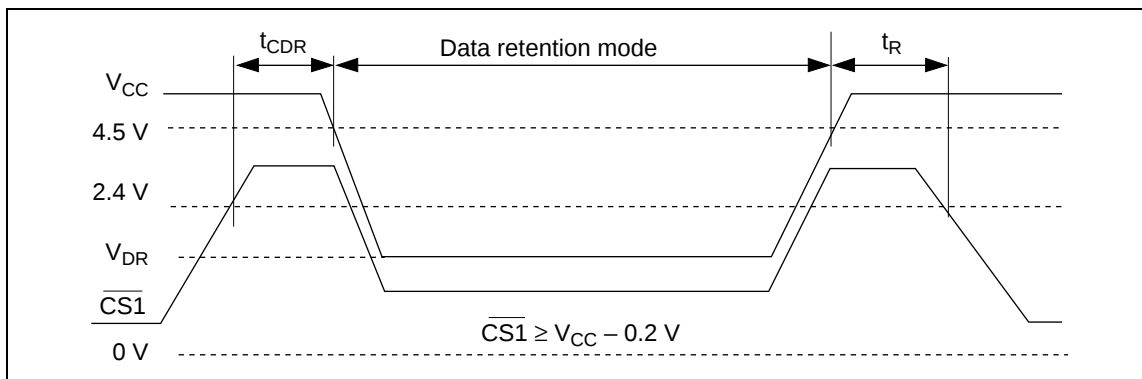
Parameter	Symbol	Min	Typ* ¹	Max	Unit	Test conditions* ³
V_{CC} for data retention	V_{DR}	2.0	—	—	V	CS1 ³ $V_{CC} - 0.2$ V, CS2 ³ $V_{CC} - 0.2$ V or CS2 ² 0.2 V Vin ³ 0 V
Data retention current	I_{CCDR}	—	1* ¹	100* ²	μA	$V_{CC} = 3.0$ V, 0 V ² Vin ² V_{CC} CS1 ³ $V_{CC} - 0.2$ V, CS2 ³ $V_{CC} - 0.2$ V or 0 V ² CS2 ² 0.2 V
Chip deselect to data retention time	t_{CDR}	0	—	—	ns	See retention waveform
Operation recovery time	t_R	5	—	—	ms	

Notes: 1. Reference data at $T_a = 25^\circ\text{C}$.

2. V_{IL} min = -0.3 V.

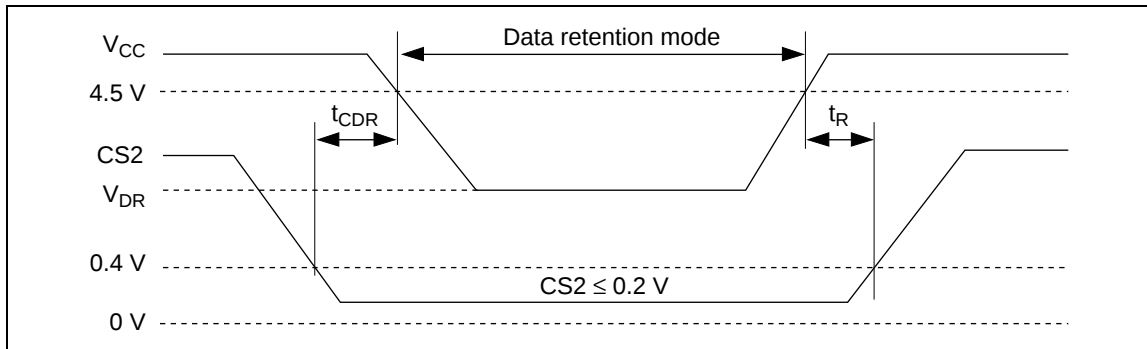
3. CS2 controls address buffer, WE buffer, CS1 buffer, OE buffer, and Din buffer. If CS2 controls data retention mode, Vin levels (address, WE, OE, CS1, I/O) can be in the high impedance state. If CS1 controls data retention mode, CS2 must be CS2 ³ $V_{CC} - 0.2$ V or 0 V ² CS2 ² 0.2 V. The other input levels (address, WE, OE, I/O) can be in the high impedance state.

