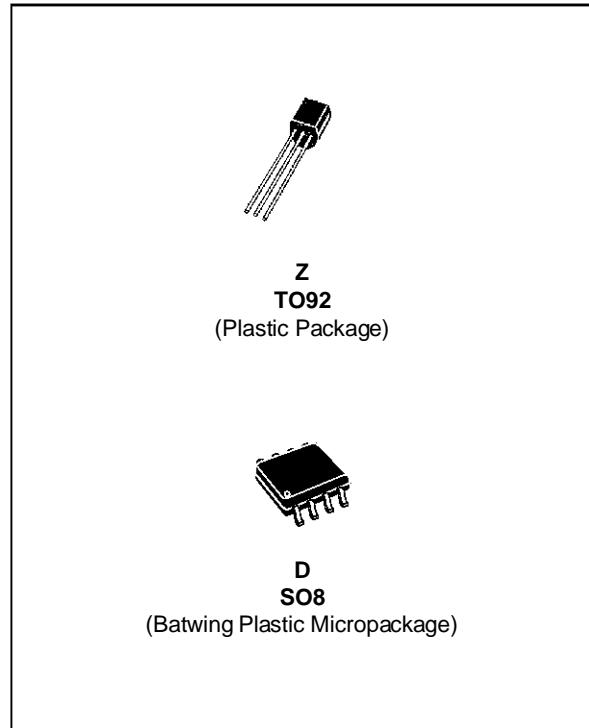


## PROGRAMMABLE VOLTAGE REFERENCE

- ADJUSTABLE OUTPUT VOLTAGE :  
 $V_{ref}$  to 36V
- SINK CURRENT CAPABILITY : 1 to 100mA
- TYPICAL OUTPUT IMPEDANCE : 0.22W
- 1% AND 2% VOLTAGE PRECISION



### DESCRIPTION

The TL431 is a programmable shunt voltage reference with guaranteed temperature stability over the entire temperature range of operation.

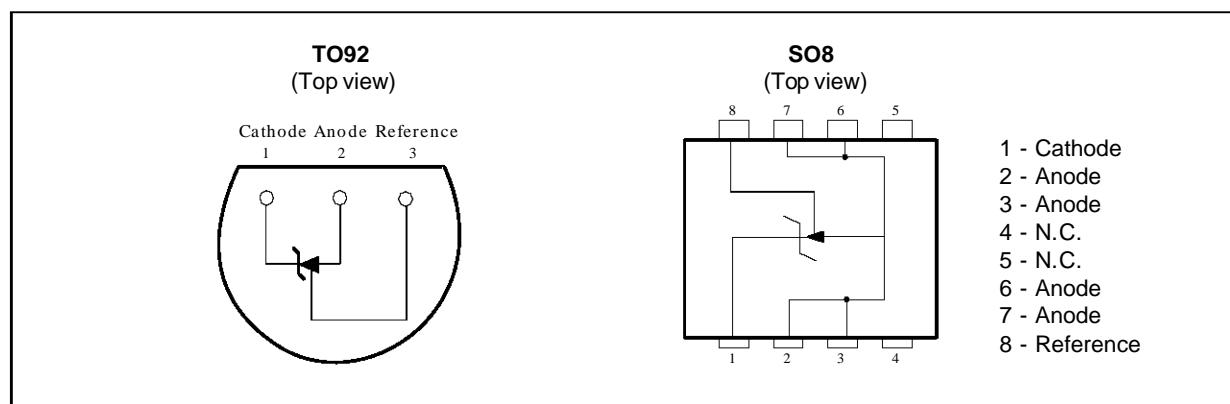
The output voltage may be set to any value between  $V_{ref}$  (approximately 2.5V) and 36V with two external resistors.

The TL431 operates with a wide current range from 1 to 100mA with a typical dynamic impedance of 0.22Ω.

