

Stepper Motor Driver with Divide by Select

Description

The CS8441 is a Stepper Motor Driver that implements an H-Bridge design in order to drive two coils in an eight step sequence per revolution in the divide by 1 mode; 16 step sequence in the divide by 2 mode. The H-Bridge is capable of delivering 85mA to the load.

The sequencer insures that the odometer is monotonic. This sequencer is configured such that simultaneous conduction does not occur. Before each successive output sequence the part is taken through a state where both outputs are turned off individually. This tends to minimize the inductive

kick back energy that the part must absorb. On chip clamp diodes are across each output to protect the part from the kick back energy that it must absorb.

Additional part protection is provided by two functions. The first being "short circuit protection". This function will protect the part in the case of a shorted or partially shorted load. The second protection function is the "overvoltage function". This function monitors the level of the supply voltage. In transient conditions such as load dump, the part will shut down, protecting itself.

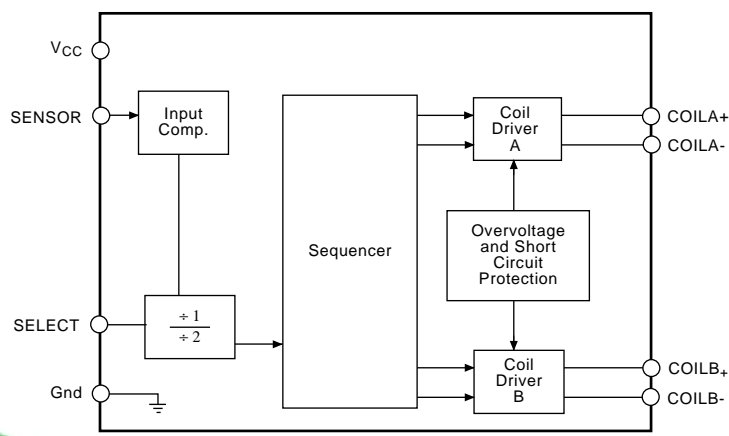
Features

- No Cross-conduction in either H-bridge
- Divide by 1 and Divide by 2 Mode
- Guaranteed Monotonic
- On Chip Flyback Diodes
- Fault Protection
Overvoltage
Load Dump Protection to 60V

Absolute Maximum Ratings

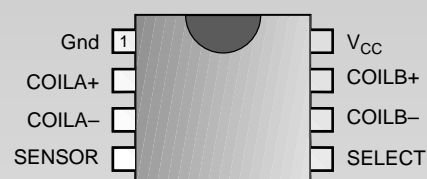
Supply Voltage (V_{CC}) (continuous) -40°C to $+125^{\circ}\text{C}$ -0.5 to 24V
 (100ms pulse transient) -40°C to $+125^{\circ}\text{C}$ -0.5 to 60V
 Input Voltage (V_{IN}) -0.3 to $V_{CC} + 0.3\text{V}$
 Storage Temperature Range (T_{STG}) -65°C to 150°C
 Junction Temperature Range -40°C to 150°C
 ESD (Human Body Model) 2kV
 Lead Temperature Soldering
 Wave Solder (through hole styles only) 10 sec. max, 260°C peak

