

SAA8115HL

Digital camera USB interface

Rev. 04 — 10 August 2000

Product specification



1. General description

The SAA8115HL is the second generation of integrated circuit applicable in PC video cameras to convert D1 video signals and analog audio signals to properly formatted USB packets.

This powerful successor of the SAA8117HL can handle up to 15 fps in VGA format or 30 fps in CIF format. High snapshot quality is achievable using the SDRAM interface to an external memory.

It is designed as a back-end of the SAA8112HL (general camera digital processing IC) and is optimized for use with the TDA8784 to TDA8787 (camera pre-processing ICs).

2. Features

- VGA (progressive mode), CIF and medium resolution (PAL non-interlaced mode) CCD sensors compliant
- D1 digital video input (8 bits YUV 4 : 2 : 2 time multiplexed)
- Internal Pulse Pattern Generator (PPG) dedicated for VGA Panasonic, CIF and medium resolution Sharp sensors or compatibles, and frame rate selection
- Frame rate converter
- SDRAM interface for high quality VGA snapshot (uncompressed 4 : 2 : 2 or 4 : 2 : 0)
- Downsampler and scaler (programmable formatter for CIF, QCIF, sub-QCIF, SIF and QSIF) controlled via SNERT (UART) interface
- Flexible compression engine controlled via SNERT (UART) interface
- Selectable output frame rate (up to 15 fps in VGA, up to 30 fps in CIF and QCIF)
- Video packetizer FIFO
- I²C-bus interface for communication between the USB protocol hardware and the external microcontroller
- Microphone/audio input to USB (microphone supply, controllable gain and ADC)
- Integrated analog bus driver (ATX)
- Integrated main oscillator
- Integrated 5 V power supply and reset circuit including functionalities for bus-powered USB device
- Programmable (frequency and duty cycle) switch mode power signal for CCD supply





SAA8115HL

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■ Miscellaneous functions (e.g. power management, PLL for audio frequencies).

3. Applications

Low-cost desktop video applications with USB interface.

4. Quick reference data

Table 1: Quick reference data

Measured over full voltage and temperature range

Symbol	Parameter	Conditions		Min	Тур	Max	Unit
V_{DDD}	digital supply voltage			3.0	3.3	3.6	V
V_{DDA}	analog supply voltage			3.0	3.3	3.6	V
$V_{\text{DDA(USB)}}$	analog supply voltage from USB		[1]	4.3	5.0	5.5	V
I_{DD}	supply current		[2]	_	100	125	mA
$I_{DD(DC-DC)}$	DC-DC supply current		[3]	_	240	320	mA
V_{I}	input signal levels	$3.0 \text{ V} < \text{V}_{DDD} < 3.6 \text{ V}$		low voltag	ge TTL com	patible	V
V_{O}	output signal levels	$3.0 \text{ V} < \text{V}_{DDD} < 3.6 \text{ V}$		low voltag	ge TTL com	patible	V
f _{clk}	clock frequency			_	48	_	MHz
T _{stg}	storage temperature			-55	_	_	°C
T _{amb}	ambient temperature			0	25	70	°C
Tj	junction temperature	T _{amb} = 70 °C		-40	_	+125	°C

^[1] This concerns pins VBUS1 and VBUS2.

- a) typical: VGA at 15 fps; V_{DDD} = V_{DDA} = 3.3 V; T_{amb} = 25 °C
- b) maximum: VGA at 30 fps; $V_{DDD} = V_{DDA} = 3.6 \text{ V}$; $T_{amb} = 70 \,^{\circ}\text{C}$.
- [3] Conditions (I_{OUT} = 125 mA):
 - a) typical: $V_{DD(USB)} = 5.0 \text{ V}$; $T_{amb} = 25 \,^{\circ}\text{C}$
 - b) maximum: $V_{DD(USB)} = 4.3 \text{ V}$; $T_{amb} = 70 ^{\circ}\text{C}$.

5. Ordering information

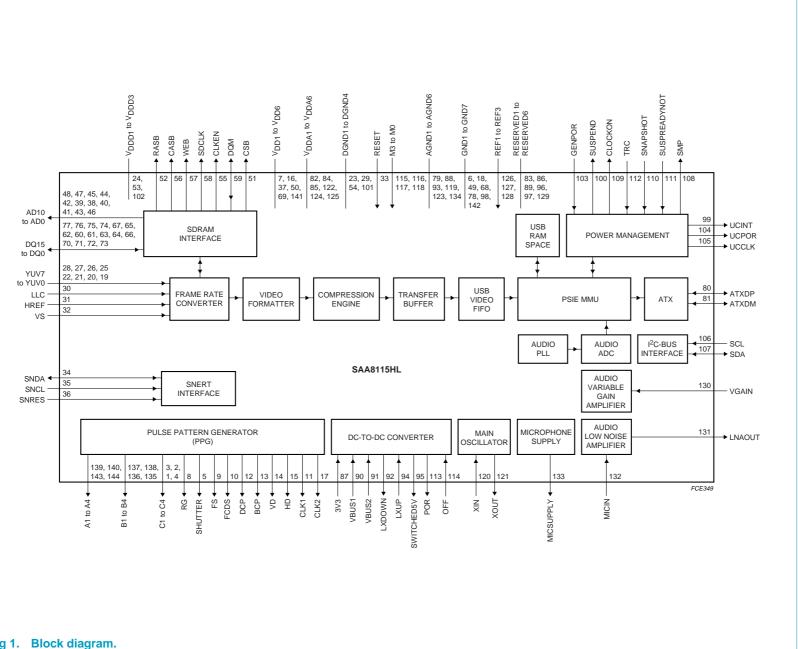
Table 2: Ordering information

Type number	Package	Package							
	Name	Description	Version						
SAA8115HL	LQFP144	plastic low profile quad flat package; 144 leads; body $20 \times 20 \times 1.4$ mm	SOT486-1						

^[2] Conditions

Block diagram

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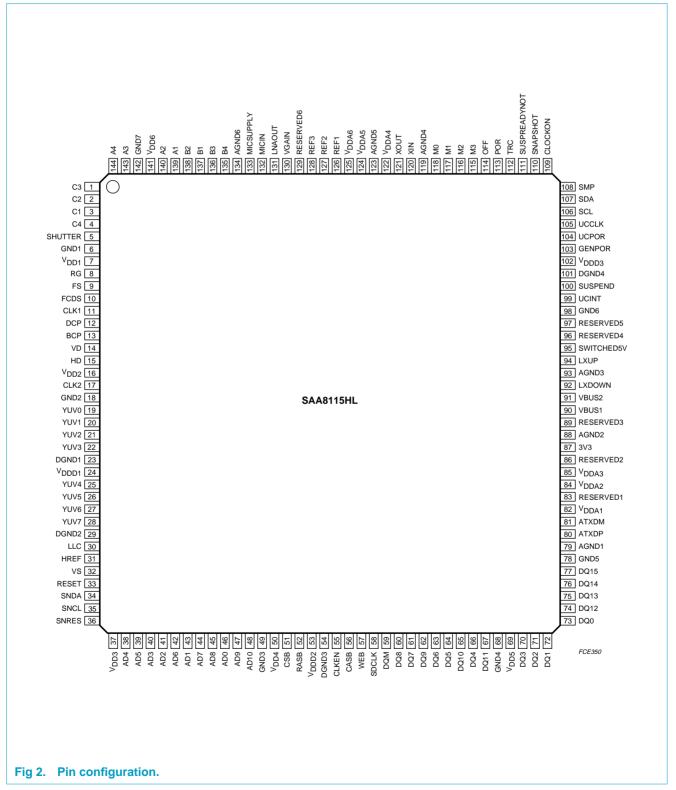