### ORDER CODES

Part number	Temperature Range	Package	
		Z	D
TL431C/AC	0°C, +70°C	•	•
TL431I/AI	-40°C, +85°C	•	•

### PIN CONNECTIONS



## ABSOLUTE MAXIMUM RATINGS

Symbol	Parameter	Value	Unit
$V_{KA}$	Cathode to Anode Voltage	37	V
$I_K$	Continuous Cathode Current Range	-100 to +150	mA
$I_{ref}$	Reference Input Current Range	-0.05 to +10	mA
$T_{oper}$	Operating Free-air Temperature Range TL431C/AC TL431I/AI	0 to +70 -40 to +85	°C
$T_{stg}$	Storage Temperature Range	-65 to +150	°C

## OPERATING CONDITIONS

Symbol	Parameter	Value	Unit
$V_{KA}$	Cathode to Anode Voltage	$V_{ref}$ to 36	V
$I_K$	Cathode Current	1 to 100	mA

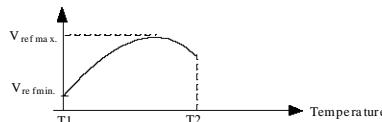
## ELECTRICAL CHARACTERISTICS

 $T_{amb} = 25^\circ\text{C}$  (unless otherwise specified)

Symbol	Parameter	TL431C			TL431AC			Unit
		Min.	Typ.	Max.	Min.	Typ.	Max.	
$V_{ref}$	Reference Input Voltage - (figure 1) $V_{KA} = V_{ref}$ , $I_K = 10\text{mA}$ $T_{amb} = 25^\circ\text{C}$ $T_{min.} \leq T_{amb} \leq T_{max.}$	2.44 2.423	2.495	2.55 2.567	2.47 2.453	2.495	2.52 2.537	V
$\Delta V_{ref}$	Reference Input Voltage Deviation Over Temperature Range - (figure 1, note1) $V_{KA} = V_{ref}$ , $I_K = 10\text{mA}$ , $T_{min.} \leq T_{amb} \leq T_{max.}$		3	17		3	15	mV
$\frac{\Delta V_{ref}}{\Delta V_{KA}}$	Ratio of Change in Reference Input Voltage to Change in Cathode to Anode Voltage - (figure 2) $I_K = 10\text{mA}$ $\Delta V_{KA} = 10\text{V}$ to $V_{ref}$ $\Delta V_{KA} = 36\text{V}$ to $10\text{V}$		-1.4 -1	-2.7 -2		-1.4 -1	-2.7 -2	mV/V
$I_{ref}$	Reference Input Current - (figure 2) $I_K = 10\text{mA}$ , $R_1 = 10\text{k}\Omega$ , $R_2 = \infty$ $T_{amb} = 25^\circ\text{C}$ $T_{min.} \leq T_{amb} \leq T_{max.}$		1.8	4 5.2		1.8	4 5.2	$\mu\text{A}$
$\Delta I_{ref}$	Reference Input Current Deviation Over Temperature Range - (figure 2) $I_K = 10\text{mA}$ , $R_1 = 10\text{k}\Omega$ , $R_2 = \infty$ $T_{min.} \leq T_{amb} \leq T_{max.}$		0.4	1.2		0.4	1.2	$\mu\text{A}$
$I_{min}$	Minimum Cathode Current for Regulation - (figure 1) $V_{KA} = V_{ref}$		0.5	1		0.5	0.6	mA
$I_{off}$	Off-State Cathode Current - (figure 3)		2.6	1000		2.6	1000	nA
$ Z_{KA} $	Dynamic Impedance - (figure 1, note 2) $V_{KA} = V_{ref}$ , $\Delta I_K = 1$ to $100\text{mA}$ , $f \leq 1\text{kHz}$		0.22	0.5		0.22	0.5	$\Omega$

Notes : 1.  $\Delta V_{ref}$  is defined as the difference between the maximum and minimum values obtained over the full temperature range.

