# INTEGRATED CIRCUITS

# DATA SHEET



# TDA10085 Single Chip DVB-S/DSS Channel Receiver

Preliminary specification File under Integrated Circuits, IC02 2000 March 16





**TDA10085** 

# **FEATURES**

- DSS and DVB-S compliant single chip demodulator & forward error correction.
- Dual 6-bit ADC on chip.
- New PLL which allows the use of a low-cost Xtal (typically 4 Mhz).
- DiSEqC 1.X from 1 to 8 bytes long sequences with modulated/unmodulated output.
- DSS dish control
- · Digital Cancellation of A/D offset.
- Simultaneous Parallel and Serial Output interface.
- Variable rate BPSK/QPSK coherent demodulator.
- · Modulation rate from 1 to 45MBaud.
- · Automatic Gain Control output.
- Digital symbol timing recovery: Acquisition range up to ±960ppm
- Digital carrier recovery: Acquisition range up to 5Mhz
- Half Nyquist filters (roll-off = 0.35 for DVB and 0.2 for DSS).
- Interpolating and anti-aliasing filters to handle variable symbol rate.
- · Channel quality estimation.
- · Spectral inversion ambiguity resolution.
- · Viterbi decoder:

Supported rates: from 1/2 to 8/9.

Constraint length K = 7

with  $G1 = 171_{8}^{\circ} G2 = 133_{8}^{\circ}$ 

Viterbi Output BER measurement.

Automatic code rate search within 1/2, 2/3 and 6/7 in DSS mode.

Automatic code rate search within 1/2, 2/3, 3/4, 5/6 and 7/8 in DVB-S mode.

- Convolutional deinterleaver and Reed Solomon decoder according to DVB and DSS specifications.
- Automatic Frame Synchronization.
- · Selectable DVB-S descrambling.
- I<sup>2</sup>C bus interface.
- 64-pin TQFP package.
- CMOS technology (0.2 μm 1.8V/3.3V).

# **APPLICATIONS**

- DVB-S receivers (ETS 300-421).
- · DSS receivers.

# **DESCRIPTION**

The TDA10085 is a single-chip channel receiver for satellite television reception which matches both DSS and DVB-S standards. The device contains a dual 6-bit flash analog to digital converter, variable rate BPSK/QPSK coherent demodulator and Forward Error Correction functions. The ADCs directly interface with I and Q analog baseband signals. After A to D conversion, the TDA10085 implements a bank of cascadable filters as well as antialias and half-Nyquist filters. Analog AGC signal is generated by an amplitude estimation function. The TDA10085 performs clock recovery at twice the Baud rate and achieves coherent demodulation without any feedback to the local oscillator. Forward Error Correction is built around two error correcting codes: a Reed-Solomon (outer code), and a Viterbi decoder (inner code). The Reed-Solomon decoder corrects up to 8 erroneous bytes among the N (204) bytes of one data packet. Convolutional deinterleaver is located between the Viterbi output and the R.S. decoder input. De-interleaver and R.S. decoder are automatically synchronized thanks to the frame synchronisation algorithm which uses the sync pattern present in each packet. The TDA10085 is controlled via an I2C bus interface. The circuit operates up to 100MHz and can process variable modulation rates, up to 45Mbaud.

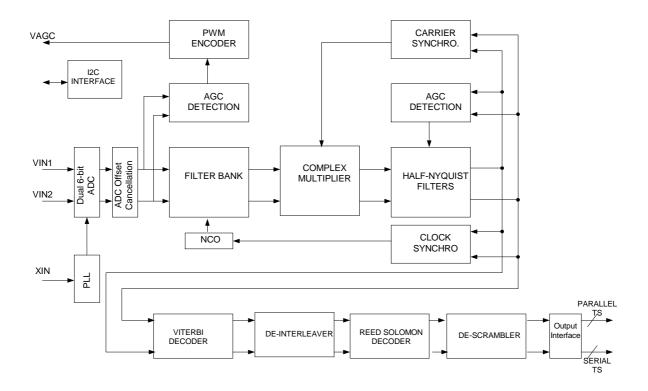
The TDA10085 provides an interrupt line which can be programmed on either events or timing information.