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Product specification

7. Pinning information

7.1 Pinning



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7.2 Pin description

Table 3: Pin description

Table 3: Pin desc	criptio		
Symbol	Pin	Type ^[1]	Description
C3	1	0	horizontal CCD transfer pulse output
C2	2	0	horizontal CCD transfer pulse output (FH1)
C1	3	0	horizontal CCD transfer pulse output (FH2)
C4	4	0	horizontal CCD transfer pulse output
SHUTTER	5	0	shutter control output for CCD charge reset
GND1	6	Р	ground 1 for output buffers
V_{DD1}	7	Р	supply voltage 1 for output buffers
RG	8	0	reset output for CCD output amplifier gate
FS	9	0	data sample-and-hold pulse output to TDA8784/87 (SHD)
FCDS	10	0	preset sample-and-hold pulse output to TDA8784/87 (SHP)
CLK1	11	0	pixel clock to TDA8784/87 and SAA8112HL
DCP	12	0	dummy clamp pulse output to TDA8784/87
ВСР	13	0	optical black clamp pulse output to TDA8784/87
VD	14	0	vertical definition pulse to SAA8112HL
HD	15	0	horizontal definition pulse to SAA8112HL
V_{DD2}	16	Р	supply voltage 2 for output buffers
CLK2	17	0	double pixel clock to SAA8112HL
GND2	18	Р	ground 2 for output buffers
YUV0	19	I	multiplexed YUV bit 0
YUV1	20	I	multiplexed YUV bit 1
YUV2	21	I	multiplexed YUV bit 2
YUV3	22	I	multiplexed YUV bit 3
DGND1	23	Р	digital ground 1 for input buffers, predrivers and for the digital core
V_{DDD1}	24	Р	digital supply voltage 1 for input buffers, predrivers and one part of the digital core
YUV4	25	I	multiplexed YUV bit 4
YUV5	26	I	multiplexed YUV bit 5
YUV6	27	I	multiplexed YUV bit 6
YUV7	28	I	multiplexed YUV bit 7
DGND2	29	Р	digital ground 2 for input buffers, predrivers and for the digital core
LLC	30	I	line-locked clock input (delayed CLK2) for YUV-port from SAA8112HL
HREF	31	I	horizontal reference input for YUV-port from SAA8112HL
VS	32	I	vertical synchronization input for YUV-port from SAA8112HL
RESET	33	I	Power-on reset input (for video processing and PPG)
SNDA	34	I/O	data input/output for SNERT-interface (communication between SAA8115HL and SAA8112HL)

Table 3: Pin description...continued

Table 3:	Pin descriptioncontinued						
Symbol	F	Pin	Type ^[1]	Description			
SNCL	3	35	I	clock input for SNERT-interface (communication between SAA8115HL and SAA8112HL)			
SNRES	3	36	1	reset input for SNERT-interface (communication between SAA8115HL and SAA8112HL)			
V_{DD3}	3	37	Р	supply voltage 3 for output buffers			
AD4	3	38	0	SDRAM output address bit 4			
AD5	3	39	0	SDRAM output address bit 5			
AD3	4	40	0	SDRAM output address bit 3			
AD2	4	41	0	SDRAM output address bit 2			
AD6	4	12	0	SDRAM output address bit 6			
AD1	4	43	0	SDRAM output address bit 1			
AD7	4	14	0	SDRAM output address bit 7			
AD8	4	45	0	SDRAM output address bit 8			
AD0	4	46	0	SDRAM output address bit 0			
AD9	4	1 7	0	SDRAM output address bit 9			
AD10	4	48	0	SDRAM output address bit 10			
GND3	4	19	Р	ground 3 for output buffers			
V_{DD4}	5	50	Р	supply voltage 4 for output buffers			
CSB	5	51	0	SDRAM chip select output			
RASB	5	52	0	SDRAM row address strobe output			
V_{DDD2}	5	53	Р	digital supply voltage 2 for the switchable digital core			
DGND3	5	54	Р	digital ground 3 for input buffers, predrivers and for the digital core			
CLKEN	5	55	0	SDRAM clock enable output			
CASB	5	56	0	SDRAM column address strobe output			
WEB	5	57	0	SDRAM write enable output			
SDCLK	5	58	0	SDRAM clock output			
DQM	5	59	I/O	SDRAM data mask enable			
DQ8	6	30	I/O	SDRAM data I/O bit 8			
DQ7	6	31	I/O	SDRAM data I/O bit 7			
DQ9	6	52	I/O	SDRAM data I/O bit 9			
DQ6	6	33	I/O	SDRAM data I/O bit 6			
DQ5	6	54	I/O	SDRAM data I/O bit 5			
DQ10	6	65	I/O	SDRAM data I/O bit 10			
DQ4	6	66	I/O	SDRAM data I/O bit 4			
DQ11	6	67	I/O	SDRAM data I/O bit 11			
GND4	6	86	Р	ground 4 for output buffers			
V_{DD5}	6	59	Р	supply voltage 5 for output buffers			
DQ3	7	70	I/O	SDRAM data I/O bit 3			
DQ2	7	71	I/O	SDRAM data I/O bit 2			
DQ1	7	72	I/O	SDRAM data I/O bit 1			

Table 3: Pin description...continued

Symbol	Pin	Type ^[1]	
DQ0	73	I/O	SDRAM data I/O bit 0
DQ12	74	I/O	SDRAM data I/O bit 12
DQ12	75	I/O	SDRAM data I/O bit 13
DQ14	76	I/O	SDRAM data I/O bit 14
DQ15	77	I/O	SDRAM data I/O bit 15
GND5	78	//O Р	ground 5 for output buffers
AGND1	79	P	analog ground 1 for ATX (transceiver)
ATXDP	80	I/O	positive driver of the differential data pair input/output (ATX)
ATXDM	81	I/O	negative driver of the differential data pair input/output (ATX)
V_{DDA1}	82	Р	analog supply voltage 1 for ATX
RESERVED1	83	-	test pin 1 (should not be used)
V_{DDA2}	84	Р	analog supply voltage 2 for bandgap (reference)
V_{DDA3}	85	Р	analog supply voltage 3 for bandgap, comparator and ring oscillator
RESERVED2	86	_	test pin 2 (should not be used)
3V3	87	I	3V3 detector input signal
AGND2	88	Р	analog ground 2 for N-switch
RESERVED3	89	_	test pin 3 (should not be used)
VBUS1	90	I	supply voltage input 1 from the USB
VBUS2	91	I	supply voltage input 2 from the USB
LXDOWN	92	0	LX coil node output (5 V downconverter)
AGND3	93	Р	analog ground 3 for N-switch
LXUP	94	I	LX coil node input (5 V upconverter)
SWITCHED5V	95	0	5 V switched power supply
RESERVED4	96	_	test pin 4 (should not be used)
RESERVED5	97	_	test pin 5 (should not be used)
GND6	98	Р	ground 6 for output buffers
UCINT	99	0	interrupt output from USB to microcontroller
SUSPEND	100	0	control output from USB protocol hardware to microcontroller
DGND4	101	Р	digital ground 4 for input buffers, predrivers and for the digital core
V_{DDD3}	102	Р	digital supply voltage 3 for input buffers, predrivers and one part of the digital core
GENPOR	103	I	Power-on reset input (for USB protocol hardware)
UCPOR	104	0	control output from USB protocol hardware to microcontroller
UCCLK	105	0	clock output from USB protocol hardware to microcontroller
SCL	106	I	slave I ² C-bus clock input
SDA	107	I/O	slave I ² C-bus data input/output

