Advance Information

1MB and 2MB Synchronous Fast Static RAM Module

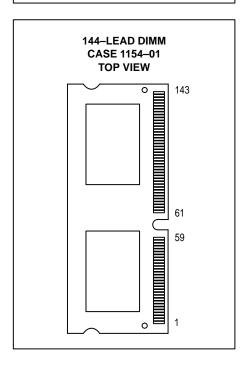
The MCM36F8 (1MB) is configured as $256K \times 36$ bits and the MCM36F9 (2MB) is configured as $512K \times 36$ bits. Both are packaged in a 144–pin dual–in–line memory module (DIMM). Each module uses Motorola's $3.3 \times 256K \times 18$ bit flow–through BurstRAMs.

_Address (A), data inputs (DQ, DP), and all control signals except output enable (G) are clock (K) controlled through positive–edge–triggered noninverting registers.

Write cycles are internally self–timed and initiated by the rising edge of the clock (K) input. This feature provides increased timing flexibility for incoming signals. Synchronous byte write (BWx) and global byte write (WE) allows writes to either individual bytes or to both bytes.

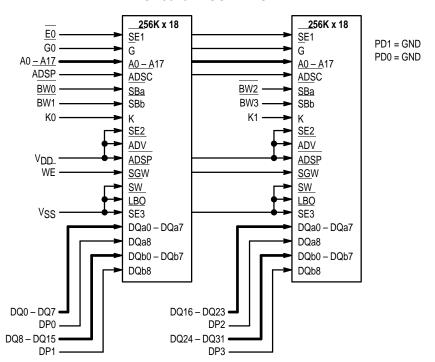
- Single 3.3 V + 10%, 5% Power Supply
- Multiple Clock Pins for Reduced Loading
- All Inputs and Outputs are LVTTL Compatible
- Byte Write and Global Write Capability
- Fast SRAM Access Times: 10 ns
- Berg Connector, Part Number: 61178-31844
- 144-Pin DIMM Module

MCM36F8 MCM36F9



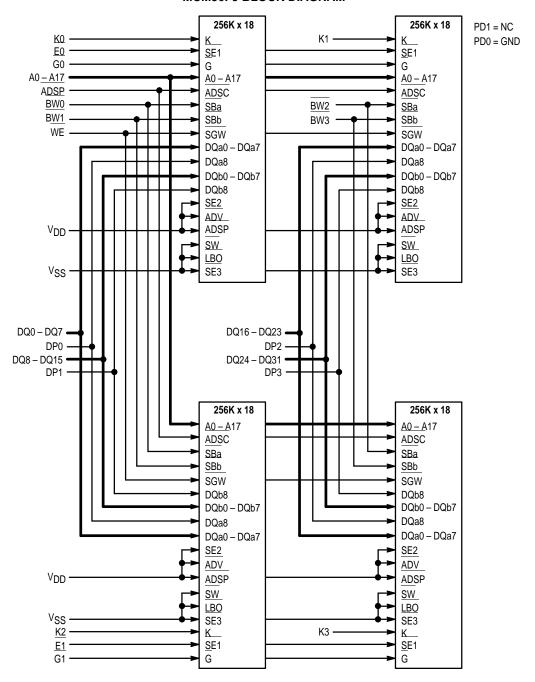
This document contains information on a new product. Specifications and information herein are subject to change without notice.