$$\Delta V_{ref} = V_{ref\ max.} - V_{ref\ min}$$



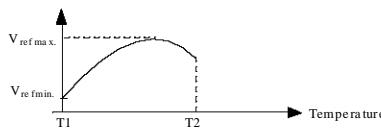
2. The dynamic Impedance is defined as  $|Z_{KA}| = \frac{\Delta V_{KA}}{\Delta I_K}$

**ELECTRICAL CHARACTERISTICS** $T_{amb} = 25^{\circ}\text{C}$  (unless otherwise specified)

Symbol	Parameter	TL431I			TL431AI			Unit
		Min.	Typ.	Max.	Min.	Typ.	Max.	
$V_{ref}$	Reference Input Voltage - (figure 1) $V_{KA} = V_{ref}$ , $I_K = 10\text{mA}$ $T_{amb} = 25^{\circ}\text{C}$ $T_{min.} \leq T_{amb} \leq T_{max.}$	2.44 2.41	2.495	2.55 2.58	2.47 2.44	2.495	2.52 2.55	V
$\Delta V_{ref}$	Reference Input Voltage Deviation Over Temperature Range - (figure 1, note1) $V_{KA} = V_{ref}$ , $I_K = 10\text{mA}$ , $T_{min.} \leq T_{amb} \leq T_{max.}$		7	30		7	17	mV
$\frac{\Delta V_{ref}}{\Delta V_{KA}}$	Ratio of Change in Reference Input Voltage to Change in Cathode to Anode Voltage - (figure 2) $I_K = 10\text{mA}$ $\Delta V_{KA} = 10\text{V}$ to $V_{ref}$ $\Delta V_{KA} = 36\text{V}$ to $10\text{V}$		-1.4 -1	-2.7 -2		-1.4 -1	-2.7 -2	mV/V
$I_{ref}$	Reference Input Current - (figure 2) $I_K = 10\text{mA}$ , $R_1 = 10\text{k}\Omega$ , $R_2 = \infty$ $T_{amb} = 25^{\circ}\text{C}$ $T_{min.} \leq T_{amb} \leq T_{max.}$		1.8	4 6.5		1.8	4 6.5	$\mu\text{A}$
$\Delta I_{ref}$	Reference Input Current Deviation Over Temperature Range - (figure 2) $I_K = 10\text{mA}$ , $R_1 = 10\text{k}\Omega$ , $R_2 = \infty$ $T_{min.} \leq T_{amb} \leq T_{max.}$		0.8	2.5		0.8	1.2	$\mu\text{A}$
$I_{min}$	Minimum Cathode Current for Regulation - (figure 1) $V_{KA} = V_{ref}$		0.5	1		0.5	0.7	mA
$I_{off}$	Off-State Cathode Current - (figure 3)		2.6	1000		2.6	1000	nA
$ Z_{KA} $	Dynamic Impedance - (figure 1, note 2) $V_{KA} = V_{ref}$ , $\Delta I_K = 1$ to $100\text{mA}$ , $f \leq 1\text{kHz}$		0.22	0.5		0.22	0.5	$\Omega$

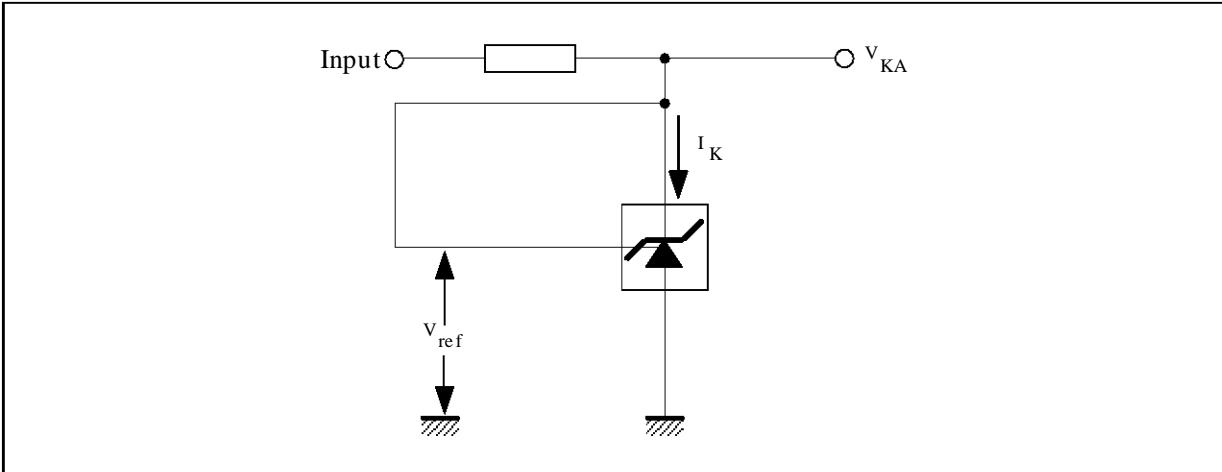
- Notes :** 1.  $\Delta V_{ref}$  is defined as the difference between the maximum and minimum values obtained over the full temperature range.

