## INTEGRATED CIRCUITS

# DATA SHEET

# TEA6321 Sound fader control circuit

Preliminary specification
File under Integrated Circuits, IC01

August 1993

## **Philips Semiconductors**



**PHILIPS** 

**TEA6321** 

#### **FEATURES**

- Source selector for four stereo and one mono inputs
- Interface for noise reduction circuits
- Interface for external equalizer
- Volume, balance and fader control
- Special loudness characteristic automatically controlled in combination with volume setting
- Bass control with equalizer filters
- Treble control
- Mute control at audio signal zero crossing
- Fast mute control via I<sup>2</sup>C-bus
- Fast mute control via pin
- I<sup>2</sup>C-bus control for all functions
- Power supply with internal power-on reset.

#### **GENERAL DESCRIPTION**

The sound fader control circuit TEA6321 is an I<sup>2</sup>C-bus controlled stereo preamplifier for car radio hi-fi sound applications.



#### **QUICK REFERENCE DATA**

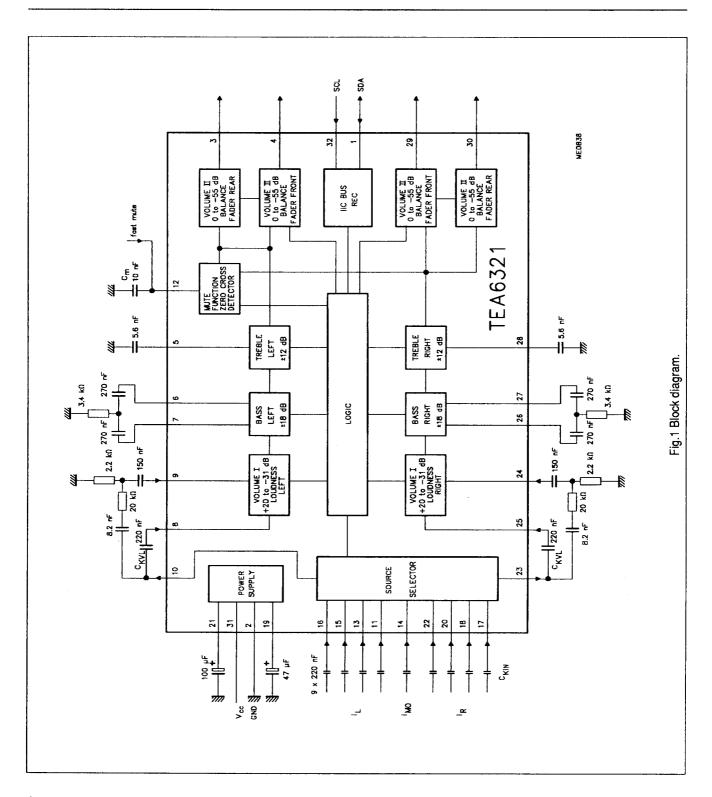
SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
Vcc	positive supply voltage		7.5	8.5	9.5	٧
lcc	supply current	V <sub>CC</sub> = 8.5 V	T-	26	_	mA
Vo(RMS)	maximum output voltage level	V <sub>CC</sub> = 8.5 V; THD ≤ 0.1%	-	2000	_	mV
Gv	volume gain		-86	_	+20	dB
G <sub>step</sub>	step resolution (volume)		-	1	_	dB
G <sub>b</sub>	bass control		-18	<b>–</b>	+18	dB
Gt	treble control		-12	_	+12	dB
Gstep	step resolution (treble)		-	1.5	_	dB
(S+N)/N	signal-plus-noise to noise ratio	$V_0 = 2.0 \text{ V}$ ; $G_V = 0 \text{ dB}$ ; unweighted	T-	105	-	dB
RR <sub>100</sub>	ripple rejection	$V_{r(RMS)} < 200 \text{ mV}$ ; f = 100 Hz; $G_v = 0 \text{ dB}$	-	75	_	dB
α <sub>cs</sub>	channel separation	250 Hz ≤ f ≤ 10 kHz; G <sub>v</sub> = 0 dB	90	96		dB

## **ORDERING INFORMATION**

EXTENDED			PACKAGE	
TYPE NUMBER	PINS	PIN POSITION	MATERIAL	CODE
TEA6321T	32	so	plastic	SOT287AH

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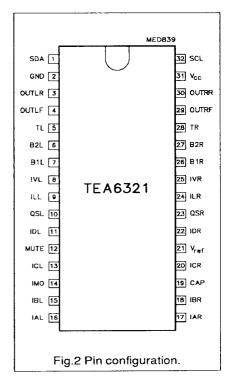


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## **TEA6321**

#### **PINNING**

SYMBOL	PIN	DESCRIPTION
SDA	1	serial data input/output
GND	2	ground
OUTLR	3	output left rear
OUTLF	4	output left front
TL	5	treble control capacitor left channel or input from an
		external equalizer
B2L	6	bass control left channel or output to an external
		equalizer
B1L	7	bass control, left channel
IVL	8	input volume I, left control part
ILL	9	input loudness, left control part
QSL	10	output source selector, left channel
IDL	11	input D left source
MUTE	12	mute control
ICL	13	input C left source
IMO	14	input mono source
IBL	15	input B left source
IAL	16	input A left source
IAR	17	input A right source
IBR	18	input B right source
CAP	19	electronic filtering for supply
ICR	20	input C right source
Vref	21	reference voltage (0.5Vcc)
IDR	22	input D right source
QSR	23	output source selector right channel
ILR	24	input loudness right channel
IVR	25	input volume I, right control part
B1R	26	bass control right channel
B2R	27	bass control right channel or output to an external
		equalizer
TR	28	treble control capacitor right channel or input from an
		external equalizer
OUTRF	29	output right front
OUTRR	30	output right rear
Vcc	31	supply voltage
SCL	32	serial clock input



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#### **FUNCTIONAL DESCRIPTION**

The source selector selects one of 4 stereo inputs or the mono input. The maximum input signal voltage is  $V_{i,(RMS)} = 2 \text{ V}$ . The outputs of the source selector and the inputs of the following volume control parts are available at pins 8 and 10 for the left channel and pins 23 and 25 for the right channel. This offers the possibility of interfacing a noise reduction system.

The volume control function is split into two sections: volume I control block and volume II control block.

The control range of volume I is between +20 dB and -31 dB in steps of 1 dB. The volume II control range is between 0 dB and -55 dB in steps of 1 dB. Although the theoretical possible control range is 106 dB (+20 dB to -86 dB), in practice a range of 86 dB (+20 dB to -66 dB) is recommended. The gain/attenuation setting of the volume I control blocks is common for both channels.

The volume I control blocks operate in combination with the loudness control. The filter is linear when the maximum gain for the volume I control (+20 dB) is selected. The filter characteristic increases automatically over a range of 32 dB down to a setting of -12 dB. That means the maximum filter characteristic is obtained at -12 dB setting of volume I. Further reduction of the volume does not further influence the filter characteristic (see Fig.5). The maximum selected filter characteristic is determined by external components. The proposed application gives a maximum boost of 17 dB for bass and 4.5 dB for treble. The loudness may be switched on or off via I2C-bus control (Table 7).

The volume I control block is followed by the bass control block. An external filter for each channel in combination with internal resistors, provides the frequency response of the bass control (see Fig.3). The adjustable range is between –18 dB and +18 dB in steps of 1.8 dB at 46 Hz.

Both, loudness and bass control result in a maximum bass boost of 35 dB for low volume settings.

The treble control block offers a control range between –12 dB and +12 dB in steps of 1.5 dB at 15 kHz. The filter characteristic is determined by a single capacitor of 5.6 nF for each channel in combination with internal resistors (see Fig.4).