Designed in 0.20 CMOS technology and housed in a 64-TQFP package, the TDA10085 operates over the commercial temperature range.

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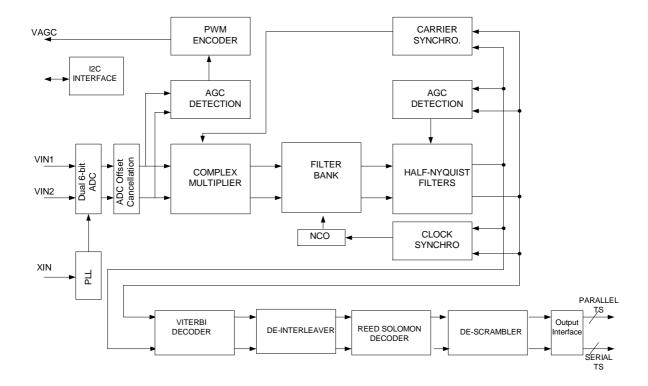
# **FIGURE 1. BLOCK DIAGRAM**

# 1.1 WITH COMPLEX MULTIPLIER AFTER ANTI-ALIASING FILTERS (POSMUL=0):



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# 1.2 WITH COMPLEX MULTIPLIER BEFORE ANTI-ALIASING FILTERS (POSMUL=1):



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**TABLE 1: ABSOLUTE MAXIMUM RATINGS** 

Parameter	Min	Max	Unit
Ambient operating temperature (Ta)	0	70	°C
DC supply voltage	- 0.5	+4.1	V
DC Core supply voltage	t.b.d	t.b.d	
DC input voltage	- 0.5	VDD + 0.5	V
DC input current		± t.b.d	mA
Lead Temperature		+ t.b.d	°C
Junction Temperature		+ t.b.d	°C

Stresses above the absolute maximum ratings may cause permanent damage to the device. Exposure to absolute maximum ratings conditions for extended periods may affect device reliability.

**TABLE 2: RECOMMENDED OPERATING CONDITIONS** 

Symbol	Parameter	Min	Тур	Max	Unit	Notes
VDDE	Digital supply voltage	3.0	3.3	3.6	V	3.3V ±10%
VDDI	Digital Core Supply Voltage	1.62	1.8	1.98	V	1.8V ±10%
VDDE5	5V supply voltage (for 5V Tolerance)	4.5	5	5.5	V	pin 25
VDD3	3V ADC Digital supply voltage		3.3			
Та	Operating temperature	0		70	° C	
AVD	Analog supply voltage	3.0	3.3	3.6	V	
AVS	Analog ground		0		V	
VINDC	DC Analog Input	VREFN		VREFP	V	
VINAC	AC Analog Input		750		mVpp	
ZIN	Analog input impedance	t.b.d	t.b.d		Ohms	
CIN	Analog input capacitance	t.b.d	t.b.d	t.b.d	pF	
VREFP	Top voltage reference		t.b.d		V	
VREFN	Bottom voltage reference		t.b.d		V	
XIN	Crystal frequency		4 Mhz		MHz	
SINAD (1)	ADC signal to noise ratio		t.b.d		dB	
THD(2)	Total Harmonic Distorsion		t.b.d		dB	
VIH(3)	High-level input voltage	t.b.d		t.b.d	V	TTL input
VIL	Low-level input voltage	t.b.d		t.b.d	V	TTL input
VOH(4)	High-level output voltage	t.b.d			V	@IOH = -2mA to -4mA
VOL(4)	Low-level output voltage			t.b.d	V	@IOL = + 2 mA to +4mA
IDD	Supply current		t.b.d		mA/MBaud	@XIN = 4Mhz/
				<u> </u>		96 Mhz Sampling
CIN	Input capacitance		t.b.d		pF	1MHz input to VSS
COUT	Output capacitance		t.b.d		pF	1MHz input to VSS

<sup>(1) &</sup>lt;u>Signal-to-noise plus distortion ratio (SINAD)</u>: ratio between the RMS magnitude of the fundamental input frequency to the RMS magnitude of all other A/D output signals.

<sup>(2) &</sup>lt;u>Total harmonic distortion (THD)</u>: ratio of the RMS sum of all harmonics of the input signal (below one half of the sample rate) to the fundamental.

