NEC

MOS INTEGRATED CIRCUIT
μPD78F0034A, 78F0034AY

8-BIT SINGLE-CHIP MICROCONTROLLER

DESCRIPTION

The μPD78F0034A is a member of the μPD780034A Subseries in the 78K/0 Series, and is equivalent to the μPD780034A but with flash memory in place of internal ROM.

The μPD78F0034AY is a member of the μPD780034AY Subseries, featuring flash memory in place of the internal ROM of the μPD780034AY.

The μPD78F0034A incorporates flash memory, which can be programmed and erased while mounted on the board.

Detailed function descriptions are provided in the following user's manuals. Be sure to read them before designing.

μPD780024A, 780034A, 780024AY, 780034AY Subseries User's Manual: U14046E
78K/0 Series User's Manual Instruction: U12326E

FEATURES

- Pin-compatible with mask ROM versions (except V$_{PP}$ pin)
- Flash memory: 32 KB**Note**
- Internal high-speed RAM: 1,024 bytes**Note**
- Supply voltage: V$_{DD}$ = 1.8 to 5.5 V

Note The flash memory and internal high-speed RAM capacities can be changed with the memory size switching register (IMS).

Remark For the differences between the flash memory and the mask ROM versions, refer to **4. DIFFERENCES BETWEEN μPD78F0034A, 78F0034AY, AND MASK ROM VERSIONS**.
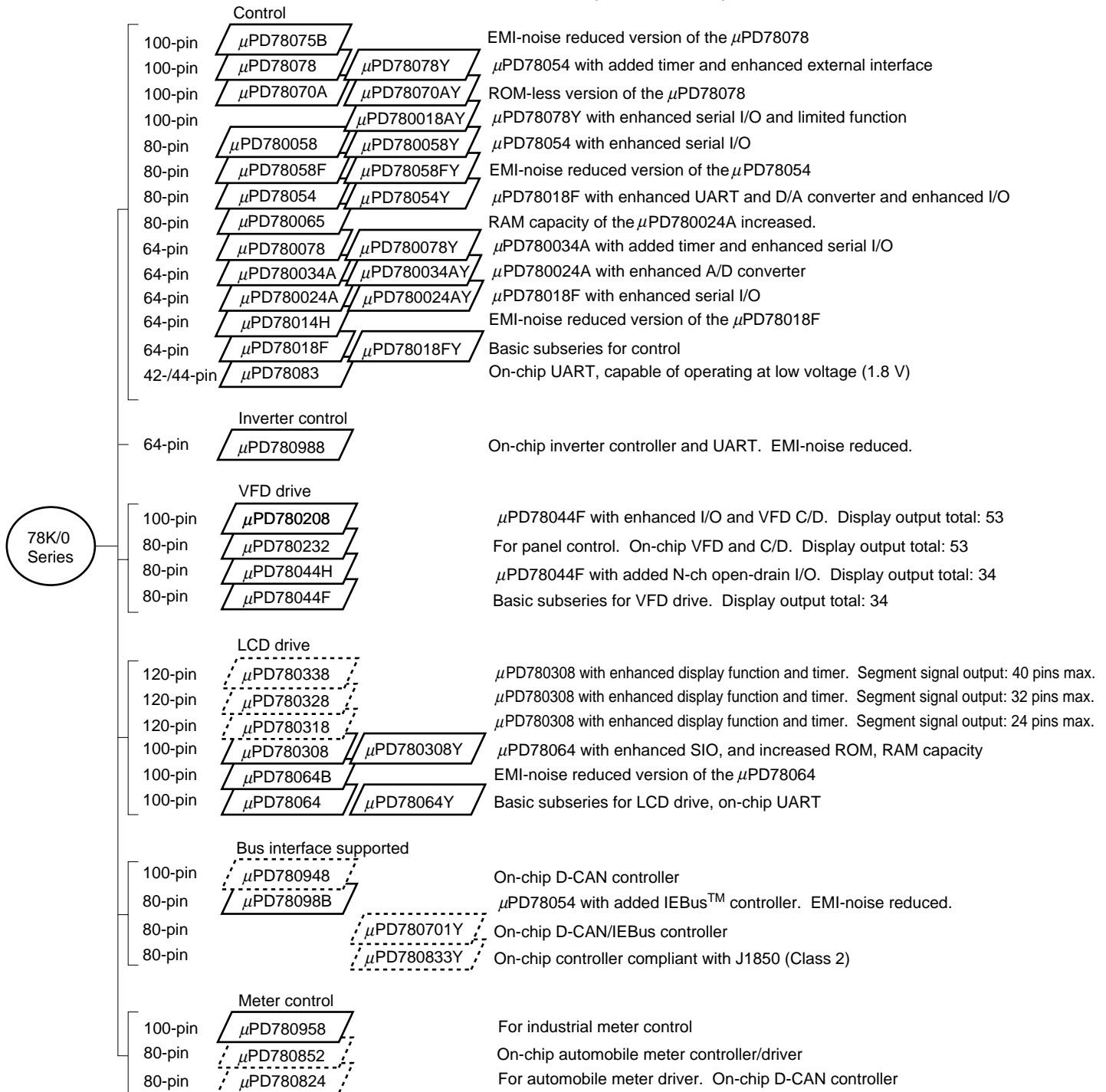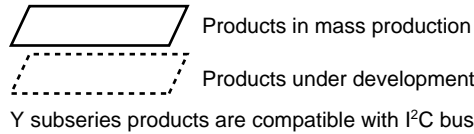
ORDERING INFORMATION

Part Number	Package	Internal ROM
μPD78F0034ACW	64-pin plastic SDIP (19.05 mm (750))	Flash memory
μPD78F0034AGC-AB8	64-pin plastic QFP (14 × 14)	Flash memory
μPD78F0034AGK-8A8	64-pin plastic LQFP (12 × 12)	Flash memory
μPD78F0034AGK-9ET	64-pin plastic TQFP (12 × 12)	Flash memory
μPD78F0034AYCW	64-pin plastic SDIP (19.05 mm (750))	Flash memory
μPD78F0034AYGC-AB8	64-pin plastic QFP (14 × 14)	Flash memory
μPD78F0034AYGK-8A8	64-pin plastic LQFP (12 × 12)	Flash memory
μPD78F0034AYGK-9ET	64-pin plastic TQFP (12 × 12)	Flash memory

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Not all devices/types available in every country. Please check with local NEC representative for availability and additional information.

78K/0 SERIES LINEUP

The products in the 78K/0 Series are listed below. The names enclosed in boxes are subseries names.

Products in mass production

Products under development

Y subseries products are compatible with I²C bus.

Control

100-pin	μPD78075B		EMI-noise reduced version of the μPD78078
100-pin	μPD78078	μPD78078Y	μPD78054 with added timer and enhanced external interface
100-pin	μPD78070A	μPD78070AY	ROM-less version of the μPD78078
100-pin		μPD780018AY	μPD78078Y with enhanced serial I/O and limited function
80-pin	μPD780058	μPD780058Y	μPD78054 with enhanced serial I/O
80-pin	μPD78058F	μPD78058FY	EMI-noise reduced version of the μPD78054
80-pin	μPD78054	μPD78054Y	μPD78018F with enhanced UART and D/A converter and enhanced I/O
80-pin	μPD780065		RAM capacity of the μPD780024A increased.
64-pin	μPD780078	μPD780078Y	μPD780034A with added timer and enhanced serial I/O
64-pin	μPD780034A	μPD780034AY	μPD780024A with enhanced A/D converter
64-pin	μPD780024A	μPD780024AY	μPD78018F with enhanced serial I/O
64-pin	μPD78014H		EMI-noise reduced version of the μPD78018F
64-pin	μPD78018F	μPD78018FY	Basic subseries for control
42-/44-pin	μPD78083		On-chip UART, capable of operating at low voltage (1.8 V)

Inverter control

64-pin	μPD780988	On-chip inverter controller and UART. EMI-noise reduced.

VFD drive

100-pin	μPD780208	μPD78044F with enhanced I/O and VFD C/D. Display output total: 53
80-pin	μPD780232	For panel control. On-chip VFD and C/D. Display output total: 53
80-pin	μPD78044H	μPD78044F with added N-ch open-drain I/O. Display output total: 34
80-pin	μPD78044F	Basic subseries for VFD drive. Display output total: 34

LCD drive

120-pin	μPD780338		μPD780308 with enhanced display function and timer. Segment signal output: 40 pins max.
120-pin	μPD780328		μPD780308 with enhanced display function and timer. Segment signal output: 32 pins max.
120-pin	μPD780318		μPD780308 with enhanced display function and timer. Segment signal output: 24 pins max.
100-pin	μPD780308	μPD780308Y	μPD78064 with enhanced SIO, and increased ROM, RAM capacity
100-pin	μPD78064B		EMI-noise reduced version of the μPD78064
100-pin	μPD78064	μPD78064Y	Basic subseries for LCD drive, on-chip UART

Bus interface supported

100-pin	μPD780948		On-chip D-CAN controller
80-pin	μPD78098B		μPD78054 with added IEBus™ controller. EMI-noise reduced.
80-pin		μPD780701Y	On-chip D-CAN/IEBus controller
80-pin		μPD780833Y	On-chip controller compliant with J1850 (Class 2)

Meter control

100-pin	μPD780958	For industrial meter control
80-pin	μPD780852	On-chip automobile meter controller/driver
80-pin	μPD780824	For automobile meter driver. On-chip D-CAN controller

78K/0
Series

Remark VFD (Vacuum Fluorescent Display) is referred to as FIP™ (Fluorescent Indicator Panel) in some documents, but the functions of the two are the same.

The major functional differences among the subseries are shown below.

- **Non Y subseries**

Function	Subseries Name	ROM Capacity	8-Bit	16-Bit	Watch	WDT	8-Bit A/D	10-Bit A/D	8-Bit D/A	Serial Interface	I/O	V_{DD} MIN. Value	External Expansion
Control	μPD78075B	32 K to 40 K	4 ch	1 ch	1 ch	1 ch	8 ch	–	2 ch	3 ch (UART: 1 ch)	88	1.8 V	√
	μPD78078	48 K to 60 K											
	μPD78070A	–									61	2.7 V	
	μPD780058	24 K to 60 K	2 ch							3 ch (time-division UART: 1 ch)	68	1.8 V	
	μPD78058F	48 K to 60 K								3 ch (UART: 1 ch)	69	2.7 V	
	μPD78054	16 K to 60 K										2.0 V	
	μPD780065	40 K to 48 K							–	4 ch (UART: 1 ch)	60	2.7 V	
	μPD780078	48 K to 60 K		2 ch			–	8 ch		3 ch (UART: 2 ch)	52	1.8 V	
	μPD780034A	8 K to 32 K		1 ch						3 ch (UART: 1 ch)	51		
	μPD780024A						8 ch	–					
	μPD78014H									2 ch	53		
	μPD78018F	8 K to 60 K											
	μPD78083	8 K to 16 K		–	–					1 ch (UART: 1 ch)	33		–
Inverter control	μPD780988	16 K to 60 K	3 ch	**Note**	–	1 ch	–	8 ch	–	3 ch (UART: 2 ch)	47	4.0 V	√
VFD drive	μPD780208	32 K to 60 K	2 ch	1 ch	1 ch	1 ch	8 ch	–	–	2 ch	74	2.7 V	–
	μPD780232	16 K to 24 K	3 ch	–	–		4 ch				40	4.5 V	
	μPD78044H	32 K to 48 K	2 ch	1 ch	1 ch		8 ch			1 ch	68	2.7 V	
	μPD78044F	16 K to 40 K								2 ch			
LCD drive	μPD780338	48 K to 60 K	3 ch	2 ch	1 ch	1 ch	–	10 ch	1 ch	2 ch (UART: 1 ch)	54	1.8 V	–
	μPD780328										62		
	μPD780318										70		
	μPD780308	48 K to 60 K	2 ch	1 ch			8 ch	–	–	3 ch (time-division UART: 1 ch)	57	2.0 V	
	μPD78064B	32 K								2 ch (UART: 1 ch)			
	μPD78064	16 K to 32 K											
Bus interface supported	μPD780948	60 K	2 ch	2 ch	1 ch	1 ch	8 ch	–	–	3 ch (UART: 1 ch)	79	4.0 V	√
	μPD78098B	40 K to 60 K		1 ch				2 ch			69	2.7 V	–
Meter control	μPD780958	48 K to 60 K	4 ch	2 ch	–	1 ch	–	–	–	2 ch (UART: 1 ch)	69	2.2 V	–
Dash board control	μPD780852	32 K to 40 K	3 ch	1 ch	1 ch	1 ch	5 ch	–	–	3 ch (UART: 1 ch)	56	4.0 V	–
	μPD780824	32 K to 60 K								2 ch (UART: 1 ch)	59		

Note 16-bit timer: 2 channels
         10-bit timer: 1 channel

• **Y subseries**

Function / Subseries Name		ROM Capacity	Timer				8-Bit A/D	10-Bit A/D	8-Bit D/A	Serial Interface	I/O	V_{DD} MIN. Value	External Expansion
			8-Bit	16-Bit	Watch	WDT							
Control	μPD78078Y	48 K to 60 K	4 ch	1 ch	1 ch	1 ch	8 ch	–	2 ch	3 ch (UART: 1 ch, I^2C: 1 ch)	88	1.8 V	√
	μPD78070AY	–									61	2.7 V	
	μPD780018AY	48 K to 60 K							–	3 ch (I^2C: 1 ch)	88		
	μPD780058Y	24 K to 60 K	2 ch						2 ch	3 ch (time division UART: 1 ch, I^2C: 1 ch)	68	1.8 V	
	μPD78058FY	48 K to 60 K								3 ch (UART: 1 ch, I^2C: 1 ch)	69	2.7 V	
	μPD78054Y	16 K to 60 K										2.0 V	
	μPD780078Y	48 K to 60 K		2 ch			–	8 ch	–	4 ch (UART: 2 ch, I^2C: 1 ch)	52	1.8 V	
	μPD780034AY	8 K to 32 K		1 ch						3 ch (UART: 1 ch, I^2C: 1 ch)	51		
	μPD780024AY						8 ch	–					
	μPD78018FY	8 K to 60 K								2 ch (I^2C: 1 ch)	53		
LCD drive	μPD780308Y	48 K to 60 K	2 ch	1 ch	1 ch	1 ch	8 ch	–	–	3 ch (time division UART: 1 ch, I^2C: 1 ch)	57	2.0 V	–
	μPD78064Y	16 K to 32 K								2 ch (UART: 1 ch, I^2C: 1 ch)			
For bus interface	μPD780701Y	60 K	3 ch	2 ch	1 ch	1 ch	16 ch	–	–	4 ch (UART: 1 ch, I^2C: 1 ch)	67	3.5 V	–
	μPD780833Y										65	4.5 V	

Remark The functions of non Y subseries and Y subseries products are the same, except for the serial interface.

OVERVIEW OF FUNCTIONS

Part Number / Item		μPD78F0034A	μPD78F0034AY
Internal memory	Flash memory	32 KB**Note**	
	High-speed RAM	1,024 bytes**Note**	
Memory space		64 KB	
General-purpose registers		8 bits × 32 registers (8 bits × 8 registers × 4 banks)	
Minimum instruction execution time		On-chip minimum instruction execution time cycle variable function	
	When main system clock selected	0.24 μs/0.48 μs/0.95 μs/1.91 μs/3.81 μs (@ 8.38 MHz operation)	
	When subsystem clock selected	122 μs (@ 32.768 kHz operation)	
Instruction set		• 16-bit operation, multiply/divide (8 bits × 8 bits, 16 bits ÷ 8 bits) • Bit manipulation (set, reset, test, Boolean operation) • BCD adjust, etc.	
I/O ports		Total: 51 • CMOS input: 8 • CMOS I/O: 39 • N-ch open-drain I/O (5 V withstand voltage): 4	
A/D converter		• 10-bit resolution × 8 channels • Operable over a wide power supply voltage range: AV_{DD} = 1.8 to 5.5 V	
Serial interface		• UART mode: 1 channel • 3-wire serial I/O mode: 2 channels	• UART mode: 1 channel • 3-wire serial I/O mode: 1 channel • I^{2}C bus mode (multimaster supporting): 1 channel
Timers		• 16-bit timer/event counter: 1 channel • 8-bit timer/event counter: 2 channels • Watch timer: 1 channel • Watchdog timer: 1 channel	
Timer outputs		3 (8-bit PWM output capable: 2)	
Clock output		65.5 kHz, 131 kHz, 262 kHz, 524 kHz, 1.05 MHz, 2.10 MHz, 4.19 MHz, 8.38 MHz (@ 8.38 MHz operation with main system clock) 32.768 kHz (@ 32.768 kHz operation with subsystem clock)	
Buzzer output		1.02 kHz, 2.05 kHz, 4.10 kHz, 8.19 kHz (@ 8.38 MHz operation with main system clock)	
Vectored interrupt sources	Maskable	Internal: 13, external: 5	
	Non-maskable	Internal: 1	
	Software	1	
Test inputs		Internal: 1, external: 1	
Supply voltage		V_{DD} = 1.8 to 5.5 V	
Operating ambient temperature		T_A = −40 to +85°C	
Package		• 64-pin plastic SDIP (19.05 mm (750)) • 64-pin plastic QFP (14 × 14) • 64-pin plastic LQFP (12 × 12) • 64-pin plastic TQFP (12 × 12)	

Note The capacities of the flash memory and the internal high-speed RAM can be changed with the memory size switching register (IMS).

CONTENTS

1. PIN CONFIGURATION (TOP VIEW)

- **64-pin plastic SDIP (19.05 mm (750))**
  μ**PD78F0034ACW, 78F0034AYCW**

P40/AD0	1		64	P67/ASTB
P41/AD1	2		63	P66/$\overline{\text{WAIT}}$
P42/AD2	3		62	P65/$\overline{\text{WR}}$
P43/AD3	4		61	P64/$\overline{\text{RD}}$
P44/AD4	5		60	P75/BUZ
P45/AD5	6		59	P74/PCL
P46/AD6	7		58	P73/TI51/TO51
P47/AD7	8		57	P72/TI50/TO50
P50/A8	9		56	P71/TI01
P51/A9	10		55	P70/TI00/TO0
P52/A10	11		54	P03/INTP3/ADTRG
P53/A11	12		53	P02/INTP2
P54/A12	13		52	P01/INTP1
P55/A13	14		51	P00/INTP0
P56/A14	15		50	V_{SS1}
P57/A15	16		49	X1
V_{SS0}	17		48	X2
V_{DD0}	18		47	V_{PP}
P30	19		46	XT1
P31	20		45	XT2
P32/SDA0[Note 1]	21		44	$\overline{\text{RESET}}$
P33/SCL0[Note 1]	22		43	AV_{DD}
P34/SI31[Note 2]	23		42	AV_{REF}
P35/SO31[Note 2]	24		41	P10/ANI0
P36/SCK31[Note 2]	25		40	P11/ANI1
P20/SI30	26		39	P12/ANI2
P21/SO30	27		38	P13/ANI3
P22/$\overline{\text{SCK30}}$	28		37	P14/ANI4
P23/RxD0	29		36	P15/ANI5
P24/TxD0	30		35	P16/ANI6
P25/ASCK0	31		34	P17/ANI7
V_{DD1}	32		33	AV_{SS}

Notes 1. SDA0 and SCL0 are incorporated only in the μPD78F0034AY Subseries.

2. SI31, SO31, and $\overline{\text{SCK31}}$ are incorporated only in the μPD78F0034A Subseries.

Cautions 1. Connect the V$_{PP}$ pin directly to V$_{SS0}$ or V$_{SS1}$ in normal operation mode.

2. Connect the AV$_{SS}$ pin to V$_{SS0}$.

Remark When the μPD78F0034A and 78F0034AY are used in application fields that require reduction of the noise generated from inside the microcontroller, the implementation of noise reduction measures, such as supplying voltage to V$_{DD0}$ and V$_{DD1}$ individually and connecting V$_{SS0}$ and V$_{SS1}$ to different ground lines, is recommended.