The basic step width of treble control is 3 dB. The intermediate steps are obtained by switching 1.5 dB boost and 1.5 dB attenuation steps.

The bass and treble control functions can be switched off via I<sup>2</sup>C-bus. In this event the internal signal flow is disconnected. The connections B2L / B2R are outputs and TL / TR are inputs for inserting an external equalizer.

The last section of the circuit is the volume II block. The balance and fader functions are performed using the same control blocks. This is realized by 4 independently controllable attenuators, one for each output. The control range of these attenuators is 55 dB in steps of 1 dB with an additional mute step.

The circuit provides 3 mute modes.

1) Zero crossing mode mute via I<sup>2</sup>C-bus using 2 independent zero crossing detectors (ZCM, see Tables 2 and 9 and Fig. 16).

2) Fast mute via mute pin (see Fig.10).

3) Fast mute via I<sup>2</sup>C-bus either by general mute (GMU see Tables 2 and 9) or volume II block setting (see Table 4).

The mute function is performed immediately if ZCM is cleared (ZCM = 0). If the bit is set (ZCM = 1) the mute is activated after changing the GMU bit. The actual mute switching is delayed until the next zero crossing of the audio frequency signal. As the two audio channels (left and right) are independent, two comparators (window detectors) are required to control independent mute switches.

To avoid a large delay of the muting switching when very low frequencies are processed, the maximum delay time is limited to typically 100 ms by an integrated timing circuit and an external capacitor ( $C_m = 10 \text{ nF}$ , see Fig.10). This timing circuit is triggered by reception of a new data word for the switch function which includes the GMU bit. After a discharge and charge period of an external capacitor the muting switch follows the GMU bit if no zero crossing was detected during that time.

The mute function can also be controlled externally. If the mute pin is switched to ground all outputs are muted immediately (hardware mute). This mute request overwrites all mute controls via the I<sup>2</sup>C-bus for the time the pin is held low. The hardware mute position is not stored in the TEA6321.

For the turn on/off behaviour the following explanation is generally valid. To avoid AF output caused by the input signal coming from preceding stages, which produce output during drop of Vcc. The mute has to be set, before the Vcc will drop. This can be achieved by I<sup>2</sup>C-bus control or by grounding the mute pin.

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For use where there is no mute in the application before turn off, a supply voltage drop of more than 1 x V<sub>BE</sub> will result in a mute during the voltage drop. The power supply should include a Vcc buffer capacitor, which provides a discharging time constant. If the input signal does not disappear after turn off the input will become audible after a certain time. A 4.7 k $\Omega$  resistor discharges the Vcc buffer capacitor, because the internal current of the IC does not discharge it completely.

The hardware mute function is favourable for use in RDS (Radio Data System) applications. The zero crossing mute avoids modulation plops. This feature is an advantage for mute during changing presets and/or sources (e. g. traffic announcement during cassette playback).

#### **LIMITING VALUES**

In accordance with the Absolute Maximum Rating System (IEC 134).

SYMBOL	PARAMETER	CONDITIONS	MIN.	MAX.	UNIT
Vcc	supply voltage		0	10	٧
T <sub>amb</sub>	operating ambient temperature		<del>-4</del> 0	+85	°C
T <sub>stg</sub>	storage temperature		-65	+150	°C
Ves	electrostatic handling	note 1			
Vn	voltage at pins: pin 1 to 2 and 3 - 32 to 2		0	Vcc	٧

#### Note to the limiting values

1. Human body model: C = 100 pF; R = 1.5 k $\Omega$ ; V  $\geq$  2 kV Charge device model: C = 200 pF; R = 0  $\Omega$ ; V  $\geq$  500 V.

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## **CHARACTERISTICS**

 $V_{CC}$  = 8.5 V;  $R_S$  = 600  $\Omega$ ,  $R_L$  = 10 k $\Omega$ ,  $C_L$  = 2.5 nF, AC coupled; f = 1 kHz;  $T_{amb}$  = +25 °C; gain control  $G_V$  = 0 dB; bass linear; treble linear; fader off; balance in mid position; loudness off; unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
Vcc	supply voltage		7.5	8.5	9.5	V
lcc	supply current		-	26	33	mA
V <sub>DC</sub>	internal DC voltage at inputs and outputs		3.83	4.25	4.68	V
V <sub>ref</sub>	internal reference voltage at pin 21			4.25	1_	V
Gv	maximum voltage gain	$R_S = 0 \Omega; R_L = \infty$	19	20	21	dB
V <sub>o(RMS)</sub>	output voltage level for					
	P <sub>max</sub> at the power output stage	THD ≤ 0.1%; see Fig.11	_	2000	_	mV
	start of clipping	THD = 1%	2300	_	-	mV
		$R_L = 2 k\Omega$ ; $C_L = 10 nF$ ; THD = 1%	2000	-	-	mV
V <sub>i(RMS)</sub>	input sensitivity	$V_0 = 2000 \text{ mV}$ ; $G_V = 20 \text{ dB}$	-	200	1-	mV
В	roll-off frequencies	C <sub>KIN</sub> = 220 nF; C <sub>KVL</sub> = 220 nF; Z <sub>i</sub> = Z <sub>i min</sub>				
		low frequency (-1 dB)	60	-	-	Hz
		low frequency (-3 dB)	30	_	-	Hz
		high frequency (-1 dB)	20000	-	-	Hz
		CKIN = 470 nF; CKVL = 100 nF;				
		$Z_i = Z_{i \text{ typ}}$		Ì		
		low frequency (–3 dB)	17	<b> </b>	-	Hz
αcs	channel separation	V <sub>i</sub> = 2 V; frequency range 250 Hz to 10 kHz	90	96	_	dB
THD	total harmonic distortion	frequency range 20 Hz to 12.5 kHz				
		$V_i = 100 \text{ mV}; G_v = 20 \text{ dB}$	_	0.1	-	%
		$V_i = 1000 \text{ mV}; G_v = 0 \text{ dB}$	-	0.05	tbn	%
		$V_i = 2000 \text{ mV}; G_v = 0 \text{ dB}$	-	0.1	-	%
		$V_i = 2000 \text{ mV}; G_V = -10 \text{ dB}$	_	0.1	_	%
RR	ripple rejection	V <sub>r(RMS)</sub> < 200 mV				
		f = 100 Hz	tbn	76	_	dB
		f = 40 Hz to 12.5 kHz	_	66	_	dB
(S+N)/N	signal-plus-noise to noise ratio	unweighted; 20 Hz to 20 kHz RMS; $V_0 = 2.0 \text{ V}$ ; see Figs 6 and 7 CCIR 468-2 weighted; quasi peak; $V_0 = 2.0 \text{ V}$	_	105	-	dB
		$G_V = 0 \text{ dB}$	_	95	_	dB
		$G_V = 0.0B$ $G_V = 12 dB$	_	88	-	dB
		$G_V = 12 \text{ dB}$ $G_V = 20 \text{ dB}$	_		-	
		Gy = 20 UD	L	81	<u> </u>	dB

