2-channel reversible motor driver BA6259N

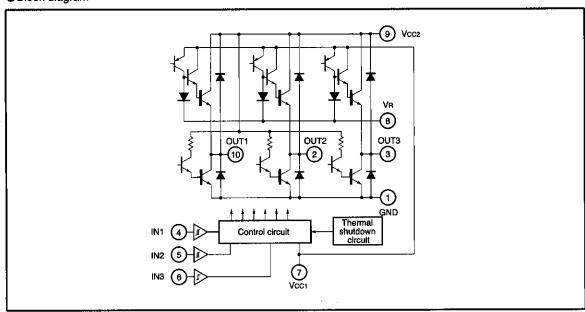
The BA6259N incorporates two reversible-motor drivers.

Features

- 1) Two reversible-motor driver circuits are built in.
- 3) SIP10pin package.

2) Built-in thermal shutdown circuit.

●Block diagram



●Absolute maximum ratings (Ta=25℃)

Parameter	Symbol	Limits	Unit	
Power supply voltage	Vcc1	20	٧	
	Vcc2	25	V	
Power dissipation	Pd	1000*1	mW	
Operating temperature	Topr	−20~75	౮	
Storage temperature	Tstg	− 50~125	,c	
Input voltage	Vin	-0.2~6	٧	
Output current	lo	1.0*2	Α	

- *1 Reduce power by 10 mW for each degree above 25 $^{\circ}\!\!\!\!\!\mathrm{C}$.
- *2 50ms pulse with a duty ratio of 1/50

●Electrical characteristics (Unless otherwise noted, Ta=25°C and Vcc=12V)

Parameter	Symbol	Min.	Тур.	Max.	Unit	Conditions	
Operating supply voltage	Vccı	8	-	18	٧		
Operating supply voltage	Vcc2	8	_	18	٧	Vcc2 < Vcc1	
Output reference voltage (pin 8)	VR	8	_	18	٧	Ve and Vcc2 are directly connected	
Current consumption	loc	_	12	24	mA	R _L =∞, 4, 5, 6pin; "L"	
LOW level input voltage	VIL	_	_	1.0	٧	4, 5, 6pin	
HIGH level input voltage	Vн	3.5	_	_	٧	4, 5, 6pin	
LOW level output voltage (pins 2, 3, 10)	Vol	_	0.3	0.5	٧	I _o =0.15A	
HIGH level output voltage (pins 2, 3, 10)	Vон	11.0	11.3	_	٧	Pins 8 and 9 are directly connected, lo = 0.15 A	

Input/output truth table

Input			Output			
4pin (IN)	5pin (IN)	6pin (IN)	10pin (OUT)	2pin (OUT)	3pin (OUT)	
L	L	L H	OPEN	OPEN	OPEN	
Н	L	L	Н	L	OPEN	
Н	L	Н	L	Н	OPEN	
L	Н	L	Н	OPEN	L	
Ł	Н	Н	L	OPEN	Н	
н	н	· L	L	L	L	

 HIGH level input is 3.5 V or more LOW level input is 1.0 V or less

Application example

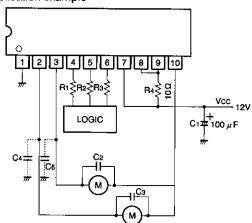
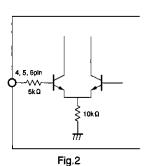


Fig.1

- C₂, C₃: Capacitors for preventing parasitic oscillation. Though the optimum capacitance depends on such PCB arrangement factors as the power supply circuit, motor characteristics, and conductor foil patterns, a range of $0.01 \sim 1~\mu$ F is recommended.
- C₄, C₅: Capacitors for preventing parasitic oscillation. They may or may not be required, depending on the PCB arrangement. A capacitance range of $0.01\sim10~\mu$ F is recommended.

Control pin equivalent circuit



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Precautions for use

- (1) Use the BA6259N with $V_{\rm B}$ (pin 8) short-circuited to $V_{\rm CC2}$ (pin 9). The $V_{\rm CC2}$ potential should be lower than the $V_{\rm CC1}$ potential. Under these conditions, the IC provides a HIGH level output voltage of 11.3V (typical, $V_{\rm CC2}$ =12V). Because a single transistor is used for the low-side output stage, the LOW level output voltage is further lowered. This results in a wide range of motor drive voltage.
- (2) Though the IC input pins can be directly connected with MOS output pins, it is recommendable to connect resistors of a few kiloohms to do3en of kiloohms between the pins for the sake of pin protection.

- (3) When reversing the rotational direction of a motor, make sure to go through the brake mode in-between the opposite directions. It is recommendable to keep the brake mode for at least 10 μ s.
- (4) Due to the effects of capacitors $C_2 \sim C_5$, the motor that is not being driven could be momentarily driven during mode switching. Check for this problem when designing your application.
- (5) It is recommendable to arrange your design so that voltage rises at V_{CC1} prior to V_{CC2} when turning on the power, and voltage falls at V_{CC1} after V_{CC2} when turning off the power.
- (6) Thermal shutdown circuit

When the thermal shutdown circuit is activated, the output is left OPEN. The circuit is activated when the IC junction temperature rises above 170°C. The temperature difference between the activation and deactivation settings is about 30°C.

●Electrical characteristic curves

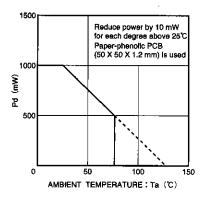


Fig.4 Power dissipation curve

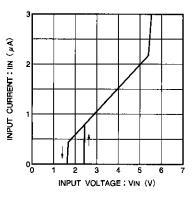


Fig.5 Input voltage vs. input current

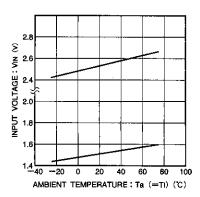


Fig.6 Input voltage vs. ambient temperature

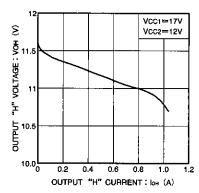


Fig.7 HIGH level output voltage vs. output current

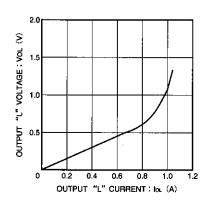
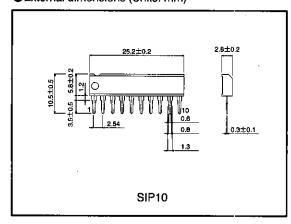


Fig.8 LOW level output voltage vs. output current

●External dimensions (Units: mm)



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