- **64-pin plastic QFP (14 × 14)**
  μ**PD78F0034AGC-AB8, 78F0034AYGC-AB8**
- **64-pin plastic LQFP (12 × 12)**
  μ**PD78F0034AGK-8A8, 78F0034AYGK-8A8**
- **64-pin plastic TQFP (12 × 12)**
  μ**PD78F0034AYGK-9ET, 78F0034AYGK-9ET**

Pin configuration (top view):

Top pins (64 to 49): P47/AD7, P46/AD6, P45/AD5, P44/AD4, P43/AD3, P42/AD2, P41/AD1, P40/AD0, P67/ASTB, P66/$\overline{\text{WAIT}}$, P65/$\overline{\text{WR}}$, P64/$\overline{\text{RD}}$, P75/BUZ, P74/PCL, P73/TI51/TO51, P72/TI50/TO50

Left pins (1 to 16):
Pin	Signal
1	P50/A8
2	P51/A9
3	P52/A10
4	P53/A11
5	P54/A12
6	P55/A13
7	P56/A14
8	P57/A15
9	V$_{SS0}$
10	V$_{DD0}$
11	P30
12	P31
13	P32/SDA0[Note 1]
14	P33/SCL0[Note 1]
15	P34/SI31[Note 2]
16	P35/SO31[Note 2]

Right pins (48 to 33):
Pin	Signal
48	P71/TI01
47	P70/TI00/TO0
46	P03/INTP3/ADTRG
45	P02/INTP2
44	P01/INTP1
43	P00/INTP0
42	V$_{SS1}$
41	X1
40	X2
39	V$_{PP}$
38	XT1
37	XT2
36	$\overline{\text{RESET}}$
35	AV$_{DD}$
34	AV$_{REF}$
33	P10/ANI0

Bottom pins (17 to 32): P36/$\overline{\text{SCK31}}$[Note 2], P20/SI30, P21/SO30, P22/$\overline{\text{SCK30}}$, P23/RxD0, P24/TxD0, P25/ASCK0, V$_{DD1}$, AV$_{SS}$, P17/ANI7, P16/ANI6, P15/ANI5, P14/ANI4, P13/ANI3, P12/ANI2, P11/ANI1

Notes 1. SDA0 and SCL0 are incorporated only in the μPD78F0034AY Subseries.

    2. SI31, SO31, and $\overline{\text{SCK31}}$ are incorporated only in the μPD78F0034A Subseries.

Cautions 1. Connect the V$_{PP}$ pin directly to V$_{SS0}$ or V$_{SS1}$ in normal operation mode.

    2. Connect the AV$_{SS}$ pin to V$_{SS0}$.

Remark When the μPD78F0034A and 78F0034AY are used in application fields that require reduction of the noise generated from inside the microcontroller, the implementation of noise reduction measures, such as supplying voltage to V$_{DD0}$ and V$_{DD1}$ individually and connecting V$_{SS0}$ and V$_{SS1}$ to different ground lines, is recommended.

A8 to A15:	Address Bus	P70 to P75:	Port 7
AD0 to AD7:	Address/Data Bus	PCL:	Programmable Clock
ADTRG:	AD Trigger Input	$\overline{RD}$:	Read Strobe
ANI0 to ANI7:	Analog Input	$\overline{RESET}$:	Reset
ASCK0:	Asynchronous Serial Clock	RxD0:	Receive Data
ASTB:	Address Strobe	$\overline{SCK30}$, $\overline{SCK31}$, SCL0:	Serial Clock
AV$_{DD}$:	Analog Power Supply	SDA0:	Serial Data
AV$_{REF}$:	Analog Reference Voltage	SI30, SI31:	Serial Input
AV$_{SS}$:	Analog Ground	SO30, SO31:	Serial Output
BUZ:	Buzzer Clock	TI00, TI01, TI50, TI51:	Timer Input
INTP0 to INTP3:	External Interrupt Input	TO0, TO50, TO51:	Timer Output
P00 to P03:	Port 0	TxD0:	Transmit Data
P10 to P17:	Port 1	V$_{DD0}$, V$_{DD1}$:	Power Supply
P20 to P25:	Port 2	V$_{PP}$:	Programming Power Supply
P30 to P36:	Port 3	V$_{SS0}$, V$_{SS1}$:	Ground
P40 to P47:	Port 4	$\overline{WAIT}$:	Wait
P50 to P57:	Port 5	$\overline{WR}$:	Write Strobe
P64 to P67:	Port 6	X1, X2:	Crystal (Main System Clock)
		XT1, XT2:	Crystal (Subsystem Clock)

2. BLOCK DIAGRAM
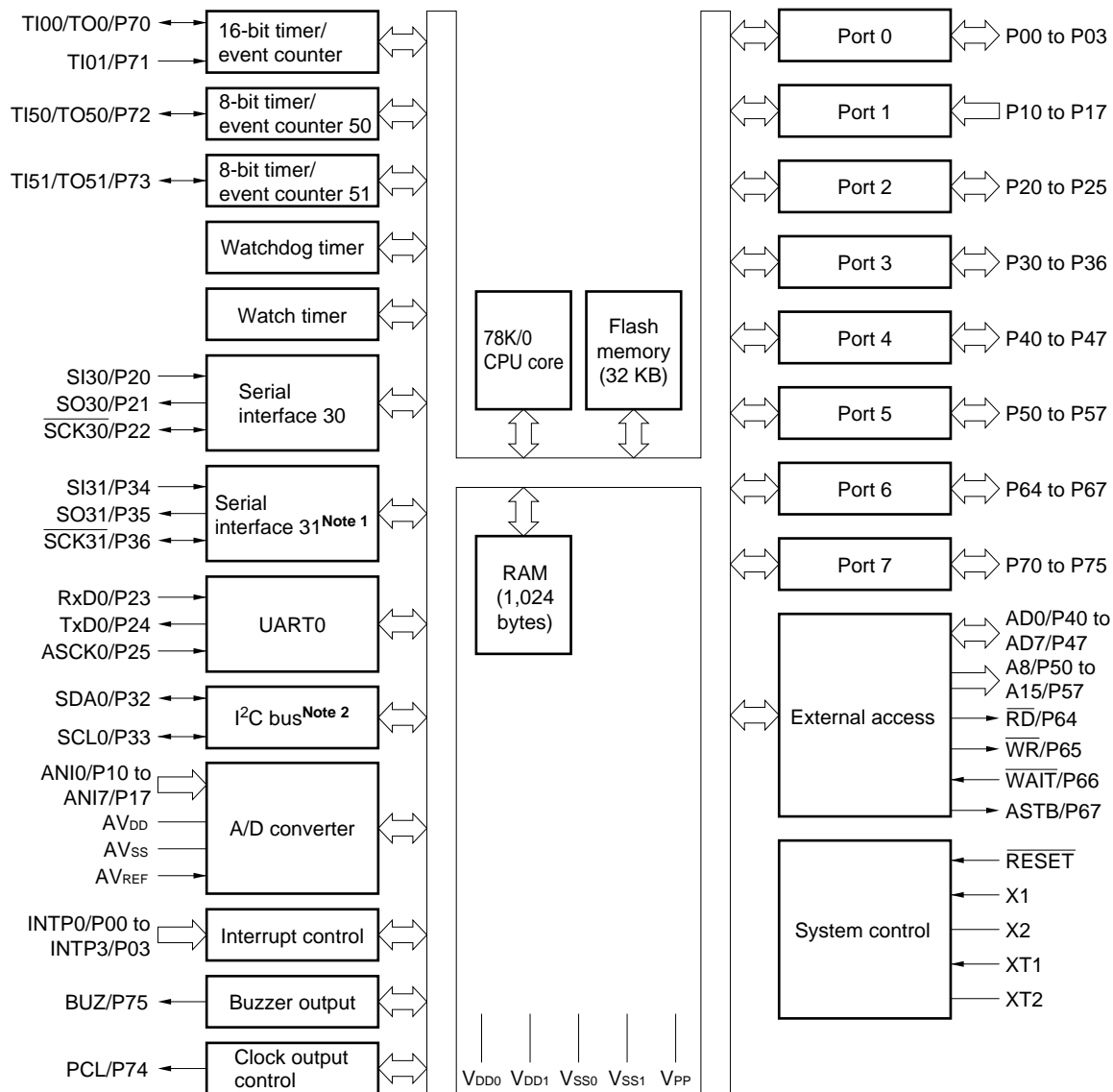
Notes 1. Incorporated only in the μPD78F0034A

2. Incorporated only in the μPD78F0034AY

3. PIN FUNCTIONS

3.1 Port Pins (1/2)

| Pin Name	I/O	Function		After Reset	Alternate Function
P00	I/O	Port 0 4-bit I/O port. Input/output can be specified in 1-bit units. An on-chip pull-up resistor can be specified by means of software.		Input	INTP0
P01					INTP1
P02					INTP2
P03					INTP3/ADTRG
P10 to P17	Input	Port 1 8-bit input-only port.		Input	ANI0 to ANI7
P20	I/O	Port 2 6-bit I/O port. Input/output can be specified in 1-bit units. An on-chip pull-up resistor can be specified by means of software.		Input	SI30
P21					SO30
P22					$\overline{\text{SCK30}}$
P23					RxD0
P24					TxD0
P25					ASCK0
P30	I/O	Port 3 7-bit I/O port. Input/output can be specified in 1-bit units.	N-ch open-drain I/O port. LEDs can be driven directly.	Input	–
P31					
P32					SDA0[Note 1]
P33					SCL0[Note 1]
P34			An on-chip pull-up resistor can be specified by means of software.		SI31[Note 2]
P35					SO31[Note 2]
P36					$\overline{\text{SCK31}}$[Note 2]
P40 to P47	I/O	Port 4 8-bit I/O port. Input/output can be specified in 1-bit units. An on-chip pull-up resistor can be specified by means of software. Interrupt request flag KRIF is set to 1 by falling edge detection.		Input	AD0 to AD7
P50 to P57	I/O	Port 5 8-bit I/O port. LEDs can be driven directly. Input/output can be specified in 1-bit units. An on-chip pull-up resistor can be specified by means of software.		Input	A8 to A15
P64	I/O	Port 6 4-bit I/O port. Input/output can be specified in 1-bit units. An on-chip pull-up resistor can be specified by means of software.		Input	$\overline{\text{RD}}$
P65					$\overline{\text{WR}}$
P66					$\overline{\text{WAIT}}$
P67					ASTB

Notes 1. SDA0 and SCL0 are incorporated only in the μPD78F0034AY Subseries.
2. SI31, SO31, and $\overline{\text{SCK31}}$ are incorporated only in the μPD78F0034A Subseries.

3.1 Port Pins (2/2)

Pin Name	I/O	Function	After Reset	Alternate Function
P70	I/O	Port 7 6-bit I/O port. Input/output can be specified in 1-bit units. An on-chip pull-up resistor can be specified by means of software.	Input	TI00/TO0
P71				TI01
P72				TI50/TO50
P73				TI51/TO51
P74				PCL
P75				BUZ

3.2 Non-Port Pins (1/2)

Pin Name	I/O	Function	After Reset	Alternate Function
INTP0	Input	External interrupt request input by which the valid edge (rising edge, falling edge, or both rising and falling edges) can be specified.	Input	P00
INTP1				P01
INTP2				P02
INTP3				P03/ADTRG
SI30	Input	Serial interface serial data input.	Input	P20
SI31[Note 1]				P34
SDA0[Note 2]	I/O	Serial interface serial data input/output	Input	P32
SO30	Output	Serial interface serial data output.	Input	P21
SO31[Note 1]				P35
$\overline{\text{SCK30}}$	I/O	Serial interface serial clock input/output.	Input	P22
$\overline{\text{SCK31}}$[Note 1]				P36
SCL0[Note 2]				P33
RxD0	Input	Serial data input for asynchronous serial interface.	Input	P23
TxD0	Output	Serial data output for asynchronous serial interface.	Input	P24
ASCK0	Input	Serial clock input for asynchronous serial interface.	Input	P25
TI00	Input	External count clock input to 16-bit timer/event counter 0. Capture trigger signal input to capture register 01 (CR01) of 16-bit timer/event counter 0.	Input	P70/TO0
TI01		Capture trigger signal input to capture register 00 (CR00) of 16-bit timer/event counter 0.		P71
TI50		External count clock input to 8-bit timer/event counter 50.		P72/TO50
TI51		External count clock input to 8-bit timer/event counter 51.		P73/TO51
TO0	Output	16-bit timer/event counter 0 output.	Input	P70/TI00
TO50		8-bit timer/event counter 50 output (shared with 8-bit PWM output).	Input	P72/TI50
TO51		8-bit timer/event counter 51 output (shared with 8-bit PWM output).		P73/TI51
PCL	Output	Clock output (for trimming of main system clock and subsystem clock).	Input	P74
BUZ	Output	Buzzer output.	Input	P75
AD0 to AD7	I/O	Lower address/data bus for extending memory externally.	Input	P40 to P47

Notes 1. SI31, SO31, and $\overline{\text{SCK31}}$ are incorporated only in the μPD78F0034A Subseries.

2. SDA0 and SCL0 are incorporated only in the μPD78F0034AY Subseries.

3.2 Non-Port Pins (2/2)

Pin Name	I/O	Function	After Reset	Alternate Function
A8 to A15	Output	Higher address bus for extending memory externally.	Input	P50 to P57
$\overline{RD}$	Output	Strobe signal output for read operation of external memory.	Input	P64
$\overline{WR}$		Strobe signal output for write operation of external memory.		P65
$\overline{WAIT}$	Input	Inserting wait for accessing external memory.	Input	P66
ASTB	Output	Strobe output which externally latches address information output to ports 4 and 5 to access external memory.	Input	P67
ANI0 to ANI7	Input	A/D converter analog input.	Input	P10 to P17
ADTRG	Input	A/D converter trigger signal input.	Input	P03/INTP3
AV_{REF}	Input	A/D converter reference voltage input.	–	–
AV_{DD}	–	A/D converter analog power supply. Set the voltage equal to V_{DD0} or V_{DD1}.	–	–
AV_{SS}	–	A/D converter ground potential. Set the voltage equal to V_{SS0} or V_{SS1}.	–	–
$\overline{RESET}$	Input	System reset input.	–	–
X1	Input	Connecting crystal resonator for main system clock oscillation.	–	–
X2	–		–	–
XT1	Input	Connecting crystal resonator for subsystem clock oscillation.	–	–
XT2	–		–	–
V_{DD0}	–	Positive power supply voltage for ports.	–	–
V_{SS0}	–	Ground potential of ports.	–	–
V_{DD1}	–	Positive power supply (except ports).	–	–
V_{SS1}	–	Ground potential (except ports).	–	–
V_{PP}	–	Applying high-voltage for program write/verify. Connect directly to V_{SS0} or V_{SS1} in normal operation mode.	–	–

3.3 Pin I/O Circuits and Recommended Connection of Unused Pins

The input/output circuit type of each pin and recommended connection of unused pins are shown in Table 3-1.

For the input/output configuration of each type, refer to Figure 3-1 .

Table 3-1. Types of Pin I/O Circuits (1/2)

Pin Name	I/O Circuit Type	I/O	Recommended Connection of Unused Pins
P00/INTP0	8-C	I/O	Input: Independently connect to V_{SS0} via a resistor. Output: Leave open.
P01/INTP1			
P02/INTP2			
P03/INTP3/ADTRG			
P10/ANI0 to P17/ANI7	25	Input	Connect to V_{DD0} or V_{SS0}.
P20/SI30	8-C	I/O	Input: Independently connect to V_{DD0} or V_{SS0} via a resistor. Output: Leave open.
P21/SO30	5-H		
P22/$\overline{SCK30}$	8-C		
P23/RxD0			
P24/TxD0	5-H		
P25/ASCK0	8-C		
P30, P31	13-P	I/O	Input: Independently connect to V_{DD0} via a resistor. Output: Leave open.
P32/SDA0**Note 1**	13-R		
P33/SCL0**Note 1**			
P34/SI31**Note 2**	8-C		Input: Independently connect to V_{DD0} or V_{SS0} via a resistor. Output: Leave open.
P35/SO31**Note 2**	5-H		
P36/$\overline{SCK31}$**Note 2**	8-C		
P40/AD0 to P47/AD7	5-H	I/O	Input: Independently connect to V_{DD0} via a resistor. Output: Leave open.
P50/A8 to P57/A15	5-H	I/O	Input: Independently connect to V_{DD0} or V_{SS0} via a resistor. Output: Leave open.
P64/$\overline{RD}$		I/O	
P65/$\overline{WR}$			
P66/$\overline{WAIT}$			
P67/ASTB			
P70/TI00/TO0	8-C		
P71/TI01			
P72/TI50/TO50			
P73/TI51/TO51			
P74/PCL	5-H		
P75/BUZ			

Notes 1. SDA0 and SCL0 are incorporated only in the μPD78F0034AY Subseries.

2. SI31, SO31, and $\overline{SCK31}$ are incorporated only in the μPD78F0034A Subseries.

Table 3-1. Types of Pin I/O Circuits (2/2)

Pin Name	I/O Circuit Type	I/O	Recommended Connection of Unused Pins
$\overline{\text{RESET}}$	2	Input	–
XT1	16		Connect to V_{DD0}.
XT2		–	Leave open.
AV_{DD}	–		Connect to V_{DD0} or V_{DD1}.
AV_{REF}			Connect to V_{SS0} or V_{SS1}.
AV_{SS}			
V_{PP}			Connect directly to V_{SS0} or V_{SS1}.

Figure 3-1. Pin I/O Circuits
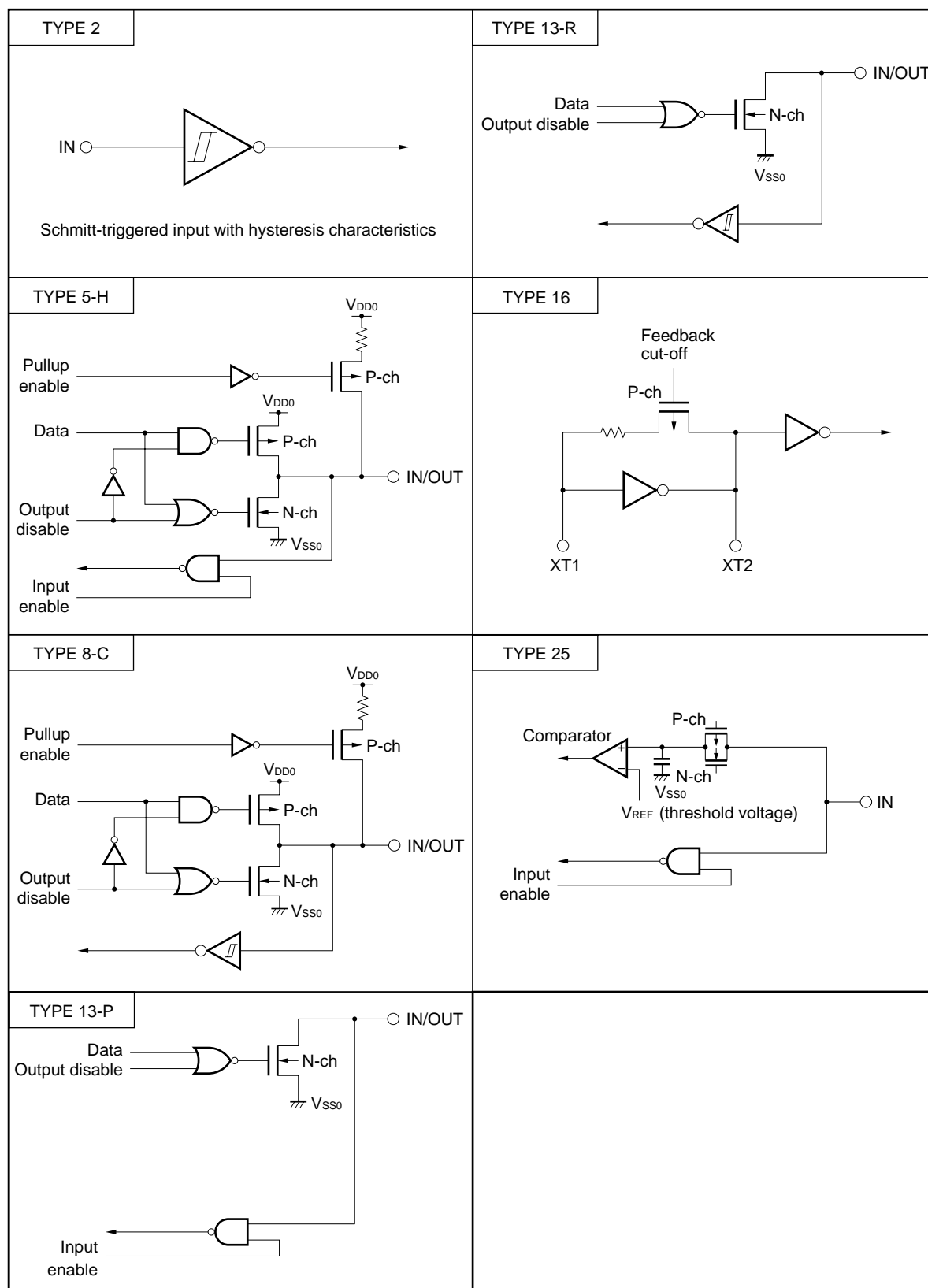
4. DIFFERENCES BETWEEN μPD78F0034A, 78F0034AY, AND MASK ROM VERSIONS

The μPD78F0034A and 78F0034AY are products provided with a flash memory which enables writing, erasing, and rewriting of programs with device mounted on the target system.

The functions of the μPD78F0034A (except the functions specified for flash memory) can be made the same as those of the mask ROM versions by setting the memory size switching register (IMS).