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
Pno(RMS)	noise output power (RMS value)	mute position;	-	_	10	nW
	only contribution of TEA6321;	note 1				
	power amplifier for 6 W					ļ
$\alpha_{\mathrm{B}}$	crosstalk (20 log V <sub>bus(p-p)</sub> / V <sub>o(RMS)</sub> )	note 2	-	110	-	dB
	between bus inputs and signal outputs				<u> </u>	<u>.</u>
Source sele	ector		<b>,</b>			<del></del>
$Z_i$	input impedance		25	35	45	kΩ
αs	input isolation of one selected source	f = 1 kHz	-	105	]-	dB
	to any other input	f = 12.5 kHz	-	95		dB
Vi(RMS)	maximum input voltage (RMS value)	THD < 0.5%; Vcc = 8.5 V	-	2.15	]_	V
		THD < 0.5%; V <sub>CC</sub> = 7.5 V	-	1.8	-	V
V <sub>DC</sub> OFF	DC offset voltage at source selector out		-	_	10	mV
	by selection of any inputs					
Zo	output impedance		Ī-	80	120	Ω
RL	output load resistance		10	_		kΩ
CL	output load capacity		0		2500	рF
Gv	voltage gain, source selector		1_	0	-	dB
	t (source selector disconnected; source re	esistance 600 O)	<del>                                     </del>			
Zi	input impedance volume input	1	100	150	200	kΩ
<b>4</b> -1	input impedance loudness input		25	33	40	kΩ
Z <sub>o</sub>	output impedance		_	80	120	Ω
RL	output load resistance		2	1=	_	kΩ
CL	output load resistance	-	0	-	10	nF
RDCI	DC load resistance at output to ground		4.7	+	1_	kΩ
		THD < 0.5%		2.15	<del></del>	V
Vi(RMS)	maximum input voltage (RMS value)	CCIR 468-2 weighted;	<del> </del>	2.13	+	+
$V_{no}$	noise output voltage	quasi peak				
		G <sub>v</sub> = 20 dB		110	220	μV
		$G_V = 20 \text{ dB}$ $G_V = 0 \text{ dB}$	-	33	50	μV
		, ·		13	22	μV
		G <sub>v</sub> = -66 dB	_		22	'
		mute position	ļ <del>-</del>	10	_	μV
Gc	total continuous control range		-	106		dB
	recommended control range			86		dB
G <sub>step</sub>	step resolution		_	1		dB
	step error between any adjoining step				0.5	dB
$\Delta G_a$	attenuator set error	$G_v = +20 \text{ to } -50 \text{ dB}$	-	-	2	dB
		$G_v = -51 \text{ to } -66 \text{ dB}$			3	dB
$\Delta G_t$	gain tracking error	$G_V = +20 \text{ to } -50 \text{ dB}$			2	dB
$\alpha_{m}$	mute attenuation	see Fig.9	100	110		dB
V <sub>DC</sub> OFF	DC step offset	$G_v = 0$ to $-66$ dB	_	0.2	10	mV
	between any adjoining step	$G_v = 20 \text{ to } 0 \text{ dB}$	1-	2	15	mV
	between any step to mute	$G_v = 0 \text{ to } -66 \text{ dB}$	_	_	10	mV

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
Volume I co	ntrol and loudness					
Gc	continuous volume control range		-	51	_ :	dB
G <sub>v</sub>	volume gain		<u>–</u> 31		20	dB
G <sub>step</sub>	step resolution		Ī —	1	_	dB
L <sub>B</sub>	maximum loudness boost	loudness on; referred to loudness off; boost is determined by external components				
		f = 40 Hz	_	17	_	dB
		f = 10 kHz	_	4.5	_	dB
Bass contro	d		J		\ . <u></u> .	-L
Gb	bass control, maximum boost	f = 46 Hz	17	18	19	dB
_	maximum attenuation	f = 46 Hz	17	18	19	dB
Gstep	step resolution (toggle switching)	f = 46 Hz	_	1.8	1_	dB
r	step error between any adjoining step	f = 46 Hz	1-	-	0.5	dB
V <sub>DC</sub> OFF	DC step offset in any bass position		-	_	10	mV
Treble contr	<del></del>		l		1	
G <sub>t</sub>	treble control, maximum boost	f = 15 kHz	111	12	13	dB
	maximum attenuation	f = 15 kHz	11	12	13	dB
	maximum boost	f > 15 kHz	-	_	15	dB
G <sub>step</sub>	step resolution (toggle switching)	f = 15 kHz	1	1.5	1_	dB
-3tcp	step error between any adjoining step	f = 15 kHz		_	0.5	dB
V <sub>DC</sub> OFF	DC step offset in any treble position			_	10	mV
	alance and fader control		I			1
Gf	continuous attenuation fader and volume control range		53.5	55	56.5	dB
G <sub>step</sub>	step resolution		_	1	2 .	dB
	attenuation set error		-	1-	1.5	dB
Mute function	on (see Fig.10)	<u> </u>				
a) Hardware		,				
Vsw	mute switch level (2 x V <sub>BE</sub> )		I –	1.45	T-	V
mute active:			•		- I	•
Vsw.Low	input level		-	<b>I</b> –	1.0	V
Існ	input current	VswLow = 1 V	-300	1_	1_	μΑ
mute passive	e: level internally defined	<u> </u>	<u> </u>		_ <b>-</b>	<u> </u>
Vsw HIGH	saturation voltage		T -	_	Vcc	V
tomu	delay until mute passive		-	-	0.5	ms
b) Zero cross		<u> </u>		•	-	
lD	discharge current		0.3	0.6	1.2	μА
Існ	charge current		-300	-150	1-	μА
Vswdel	delay switch level (3 x V <sub>BE</sub> )		-	2.2	1-	v
tDEV	delay time	C <sub>m</sub> = 10 nF	1_	100	_	ms
VwIND	window for audio signal zero crossing detection		_	30	40	mV

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
Muting at po	ower supply drop					
VCC-DROP	supply drop for mute active			$V_{19} - 0.7$	_	V
Power on re	set (when reset is active the GMU-bit (ger	neral mute) is set and th	e I <sup>2</sup> C-bus	receiver is	in reset p	osition)
Vcc	increasing supply voltage start of reset		<b> </b> -	_	2.5	V
	end of reset		5.2	6.0	6.8	V
	decreasing supply voltage start of reset		4.2	5.0	5.8	V
Digital part						
I <sup>2</sup> C-bus pins;	see note 3					
ViH	HIGH level input voltage		3	_	9.5	V
VIL	LOW level input voltage		-0.3	_	+1.5	٧
hн	HIGH level input current		-10	_	+10	μА
l <sub>IL</sub>	LOW level input current		-10	_	+10	μА
Vol	LOW level output voltage	IL = 3 mA	_	-	0.4	V

#### Notes to the characteristics

- 1. The indicated values for output power assume a 6 W power amplifier at 4 Ω with 20 dB gain and a fixed attenuator of 12 dB in front of it. Signal-to-noise ratios exclude noise contribution of the power amplifier.
- 2. The transmission contains: total initialization with MAD and Subaddress for volume and 8 data words, see also definition of characteristics, clock frequency = 50 kHz, repetition burst rate = 400 Hz, maximum bus signal amplitude = 5 V<sub>P-P</sub>.
- 3. The AC characteristics are in accordance with the I<sup>2</sup>C-bus specification. Full specification of I<sup>2</sup>C-bus will be supplied on request.

#### I<sup>2</sup>C-BUS PROTOCOL

#### I<sup>2</sup>C-bus format

S	SLAVE ADDRESS	Α	SUBADDRESS	Α	DATA	Α	Р	

#### Where:

S = start condition SLAVE ADDRESS (MAD)= 1000 0000

A = acknowledge, generated by the slave

SUBADDRESS (SAD) = see Table 1

DATA = see Table 1

P = STOP condition

If more than 1 byte of DATA is transmitted, then auto-increment of the significant subaddress is performed.

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#### **Subaddress**

Table 1 Second byte after MAD.

FUNCTION	BIT	MSB							LSB
FONCTION	ВП	7	6	5	4	3	2	1	0
volume/loudness	V	0	0	0	0	0	0	0	0
fader front right	FFR	0	0	0	0	0	0	0	1
fader front left	FFL	0	0	0	0	0	0	1	0
fader rear right	FRR	0	0	0	0	0	0	1	1
fader rear left	FRL	0	0	0	0	0	1	0	0
bass	BA	0	0	0	0	0	1	0	1
treble	TR	0	0	0	0	0	1	1	0
switch	S	0	0	0	0	0	1	1	1
					<b>.</b>		signific	ant suba	ddress

## Definition of third byte

Table 2 Third byte after MAD and SAD.