 Table 3:
 Pin description...continued

Symbol	Pin	Type ^[1]	
SMP	108	0	switch mode power pulse output for CCD supplies
CLOCKON	109	0	control output for main oscillator switched on
SNAPSHOT	110	I	input for remote wake-up (snapshot)
SUSPREADYNOT	111	I	input from microcontroller for SUSPEND mode
TRC	112	I	threshold control input for enabling clock
POR	113	0	3.3 V supply domain ready indicator output
OFF	114	I	disable 5 V switchable supply domain input
M3	115	I	test mode control input signal bit 3
M2	116	I	test mode control input signal bit 2
M1	117	I	test mode control input signal bit 1
MO	118	I	test mode control input signal bit 0
AGND4	119	Р	analog ground 4 for crystal oscillator (48 MHz, 3rd overtone)
XIN	120	I	oscillator input
XOUT	121	0	oscillator output
V_{DDA4}	122	Р	analog supply voltage 4 for crystal oscillator (48 MHz, 3rd overtone)
AGND5	123	Р	analog ground 5 for PLL
V_{DDA5}	124	Р	analog supply voltage 5 for PLL
V_{DDA6}	125	Р	analog supply voltage 6 for amplifier and ADC
REF1	126	I	reference voltage 1 (used in the ADC)
REF2	127	I	reference voltage 2 (used in the ADC)
REF3	128	I	reference voltage 3 (used in the amplifier and the ADC)
RESERVED6	129	0	test pin 6 (should not be used)
VGAIN	130	I	variable gain amplifier input
LNAOUT	131	0	low noise amplifier output
MICIN	132	I	microphone input
MICSUPPLY	133	0	microphone supply output
AGND6	134	Р	analog ground 6 for amplifier and ADC
B4	135	0	vertical CCD load pulse output (VH1X)
B3	136	0	vertical CCD load pulse output (VH3X)
B1	137	0	vertical CCD load pulse output
B2	138	0	vertical CCD load pulse output
A1	139	0	vertical CCD transfer pulse output (V1X)
A2	140	0	vertical CCD transfer pulse output (V2X)
V_{DD6}	141	Р	supply voltage 6 for output buffers
GND7	142	Р	ground 7 for output buffers
A3	143	0	vertical CCD transfer pulse output (V3X)
A4	144	0	vertical CCD transfer pulse output (V4X)

^[1] I = input, O = output and P = power supply.

8. Functional description

8.1 Video synchronization

The video synchronization module is capable of locking to the video signal implementing a horizontal gate signal HREF (HREF = HIGH when data is valid) and a VS signal indicating the start of a new video frame.

8.2 Frame rate converter and SDRAM interface

An optional SDRAM (external) can be accessed using the SDRAM interface which is integrated in the SAA8115HL. Pinning and functionality is based on the NEC μ PD4516161 (16 Mbits) and the NEC μ PD4564163 (64 Mbits).

When used, the memory is placed at the video input of the SAA8115HL before prefilter, scaler and compression engine. At this point only YUV 4:2:2 formatted data is available.

The use of the SDRAM is twofold:

- Lowering the frame rate. The memory enables to store one frame of video accumulated at a specific rate and to read it out at a lower frame rate. For interline VGA sensors, the input frame rate is either 30 fps or 15 fps. It can be lowered with a factor of 2, 3, 6, 16 or 32. For CIF or medium resolution PAL, the input frame rate is only 30 fps
- Enhanced snapshot mode. Storage of full size VGA pictures in 4 : 2 : 2 format which can be retrieved upon dedicated software command.

8.3 Video formatter: downsampler and cutter

This block is used to achieve the required output format from the specified sensor formats (see Figure 3). It works for YUV 4:2:2 only. In RAW mode this block is by-passed to create a full resolution snapshot.

Horizontally a downsampling from 512 or 640 to either 384, 320, 192 or 160 or from 352 to 176 is necessary. The horizontal downsampling is performed with the use of a Variable Phase Delay filter (VPD-4). This filter can realize the needed downsample factors. To avoid aliasing, this module also contains a prefilter which has four modes:

- No filter for medium resolution PAL (512 \times 288) to CIF (352 \times 288) or SIF (320 \times 240)
- Prefilter A (3 taps) for VGA (640 \times 480) to CIF or SIF, CIF to QCIF (176 \times 144) or QSIF (160 \times 120)
- Prefilter B (7 taps) for medium resolution PAL to QCIF or QSIF
- Prefilter A combined with prefilter B-comb (13 taps) for VGA to QCIF or QSIF.

Prefilter B-comb is similar to prefilter B but inserts extra taps with amplification 0.

The vertical downsampling in PAL mode is from CIF to QCIF only. This is done via a vertical filter A (3 taps). In VGA mode a 4 taps polyphase filter is applied to scale from 640×480 to CIF and QCIF.

From a full size QCIF picture a sub-QCIF (128×96) cut can be made. For the zoomed sub-QCIF format, the origin (upper left corner) is programmable via SNERT in 13 steps (both horizontally and vertically), so that an electronic pan and tilt is possible.

The incoming 4 : 2 : 2 data is vertically filtered to 4 : 2 : 0, in order to be sent over USB, by throwing away colour samples. In the even lines the V-samples are discarded, in the odd lines the U-samples.

8.4 Compression engine

The compression engine module (see Figure 3) can process VGA, CIF, SIF, QCIF and QSIF but has optimal performance with CIF resolution (30 fps) and VGA resolution (5 fps). The algorithm is Philips proprietary. The compression ratio is continuously programmable by setting the maximum number of bits which can be used for 4 compressed lines, a so-called band (see Table 4). It is possible to reduce the YUV input data by scaling down (divide by 2 or divide by 4 operations) to 7 or 6 bits per sample. For compression with an output rate below 2 bpp (bits per pixel) it leads to performance improvement.

For a number of compression ratios, performance is also improved thanks to different quantization tables which are defined and stored in a ROM. The required table must be selected via software.

Real time decoding can be done in software on any Pentium^{™1} platform.

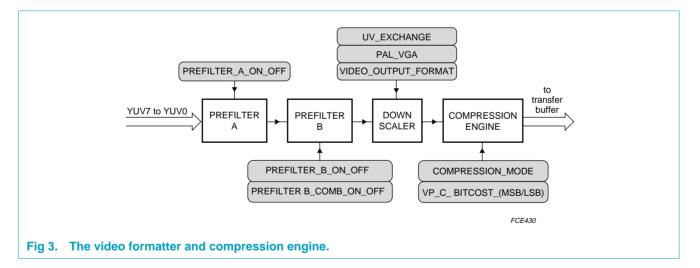


Table 4: Data rate performed by compression engine

Format	Advised data rate	Maximum data rate
CIF/SIF	2 bpp	12 bpp (uncompressed)
QCIF/QSIF	6 bpp	uncompressed
VGA high quality	3 bpp	4 bpp
VGA	1.5 bpp	3 bpp
RAW VGA high quality	4 bpp	4 bpp

Pentium — is a trademark of Intel Corp.

8.5 Transfer buffer

The transfer buffer module (see Figure 4) takes care of a smooth transfer of the data to the FIFO of the USB. Moreover the transfer buffer can insert inband synchronization words in the video data stream. This function can be switched on and off with INBAND_CONTROL in register VP_TR_CONTROL (0x36).

The synchronization words can only be used with non-compressed data stream and are formatted like 0x00 0xFF 0x<framecounter>₇linecounter>₉. (Subscript denotes the number of bits and the frame counter is circular incrementing).