Tables 4-1 and 4-2 show the differences between the μPD78F0034A, 78F0034AY and the mask ROM versions.

Table 4-1. Differences Between μPD78F0034A and Mask ROM Versions

Item	μPD78F0034A	Mask ROM Versions	
		μPD780034A Subseries	μPD780024A Subseries**Note**
Internal ROM structure	Flash memory	Mask ROM	
Internal ROM capacity	32 KB	μPD780031A: 8 KB μPD780032A: 16 KB μPD780033A: 24 KB μPD780034A: 32 KB	μPD780021A: 8 KB μPD780022A: 16 KB μPD780023A: 24 KB μPD780024A: 32 KB
Internal high-speed RAM capacity	1,024 bytes	μPD780031A: 512 bytes μPD780032A: 512 bytes μPD780033A: 1,024 bytes μPD780034A: 1,024 bytes	μPD780021A: 512 bytes μPD780022A: 512 bytes μPD780023A: 1,024 bytes μPD780024A: 1,024 bytes
A/D converter resolution	10 bits		8 bits
Mask option specification of on-chip pull-up resistor for pins P30 to P33	Not available	Available	
IC pin	Not provided	Provided	
V$_{PP}$ pin	Provided	Not provided	
Electrical specifications, recommended soldering conditions	Refer to the data sheet of individual products.		

Note The μPD78F0034A can be used as the flash memory version of the μPD780024A Subseries.

Caution There are differences in noise immunity and noise radiation between the flash memory and mask ROM versions. When pre-producing an application set with the flash memory version and then mass producing it with the mask ROM version, be sure to conduct sufficient evaluations on the commercial samples (CS) (not engineering samples (ES)) of the mask ROM versions.

Table 4-2. Differences Between μPD78F0034AY and Mask ROM Versions

Item	μPD78F0034AY	Mask ROM Versions	
		μPD780034AY Subseries	μPD780024AY Subseries[Note]
Internal ROM structure	Flash memory	Mask ROM	
Internal ROM capacity	32 KB	μPD780031AY: 8 KB μPD780032AY: 16 KB μPD780033AY: 24 KB μPD780034AY: 32 KB	μPD780021AY: 8 KB μPD780022AY: 16 KB μPD780023AY: 24 KB μPD780024AY: 32 KB
Internal high-speed RAM capacity	1,024 bytes	μPD780031AY: 512 bytes μPD780032AY: 512 bytes μPD780033AY: 1,024 bytes μPD780034AY: 1,024 bytes	μPD780021AY: 512 bytes μPD780022AY: 512 bytes μPD780023AY: 1,024 bytes μPD780024AY: 1,024 bytes
A/D converter resolution	10 bits		8 bits
Mask option specification of on-chip pull-up resistor for pins P30 and P31	Not available	Available	
IC pin	Not provided	Provided	
V$_{PP}$ pin	Provided	Not provided	
Electrical specifications, recommended soldering conditions	Refer to the data sheet of individual products.		

Note The μPD78F0034AY can be used as the flash memory version of the μPD780024AY Subseries.

Caution There are differences in noise immunity and noise radiation between the flash memory and mask ROM versions. When pre-producing an application set with the flash memory version and then mass producing it with the mask ROM version, be sure to conduct sufficient evaluations on the commercial samples (CS) (not engineering samples (ES)) of the mask ROM versions.

5. MEMORY SIZE SWITCHING REGISTER (IMS)

IMS is a register that is set by software and is used to specify a part of the internal memory that is not to be used. By setting memory size switching register (IMS), the internal memory of the μPD78F0034A and 78F0034AY can be mapped identically to that of a mask ROM version.

IMS is set with an 8-bit memory manipulation instruction.

$\overline{\text{RESET}}$ input sets the IMS to CFH.

Caution   The initial value of IMS is setting disabled (CFH).   Be sure to set C8H or the value of the target mask ROM version at the moment of initial setting.

Figure 5-1. Format of Memory Size Switching Register

	7	6	5	4	3	2	1	0	Address	After reset	R/W
IMS	RAM2	RAM1	RAM0	0	ROM3	ROM2	ROM1	ROM0	FFF0H	CFH	R/W

ROM3	ROM2	ROM1	ROM0	Selection of Internal ROM Capacity
0	0	1	0	8 KB
0	1	0	0	16 KB
0	1	1	0	24 KB
1	0	0	0	32 KB
Other than above				Setting prohibited

RAM2	RAM1	RAM0	Selection of Internal High-Speed RAM Capacity
0	1	0	512 bytes
1	1	0	1,024 bytes
Other than above			Setting prohibited
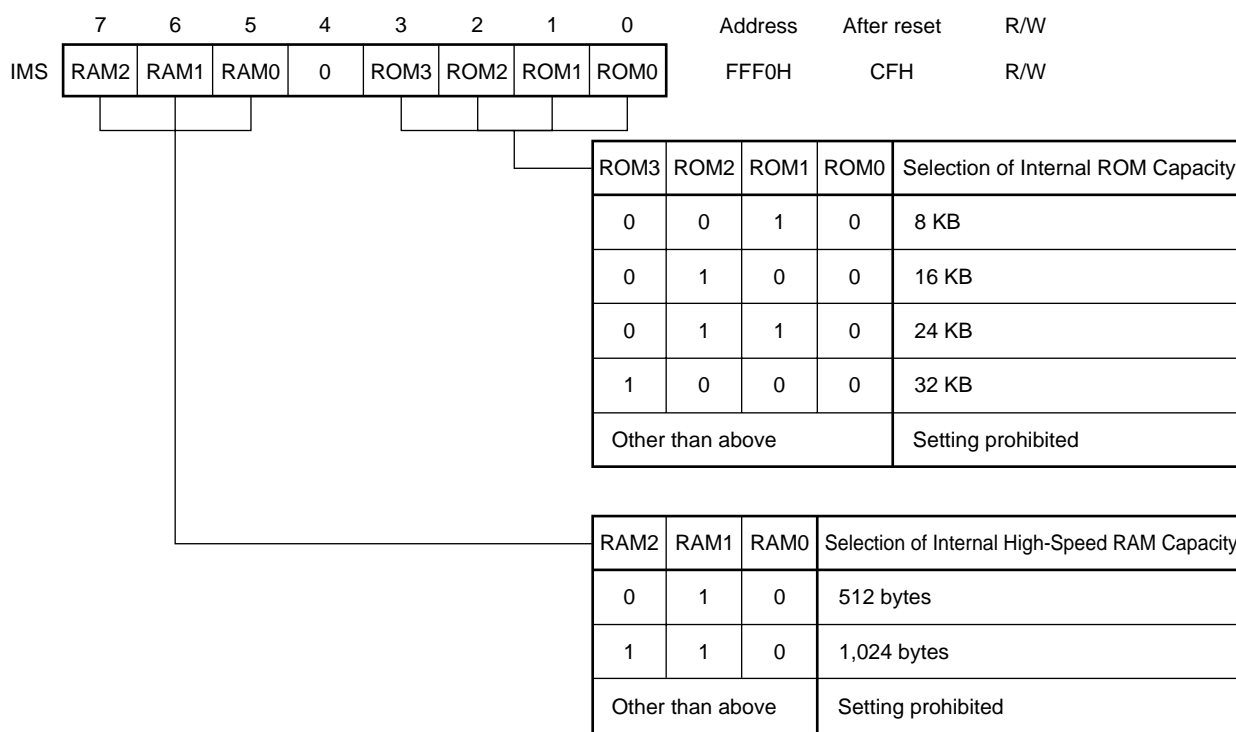
Table 5-1 shows the IMS set value to make the memory mapping the same as those of mask ROM versions.

Table 5-1. Set Value of Memory Size Switching Register

Target Mask ROM Versions	IMS Set Value
μPD780031A, 780031AY	42H
μPD780032A, 780032AY	44H
μPD780033A, 780033AY	C6H
μPD780034A, 780034AY	C8H

6. FLASH MEMORY PROGRAMMING

Writing to flash memory can be performed without removing the memory from the target system (on board programming). Writing is performed with the dedicated flash programmer (Flashpro II (part No.: FL-PR2) or Flashpro III (part No.: FL-PR3 and PG-FP3)) connected to the host machine and the target system.

Writing to flash memory can also be performed using flash memory writing adapter connected to Flashpro II or Flashpro III.

Remark FL-PR2 and FL-PR3 are products of Naito Densei Machida Mfg. Co., Ltd.

6.1 Selection of Communication Mode

Writing to a flash memory is performed using Flashpro II or Flashpro III in a serial communication. Select one of the communication modes in Tables 6-1 and 6-2. The selection of the communication mode is made by using the format shown in Figure 6-1. Each communication mode is selected by the number of V$_{PP}$ pulses shown in Tables 6-1 and 6-2.

Table 6-1. List of Communication Mode (μPD78F0034A)

Communication Mode	Channels	Pin Used	V$_{PP}$ Pulses
3-wire serial I/O	2	SI30/P20 SO30/P21 SCK30/P22	0
		SI31/P34 SO31/P35 SCK31/P36	1
UART	1	RxD0/P23 TxD0/P24	8
Pseudo 3-wire serial I/O	1	P72/TI50/TO50 (serial clock input) P71/TI01 (serial data output) P70/TI00/TO0 (serial data input)	12

Caution Be sure to select a communication mode using the number of V$_{PP}$ pulses shown in Table 6-1.

Table 6-2. List of Communication Mode (μPD78F0034AY)

Communication Mode	Channels	Pin Used	V_{PP} Pulses
3-wire serial I/O	1	SI30/P20 SO30/P21 $\overline{\text{SCK30}}$/P22	0
I²C bus	1	SDA0/P32 SCL0/P33	4
UART	1	RxD0/P23 TxD0/P24	8
Pseudo 3-wire serial I/O	1	P72/TI50/TO50 (serial clock input) P71/TI01 (serial data output) P70/TI00/TO0 (serial data input)	12

Caution   Be sure to select a communication mode using the number of V_{PP} pulses shown in Table 6-2.

Figure 6-1. Format of Communication Mode Selection
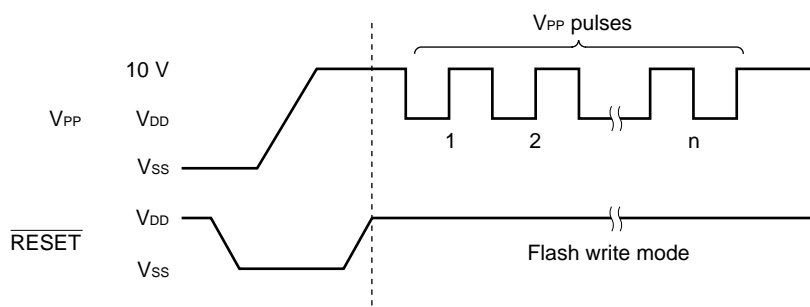
6.2 Flash Memory Programming Functions

Operations such as writing to flash memory are performed by various command/data transmission and reception operations according to the selected communication mode. Table 6-3 shows major functions of flash memory programming.

Table 6-3. Major Functions of Flash Memory Programming

Function	Description
Reset	Used to stop write operation and detect transmission cycle.
Batch verify	Compares the entire memory contents with the input data.
Batch erase	Erases the entire memory contents.
Batch blank check	Checks the deletion status of the entire memory.
High-speed write	Performs write to the flash memory based on the write start address and the number of data to be written (number of bytes).
Continuous write	Performs continuous write based on the information input with high-speed write operation.
Status	Used to confirm the current operating mode and operation end.
Oscillation frequency setting	Sets the frequency of the resonator.
Erase time setting	Sets the memory erase time.
Baud rate setting	Sets the communication rate for UART mode
I^{2}C mode setting	Sets standard/high-speed mode for I^{2}C bus mode
Silicon signature read	Outputs the device name and memory capacity, and device block information.

6.3 Connection of Flashpro II and Flashpro III

The connection of Flashpro II or Flashpro III and the μPD78F0034A or 78F0034AY differs according to the communication mode (3-wire serial I/O, UART, and pseudo 3-wire serial I/O). The connection for each communication mode is shown in Figures 6-2 to 6-5, respectively.

Figure 6-2. Connection of Flashpro II or Flashpro III for 3-Wire Serial I/O Mode
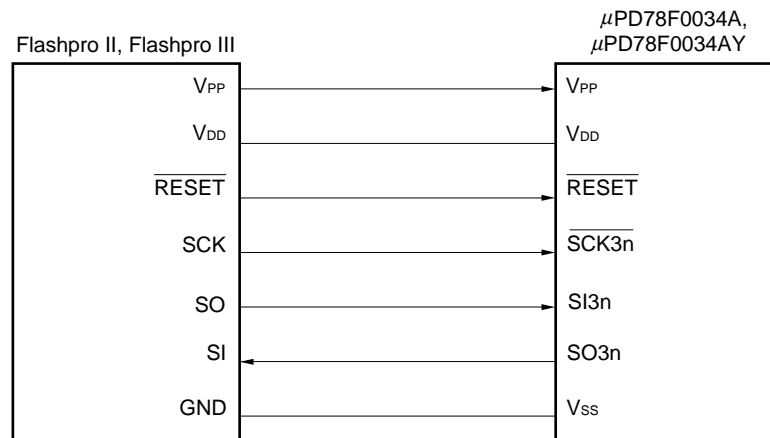
Remark μPD78F0034A: n = 0, 1
μPD78F0034AY: n = 0

Figure 6-3. Connection of Flashpro II or Flashpro III for UART Mode

Flashpro II, Flashpro III

μPD78F0034A,
μPD78F0034AY

Flashpro side	μPD side
V_{PP}	V_{PP}
V_{DD}	V_{DD}
$\overline{RESET}$	$\overline{RESET}$
SO	RxD0
SI	TxD0
GND	V_{SS}
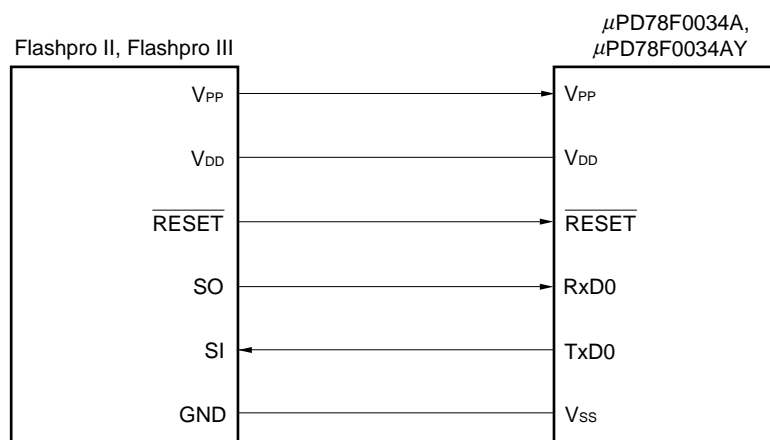
Figure 6-4. Connection of Flashpro II or Flashpro III for Pseudo 3-Wire Serial I/O Mode

Flashpro II, Flashpro III

μPD78F0034A,
μPD78F0034AY

Flashpro side	μPD side
V_{PP}	V_{PP}
V_{DD}	V_{DD}
$\overline{RESET}$	$\overline{RESET}$
SCK	P72 (serial clock input)
SO	P70 (serial data input)
SI	P71 (serial data output)
GND	V_{SS}
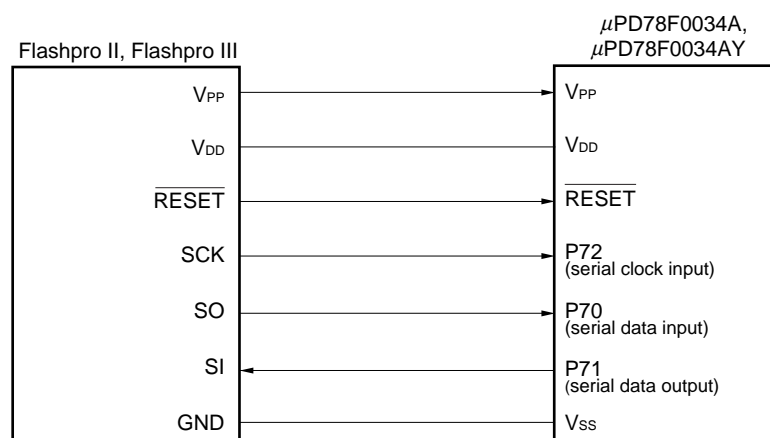
Figure 6-5. Connection of Flashpro II or Flashpro III for I^{2}C Bus Mode (μPD78F0034AY only)

Flashpro II, Flashpro III

μPD78F0034AY

Flashpro side	μPD side
V_{PP}	V_{PP}
V_{DD}	V_{DD}
$\overline{RESET}$	$\overline{RESET}$
SO	SCL0
SI	SDA0
GND	V_{SS}
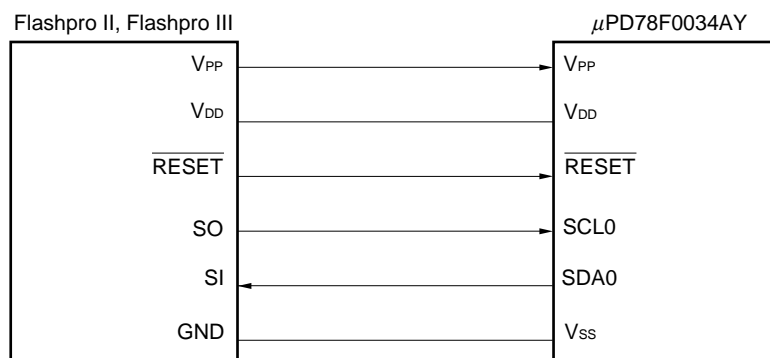
7. ELECTRICAL SPECIFICATIONS

Absolute Maximum Ratings (T$_A$ = 25°C)

Parameter	Symbol	Conditions		Ratings	Unit
Supply voltage	V$_{DD}$			−0.3 to +6.5	V
	V$_{PP}$			−0.3 to +10.5	V
	AV$_{DD}$			−0.3 to V$_{DD}$ + 0.3**Note**	V
	AV$_{REF}$			−0.3 to V$_{DD}$ + 0.3**Note**	V
	AV$_{SS}$			−0.3 to +0.3	V
Input voltage	V$_{I1}$	P00 to P03, P10 to P17, P20 to P25, P34 to P36, P40 to P47, P50 to P57, P64 to P67, P70 to P75, X1, X2, XT1, XT2, $\overline{\text{RESET}}$		−0.3 to V$_{DD}$ + 0.3**Note**	V
	V$_{I2}$	P30 to P33	N-ch open drain	−0.3 to +6.5	V
Output voltage	V$_O$			−0.3 to V$_{DD}$ + 0.3**Note**	V
Analog input voltage	V$_{AN}$	P10 to P17	Analog input pin	AV$_{SS}$ −0.3 to AV$_{REF}$ + 0.3**Note** and −0.3 to V$_{DD}$ + 0.3**Note**	V
Output current, high	I$_{OH}$	Per pin		−10	mA
		Total for P00 to P03, P40 to P47, P50 to P57, P64 to P67, P70 to P75		−15	mA
		Total for P20 to P25, P30 to P36		−15	mA
Output current, low	I$_{OL}$	Per pin for P00 to P03, P20 to P25, P34 to P36, P40 to P47, P64 to P67, P70 to P75		20	mA
		Per pin for P30 to P33, P50 to P57		30	mA
		Total for P00 to P03, P40 to P47, P64 to P67, P70 to P75		50	mA
		Total for P20 to P25		20	mA
		Total for P30 to P36		100	mA
		Total for P50 to P57		100	mA
Operating ambient temperature	T$_A$			−40 to +85	°C
Storage temperature	T$_{stg}$			−40 to +125	°C

Note 6.5 V or below

Caution   Product quality may suffer if the absolute maximum rating is exceeded even momentarily for any parameter. That is, the absolute maximum ratings are rated values at which the product is on the verge of suffering physical damage, and therefore the product must be used under conditions that ensure that the absolute maximum ratings are not exceeded.
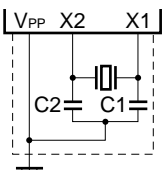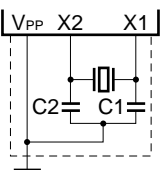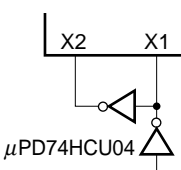
Capacitance (T$_A$ = 25°C, V$_{DD}$ = V$_{SS}$ = 0 V)

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
Input capacitance	C$_{IN}$	f = 1 MHz Unmeasured pins returned to 0 V.				15	pF
I/O capacitance	C$_{IO}$	f = 1 MHz Unmeasured pins returned to 0 V.	P00 to P03, P20 to P25, P34 to P36, P40 to P47, P50 to P57, P64 to P67, P70 to P75,			15	pF
			P30 to P33			20	pF

Remark Unless otherwise specified, the characteristics of alternate-function pins are the same as those of port pins.