Block Diagram



Package Options

8 Lead PDIP



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Electrical Characteristics: Unless otherwise stated, these specifications apply for $-40^{\circ}\text{C} \leq T_A \leq 125^{\circ}\text{C}$, $6.5\text{V} \leq V_{CC} \leq 15.5\text{V}$. All voltage shall be referenced to Gnd unless otherwise noted. Overvoltage shutdown of coils occurs when $V_{CC} > 16\text{V}$.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
■ Supply, V_{CC}					
Supply Voltage Range	$-40^{\circ}\text{C} \leq T_A \leq 125^{\circ}\text{C}$	6.5		15.5	VDC
	$-40^{\circ}\text{C} \leq T_A \leq 25^{\circ}\text{C}$	6.5		24.0	VDC
	Transient Pulse, 100ms			35.0	VDC
Supply Current	$V_{CC} = 15.5\text{VDC}$ Outputs not loaded		24	35	mA
Overvoltage Shutdown		16		23	V
■ Speed Sensor Input, SENSOR					
Input Frequency Range			0.2	1.0	kHz
Switching Threshold		1.2		2.4	VDC
Hysteresis		300	500		mVDC
Input Bias Current	$0.8\text{VDC} \leq V_{IN} \leq V_{CC}$		0.1	± 1.0	μA
Input Voltage Range		0		V_{CC}	VDC
Operating Input Voltage	10k Ω Resistor in Series			-15 to V_{CC}	VDC
Input Clamp Current	I Clamp at $V_{IN} = 0\text{VDC}$		-0.4	-5.0	mA
■ Divider Select Input, SELECT					
Logic 0 Input Voltage				100	mVDC
Logic 1 Input Voltage		3.0			VDC
Logic 0 Input Current	$0\text{V} \leq V_{IN} \leq 100\text{mV}$		-1	-100	μA
Logic 1 Input Current	$3\text{V} \leq V_{IN} \leq 15.5\text{VDC}$		0.75	2.00	mA
■ Coil Output Drivers					
Coil Load	+25 $^{\circ}\text{C}$	198	210	222	Ω
Coil Inductance			80		mH
Coil Resistance Temperature	Coefficient			0.35	%/ $^{\circ}\text{C}$
* Energized Coil Voltage (Both Polarities) A and B	$V_{CC} = 6.5\text{VDC}$	$V_{CC} - 1.5\text{V}$	$V_{CC} - 0.9\text{V}$		VDC
	$V_{CC} = 10.0\text{VDC}$	$V_{CC} - 1.6\text{V}$	$V_{CC} - 1.0\text{V}$		VDC
	$V_{CC} = 15.5\text{VDC}$, $-20^{\circ}\text{C} \leq T_A \leq 125^{\circ}\text{C}$	$V_{CC} - 1.75\text{V}$	$V_{CC} - 1.1\text{V}$		VDC
	$V_{CC} = 15.5\text{VDC}$, $-40^{\circ}\text{C} \leq T_A \leq -20^{\circ}\text{C}$	$V_{CC} - 2.0\text{V}$	$V_{CC} - 1.2\text{V}$		VDC
De-Energized Coil Leakage Current				± 100	μA
■ Short Circuit Protection					
Short Circuit Threshold I Coil A + I Coil B			275	400	mA
Short Circuit Turn-Off Delay			5		μs

* Voltage across the coils shall be measured at the specific voltages, but shall also be within linearly interpolated limits.

Package Pin Description

PACKAGE PIN #	PIN SYMBOL	FUNCTION
8L PDIP		
1	Gnd	Ground connection.
2	COILA+	Output stage, when active, this pin supplies current to COIL A.
3	COILA-	Output stage, when active, this pin supplies current to COIL A.
4	SENSOR	Input signal from wheel speed or engine rpm.
5	SELECT	Selects divide by 1 or divide by 2 mode.
6	COILB-	Output stage, when active, this pin supplies current to COIL B.
7	COILB+	Output stage, when active, this pin supplies current to COIL B.
8	V _{CC}	Supply Voltage.

Circuit Operation

Speed Sensor Input

SENSOR is a PNP comparator input which accepts a sine wave input or a square wave input. This input is protected from excursions above V_{CC} as well as any below ground, as long as the current is limited to 1.5mA. It has an active clamp set to zero volts to prevent negative input voltages from disrupting normal operation. The sensor input can withstand 150V_{DC} as long as the input current is limited to 1.5mA max using a series resistor of 100kΩ.

Coil Driver Outputs

Simultaneously energizing the source and sink on either leg is not permitted. i.e. Q1 & Q2 or Q3 & Q4 cannot be energized simultaneously.

Circuit function is not affected by inductive transients due to coil loads as specified in Transition States section.

The transition states occur as indicated in Table 1 without any intermediate states permitted.

