## INTEGRATED CIRCUITS

# DATA SHEET

# **TEA5762**Self tuned radio

Preliminary specification
File under Integrated Circuits, IC01

1995 Jun 23





Self tuned radio TEA5762

#### **FEATURES**

- The tuning system has an optimized IC partitioning both from application (omitting interferences) and flexibility (removable front panel option) point of view: the tuning synthesizer is on-chip with the radio
- The tuning quality is superior and requires no IF counter for stop-detection; it is insensitive to ceramic filter tolerances
- In combination with the microcontroller, fast, low-power operation of preset mode, manual search, automatic search and automatic store are possible
- The local (internal) controller function facilitates reduced and simplified microcontroller software
- The high integration level means fewer external components with regard to the communication between the radio and the microcontroller and a simple and small printed-circuit board (PCB)
- The inherent FUZZY LOGIC behaviour of STR (Self Tuned Radio), which mimics hand tuning, yields a potentially fast yet reliable tuning operation
- The level of the incoming signal at which the radio must lock is software programmable
- Two programmable ports
- · FM-on/off port to control the external FM front end
- High selectivity with distributed IF gain
- Soft mute
- · Signal dependent stereo-blend
- High impedance MOSFET input on AM
- Wide supply voltage range of 2.5 to 12 V
- Low current consumption 18 mA at AM and FM (including tuning synthesizer for AM)
- · Low noise figure
- · Low output distortion
- Due to the new tuning concept, the tuning is independent of the channel spacing.

#### **GENERAL DESCRIPTION**

The TEA5762 is a 44-pin integrated AM-radio and FM-IF and demodulator part including a novel tuning concept. The radio part is based on the TEA5712.

It is designed for the use with an external FM-front end.

The new tuning concept combines the advantages of hand tuning with electronic facilities and features. User intelligence is incorporated into the tuning algorithm and an improvement of the analog signal processing is used for the AFC function.

#### **ORDERING INFORMATION**

TYPE		PACKAGE	
NUMBER	NAME	DESCRIPTION	VERSION
TEA5762H	QFP44	plastic quad flat package; 44 leads (lead length 1.3 mm); body $10 \times 10 \times 1.75$ mm	SOT307-2

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#### **QUICK REFERENCE DATA**

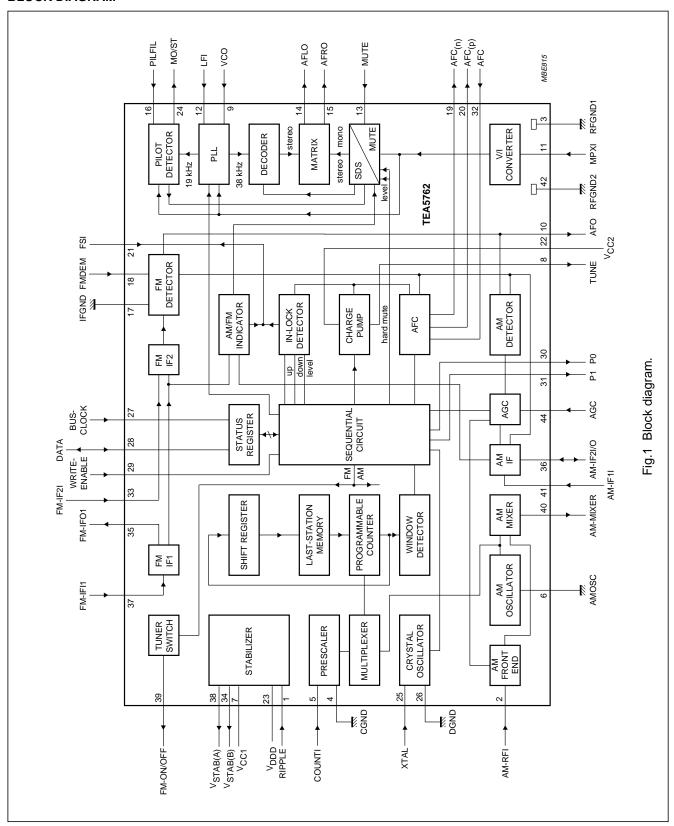
SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
V <sub>CC1</sub>	supply voltage 1		2.5	-	12	V
V <sub>CC2</sub>	supply voltage 2 for tuning		_	-	12	V
V <sub>tune</sub>	tuning voltage		0.7	_	V <sub>CC2</sub> - 0.75	V
I <sub>CC1</sub>	supply current 1	AM mode	12	15	18	mA
		FM mode	13	16	19	mA
I <sub>DDD</sub>	digital supply current	AM mode	_	3.3	_	mA
		FM mode	_	2.7	_	mA
I <sub>CC2</sub>	supply current 2 for tuning in preset mode (band-end to band-end)		_	-	640	μΑ
T <sub>amb</sub>	operating ambient temperature		-15	_	+60	°C
AM perform	mance; note 1		•	•	_	
V <sub>10</sub>	AF output voltage	V <sub>i1</sub> = 5 mV	36	45	70	mV
V <sub>i1</sub>	RF sensitivity input voltage	S/N = 26 dB	40	55	70	μV
THD	total harmonic distortion	V <sub>i1</sub> = 1 mV	_	0.8	2.0	%
FM perform	nance; note 2					
V <sub>10</sub>	AF output voltage	V <sub>i4</sub> = 5 mV	40	48	57	mV
V <sub>i4</sub>	IF sensitivity input voltage	$V_{10} = -3 \text{ dB};$ $V_{10} = 0 \text{ dB at } V_{i4} = 10 \text{ mV}$	_	20	30	μV
THD	total harmonic distortion	IF filter SFE10.7MS3A20K-A	_	0.3	0.8	%
MPX perfo	rmance; note 3		'	•	•	•
$\alpha_{ t CS}$	channel separation	V <sub>i4</sub> = 30 mV	26	30	_	dB

#### Notes

- 1. Conditions AM:  $V_{CC1} = 3 \text{ V}$ ;  $V_{CC2} = 12 \text{ V}$ ;  $V_{DDD} = 3 \text{ V}$ ;  $f_i = 1 \text{ MHz}$ ; m = 0.3;  $f_m = 1 \text{ kHz}$ ; measured in Fig.8 with S1 in position A and S2 in position B; unless otherwise specified.
- 2. Conditions FM:  $V_{CC1} = 3 \text{ V}$ ;  $V_{CC2} = 12 \text{ V}$ ;  $V_{DDD} = 3 \text{ V}$ ;  $f_i = 10.7 \text{ MHz}$ ;  $\Delta f_m = 22.5 \text{ kHz}$ ;  $f_m = 1 \text{ kHz}$ ; measured in Fig.8 with S2 in position A and S3 in position A; unless otherwise specified.
- 3. Conditions MPX:  $V_{CC1} = 3 \text{ V}$ ;  $V_{CC2} = 12 \text{ V}$ ;  $V_{DDD} = 3 \text{ V}$ ;  $V_{i3(L+R)} = 155 \text{ mV}$ ;  $V_{pilot} = 15.5 \text{ mV}$ ;  $V_{i} = 1 \text{ kHz}$ ; measured in Fig.8 with S2 in position B and S3 in position B; unless otherwise specified.