Main System Clock Oscillator Characteristics (T$_A$ = –40 to +85°C, V$_{DD}$ = 1.8 to 5.5 V)

Resonator	Recommended Circuit	Parameter	Conditions	MIN.	TYP.	MAX.	Unit
Ceramic resonator	VPP X2 X1 C2 C1	Oscillation frequency (f$_X$)**Note 1**	V$_{DD}$ = 4.0 to 5.5 V	1.0		8.38	MHz
				1.0		5.0	
		Oscillation stabilization time**Note 2**	After V$_{DD}$ reaches oscillation voltage range MIN.			4	ms
Crystal resonator	VPP X2 X1 C2 C1	Oscillation frequency (f$_X$)**Note 1**	V$_{DD}$ = 4.0 to 5.5 V	1.0		8.38	MHz
				1.0		5.0	
		Oscillation stabilization time**Note 2**	V$_{DD}$ = 4.0 to 5.5 V			10	ms
						30	
External clock	X2 X1 μPD74HCU04	X1 input frequency (f$_X$)**Note 1**	V$_{DD}$ = 4.0 to 5.5 V	1.0		8.38	MHz
				1.0		5.0	
		X1 input high-/low-level width (t$_{XH}$, t$_{XL}$)	V$_{DD}$ = 4.0 to 5.5 V	50		500	ns
				85		500	
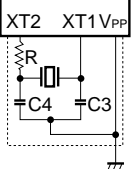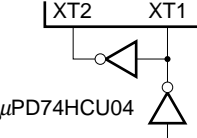
Notes 1. Indicates only oscillator characteristics. Refer to **AC Characteristics** for instruction execution time.
     2. Time required to stabilize oscillation after reset or STOP mode release.

Cautions 1. When using the main system clock oscillator, wire as follows in the area enclosed by the broken lines in the above figures to avoid an adverse effect from wiring capacitance.

- **Keep the wiring length as short as possible.**
- **Do not cross the wiring with the other signal lines.**
- **Do not route the wiring near a signal line through which a high fluctuating current flows.**
- **Always make the ground point of the oscillator capacitor to the same potential as V$_{SS1}$.**
- **Do not ground the capacitor to a ground pattern through which a high current flows.**
- **Do not fetch signals from the oscillator.**

2. When the main system clock is stopped and the system is operating on the subsystem clock, wait until the oscillation stabilization time has been secured by the program before switching back to the main system clock.

Subsystem Clock Oscillator Characteristics (T$_A$ = −40 to +85°C, V$_{DD}$ = 1.8 to 5.5 V)

Resonator	Recommended Circuit	Parameter	Conditions	MIN.	TYP.	MAX.	Unit
Crystal resonator	XT2 XT1 V$_{PP}$ R C4 C3	Oscillation frequency (f$_{XT}$)**Note 1**		32	32.768	35	kHz
		Oscillation stabilization time**Note 2**	V$_{DD}$ = 4.0 to 5.5 V		1.2	2	s
						10	
External clock	XT2 XT1 μPD74HCU04	X1 input frequency (f$_{XT}$)**Note 1**		32		38.5	kHz
		X1 input high-/low-level width (t$_{XTH}$, t$_{XTL}$)		5		15	μs

Notes 1. Indicates only oscillator characteristics. Refer to **AC Characteristics** for instruction execution time.
   2. Time required to stabilize oscillation after V$_{DD}$ reaches oscillator voltage MIN.

Cautions 1. When using the subsystem clock oscillator, wire as follows in the area enclosed by the broken lines in the above figures to avoid an adverse effect from wiring capacitance.

   • **Keep the wiring length as short as possible.**
   • **Do not cross the wiring with the other signal lines.**
   • **Do not route the wiring near a signal line through which a high fluctuating current flows.**
   • **Always make the ground point of the oscillator capacitor to the same potential as V$_{SS1}$.**
   • **Do not ground the capacitor to a ground pattern through which a high current flows.**
   • **Do not fetch signals from the oscillator.**

   2. The subsystem clock oscillator is designed as a low-amplitude circuit for reducing current consumption, and is more prone to malfunction due to noise than the main system clock oscillator. Particular care is therefore required with the wiring method when the subsystem clock is used.

Recommended Oscillator Constant

Main System Clock: Ceramic Resonator (T$_A$ = –40 to +85°C)

Manufacturer	Part Number	Frequency	Recommended Circuit Constant		Oscillation Voltage Range	
		(MHz)	C1 (pF)	C2 (pF)	MIN. (V)	MAX. (V)
Murata Mfg. Co., Ltd.	CSB1000J	1.00	100	100	1.9	5.5
	CSA2.00MG040	2.00	100	100	2.0	5.5
	CST2.00MG040	2.00	On-chip	On-chip	2.0	5.5
	CSA3.58MG	3.58	30	30	2.0	5.5
	CST3.58MGW	3.58	On-chip	On-chip	2.0	5.5
	CSA3.58MG093	3.58	30	30	1.8	5.5
	CST3.58MGW093	3.58	On-chip	On-chip	1.8	5.5
	CSA4.19MG	4.19	30	30	2.0	5.5
	CST4.19MGW	4.19	On-chip	On-chip	2.0	5.5
	CSA4.19MG093	4.19	30	30	1.8	5.5
	CST4.19MGW093	4.19	On-chip	On-chip	1.8	5.5
	CSA5.00MG	5.00	30	30	2.0	5.5
	CST5.00MGW	5.00	On-chip	On-chip	2.0	5.5
	CSA5.00MG093	5.00	30	30	1.8	5.5
	CST5.00MGW093	5.00	On-chip	On-chip	1.8	5.5
	CSA8.00MTZ	8.00	30	30	4.0	5.5
	CST8.00MTW	8.00	On-chip	On-chip	4.0	5.5
	CSA8.00MTZ093	8.00	30	30	4.0	5.5
	CST8.00MTW093	8.00	On-chip	On-chip	4.0	5.5
	CSA8.38MTZ	8.38	30	30	4.0	5.5
	CST8.38MTW	8.38	On-chip	On-chip	4.0	5.5
	CSA8.38MTZ093	8.38	30	30	4.0	5.5
	CST8.38MTW093	8.38	On-chip	On-chip	4.0	5.5
TDK	CCR3.58MC3	3.58	On-chip	On-chip	1.8	5.5
	CCR4.19MC3	4.19	On-chip	On-chip	1.8	5.5
	CCR5.0MC3	5.00	On-chip	On-chip	1.8	5.5
	CCR8.0MC5	8.00	On-chip	On-chip	2.2	5.5
	CCR8.38MC5	8.38	On-chip	On-chip	2.2	5.5

Caution   The oscillator constant and oscillation voltage range indicate conditions of stable oscillation. Oscillation frequency precision is not guaranteed. For applications requiring oscillation frequency precision, the oscillation frequency must be adjusted on the implementation circuit. For details please contact directly the manufacturer of the resonator you will use.

DC Characteristics (T_A = –40 to +85°C, V_{DD} = 1.8 to 5.5 V)

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
Output current, high	I_{OH}	Per pin				−1	mA
		All pins				−15	mA
Output current, low	I_{OL}	Per pin for P00 to P03, P20 to P25, P34 to P36, P40 to P47, P64 to P67, P70 to P75				10	mA
		Per pin for P30 to P33, P50 to P57				15	mA
		Total for P00 to P03, P40 to P47, P64 to P67, P70 to P75				20	mA
		Total for P20 to P25				10	mA
		Total for P30 to P36				70	mA
		Total for P50 to P57				70	mA
Input voltage, high	V_{IH1}	P10 to P17, P21, P24, P35, P40 to P47, P50 to P57, P64 to P67, P74, P75	V_{DD} = 2.7 to 5.5 V	$0.7V_{DD}$		V_{DD}	V
				$0.8V_{DD}$		V_{DD}	V
	V_{IH2}	P00 to P03, P20, P22, P23, P25, P34, P36, P70 to P73, $\overline{RESET}$	V_{DD} = 2.7 to 5.5 V	$0.8V_{DD}$		V_{DD}	V
				$0.85V_{DD}$		V_{DD}	V
	V_{IH3}	P30 to P33 (N-ch open-drain)	V_{DD} = 2.7 to 5.5 V	$0.7V_{DD}$		5.5	V
				$0.8V_{DD}$		5.5	V
	V_{IH4}	X1, X2	V_{DD} = 2.7 to 5.5 V	V_{DD} − 0.5		V_{DD}	V
				V_{DD} − 0.2		V_{DD}	V
	V_{IH5}	XT1, XT2	V_{DD} = 4.0 to 5.5 V	$0.8V_{DD}$		V_{DD}	V
				$0.9V_{DD}$		V_{DD}	V
Input voltage, low	V_{IL1}	P10 to P17, P21, P24, P35, P40 to P47, P50 to P57, P64 to P67, P74, P75	V_{DD} = 2.7 to 5.5 V	0		$0.3V_{DD}$	V
				0		$0.2V_{DD}$	V
	V_{IL2}	P00 to P03, P20, P22, P23, P25, P34, P36, P70 to P73, $\overline{RESET}$	V_{DD} = 2.7 to 5.5 V	0		$0.2V_{DD}$	V
				0		$0.15V_{DD}$	V
	V_{IL3}	P30 to P33	4.0 V ≤ V_{DD} ≤ 5.5 V	0		$0.3V_{DD}$	V
			2.7 V ≤ V_{DD} < 4.0 V	0		$0.2V_{DD}$	V
			1.8 V ≤ V_{DD} < 2.7	0		$0.1V_{DD}$	V
	V_{IL4}	X1, X2	V_{DD} = 2.7 to 5.5 V	0		0.4	V
				0		0.2	V
	V_{IL5}	XT1, XT2	V_{DD} = 4.0 to 5.5 V	0		$0.2V_{DD}$	V
				0		$0.1V_{DD}$	V
Output voltage, high	V_{OH1}	V_{DD} = 4.0 to 5.5 V, I_{OH} = −1 mA		V_{DD} − 1.0		V_{DD}	V
		I_{OH} = −100 μA		V_{DD} − 0.5		V_{DD}	V
Output voltage, low	V_{OL1}	P30 to P33	V_{DD} = 4.0 to 5.5 V, I_{OL} = 15 mA			2.0	V
		P50 to P57			0.4	2.0	V
		P00 to P03, P20 to P25, P34 to P36, P40 to P47, P64 to P67, P70 to P75	V_{DD} = 4.0 to 5.5 V, I_{OL} = 1.6 mA			0.4	V
	V_{OL2}	I_{OL} = 400 μA				0.5	V

Remark Unless otherwise specified, the characteristics of alternate-function pins are the same as those of port pins.

DC Characteristics (T$_A$ = −40 to +85°C, V$_{DD}$ = 1.8 to 5.5 V)

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
Input leakage current, high	I$_{LIH1}$	V$_{IN}$ = V$_{DD}$	P00 to P03, P10 to P17, P20 to P25, P34 to P36, P40 to P47, P50 to P57, P64 to P67, P70 to P75, $\overline{RESET}$			3	μA
	I$_{LIH2}$		X1, X2, XT1, XT2			20	μA
	I$_{LIH3}$	V$_{IN}$ = 5.5 V	P30 to P33			3	μA
Input leakage current, low	I$_{LIL1}$	V$_{IN}$ = 0 V	P00 to P03, P10 to P17, P20 to P25, P34 to P36, P40 to P47, P50 to P57, P64 to P67, P70 to P75, $\overline{RESET}$			−3	μA
	I$_{LIL2}$		X1, X2, XT1, XT2			−20	μA
	I$_{LIL3}$		P30 to P33			−3	μA
Output leakage current, low	I$_{LOH}$	V$_{OUT}$ = V$_{DD}$				3	μA
Output leakage current, low	I$_{LOL}$	V$_{OUT}$ = 0 V				−3	μA
Software pull-up resistor	R	V$_{IN}$ = 0 V, P00 to P03, P20 to P25, P34 to P36, P40 to P47, P50 to P57, P64 to P67, P70 to P75		15	30	90	kΩ

Remark Unless otherwise specified, the characteristics of alternate-function pins are the same as those of port pins .

DC Characteristics (TA = –40 to +85°C, VDD = 1.8 to 5.5 V)

Parameter	Symbol	Conditions			MIN.	TYP.	MAX.	Unit
Supply current[Note 1]	IDD1	8.38 MHz crystal oscillation operating mode	VDD = 5.0 V ±10%[Note 2]	A/D converter stopped		10.5	21	mA
				A/D converter operating		11.5	23	mA
		5.00 MHz crystal oscillation operation mode	VDD = 3.0 V ±10%[Note 2]	A/D converter stopped		4.5	9	mA
				A/D converter operating		5.5	11	mA
			VDD = 2.0 V ±10%[Note 3]	A/D converter stopped		1	2	mA
				A/D converter operating		2	6	mA
	IDD2	8.38 MHz crystal oscillation HALT mode	VDD = 5.0 V ±10%[Note 2]	Peripheral functions stopped		1.2	2.4	mA
				Peripheral functions operating			5	mA
		5.00 MHz crystal oscillation HALT mode	VDD = 3.0 V ±10%[Note 2]	Peripheral functions stopped		0.4	0.8	mA
				Peripheral functions operating			1.7	mA
			VDD = 2.0 V ±10%[Note 3]	Peripheral functions stopped		0.2	0.4	mA
				Peripheral functions operating			1.1	mA
	IDD3	32.768 kHz crystal oscillation operating mode[Note 4]	VDD = 5.0 V ±10%[Note 2]			115	230	μA
			VDD = 3.0 V ±10%[Note 2]			95	190	μA
			VDD = 2.0 V ±10%[Note 3]			75	150	μA
	IDD4	32.768 kHz crystal oscillation HALT mode[Note 4]	VDD = 5.0 V ±10%[Note 2]			30	60	μA
			VDD = 3.0 V ±10%[Note 2]			6	18	μA
			VDD = 2.0 V ±10%[Note 3]			2	10	μA
	IDD5	XT1 = 0 V, STOP mode When feed-back resistor not used	VDD = 5.0 V ±10%[Note 2]			0.1	30	μA
			VDD = 3.0 V ±10%[Note 2]			0.05	10	μA
			VDD = 2.0 V ±10%[Note 3]			0.05	10	μA

Notes 1. Refers to the total current flowing through the internal power supply (VDD0 and VDD1). Includes peripheral operating current (however, current flowing through the pull-up resistors of ports and the AVREF pin is not included).

    2. When the processor clock control register (PCC) is set to 00H.

    3. When PCC is set to 02H.

    4. When the main system clock is stopped.

AC Characteristics

(1) Basic operation (T$_A$ = –40 to +85°C, V$_{DD}$ = 1.8 to 5.5 V)

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
Cycle time (Min. instruction execution time)	T$_{CY}$	Operating on main system clock	4.0 ≤ V$_{DD}$ ≤ 5.5 V	0.24		16	μs
			2.7 V ≤ V$_{DD}$ < 4.0 V	0.4		16	μs
				1.6		16	μs
		Operating on subsystem clock		103.9**Note 1**	122	125	μs
TI00, TI01 input high-/low-level width	t$_{TIH0}$, t$_{TIL0}$	4.0 V ≤ V$_{DD}$ ≤ 5.5 V		2/f$_{sam}$ + 0.1**Note 2**			μs
		2.7 V ≤ V$_{DD}$ < 4.0 V		2/f$_{sam}$ + 0.2**Note 2**			μs
				2/f$_{sam}$ + 0.5**Note 2**			μs
TI50, TI51 input frequency	f$_{TI5}$	V$_{DD}$ = 2.7 to 5.5 V		0		4	MHz
				0		275	kHz
TI50, TI51 input high-/low-level width	t$_{TIH5}$, t$_{TIL5}$	V$_{DD}$ = 2.7 to 5.5 V		100			ns
				1.8			μs
Interrupt request input high-/low-level width	t$_{INTH}$, t$_{INTL}$	INTP0 to INTP3, P40 to P47	V$_{DD}$ = 2.7 to 5.5 V	1			μs
				2			μs
$\overline{RESET}$ low-level width	t$_{RSL}$	V$_{DD}$ = 2.7 to 5.5 V		10			μs
				20			μs

Notes 1. Value when using an external clock. When using a crystal resonator, the value becomes 114 μs (MIN.).
2. Selection of f$_{sam}$ = f$_X$, f$_X$/4, f$_X$/64 is possible using bits 0 and 1 (PRM00, PRM01) of prescaler mode register 0 (PRM0). However, if the TI00 valid edge is selected as the count clock, the value becomes f$_{sam}$ = f$_X$/8.

TCY vs. VDD (main system clock)
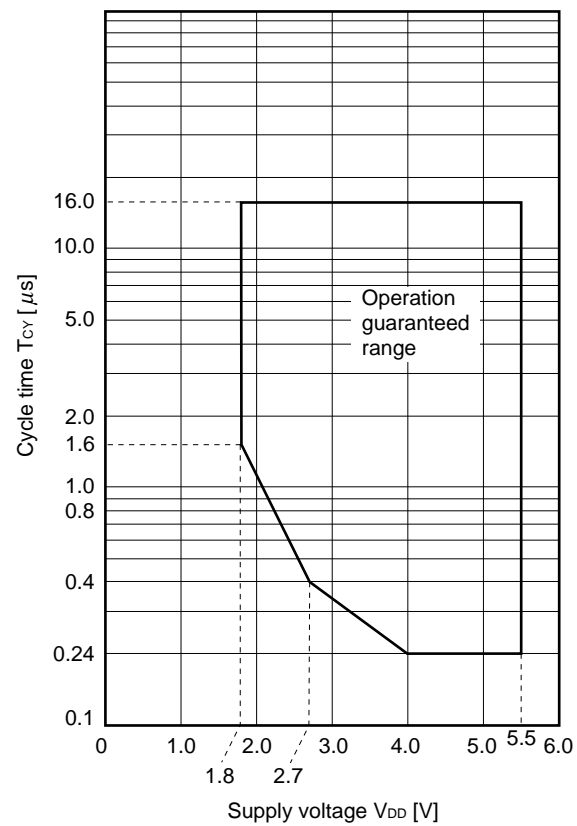
(2) Read/write operation (T_A = –40 to +85°C, V_{DD} = 4.0 to 5.5 V) (1/3)

Parameter	Symbol	Conditions	MIN.	MAX.	Unit
ASTB high-level width	t_{ASTH}		$0.3t_{CY}$		ns
Address setup time	t_{ADS}		20		ns
Address hold time	t_{ADH}		6		ns
Input time from address to data	t_{ADD1}			$(2 + 2n)t_{CY} - 54$	ns
	t_{ADD2}			$(3 + 2n)t_{CY} - 60$	ns
Output time from $\overline{RD}\downarrow$ to address	t_{RDAD}		0	100	ns
Input time from $\overline{RD}\downarrow$ to data	t_{RDD1}			$(2 + 2n)t_{CY} - 87$	ns
	t_{RDD2}			$(3 + 2n)t_{CY} - 93$	ns
Read data hold time	t_{RDH}		0		ns
$\overline{RD}$ low-level width	t_{RDL1}		$(1.5 + 2n)t_{CY} - 33$		ns
	t_{RDL2}		$(2.5 + 2n)t_{CY} - 33$		ns
Input time from $\overline{RD}\downarrow$ to $\overline{WAIT}\downarrow$	t_{RDWT1}			$t_{CY} - 43$	ns
	t_{RDWT2}			$t_{CY} - 43$	ns
Input time from $\overline{WR}\downarrow$ to $\overline{WAIT}\downarrow$	t_{WRWT}			$t_{CY} - 25$	ns
$\overline{WAIT}$ low-level width	t_{WTL}		$(0.5 + n)t_{CY} + 10$	$(2 + 2n)t_{CY}$	ns
Write data setup time	t_{WDS}		60		ns
Write data hold time	t_{WDH}		6		ns
$\overline{WR}$ low-level width	t_{WRL1}		$(1.5 + 2n)t_{CY} - 15$		ns
Delay time from ASTB$\downarrow$ to $\overline{RD}\downarrow$	t_{ASTRD}		6		ns
Delay time from ASTB$\downarrow$ to $\overline{WR}\downarrow$	t_{ASTWR}		$2t_{CY} - 15$		ns
Delay time from $\overline{RD}\uparrow$ to ASTB$\uparrow$ in external fetch	t_{RDAST}		$0.8t_{CY} - 15$	$1.2t_{CY}$	ns
Hold time from $\overline{RD}\uparrow$ to address in external fetch	t_{RDADH}		$0.8t_{CY} - 15$	$1.2t_{CY} + 30$	ns
Write data output time from $\overline{RD}\uparrow$	t_{RDWD}		40		ns
Write data output time from $\overline{WR}\downarrow$	t_{WRWD}		10	60	ns
Hold time from $\overline{WR}\uparrow$ to address	t_{WRADH}		$0.8t_{CY} - 15$	$1.2t_{CY} + 30$	ns
Delay time from $\overline{WAIT}\uparrow$ to $\overline{RD}\uparrow$	t_{WTRD}		$0.8t_{CY}$	$2.5t_{CY} + 25$	ns
Delay time from $\overline{WAIT}\uparrow$ to $\overline{WR}\uparrow$	t_{WTWR}		$0.8t_{CY}$	$2.5t_{CY} + 25$	ns

Remarks 1. t_{CY} = $T_{CY}/4$

2. n indicates the number of waits.