$$\Delta V_{ref} = V_{ref\ max.} - V_{ref\ min}$$

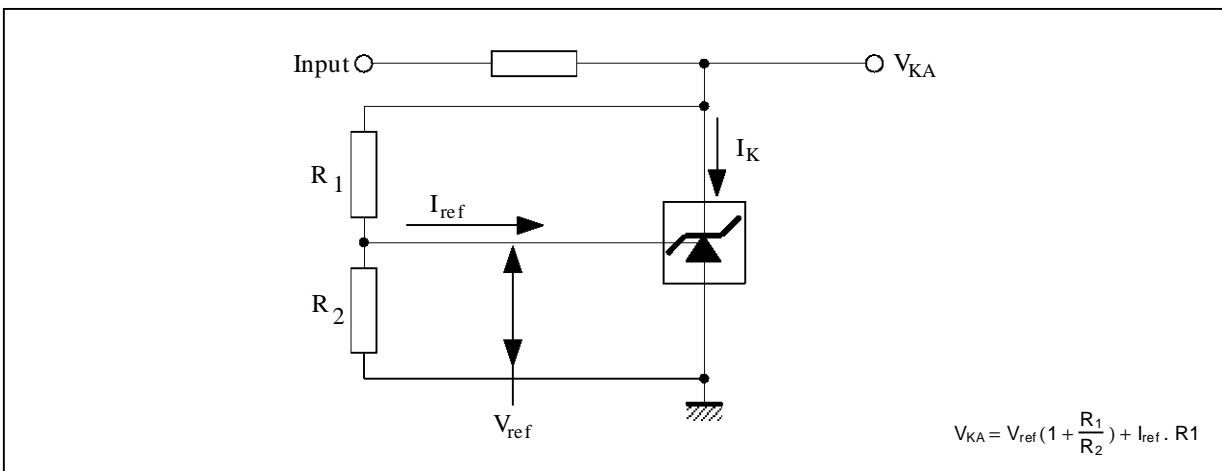


2. The dynamic Impedance is defined as  $|Z_{KA}| = \frac{\Delta V_{KA}}{\Delta I_K}$

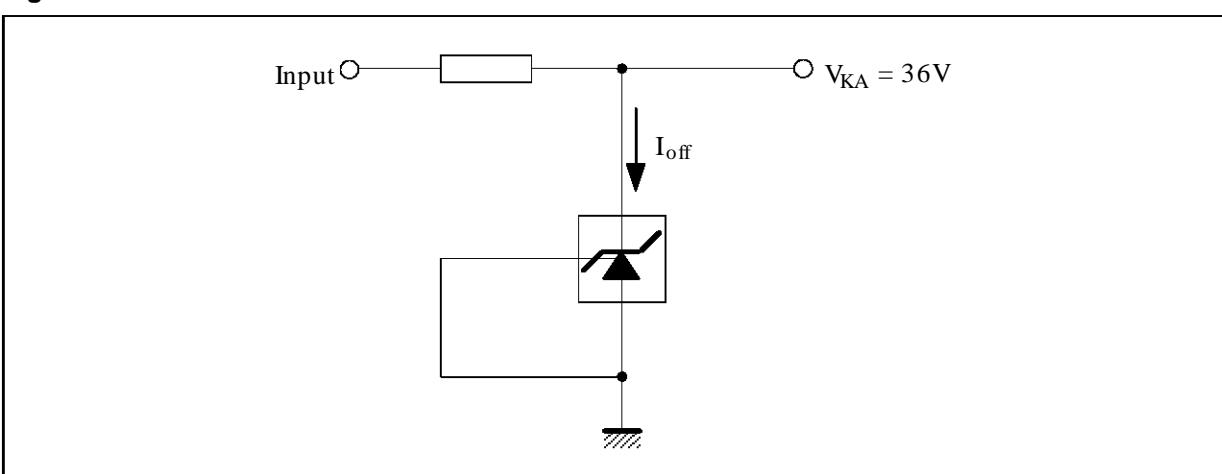
**Figure 1 :** Test Circuit for  $V_{KA} = V_{ref}$