Table 1: Transition States

Output State Table		
State	Coil A	Coil B
0	+	+
1	OFF	+
2	-	+
3	-	OFF
4	-	-
5	OFF	-
6	+	-
7	+	OFF

The polarity definition for the coil driver outputs is as follows:

Polarity	Connect	Connect
	Coil +	Coil -
Positive (+)	V _{CC}	Gnd
Negative (-)	Gnd	V _{CC}

Divider Select Input

The speed sensor input frequency is divided by one or divided by two by connecting the divider select input, (Pin 5) as follows:

Logic 0 = divide by 2

Logic 1 = divide by 1

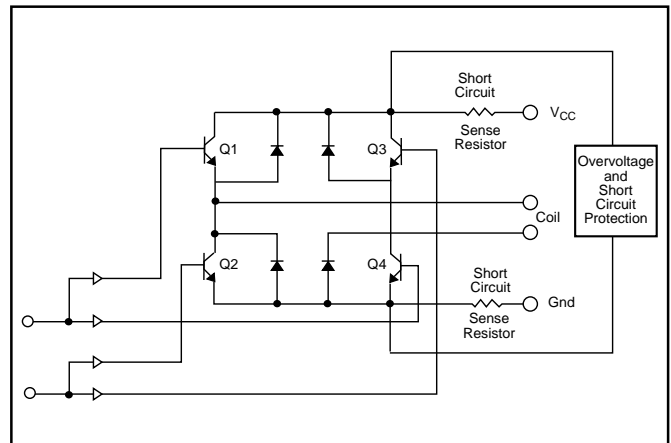


Figure 1: Coil Driver Output

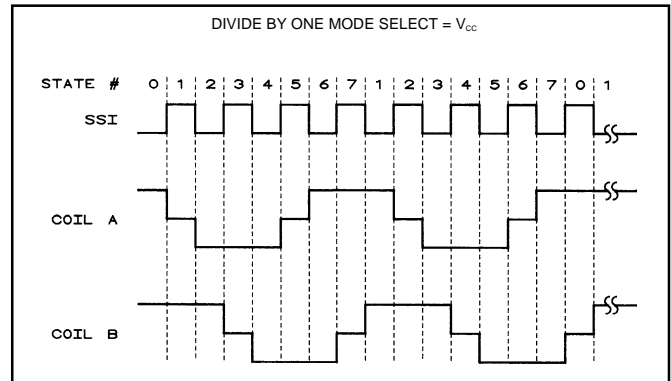


Figure 2: Divide by 1 SELECT Mode

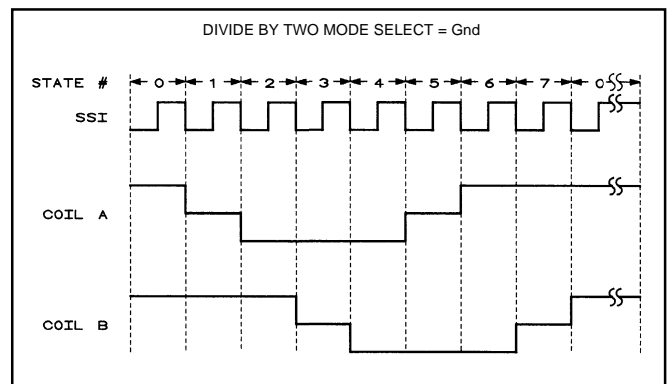
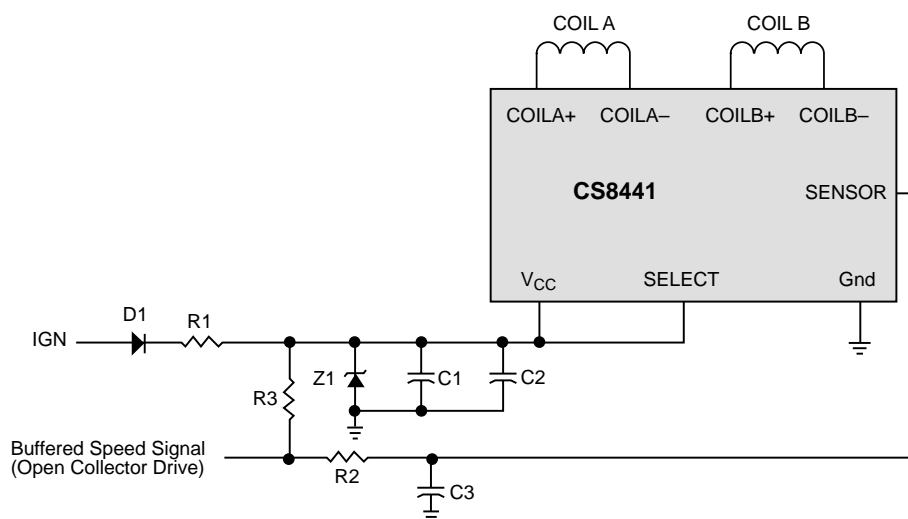