3. C_L = 100 pF (C_L is the load capacitance of the AD0 to AD7, A8 to A15, $\overline{RD}$, $\overline{WR}$, $\overline{WAIT}$, and ASTB pins.)

(2) Read/write operation (T$_A$ = –40 to +85°C, V$_{DD}$ = 2.7 to 4.0 V) (2/3)

Parameter	Symbol	Conditions	MIN.	MAX.	Unit
ASTB high-level width	t$_{ASTH}$		0.3t$_{CY}$		ns
Address setup time	t$_{ADS}$		30		ns
Address hold time	t$_{ADH}$		10		ns
Input time from address to data	t$_{ADD1}$			(2 + 2n)t$_{CY}$ – 108	ns
	t$_{ADD2}$			(3 + 2n)t$_{CY}$ – 120	ns
Output time from $\overline{RD}\downarrow$ to address	t$_{RDAD}$		0	200	ns
Input time from $\overline{RD}\downarrow$ to data	t$_{RDD1}$			(2 + 2n)t$_{CY}$ – 148	ns
	t$_{RDD2}$			(3 + 2n)t$_{CY}$ – 162	ns
Read data hold time	t$_{RDH}$		0		ns
$\overline{RD}$ low-level width	t$_{RDL1}$		(1.5 + 2n)t$_{CY}$ – 40		ns
	t$_{RDL2}$		(2.5 + 2n)t$_{CY}$ – 40		ns
Input time from $\overline{RD}\downarrow$ to $\overline{WAIT}\downarrow$	t$_{RDWT1}$			t$_{CY}$ – 75	ns
	t$_{RDWT2}$			t$_{CY}$ – 60	ns
Input time from $\overline{WR}\downarrow$ to $\overline{WAIT}\downarrow$	t$_{WRWT}$			t$_{CY}$ – 50	ns
$\overline{WAIT}$ low-level width	t$_{WTL}$		(0.5 + 2n)t$_{CY}$ + 10	(2 + 2n)t$_{CY}$	ns
Write data setup time	t$_{WDS}$		60		ns
Write data hold time	t$_{WDH}$		10		ns
$\overline{WR}$ low-level width	t$_{WRL1}$		(1.5 + 2n)t$_{CY}$ – 30		ns
Delay time from ASTB$\downarrow$ to $\overline{RD}\downarrow$	t$_{ASTRD}$		10		ns
Delay time from ASTB$\downarrow$ to $\overline{WR}\downarrow$	t$_{ASTWR}$		2t$_{CY}$ – 30		ns
Delay time from $\overline{RD}\uparrow$ to ASTB$\uparrow$ in external fetch	t$_{RDAST}$		0.8t$_{CY}$ – 30	1.2t$_{CY}$	ns
Hold time from $\overline{RD}\uparrow$ to address in external fetch	t$_{RDADH}$		0.8t$_{CY}$ – 30	1.2t$_{CY}$ + 60	ns
Write data output time from $\overline{RD}\uparrow$	t$_{RDWD}$		40		ns
Write data output time from $\overline{WR}\downarrow$	t$_{WRWD}$		20	120	ns
Hold time from $\overline{WR}\uparrow$ to address	t$_{WRADH}$		0.8t$_{CY}$ – 30	1.2t$_{CY}$ + 60	ns
Delay time from $\overline{WAIT}\uparrow$ to $\overline{RD}\uparrow$	t$_{WTRD}$		0.5t$_{CY}$	2.5t$_{CY}$ + 50	ns
Delay time from $\overline{WAIT}\uparrow$ to $\overline{WR}\uparrow$	t$_{WTWR}$		0.5t$_{CY}$	2.5t$_{CY}$ + 50	ns

Remarks 1. t$_{CY}$ = T$_{CY}$/4

2. n indicates the number of waits.

3. C$_L$ = 100 pF (C$_L$ is the load capacitance of the AD0 to AD7, A8 to A15, $\overline{RD}$, $\overline{WR}$, $\overline{WAIT}$, and ASTB pins.)

(2) Read/write operation (T$_A$ = −40 to +85°C, V$_{DD}$ = 1.8 to 2.7 V)   **(3/3)**

Parameter	Symbol	Conditions	MIN.	MAX.	Unit
ASTB high-level width	t$_{ASTH}$		0.3t$_{CY}$		ns
Address setup time	t$_{ADS}$		120		ns
Address hold time	t$_{ADH}$		20		ns
Input time from address to data	t$_{ADD1}$			(2 + 2n)t$_{CY}$ − 233	ns
	t$_{ADD2}$			(3 + 2n)t$_{CY}$ − 240	ns
Output time from $\overline{RD}$↓ to address	t$_{RDAD}$		0	400	ns
Input time from $\overline{RD}$↓ to data	t$_{RDD1}$			(2 + 2n)t$_{CY}$ − 325	ns
	t$_{RDD2}$			(3 + 2n)t$_{CY}$ − 332	ns
Read data hold time	t$_{RDH}$		0		ns
$\overline{RD}$ low-level width	t$_{RDL1}$		(1.5 + 2n)t$_{CY}$ − 92		ns
	t$_{RDL2}$		(2.5 + 2n)t$_{CY}$ − 92		ns
Input time from $\overline{RD}$↓ to $\overline{WAIT}$↓	t$_{RDWT1}$			t$_{CY}$ − 350	ns
	t$_{RDWT2}$			t$_{CY}$ − 132	ns
Input time from $\overline{WR}$↓ to $\overline{WAIT}$↓	t$_{WRWT}$			t$_{CY}$ − 100	ns
$\overline{WAIT}$ low-level width	t$_{WTL}$		(0.5 + 2n)t$_{CY}$ + 10	(2 + 2n)t$_{CY}$	ns
Write data setup time	t$_{WDS}$		60		ns
Write data hold time	t$_{WDH}$		20		ns
$\overline{WR}$ low-level width	t$_{WRL1}$		(1.5 + 2n)t$_{CY}$ − 60		ns
Delay time from ASTB↓ to $\overline{RD}$↓	t$_{ASTRD}$		20		ns
Delay time from ASTB↓ to $\overline{WR}$↓	t$_{ASTWR}$		2t$_{CY}$ − 60		ns
Delay time from $\overline{RD}$↑ to ASTB↑ in external fetch	t$_{RDAST}$		0.8t$_{CY}$ − 60	1.2t$_{CY}$	ns
Hold time from $\overline{RD}$↑ to address in external fetch	t$_{RDADH}$		0.8t$_{CY}$ − 60	1.2t$_{CY}$ + 120	ns
Write data output time from $\overline{RD}$↑	t$_{RDWD}$		40		ns
Write data output time from $\overline{WR}$↓	t$_{WRWD}$		40	240	ns
Hold time from $\overline{WR}$↑ to address	t$_{WRADH}$		0.8t$_{CY}$ − 60	1.2t$_{CY}$ + 120	ns
Delay time from $\overline{WAIT}$↑ to $\overline{RD}$↑	t$_{WTRD}$		0.5t$_{CY}$	2.5t$_{CY}$ + 100	ns
Delay time from $\overline{WAIT}$↑ to $\overline{WR}$↑	t$_{WTWR}$		0.5t$_{CY}$	2.5t$_{CY}$ + 100	ns

Remarks 1. t$_{CY}$ = T$_{CY}$/4

         2. n indicates the number of waits.

         3. C$_L$ = 100 pF (C$_L$ is the load capacitance of the AD0 to AD7, A8 to A15, $\overline{RD}$, $\overline{WR}$, $\overline{WAIT}$, and ASTB pins.)

(3) Serial interface (T_A = –40 to +85°C, V_{DD} = 1.8 to 5.5 V)

(a) 3-wire serial I/O mode ($\overline{\text{SCK3n}}$... internal clock output)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
$\overline{\text{SCK3n}}$ cycle time	t_{KCY1}	4.0 V ≤ V_{DD} ≤ 5.5 V	954			ns
		2.7 V ≤ V_{DD} < 4.0 V	1,600			ns
			3,200			ns
$\overline{\text{SCK3n}}$ high-/low-level width	t_{KH1} t_{KL1}	V_{DD} = 4.0 to 5.5 V	$t_{KCY1}/2 - 50$			ns
			$t_{KCY1}/2 - 100$			ns
SI3n setup time (to $\overline{\text{SCK3n}}$↑)	t_{SIK1}	4.0 V ≤ V_{DD} ≤ 5.5 V	100			ns
		2.7 V ≤ V_{DD} < 4.0 V	150			ns
			300			ns
SI3n hold time (from $\overline{\text{SCK3n}}$↑)	t_{KSI1}		400			ns
Output delay time from $\overline{\text{SCK3n}}$↓ to SO3n	t_{KSO1}	C = 100 pF**Note**			300	ns

Note C is the load capacitance of the $\overline{\text{SCK3n}}$ and SO3n output lines.

(b) 3-wire serial I/O mode ($\overline{\text{SCK3n}}$... external clock input)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
$\overline{\text{SCK3n}}$ cycle time	t_{KCY2}	4.0 V ≤ V_{DD} ≤ 5.5 V	800			ns
		2.7 V ≤ V_{DD} < 4.0 V	1,600			ns
			3,200			ns
$\overline{\text{SCK3n}}$ high-/low-level width	t_{KH2} t_{KL2}	4.0 V ≤ V_{DD} ≤ 5.5 V	400			ns
		2.7 V ≤ V_{DD} < 4.0 V	800			ns
			1,600			ns
SI3n setup time (to $\overline{\text{SCK3n}}$↑)	t_{SIK2}		100			ns
SI3n hold time (from $\overline{\text{SCK3n}}$↑)	t_{KSI2}		400			ns
Output delay time from $\overline{\text{SCK3n}}$↓ to SO3n	t_{KSO2}	C = 100 pF**Note**			300	ns

Note C is the load capacitance of the SO3n output line.

Remark μPD78F0034A: n = 0, 1
         μPD78F0034AY: n = 0

(c) UART mode (dedicated baud rate generator output)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Transfer rate		4.0 V ≤ V_{DD} ≤ 5.5 V			131,031	bps
		2.7 V ≤ V_{DD} < 4.0 V			78,125	bps
					39,063	bps

(d) UART mode (external clock input)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
ASCK0 cycle time	t_{KCY3}	4.0 V ≤ V_{DD} ≤ 5.5 V	800			ns
		2.7 V ≤ V_{DD} < 4.0 V	1,600			ns
			3,200			ns
ASCK0 high-/low-level width	t_{KH3}, t_{KL3}	4.0 V ≤ V_{DD} ≤ 5.5 V	400			ns
		2.7 V ≤ V_{DD} < 4.0 V	800			ns
			1,600			ns
Transfer rate		4.0 V ≤ V_{DD} ≤ 5.5 V			39,063	bps
		2.7 V ≤ V_{DD} < 4.0 V			19,531	bps
					9,766	bps

(e) UART mode (infrared data transfer mode)

Parameter	Symbol	Conditions	MIN.	MAX.	Unit
Transfer rate		V_{DD} = 4.0 to 5.5 V		131,031	bps
Bit rate allowable error		V_{DD} = 4.0 to 5.5 V		±0.87	%
Output pulse width		V_{DD} = 4.0 to 5.5 V	1.2	0.24/fbr[Note]	μs
Input pulse width		V_{DD} = 4.0 to 5.5 V	4/f_X		μs

Note fbr: Specified baud rate

(f) I^{2}C bus Mode (μPD78F0034AY only)

Parameter		Symbol	Standard Mode		High-Speed Mode		Unit
			MIN.	MAX.	MIN.	MAX.	
SCL0 clock frequency		f_{CLK}	0	100	0	400	kHz
Bus free time (between stop and start condition)		t_{BUF}	4.7	–	1.3	–	μs
Hold time[Note 1]		$t_{HD:STA}$	4.0	–	0.6	–	μs
SCL0 clock low-level width		t_{LOW}	4.7	–	1.3	–	μs
SCL0 clock high-level width		t_{HIGH}	4.0	–	0.6	–	μs
Start/restart condition setup time		$t_{SU:STA}$	4.7	–	0.6	–	μs
Data hold time	CBUS compatible master	$t_{HD:DAT}$	5.0	–	–	–	μs
	I^{2}C bus		0[Note 2]	–	0[Note 2]	0.9[Note 3]	μs
Data setup time		$t_{SU:DAT}$	250	–	100[Note 4]	–	ns
SDA0 and SCL0 signal rise time		t_R	–	1,000	20 + 0.1Cb[Note 5]	300	ns
SDA0 and SCL0 signal fall time		t_F	–	300	20 + 0.1Cb[Note 5]	300	ns
Stop condition setup time		$t_{SU:STO}$	4.0	–	0.6	–	μs
Spike pulse width controlled by input filter		t_{SP}	–	–	0	50	ns
Capacitive load per each bus line		Cb	–	400	–	400	pF

Notes 1. In the start condition, the first clock pulse is generated after this hold time.

2. To fill in the undefined area of the SCL0 falling edge, it is necessary for the device to internally provide at least 300 ns of hold time for the SDA0 signal (which is $V_{IHmin.}$ of the SCL0 signal).

3. If the device does not extend the SCL0 signal low hold time (t_{LOW}), only maximum data hold time $t_{HD:DAT}$ needs to be fulfilled.

4. The high-speed mode I^{2}C bus is available in a standard mode I^{2}C bus system. At this time, the conditions described below must be satisfied.
  • If the device does not extend the SCL0 signal low state hold time
    $t_{SU:DAT} \geq$ 250 ns
  • If the device extends the SCL0 signal low state hold time
    Be sure to transmit the next data bit to the SDA0 line before the SCL0 line is released ($t_{Rmax.}$ + $t_{SU:DAT}$ = 1,000 + 250 = 1,250 ns by standard mode I^{2}C bus specification).

5. Cb: Total capacitance per one bus line (unit: pF)

AC Timing Measurement Point (Excluding X1, XT1 Input)

Clock Timing

X1 input

TI Timing

TI00, TI01

TI50, TI51
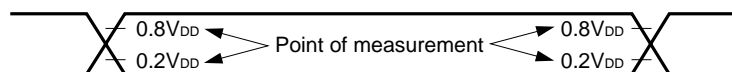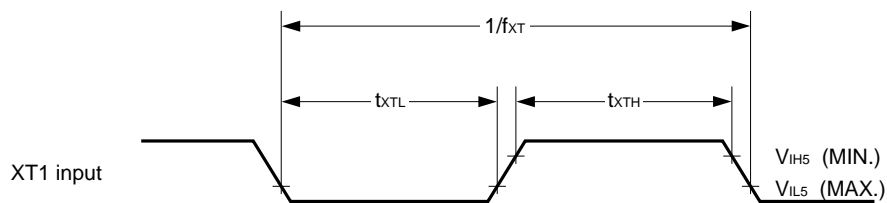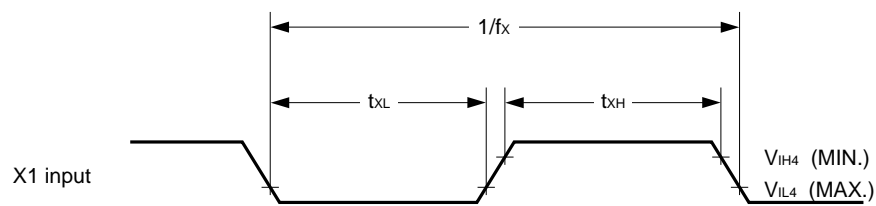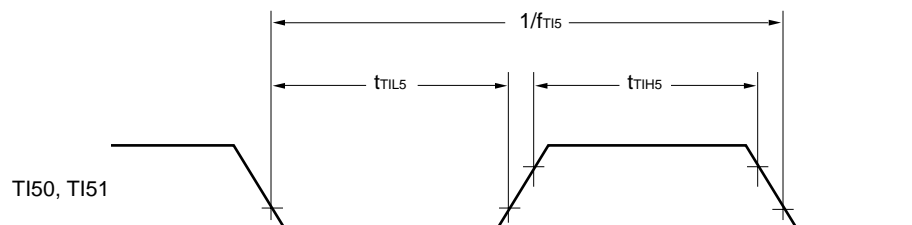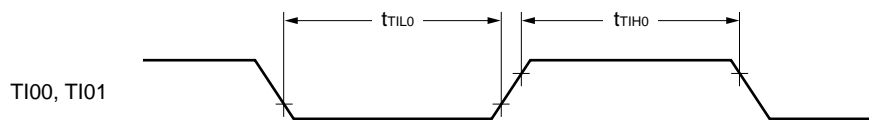
Interrupt Request Input Timing