The non-compressed data is formatted like:

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4 : 2 : 0: <optional sync word><Y0><Y1><Y2><Y3><C0><C2><Y4><Y5><Y6><Y7><C4><C6>....,
```

4:2:2:<optional sync word><Y0><Y1><Y2><Y3><U0><V0><U2><V2><Y4>....,

where C denotes U-data in the even lines (0, 2, 4 etc.) and V-data in the odd lines (1, 3, 5 etc.).

8.6 USB video FIFO

The USB video FIFO is programmed via the I²C-bus (see Figure 5). The FIFO is designed to achieve three different packets containing video on the isochronous USB channel. Video data is contained in a chain of equally sized USB packets, except for the last packet of a video frame which is always smaller. The video frames can be separated from each other by one or more 0-length packets. For low frame rates (below 10 frames per second) there are always 0-length packets in the stream.

The host can synchronize on the smaller packets for the high frame rates and on the 0-length packets for the low frame rates.

For every mode the FIFO must be adjusted. There are three parameters to program the video FIFO:

- PACKET_SIZE (0x06): this value indicates the length of all packets with video data except for the last packet of a video frame
- FIFO_OFFSET (0x04): this value indicates the number of data in the FIFO before a new packet will be transmitted over USB
- READ_SPACING (0x07): this value indicates the number of 12 MHz clock cycles between read actions from the FIFO.

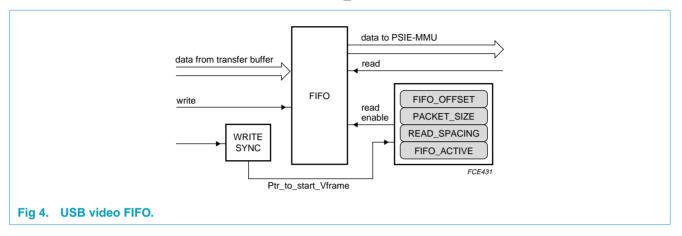
Moreover the FIFO is enabled and disabled with FIFO_ACTIVE (0x05).

The write process to the FIFO is controlled by the transfer buffer and not programmable.

The read process is executed in the PSIE-MMU and is driven by the USB frame interval (1 ms). Every frame interval the PSIE-MMU tries to read PACKET_SIZE bytes from the FIFO. This read process will not be started when a new video frame is stored in the FIFO and there are less than FIFO_OFFSET bytes written. The read process stops if the next bytes are of another video frame, or if the read-pointer would overtake the write-pointer.

READ_SPACING determines the read rate. Its value can easily be determined with the formula:

$$\mathsf{READ_SPACING} < \frac{12000}{\mathsf{PACKET_SIZE}}$$



8.7 PSIE-MMU, I²C-bus interface and USB RAM space

The Programmable Serial Interface Engine (PSIE) and Memory Management Unit (MMU) is the heart of the USB protocol hardware (see Figure 5). It formats the actual packets that are transferred to the USB and passes the incoming packets to the right end-point buffers. These buffers are allocated as part of the USB RAM space.

The microcontroller communicates via the I²C-bus with the PSIE-MMU. The I²C-bus protocol distinguishes three register spaces. These spaces are addressed via different commands. The command is sent to the command address.

Depending on the command it is sent to the PSIE-MMU and/or to the command interpreter which configures the (de-)mux to open the path to the right register space. Subsequent write/reads to/from the data address store or retrieve data from the register space selected by the command.

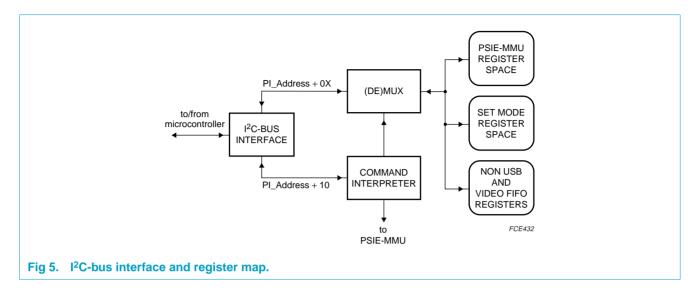
8.8 ATX interface

The SAA8115HL contains an analog bus driver, called the ATX. It incorporates a differential and two single-ended receivers and a differential transmitter.

The interface to the bus consists of a differential data pair (ATXDM and ATXDP).

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8.9 Audio

The SAA8115HL contains a microphone supply and an amplifier circuit composed of two stages: a Low Noise Amplifier (LNA) and a variable gain amplifier. The LNA has a fixed gain of 26 dB while the variable gain amplifier can be programmed between 0 and 30 dB by steps of 2 dB. The gain control can be done via either the SNERT interface or the I²C-bus interface (see Table 60). The serial interface must be first selected using bit SIS (see Table 60). The frequency transfer characteristic of the audio path must be controlled via external high-pass or low-pass filters.

The PLL converts the 48 MHz to $256f_s$ (f_s = audio sample frequency). There are three modes for the PLL to achieve the sample frequencies of 48, 44.1 or 32 kHz (see Table 5).

The bitstream ADC samples the audio signal. It runs at an oversample rate of 256 times the base sample rate. In the application, the bitstream can be converted to parallel 16-bit samples. This conversion is programmable with respect to the effective sample frequency (dropping sample results in a lower effective sample frequency) and sample resolution. As a result the effective sample rate can be determined.

ADC clock Clock Dividina Sample (MHz) number frequency (MHz) (kHz) 8.1920 32 4.096 1 2 2.048 16 4 8 1.042 [1] [1] 8 11.2996 44.1 5.6448 1 2 22.05 2.8224 4 11.025 1.4112 8 5.5125 0.7056 12.2880 1 6.144 48 2 24 3.072 4 12 1.536 8 0.768 6

Table 5: ADC clock frequencies and sample frequencies

8.10 Sensor pulse pattern generator

The SAA8115HL incorporates a Pulse Pattern Generator (PPG) function. The PPG can be used for medium resolution PAL, CIF and VGA CCD-sensors (see Table 6).

Depending on the sensor type, an external inverter driver should be required to convert the 3.3 V pulses into a voltage suitable for the used CCD-sensor.

The active video size is 512×288 for medium resolution PAL, 352×288 for CIF and 640×480 for VGA. The total H \times V size are 685×292 for medium resolution PAL/CIF and 823×486 for VGA. It should be noted that additional HD pulses are added during the vertical blanking interval to reach a total of 312 lines in PAL and CIF modes and 525 lines in VGA mode as required by the SAA8112HL.

A high level of flexibility is available for the PPG thanks to 19 internal registers (see Section 9.1.3).

Table 6: Typical SAA8115HL compatible sensors

Sensor type	Brand	Part number	
VGA	Sony	ICX098AK	
	Panasonic	MN3777PP and MN37771PT	
	Sharp	LZ24BP	
Medium resolution PAL	Sony	ICX054, ICX086 and ICX206	
	Panasonic	MN37210FP	
	Sharp	LZ2423B and LZ2423H	
	Toshiba	TCD5391AP	
CIF	Sharp	LZ244D and LZ2547	
Other sensors	all the sensors fully compatib	ole with the above mentioned sensors	

^[1] Not supported.

8.11 Power management

USB requires the device to switch power states. The SAA8115HL contains a power management module since the complete camera may not consume more than 500 μ A during the power state called SUSPEND. This requires that even the crystal oscillator must be switched off. The SAA8115HL is not functional except for some logic that enables the IC to wake-up the camera. After wake-up of the SAA8115HL first the clock to the microcontroller is generated and thereafter an interrupt is generated to wake-up the microcontroller. Therefore the clock of the microcontroller is generated by the SAA8115HL.