FUNCTION	ВІТ	MSB							LSB
FONCTION	ВП	7	6	5	4	3	2	1	0
volume/loudness	V	ZCM	LOFF	V5	V4	V3	V2	V1	Vo
fader front right	FFR	X	Х	FFR5	FFR4	FFR3	FFR2	FFR1	FFR0
fader front left	FFL	X	Х	FFL5	FFL4	FFL3	FFL2	FFL1	FFL0
fader rear right	FRR	Х	X	FRR5	FRR4	FRR3	FRR2	FRR1	FRR0
fader rear left	FRL	Х	Х	FRL5	FRL4	FRL3	FRL2	FRL1	FRL0
bass	BA	Х	Х	Х	BA4	ВАЗ	BA2	BA1	BA0
treble	TR	Х	Х	Х	TR4	TR3	TR2	TR1	TR0
switch	S	GMU	X	Х	Х	X	SC2	SC1	SC0

## Function of the bits:

V0 to V5	volume control
40 to 43	volume control

LOFF switch loudness on/off
FRR0 to FRR5 fader control front right
FFL0 to FFL5 fader control front left
FRR0 to FRR5 fader control rear right
FRL0 to FRL5 fader control rear left

BA0 to BA4 bass control
TR0 to TR4 treble control

SC0 to SC2 source selector control

GMU mute control for all outputs (general mute)

ZCM zero crossing mode

X don't care bits (logic 1 during testing)

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Table 3 Volume setting.

0 (40)			D#	ATA		
G <sub>v</sub> (dB)	V5	V4	V3	V2	V1	V0
20	1	1	1	1	1	1
19	1	1	1	1	1	0
18	1	1	1	1	0	1
17	1	1	1	1	0	0
16	1	1	1	0	1	11
15	1	1	1	0	1	0
14	1	1	1	0	0	1
13	1	1	1	0	0	0
12	1	1	0	1	1	1
11	1	1	0	1	1	0
10	1	1	0	1	0	1
9	1	1	0	1	0	0
8	1	1 1	0	0	1	1
7	1	1	0	0	1	0
6	1	1	0	0	0	1
5	1	1	0	0	0	0
4	1	0	1	1	1	1
3	1	0	1	1	1	0
2	1	0	1	1	0	1
1	1	0	1	1	0	0
Ö	1	Ō	1	0	1	1
<u>_1</u>	1	0	1	0	1	0
<u>-2</u>	1	0	1	0	0	1
<u>-3</u>	1	0	1	0	0	0
<u>-4</u>	1	0	Ó	1	1	1
<u>-5</u>	1	Ö	0	1	1	0
<u>–6</u>	1	0	0	1	0	1
_ <del></del> 7	1	0	0	1	0	0
<del>-</del> 8	1	0	0	0	1	1
<del>_</del> 9	1	T o	0	0	1	0
_ <u></u>	1	Ö	0	0	0	1
<u>-11</u>	1	0	0	0	0	0

Loudness on: the increment of the loudness characteristic is linear at every volume step in the range from +20 dB to -11 dB.

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Table 3 Volume setting (continued).

C (4D)			DA	ATA		
G <sub>v</sub> (dB)	V5	V4	V3	<b>V2</b>	<b>V</b> 1	Vo
-12	0	1	1	1	1	1
<b>–13</b>	0	1	1	1	1	0
-14	0	1	1	1	0	1
-15	0	1	1	1	0	0
-16	0	1	1	0	1	1
-17	0	1	1	0	1	0
-18	0	1	1	0	0	1
-19	0	1	1	0	0	0
-20	0	1	0	1	1	1
-21	0	1	0	1	1	0
-22	0	1	0	1	0	1
-23	0	1	0	1	0	0
-24	0	1	0	0	1	1
<b>–25</b>	0	1	0	0	1	0
-26	0	1	0	0	0	1
-27	0	1.	0	0	0	0
-28	0	0	1	1	1	1
-29	0	0	1	1	1	0
-30	0	0	1	11	0	11
-31	0	0	11	1	0	0

Loudness characteristic is constant in a range from -11 dB to -31 dB.

Table 3 Volume setting (continued).

C (4P)			DA	TA		
G <sub>v</sub> (dB)	<b>V</b> 5	V4	V3	V2	V1	VO
-28	0	0	11	0	1	1
				•		
-				-		
31	0	0	0	0	0	0

Repetition of steps in a range from -28 dB to -31 dB.

Table 4 Fader setting.

			DA	TA		
	FRR5	FRR4	FRR3	FRR2	FRR1	FRR0
G <sub>v</sub> (dB)	FRL5	FRL4	FRL3	FRL2	FRL1	FRLO
	FFL5	FFL4	FFL3	FFL2	FFL1	FFL0
	FFR5	FFR4	FFR3	FFR2	FFR1	FFR0
0	1	1	1	1	1	1
<b>–1</b>	1	1	1	1	1	0
-2	1	1	1	1	0	1
-3	1	1	1	1	0	0
-4	1	1	1	0	1	1
-5	1	1	1	0	1	0
-6	1	1	1	0	0	11
<b>–</b> 7	1	1	1	0	0	0
-8	11	1	0	1	1	1
-9	11	1	0	1	1	0
-10	1	1	0	1	0	11
-11	1	1	0	1	0	0
-12	11	1	0	0	1	1
<b>–13</b>	11	11	0	0	1	0
-14	1	1	0	0	0	11
<u>–15</u>	1	11	0	0	0	0
-16	1	0	1	1 1	1	1
-17	1	0	1	1	1	0
-18	11	0	11	1	0	11
<u>–19</u>		0	1	1	0	0
-20	1	0	1	0	1	11
-21	1	0	1	0	1	0
-22	1	0	11	0	0	1 1
-23	1	0	11	0	0	0
<u>-24</u>		0	0	1	1	1
<u>-25</u>	1	0	0	1	1	0
<u>-26</u>	1	0	0	1 1	0	1
<u>-27</u>	1	0	0	1 0	0	0
-28 20	1	0	0	0	1 1	0
<u>-29</u>	1	0	0	0	0	1
<u>30</u> 31	1	0	0	0	0	0
-31 -32	0	1	1	1	1	1
<u>-3∠</u> -33	0	1	1	1	1 1	Ö
-33 -34	0	1	1	+ + -	0	1
-3 <del>4</del> -35	0	1	1	<del>                                     </del>	0	0
-36	0	1	1	0	1 1	1
<u>–36</u> –37	0		1	0	1	0
	0	1	1	0	0	1

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			DA	TA		
	FRR5	FRR4	FRR3	FRR2	FRR1	FRR0
G <sub>v</sub> (dB)	FRL5	FRL4	FRL3	FRL2	FRL1	FRL0
	FFL5	FFL4	FFL3	FFL2	FFL1	FFL0
	FFR5	FFR4	FFR3	FFR2	FFR1	FFR0
-39	0	1	1	0	0	0
<del>-4</del> 0	0	1	0	1	1	1
-41	0	1	0	1	1	0
-42	0	1	0	1	0	1
<b>–43</b>	0	1	0	1	0	0
-44	0	1	0	0	1	0
<b>-45</b>	0	1	0	0	1	0
<del>-4</del> 6	0	1	0	0	0	1
<del>-4</del> 7	0	1	0	0	0	0
-48	0	0	1	1	1	1
<del>-4</del> 9	0	0	1	1	1	0
<i>–</i> 50	0	0	1	1	0	1
<u>–51</u>	0	0	1	1	0	0
<b>-52</b>	0	0	1	0	1	1
-53	0	0	1	0	11	0
-54	0	0	1	0	0	1
<b>–55</b>	0	0	1	0	0	0
mute	0	0	0	1	11	1
mute	0	0	0	11	1	0
mute	0	0	0	11	0	11
mute	0	0	0	1	0	0
mute	0	0	0	0	1	11
mute	0	0	0	0	1	0
mute	0	0	0	0	0	1
mute	0	0	0	0	0	0

For a particular range the data is always the same, only the subaddress changes.