INTP0 to INTP2

t_{INTL} t_{INTH}

INTP3

t_{INTL}
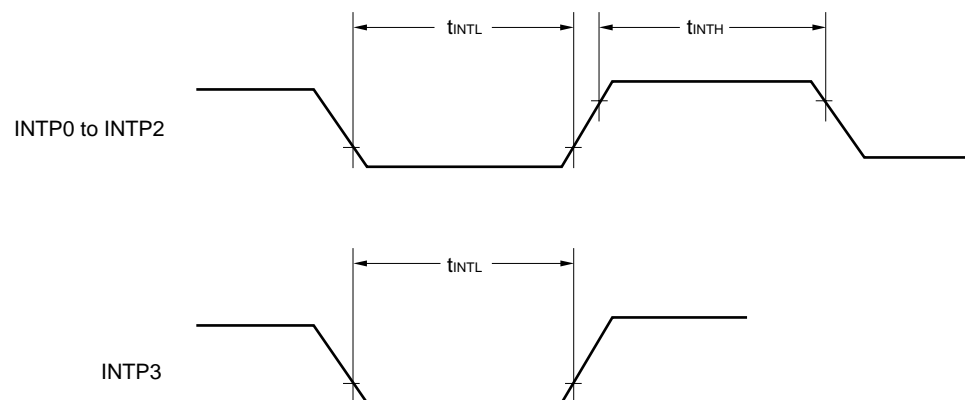
RESET Input Timing

RESET

t_{RSL}
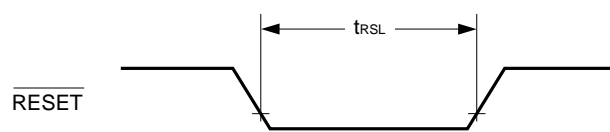
Read/Write Operation

External fetch (no wait):
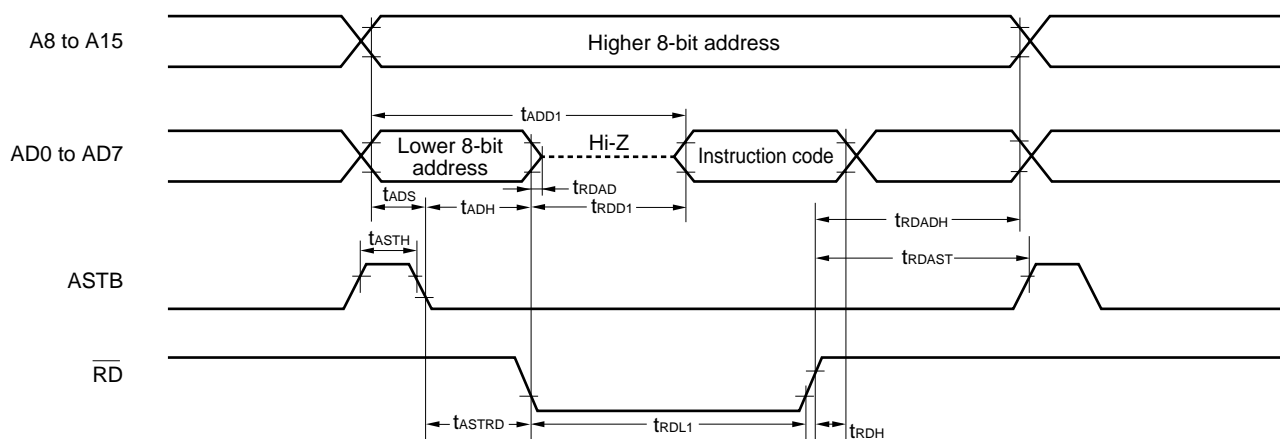
External fetch (wait insertion):
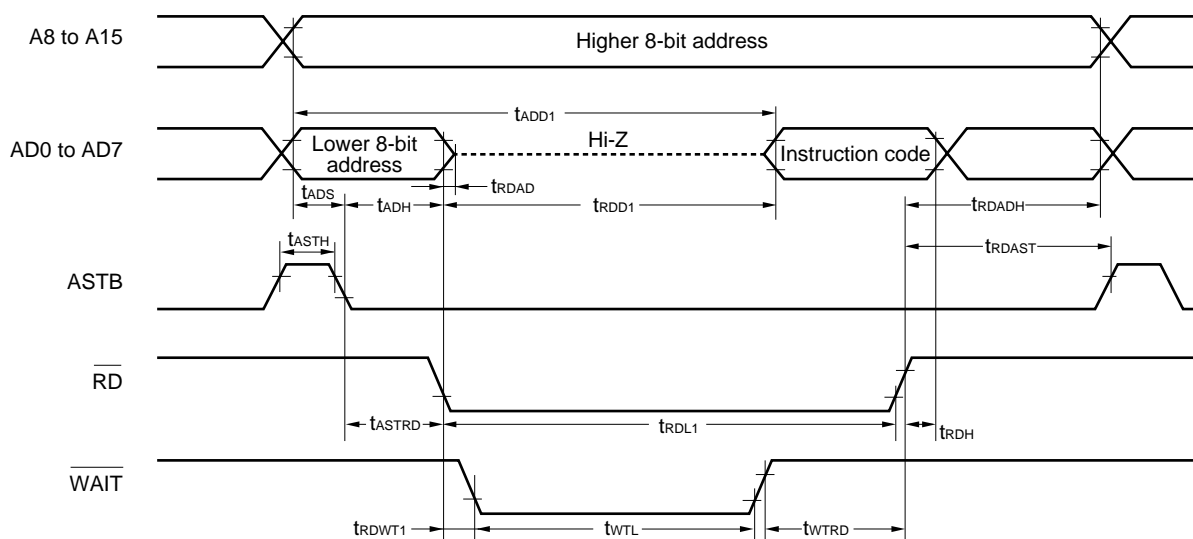
External data access (no wait):
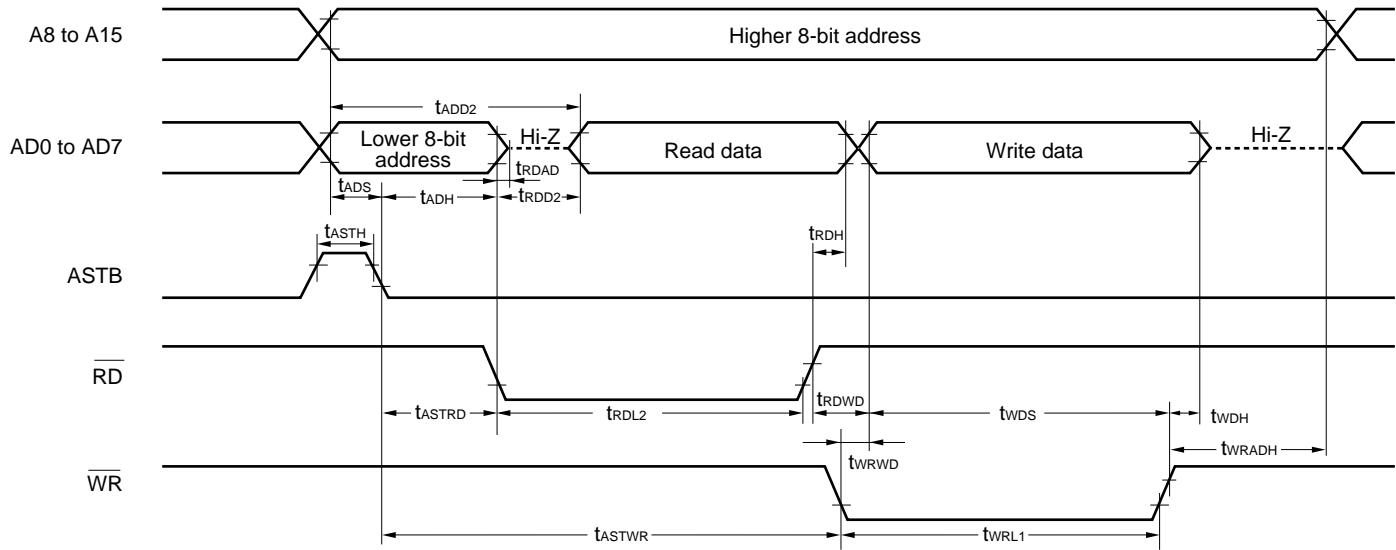
External data access (wait insertion):
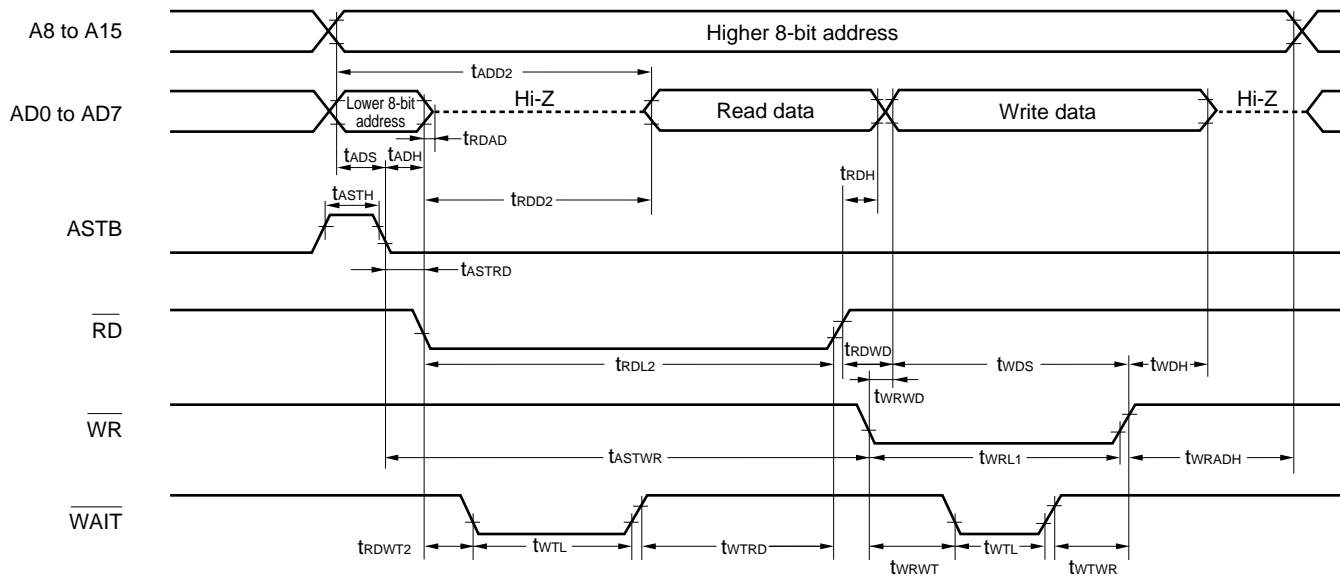
Serial Transfer Timing

3-wire serial I/O mode:
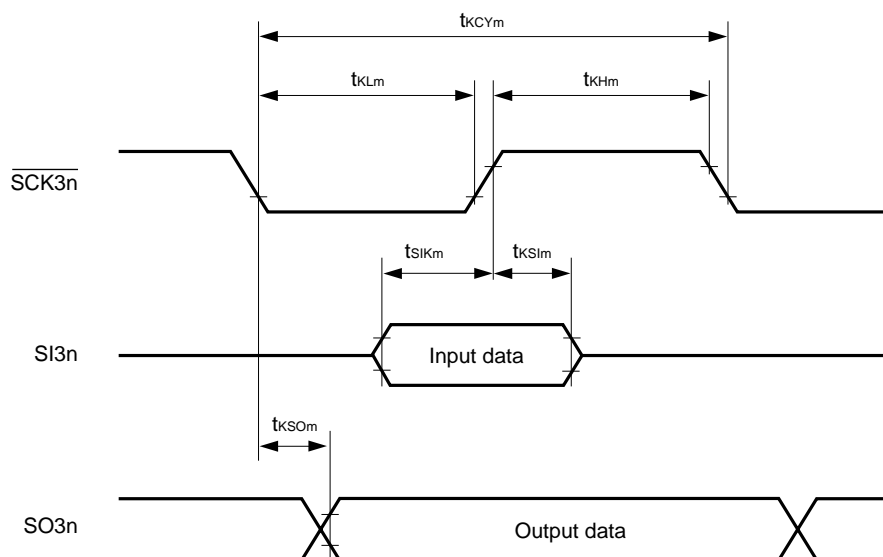
Remarks 1. m = 1, 2
   2. μPD78F0034A: n = 0, 1
   3. μPD78F0034AY: n = 0

UART mode (external clock input):
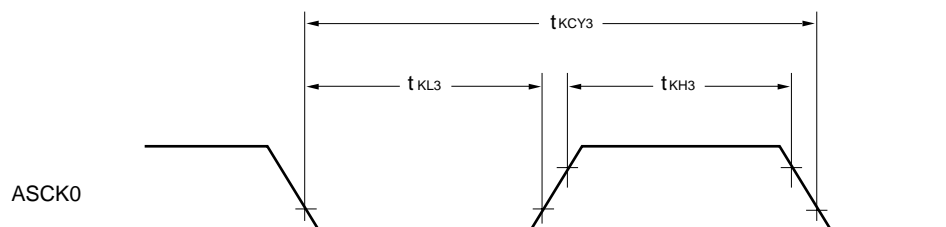
I^{2}C bus mode (μPD78F0034AY only):
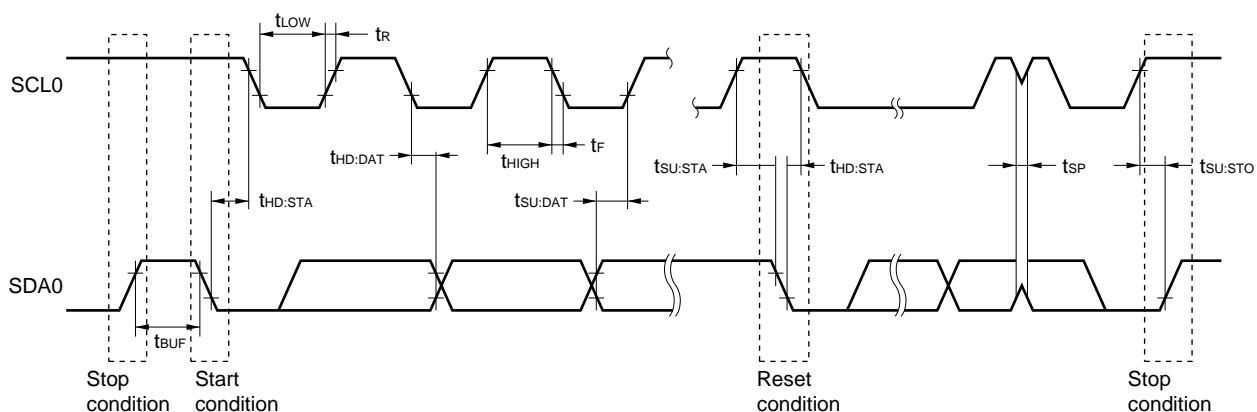
A/D Converter Characteristics (T$_A$ = –40 to +85°C, V$_{DD}$ = AV$_{DD}$ = AV$_{REF}$ = 1.8 to 5.5 V, AV$_{SS}$ = V$_{SS}$ = 0 V)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Resolution			10	10	10	bit
Overall error[Note]		4.0 V ≤ AV$_{REF}$ ≤ 5.5 V		±0.2	±0.4	%FSR
		2.7 V ≤ AV$_{REF}$ < 4.0 V		±0.3	±0.6	%FSR
		1.8 V ≤ AV$_{REF}$ < 2.7 V		±0.6	±1.2	%FSR
Conversion time	t$_{CONV}$	4.0 V ≤ AV$_{REF}$ ≤ 5.5 V	14		96	μs
		2.7 V ≤ AV$_{REF}$ < 4.0 V	19		96	μs
		1.8 V ≤ AV$_{REF}$ < 2.7 V	28		96	μs
Zero-scale error[Notes 1, 2]		4.0 V ≤ AV$_{REF}$ ≤ 5.5 V			±0.4	%FSR
		2.7 V ≤ AV$_{REF}$ < 4.0 V			±0.6	%FSR
		1.8 V ≤ AV$_{REF}$ < 2.7 V			±1.2	%FSR
Full-scale error[Notes 1, 2]		4.0 V ≤ AV$_{REF}$ ≤ 5.5 V			±0.4	%FSR
		2.7 V ≤ AV$_{REF}$ < 4.0 V			±0.6	%FSR
		1.8 V ≤ AV$_{REF}$ < 2.7 V			±1.2	%FSR
Integral linearity error[Note 1]		4.0 V ≤ AV$_{REF}$ ≤ 5.5 V			±2.5	LSB
		2.7 V ≤ AV$_{REF}$ < 4.0 V			±4.5	LSB
		1.8 V ≤ AV$_{REF}$ < 2.7 V			±8.5	LSB
Differential linearity error		4.0 V ≤ AV$_{REF}$ ≤ 5.5 V			±1.5	LSB
		2.7 V ≤ AV$_{REF}$ ≤ 4.0 V			±2.0	LSB
		1.8 V ≤ AV$_{REF}$ < 2.7 V			±3.5	LSB
Analog input voltage	V$_{IAN}$		0		AV$_{REF}$	V
Reference voltage	AV$_{REF}$		1.8		AV$_{DD}$	V
Resistance between AV$_{REF}$ and AV$_{SS}$	R$_{REF}$	A/D conversion is not performed	20	40		kΩ

Notes 1. Excluding quantization error (±1/2 LSB).

2. Indicated as a ratio to the full-scale value (%FSR).

Remark When the μPD78F0034A or 78F0034AY is used as an 8-bit resolution A/D converter, the specifications are the same as for the μPD780024A or 78F0024AY Subseries A/D converter.

Data Memory STOP Mode Low Supply Voltage Data Retention Characteristics (T$_A$ = –40 to +85°C)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Data retention supply voltage	V$_{DDDR}$		1.6		5.5	V
Data retention supply current	I$_{DDDR}$	V$_{DDDR}$ = 1.6 V Subsystem clock stop (XT1 = V$_{DD}$) and feed-back resistor disconnected		0.1	30	μA
Release signal set time	t$_{SREL}$		0			μs
Oscillation stabilization wait time	t$_{WAIT}$	Release by $\overline{RESET}$		$2^{17}/f_X$		s
		Release by interrupt request		**Note**		s

Note Selection of $2^{12}/f_X$ and $2^{14}/f_X$ to $2^{17}/f_X$ is possible using bits 0 to 2 (OSTS0 to OSTS2) of the oscillation stabilization time select register (OSTS).

Data Retention Timing (STOP Mode Release by $\overline{\text{RESET}}$)
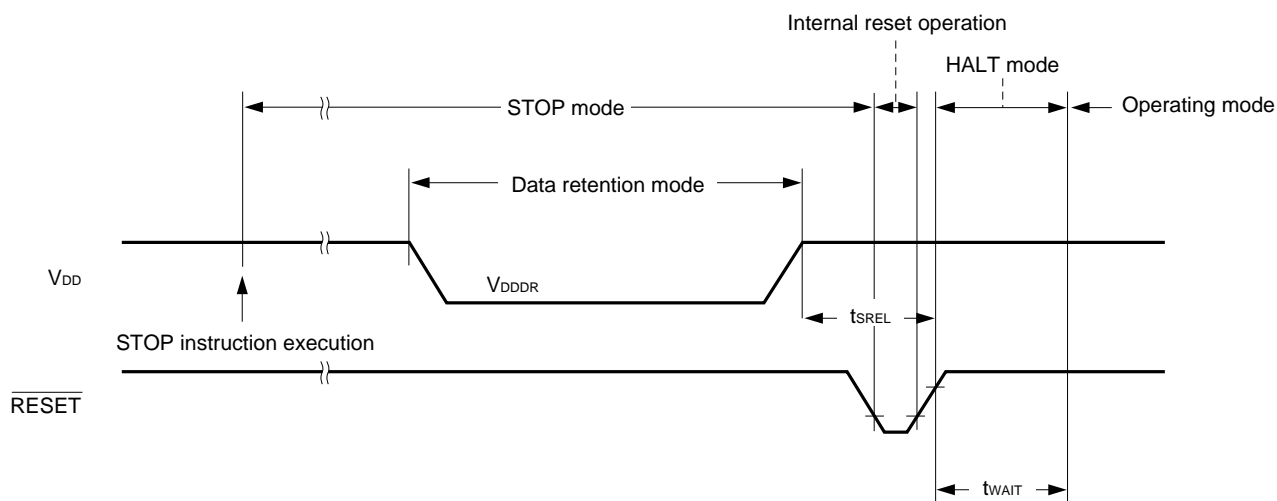
Data Retention Timing (Standby Release Signal: STOP Mode Release by Interrupt Request Signal)
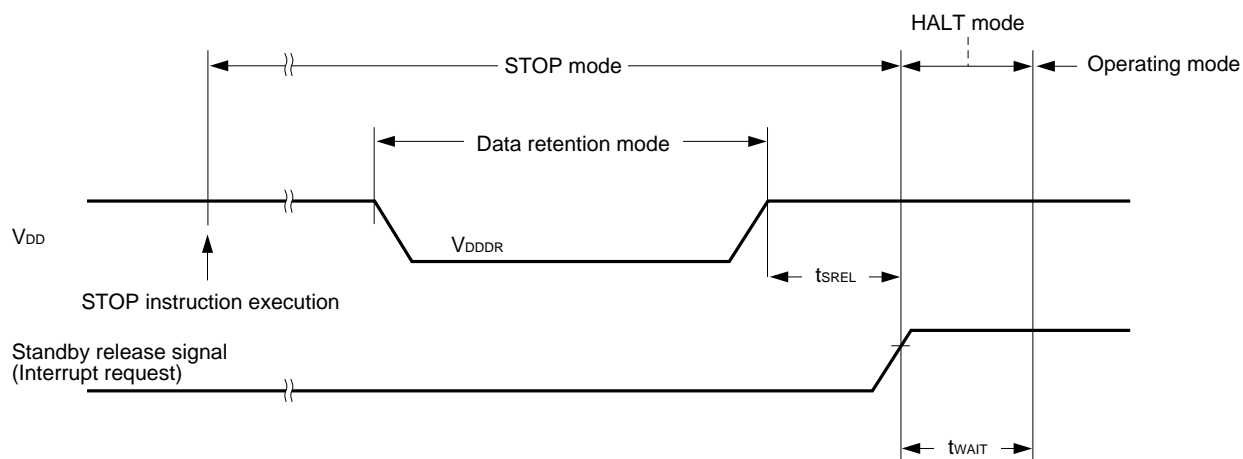
Flash Memory Programming Characteristics (V_{DD} = 2.7 to 5.5 V, V_{SS} = 0 V, V_{PP} = 9.7 to 10.3 V)

(1) Basic characteristics

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Operating frequency	f_X	$4.0 \leq V_{DD} \leq 5.5$ V	1.0		8.38	MHz
		$2.7 \leq V_{DD} < 4.0$ V	1.0		5.0	MHz
Supply voltage	V_{DD}	Operation voltage when writing	2.7		5.5	V
	V_{PPL}	Upon V_{PP} low-level detection	0		$0.2V_{DD}$	V
	V_{PP}	Upon V_{PP} high-level detection	$0.8V_{DD}$	V_{DD}	$1.2V_{DD}$	V
	V_{PPH}	Upon V_{PP} high-voltage detection	9.7[Note 1]	10.0[Note 1]	10.3[Note 1]	V
V_{DD} supply current	I_{DD}				10	mA
V_{PP} supply current	I_{PP}	V_{PP} =10.0 V		75	100	mA
Write time (per byte)	T_{WRT}		50		500	μs
Number of rewrites	C_{WRT}				20[Note 2]	Times
Erase time	T_{ERASE}		1		20	s
Programming temperature	T_{PRG}		+10		+40	°C

Notes 1. For the product grades "K, E, and P", 10.2 V (MIN.), 10.3 V (TYP.), and 10.4 V (MAX.), are applied.
2. For the product specification "K and E", the number is 1 (MAX.).