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#### **BLOCK DIAGRAM**



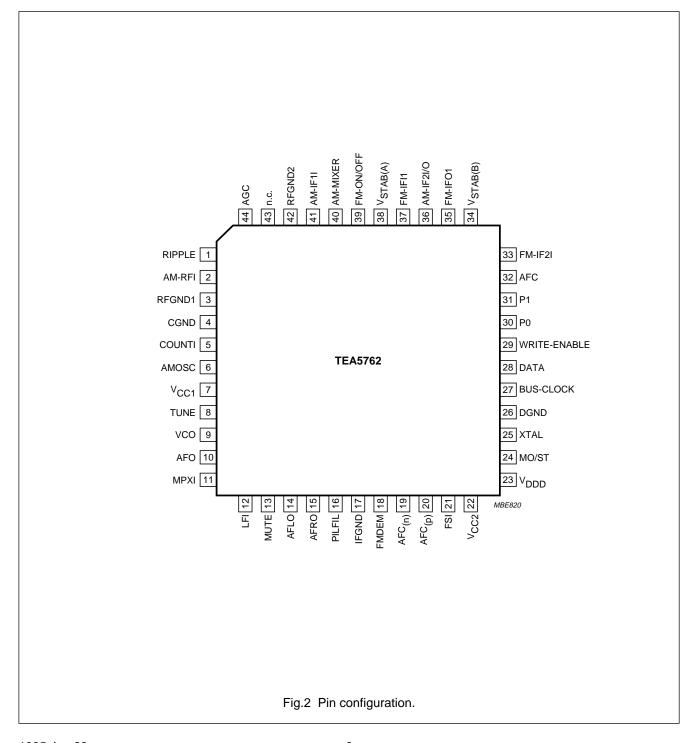
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#### **PINNING**

SYMBOL	PIN	DESCRIPTION
RIPPLE	1	ripple capacitor input
AM-RFI	2	AM-RF input
RFGND1	3	RF ground 1 and substrate
CGND	4	counter ground
COUNTI	5	counter input
AMOSC	6	parallel tuned AM oscillator circuit to ground
V <sub>CC1</sub>	7	supply voltage 1
TUNE	8	tuning output current
VCO	9	voltage controlled oscillator input
AFO	10	AM/FM AF output (output impedance typical 5 k $\Omega$ )
MPXI	11	stereo decoder input (input impedance typical 150 k $\Omega$ )
LFI	12	loop-filter input
MUTE	13	mute input
AFLO	14	left channel output (output impedance typical 4.3 k $\Omega$ )
AFRO	15	right channel output (output impedance typical 4.3 k $\Omega$ )
PILFIL	16	pilot detector filter input
IFGND	17	ground of IF, detector and MPX stage
FMDEM	18	ceramic discriminator input
AFC <sub>(n)</sub>	19	AFC negative output
AFC <sub>(p)</sub>	20	AFC positive output
FSI	21	field-strength indicator
V <sub>CC2</sub>	22	supply voltage 2 (for tuning)
$V_{DDD}$	23	digital supply voltage
MO/ST	24	mono/stereo and tuning indication output
XTAL	25	crystal input
DGND	26	digital ground
BUS-CLOCK	27	bus-clock input
DATA	28	bus data input/output
WRITE-ENABLE	29	bus write enable input
P0	30	programmable output port (P0)
P1	31	programmable output port (P1)
AFC	32	450 kHz LC input circuit for AM AFC
FM-IF2I	33	FM-IF input 2 (input impedance typical 330 $\Omega$ )
V <sub>STAB(B)</sub>	34	internal stabilized supply voltage (B)
FM-IFO1	35	FM-IF output 1 (input impedance typical 330 $\Omega$ )
AM-IF2I/O	36	input/output to IFT; output current source
FM-IFI1	37	FM-IF input 1 (input impedance typical 330 $\Omega$ )
V <sub>STAB(A)</sub>	38	internal stabilized supply voltage (A)
FM-ON/OFF	39	FM ON/OFF port
AM-MIXER	40	open-collector output to IFT

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SYMBOL	PIN	DESCRIPTION
AM-IF1I	41	IFT or ceramic filter input (input impedance typical 3 k $\Omega$ )
RFGND2	42	FM-RF ground 2
n.c.	43	not connected
AGC	44	AGC capacitor input



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#### **FUNCTIONAL DESCRIPTION**

The TEA5762 is an integrated radio circuit with AM-receiver and FM-IF part with demodulator and stereo decoder. The circuit includes digital tuning and control functions.

#### The radio

The AM circuit incorporates a double balanced mixer, a one-pin low voltage oscillator (up to 30 MHz) and is designed for distributed selectivity.

The AM input is designed to be connected to the top of a tuned circuit. AGC controls the IF amplification and for large signals it lowers the input impedance of the AM front end.

The first AM selectivity can be an IF-Tank (IFT) or an IFT combined with a ceramic filter; the second one is an IFT.

For FM operation an external FM front end is necessary. This is switched on and off by the FM-ON/OFF signal which is generated in the bus system.

The AFC circuit in the TEA5762 provides a tuning voltage to drive the VCO of the external FM front end.

The frequency of the external VCO is counted in the Self Tuned Radio (STR) tuning system.

The FM-IF circuit is designed for distributed IF ceramic filters. The FM quadratic detector uses a ceramic resonator.