Low V_{CC} Data Retention Timing Waveform (1) ($\overline{\text{CS1}}$ Controlled)



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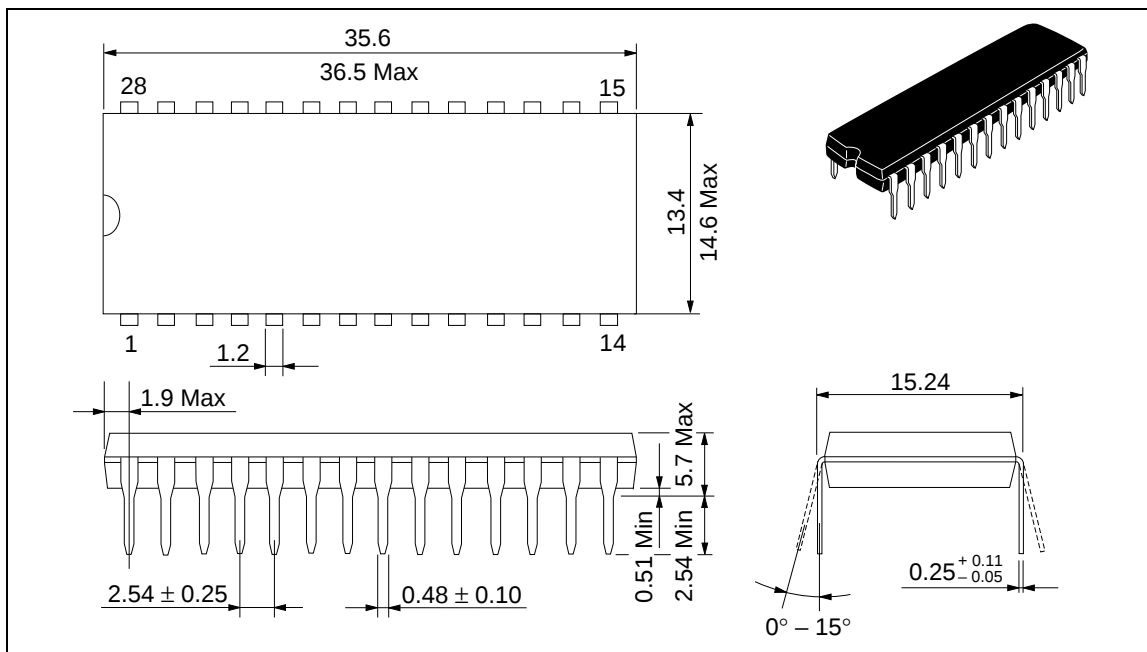
Low V_{CC} Data Retention Timing Waveform (2) (CS2 Controlled)



Package Dimensions

HM6264BLFPI Series (DP-28)

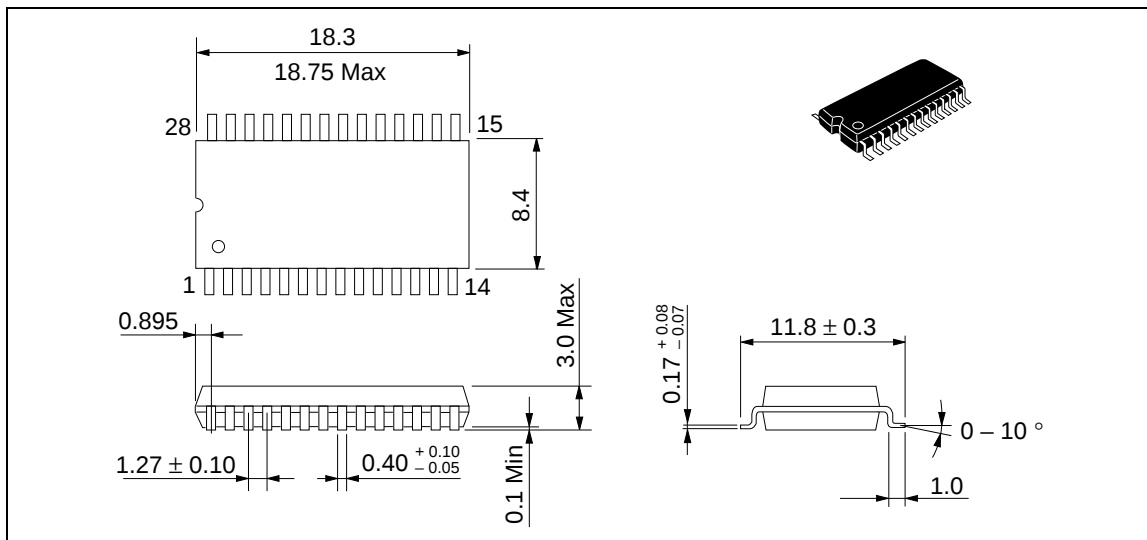
Unit: mm



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HM6264BLPI Series (FP-28DA)

Unit: mm



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0.0	Dec. 1, 1995	Initial issue	I. Ogiwara	K. Yoshizaki
1.0	Sep. 5, 1996	Deletion of Preliminary		