# Serial-In Parallel-Out Shift Register

The SN74LS164 is a high speed 8-Bit Serial-In Parallel-Out Shift Register. Serial data is entered through a 2-Input AND gate synchronous with the LOW to HIGH transition of the clock. The device features an asynchronous Master Reset which clears the register setting all outputs LOW independent of the clock. It utilizes the Schottky diode clamped process to achieve high speeds and is fully compatible with all ON Semiconductor TTL products.

- Typical Shift Frequency of 35 MHz
- Asynchronous Master Reset
- Gated Serial Data Input
- Fully Synchronous Data Transfers
- Input Clamp Diodes Limit High Speed Termination Effects
- ESD > 3500 Volts

#### **GUARANTEED OPERATING RANGES**

Symbol	Parameter	Min	Тур	Max	Unit
V <sub>CC</sub>	Supply Voltage	4.75	5.0	5.25	V
T <sub>A</sub>	Operating Ambient Temperature Range	0	25	70	°C
I <sub>OH</sub>	Output Current – High			-0.4	mA
I <sub>OL</sub>	Output Current – Low			8.0	mA



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LOW POWER SCHOTTKY



PLASTIC N SUFFIX CASE 646



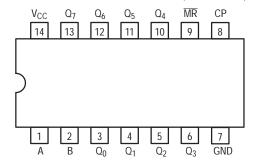
SOIC D SUFFIX CASE 751A

#### **ORDERING INFORMATION**

Device	Package	Shipping
SN74LS164N	14 Pin DIP	2000 Units/Box
SN74LS164D	14 Pin	2500/Tape & Reel

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# **CONNECTION DIAGRAM DIP (TOP VIEW)**



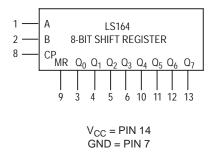
NOTE: The Flatpak version has the same pinouts (Connection Diagram) as the Dual In-Line Package.

		LOADING (Note a)	
PIN NAMES		HIGH	LOW
A, B	Data Inputs	0.5 U.L.	0.25 U.L.
CP	Clock (Active HIGH Going Edge) Input	0.5 U.L.	0.25 U.L.
MR	Master Reset (Active LOW) Input	0.5 U.L.	0.25 U.L.
$Q_0 - Q_7$	Outputs	10 U.L.	5 U.L.

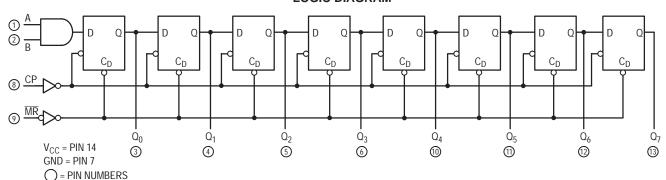
#### NOTES:

a) 1 TTL Unit Load (U.L.) = 40  $\mu$ A HIGH/1.6 mA LOW.

# LOGIC SYMBOL



#### LOGIC DIAGRAM



# **FUNCTIONAL DESCRIPTION**

The LS164 is an edge-triggered 8-bit shift register with serial data entry and an output from each of the eight stages. Data is entered serially through one of two inputs (A or B); either of these inputs can be used as an active HIGH Enable for data entry through the other input. An unused input must be tied HIGH, or both inputs connected together.

Each LOW-to-HIGH transition on the Clock (CP) input shifts data one place to the right and enters into  $Q_0$  the logical AND of the two data inputs (A•B) that existed before the rising clock edge. A LOW level on the Master Reset ( $\overline{\text{MR}}$ ) input overrides all other inputs and clears the register asynchronously, forcing all Q outputs LOW.

#### **MODE SELECT — TRUTH TABLE**

OPERATING		INPUTS		OUTPUTS		
MODE	MR	Α	В	$Q_0$	Q <sub>1</sub> –Q <sub>7</sub>	
Reset (Clear)	L	Х	Х	L	L – L	
Shift	H H H	l h h	   h   h	LLH	q <sub>0</sub> – q <sub>6</sub> q <sub>0</sub> – q <sub>6</sub> q <sub>0</sub> – q <sub>6</sub> q <sub>0</sub> – q <sub>6</sub>	

L (I) = LOW Voltage Levels

H (h) = HIGH Voltage Levels

X = Don't Care

 $<sup>\</sup>label{eq:qn} q_n = \text{Lower case letters indicate the state of the referenced input or output one} \\ \text{set-up time prior to the LOW to HIGH clock transition.}$ 

# DC CHARACTERISTICS OVER OPERATING

TEMPERATURE RANGE (unless otherwise specified)

		Limits					
Symbol	Parameter	Min	Тур	Max	Unit	Test C	onditions
V <sub>IH</sub>	Input HIGH Voltage	2.0			V	Guaranteed Input All Inputs	t HIGH Voltage for
V <sub>IL</sub>	Input LOW Voltage			0.8	V	Guaranteed Input All Inputs	t LOW Voltage for
V <sub>IK</sub>	Input Clamp Diode Voltage		-0.65	-1.5	V	V <sub>CC</sub> = MIN, I <sub>IN</sub> =	–18 mA
V <sub>OH</sub>	Output HIGH Voltage	2.7	3.5		V	V <sub>CC</sub> = MIN, I <sub>OH</sub> = or V <sub>IL</sub> per Truth T	
.,	0 / / 0 / / / /		0.25	0.4	V	I <sub>OL</sub> = 4.0 mA	$V_{CC} = V_{CC} MIN,$
V <sub>OL</sub>	Output LOW Voltage		0.35	0.5	V	I <sub>OL</sub> = 8.0 mA	V <sub>IN</sub> = V <sub>IH</sub> or V <sub>IL</sub> per Truth Table
	land HOLL Company			20	μΑ	V <sub>CC</sub> = MAX, V <sub>IN</sub> :	= 2.7 V
1 <sub>IH</sub>	Input HIGH Current			0.1	mA	V <sub>CC</sub> = MAX, V <sub>IN</sub> :	= 7.0 V
I <sub>IL</sub>	Input LOW Current			-0.4	mA	$V_{CC} = MAX, V_{IN} = 0.4 V$	
I <sub>OS</sub>	Short Circuit Current (Note 1)	-20		-100	mA	V <sub>CC</sub> = MAX	
I <sub>CC</sub>	Power Supply Current			27	mA	V <sub>CC</sub> = MAX	

Note 1: Not more than one output should be shorted at a time, nor for more than 1 second.