The PLL stereo decoder incorporates a signal dependent stereo-blend circuit and a soft-mute circuit.

#### **Tuning**

The tuning-concept of STR is based on FUZZY LOGIC: it mimics hand tuning (hand tuning is a combination of coarse and fine tuning to the qualitatively best frequency position). As a consequence the tuning system is very fast.

The tuning algorithm, which is controlled by the sequential circuit (see Fig.1), is completely integrated. Thus only a few external components are required.

The bus and the microcontroller can be kept very simple. The bus only consists of three wires (bus-clock, data and write enable). The microcontroller must basically give two instructions:

- · Preset operation
- · Search operation.

#### PRESET OPERATION

In preset mode, the microcontroller has to load information such as frequency band, frequency and mono/stereo. This information has to be sent via the bus to STR. The internal algorithm controls the tuning sequence as follows: the information is loaded into a shift register, a last-station memory and the counter. The Automatic Frequency Control (AFC) is switched off. The counter starts counting the VCO frequency and the tuning voltage is varied until the desired frequency roughly equals the real frequency. The AFC is then switched on and the counter is switched off. The real frequency is now tuned precisely to the desired frequency.

After the AFC has tuned the real frequency to the desired frequency an in-lock signal can be generated. In order to obtain a reliable in-lock signal, there are two parameters measured: the field strength and the S-curve. The field strength indicates the strength of the station and by looking at the S-curve the system can distinguish false in-locks from real in-locks (false in-locks occur on the wrong slope of the S-curve).

In the FM mode the tuning voltage controls the VCO of the external FM front end and the frequency of the VCO is counted in the TEA5762.

In the event of fading or pulling, the in-lock signal becomes logic 0, the synthesizer will be switched on again and the algorithm will be repeated.

#### **SEARCH OPERATION**

During a search operation, the only action the microcontroller has to take is: sending the desired band plus the direction and the search sensitivity level to STR. The search operation is performed by the charge pump until an in-lock signal is generated (combination of measuring the field strength and the S-curve). The AFC then fine tunes to the station. The frequency belonging to the found station will be counted by the counter and written into the last-station memory and the shift register of the counter. At this time the frequency is available in the shift register and can be read by the microcontroller. The microcontroller decides whether the frequency is within the desired frequency band. If it is, this frequency can be stored under a preset and if it is not, a new search action should be started.

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#### Description of the bus

The TEA5762 radio has a bus which consists of three wires, as shown in Table 1.

These three signals, together with the mono/stereo pin (MO/ST, pin 24), communicate with the microcontroller. The mono/stereo indicator has two functions, which are controlled by the bus-clock, as shown in Table 2.

The TEA5762 has a 25-bit shift register; see Table 3 for an explanation of the shift register bits.

If in search mode no transmitter can be found, all frequency bits of the shift register are set to logic 1.

The bus protocol is depicted in Figs 3 and 4.

Table 1 Bus signals

SIGNAL	PIN	DESCRIPTION
BUS-CLOCK	27	software driven clock input
DATA	28	data input/output
WRITE-ENABLE	29	write/read-input

Table 2 Bus clock functions

BUS CLOCK	PIN 24	RESULT
LOW	LOW	stereo
LOW	HIGH	mono
HIGH	LOW	tuned
HIGH	HIGH	not tuned

Table 3 Explanation of the shift register bits

BIT	DESCRIPTION	LOGIC STATE	RESULT
S.24 (MSB)	search start/end	0	after a search when a station is found or after a preset
		1	during the search action
D.23	search up/down	0	indicates if the radio has to search down
		1	indicates if the radio has to search up
M.22	mono/stereo	0	stereo is allowed
		1	mono is required (radio switched to forced mono)
B0.21	band	see Table 4	selects FM/MW/LW/SW band
B1.20	band	see Table 4	selects FM/MW/LW/SW band
P0.19	port	note 1	user programmable bits which e.g. can be used as band switch driver
P1.18	port	note 1	user programmable bits which e.g. can be used as band switch driver
S0.17	search-level of station	see Table 5	determines the locking field strength during an automatic search, automatic store or manual search
S1.16	search-level of station	see Table 5	determines the locking field strength during an automatic search, automatic store or manual search
15	dummy	_	buffer
F.14 to F.0 (LSB)	frequency	_	determine the tuning frequency of the radio; see Table 6 for the bit values

#### Note

- 1. The output pins 30 and 31 can drive currents up to 5 mA. Bits 19 (P0) and 18 (P1) control the output voltage of the control pins P0 (pin 30) and P1 (pin 31):
  - a) bit 19 (P0) LOW sets P0 (pin 30) to LOW
  - b) bit 19 (P0) HIGH sets P0 (pin 30) to HIGH
  - c) bit 18 (P1) LOW sets P1 (pin 31) to LOW
  - d) bit 18 (P1) HIGH sets P1 (pin 31) to HIGH.

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Table 4 Truth table for bits 21 and 20

В0	B1	BAND SELECT
0	0	FM <sup>(1)</sup>
0	1	MW
1	0	LW
1	1	SW

#### Note

1. When FM is selected, the control output FM-ON/OFF is set LOW to switch on the external FM front end.

**Table 5** Truth table for bits 16 and 17

S1 S0		SIGNAL RECEPTION(1)			
31	30	FM IF INPUT AM RF INPUT			
0	0	>50 μV	>28 μV		
0	1	>100 μV	>40 μV		
1	0	>300 μV	>63 μV		
1	1	>1500 μV	>1000 μV		

#### Note

1. The given values for signal reception are corresponding to a -3 dB point of 20  $\mu$ V for FM.

Table 6 Values for bits 14 to 0

ВІТ	BIT VALUE	FM VALUE <sup>(1)</sup> (kHz)	AM VALUE <sup>(2)</sup> (kHz)
14	214	_	16384
13	2 <sup>13</sup>	102400	8192
12	212	51200	4096
11	2 <sup>11</sup>	25600	2048
10	2 <sup>10</sup>	12800	1024
9	2 <sup>9</sup>	6400	512
8	28	3200	256
7	2 <sup>7</sup>	1600	128
6	2 <sup>6</sup>	800	64
5	2 <sup>5</sup>	400	32
4	24	200	16
3	2 <sup>3</sup>	100	8
2	2 <sup>2</sup>	50	4
1	21	25	2
0	20	12.5	1

#### Notes

- FM value of the affected oscillators;
   FM VALUE = FM-RF + FM-IF.
- AM value of the affected oscillators;AM VALUE = AM-RF + AM-IF.