Table 5 Bass setting.

O (-ID)			DATA		
G <sub>v</sub> (dB)	BA4	BA3	BA2	BA1	BA0
18	1	1	1	1	1
16.2	1	1	1	1	0
18	1	1	1	0	1
16.2	1	1	1	0	0
18	1	1	0	1	1
16.2	1	1	0	1	0
14.4	1	1	0	0	1
12.6	1	1	0	0	0
10.8	1	0	1	1	_1
9	1	0	1	1	0
7.2	1	0	1	0	1
5.4	1	0	1	0	0
3.6	1	0	0	1	1
1.8	1	0	0	1	0
0 *	1	0	0	0	1
0 **	1	0	0	0	0
-1.8	0	1	1	1	11
-3.6	0	1	1	1	0
-5.4	0	1	1	0	1
-7.2	0	1	1	0	0
<b>-</b> 9	0	1	0	1	1
-10.8	0	1	0	1	0
-12.6	0	1	0	0	1
-14.4	0	1	0	0	0
-16.2	0	0	1	11	1
-18	0	0	1	1	0
-16.2	Ö	0	1	0	1
-18	0	0	1	0	0
***	0	0	0	1	1
***	0	Ō	0	1	0
***	0	Ō	0	0	1
*** ****	0	0	0	0	0

<sup>\*</sup> Recommended data word for step 0 dB.

<sup>\*\*</sup> Result of 1.8 dB boost and 1.8 dB attenuation.

<sup>\*\*\*</sup> The last four bass control data words mute the bass response.

<sup>\*\*\*\*</sup> The last bass control and treble control data words (00000) enable the external equalizer connection.

Table 6 Treble setting.

C (4D)			DATA		
G <sub>v</sub> (dB)	TR4	TR3	TR2	TR1	TR0
12	1	1	1	1	1
10.5	1	1	1	1	0
12	1	1	1	0	1
10.5	1	1	1	0	0
12	1	1	0	1	1
10,5	1	1	0	1	0
12	1	1	0	0	1
10.5	1	1	0	0	0
9	1	0	1	1	1
7.5	1	0	1	1	0
6	1	0	1	0	1
4.5	1	0	1	0	0
3	1	0	0	1	1
1.5	1	0	0	1	0
0 *	1	0	0	0	1
0 **	1	0	0	0	0
-1.5	0	1	1	1	1
-3	0	1	1	1	0
-4.5	0	1	1	0	1
<u>-6</u>	0	1	1	0	0
<i>−</i> 7.5	0	1	0	1	1
<b>–9</b>	0	1	0	1	0
_10.5	0	1	0	0	1
-12	0	1	0	0	0
***	0	0	11	1	1
***	0	0	11	1	0
***	0	0	1	0	1
***	0	0	1	0	0
***	0	0	0	1	1
***	0	0	0	1	0
***	0	0	0	0	1
*** ****	0	0	0	0	0

<sup>\*</sup> Recommended data word for step 0 dB.

<sup>\*\*</sup> Result of 1.5 dB boost and 1.5 dB attenuation.

<sup>\*\*\*</sup> The last eight treble control data words select treble cut.

<sup>\*\*\*\*</sup> The last treble control and bass control data words (00000) enable the external equalizer connection.

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## Table 7 Loudness setting.

CHARACTERISTIC	DATA L OFF
with loudness	0
linear	1

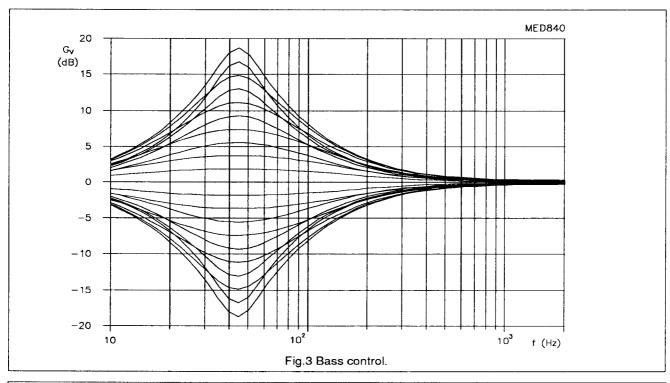
## Table 8 Selected inputs.

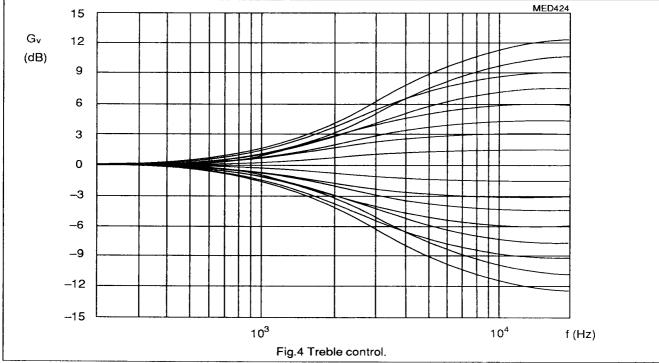
INPUTS		DATA	
INPUIS	SC2	SC1	SC0
IAL, IAR stereo	1	1	1
IBL, IBR stereo	1	1	0
ICC, ICR stereo	1	0	1
IDL, IDR stereo	1	0	0
IMO, mono	0	Х	X

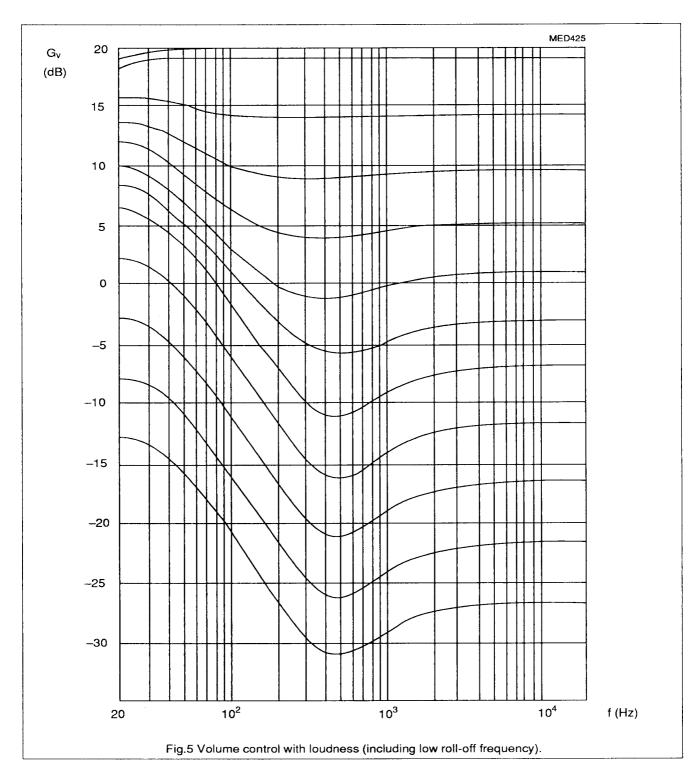
#### Table 9 Mute mode.