<sup>(3)</sup> All inputs are 5V tolerant except CLB# pin.

<sup>(4)</sup> IOH, IOL =  $\pm 4$ mA only for pins : OCLK, SDA, SCL\_0, SDA\_0.

# Single Chip DVB-S/DSS Channel Receiver

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### **FUNCTIONAL DESCRIPTION**

### % PLI

The TDA10085 implements a PLL used as clock multiplier by [M/(N.P)], so that the crystal can be low frequency (fundamental tone – typically 4Mhz)

### **% DUAL 6-BIT ADC**

The TDA10085 implements a dual 6-bit ADC. The architecture is a standard flash one based on 63 latched comparators determining simultaneously the precise analog signal level. No external voltage references are required to use the ADCs.

Furthermore, a new stage was added on the TDA10085 in order to cancel the possible offset generated by the A./D converter. This is especially important for the very low baud rate applications.

### **% FILTER BANK**

The filter bank contains 2 selectable Anti-Alias Low Pass filters (AAF) which, combined with cascadable decimation filters, allows to perform variable rate demodulation over a ratio of up to 45. An automatic selection of the filter Gain was added in the TDA10085 in order to facilitate the use of the IC.

### **% COMPLEX MUTIPLIER**

Coherent data demodulation (BPSK or QPSK) is performed by complex multiplication of the incoming symbol with the computed correction angle. This leads to a rotation and a stabilization of the PSK constellation when the algorithms of carrier and clock recovery have both converged.

The position of this complex multiplier is programmable and can be either after antialiasing filters or before any filtering.

# **% HALF NYQUIST FILTERS**

Half-Nyquist filtering is performed in each arm of the constellation. 2 programmable roll-off are available depending on the selected standard. The digital filter has 19 (roll-off 0.35) or 25 (roll-off 0.2) taps to provide an outband attenuation of 40dB.

# **& CARRIER SYNCHRONIZER**

The carrier synchronizer block implements successively a phase/frequency comparator, a programmable digital second order loop filter, a phase accumulator (NCO) that accumulates the phase error and drives a sine/cosine table to determine the angle for correction, applied to the complex multiplier.

### **& CLOCK SYNCHRONIZER**

The clock phase detector block implements the algorithm for variable rate digital timing recovery. The digital second order loop filter is programmable, and provides an 8-bit command to the NCO block for clock recovery.

# % AGC

This block calculates the magnitude of the I and Q channels after ADC converter. The value is then compared to a programmable threshold value, filtered and PWM encoded before being output on the VAGC pin.

Furthermore an internal AGC was added on the Half-Nyquist filters block in order to control the internal dynamic of the signal.

## **% VITERBI DECODER**

The Viterbi decoder performs a maximum likelihood estimation over the received data on the basis of four-bit quantized samples of the demodulated signals. The average truncation length is 144. The rate R can be chosen between R = 1/2 and R = 8/9 (punctured codes). Automatic viterbi rate recovery can be selected, so as automatic spectral inversion ambiguity resolution. The rate search is performed among rates 1/2, 2/3, 3/4, 5/6 and 7/8 In DVB-S standard and among rates 1/2, 2/3 and 6/7 in DSS mode. Output Bit Error Rate (VBER) is computed by the RS deocoder. Differential decoding is selectable. The Viterbi decoder provides decoded data and the corresponding clock.

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### **& FRAME SYNCHRONIZATION AND DEINTERLEAVING**

The Viterbi decoder provides errors which occur in bursts. The length of some error bursts may exceed that which can be reliably corrected by the Reed-Solomon decoder. The implemented de-interleaving is a convolutional one of depth 12 for DVB and 13 for DSS. The first operation consists in synchronizing the de-interleaver. This is accomplished by detecting  $\alpha$  consecutive sync Words (or sync) which are present as the first byte of each packet.

Next, the RAM memory associated with the de-interleaver fills up and the first deinterleaved bytes are provided to the input of the Reed-Solomon decoder. The state  $\underline{\text{mac}}$ hine of the de-interleaver goes to the control phase which counts  $\beta$  consecutive missed sync Words (or  $\overline{\text{sync}}$ ) before declaring the system desynchronized and going back to the sync. phase.  $\alpha$  and  $\beta$  are programmable through the I2C interface.