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#### READING DATA

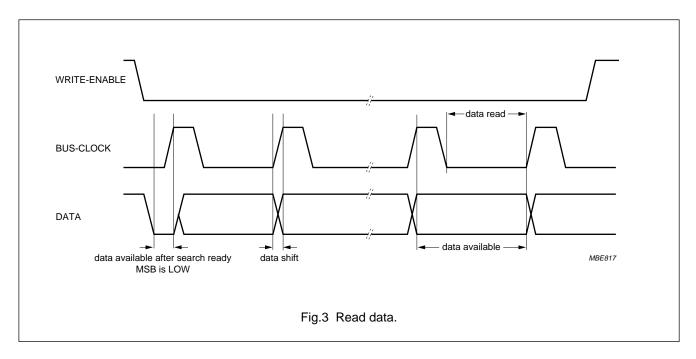
While write enable is LOW data can be read by the microcontroller. At a rising edge of the bus-clock, data is shifted out of the register. This data is available from the point where the bus-clock is HIGH until the next rising edge of the bus-clock occurs; see Fig.3

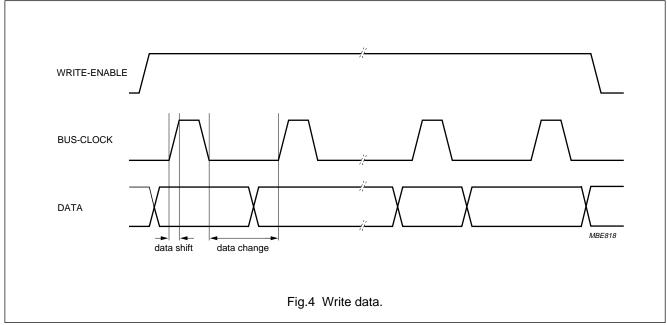
To read the entire shift register 24 clock pulses are necessary.

#### WRITING DATA

While write enable is HIGH the microcontroller can transmit data to the TEA5762 (hard mute is active). At a rising edge of the bus-clock, the register shifts and accepts one bit into LSB. At clock LOW the microcontroller writes data; see Fig.4.

To write the entire shift register 25 clock pulses are necessary.





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#### **BUS TIMING**

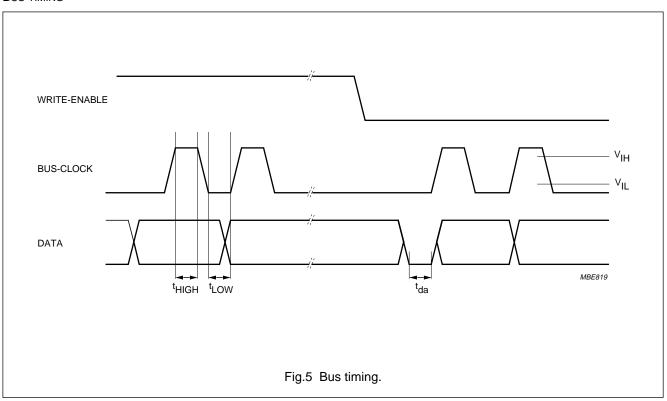


Table 7 Digital inputs

SYMBOL	PARAMETER	MIN.	MAX.	UNIT
Digital inputs		•	·	·
V <sub>IH</sub>	HIGH level input voltage	1.4	_	V
V <sub>IL</sub>	LOW level input voltage	_	0.6	V
Timing		•	•	•
f <sub>clk</sub>	clock input	_	300	kHz
t <sub>HIGH</sub>	clock HIGH time	1.67	_	μs
t <sub>LOW</sub>	clock LOW time	1.67	_	μs
t <sub>da</sub>	shift register available after 'search ready'	_	14	μs

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#### **LIMITING VALUES**

In accordance with the Absolute Maximum Rating System (IEC 134).

SYMBOL	PARAMETER	CONDITIONS	MIN.	MAX.	UNIT
V <sub>CC1</sub>	supply voltage 1		0	13.2	V
P <sub>tot</sub>	total power dissipation	T <sub>amb</sub> = 70 °C	_	250	mW
T <sub>stg</sub>	storage temperature		-65	+150	°C
T <sub>amb</sub>	operating ambient temperature		-15	+60	°C
Tj	operating junction temperature		-15	+150	°C
V <sub>es</sub>	electrostatic handling for all pins	note 1	_	±200	V

#### Note

1. Charge device model: equivalent to discharging a 200 pF capacitor via a 0  $\Omega$  series resistor.

#### THERMAL CHARACTERISTICS

SYMBOL	PARAMETER	VALUE	UNIT
R <sub>th j-a</sub>	thermal resistance from junction to ambient in free air	65	K/W

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#### **CHARACTERISTICS**

 $V_{CC1}$  = 3 V;  $T_{amb}$  = 25 °C; unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
V <sub>CC1</sub>	supply voltage 1		2.5	_	12	V
V <sub>CC2</sub>	supply voltage 2 for tuning		_	_	12	V
$V_{DDD}$	digital supply voltage		2.5	-	12	V
V <sub>tune</sub>	tuning voltage		0.7	_	V <sub>CC2</sub> - 0.75	V
I <sub>CC2</sub>	supply current 2 for tuning in preset mode (band-end to band-end)		_	_	640	μΑ
f <sub>clk(max)</sub>	maximum bus-clock frequency		_	_	300	kHz
I <sub>CC1</sub>	current consumption during acquisition of V <sub>CC1</sub>	AM mode	12	15	18	mA
		FM mode	12.5	15.5	18.5	mA
I <sub>DDD</sub>	current consumption during acquisition of I <sub>DDD</sub>	AM mode	_	4.8	_	mA
		FM mode	_	5.5	_	mA
I <sub>CC1</sub>	current consumption after acquisition of V <sub>CC1</sub>	AM mode	12	15	18	mA
		FM mode	13	16	19	mA
I <sub>DDD</sub>	current consumption after acquisition of I <sub>DDD</sub>	AM mode	_	3.2	_	mA
		FM mode	_	2.7	_	mA
t <sub>search</sub>	synthesizer auto-search time for empty band	FM mode	_	-	10	s
t <sub>acqu</sub>	synthesizer preset acquisition time between two	FM	_	100	_	ms
	band limits	MW	_	150	_	ms
		LW	_	1000	_	ms
		SW	_	500(1)	_	ms
f <sub>band</sub>	frequency band range of the synthesizer	AM mode	0.144	_	30	MHz
$\Delta f_{FM}$	AFC inaccuracy of FM	with Mitsumi front end	_	_	1	kHz
$\Delta f_{AM}$	AFC inaccuracy of AM		_	_	100	Hz
I <sub>P0/P1(sink)</sub>	sink current of software programmable output P0/P1	V <sub>CC1</sub> = 5 V	_	_	7	mA
I <sub>P0/P1(source)</sub>	source current of software programmable output P0/P1	V <sub>CC1</sub> = 5 V	5	_	7	mA