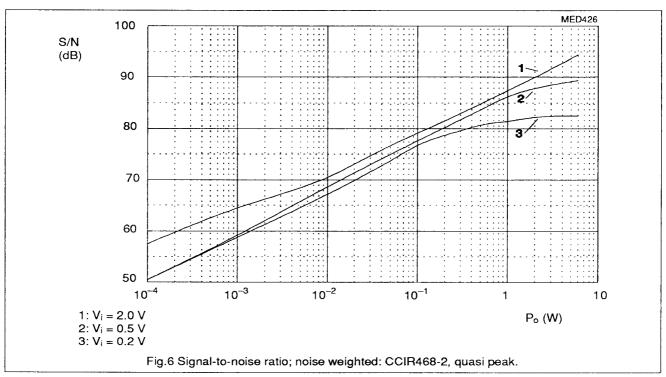
GMU	ZCM	mode
0	0	direct mute off
0	1	mute off delayed until the next zero crossing
1	0	direct mute
1	1	mute delayed until the next zero crossing

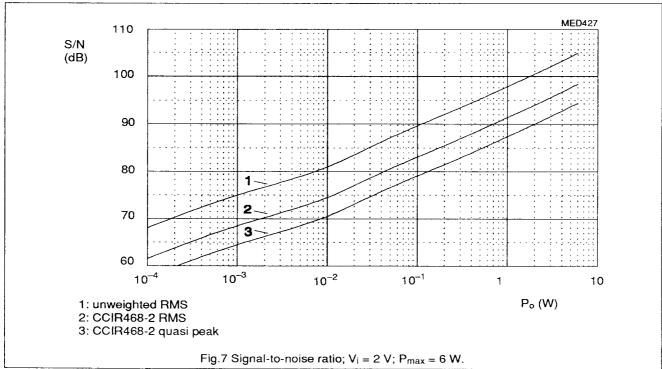
X = don't care bits (logic 1 during testing)

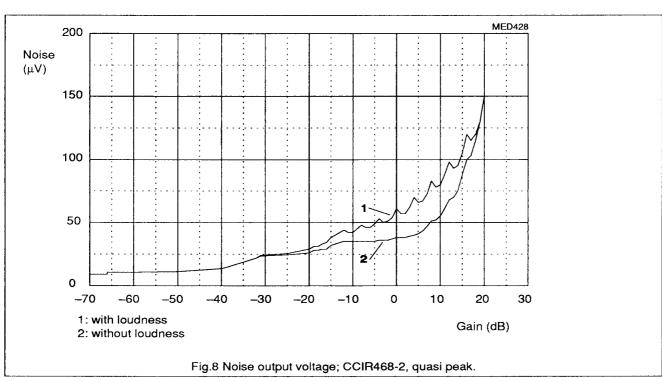


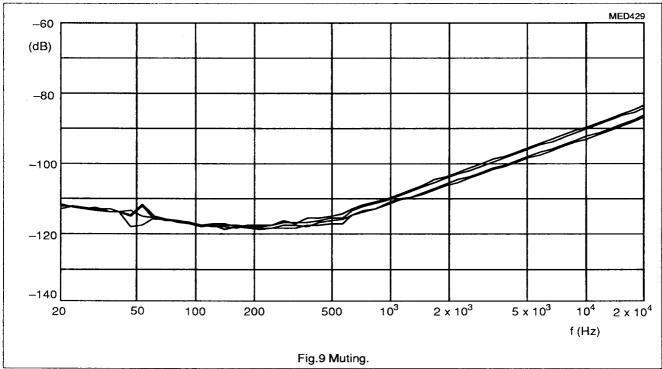


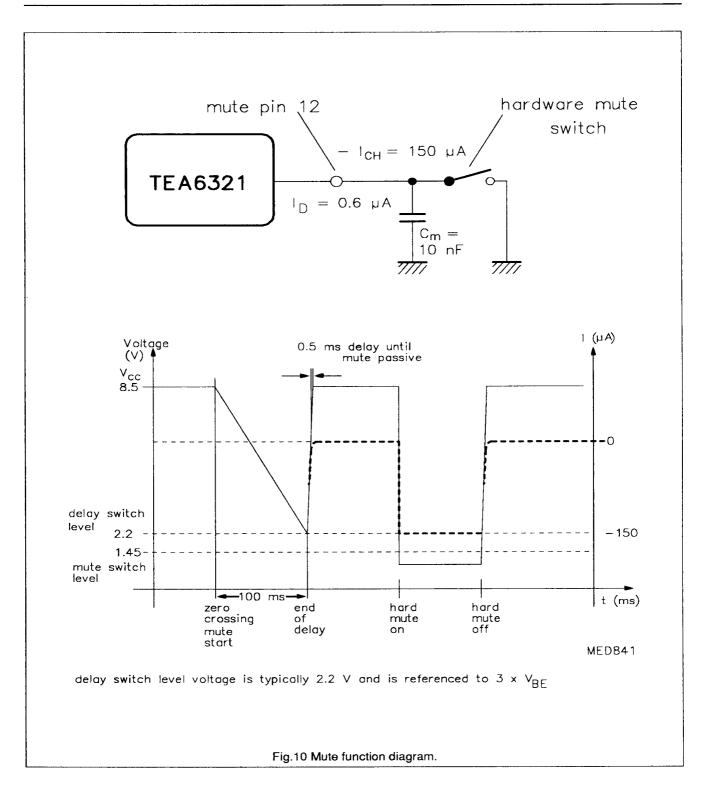








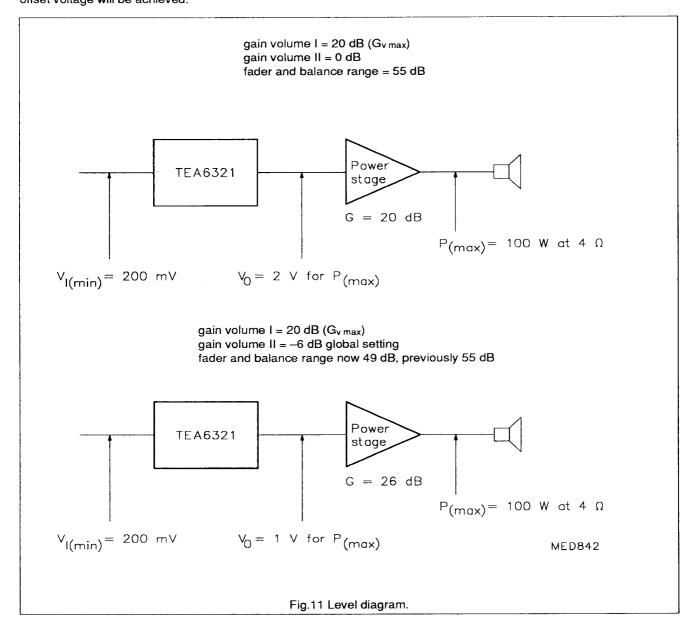




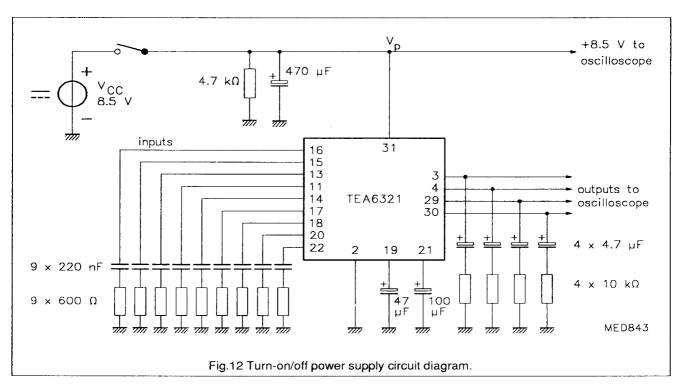
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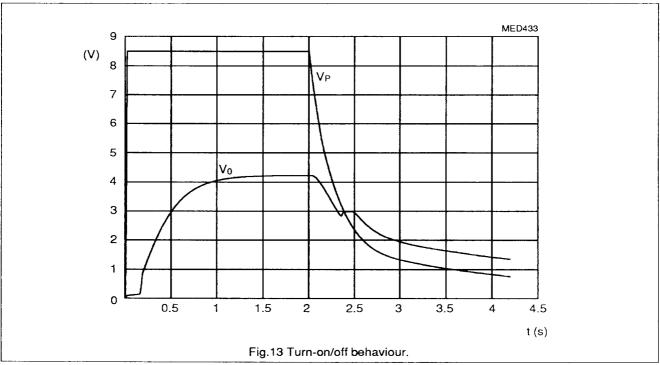
If the 20 dB gain is not required for the maximum volume position, it will be an advantage to use the maximum boost gain and then increased attenuation in the last section, Volume II.