MCM36F8 BLOCK DIAGRAM



MCM36F8•MCM36F9 MOTOROLA FAST SRAM

MCM36F9 BLOCK DIAGRAM



MOTOROLA FAST SRAM MCM36F8•MCM36F9

PIN ASSIGNMENT 144-LEAD DIMM TOP VIEW

VSS A0 A2 A4 VDD NC NC VSS A6 A8 A10 NC VDD A12 A14 A16 VSS BW0 E0 VSS DQ0 VDD DQ2 DQ4 DQ6 VSS	1 3 5 7 9 11 13 15 17 19 21 23 25 27 29 31 33 35 37 39 41 43 45 47 49 51 55 57 59	2 4 6 8 10 12 14 16 18 20 22 24 26 28 30 32 34 36 38 40 42 44 46 48 50 52 54 56 56 56 56 56 56 56 56 56 56 56 56 56	VSS A1 A3 A5 VDD NC NC VSS A7 A9 A11 NC VDD A13 A15 VSS BW1 VSS DQ1 VDD DQ3 DQ7 VSS
VDD DQ8 DQ10 VSS DQ12 DQ14 DP0 NC NC VSS WE NC VDD NC NC NC VDD NC NC NC VDD NC NC NC VSS BW2 E1 VDD DQ16 DQ18 NC NC VSS CQ20 VSS DQ20 DQ24 DQ26 DQ28 VDD DQ30 DP2 VSS	61 63 65 67 69 71 73 75 77 79 81 83 85 87 89 91 93 95 97 99 101 103 105 107 109 111 113 115 117 119 121 123 125 127 129 131 133 135 137 139 141 143	62 64 66 68 70 72 74 76 78 80 82 84 86 88 90 92 94 96 98 100 102 104 116 118 120 122 124 126 128 130 132 134 136 138 140 142 144	VDD DQ9 DQ1 VSS DQ1 DP1 NC

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PIN DESCRIPTIONS

Pin Locations	Symbol	Туре	Description
3, 4, 5, 6, 7, 8, 17, 18, 19, 20, 21, 22, 27, 28, 29, 30, 31, 32	A0 – A17	Input	Synchronous Address Inputs: These inputs are registered and must meet setup and hold times.
82	ADSP	Input	Synchronous Addresss Status Controller: Initiates read, write, or chip deselect cycle.
39, 40, 103, 104	BW0 – BW3	Input	Synchronous Byte Write Inputs: x refers to the byte being written (byte a, b, c, d). WE overrides BWx.
73, 74, 141, 142	DP0 – DP3		Synchronous Parity Data Inputs/Outputs.
(a) 49, 50, 53, 54, 55, 56, 57, 58, (b) 63, 64, 65, 66, 69, 70, 71, 72 (c) 109, 110, 111, 112, 125, 126, 129, 130 (d) 131, 132, 133, 134, 135, 136, 139, 140	DQ0 – DQ31	I/O	Synchronous Data Inputs/Outputs.
41, 105	E0, E1	Input	Synchronous Chip Enable: Active low to enable chip. Negated high — deselects chip when ADSP is asserted.
42, 106	G0, G1	Input	Asynchronous Output Enable Input.
46, 45, 122, 121	K0 – K3	Input	Clock: This signal registers the address, data in, and all control signals except G.
35, 36	PD0, PD1	Output	Presence Detect Bits.
81	WE	Input	Synchronous Global Write: <u>This</u> signal writes all bytes regardless of the status of the BWx signals. If only byte write signals SBx are being used, tie this pin high.
9, 10, 25, 26, 51, 52, 61, 62, 85, 86, 93, 94, 107, 108, 137, 138	V _{DD}	Supply	Power Supply: 3.3 V + 10%, – 5%.
1, 2, 15, 16, 33, 34, 37, 38, 43, 44, 47, 48, 59, 60, 67, 68, 79, 80, 101, 102, 119, 120, 123, 124, 127, 128, 143, 144	VSS	Supply	Ground.
11, 12, 13, 14, 23, 24, 75, 76, 77, 78, 83, 84, 87, 88, 89, 90, 91, 92, 95, 96, 97, 98, 99, 100, 113, 114, 115, 116, 117, 118	NC	_	No Connection: There is no connection to the chip.

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TRUTH TABLE (See Notes 1 through 4)

Next Cycle	Address Used	Ex	ADSP	Gx	DQx	WRITE ^{2, 4}
Deselect	None	1	0	Х	High-Z	Х
Begin Read	External	0	0	0	DQ	Read
Read	Current	Х	1	1	High-Z	Read
Read	Current	Х	1	0	DQ	Read
Begin Write	External	0	0	Х	High-Z	Write
Write	Current	Х	1	Х	High-Z	Write

NOTES:

- 1. X = don't care, 1 = logic high, 0 = logic low.
- 2. Write is defined as either any BWx or WE low.
- 3. Gx is an asynchronous signal and is not sampled by the clock K. Gx drives the bus immediately (t_{GLQX}) following Gx going low.
- 4. On write cycles that follow read cycles, Gx must be negated prior to the start of the write cycle to ensure proper write data setup times. Gx must also remain negated at the completion of the write cycle to ensure proper write data hold times.