#### Note

1. Depending on band.

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#### **AM CHARACTERISTICS**

Input frequency = 1 MHz; m = 0.3;  $f_{mod} = 1$  kHz; measured in test circuit at pin 10 (see Fig.8); S2 in position B;  $V_{i1}$  measured at input of matching network at pin 2; matching network adjusted to maximum output voltage at low input level; refer to test circuit (see Fig.8); unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
V <sub>10</sub>	AF output voltage	$V_{i1} = 5 \text{ mV}$	36	45	70	mV
V <sub>i1</sub>	RF sensitivity input voltage	S/N = 26 dB	40	55	70	μV
V <sub>il</sub>	large signal voltage handling capacity	m = 0.8; THD ≤ 8%	150	300	_	mV
PSSR	power supply ripple rejection $(V_{10}/\Delta V_7)$	$\Delta V_7 = 100 \text{ mV (RMS)};$ 100 Hz; $V_7 = 3.0 \text{ V}$	_	-47	_	dB
li	input current (pin 2)	V <sub>44</sub> = 0.2 V	_	0	_	μΑ
C <sub>i</sub>	input capacitance (pin 2)	V <sub>44</sub> = 0.2 V	_	_	4	pF
G <sub>c</sub>	front end conversion gain	V <sub>44</sub> = 0.2 V	5	10	14	dB
		V <sub>44</sub> = 0.9 V	-26	-14	0	dB
S/N	signal-to-noise ratio		_	50	_	dB
THD	total harmonic distortion	V <sub>i1</sub> = 1 mV	_	0.8	2.0	%
α <sub>450</sub>	IF suppression	V <sub>10</sub> = 30 mV	_	56	_	dB

#### **FM-IF CHARACTERISTICS**

Input frequency = 10.7 MHz;  $\Delta f$  = 22.5 kHz;  $f_{mod}$  = 1 kHz; measured in test circuit (see Fig.8) at pin 10; S2 in position B; refer to test circuit (see Fig.8); unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
V <sub>10</sub>	AF output voltage	V <sub>i4</sub> = 10 mV	40	48	57	mV
V <sub>i4</sub>	IF limiting sensitivity	$V_{10} = -3 \text{ dB}; V_{10} = 0 \text{ dB at}$ $V_{i4} = 10 \text{ mV}$	_	50	80	μV
PSSR	power supply ripple rejection $(V_{10}/\Delta V_7)$	$\Delta V_7 = 100 \text{ mV (RMS)};$ 100 Hz; $V_7 = 3.0 \text{ V}$	-44	_	_	dB
S/N	signal-to-noise ratio	V <sub>i4</sub> = 10 mV	62	_	_	dB
THD	total harmonic distortion	IF filter SFE10.7MS3A20K-A	_	0.3	0.8	%

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#### STEREO DECODER CHARACTERISTICS

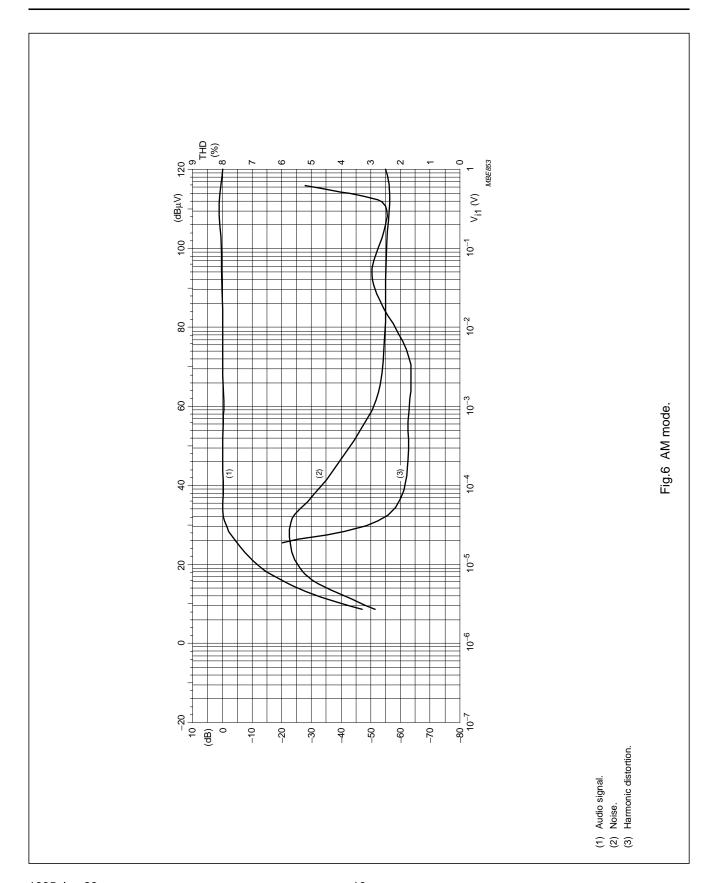
 $V_{i3(L+R)}$  = 155 mV;  $V_{pilot}$  = 15.5 mV; f = 1 kHz; apply unmodulated RF signal of 100 mV to front end to set radio to maximum channel separation; soft mute off (S4 in position A); unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
V <sub>14/15</sub>	AF output voltage		_	160	_	mV
V <sub>pilot(s)</sub>	switch to stereo		_	8	12	mV
V <sub>pilot(m)</sub>	switch to mono		2	5	_	mV
V <sub>AF-L</sub> /V <sub>i3</sub>	MPX voltage gain		-1.5	_	+1.5	dB
S/N	signal-to-noise ratio	V <sub>pilot</sub> = 15.5 mV (stereo)	_	74	_	dB
THD	total harmonic distortion		_	0.5	1.0	%
$\alpha_{cs}$	channel separation		26	30	_	dB
α <sub>19</sub>	carrier and harmonic suppression	19 kHz (200 mV) = 0 dB	27	32	_	dB
α <sub>38</sub>		38 kHz	16	21	_	dB
α	stereo-blend	V <sub>i4</sub> = 5 mV	22	30	_	dB
		$V_{i4} = 200 \mu V$	_	1	2	dB
mute(s)	soft mute depth	$V_{i4} = 30 \mu V; V_{14} = V_{15}$	-1	0	_	dB
		$V_{i4} = 10 \mu V; V_{14} = V_{15}$	_	-6	-10	dB

