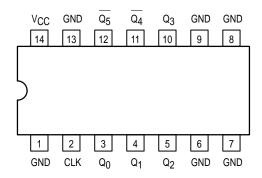
Low Skew CMOS Clock Driver

The MC88913 is a high–speed, low power, hex divide–by–two D–type flip–flop with two inverting and four non–inverting outputs that have closely matched propagation delays. With a TTL compatible buffered clock input that is common to all flip–flops, the MC88913 is ideal for use in high–frequency systems as a clock driver, providing multiple outputs that are synchronous.

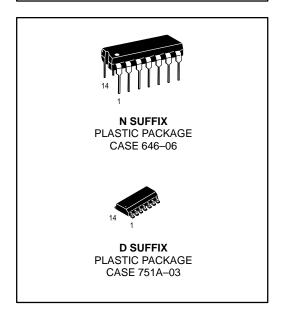
- Minimum Clock Input fMAX of 110MHz
- TTL Compatible Positive Edge-Triggered Clock
- · Matched Outputs for Synchronous Applications
- · Outputs Source/Sink 24mA
- Part-to-Part Skew of Less Than 4.0ns
- Guaranteed Rise and Fall Times for a Given Capacitive Load

Pinout: 14-Lead Plastic (Top View)



MC88913

LOW SKEW CMOS CLOCK DRIVER



MAXIMUM RATINGS*

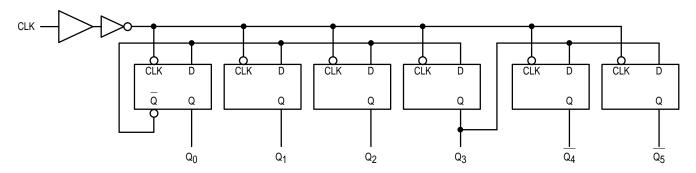
Symbol	Parameter	Value	Units
VCC	DC Supply Voltage (Referenced to GND)	-0.5 to +7.0	V
V _{in}	DC Input Voltage (Referenced to GND)	-0.5 to V _{CC} + 0.5	V
V _{out}	DC Output Voltage (Referenced to GND)	-0.5 to V _{CC} + 0.5	V
l _{in}	DC Input Current, per Pin	± 20	mA
l _{out}	DC Output Sink/Source Current, per Pin	± 50	mA
Icc	DC V _{CC} or GND Current per Output Pin	± 50	mA
P _D	Power Dissipation in Still Air Plastic Package** SOIC Package**	750 500	mW
T _{stg}	Storage Temperature	-65 to +150	°C
TL	Lead Temperature, 1mm from Case for 10s (Plastic or SOIC Package)	260	°C

^{*} Maximum Ratings are those values beyond which damage to the device may occur. Functional operation should be restricted to the Recommended Operating Conditions.

MOTOROLA

^{**} Derating: Plastic Package: -10mW/°C from 65°C to 125°C SOIC Package: -7.0mW/°C from 65°C to 125°C

LOGIC DIAGRAM



NOTE: This diagram is provided only for understanding of logic operation and should not be used to estimate propagation delays

RECOMMENDED OPERATING CONDITIONS

Symbol	Parameter	Min	Max	Unit
Vcc	DC Supply Voltage (Referenced to GND)	2.0	6.0	V
V _{in} , V _{out}	DC Input Voltage, Output Voltage (Referenced to GND)	0	VCC	V
TA	Operating Temperature	-40	+85	°C
t _r , t _f	Input Rise and Fall Time V _{in} from 0.8 to 2.0V V _{meas} from 0.8 to 2.0V	0	10 8.0	ns/V

DC CHARACTERISTICS (unless otherwise specified)

Symbol	Parameter		Unit	Condition
ICC	Maximum Quiescent Supply Current	80	μА	V _{IN} = V _{CC} or GND V _{CC} = 5.5V, T _A = Worst Case
ICC	Maximum Quiescent Supply Current	8.0	μА	$V_{IN} = V_{CC}$ or GND $V_{CC} = 5.5V$, $T_A = 25^{\circ}C$
ICCT	Maximum Additional I _{CC} /Input	1.5	mA	$V_{IN} = V_{CC} - 2.1V$ $V_{CC} = 5.5V$, $T_A = Worst Case$

AC OPERATING REQUIREMENTS

			T _A = 25°C C _L = 50 pF			0 to +85°C : 50 pF	
Symbol	Parameter	V _{CC} (V)	Min	Max	Min	Max	Unit
tw	CLK Pulse Width (HIGH to LOW)	5.0	3.0		3.0		ns