Therefore the loudness will be at the correct place and a lower noise and offset voltage will be achieved.

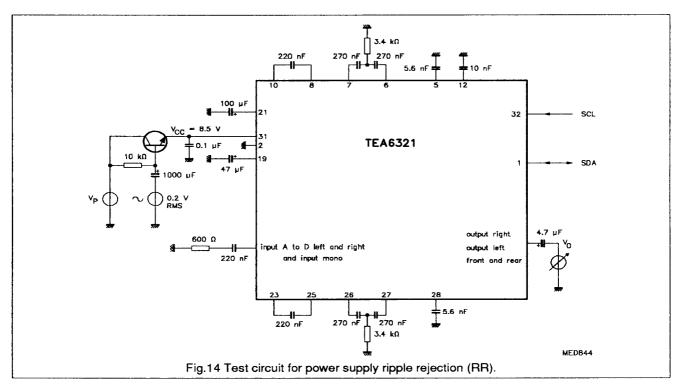


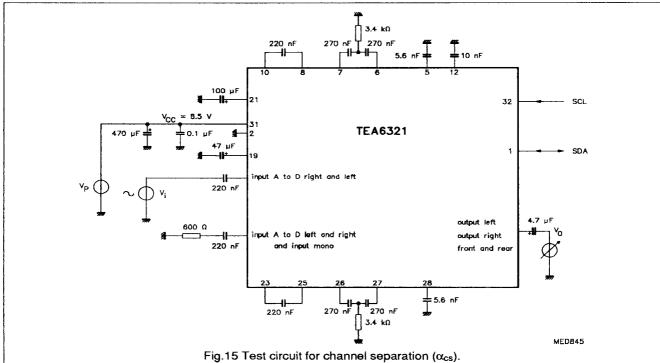
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## **TEA6321**

# Selection of input signals by using the zero crossing mute mode

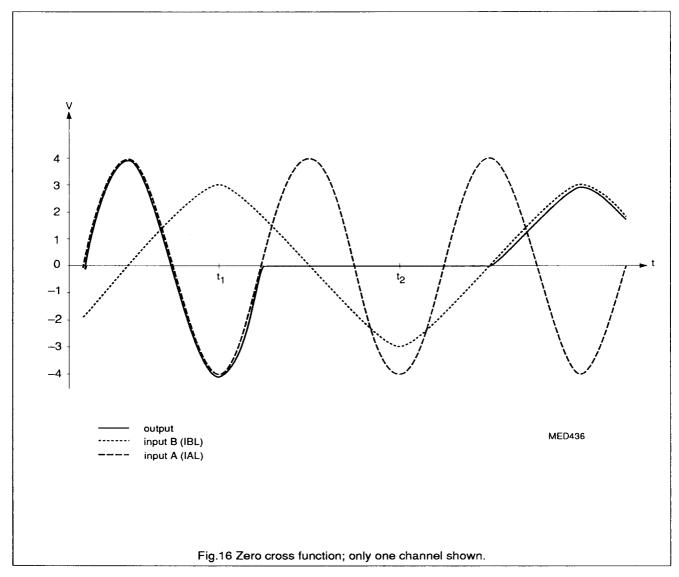
A selection from input A (IAL) to input B (IBL) left sources produces a modulation click depending on the difference of the signal values at the time of switching.

At  $t_1$  the maximum possible difference between signals is 7  $V_{(p-p)}$  and gives a large click. Using the zero cross detector no modulation click is audible.

For example: The selection is enabled at t<sub>1</sub>, the microcontroller sets the zero cross bit (ZCM = 1) and then the mute bit (GMU = 1) via the I<sup>2</sup>C-bus. The output signal follows the input A signal, until the next zero crossing occurs and then activates mute.

After a fixed delay time at t<sub>2</sub>, the microcontroller sends the bits for input switching and mute inactive.

The output signal remains muted until the next signal zero crossing of input B (IBL) occurs, and then follows that signal. The delay time  $t_2-t_1$  is e. g. 40 ms. Therefore is the capacity CM=3.3 nF. The zero cross function is working at the lowest frequency of 40 Hz determined by the CM capacitor.



## **TEA6321**

# Loudness filter calculation example

Fig.17 shows the basic loudness circuit with an external low pass filter application.  $R_1$  allows an attenuation range of 21 dB while the boost is determined by the gain stage  $V_2$ . Both result in a loudness control range of +20 dB to -12 dB. Defining  $f_{reference}$  as the frequency where the level does not change while switching loudness on/off. The external resistor  $R_3$  for  $f_{reference} \rightarrow \infty$  can be calculated as

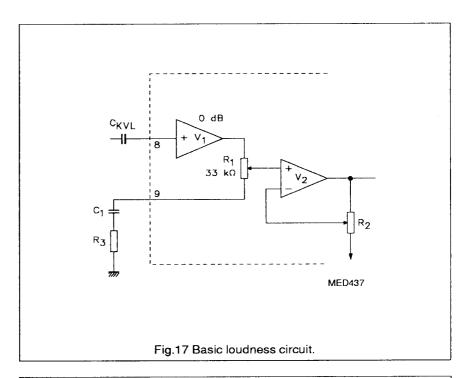
$$R_3 = R_1 \, \frac{10^{\,G_{v/20}}}{1-10^{\,G_{v/20}}}$$

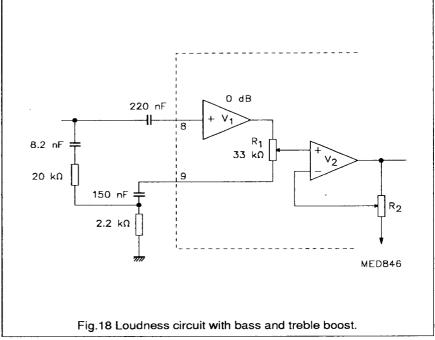
with  $G_V=-21$  dB and  $R_1=33~k\Omega$   $R_3=3.2~k\Omega$  is generated. For the low pass filter characteristic the value of the external capacitor  $C_1$  can be determined by setting a specific boost for a defined frequency and referring the gain to  $G_V$  at freference as indicated above.

$$\big|\frac{1}{j\omega C_1}\big| = \frac{(R_1 + R_3) \times 10^{G_{u/20}} - R_3}{1 - 10^{G_{u/20}}}$$

For example: 3 dB boost at f=1 kHz  $G_v=G_v$  reference +3 dB =-18 dB; f=1 kHz and  $C_1=100$  nF If a loudness characteristic with additional high frequency boost is desired, an additional high pass section has to be included in the external filter circuit as indicated in the block diagram. A filter configuration that provides AC coupling avoids offset voltage problems.

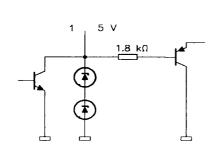
Fig.18 shows an example of the loudness circuit with bass and treble boost. The calculation of this network is numeric.