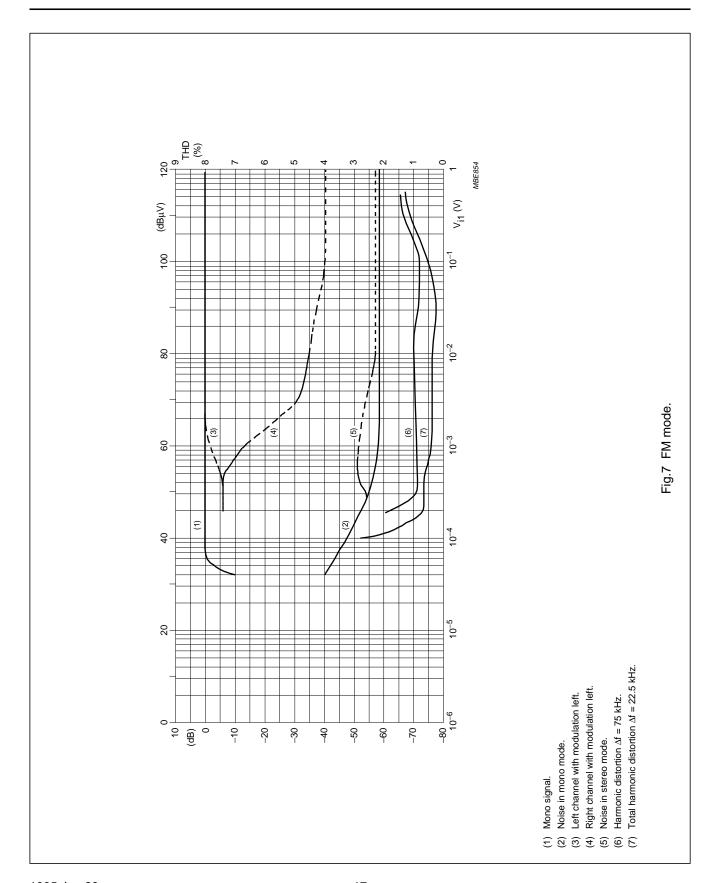
#### **TUNING CHARACTERISTICS**

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
$V_{FM}$	FM voltage levels	$\alpha_{-3 \text{ dB}}$ -point at $V_{i4} = 20 \mu V$				
	high (auto-store/search)	S0 = 1; S1 = 1	600	1500	5000	μV
	medium (auto-store/search)	S0 = 0; S1 = 1	100	300	550	μV
	low (auto-store/search)	S0 = 1; S1 = 0	40	100	200	μV
	nominal (preset mode/tuning indication)	S0 = 0; S1 = 0	30	50	90	μV
V <sub>AM</sub>	AM voltage levels	$\alpha_{-3 \text{ dB}}$ -point at $V_{i4} = 20 \mu V$				
	high (auto-store/search)	S0 = 1; S1 = 1	400	1000	2500	μV
	medium (auto-store/search)	S0 = 0; S1 = 1	50	63	80	μV
	low (auto-store/search)	S0 = 1; S1 = 0	32	40	50	μV
	nominal (preset mode/tuning indication)	S0 = 0; S1 = 0	25	28	40	μV
V <sub>AFC(off)</sub>	AFC voltage off mode	$\alpha_{-3 \text{ dB}}$ -point at $V_{i4} = 20 \mu V$				
		FM mode	_	3	_	μV
		AM mode	_	25	_	μV
mute(h)	hard mute	write enable HIGH	_	60	_	dB

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#### INTERNAL CIRCUITS

Table 8 Equivalent pin circuits and pin voltages

PIN	SYMBOL	SYMBOL DC VOLTAGE (V)		EQUIVALENT CIRCUIT
		AM	FM	
1	RIPPLE	2.1	2.1	1 kΩ 1 kΩ 70 pF MBE821
2	AM-RFI	0	0	4
3	RFGND1	_	_	
4	CGND	0	0	
5	COUNTI	0	0	5 MBE823
6	AMOSC	0	0	6 MBE824
7	V <sub>CC1</sub>	3.0	3.0	

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PIN	DC VOLTAGE (V)			EQUIVALENT CIRCUIT
		AM	FM	
8	TUNE	-	-	8 8 MBE 825
9	VCO	1.3	0.95	9 10 kΩ MBE826
10	AFO	0.6	0.7	10 17 MBE827
11	MPXI	1.23	1.23	150 kΩ 150 kΩ 17 150 kΩ MBE828

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PIN	DC VOLTAGE (V)			EQUIVALENT CIRCUIT
	AM FM			
12	LFI	0.1	0.8	12 13 kΩ 17 MBE829
13	MUTE	0.7	0.7	13
14	AFLO	0.65	0.65	14 5 kΩ MBE831
15	AFRO	0.65	0.65	15 5 kΩ MBE832

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PIN	SYMBOL	DC VOL		EQUIVALENT CIRCUIT
		AM	FM	
16	PILFIL	0.95	0.95	10 kΩ 10 kΩ MBE833
17	IFGND	0	0	
18	FMDEM	_	1.0	180 Ω 910 Ω MBE834
19	AFC <sub>(n)</sub>	_	_	
20	AFC <sub>(p)</sub>	_	-	10 kΩ 10 kΩ 0 19/20 0 MBE835
21	FSI	_	_	1.4 V 40 kΩ  12 to 34 kΩ (dependent on bits 16 and 17)  MBE836
22	V <sub>CC2</sub>	_	_	
23	V <sub>DDD</sub>	3.0	3.0	