ABSOLUTE MAXIMUM RATINGS (Voltages Referenced to V_{SS} = 0 V)

Rating	Symbol	Value	Unit
Power Supply Voltage	V _{DD}	- 0.5 to + 4.6	V
Voltage Relative to VSS	V _{in} , V _{out}	- 0.5 to V _{DD} + 0.5	V
Output Current (per I/O)	l _{out}	± 20	mA
Temperature Under Bias	T _{bias}	- 10 to + 85	°C
Storage Temperature	T _{stg}	- 55 to + 125	°C

NOTE: Permanent device damage may occur if ABSOLUTE MAXIMUM RATINGS are exceeded. Functional operation should be restricted to RECOMMENDED OPER-ATING CONDITIONS. Exposure to higher than recommended voltages for extended periods of time could affect device reliability.

This device contains circuitry to protect the inputs against damage due to high static voltages or electric fields; however, it is advised that normal precautions be taken to avoid application of any voltage higher than maximum rated voltages to this high–impedance circuit.

This BiCMOS memory circuit has been designed to meet the dc and ac specifications shown in the tables, after thermal equilibrium has been established.

This device contains circuitry that will ensure the output devices are in High–Z at power up.

MCM36F8∙MCM36F9 MOTOROLA FAST SRAM

DC OPERATING CONDITIONS AND CHARACTERISTICS

 $(V_{DD} = 3.3 \text{ V} + 10\%, -5\%, T_A = 0 \text{ to } 70^{\circ}\text{C}, \text{ Unless Otherwise Noted})$

RECOMMENDED OPERATING CONDITIONS (Voltages Referenced to $V_{SS} = 0 V$)

Parameter	Symbol	Min	Тур	Max	Unit
Supply Voltage	V_{DD}	3.135	3.3	3.6	V
Input High Voltage	V _{IH}	2.0	_	V _{DD} + 0.5	V
Input Low Voltage	V _{IL}	- 0.5*	_	0.8	V

^{*} $V_{IL} \ge -2.0 \text{ V for } t \le t_{KHKH}/2.$

DC CHARACTERISTICS

Parameter	Symbol	Min	Max	Unit
Input Leakage Current (0 $V \le V_{in} \le V_{DD}$)	I _{lkg(I)}	_	± 1.0	μΑ
Output Leakage Current (0 $V \le V_{in} \le V_{DD}$)	I _{lkg(O)}	_	± 1.0	μΑ
Output Low Voltage (I _{OL} = + 8.0 mA)	V _{OL}	_	0.4	V
Output High Voltage (I _{OH} = -4.0 mA)	Voн	2.4		V

POWER SUPPLY CURRENTS

Parameter		Symbol	Min	Max	Unit	Notes
AC Supply Current (Device Selected, All Outputs Open, Cycle Time ≥ t _{KHKH} min)	MCM36F8DG10 MCM36F9DG10	IDDA		550 860	mA	1, 2, 3
CMOS Standby Supply Current (Deselected, Clock (K) Cycle Time \geq t _{KHKH} , All Inputs Toggling at CMOS Levels V _{in} \leq V _{SS} + 0.2 V or \geq V _{DD} - 0.2 V)	MCM36F8DG10 MCM36F9DG10	I _{SB1}	_	310 620	mA	
Clock Running Supply Current (Deselected, Clock (K) Cycle Time \geq t _{KHKH} , All Other Inputs Held to Static CMOS Levels V _{in} \leq V _{SS} + 0.2 V or \geq V _{DD} - 0.2 V)	MCM36F8DG10 MCM36F9DG10	I _{SB2}	I	190 380	mA	4

NOTES:

- 1. Reference AC Operating Conditions and Characteristics for input and timing (V_{IH}/V_{IL} , t_{I}/t_{f} , pulse level 0 to 3.0 V, V_{IH} = 3.0 V).
- 2. All addresses transition simultaneously low (LSB) and then high (HSB).
- 3. Data states are all zero.
- 4. Device in deselected mode as defined by the Truth Table.

