68030/040 PECL to TTL Clock Driver

The MC10H/100H640 generates the necessary clocks for the 68030, 68040 and similar microprocessors. It is guaranteed to meet the clock specifications required by the 68030 and 68040 in terms of part–to–part skew, within–part skew and also duty cycle skew.

The user has a choice of using either TTL or PECL (ECL referenced to +5.0V) for the input clock. TTL clocks are typically used in present MPU systems. However, as clock speeds increase to 50MHz and beyond, the inherent superiority of ECL (particularly differential ECL) as a means of clock signal distribution becomes increasingly evident. The H640 also uses differential PECL internally to achieve its superior skew characteristic.

The H640 includes divide–by–two and divide–by–four stages, both to achieve the necessary duty cycle skew and to generate MPU clocks as required. A typical 50MHz processor application would use an input clock running at 100MHz, thus obtaining output clocks at 50MHz and 25MHz (see Logic Diagram).

The 10H version is compatible with MECL $10H^{TM}$ ECL logic levels, while the 100H version is compatible with 100K levels (referenced to +5.0V).

- Generates Clocks for 68030/040
- Meets 030/040 Skew Requirements
- TTL or PECL Input Clock
- Extra TTL and PECL Power/Ground Pins
- Asynchronous Reset
- Single +5.0V Supply

Function

Reset (R): LOW on RESET forces all Q outputs LOW and all \overline{Q} outputs HIGH.

Power–Up: The device is designed to have the POS edges of the $\div 2$ and $\div 4$ outputs synchronized at power up.

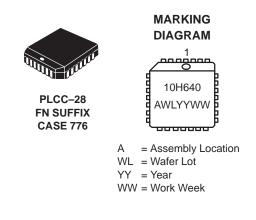
Select (SEL): LOW selects the ECL input source (DE/\overline{DE}). HIGH selects the TTL input source (DT).

The H640 also contains circuitry to force a stable state of the ECL input differential pair, should both sides be left open. In this case, the DE side of the input is pulled LOW, and \overline{DE} goes HIGH.



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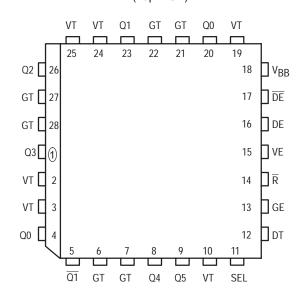


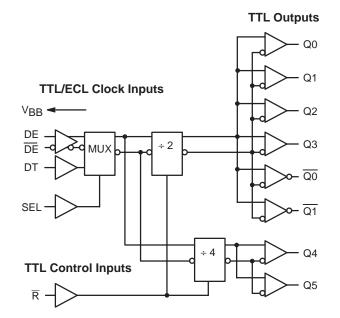
ORDERING INFORMATION

Device	Shipping	
MC10H640FN	PLCC-28	37 Units/Rail
MC100H640FN	PLCC-28	37 Units/Rail

Pinout: 28–Lead PLCC (Top View)

LOGIC DIAGRAM





PIN NAMES

PIN	FUNCTION
GT	TTL Ground (0 V)
VT	TTL V _{CC} (+5.0 V)
VE	ECL V _{CC} (+5.0 V)
GE	ECL Ground (0 V)
DE, DE	ECL Signal Input (positive ECL)
	V _{BB} Reference Output TTL Signal Input
Qn, Qn	Signal Outputs (TTL)
SEL	Input Select (TTL)
R	Reset (TTL)

AC CHARACTERISTICS (VT = VE = $5.0V \pm 5\%$)