When the inverted sync word is detected at the input of the de-interleaver ( $\pi$  ambiguity at the input of the Viterbi decoder), the bytes provided to the Reed-Solomon decoder are inverted at the output of the de-interleaver.

### **% REED-SOLOMON DECODER**

The Reed-Solomon decoder decodes the symbol stream from the de-interleaver according to the (N=204 for DVB and N=146 for DSS) shortened Reed-Solomon code. The Reed-Solomon code is defined over the finite Galois field GF (28). The field generator polynomial is given by:

$$G(x) = \prod_{i=0}^{15} (x + \alpha^{i})$$

This Reed-Solomon decoder corrects up to eight erroneous symbols in each block. When the correction capability of the decoder is exceeded, the block is not changed and is provided as it has been entered. In this case the flag UNCOR is set and the MSB of the second byte in the MPEG2 frame is forced to one (TEI: Transport Error Indicator in DVB-S). The correction capability of the RS decoder can be inhibited.

# **& DESCRAMBLER (DVB-S)**

In order to comply with energy dispersal requirements of radio transmission regulations and to ensure adequate binary transitions, the MPEG2 frames are scrambled at the encoder side. Dual operation is achieved at the output of the Reed-Solomon decoder using the same scrambler/descrambler. The polynomial for the pseudo random binary sequence (PRBS generator is  $1 + x^{14} + x^{15}$ ). The PRBS registers are initialized at the start of every eight transport packets. To provide an initialization signal for the descrambler, the MPEG2 sync byte of the first transport packet is inverted from  $47_{16}$  to  $88_{16}$ . When detected, the descrambler is loaded with the initial sequence "100101010000000". The descrambler can be inhibited. Before being provided, the inverted sync pattern  $88_{16}$  is reinverted in order to get the original MPEG2 sync word  $47_{16}$ .

### % INTERFACE

A new Output interface was added in the TDA10085 in order to output simultaneously the serial AND parallel transport stream.

Furthermore, the TDA10085 integrates an I<sup>2</sup>C interface in slave mode. This I<sup>2</sup>C interface fulfills the Philips component I<sup>2</sup>C bus specification.

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# **INPUT – OUTPUT SIGNAL DESCRIPTION**

Symbol	Pin Number	Туре	Description
CLB#	46	I	The CLB# input is asynchronous and active low, and clears the
		3.3V	TDA10085. When CLB# goes low, the circuit immediately enters its
			RESET mode and normal operation will resume 3 XIN rising edges later
			after CLB# returned high. The I <sup>2</sup> C register contents are all initialized to
			their default values. The minimum width of CLB# at low level is 3 XIN
VINI	2	1	clock periods.  Crystal oscillator input pin. Typically a fundamental XTAL oscillator is
XIN	2	ı	connected between the XIN and XOUT pins.
XOUT	1	I	Crystal oscillator output pin. Typically a fundamental XTAL oscillator is
7.001		·	connected between the XIN and XOUT pins.
PLLGND	6	I	Analog ground for the PLL.
PLLVCC	7	I	Analog positive supply voltage for the PLL. PLLVCC is typically 3.3V.
DVCC	4	I	Digital PLL Core Supply Voltage (typically 1.8V)
DGND	5	I	Digital PLL Core Ground Voltage
VAGC	30	OD	PWM encoded output signal for AGC. This signal is typically fed to the
		/	AGC amplifier through a single RC network. The maximum signal
		0	frequency on VAGC output is SACLK / 4. The refresh frequency of AGC
			information is the symbol rate divided by 2048.
			This output can be selected by I <sup>2</sup> c to be open drain or 3.3V capable.
CTRL1	21	I/OD	ConTRoL line output. This output is directly programmable through the
			I2C interface. Its default value is a logical "1".
			CTRL1 is an open drain output and therefore requires an external pull-
CTRL2	22	I/OD	up resistor to either 3.3V or 5V.  ConTRoL line output. This output is directly programmable through the
CTRLZ	22	1/00	I2C interface. Its default value is a logical "0". CTRL2 is an open drain
			output and therefore requires an external pull-up resistor to either 3.3V
			or 5V.
CTRL3	31	I/OD	ConTRoL Line input/output. This pin is directly programmable through
			the I <sup>2</sup> C interface. Its default configuration is an input. A pull-up to 3.3V or
			5V, or a pull-down resistor to GND must be connected to CTRL3.
DO[7:0]	62,61,60,59,54,	I/O	Transport Stream Data Output. These 8-bit parallel data are the outputs
	53,52,51		of the TDA10085 after demodulation, Viterbi decoding, de-interleaving,
			RS decoding and de-scrambling. There are 3 possible output interfaces:
OCLK	F0	0	two parallel and one serial.  Output CLock. OCLK is the output clock for the parallel DO[7:0] outputs.
OCLK	50	0	OCLK is internally generated depending on which type of interface is
			selected.
DEN	49	I/O	Data ENable : this output signal is high when there is valid data on bus
DEIN	45	1/0	DO[7:0].
UNCOR	48	I/O	UNCORrectable packet. This output signal goes high on a rising edge of
		-	OCLK when the provided packet is uncorrectable.
PSYNC	47	I/O	Packet SYNChro. This output signal goes high on a rising edge of OCLK
			each time the first byte of a packet is provided.
FEL	37	OD	Front End Locked. This output signal goes high when the demodulator,
			the Viterbi decoder and the de-interleaver are all synchronized. FEL is
			an open drain output and therefore requires an external pull up resistor
			to either 3.3V or 5V.
			Furthermore the FEL pin can be set by I <sup>2</sup> C to be the interrupt pin.