# AC CHARACTERISTICS $(T_A = 25^{\circ}C)$

		Limits				
Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions
f <sub>MAX</sub>	Maximum Clock Frequency	25	36		MHz	
t <sub>PHL</sub>	Propagation Delay MR to Output Q		24	36	ns	$V_{CC} = 5.0 \text{ V}$ $C_{L} = 15 \text{ pF}$
t <sub>PLH</sub> t <sub>PHL</sub>	Propagation Delay Clock to Output Q		17 21	27 32	ns	

# AC SETUP REQUIREMENTS $(T_A = 25^{\circ}C)$

		Limits					
Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions	
t <sub>W</sub>	CP, MR Pulse Width	20			ns		
t <sub>s</sub>	Data Setup Time	15			ns	V 50V	
t <sub>h</sub>	Data Hold Time	5.0			ns	V <sub>CC</sub> = 5.0 V	
t <sub>rec</sub>	MR to Clock Recovery Time	20			ns		

# **AC WAVEFORMS**

\*The shaded areas indicate when the input is permitted to change for predictable output performance.

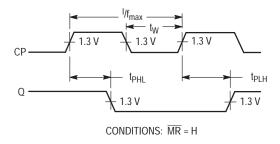


Figure 1. Clock to Output Delays and Clock Pulse Width

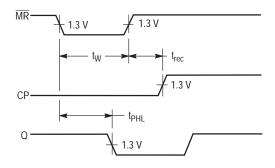


Figure 2. Master Reset Pulse Width, Master Reset to Output Delay and Master Reset to Clock Recovery Time

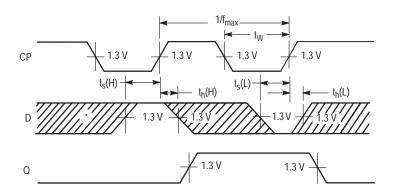
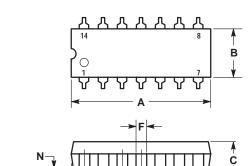


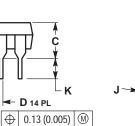
Figure 3. Data Setup and Hold Times

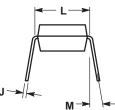
# **PACKAGE DIMENSIONS**

### **N SUFFIX** PLASTIC PACKAGE CASE 646-06 ISSUE M



-T-SEATING PLANE

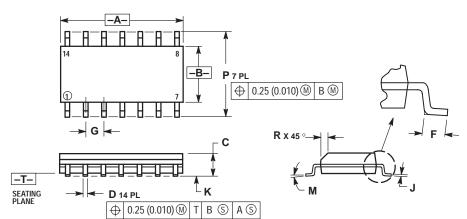




- NOTES:
  1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
  2. CONTROLLING DIMENSION: INCH.
  3. DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL.
  4. DIMENSION B DOES NOT INCLUDE MOLD FLASH.
  5. ROUNDED CORNERS OPTIONAL.

	INC	HES	MILLIN	IETERS	
DIM	MIN	MAX	MIN	MAX	
Α	0.715	0.770	18.16	18.80	
В	0.240	0.260	6.10	6.60	
С	0.145	0.185	3.69	4.69	
D	0.015	0.021	0.38	0.53	
F	0.040	0.070	1.02	1.78	
G	0.100	BSC	2.54 BSC		
Н	0.052	0.095	1.32	2.41	
J	0.008	0.015	0.20	0.38	
K	0.115	0.135	2.92	3.43	
L	0.290	0.310	7.37	7.87	
М		10°		10°	
N	0.015	0.039	0.38	1.01	

# **D SUFFIX** PLASTIC SOIC PACKAGE CASE 751A-03 ISSUE F



- NOTES:
  1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
  2. CONTROLLING DIMENSION: MILLIMETER.
  3. DIMENSIONS A AND B DO NOT INCLUDE MOLD PROTRUSION.
  4. MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER SIDE.
  5. DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127 (0.005) TOTAL IN EXCESS OF THE D DIMENSION AT MAXIMUM MATERIAL CONDITION.

	MILLIN	METERS	INCHES		
DIM	MIN	MAX	MIN	MAX	
Α	8.55	8.75	0.337	0.344	
В	3.80	4.00	0.150	0.157	
С	1.35	1.75	0.054	0.068	
D	0.35	0.49	0.014	0.019	
F	0.40	1.25	0.016	0.049	
G	1.27	BSC	0.050 BSC		
J	0.19	0.25	0.008	0.009	
K	0.10	0.25	0.004	0.009	
M	0 °	7°	0 °	7°	
Р	5.80	6.20	0.228	0.244	
R	0.25	0.50	0.010	0.019	

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**JAPAN**: ON Semiconductor, Japan Customer Focus Center 4–32–1 Nishi–Gotanda, Shinagawa–ku, Tokyo, Japan 141–8549

**Phone**: 81–3–5487–8345 **Email**: r14153@onsemi.com

Fax Response Line: 303-675-2167

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