			0	°C	25	o.c	85°C			
Symbol	Characteristic	•	Min	Max	Min	Max	Min	Max	Unit	Condition
^t PLH	Propagation Delay ECL D to Output	Q0–Q3	4.9	5.9	4.9	5.9	5.2	6.2	ns	CL = 25pF
^t PLH	Propagation Delay TTL D to Output	1	5.0	6.0	5.0	6.0	5.3	6.3	ns	CL = 25pF
tskwd*	Within-Device Skew	1		0.5		0.5		0.5	ns	CL = 25pF
^t PLH	Propagation Delay ECL D to Output	<u>Q0</u> , <u>Q1</u>	4.9	5.9	4.9	5.9	5.2	6.2	ns	CL = 25pF
^t PLH	Propagation Delay TTL D to Output		5.0	6.0	5.0	6.0	5.3	6.3	ns	CL = 25pF
^t PLH	Propagation Delay ECL D to Output	Q4, Q5	4.9	5.9	4.9	5.9	5.2	6.2	ns	CL = 25pF
^t PLH	Propagation Delay TTL D to Output		5.0	6.0	5.0	6.0	5.3	6.3	ns	CL = 25pF
^t PD	Propagation Delay R to Output	All Outputs	4.3	6.3	4.3	6.3	5.0	7.0	ns	CL = 25pF
t _R t _F	Output Rise/Fall Time 0.8 V – 2.0 V	All Outputs		2.5 2.5		2.5 2.5		2.5 2.5	ns	CL = 25pF
f _{max}	Maximum Input Frequence	;y	135		135		135		MHz	CL = 25pF
t _{pw}	Minimum Pulse Width		1.50		1.50		1.50		ns	
t _{rr}	Reset Recovery Time		1.25		1.25		1.25		ns	

* Within–Device Skew defined as identical transitions on similar paths through a device.

$V_{\mbox{CC}}$ and \mbox{C}_L RANGES TO MEET DUTY CYCLE REQUIREMENTS

(0°C \leq TA \leq 85°C Output Duty Cycle Measured Relative to 1.5V)

Symbol	Characteristic			Nom	Мах	Unit	Condition
	Range of V _{CC} and CL to meet minimum pulse width (HIGH or LOW) = 11.5 ns at $f_{out} \leq 40 \text{ MHz}$	V _{CC} CL	4.75 10	5.0	5.25 50	V pF	$\frac{Q0-Q3}{Q0-Q1}$
	Range of V _{CC} and CL to meet minimum pulse width (HIGH or LOW) = 9.5 ns at 40 < $f_{OUt} \le 50~\text{MHz}$	V _{CC} CL	4.875 15	5.0	5.125 27	V pF	Q0–Q3

DC CHARACTERISTICS (VT = VE = $5.0 \text{ V} \pm 5\%$)

			0°C		25°C		85°C			
Symbol	Characteristic	;	Min	Max	Min	Max	Min	Max	Unit	Condition
IEE	Power Supply Current	ECL		57		57		57	mA	VE Pin
ІССН		TTL		30		30		30	mA	Total all VT pins
ICCL				30		30		30	mA	

TTL DC CHARACTERISTICS (VT = VE = $5.0 \text{ V} \pm 5\%$)

		O°C		25°C		85°C			
Symbol	Characteristic	Min	Мах	Min	Max	Min	Мах	Unit	Condition
VIH VIL	Input HIGH Voltage Input LOW Voltage	2.0	0.8	2.0	0.8	2.0	0.8	V	
Ιн	Input HIGH Current		20 100		20 100		20 100	μA	V _{IN} = 2.7V V _{IN} = 7.0V
۱ _{IL}	Input LOW Current		-0.6		-0.6		-0.6	mA	V _{IN} = 0.5V
VOH	Output HIGH Voltage	2.5 2.0		2.5 2.0		2.5 2.0		V	I _{OH} = -3.0mA I _{OH} = -15mA
VOL	Output LOW Voltage		0.5		0.5		0.5	V	I _{OL} = 24mA
VIK	Input Clamp Voltage		-1.2		-1.2		-1.2	V	I _{IN} = -18mA
IOS	Output Short Circuit Current	-100	-225	-100	-225	-100	-225	mA	V _{OUT} = 0V

10H PECL DC CHARACTERISTICS (VT = VE = $5.0 \text{ V} \pm 5\%$)