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TMD	18	I	TEST input. This input pin must be grounded for normal operation of the TDA10085.
ENSERI	19	I	ENable SERIal: When High, the Serial Transport Stream is present on the Boundary Scan Pin (TRST, TDO, TCK, TDI, TMS). When low the BS pins are available.
TRST	36	I/O	Test ReSeT. This active low input signal is used to reset the TAP controller when in boundary scan mode. In normal mode of operation TRST must be set low. In Serial Mode (ENSERI=1), TRST is the psync output.
TDO	45	0	Test Data Out. This is the serial Test output pin used in boundary scan mode. Serial Data are provided on the falling edge of TCK. In Serial Mode (ENSERI=1), TDO is the enable output.
TCK	35	I/O	Test Clock: an independant clock used to drive the TAP controller when in boundary scan mode. In normal mode of operation, TCK must be grounded. In Serial Mode (ENSERI=1), TCK is the clock output.
TDI	40	I/O	Test Data In. The serial input for Test data and instruction when in boundary scan mode. In normal mode of operation, TDI must be set to GND or VDDx In Serial Mode (ENSERI=1), TDI is the data output.
TMS	34	I/O	Test Mode Select. This input signal provides the logic levels needed to change the TAP controller from state to state.  In normal mode of operation, TMS must be set to VDD.  In Serial Mode (ENSERI=1), TMS is the uncorrectable output
SADDR0	17	I	SADDR0 input signal is the LSB of the I2C address of the TDA10085.The MSBs are internally set to 000111. Therefore the complete I2C address of the TDA10085 is (MSB to LSB): 0, 0, 0, 1, 1, 1, SADDR0.
SDA	32	I/OD	SDA is a bidirectional signal. It is the serial input/output of the I2C internal block. A pull-up resistor (typically 2.2 k•) must be connected between SDA and 5V for proper operation (Open Drain output).
SCL	33	I	I2C clock input. SCL should nominally be a square wave with a maximum frequency of 400 KHz. SCL is generated by the system I2C master.
IICDIV	20	I	IICDIV allows to select the frequency of the I2C internal system clock, depending on the crystal frequency. Internal I2C clock is a division of XIN by 4 <sup>IICDIV</sup> and must be between 4 and 20 MHz
VIN1	15	I	Analog signal Input for channel I.
VIN2	12	I	Analog signal Input for channel Q.
VREFN	14	0	Analog negative voltage reference. A decoupling capacitor of typically 0.1µF must be placed as close as possible between VREFN and GND. The typical voltage value at VREFN is 1.25V.
VREFP	13	0	Analog positive voltage reference. A decoupling capacitor of typically 0.1 $\mu\text{F}$ must be placed as closed as possible between VREFP and GND. The typical voltage value at VREFP is 2V.
AVD	16	I	Analog positive supply voltage. AVD is typically 3.3V. A $0.1\mu F$ decoupling capacitor must be placed between AVD and AVS.
AVS	11	I	Analog ground voltage.