$\textbf{MCM36F8 CAPACITANCE} \ (f = 1.0 \ \text{MHz}, \ \text{dV} = 3.0 \ \text{V}, \ T_{A} = 0 \ \text{to} \ 70^{\circ}\text{C}, \ \text{Periodically Sampled Rather Than} \ 100\% \ \text{Tested})$

	Parameter	Symbol	Тур	Max	Unit
Input Capacitance	BWx, K Other Inputs	C _{in}	_ _	10 15	pF
I/O Capacitance		C _{I/O}	_	13	pF

$\textbf{MCM36F9 CAPACITANCE} \ (f = 1.0 \ \text{MHz}, \ \text{dV} = 3.0 \ \text{V}, \ T_{A} = 0 \ \text{to} \ 70 \ ^{\circ}\text{C}, \ \text{Periodically Sampled Rather Than } 100\% \ \text{Tested})$

Parameter	Symbol	Тур	Max	Unit
Input CapacitanceK Addr, ADSP, WE Other Inputs		_ _ _	10 25 15	pF
I/O Capacitance	C _{I/O}	_	21	pF

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AC OPERATING CONDITIONS AND CHARACTERISTICS

 $(V_{DD} = 3.3 \text{ V} + 10\%, -5\%, T_A = 0 \text{ to } 70^{\circ}\text{C}, \text{ Unless Otherwise Noted})$

Input Timing Measurement Reference Level 1.25 V	Output Timing Reference Level
Input Pulse Levels 0 to 2.5 V	Output Load See Figure 1 Unless Otherwise Noted
Input Rise/Fall Time 1 V/ns (20 to 80%)	

DATA RAM READ/WRITE CYCLE TIMING (See Notes 1, 2, 3, and 4)

		MCM36 MCM36			
Parameter	Symbol	Min	Max	Unit	Notes
Cycle Time	^t KHKH	15	_	ns	
Clock Access Time	^t KHQV	_	10	ns	
Output Enable to Output Valid	^t GLQV	_	3.5	ns	
Clock High to Output Active	^t KHQX1	0	_	ns	5
Clock High to Output Change	^t KHQX2	2	_	ns	5
Output Enable to Output Active	^t GLQX	0	_	ns	5
Output Disable to Q High–Z	^t GHQZ	_	3.5	ns	5, 6
Clock High to Q High-Z	^t KHQZ	2	3.5	ns	5, 6
Clock High Pulse Width	^t KHKL	4.5	_	ns	
Clock Low Pulse Width	^t KLKH	4.5	_	ns	
Setup Times: Address ADSP Data In Write Chip Enable	^t AVKH ^t ADKH ^t DVKH ^t WVKH ^t EVKH	2	ı	ns	
Hold Times: Address ADSP, ADSC, ADV Data In Write Chip Enable	[†] KHAX [†] KHADX [†] KHDX [†] KHWX [†] KHEX	0.5	_	ns	

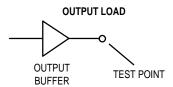
NOTES:

- 1. Write is defined as either any BWx and SW low or WE is low.
- 2. Chip Enable is defined as E0 low, SE2 high, and SE3 low whenever ADSP or ADSC is asserted.
- 3. All read and write cycle timings are referenced from K0 or G0.
- 4. G0 is a don't care after write cycle begins. To prevent bus contention, G0 should be negated prior to start of write cycle.
- 5. This parameter is sampled and not 100% tested.
- 6. Measured at ± 200 mV from steady state.

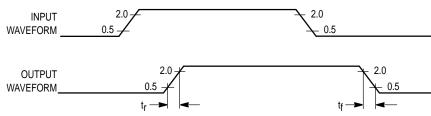
TIMING LIMITS

The table of timing values shows either a minimum or a maximum limit for each parameter. Input requirements are specified from the external system point of view. Thus, address setup time is shown as a minimum since the system must supply at least that much time (even though most devices do not require it). On the other hand, responses from the memory are specified from the device point of view. Thus, the access time is shown as a maximum since the device never provides data later than that time.