The power management module also sets a flag in register SET_MODE_AND_READ (PSIE_MMU_STATUS). After a reset the microcontroller should check this register via the I²C-bus and find the cause of the wake-up. Different causes may require different start-up routines.

The internal video processing core uses another supply domain which can be switched off during SUSPEND mode.

The PPG is switched off by setting PPG_RESUME_MODE (0x08) and resetting PAL VGA (0x09).

In non CIF modes the power consumption is reduced by resetting COMPRESSION_MODE (0x2F) and COMPRESSION_CLOCK (0x09).

The SAA8115HL has the feature to autonomously wake-up from SUSPEND mode, but requires microcontroller interference before going in SUSPEND mode (via the signal on pin SUSPREADYNOT).

Since the main oscillator of the SAA8115HL is switched off during SUSPEND mode, precautions are needed to avoid undefined states when the clock is switched on. This is ensured via the pins CLOCKON and TRC. Pin CLOCKON goes HIGH as soon as the main oscillator is switched on. The oscillator will need some time to make a stable 48 MHz signal. However, the clock is only passed through to other parts of the SAA8115HL when the level on pin TRC reaches a certain threshold. The time needed to reach the threshold can be trimmed with an external RC circuit.

8.12 Power supply

A power supply regulator is integrated in the device. This DC-to-DC converter transforms the USB supply voltage (range from 4.0 to 5.5 V) into a stable 5 V supply voltage. This power domain is switchable. The power circuit also generates a reset signal when the external 3.3 V supply voltage is stable and in range.

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9. Control register description

This specification gives an overview of all registers.

9.1 SNERT (UART)

The SAA8115HL is partly controlled via SNERT. The frame rate converter, the SDRAM interface, the video formatter, the compression engine, the PPG, the SMP and the audio functions are controlled via SNERT. This SNERT interface works independently from the frame rate and can always be operated in the full frequency range.

Via SNERT the following registers are accessible (see Table 7).

Table 7: SNERT write registers SAA8115HL

Address	Function
00	write register soft reset (see Table 8)
01 to 05	write registers Frame Rate Converter (FRC) including the SDRAM interface
06 and 07	reserved
08 to 1A	write registers Pulse Pattern Generator (PPG)
1B to 1F	reserved
20 to 38	write registers video formatter and compression engine
39 to 3C	reserved
3D and 3E	write registers Switch Mode Power (SMP)
3F	write register audio variable gain amplifier

9.1.1 General register

Table 8: Detailed description of SNERT general register 0x00

Bit								SNERT register 00: SOFT_RESET
7	6	5	4	3	2	1	0	Parameter
Χ	Χ	Χ	Χ	Χ				reserved
								RESET_VP_C
					1			compression engine in reset state
					0			compression engine operating
								RESET_VP_VF
						1		formatter engine in reset state
						0		formatter engine operating
								RESET_FRC
							1	frame rate converter engine in reset state (by default)
							0	frame rate converter engine operating

9.1.2 Frame rate converter and SDRAM interface registers

Table 9: Detailed description of SNERT FRC and SDRAM register 0x01

Bit								SNERT register 01: FRC_CONTROL_0
7	6	5	4	3	2	1	0	Parameter
Χ								reserved
	Χ	Χ	Χ					number of active lines after rising edge of VS signal; range: 0 to 6 (by default 0)
								FRAMERATE_DIVIDER_SELECT_BIT
				1	1	1		undefined
				1	1	0		32 (30 fps in; 0.9375 fps out)
				1	0	1		16 (15 fps in; 0.9375 fps out)
				1	0	0		6 (30 fps in; 5 fps out)
				0	1	1		3 (30 fps in; 10 fps out) or (15 fps in; 5 fps out)
				0	1	0		2 (30 fps in; 15 fps out) or (15 fps in; 7.5 fps out)
				0	0	1		1 (1 fps in; 1 fps out) (by default)
				0	0	0		undefined
								LLC_CLKFREQ
							1	24 MHz (by default)
							0	12 MHz

Table 10: Detailed description of SNERT FRC and SDRAM register 0x02

Bit								SNERT register 02: FRC_CONTROL_1
7	6	5	4	3	2	1	0	Parameter
Χ	Χ	Χ						reserved
								REFRESH_MODE
			1					automatic SRAM refresh
			0					precharge command as implicit refresh (by default)
								REFRESH_CLOCK (MSBs)
				Χ	Χ			see Table 12
								INPUT_FORMAT
						1	1	undefined
						1	0	medium resolution
						0	1	CIF
						0	0	VGA (by default)

Table 11: Detailed description of SNERT FRC and SDRAM register 0x03

Bit								SNERT register 03: FRC_ROWWIDTH
7	6	5	4	3	2	1	0	Parameter
Х	Χ	Χ	Χ	Χ	Χ	Х	Х	specifies the width of the row of the SDRAM
								95 for PAL sensors
								159 for VGA sensors (by default)
								63 for CIF sensors



Table 12: Detailed description of SNERT FRC and SDRAM register 0x04

Bit								SNERT register 04: FRC_REFRESH_LSB
7	6	5	4	3	2	1	0	Parameter
Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ	specifies the number of clock cycles between two refresh cycles
								246 for PAL sensors
								395 for VGA sensors (by default)
								239 for CIF sensors

Table 13: Detailed description of SNERT FRC and SDRAM register 0x05

Bit								SNERT register 05: FRC_STOPWRITE
7	6	5	4	3	2	1	0	Parameter
Х	Χ	Χ	Χ	Χ	Χ	Χ	Х	number of lines in a frame
								243 for VGA sensors (by default)
								146 for PAL or CIF sensors

9.1.3 Pulse pattern generator registers

Table 14: Detailed description of SNERT PPG register 0x08

3it								SNERT register 08: PPG_CONTROL_0
7	6	5	4	3	2	1	0	Parameter
Χ	Χ	Χ						reserved
								SHUTTER_UPDATE_BUFFER
			1					during the vertical blanking (shutter speed is buffered)
			0					immediately (by default)
								PPG_RESUME_MODE
				1				switched off (except vertical transfer pulses in case of VGA sensors)
				0				operating (by default)
								PPG _FRAMERATE
					1	1	Χ	undefined
					1	0	1	5 fps
					1	0	0	10 fps
					0	1	1	15 fps
					0	1	0	20 fps
					0	0	1	24 fps
					0	0	1	30 fps (by default)

Table 15: Detailed description of SNERT PPG register 0x09

Bit								SNERT register 09: PPG_CONTROL_1
7	6	5	4	3	2	1	0	Parameter
Х								reserved
								COMPRESSION_CLOCK
	1	1	Χ	Χ				reserved
	1	0	1	1				24 MHz
	1	0	1	0				19.2 MHz
	1	0	0	1				16 MHz
	1	0	0	0				12 MHz (by default)
	0	1	1	1				9.6 MHz
	0	1	1	0				8.0 MHz
	0	1	0	1				6.0 MHz
	0	1	0	0				4.8 MHz
	0	0	1	1				4.0 MHz
	0	0	1	0				2.4 MHz
	0	0	0	1				2.0 MHz
	0	0	0	0				off
								VGA_SENSOR_TYPE (valid if MSB set to logic 0)
					1	1		VGA (Sony and Panasonic)
					1	0		VGA (Sharp)
					0	Х		reserved
								PAL_VGA
							1	PAL or CIF timing
							0	VGA timing (by default)

Table 16: Detailed description of SNERT PPG register 0x0A

Bit								SNERT register 0A: PPG_H_CTRL
7	6	5	4	3	2	1	0	Parameter
Χ								reserved
								RG_SHORT
	1							RG pulse width is set to half of nominal value