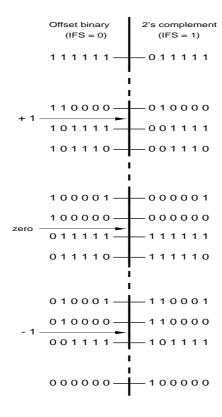
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SCL_0	29	OD	This output is equivalent to the SCL input, but can be tristated by I2C programmation. A pull-up resistor (typically $22K\Omega$ ) must be connected between this pin and 5V.
SDA_0	28	I/OD	This signal is equivalent to the SDA I/O of the TDA10085 but can be tristated by I2C programmation. SDA_0 is bidirectionnal. A pull-up resistor (typically $22K\Omega$ ) must be connected between this pin and VCC.
22K	63	0	This output pin provides the 22KHz used to control the antena LNB. This
		3.3V	output is controlled via the I2C interface.
VSSI	8,23,39,56,64	I	Digital Core ground voltage.
VDDI	3,9,24,38,55	I	Digital Core supply voltage.(Typically 1.8V)_
VSSE	26,44,58	I	Digital ground voltage
VDDE	27,43,57	I	Digital supply voltage.(Typically 3.3V)_
VDDE5	25	I	Digital 5V supply voltage.(for the 5V Tolerance)
VDD3	10	I	Analog 3.3 Suply Voltage for the A/D Converter
ADVD	42	I	Analog Supply Voltage for the 2 <sup>nd</sup> PLL (typically 1.8V)
ADVS	41	I	Analog Ground Voltage for the 2 <sup>nd</sup> PLL.

# **TABLE 3. I,Q INPUT FORMAT**

This table is to be used with an external 6-bit ADC.



Note: (+1) and (-1) levels correspond to AGCR[4:0] set to B<sub>16</sub>.

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# **TABLE 4. PUNCTURING AND MAPPING**

Rate	R	Inhibition Flags	Mapping
1/2	000	inh[0] = 1	I = X1
		inh[1] = 1	Q = Y1
2/3	001	inh[0] = 10 10	I = X1Y2Y3
		inh[1] = 11 11	Q = Y1X3Y4
3/4	010	inh[0] = 101	I = X1Y2
		inh[1] = 110	Q = Y1X3
4/5	011	inh[0] = 1000 1000	I = X1Y2Y4Y5Y7
		inh[1] = 1111 1111	Q = Y1Y3X5Y6Y8
5/6	100	inh[0] = 10101	I = X1Y2Y4
		inh[1] = 11010	Q = Y1X3X5
6/7	101	inh[0] = 100101 100101	I = X1Y2X4X6Y7Y9Y11
		inh[1] = 111010 111010	Q = Y1Y3Y5X7Y8X10 X12
7/8	110	inh[0] = 1000101	I = X1Y2X4Y6
		inh[1] = 1111010	Q = Y1Y3X5X7
8/9	111	inh[0] = 10001011 10001011	I = X1Y2Y4Y6X8Y9Y11X13X15
		inh[1] = 11110100 11110100	Q = Y1Y3X5X7X9Y10Y12Y14X16

### Notes:

<sup>1.</sup>Polynomial X is G1=171 inhibited with inh[0]

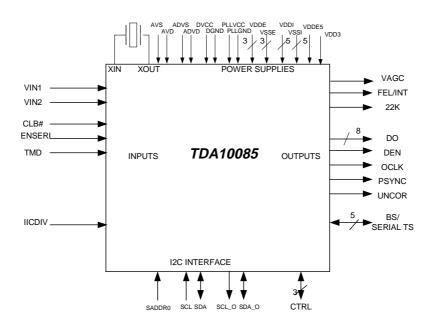
<sup>2.</sup>Polynomial Y is G2=133 inhibited with inh[1]

<sup>3.</sup>In DVB and RAUTO modes, the only Viterbi rates that the internal state machine will look for synchronization are: 1/2, 2/3, 3/4, 5/6 and 7/8.

