

APPLICATION NOTE

Optimizing the ST6 A/D Converter Accuracy

J. NICOLAI

INTRODUCTION

When using the internal Analog to Digital Converter of the ST62 family and maximum A/D converter accuracy is required, it is desirable to filter out any noise present on the analog input, but also noise present on the ground and V_{cc} supply lines of the MCU as V_{cc} is also the voltage reference of the A/D converter. Good decoupling must be made with capacitors on the analog input and between V_{cc} and ground. It is also recommended to put the MCU in wait state while the conversion is in progress, so as to minimize noise injected into V_{cc} by the operation of the micro-controller itself.

Finally, when enough time is available, it is highly recommended to make several successive A/D conversions and take an average of the results. This is the most effective way to get the most accuracy out of the ST6 family A/D converter.

The following code fragment demonstrates a burst of 256 successive measurements, after which the average is put into the accumulator. The whole routine takes approximately 30 milli-seconds with an 8 MHz clock. When less time is available, it is of course possible to reduce the number of conversions: 8, 16 or 32 conversions also give good results, although the most conversions give the best results.

NOTES:

THE SOFTWARE INCLUDED IN THIS NOTE IS FOR GUIDANCE ONLY. SGS-THOMSON SHLL NOT BE HELD LIABLE FOR ANY DIRECT, INDIRECT OR CONSEQUENTIAL DAMAGES WITH RESPECT TO ANY CLAIMS ARISING FROM USE OF THE SOFTWARE.

```
;****************** SUBROUTINE AVERAGE *****************
;description: measures ADC input 256 times and stores average *
          of the 256 measures into accumulator
; ********************
average
     ldi ior,10h
                  ; global enable interrupts
                  ;aver_lo, aver_hi and count are RAM registers
     clr aver_lo
     clr aver hi
     ldi count,255
                 ; set for 256 measurements
aver1
     ldi adcc,10110000b ; start conversion with interrupt
     wait
     ld a,adc
add a, aver_lo
     jrnc aver2
     inc aver hi
aver2 ld aver_lo,a
;========== end of two byte addition
     ld a, count
     jrz aver4
     dec count
                 ;do it 256 times
     jp aver1
aver4
     ld a,aver_lo
                 ;round to next value if decimal part >0.5
     cpi a,127
     jrc aver3
     inc aver hi
aver3 ld a, aver_hi ;store high byte of result into accumulator,
                  ; the low byte is not significant
     ret
             ****** interrupt service routine ********
adcint
     ldi adcc,10h
     reti
.org OffOh
     jp adcint
```

Information furnished is believed to be accurate and reliable. However, SGS-THOMSON Microelectronics assumes no responsability for the consequences of use of such information nor for any infringement of patents or other rights of third parties which may result from its use. No license is granted by implication or otherwise under any patent or patent rights of SGS-THOMSON Microelectronics. Specifications mentioned in this publication are subject to change without notice. This publication supersedes and replaces all information previously supplied. SGS-THOMSON Microelectronics products are not authorized for use as critical components in life support devices or systems without the express written approval of SGS-THOMSON Microelectronics.

© 1994 SGS-THOMSON Microelectronics - All Rights Reserved

Purchase of I²C Components by SGS-THOMSON Microelectronics, conveys a license under the Philips I²C Patent. Rights to use these components in an I²C system, is granted provided that the system conforms to the I²C Standard Specifications as defined by Philips.

SGS-THOMSON Microelectronics GROUP OF COMPANIES

Australia - Brazil - France - Germany - Hong Kong - Italy - Japan - Korea - Malaysia - Malta - Morocco The Netherlands - Singapore - Spain - Sweden - Switzerland - Taiwan - Thailand - United Kingdom - U.S.A.