(2) Serial write operation characteristics

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
V_{PP} set time	t_{PSRON}	V_{PP} high voltage	1.0			μs
Set time from $V_{DD}\uparrow$ to $V_{PP}\uparrow$	t_{DRPSR}	V_{PP} high voltage	1.0			μs
Set time from $V_{PP}\uparrow$ to $\overline{RESET}\uparrow$	t_{PSRRF}	V_{PP} high voltage	1.0			μs
V_{PP} count start time from $\overline{RESET}\uparrow$	t_{RFCF}		1.0			μs
Count execution time	t_{COUNT}				2.0	ms
V_{PP} counter high-level width	t_{CH}		8.0			μs
V_{PP} counter low-level width	t_{CL}		8.0			μs
V_{PP} counter noise elimination width	t_{NFW}			40		ns

Flash Memory Write Mode Set Timing
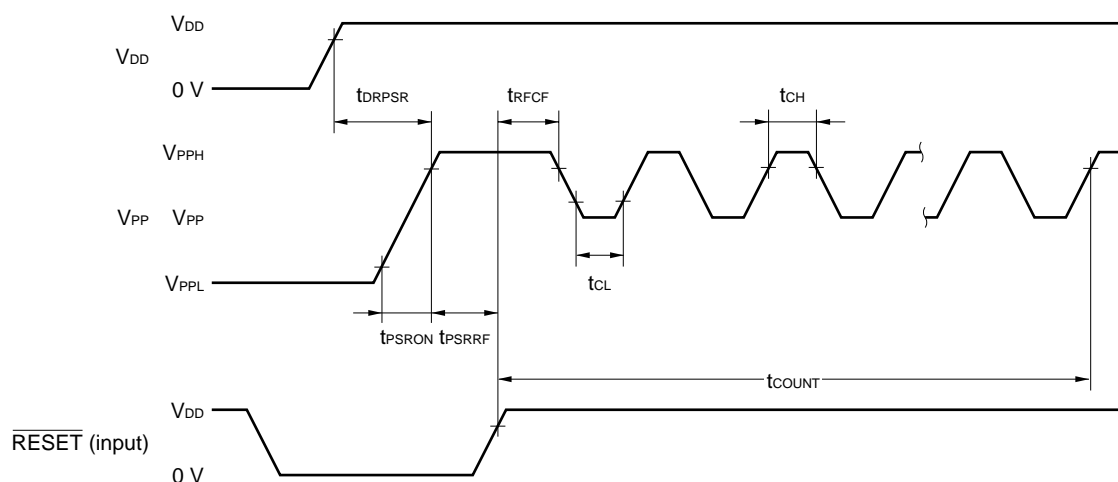
8. PACKAGE DRAWINGS

64-PIN PLASTIC SDIP (19.05mm(750))
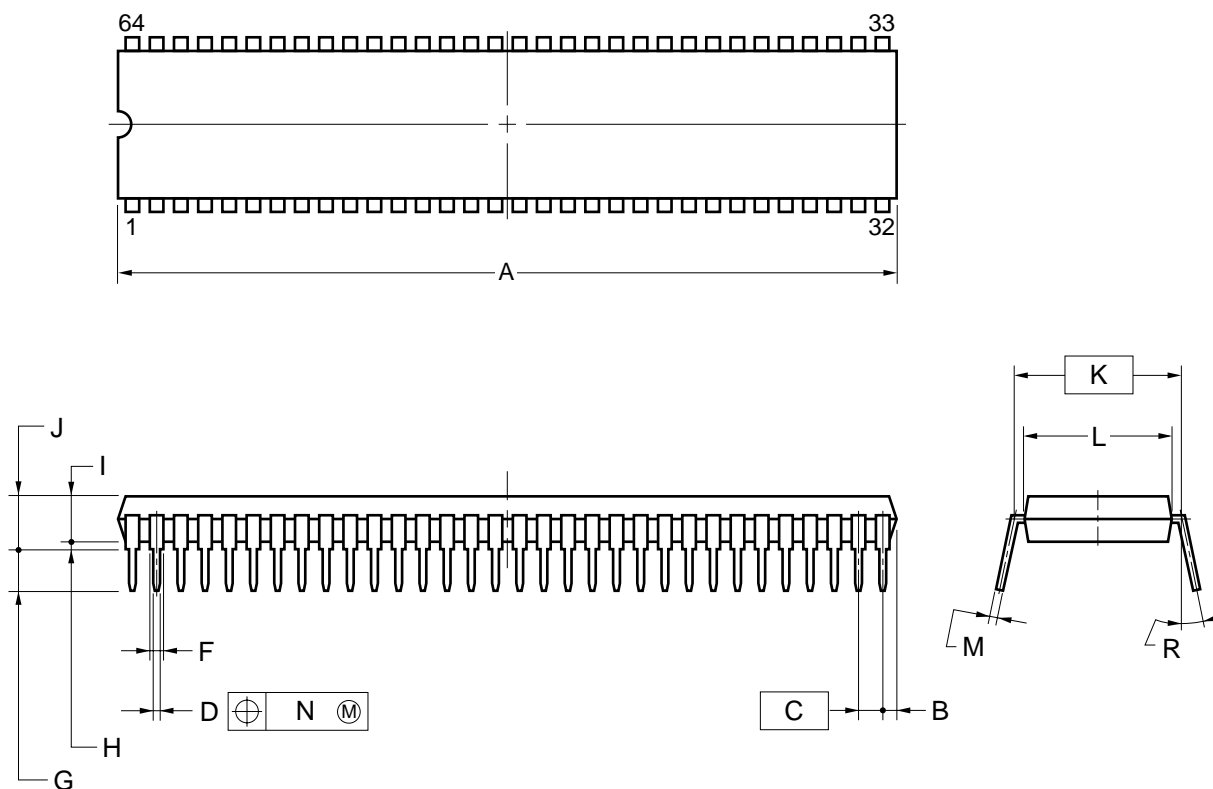
NOTES

1. Each lead centerline is located within 0.17 mm of
   its true position (T.P.) at maximum material condition.

2. Item "K" to center of leads when formed parallel.

ITEM	MILLIMETERS
A	$58.0^{+0.68}_{-0.20}$
B	1.78 MAX.
C	1.778 (T.P.)
D	0.50±0.10
F	0.9 MIN.
G	3.2±0.3
H	0.51 MIN.
I	$4.05^{+0.26}_{-0.20}$
J	5.08 MAX.
K	19.05 (T.P.)
L	17.0±0.2
M	$0.25^{+0.10}_{-0.05}$
N	0.17
R	0 ~ 15°

P64C-70-750A,C-4

Remark The package and material of ES products are the same as mass produced products.

64-PIN PLASTIC QFP (14x14)

detail of lead end
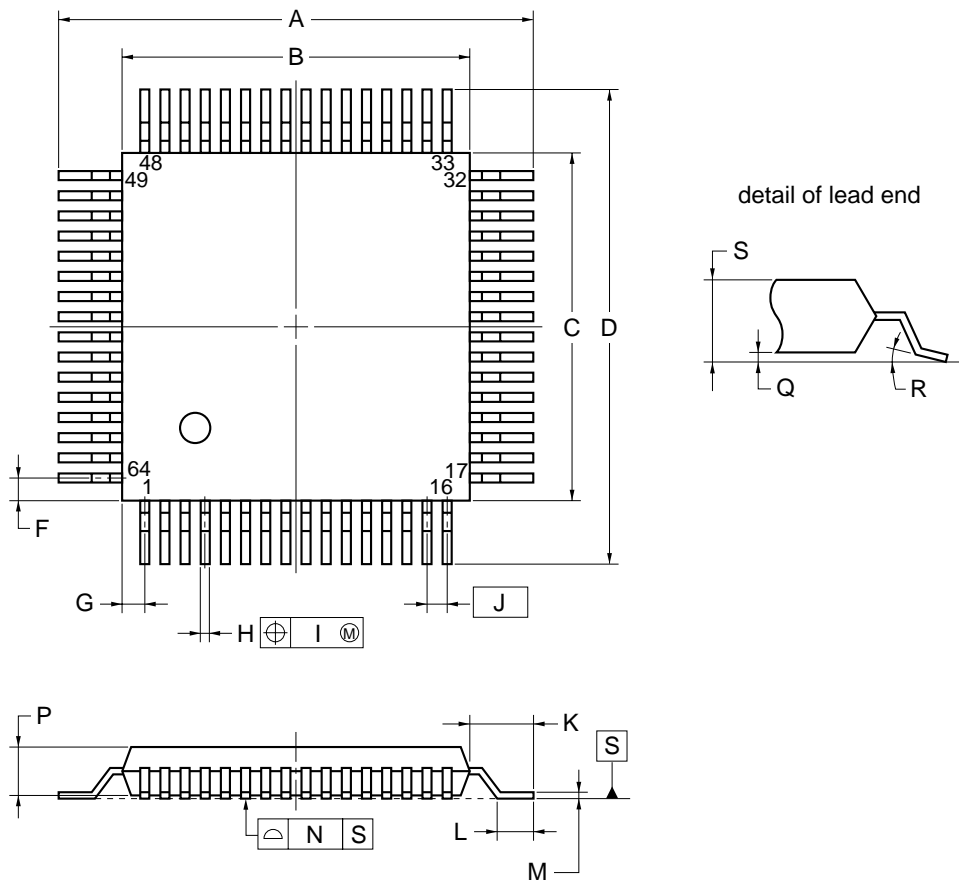
NOTE

Each lead centerline is located within 0.15 mm of
its true position (T.P.) at maximum material condition.

ITEM	MILLIMETERS
A	17.6±0.4
B	14.0±0.2
C	14.0±0.2
D	17.6±0.4
F	1.0
G	1.0
H	$0.37^{+0.08}_{-0.07}$
I	0.15
J	0.8 (T.P.)
K	1.8±0.2
L	0.8±0.2
M	$0.17^{+0.08}_{-0.07}$
N	0.10
P	2.55±0.1
Q	0.1±0.1
R	5°±5°
S	2.85 MAX.

P64GC-80-AB8-5

Remark The package and material of ES products are the same as mass produced products.

64-PIN PLASTIC LQFP (12x12)
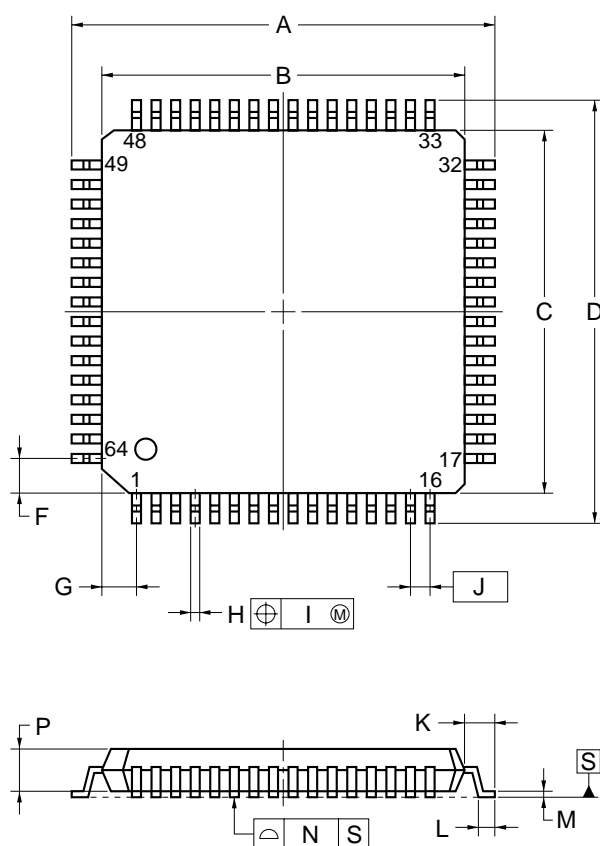
detail of lead end
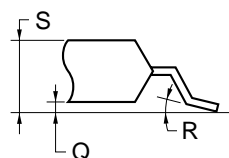
NOTE

Each lead centerline is located within 0.13 mm of
its true position (T.P.) at maximum material condition.

ITEM	MILLIMETERS
A	14.8±0.4
B	12.0±0.2
C	12.0±0.2
D	14.8±0.4
F	1.125
G	1.125
H	0.32±0.08
I	0.13
J	0.65 (T.P.)
K	1.4±0.2
L	0.6±0.2
M	$0.17^{+0.08}_{-0.07}$
N	0.10
P	1.4±0.1
Q	0.125±0.075
R	5°±5°
S	1.7 MAX.

P64GK-65-8A8-3

Remark The package and material of ES products are the same as mass produced products.

64-PIN PLASTIC TQFP (12x12)
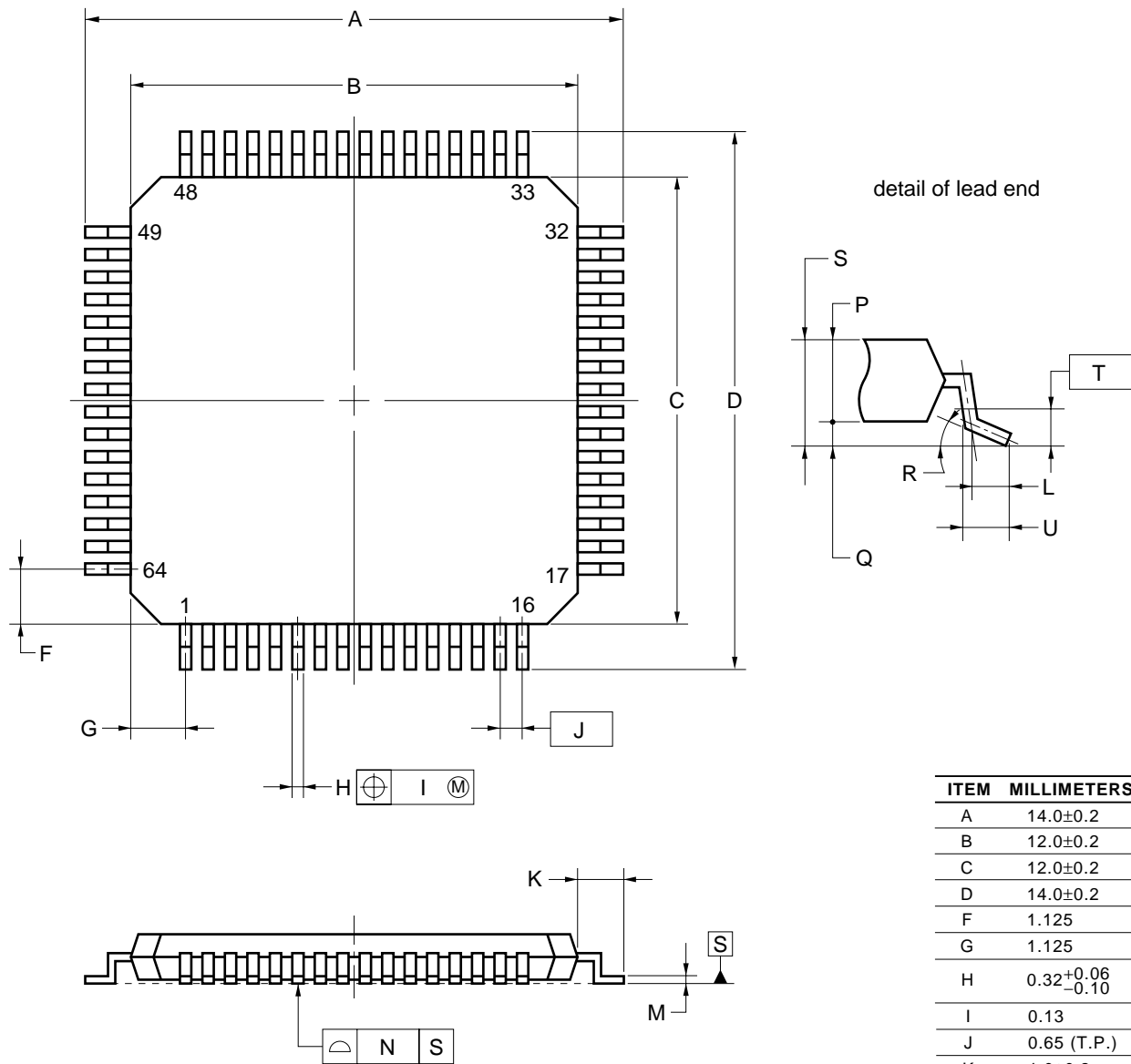
detail of lead end

ITEM	MILLIMETERS
A	14.0±0.2
B	12.0±0.2
C	12.0±0.2
D	14.0±0.2
F	1.125
G	1.125
H	$0.32^{+0.06}_{-0.10}$
I	0.13
J	0.65 (T.P.)
K	1.0±0.2
L	0.5
M	$0.17^{+0.03}_{-0.07}$
N	0.10
P	1.0
Q	0.1±0.05
R	$3°^{+4°}_{-3°}$
S	1.1±0.1
T	0.25
U	0.6±0.15

P64GK-65-9ET-2

NOTE

Each lead centerline is located within 0.13 mm of
its true position (T.P.) at maximum material condition.

Remark The package and material of ES products are the same as mass produced products.

9. RECOMMENDED SOLDERING CONDITIONS

The μPD78F0034A, 78F0034AY should be soldered and mounted under the following recommended conditions.

For details of the recommended soldering conditions, refer to the document **Semiconductor Device Mounting Technology Manual (C10535E)**.

For soldering methods and conditions other than those recommended below, contact your NEC sales representative.

Table 9-1. Surface Mounting Type Soldering Conditions (1/2)

(1) μPD78F0034AGC-AB8: 64-pin plastic QFP (14 $\times$ 14)
μPD78F0034AYGC-AB8: 64-pin plastic QFP (14 $\times$ 14)

Soldering Method	Soldering Conditions	Recommended Condition Symbol
Infrared reflow	Package peak temperature: 235°C, Time: 30 seconds max. (at 210°C or higher), Count: Two times or less	IR35-00-2
VPS	Package peak temperature: 215°C, Time: 40 seconds max. (at 200°C or higher), Count: Two times or less	VP15-00-2
Wave soldering	Solder bath temperature: 260°C max., Time: 10 seconds max., Count: Once, Preheating temperature: 120°C max. (package surface temperature)	WS60-00-1
Partial heating	Pin temperature: 300°C max., Time: 3 seconds max. (per pin row)	–

Caution Do not use different soldering methods together (except for partial heating).

(2) μPD78F0034AGK-8A8: 64-pin plastic LQFP (12 $\times$ 12)
μPD78F0034AYGK-8A8: 64-pin plastic LQFP (12 $\times$ 12)

Soldering Method	Soldering Conditions	Recommended Condition Symbol
Infrared reflow	Package peak temperature: 235°C, Time: 30 seconds max. (at 210°C or higher), Count: Two times or less, Exposure limit: 7 days**Note** (after 7 days, prebake at 125°C for 10 hours)	IR35-107-2
VPS	Package peak temperature: 215°C, Time: 40 seconds max. (at 200°C or higher), Count: Two times or less, Exposure limit: 7 days**Note** (after 7 days, prebake at 125°C for 10 hours)	VP15-107-2
Wave soldering	Solder bath temperature: 260°C max., Time: 10 seconds max., Count: Once, Preheating temperature: 120°C max. (package surface temperature) Exposure limit: 7 days**Note** (after 7 days, prebake at 125°C for 10 hours)	WS60-107-1
Partial heating	Pin temperature: 300°C max., Time: 3 seconds max. (per pin row)	–

Note After opening the dry pack, store it at 25°C or less and 65% RH or less for the allowable storage period.

Caution Do not use different soldering methods together (except for partial heating).

<div align="center">**Table 9-1. Surface Mounting Type Soldering Conditions (2/2)**</div>

(3) μPD78F0034AGK-9ET: 64-pin plastic TQFP (12 $\times$ 12)
    μPD78F0034AYGK-9ET: 64-pin plastic TQFP (12 $\times$ 12)

Soldering Method	Soldering Conditions	Recommended Condition Symbol
Infrared reflow	Package peak temperature: 235°C, Time: 30 seconds max. (at 210°C or higher), Count: Two times or less, Exposure limit: 7 days**Note** (after 7 days, prebake at 125°C for 10 hours)	IR35-107-2
VPS	Package peak temperature: 215°C, Time: 40 seconds max. (at 200°C or higher), Count: Two times or less, Exposure limit: 7 days**Note** (after 7 days, prebake at 125°C for 10 hours)	VP15-107-2
Partial heating	Pin temperature: 300°C max., Time: 3 seconds max. (per pin row)	–

Note   After opening the dry pack, store it at 25°C or less and 65% RH or less for the allowable storage period.

Caution   Do not use different soldering methods together (except for partial heating).

<div align="center">**Table 9-2. Insertion Type Soldering Conditions**</div>

μPD78F0034ACW: 64-pin plastic SDIP (19.05 mm (750))
μPD78F0034AYCW: 64-pin plastic SDIP (19.05 mm (750))

Soldering Method	Soldering Conditions
Wave soldering (pin only)	Solder bath temperature: 260°C max., Time: 10 seconds max.
Partial heating	Pin temperature: 300°C max., Time: 3 seconds max. (per pin row)

Caution   Apply wave soldering only to the pins and be careful not to bring solder into direct contact with the package.

APPENDIX A. DEVELOPMENT TOOLS

The following development tools are available for system development using the μPD78F0034A, 78F0034AY Subseries.

Also refer to **(5) Cautions on Using Development Tools**.