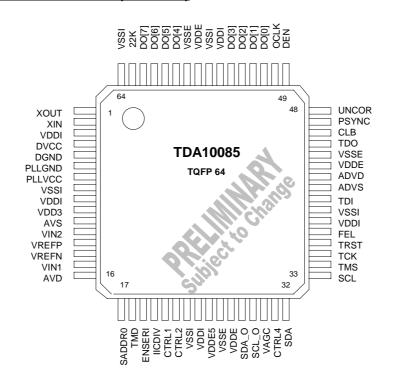
<sup>4.</sup>In DSS and RAUTO modes, the only Viterbi rates that the internal state machine will look for synchronization are : 1/2, 2/3 and 6/7.

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# **FIGURE 2. BLOCK DIAGRAM**



# **FIGURE 3. PIN CONFIGURATION (64 TQFP)**



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# **TABLE 5. PIN DESCRIPTION**

D:	D: N	_
Pin	Pin Name	Туре
1	XOUT	I
2	XIN	I
3 4	VDDI	-
4	DVCC	-
5	DGND	-
5 6 7	PLLGND	-
	PLLVCC	-
8	VSSI	-
9	VDDI	-
10	VDD3	-
11	AVS	-
12	VIN2	ı
13	VREFP	0
14	VREFN	0
15	VIN1	I
16	AVD	-
17	SADDRO	I
18	TMD	I
19	ENSERI	I
20	IICDIV	I
21	CTRL1 CTRL2	I/OD
22	CTRL2	I/OD
23	VSSI	-
24	VDDI	-
25	VDDE5	-
26	VSSE	-
27	VDDE	-
28	SDA_0	I/OD
29	SCL_0	OD
30	VAGC	O or OD
31	CTRL3	I/OD
32	SDA	I/OD
33	SCL	I

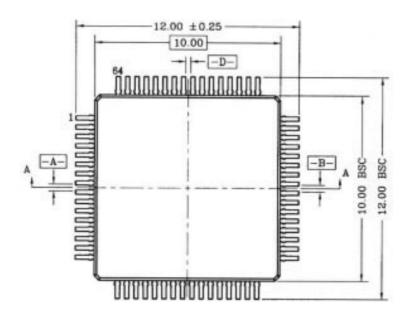
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Pin	Pin Name	Type
34	TMS	I/O
35	TCK	I/O
36	TRST	I/O
37	FEL	OD
38	VDDI	-
39	VSSI	-
40	TDI	- I/O
41	ADVS	-
42	ADVD	-
43	VDDE	-
44	VSSE	-
45	TDO	0
46	CLB#	I
47	PSYNC	1/0
48	UNCOR	I/O
49	DEN	I/O
50	OCLK	0
51	DO[0]	I/O
52	DO[1]	I/O
53	DO[2]	I/O
54	DO[3]	1/0
55	VDDI	-
56	VSSI	-
57	VDDE	-
58	VSSE	-
59	DO[4]	I/O
60	DO[5]	I/O
61	DO[6]	I/O
62	DO[7]	I/O
63	22K	I/O
64	VSSI	-

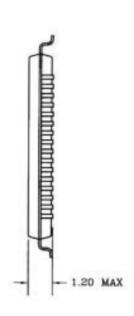
### Notes

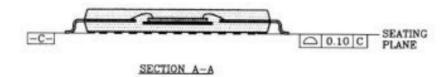
- 1.All inputs (I) are TTL, 5V tolerant inputs except CLB# pin.
- 2.OD are Open Drain 5V outputs, so they must be connected to a pull-up resistor to either 3.3V or 5V.
- 3. DGND, VSSI and VSSE can be connected to the same GND ground.

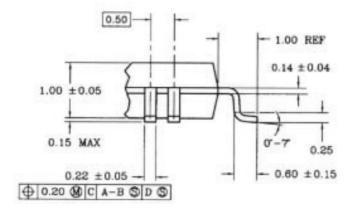
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# **PACKAGE DESCRIPTION**









### NOTES

- 1. DIMENSIONS ARE IN MILLIMETERS.
- 2. LEADFRAME MATERIAL: COPPER.
- TO BE MOLDED CAVITY UP (SEE SECTION A-A).

TDA10085

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DATA SHEET STATUS	PRODUCT STATUS	DEFINITIONS (1)
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2000 March 16

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