Figure 1. AC Test Load



UNLOADED RISE AND FALL TIME MEASUREMENT

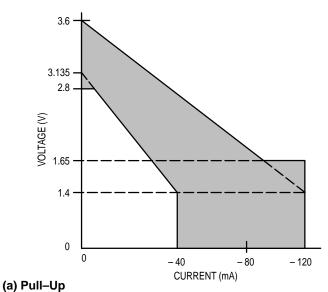


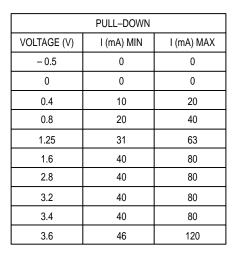
NOTES:

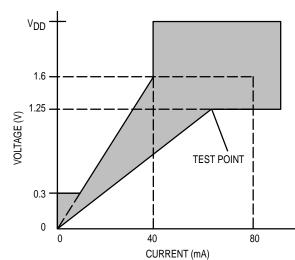
- 1. Input waveform has a slew rate of 1 V/ns.
- 2. Rise time is measured from 0.5 to 2.0 V unloaded.
- 3. Fall time is measured from 2.0 to 0.5 V unloaded.

Figure 2. Unloaded Rise and Fall Time Characterization

	PULL-UP	
VOLTAGE (V)	I (mA) MIN	I (mA) MAX
- 0.5	- 50	- 150
0	- 50	- 150
1.4	- 50	- 150
1.65	- 46	- 130
2.0	- 35	- 101
3.135	0	- 25





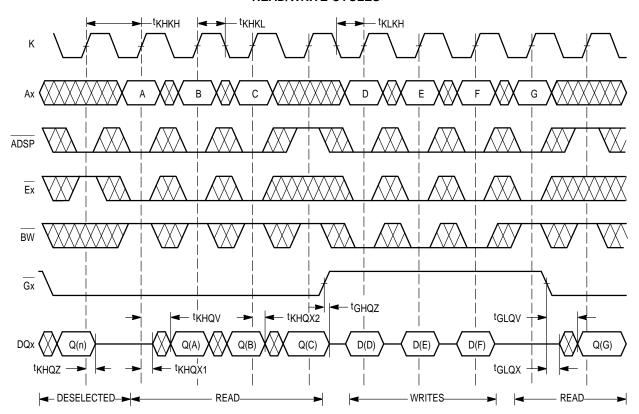


(b) Pull-Down Figure 3. Output Buffer Characteristics

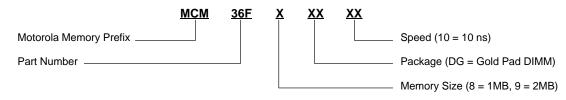
MOTOROLA FAST SRAM MCM36F8•MCM36F9

9

READ/WRITE CYCLES



ORDERING INFORMATION (Order by Full Part Number)

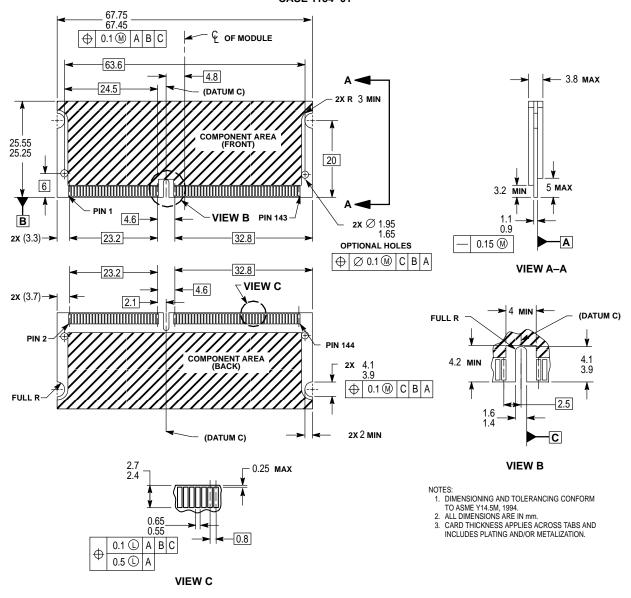


Full Part Numbers — MCM36F8DG10 MCM36F9DG10

MCM36F8•MCM36F9 MOTOROLA FAST SRAM

PACKAGE DIMENSIONS

144-LEAD DIMM CASE 1154-01



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