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PIN	SYMBOL	DC VOLTAGE (V)		EQUIVALENT CIRCUIT
		AM	FM	
24	MO/ST	-	_	24 100 Ω 26 MBE837
25	XTAL	_	_	50 kΩ 50 kΩ 50 kΩ MBE838
26	DGND	0	0	
27	BUS-CLOCK	_	_	27 MBE839
28	DATA	-	_	100 Ω
29	WRITE- ENABLE	-	_	28 100 kΩ 29 26 MBE840

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PIN	SYMBOL	DC VOI		EQUIVALENT CIRCUIT
		AM	FM	
30	P0	_	_	23 0 + + + -
31	P1	_	-	30/31 ο
32	AFC	_	_	34 20 kΩ MBE842
33	FM-IF2I	-	0.73	34 140 Ω 2.2 kΩ 6 pF 11 MBE843
34	V <sub>STAB(B)</sub>	1.4	1.4	1 kΩ 1 MBE844

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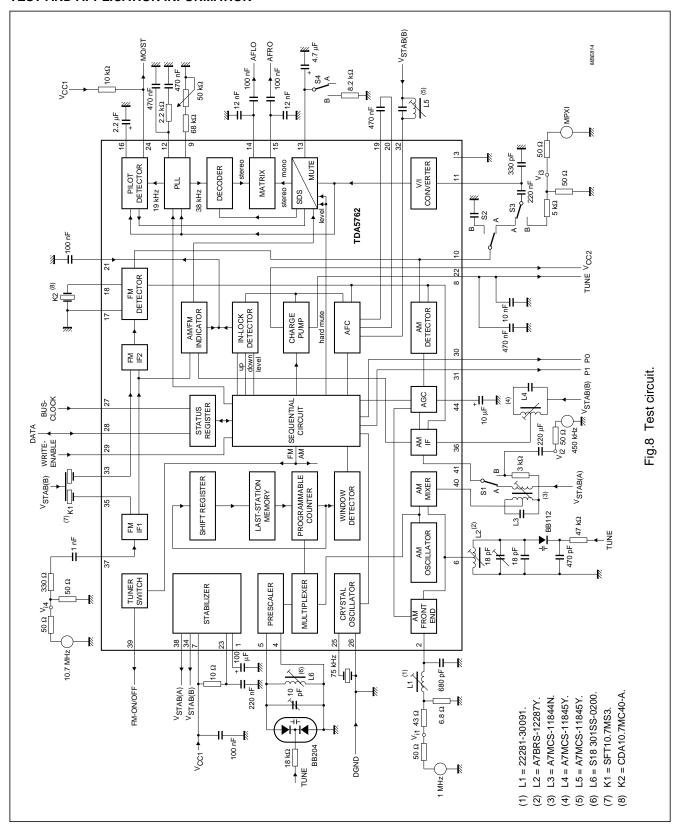
PIN	SYMBOL	DC VOLTAGE (V)		EQUIVALENT CIRCUIT				
		AM	FM					
35	FM-IFO1	-	0.69	35 560 Ω MBE845				
36	AM-IF2I/O	1.4	1.4	34 36 3.6 kΩ 3.6 kΩ MBE846				
37	FM-IFI1	-	0.73	38 37 140 Ω 1.9 kΩ 6 pF 1.9 kΩ				
38	V <sub>STAB(A)</sub>	1.4	1.4	1 kΩ 1 MBE848				
39	FM-ON/OFF	-	-	39 ·				

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PIN	SYMBOL	DC VOLTAGE (V)		EQUIVALENT CIRCUIT			
		AM	FM				
40	AM-MIXER	1.4	1.4	38 MBE850			
41	AM-IF1I	1.4	1.4	38 3 κΩ 7.5 κΩ 7.5 κΩ MBE851			
42	RFGND2	0	0				
43	n.c.	_	_				
44	AGC	0.1	0.7	$\begin{array}{c} 1 \text{ k}\Omega \\ 1 \text{ k}\Omega \\ 1 \text{ MBE852} \end{array}$			

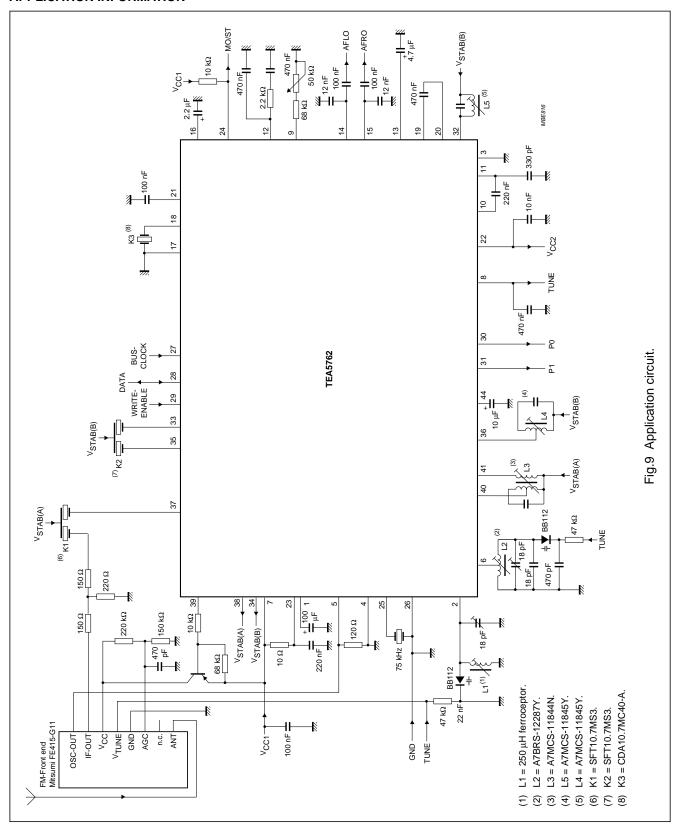
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#### **TEST AND APPLICATION INFORMATION**



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#### **APPLICATION INFORMATION**