	0							RG pulse width is set to nominal value
								FH2_CTRL (non FT mode) [1]
		1	Χ	1				no horizontal blanking
		1	Χ	0				no horizontal blanking, pulse inverted
		0	1	1				blanked to HIGH, starts HIGH
		0	1	0				blanked to LOW, starts LOW
		0	0	1				blanked to LOW, starts HIGH
		0	0	0				blanked to HIGH, starts LOW
								FH1_CTRL (non FT mode) ^[1]
					1	Χ	1	no horizontal blanking, pulse inverted
					1	Χ	0	no horizontal blanking
					0	1	1	blanked to HIGH, starts LOW
					0	1	0	blanked to HIGH, starts HIGH
					0	0	1	blanked to HIGH, starts LOW
					0	0	0	blanked to LOW, starts HIGH

^[1] If bits [5 to 3] equal bits [2 to 0] then FH2 is the inverse of FH1.

Table 17: Detailed description of SNERT PPG register 0x0B

Bit								SNERT register 0B: PPG_V_INV
7	6	5	4	3	2	1	0	Parameter
								A4_INV
1								positive pulses
0								negative pulses
								A3_INV
	1							positive pulses
	0							negative pulses
								A2_INV
		1						negative pulses
		0						positive pulses
								A1_INV
			1					negative pulses
			0					positive pulses
								B4_INV
				1				positive pulses
				0				negative pulses
								B3_INV
					1			positive pulses
					0			negative pulses
								B2_INV
						1		negative pulses
						0		positive pulses
								B1_INV
							1	negative pulses
							0	positive pulses

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Table 18: Detailed description of SNERT PPG register 0x0C

Bit								SNERT register 0C: PPG_H_INV
7	6	5	4	3	2	1	0	Parameter
								CLK2_INV
1								inverted pulses
0								nominal pulses
								CLK1_INV
	1							inverted pulses
	0							nominal pulses
								FS_INV
		1						positive pulses
		0						negative pulses
								FCDS_INV
			1					positive pulses
			0					negative pulses
								FR_INV
				1				positive pulses
				0				negative pulses
								C3_INV
					1			negative pulses
					0			positive pulses
								C2_INV
						1		negative pulses
						0		positive pulses
								C1_INV
							1	negative pulses
							0	positive pulses

Table 19: Detailed description of SNERT PPG register 0x0D

							SNERT register 0D: PPG_MISC_INV
6	5	4	3	2	1	0	Parameter
							SELECT_A2
							A2 is HIGH during read-out gate in line 2
							A2 is LOW during read-out gate in line 2
							SELECT_A3
1							A3 equals A4 (in case of VGA type 1 sensors)
0							A3 equals A2
							C4_INV
	1						negative pulses
	0						positive pulses
							CR_INV
		1					positive pulses
		0					negative pulses
							BCP_INV
			1				negative pulses
			0				positive pulses
							DCP_INV
				1			negative pulses
				0			positive pulses
							HD_INV
					1		negative pulses
					0		positive pulses
							VD_INV
						1	negative pulses
						0	positive pulses
	1	1 0	1 0 1 0	1 0 1 0	1 0 0 1 0 1 0 0 1	1 0 1 0 1 0 1 0 1 0 1 0 1 1 0 0 1 1 0 0 1 1 0 0 1 1 0 1	

Table 20: Detailed description of SNERT PPG register 0x0E

Bit								SNERT register 0E: PPG_SHUTTERSPEED_V_LSB
7	6	5	4	3	2	1	0	Parameter
Х	Х	Х	Χ	Χ	Χ	Χ	Χ	8 LSBs of line number (9 bits)

Table 21: Detailed description of SNERT PPG register 0x0F

Bit								SNERT register 0F: PPG_SHUTTERSPEED_H_LSB
7	6	5	4	3	2	1	0	Parameter
Х	Χ	Χ	Χ	Χ	Χ	Χ	Χ	8 LSBs of pixel number (10 bits)

Table 22: Detailed description of SNERT PPG register 0x10

								•
Bit								SNERT register 10: PPG_SHUTTERSPEED_MSB
7	6	5	4	3	2	1	0	Parameter
Χ	Χ	Χ	Χ					reserved
								SENSOR_TYPE
				1				Sony
				0				Sharp
					Х	Χ		MSBs of pixel number (10 bits)
							Χ	MSBs of line number (9 bits)

Table 23: Detailed description of SNERT PPG register 0x11

Bit								SNERT register 11: PPG_BCP_START_LSB
7	6	5	4	3	2	1	0	Parameter
Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ	8 LSBs of pixel number (10 bits) where BCP starts

Table 24: Detailed description of SNERT PPG register 0x12

Bit								SNERT register 12: PPG_BCP_STOP_LSB
7	6	5	4	3	2	1	0	Parameter
Χ	Χ	Χ	Χ	Χ	Χ	Χ	Х	8 LSBs of pixel number (10 bits) where BCP stops

Table 25: Detailed description of SNERT PPG register 0x13

Bit								SNERT register 13: PPG_DCP_START_LSB
7	6	5	4	3	2	1	0	Parameter
Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ	8 LSBs of pixel number (10 bits) where DCP starts

Table 26: Detailed description of SNERT PPG register 0x14

Bit								SNERT register 14: PPG_DCP_STOP_LSB
7	6	5	4	3	2	1	0	Parameter
Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ	8 LSBs of pixel number (10 bits) where DCP stops

Table 27: Detailed description of SNERT PPG register 0x15

Bit								SNERT register 15: PPG_BCP_DCP_MSB
7	6	5	4	3	2	1	0	Parameter
X	Χ							MSBs of PPG_DCP_STOP
		Χ	Χ					MSBs of PPG_DCP_START
				Χ	Χ			MSBs of PPG_BCP_STOP
						Χ	Χ	MSBs of PPG_BCP_START

Table 28: Detailed description of SNERT PPG register 0x16

Bit								SNERT register 16: PPG_B3_START_LSB
7	6	5	4	3	2	1	0	Parameter
Х	Х	Х	Χ	Χ	Χ	Χ	Χ	8 LSBs of pixel number (10 bits) where B3 starts

Table 29: Detailed description of SNERT PPG register 0x17

Bit								SNERT register 14: PPG_B3_STOP_LSB
7	6	5	4	3	2	1	0	Parameter
Х	Χ	Χ	Х	Χ	Χ	Х	Х	8 LSBs of pixel number (10 bits) where B3 stops

Table 30: Detailed description of SNERT PPG register 0x18

Bit								SNERT register 18: PPG_B4_START_LSB
7	6	5	4	3	2	1	0	Parameter
Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ	8 LSBs of pixel number (10 bits) where B4 starts

Table 31: Detailed description of SNERT PPG register 0x19

Bit								SNERT register 19: PPG_B4_STOP_LSB
7	6	5	4	3	2	1	0	Parameter
Х	Χ	Χ	Χ	Χ	Χ	Χ	Χ	8 LSBs of pixel number (10 bits) where B4 stops

Table 32: Detailed description of SNERT PPG register 0x1A

Bit								SNERT register 1A: PPG_B3_B4_MSB
Dit								SNERT register IA. FFO_D3_D4_MOD
7	6	5	4	3	2	1	0	Parameter
Χ	Χ							MSBs of PPG_B4_STOP
		Χ	Χ					MSBs of PPG_B4_START
				Χ	Χ			MSBs of PPG_B3_STOP
						Χ	Х	MSBs of PPG_B3_START

9.1.4 Video formatter and compression engine registers

Table 33: Detailed description of SNERT video formatter register 0x20

it								SNERT register 20: VP_VF_CONTRL_0
7	6	5	4	3	2	1	0	Parameter
Χ	Χ							reserved
								UV_EXCHANGE
		Χ						exchange chrominance irregularities if needed
								SCALE_DATA: limits the number of bits of the video signal
			1	1				undefined
			1	0				6 bits
			0	1				7 bits
			0	0				8 bits
								PREFILTER_B_COMB_ON_OFF (if filter B is on)
					1			prefilter B_COMB with 13 taps
					0			prefilter B_COMB with 7 taps
								PREFILTER_B_ON_OFF
						1		on with 7 taps
						0		bypassed
								PREFILTER_A_ON_OFF
							1	on with 3 taps
							0	bypassed

Table 34: Detailed description of SNERT video formatter register 0x21

Bit								SNERT register 21: VP_VF_CONTRL_1
7	6	5	4	3	2	1	0	Parameter
								420_FIL_BYPASS: 4 : 2 : 0 formatter mode
1								throw away samples
0								average UV samples
								VGA_RAW: data mode
	1							raw data, no scaling or 4:2:0 formatting