CAPACITANCE

Symbol	Parameter	Тур	Unit	Condition
C _{IN}	Input Capacitance	4.5	pF	V _{CC} = 5.0V
C _{PD}	Power Dissipation Capacitance	30	pF	V _{CC} = 5.0V

MOTOROLA 2

DC CHARACTERISTICS

			T _A = +25°C		T _A = −40 to +85°C		
Symbol	Parameter	VCC	Тур	Gua	aranteed Max	Unit	Conditions
VIH	Minimum High Level Input Voltage	4.5 5.5	1.5 1.5	2.0 2.0	2.0 2.0	V	V _{OUT} = 0.1V or V _{CC} - 0.1V
V _{IL}	Maximum Low Level Input Voltage	4.5 5.5	1.5 1.5	0.8 0.8	0.8 0.8	V	V _{OUT} = 0.1V or V _{CC} - 0.1V
VOH	Minimum High Level	4.5 5.5	4.49 5.49	4.4 5.4	4.4 5.4	V	I _{OUT} = -50μA
		4.5 5.5		3.86 4.86	3.76 4.76	V	* VIN = VIL or VIH IOH = -24 mA -24mA
VOL	Maximum Low Level Output Voltage	4.5 5.5	0.001 0.001	0.1 0.1	0.1 0.1	V	I _{OUT} = 50μA
		4.5 5.5		0.36 0.36	0.44 0.44	V	*VIN = VIL or VIH IOH = 24mA 24mA
I _{IN}	Maximum Input	5.5		±0.1	±0.1	μΑ	V _I = V _{CC} , GND
^I CCT	Maximum I _{CC} /Input	5.5	0.6		1.5	mA	$V_I = V_{CC} - 2.1V$
lold	Minimum Dynamic Output Current**	5.5			75	mA	V _{OLD} = 1.65V
IOHD		5.5			-75	mA	V _{OHD} = 3.85V

All outputs loaded; thresholds on inputs associated with output under test. Maximum test duration 20ms, one output at a time.

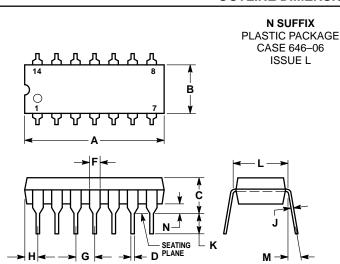
AC CHARACTERISTICS ($V_{CC} = 5.0V \pm 10\%$)

			T _A = 25°C C _L = 50 pF		T _A = -40 C _L =	0 to +85°C : 50 pF		
Symbol	Parameter	V _{CC} (V)	Min	Max	Min	Max	Unit	
f _{MAX}	Maximum Clock Frequency (50% Duty Cycle)	5.0	110		110		MHz	
tPLH, tPHL	Propagation <u>Delay</u> CLK to Q _n , Q _n	5.0	4.0	10.5	4.0	11.5	ns	
tpV	Propagation Delay Variation CLK to Q ₀ , Q ₁ , Q ₂ (see Note 1)	5.0		4.0		5.0	ns	
	Propagation Delay Variation CLK to All Outputs (see Note 1)	5.0		4.5		5.5	ns	
tps	Propagation Delay Skew (Q ₀ , Q ₁ , Q ₂) tp _{HL} Actual - tp _{LH} Actual	5.0		1.0		1.0	ns	
	Propagation Delay Skew (All Outputs) tp _{HL} Actual - tp _{LH} Actual	5.0		1.5		1.5	ns	
tos	Output–to–Output Skew (Q $_0$, Q $_1$, Q $_2$) t $_p$ Q $_n$ - t $_p$ Q $_m$ (see Note 2)	5.0		1.0		1.0	ns	
	Output-to-Output Skew (All Outputs) tp Qn - tp Qm (see Note 2)	5.0		1.5		1.5	ns	
^t rise ^t fall	Rise/Fall Time for Q ₀ , Q ₁ , Q ₂ (0.2 x V _{CC} to 0.8 x V _{CC})	5.0		3.0		4.0	ns	
	Rise/Fall Time for All Outputs (0.2 x V _{CC} to 0.8 x V _{CC})	5.0		3.5		4.5	ns	

For a given set of conditions (i.e., capacitive load, temperature and V_{CC}) the variation from device to device is guaranteed to be less than or equal to the maximum.
 Where t_p Q_n and t_p Q_m are the actual propagation delays (any combination of HIGH or LOW) for any two separate outputs from a given high transition of CLK.