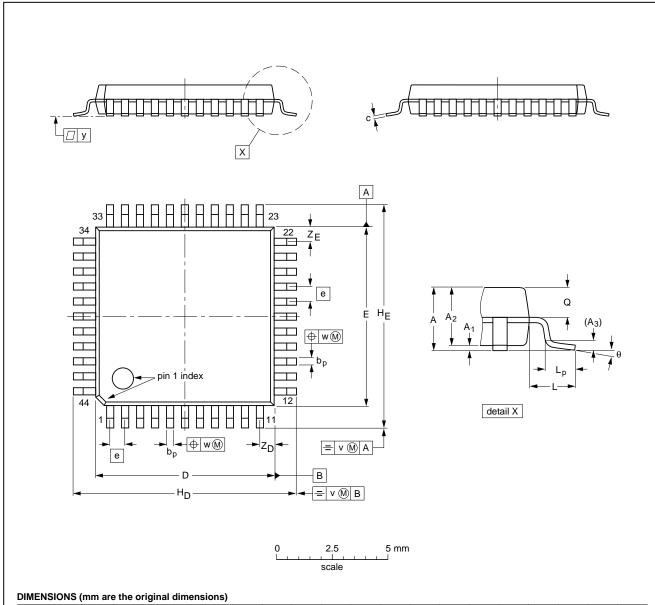


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#### **PACKAGE OUTLINE**

QFP44: plastic quad flat package; 44 leads (lead length 1.3 mm); body 10 x 10 x 1.75 mm

SOT307-2



UNIT	A max.	A <sub>1</sub>	A <sub>2</sub>	A <sub>3</sub>	bp	С	D <sup>(1)</sup>	E <sup>(1)</sup>	е	H <sub>D</sub>	HE	L	Lp	ø	v	w	у	Z <sub>D</sub> <sup>(1)</sup>	Z <sub>E</sub> <sup>(1)</sup>	θ
mm	2.10	0.25 0.05	1.85 1.65	0.25	0.40 0.20	0.25 0.14	10.1 9.9	10.1 9.9	0.8	12.9 12.3	12.9 12.3	1.3	0.95 0.55	0.85 0.75	0.15	0.15	0.1	1.2 0.8	1.2 0.8	10° 0°

#### Note

1. Plastic or metal protrusions of 0.25 mm maximum per side are not included.

OUTLINE		REFER	EUROPEAN	ISSUE DATE		
VERSION	IEC	JEDEC	EIAJ		PROJECTION	ISSUE DATE
SOT307-2						<del>92-11-17</del> 95-02-04

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#### **SOLDERING QFP or SO**

#### Introduction

There is no soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and surface mounted components are mixed on one printed-circuit board. However, wave soldering is not always suitable for surface mounted ICs, or for printed-circuits with high population densities. In these cases reflow soldering is often used.

This text gives a very brief insight to a complex technology. A more in-depth account of soldering ICs can be found in our "IC Package Databook" (order code 9398 652 90011).

#### Reflow soldering

Reflow soldering techniques are suitable for all QFP and SO packages.

The choice of heating method may be influenced by larger plastic QFP packages (44 leads, or more). If infrared or vapour phase heating is used and the large packages are not absolutely dry (less than 0.1% moisture content by weight), vaporization of the small amount of moisture in them can cause cracking of the plastic body. For more information, refer to the Drypack chapter in our "Quality Reference Manual" (order code 9398 510 63011).

Reflow soldering requires solder paste (a suspension of fine solder particles, flux and binding agent) to be applied to the printed-circuit board by screen printing, stencilling or pressure-syringe dispensing before package placement.

Several techniques exist for reflowing; for example, thermal conduction by heated belt. Dwell times vary between 50 and 300 seconds depending on heating method. Typical reflow temperatures range from 215 to 250 °C.

Preheating is necessary to dry the paste and evaporate the binding agent. Preheating duration: 45 minutes at  $45\,^{\circ}\text{C}$ .

#### Wave soldering

QFP

Wave soldering is **not** recommended for QFP packages. This is because of the likelihood of solder bridging due to closely-spaced leads and the possibility of incomplete solder penetration in multi-lead devices.

If wave soldering cannot be avoided, the following conditions must be observed:

- A double-wave (a turbulent wave with high upward pressure followed by a smooth laminar wave) soldering technique should be used.
- The footprint must be at an angle of 45° to the board direction and must incorporate solder thieves downstream and at the side corners.

Even with these conditions, do not consider wave soldering the following packages: QFP52 (SOT379-1), QFP100 (SOT317-1), QFP100 (SOT317-2), QFP100 (SOT382-1) or QFP160 (SOT322-1).

SO

Wave soldering techniques can be used for all SO packages if the following conditions are observed:

- A double-wave (a turbulent wave with high upward pressure followed by a smooth laminar wave) soldering technique should be used.
- The longitudinal axis of the package footprint must be parallel to the solder flow.
- The package footprint must incorporate solder thieves at the downstream end.

METHOD (QFP or SO)

During placement and before soldering, the package must be fixed with a droplet of adhesive. The adhesive can be applied by screen printing, pin transfer or syringe dispensing. The package can be soldered after the adhesive is cured.

Maximum permissible solder temperature is 260 °C, and maximum duration of package immersion in solder is 10 seconds, if cooled to less than 150 °C within 6 seconds. Typical dwell time is 4 seconds at 250 °C.

A mildly-activated flux will eliminate the need for removal of corrosive residues in most applications.

#### Repairing soldered joints

Fix the component by first soldering two diagonally-opposite end leads. Use only a low voltage soldering iron (less than 24 V) applied to the flat part of the lead. Contact time must be limited to 10 seconds at up to 300 °C. When using a dedicated tool, all other leads can be soldered in one operation within 2 to 5 seconds at 270 to 320 °C.

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#### **DEFINITIONS**

Data sheet status							
Objective specification	This data sheet contains target or goal specifications for product development.						
Preliminary specification	This data sheet contains preliminary data; supplementary data may be published later.						
Product specification	This data sheet contains final product specifications.						
Limiting values							
Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 134). Stress above one or							

Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

#### **Application information**

Where application information is given, it is advisory and does not form part of the specification.

#### LIFE SUPPORT APPLICATIONS

These products are not designed for use in life support appliances, devices, or systems where malfunction of these products can reasonably be expected to result in personal injury. Philips customers using or selling these products for use in such applications do so at their own risk and agree to fully indemnify Philips for any damages resulting from such improper use or sale.

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