	0							YUV data
								VIDEO_OUTPUT_FORMAT
		1	1	1				undefined
		1	1	0				SIF
		1	0	1				QSIF
		1	0	0				undefined
		0	1	1				VGA
		0	1	0				CIF
		0	0	1				QCIF
		0	0	0				sub-QCIF
								VIDEO_INPUT_FORMAT
					1	1	1	undefined
					1	1	0	square SIF (sensors with square pixels)
					1	0	1	CIF (sensors with 12/11 pixel ratio format)
					1	0	0	medium resolution PAL
					0	1	1	undefined
					0	1	0	undefined
					0	0	1	undefined
					0	0	0	VGA

Table 35: Detailed description of SNERT video formatter register 0x22

Bit								SNERT register 22: VP_VF_VCOEF_C0_0
7	6	5	4	3	2	1	0	Parameter
Х								reserved
	Χ	Χ	Χ	Χ	Χ	Χ	Χ	vertical filter coefficient tap 0 phase 0

Table 36: Detailed description of SNERT video formatter register 0x23

Bit								SNERT register 23: VP_VF_VCOEF_C0_1
7	6	5	4	3	2	1	0	Parameter
Χ								reserved
	Χ	Χ	Χ	Χ	Χ	Χ	Χ	vertical filter coefficient tap 0 phase 1

				_	
Table 37.	Detailed des	crintion of 9	SNERT video 1	formatter r	agistar Nv2/
Table 31.	Detailed des		SINLINI VIUCU I	ioiiiiailei i	CUISICI UXZ4

Bit								SNERT register 24: VP_VF_VCOEF_C0_2
7	6	5	4	3	2	1	0	Parameter
Х								reserved
	Χ	Χ	Χ	Χ	Χ	Χ	Χ	vertical filter coefficient tap 0 phase 2

Table 38: Detailed description of SNERT video formatter register 0x25

Bit								SNERT register 25: VP_VF_VCOEF_C1_0
7	6	5	4	3	2	1	0	Parameter
Χ								reserved
	Χ	Χ	Χ	Χ	Χ	Χ	Х	vertical filter coefficient tap 1 phase 0

Table 39: Detailed description of SNERT video formatter register 0x26

Bit								SNERT register 26: VP_VF_VCOEF_C1_1
7	6	5	4	3	2	1	0	Parameter
Χ								reserved
	Χ	Χ	Χ	Χ	Χ	Χ	Х	vertical filter coefficient tap 1 phase 1

Table 40: Detailed description of SNERT video formatter register 0x27

Bit								SNERT register 27: VP_VF_VCOEF_C1_2
7	6	5	4	3	2	1	0	Parameter
Χ								reserved
	Χ	Χ	Χ	Χ	Χ	Χ	Χ	vertical filter coefficient tap 1 phase 2

Table 41: Detailed description of SNERT video formatter register 0x28

Bit								SNERT register 28: VP_VF_VCOEF_C2_0
7	6	5	4	3	2	1	0	Parameter
Х								reserved
	Χ	Χ	Χ	Χ	Χ	Χ	Χ	vertical filter coefficient tap 2 phase 0

Table 42: Detailed description of SNERT video formatter register 0x29

Bit								SNERT register 29: VP_VF_VCOEF_C2_1
7	6	5	4	3	2	1	0	Parameter
Χ								reserved
	Χ	Χ	Χ	Χ	Χ	Χ	Х	vertical filter coefficient tap 2 phase 1

Table 43: Detailed description of SNERT video formatter register 0x2A

Bit								SNERT register 2A: VP_VF_VCOEF_C2_2
7	6	5	4	3	2	1	0	Parameter
Χ								reserved
	Χ	Χ	Χ	Χ	Χ	Χ	Х	vertical filter coefficient tap 2 phase 2

Table 44: Detailed description of SNERT video formatter register 0x2B

Bit								SNERT register 2B: VP_VF_VCOEF_C3_0
7	6	5	4	3	2	1	0	Parameter
Х								reserved
	Χ	Χ	Χ	Χ	Χ	Χ	Χ	vertical filter coefficient tap 3 phase 0

Table 45: Detailed description of SNERT video formatter register 0x2C

Bit								SNERT register 2C: VP_VF_VCOEF_C3_1
7	6	5	4	3	2	1	0	Parameter
Χ								reserved
	Χ	Χ	Χ	Χ	Χ	Χ	Х	vertical filter coefficient tap 3 phase 1

Table 46: Detailed description of SNERT video formatter register 0x2D

Bit								SNERT register 2D: VP_VF_VCOEF_C3_2
7	6	5	4	3	2	1	0	Parameter
Х								reserved
	Χ	Χ	Χ	Χ	Χ	Χ	Χ	vertical filter coefficient tap 3 phase 2

Table 47: Detailed description of SNERT video formatter register 0x2E

Bit									SNERT register 2E: VP_VF_LIMITER
7	6	6	5	4	3	2	1	0	Parameter
Χ	Х	X	Х	Х	Χ	Χ	Χ	Χ	output of the video formatter is clipped to this maximum value

Table 48: Detailed description of SNERT compression engine register 0x2F

Bit								SNERT register 2F: VP_VF_CONTROL
7	6	5	4	3	2	1	0	Parameter
Χ								reserved
								QTABLE_SELECT: quantization table select
	Χ	Χ	Χ	Χ				range [0 : 15]
								DC_COEFF_LENGTH
					1	1		undefined
					1	0		8 bits
					0	1		7 bits
					0	0		6 bits
								COMPRESSION_MODE
							1	on
							0	off (by default)

Table 49: Detailed description of SNERT compression engine register 0x30

Bit								SNERT register 30: VP_C_YMASK
7	6	5	4	3	2	1	0	Parameter
Х	Χ	Χ	Χ	Χ	Χ	Χ	Х	operates an AND between this value and the compression engine input; can be used to set bit positions in the Y signal to 0 (by default 0x00)

Table 50: Detailed description of SNERT compression engine register 0x31

Bit								SNERT register 31: VP_C_UVMASK
7	6	5	4	3	2	1	0	Parameter
Х	Χ	Χ	Х	Χ	Χ	Х	Χ	operates an AND between this value and the compression engine input; can be used to set bit positions in the UV signal to 0 (by default 0x00)

Table 51: Detailed description of SNERT compression engine register 0x32

Bit								SNERT register 32: VP_C_BITCOST_MSB
7	6	5	4	3	2	1	0	Parameter
Χ	Χ	Χ	Х	Χ	Χ	Х	Χ	set the compression ratio; the bitcost determines the maximum number of bits generated by the compression algorithm for 4 subsequent lines

Table 52: Detailed description of SNERT compression engine register 0x33

Bit								SNERT register 33: VP_C_BITCOST_LSB
7	6	5	4	3	2	1	0	Parameter
Х	Χ	Χ	Χ	Χ	Χ	Χ	Х	set the compression ratio; the bitcost determines the maximum number of bits generated by the compression algorithm for 4 subsequent lines

Table 53: Detailed description of SNERT compression engine register 0x34

Bit								SNERT register 34: VP_C_THRESHOLD_MSB
7	6	5	4	3	2	1	0	Parameter
Х	Χ	Χ	Χ	Χ	Χ	Χ	Х	output of the video formatter is clipped to this maximum value

Table 54: Detailed description of SNERT compression engine register 0x35

Bit								SNERT register 35: VP_C_THRESHOLD_LSB
7	6	5	4	3	2	1	0	Parameter
X	Χ	Χ	Χ	Χ	Χ	X	Χ	threshold must be set to: (number of UV blocks per band) × (DC_COEFF_LENGTH + 2)

Table 55: Detailed description of SNERT compression engine register 0x36

Bit								SNERT register 36: VP_TR_CONTROL
7	6	5	4	3	2	1	0	Parameter
Χ								reserved
								VGA_FORMAT
	1							4:2:2 (uncompressed only)
	0							4:2:0
								INBAND_CONTROL
		1						on
		0						off
								LLC_OUT_DIV: select the rate at which the video data is transmitted to the USB core
			Х	Х	Х	Х	Χ	range [1 to 31]

Table 56: Detailed description of SNERT compression engine register 0x37

Bit								SNERT register 37: VP_TR_SQCIF_OFFSET
7	6	5	4	3	2	1	0	Parameter
								VERTICAL_OFFSET
Χ	Χ	Χ	Χ					range 3 × [0 to 15]
								HORIZONTAL_OFFSET
				Χ	Χ	Χ	Χ	range $4 \times [0 \text{ to } 12]$

Table 57: Detailed description of SNERT compression engine register 0x38

Bit								SNERT register 38: VP_VS_V_SHIFT
7	6	5	4	3	2	1	0	Parameter
Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ	shift internal line counter with respect to VS pulse

9.1.5 Switch mode power registers

Table 58: Detailed description of SNERT SMP register 0x3D

Bit								SNERT register 3D: SMP_PERIOD
7	6	5	4	3	2	1	0	Parameter
Х	Х	Χ	Х	Χ	Χ	Χ	Χ	period of SMP signal in units of 4 × XOSC_PERIOD (0 by default)

Table 59: Detailed description of SNERT SMP register 0x3E

Bit								SNERT register 3E: SMP_LOWTIME
7	6	5	4	3	2	1	0	Parameter