		0°C		25°C		85°C			
Symbol	Characteristic	Min	Мах	Min	Мах	Min	Max	Unit	Condition
I _{INH} I _{INL}	Input HIGH Current Input LOW Current	0.5	225	0.5	175	0.5	175	μΑ	
VIH* VIL*	Input HIGH Voltage Input LOW Voltage	3.83 3.05	4.16 3.52	3.87 3.05	4.19 3.52	3.94 3.05	4.28 3.555	V	VE = 5.0V
V _{BB} *	Output Reference Voltage	3.62	3.73	3.65	3.75	3.69	3.81	V	

*NOTE: PECL levels are referenced to V_{CC} and will vary 1:1 with the power supply. The values shown are for V_{CC} = 5.0V.

100H PECL DC CHARACTERISTICS (VT = VE = $5.0 \text{ V} \pm 5\%$)

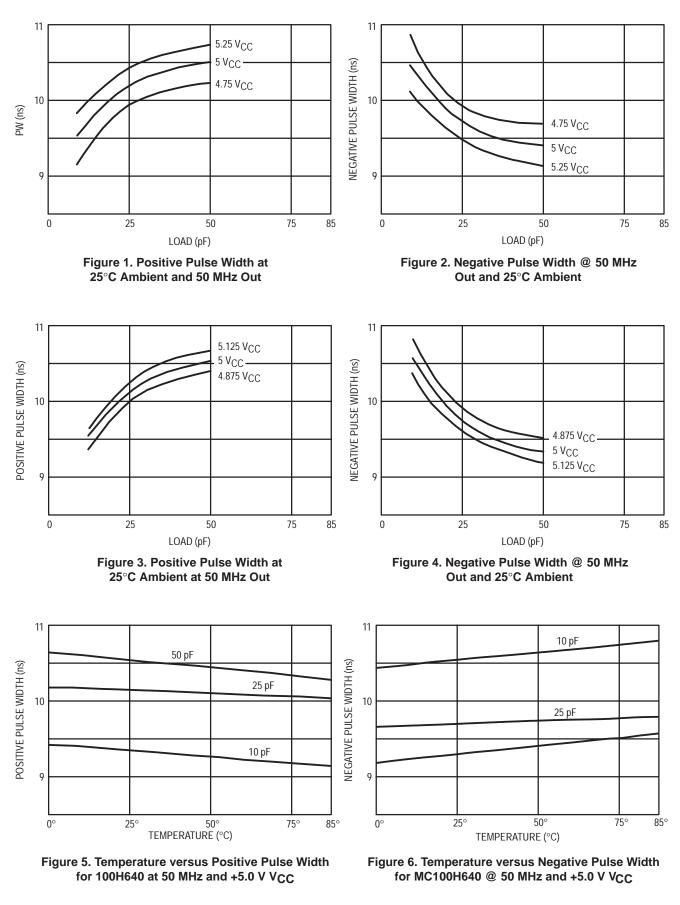
		0°C		25°C		85°C			
Symbol	Characteristic	Min	Мах	Min	Мах	Min	Мах	Unit	Condition
I _{INH} I _{INL}	Input HIGH Current Input LOW Current	0.5	225	0.5	175	0.5	175	μA	
VIH* VIL*	Input HIGH Voltage Input LOW Voltage	3.835 3.19	4.12 3.525	3.835 3.19	4.12 3.525	3.835 3.19	4.12 3.525	V	VE = 5.0V
V _{BB} *	Output Reference Voltage	3.62	3.74	3.62	3.74	3.62	3.74	V	

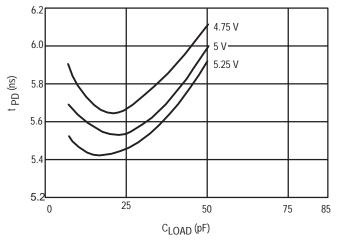
*NOTE: PECL levels are referenced to V_{CC} and will vary 1:1 with the power supply. The values shown are for V_{CC} = 5.0V.