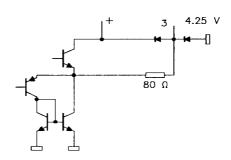


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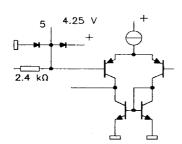
## INTERNAL PIN CONFIGURATIONS



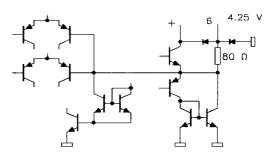
Pin 1: SDA (I<sup>2</sup>C-bus data)



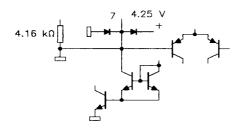
Pin 3: Output left, rear Pin 4: Output left, front Pin 29: Output right, front Pin 30: Output right, rear



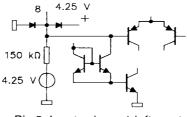
Pin 5: Treble control capacitor, left channel Pin 28: Treble control capacitor, right channel



Pin 6: Bass control output, left channel Pin 27: Bass control output, right channel



Pin 7: Bass control input, left channel Pin 26: Bass control input, right channel



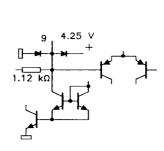
Pin 8: Input volume 1 left, control part Pin 25: Input volume 1 right, control part

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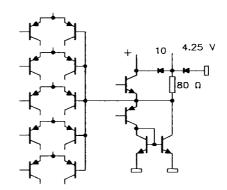
Pin equivalent circuits  $V_{CC} = 8.5 \text{ V}$  (All values shown are typical DC values)

Fig.19 Internal circuits (continued in Fig.20).

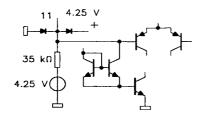
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Pin 9: Input loudness left, control part Pin 24: Input loudness right, control part



Pin 10: Output source selector, left channel Pin 23: Output source selector, right channel



Pin 11: Input D left source Pin 13: Input C left source

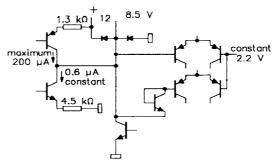
Pin 14: Input mono source Pin 15: Input B left source

Pin 16: Input A left source Pin 17: Input A right source

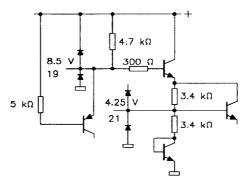
Pin 18: Input B right source

Pin 20: Input C right source

Pin 22: Input D right source



Pin 12: Mute control



Pin 19: Filtering for supply Pin 21: Reference voltage

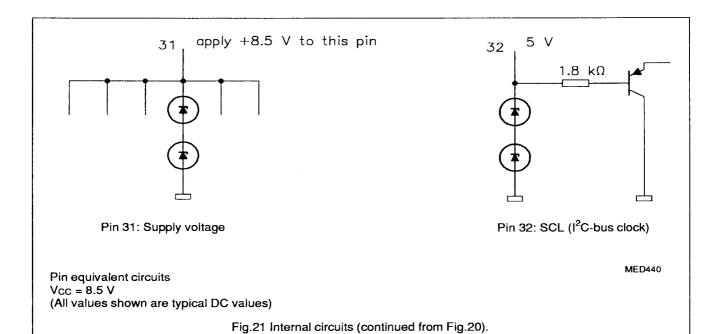
Pin equivalent circuits

 $V_{CC} = 8.5 V$ 

(All values shown are typical DC values)

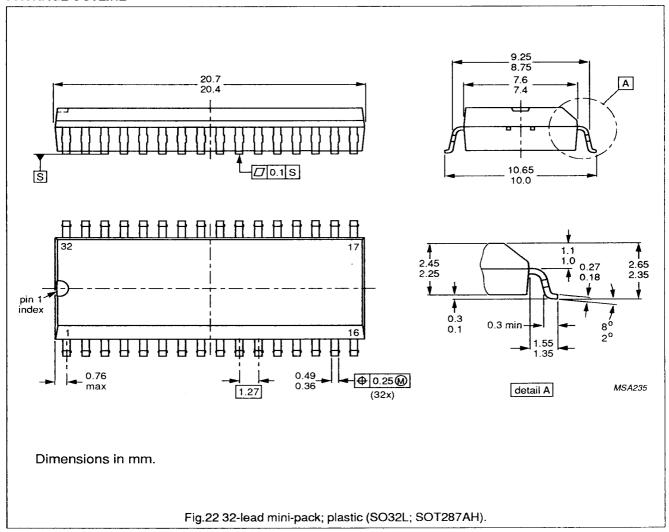
MED439

Fig.20 Internal circuits (continued from Fig.19).



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#### **PACKAGE OUTLINE**



TEA6321

# SOLDERING Plastic mini-packs

BY WAVE

During placement and before soldering, the component must be fixed with a droplet of adhesive. After curing the adhesive, the component can be soldered. The adhesive can be applied by screen printing, pin transfer or syringe dispensing.

Maximum permissible solder temperature is 260 °C and maximum duration of package immersion in solder bath is 10 s, if allowed to cool to less than 150 °C within 6 s. Typical dwell time is 4 s at 250 °C.

A modified wave soldering technique is recommended using two solder waves (dual-wave) in which a turbulent wave with high upward pressure is followed by a smooth laminar wave. Using a mildly-activated flux eliminates the need for removal of corrosive residues in most applications.

BY SOLDER PASTE REFLOW

Reflow soldering requires the solder paste (a suspension of fine solder particles, flux and binding agent) to be applied to the substrate by screen printing, stencilling or pressure-syringe dispensing before device placement.

Several techniques exist for reflowing; for example, thermal conduction by heated belt, infrared, and vapour-phase reflow. Dwell times vary between 50 and 300 s according to method. Typical reflow temperatures range from 215 to 250 °C.

Preheating is necessary to dry the paste and evaporate the binding agent. Preheating duration: 45 min at 45 °C.

REPAIRING SOLDERED JOINTS (BY HAND-HELD SOLDERING IRON OR PULSE-HEATED SOLDER TOOL)

Fix the component by first soldering two, diagonally opposite, end pins. Apply the heating tool to the flat part of the pin only. Contact time must be limited to 10 s at up to 300 °C. When using proper tools, all other pins can be soldered in one operation within 2 to 5 s at between 270 and 320 °C. (Pulse-heated soldering is not recommended for SO packages).

For pulse-heated solder tool (resistance) soldering of VSO packages, solder is applied to the substrate by dipping or by an extra thick tin/lead plating before package placement.

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#### **DEFINITIONS**

Data sheet status	
Objective specification	This data sheet contains target or goal specifications for product development.
Preliminary specification	This data sheet contains preliminary data; supplementary data may be published later.
Product specification	This data sheet contains final product specifications.
Limiting values	
more of the limiting values operation of the device at	in accordance with the Absolute Maximum Rating System (IEC 134). Stress above one of smay cause permanent damage to the device. These are stress ratings only and these or at any other conditions above those given in the Characteristics sections of this d. Exposure to limiting values for extended periods may affect device reliability.
Application information	
Where application informa	ation is given, it is advisory and does not form part of the specification.

#### **LIFE SUPPORT APPLICATIONS**

These products are not designed for use in life support appliances, devices, or systems where malfunction of these products can reasonably be expected to result in personal injury. Philips customers using or selling these products for use in such applications do so at their own risk and agree to fully indemnify Philips for any damages resulting from such improper use or sale.

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Purchase of Philips I<sup>2</sup>C components conveys a license under the Philips' I<sup>2</sup>C patent to use the components in the I<sup>2</sup>C system provided the system conforms to the I<sup>2</sup>C specification defined by Philips. This specification can be ordered using the code 9398 393 40011.

August 1993

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