Figure 3: Divide by 2 SELECT Mode

Odometer Application Diagram

C1 - 10 μ F
 C2 - 0.1 μ F
 C3 - 0.01 μ F
 R1 - 3.9 Ω , 500mW
 R2 - 100k Ω
 R3 - 15k Ω
 D1 - 1A, 600PIV
 Z1 - 50V, 500mW
 COIL A - 210 \pm 12 Ω , 80mH
 COIL B - 210 \pm 12 Ω , 80mH



Package Specification

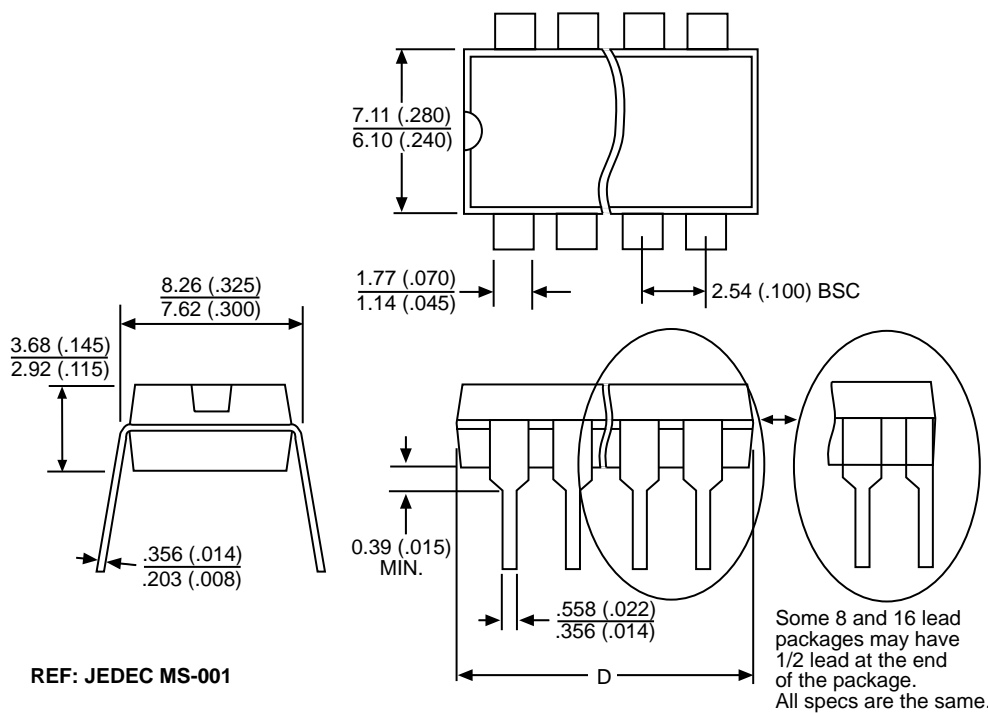
PACKAGE DIMENSIONS IN mm (INCHES)

Lead Count	D			
	Metric		English	
	Max	Min	Max	Min
8 Lead PDIP	10.16	9.02	.400	.355

PACKAGE THERMAL DATA

Thermal Data		8 Lead PDIP	
$R_{\theta JC}$	typ	52	$^{\circ}\text{C}/\text{W}$
$R_{\theta JA}$	typ	100	$^{\circ}\text{C}/\text{W}$

Plastic DIP (N); 300 mil wide



Ordering Information

Part Number	Description
CS8441YN8	8 Lead PDIP

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