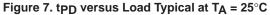
10/100H640 DUTY CYCLE CONTROL

To maintain a duty cycle of $\pm 5\%$ at 50MHz, limit the load capacitance and/or power supply variation as shown in Figures 1 and 2. For a $\pm 2.5\%$ duty cycle limit, see Figures 3 and 4. Figures 5 and 6 show duty cycle variation with temperature. Figure 7 shows typical TPD versus load. Figure 8 shows reset recovery time. Figure 9 shows output states after power up.

Best duty cycle control is obtained with a single μ P load and minimum line length.







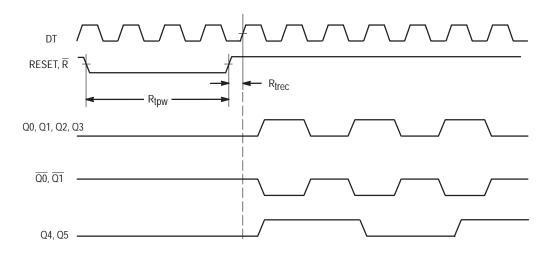
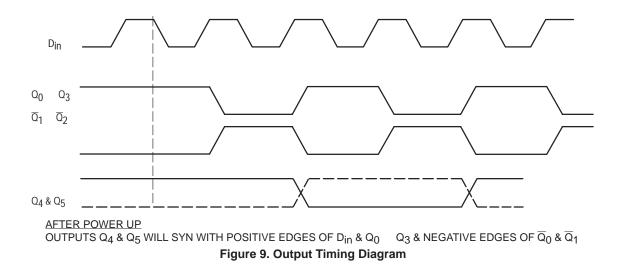
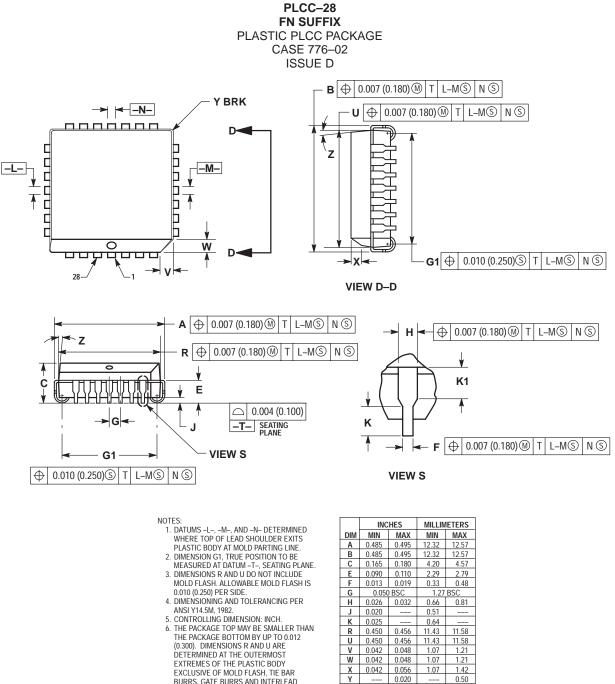


Figure 8. MC10H/100H640 Clock Phase and Reset Recovery Time After Reset Pulse



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- DETERMINED AT THE OUTERMOST EXTREMES OF THE PLASTIC BODY EXCLUSIVE OF MOLD FLASH, TIE BAR BURRS, GATE BURRS AND INTERLEAD FLASH, BUT INCLUDING ANY MISMATCH BETWEEN THE TOP AND BOTTOM OF THE PLASTIC BODY.
- 7. DIMENSION H DOES NOT INCLUDE DAMBAR PROTRUSION OR INTRUSION. THE DAMBAR PROTRUSION(S) SHALL NOT CAUSE THE H DIMENSION TO BE GREATER THAN 0.037 (0.940). THE DAMBAR INTRUSION(S) SHALL NOT CAUSE THE H DIMENSION TO BE SMALLER THAN 0.025 (0.635).

0.020

G1 0.410 0.430 10.42

20 10°

Ζ

K1 0.040

0.50

10.92

20 10°

1.02

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