3 MOTOROLA

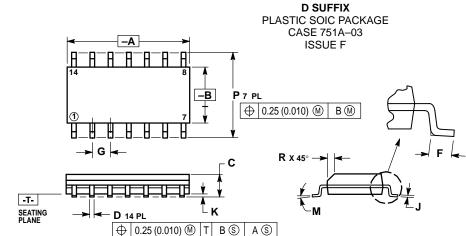
OUTLINE DIMENSIONS



NOTES:

- LEADS WITHIN 0.13 (0.005) RADIUS OF TRUE POSITION AT SEATING PLANE AT MAXIMUM MATERIAL CONDITION.
 DIMENSION L TO CENTER OF LEADS WHEN
- FORMED PARALLEL.
- 3. DIMENSION B DOES NOT INCLUDE MOLD
- FLASH.
 4. ROUNDED CORNERS OPTIONAL.

	INC	HES	MILLIMETER		
DIM	MIN	MAX	MIN	MAX	
Α	0.715	0.770	18.16	19.56	
В	0.240	0.260	6.10	6.60	
С	0.145	0.185	3.69	4.69	
D	0.015	0.021	0.38	0.53	
F	0.040	0.070	1.02	1.78	
G	0.100	BSC	2.54	BSC	
Н	0.052	0.095	1.32	2.41	
J	0.008	0.015	0.20	0.38	
K	0.115	0.135	2.92	3.43	
L	0.300	BSC	7.62 BSC		
M	0°	10°	0°	10°	
N	0.015	0.039	0.39	1.01	



NOTES:

- DIMENSIONING AND TOLERANCING PER ANSI
 Y14 5M 1982
- Y14.5M, 1982.
 2. CONTROLLING DIMENSION: MILLIMETER.
- DIMENSIONS A AND B DO NOT INCLUDE MOLD PROTRUSION.
- 4. MAXIMUM MOLD PROTRUSION 0.15 (0.006)
- PER SIDE.

 5. DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR DROTRUSION. HALLOWABLE DAMBAR DROTRUSION.
- PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127 (0.005) TOTAL IN EXCESS OF THE D DIMENSION AT MAXIMUM MATERIAL CONDITION.

	MILLIMETERS		INC	HES
DIM	MIN	MAX	MIN	MAX
Α	8.55	8.75	0.337	0.344
В	3.80	4.00	0.150	0.157
С	1.35	1.75	0.054	0.068
D	0.35	0.49	0.014	0.019
F	0.40	1.25	0.016	0.049
G	1.27	BSC	0.050	BSC
J	0.19	0.25	0.008	0.009
K	0.10	0.25	0.004	0.009
M	0°	7°	0°	7°
Р	5.80	6.20	0.228	0.244
R	0.25	0.50	0.010	0.019

Motorola reserves the right to make changes without further notice to any products herein. Motorola makes no warranty, representation or guarantee regarding the suitability of its products for any particular purpose, nor does Motorola assume any liability arising out of the application or use of any product or circuit, and specifically disclaims any and all liability, including without limitation consequential or incidental damages. "Typical" parameters can and do vary in different applications. All operating parameters, including "Typicals" must be validated for each customer application by customer's technical experts. Motorola does not convey any license under its patent rights nor the rights of others. Motorola products are not designed, intended, or authorized for use as components in systems intended for surgical implant into the body, or other applications intended to support or sustain life, or for any other application in which the failure of the Motorola product could create a situation where personal injury or death may occur. Should Buyer purchase or use Motorola products for any such unintended or unauthorized application, Buyer shall indemnify and hold Motorola and its officers, employees, subsidiaries, affiliates, and distributors harmless against all claims, costs, damages, and expenses, and reasonable attorney fees arising out of, directly or indirectly, any claim of personal injury or death associated with such unintended or unauthorized use, even if such claim alleges that Motorola was negligent regarding the design or manufacture of the part. Motorola and

How to reach us:

USA/EUROPE: Motorola Literature Distribution; P.O. Box 20912; Phoenix, Arizona 85036. 1–800–441–2447

MFAX: RMFAX0@email.sps.mot.com –TOUCHTONE (602) 244–6609 INTERNET: http://Design-NET.com

JAPAN: Nippon Motorola Ltd.; Tatsumi-SPD-JLDC, Toshikatsu Otsuki, 6F Seibu-Butsuryu-Center, 3–14–2 Tatsumi Koto-Ku, Tokyo 135, Japan. 03–3521–8315

HONG KONG: Motorola Semiconductors H.K. Ltd.; 8B Tai Ping Industrial Park, 51 Ting Kok Road, Tai Po, N.T., Hong Kong. 852–26629298



MC88913/D