(1) Language Processing Software

RA78K/0	Assembler package common to 78K/0 Series
CC78K/0	C compiler package common to 78K/0 Series
DF780034	Device file for μPD780034A, 78F0034AY Subseries
CC78K/0-L	C compiler library source file common to 78K/0 Series

(2) Flash Memory Writing Tools

Flashpro II (part No. FL-PR2), Flashpro III (part No. FL-PR3, PG-FP3)	Flash programmer dedicated to microcontrollers with on-chip flash memory
FA-64CW, FA-64GC, FA-64GK FA-64GK-9ET	Adapter for flash memory writing

(3) Debugging Tools
• When IE-78K0-NS in-circuit emulator is used

IE-78K0-NS	In-circuit emulator common to 78K/0 Series
IE-70000-MC-PS-B	Power supply unit for IE-78K0-NS
IE-78K0-NS-PA	Performance board that enhances and expands the IE-78K0-NS functions
IE-70000-98-IF-C	Adapter required when using PC-9800 series PC (except notebook type) as host machine (C bus supported)
IE-70000-CD-IF-A	PC card and interface cable when using PC-9800 series notebook PC as host machine (PCMCIA socket supported)
IE-70000-PC-IF-C	Adapter required when using IBM PC/AT™ or compatible as host machine (ISA bus supported)
IE-70000-PCI-IF	Adapter necessary when using PC in which PCI bus is incorporated as host machine
IE-780034-NS-EM1	Emulation board to emulate the μPD780034A, 78F0034AY Subseries
NP-64CW	Emulation probe for 64-pin plastic SDIP (CW type)
NP-64GC NP-64GC-9ET	Emulation probe for 64-pin plastic QFP (CG-AB8 type)
NP-64GK	Emulation probe for 64-pin plastic LQFP (CG-8A8 type) and 64-pin plastic TQFP (GK-9ET type)
EV-9200GC-64	Conversion socket to connect the NP-64GC and a target system board on which a 64-pin plastic QFP (GC-AB8 type) can be mounted
TGC-064SAP	Conversion adapter to connect the NP-64GC-TQ and a target system board on which a 64-pin plastic QFP (GC-AB8 type) can be mounted
TGK-064SBW	Conversion adapter to connect the NP-64GK and a target system board on which a 64-pin plastic LQFP (GC-8A8 type) can be mounted
TGK-064SBP	Conversion adapter to connect the NP-64GK and a target system board on which a 64-pin plastic TQFP (GK-9ET type) can be mounted
ID78K0-NS	Integrated debugger for IE-78K0-NS
SM78K0	System simulator common to 78K/0 Series
DF780034	Device file for μPD780034A, 78F0034AY Subseries

• **When using in-circuit emulator IE-78001-R-A**

IE-78001-R-A	In-circuit emulator common to 78K/0 Series
IE-70000-98-IF-C	Adapter required when using PC-9800 series as host machine (excluding notebook PCs) (C bus supported)
IE-70000-PC-IF-C	Adapter required when using IBM PC/AT or compatible as host machine (ISA bus supported)
IE-70000-PCI-IF	Adapter required when using PC in which PCI bus is incorporated as host machine
IE-78000-R-SV3	Interface adapter and cable when using EWS as host machine
IE-780034-NS-EM1	Emulation board to emulate μPD780034A, 78F0034AY Subseries
IE-78K0-R-EX1	Emulation probe conversion board to use IE-780034-NS-EM1 on IE-78001-R-A
EP-78240CW-R	Emulation probe for 64-pin plastic SDIP (CW type)
EP-78240GC-R	Emulation probe for 64-pin plastic QFP (GC-AB8 type)
EP-78012GK-R	Emulation probe for 64-pin plastic LQFP (GK-8A8 type) and 64-pin plastic TQFP (GK-9ET type)
EV-9200GC-64	Conversion socket to connect the EP-78240GC-R and a target system board on which a 64-pin plastic QFP (GC-AB8 type) can be mounted
TGK-064SBW	Conversion adapter to connect the NP-64GK and a target system board designed on which a 64-pin plastic LQFP (GK-8A8) can be mounted
TGK-064SBP	Conversion adapter to connect the EP-78012GK-R and a target system board on which a 64-pin plastic TQFP (GK-9ET type) can be mounted
ID78K0	Integrated debugger for IE-78001-R-A
SM78K0	System simulator common to 78K/0 Series
DF780034	Device file for μPD780034A, 78F0034AY Subseries

(4) Real-Time OS

RX78K/0	Real-time OS for 78K/0 Series
MX78K0	OS for 78K/0 Series

(5) Cautions on Using Development Tools

- The ID-78K0-NS, ID78K0, and SM78K0 are used in combination with the DF780034.
- The CC78K0 and RX78K/0 are used in combination with the RA78K0 and the DF780034.
- The FL-PR2, FL-PR3, FA-64CW, FA-64GC, FA64GK, FA-64GK-9ET, NP-64CW, NP64GC, and NP-64GK are products made by Naito Densei Machida Mfg. Co., Ltd. (+81-44-822-3813).
  Contact an NEC distributor regarding the purchase of these products.
- The TGK-064SBW, TGC-064SAP, and TGK-064-SBP are products made by TOKYO ELETECH CORPORATION. For further information contact Daimaru Kogyo, Ltd.

  <div align="center">Tokyo Electronic Division (+81-3-3820-7112)</div>
  <div align="center">Osaka Electronic Division (+81-6-6244-6672)</div>

- For third party development tools, see the **Single-Chip Microcontroller Selection Guide (U11069E)**.
- The host machines and OSs supporting each software are as follows.

Host Machine [OS] Software	PC PC-9800 series [Windows^{TM}] IBM PC/AT or compatibles [Japanese/English Windows]	EWS HP9000 series 700^{TM} [HP-UX^{TM}] SPARCstation^{TM} [SunOS^{TM}, Solaris^{TM}] NEWS^{TM} (RISC) [NEWS-OS^{TM}]
RA78K0	√**Note**	√
CC78K0	√**Note**	√
ID78K0-NS	√	–
ID78K0	√	√
SM78K0	√	–
RX78K/0	√**Note**	√
MX78K0	√**Note**	√

Note DOS-based software

Conversion Socket Drawing (EV-9200GC-64) and Footprints

Figure A-1. EV-9200GC-64 Drawing (For Reference Only)
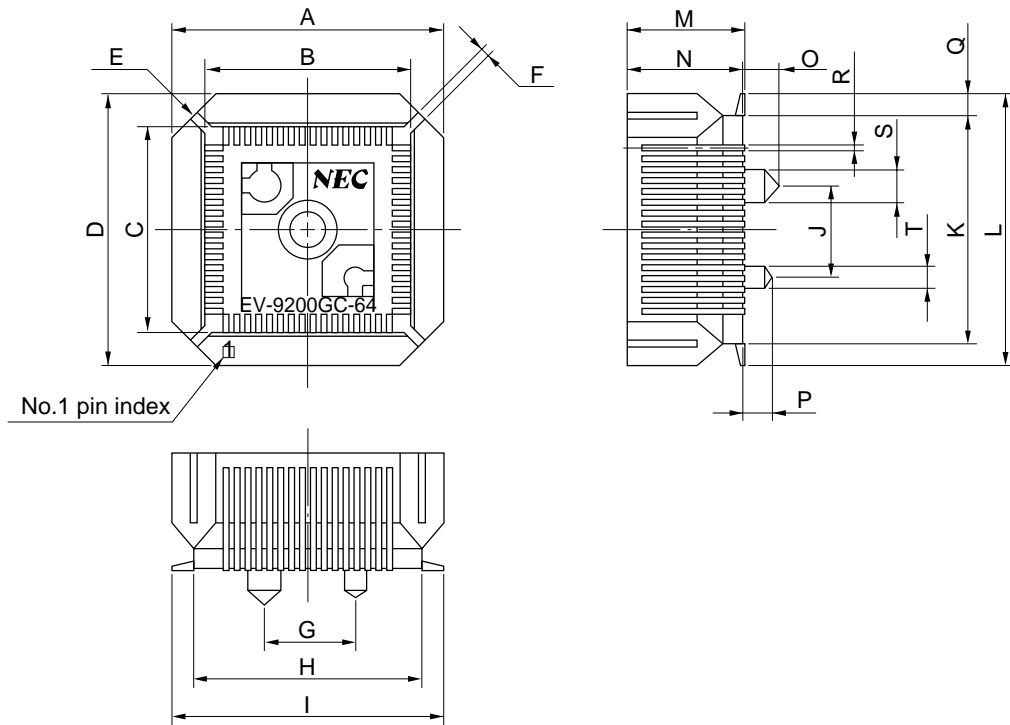
EV-9200GC-64-G0

ITEM	MILLIMETERS	INCHES
A	18.8	0.74
B	14.1	0.555
C	14.1	0.555
D	18.8	0.74
E	4-C 3.0	4-C 0.118
F	0.8	0.031
G	6.0	0.236
H	15.8	0.622
I	18.5	0.728
J	6.0	0.236
K	15.8	0.622
L	18.5	0.728
M	8.0	0.315
N	7.8	0.307
O	2.5	0.098
P	2.0	0.079
Q	1.35	0.053
R	0.35±0.1	$0.014^{+0.004}_{-0.005}$
S	ϕ2.3	ϕ0.091
T	ϕ1.5	ϕ0.059

Figure A-2. EV-9200GC-64 Footprints (For Reference Only)
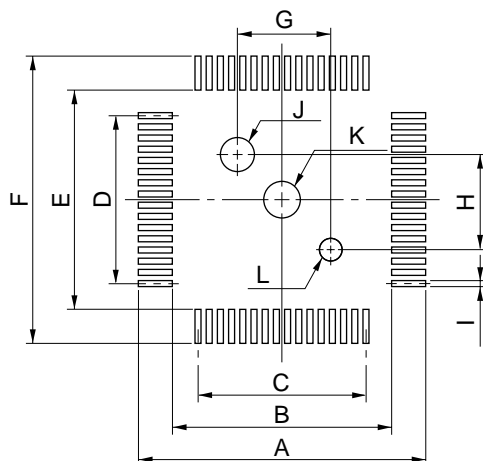
EV-9200GC-64-P1E

ITEM	MILLIMETERS	INCHES
A	19.5	0.768
B	14.8	0.583
C	$0.8{\pm}0.02 \times 15{=}12.0{\pm}0.05$	$0.031^{+0.002}_{-0.001} \times 0.591{=}0.472^{+0.003}_{-0.002}$
D	$0.8{\pm}0.02 \times 15{=}12.0{\pm}0.05$	$0.031^{+0.002}_{-0.001} \times 0.591{=}0.472^{+0.003}_{-0.002}$
E	14.8	0.583
F	19.5	0.768
G	$6.00{\pm}0.08$	$0.236^{+0.004}_{-0.003}$
H	$6.00{\pm}0.08$	$0.236^{+0.004}_{-0.003}$
I	$0.5{\pm}0.02$	$0.197^{+0.001}_{-0.002}$
J	$\phi 2.36{\pm}0.03$	$\phi 0.093^{+0.001}_{-0.002}$
K	$\phi 2.2{\pm}0.1$	$\phi 0.087^{+0.004}_{-0.005}$
L	$\phi 1.57{\pm}0.03$	$\phi 0.062^{+0.001}_{-0.002}$

Caution Dimensions of mount pad for EV-9200 and that for target device (QFP) may be different in some parts. For the recommended mount pad dimensions for QFP, refer to "SEMICONDUCTOR DEVICE MOUNTING TECHNOLOGY MANUAL" (C10535E).

Conversion Adapter Drawing (TGK-064SBW)

Figure A-3. TGK-064SBW Drawing (For Reference Only)

ITEM	MILLIMETERS	INCHES
A	18.4	0.724
B	0.65x15=9.75	0.026x0.591=0.384
C	0.65	0.026
D	7.75	0.305
E	10.15	0.400
F	12.55	0.494
G	14.95	0.589
H	0.65x15=9.75	0.026x0.591=0.384
I	11.85	0.467
J	18.4	0.724
K	C 2.0	C 0.079
L	12.45	0.490
M	10.25	0.404
N	7.7	0.303
O	10.02	0.394
P	14.92	0.587
Q	11.1	0.437
R	1.45	0.057
S	1.45	0.057
T	4-ϕ1.3	4-ϕ0.051
U	1.8	0.071
V	5.0	0.197
W	ϕ5.3	ϕ0.209
X	4-C 1.0	4-C 0.039
Y	ϕ3.55	ϕ0.140
Z	ϕ0.9	ϕ0.035

ITEM	MILLIMETERS	INCHES
a	ϕ0.3	ϕ0.012
b	1.85	0.073
c	3.5	0.138
d	2.0	0.079
e	3.9	0.154
f	1.325	0.052
g	1.325	0.052
h	5.9	0.232
i	0.8	0.031
j	2.4	0.094
k	2.7	0.106

TGK-064SBW-G0E

Note: Product made by TOKYO ELETECH CORPORATION.

Conversion Adapter Drawing (TGK-064SBP)

Figure A-4. TGK-064SBP Drawing (For Reference Only) (Unit: mm)

ITEM	MILLIMETERS	INCHES	ITEM	MILLIMETERS	INCHES
A	18.4	0.724	a	ϕ0.9	ϕ0.035
B	0.65x15=9.75	0.026x0.591=0.384	b	ϕ0.3	ϕ0.012
C	0.65	0.026	c	(16.95)	(0.667)
D	7.75	0.305	d	7.35	0.289
E	10.15	0.400	e	1.2	0.047
F	12.55	0.494	f	1.85	0.073
G	14.95	0.589	g	3.5	0.138
H	0.65x15=9.75	0.026x0.591=0.384	h	2.0	0.079
I	11.85	0.467	i	6.0	0.236
J	18.4	0.724	j	0.25	0.010
K	C 2.0	C 0.079	k	1.325	0.052
L	12.45	0.490	l	1.325	0.052
M	10.25	0.404	m	2.4	0.094
N	7.7	0.303	n	2.7	0.106
O	10.02	0.394			
P	14.92	0.587		**TGK-064SBP-G0E**	
Q	18.4	0.724			
R	11.1	0.437			
S	1.45	0.057			
T	1.45	0.057			
U	5.0	0.197			
V	4-ϕ1.3	ϕ0.051			
W	1.8	0.071			
X	ϕ5.3	ϕ0.209			
Y	4-C 1.0	4-C 0.039			
Z	ϕ3.55	ϕ0.140			

Note: Product made by TOKYO ELETECH CORPORATION.

APPENDIX B. RELATED DOCUMENTS

The related documents indicated in this publication may include preliminary versions. However, preliminary versions are not marked as such.

Documents Related to Devices

Document Name	Document No.	
	English	Japanese
μPD780024A, 780034A, 780024AY, 780034AY Subseries User's Manual	U14046E	U14046J
μPD780031A, 780032A, 780033A, 780034A, 780031AY, 780032AY, 780033AY, 780034AY Data Sheet	U14044E	U14044J
μPD78F0034A, 78F0034AY Data Sheet	This manual	U14040J
78K/0 Series User's Manual Instruction	U12326E	U12326J
78K/0, 78K/0S Series Application Note Flash memory write	U14458E	U14458J

Documents Related to Development Tools (User's Manuals)

Document Name		Document No.	
		English	Japanese
RA78K0 Assembler Package	Operation	U11802E	U11802J
	Assembly Language	U11801E	U11801J
	Structured Assembly Language	U11789E	U11789J
RA78K Series Structured Assembler Preprocessor		EEU-1402	U12323J
CC78K/0 C Compiler	Operation	U11517E	U11517J
	Language	U11518E	U11518J
IE-78K0-NS		–	U13731J
IE-78001-R-A		–	U14142J
IE-780034-NS-EM1		To be prepared	To be prepared
EP-78240		U10332E	EEU-986
EP-78012GK-R		EEU-1538	EEU-5012
SM78K0 System Simulator Windows based	Reference	U10181E	U10181J
SM78K Series System Simulator	External Part User Open Interface Specifications	U10092E	U10092J
ID78K0-NS Integrated Debugger Windows based	Reference	U12900E	U12900J
ID78K0 Integrated Debugger EWS based	Reference	–	U11151J
ID78K0 Integrated Debugger PC based	Reference	U11539E	U11539J
ID78K0 Integrated Debugger Windows based	Guide	U11649E	U11649J

Caution   The related documents listed above are subject to change without notice. Be sure to read the latest version of each document before designing.

Documents Related to Embedded Software (User's Manuals)

Document Name		Document No.	
		English	Japanese
78K/0 Series Real-time OS	Fundamental	U11537E	U11537J
	Installation	U11536E	U11536J
78K/0 Series OS MX78K0	Fundamental	U12257E	U12257J

Other Related Documents

Document Name	Document No.	
	English	Japanese
SEMICONDUCTOR SELECTION GUIDE Products & Packages (CD-ROM)	X13769X	
Semiconductor Device Mounting Technology Manual	C10535E	C10535J
Quality Grades on NEC Semiconductor Devices	C11531E	C11531J
NEC Semiconductor Device Reliability/Quality Control System	C10983E	C10983J
Guide to Prevent Damage for Semiconductor Devices by Electrostatic Discharge (ESD)	C11892E	C11892J
Microcomputer - Related Products by Third Party	–	U11416J

Caution   The related documents listed above are subject to change without notice. Be sure to read the latest version of each document before designing.

NOTES FOR CMOS DEVICES

① **PRECAUTION AGAINST ESD FOR SEMICONDUCTORS**

Note:

Strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it once, when it has occurred. Environmental control must be adequate. When it is dry, humidifier should be used. It is recommended to avoid using insulators that easily build static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work bench and floor should be grounded. The operator should be grounded using wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with semiconductor devices on it.

② **HANDLING OF UNUSED INPUT PINS FOR CMOS**

Note:

No connection for CMOS device inputs can be cause of malfunction. If no connection is provided to the input pins, it is possible that an internal input level may be generated due to noise, etc., hence causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using a pull-up or pull-down circuitry. Each unused pin should be connected to V_{DD} or GND with a resistor, if it is considered to have a possibility of being an output pin. All handling related to the unused pins must be judged device by device and related specifications governing the devices.

③ **STATUS BEFORE INITIALIZATION OF MOS DEVICES**

Note:

Power-on does not necessarily define initial status of MOS device. Production process of MOS does not define the initial operation status of the device. Immediately after the power source is turned ON, the devices with reset function have not yet been initialized. Hence, power-on does not guarantee out-pin levels, I/O settings or contents of registers. Device is not initialized until the reset signal is received. Reset operation must be executed immediately after power-on for devices having reset function.

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Solaris and SunOS are trademarks of Sun Microsystems, Inc.
NEWS and NEWS-OS are trademarks of Sony Corporation.

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Some information contained in this document may vary from country to country. Before using any NEC product in your application, please contact the NEC office in your country to obtain a list of authorized representatives and distributors. They will verify:

- Device availability

- Ordering information

- Product release schedule

- Availability of related technical literature

- Development environment specifications (for example, specifications for third-party tools and components, host computers, power plugs, AC supply voltages, and so forth)

- Network requirements

In addition, trademarks, registered trademarks, export restrictions, and other legal issues may also vary from country to country.

NEC Electronics Inc. (U.S.)
Santa Clara, California
Tel: 408-588-6000
        800-366-9782
Fax: 408-588-6130
        800-729-9288

NEC Electronics (Germany) GmbH
Duesseldorf, Germany
Tel: 0211-65 03 02
Fax: 0211-65 03 490

NEC Electronics (UK) Ltd.
Milton Keynes, UK
Tel: 01908-691-133
Fax: 01908-670-290

NEC Electronics Italiana s.r.l.
Milano, Italy
Tel: 02-66 75 41
Fax: 02-66 75 42 99

NEC Electronics (Germany) GmbH
Benelux Office
Eindhoven, The Netherlands
Tel: 040-2445845
Fax: 040-2444580

NEC Electronics (France) S.A.
Velizy-Villacoublay, France
Tel: 01-30-67 58 00
Fax: 01-30-67 58 99

NEC Electronics (France) S.A.
Madrid Office
Madrid, Spain
Tel: 91-504-2787
Fax: 91-504-2860

NEC Electronics (Germany) GmbH
Scandinavia Office
Taeby, Sweden
Tel: 08-63 80 820
Fax: 08-63 80 388

NEC Electronics Hong Kong Ltd.
Hong Kong
Tel: 2886-9318
Fax: 2886-9022/9044

NEC Electronics Hong Kong Ltd.
Seoul Branch
Seoul, Korea
Tel: 02-528-0303
Fax: 02-528-4411

NEC Electronics Singapore Pte. Ltd.
United Square, Singapore
Tel: 65-253-8311
Fax: 65-250-3583

NEC Electronics Taiwan Ltd.
Taipei, Taiwan
Tel: 02-2719-2377
Fax: 02-2719-5951

NEC do Brasil S.A.
Electron Devices Division
Guarulhos-SP Brasil
Tel: 55-11-6462-6810
Fax: 55-11-6462-6829

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