**Figure 2 :** Test Circuit for  $V_{KA} > V_{ref}$

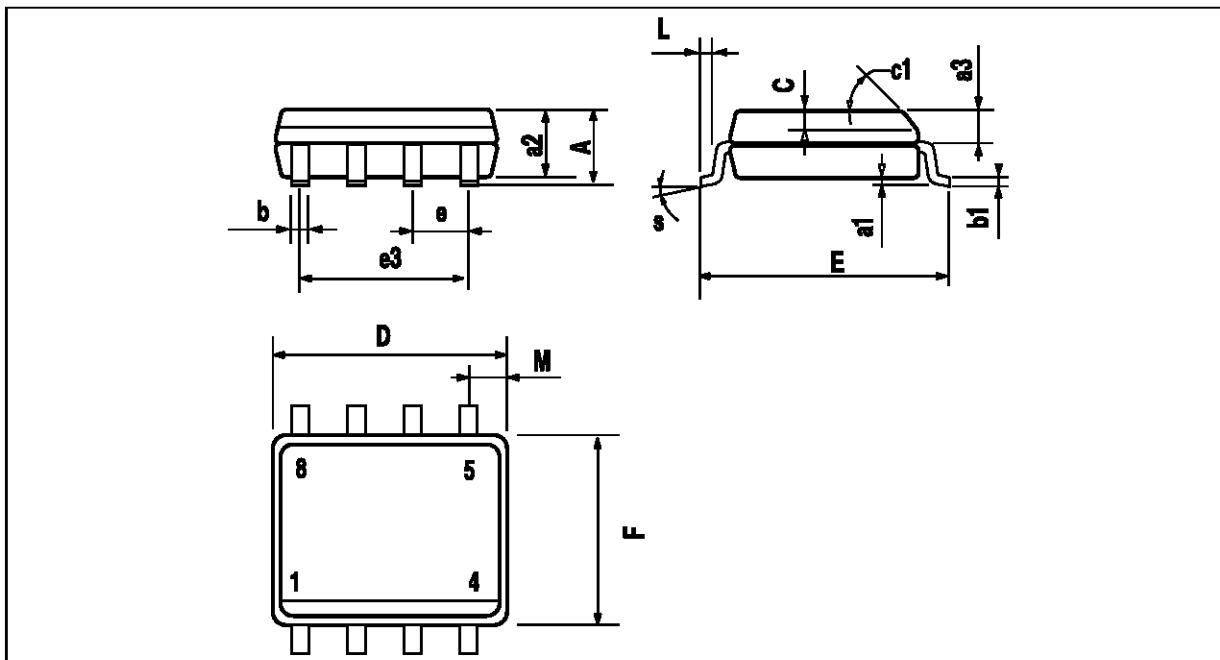


**Figure 3 :** Test Circuit for  $I_{off}$



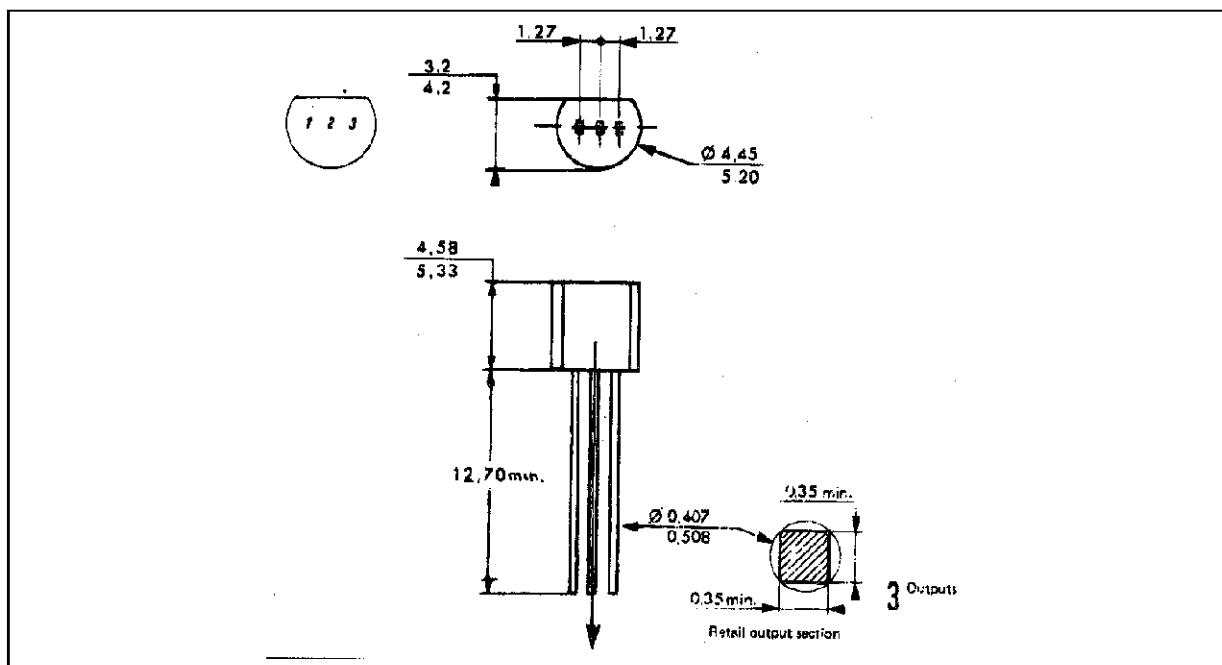
## PACKAGE MECHANICAL DATA

8 PINS - BATWING PLASTIC MICROPACKAGE (SO8)



Dimensions	Millimeters			Inches		
	Min.	Typ.	Max.	Min.	Typ.	Max.
A			1.75			0.069
a1	0.1		0.25	0.004		0.010
a2			1.65			0.065
a3	0.65		0.85	0.026		0.033
b	0.35		0.48	0.014		0.019
b1	0.19		0.25	0.007		0.010
C	0.25		0.5	0.010		0.020
c1	45° (typ.)					
D	4.8		5.0	0.189		0.197
E	5.8		6.2	0.228		0.244
e		1.27			0.050	
e3		3.81			0.150	
F	3.8		4.0	0.150		0.157
L	0.4		1.27	0.016		0.050
M			0.6			0.024
S	8° (max.)					

**PACKAGE MECHANICAL DATA**  
3 PINS - PLASTIC PACKAGE TO92



Dimensions	Millimeters			Inches		
	Min.	Typ.	Max.	Min.	Typ.	Max.
L		1.27			0.05	
B	3.2	3.7	4.2	0.126	0.1457	0.1654
O1	4.45	5.00	5.2	0.1752	0.1969	0.2047
C	4.58	5.03	5.33	0.1803	0.198	0.2098
K	12.7			0.5		
O2	0.407	0.5	0.508	0.016	0.0197	0.02
a	0.35			0.0138		

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