Х	Χ	Χ	Χ	Χ	Χ	Χ	Χ	low edge of SMP signal in units of 4 × XOSC_PERIOD (0 by default)

9.1.6 Audio variable gain amplifier

Table 60: Detailed description of SNERT audio gain amplifier register 0x3F

Bit								SNERT register 3F: AUDIO_VGAIN
7	6	5	4	3	2	1	0	Parameter
Χ	Χ							reserved
								SIS: serial interface select
		1						SNERT
		0						I ² C-bus
			Χ					reserved
				Χ	Х	Χ	Х	variable gain settings (0 to 30 dB)

9.2 I²C-bus interface

The USB function has its own I²C-bus interface for communication with the microcontroller. The I²C-bus uses two addresses:

- Command address for writing commands to the Memory Manager (MM)
- Data address for writing/reading data to/from the Memory Manager (MM).

An address is a byte. The 7 MSBs are the actual address, the LSB is the R/\overline{W} bit. When it is logic 0, data is transferred from the master to the slave, when it is logic 1, data is written from the slave to the master.

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The 6 MSBs of the two addresses are equal and are defined by the $PI_Address = 010111$ (see Table 61). The LSB of the address differentiates between the command address and the data address. When bit 1 is logic 1 the address is the command address (0x5E) and when bit 1 is logic 0 the address is one of the data addresses (0x5C or 0x5D).

Table 61: I²C-bus addresses

Bit								Address
7	6	5	4	3	2	1	0	
0	1	0	1	1	1	0	0	0x5C: for writing data to the memory manager
0	1	0	1	1	1	0	1	0x5D: for reading data from the memory manager
0	1	0	1	1	1	1	0	0x5E: for writing commands
0	1	0	1	1	1	1	1	0x5F: not in use

9.2.1 Commands

The commands listed in Table 62 must be sent to the I²C-bus address 0x5E.

Table 62: I²C-bus USB command codes

Bit								Function
DIL								FUNCTION
7	6	5	4	3	2	1	0	
0	0		en	d-poin	t numl	oer		select end-point
0	1		en	d-poin	t numl	oer		read/write status
1	0		en	d-poin	t numl	oer		initialize/read status information
1	1	0	1		add	ress		read/write register bank
1	1	1	0	0	Х	Χ	Χ	not used
1	1	1	0	1	0	0	0	set non-USB register
1	1	1	1	0	0	0	0	read/write data
1	1	1	1	0	0	0	1	acknowledge setup
1	1	1	1	0	0	1	0	set buffer empty
1	1	1	1	1	0	1	0	set buffer full
1	1	1	1	0	1	0	0	read interrupt register
1	1	1	1	0	1	0	1	read current frame number
1	1	1	1	0	1	1	0	send resume
1	1	1	1	0	1	1	1	set status change bits
1	1	1	1	0	0	1	1	set mode

Table 63: Detailed description of set mode and write register overview

Byte	Set_mode_and_write
3	N1 timer: programmable timer for power management; counts 12 MHz cycles; must be bigger than number of cycles needed for the microcontroller to go in power-down state after pin SUSPREADYNOT is made LOW
2	N2 timer: programmable timer for power management; counts 12 MHz cycles; determines the time between the microcontroller clock is switched off and the main clock is switched off
1	PSIE-MMU control byte (see Table 64)

Table 64: Detailed description of set mode and write byte 3

Bit								PSIE-MMU control byte
7	6	5	4	3	2	1	0	Parameter
Χ	Χ	Х						reserved
								interrupt after isochronous audio transfer
			1					for each isochronous audio transfer an interrupt to the microcontroller will be generated; default set to logic 1 upon general Power-on reset and/or bus reset by the SAA8115HL
			0					no interrupts are given to the microcontroller
								interrupt after isochronous video transfer
				1				for each isochronous video transfer an interrupt to the microcontroller will be generated; default set to logic 1 upon general Power-on reset and/or bus reset by the SAA8115HL
				0				no interrupts are given to the microcontroller
								audio end-point
					1			audio end-point enabled; default set to logic 1 upon general Power-on reset and/or bus reset by the SAA8115HL
					0			audio end-point disabled; the PSIE-MMU will not react on in-tokens on the audio end-point
								video end-point
						1		video end-point enabled; default set to logic 1 upon general Power-on reset and/or bus reset by the SAA8115HL
						0		video end-point disabled; the PSIE-MMU will not react on in-tokens on the video end-point
								error debug mode
							1	interrupts are generated only in the event the transfer is not successfully completed; the microcontroller can read data from the interrupt and status registers to see the cause of this error
							0	all successful USB transactions are reported to the microcontroller via an interrupt; default set to logic 0 upon general power-on reset by the SAA8115HL

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Table 65: Detailed description of set mode and read status byte

Bit								PSIE-MMU status byte
7	6	5	4	3	2	1	0	Parameter
Χ	Χ	Χ	Χ					reserved
								remote wake-up status flag
				1				remote wake-up when device is in SUSPEND mode
				0				no remote wake-up
								resume status flag
					1			bus resume by the host when device is in SUSPEND mode
					0			no bus resume
								bus reset status flag
						1		bus reset
						0		no bus reset
								power-up status flag
							1	general power-up reset
							0	no power-up reset

9.2.2 End-points

The SAA8115HL has 6 logical end-points which are listed in Table 66.

Table 66: Mapping of logical to physical end-point numbers for used end-points

End-point name	Logical	Buffer size	Physical end-point			
	end-point		Out	In		
Control end-point	0	8	0	1		
Control end-point	1	8	2	3		
Interrupt end-point	2	8	_	4		
Interrupt end-point	3	8	_	5		
Iso video end-point	4	96.0	_	6		
Iso video end-point	5	35.1	_	7		

9.2.3 Control top registers

The following registers can be written on I^2C -bus address 1 after the command 0xE8 on I^2C -bus address 0.

Table 67: I²C-bus control top registers

Address	Control top registers (base address: 0x08)
0x08	clock control
0x09	reset control
0x0A	mux block control
0x0B	power-on analog modules control

Table 68: Detailed description of I²C-bus control top registers 0x08

Bit								Top register 0x08: clkshop_control
7	6	5	4	3	2	1	0	Parameter
								select ADC clock source
1								sel_ad: clock generated from ADC
0								sel_pll: clock generated from PLL
								set clock dividers for ADC
	0	0						set_divide00: divided by 1
	0	1						set_divide01: divided by 2
	1	0						set_divide10: divided by 4
	1	1						set_divide11: divided by 8
			Χ					reserved
								disable 48 MHz clock
				1				dis_clk_48: disable 48 MHz clock
				0				enable clock
								disable receiver clock
					1			dis_clk_rec: disable receiver clock
					0			enable clock
								disable ADC clock
						1		dis_clk_ad: disable ADC clock
						0		enable clock
							Χ	reserved

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Table 69: Detailed description of I²C-bus control top registers 0x09

Bit								Top register 0x09: rst_gen and PLL_control
7	6	5	4	3	2	1	0	Parameter
								set PLL frequency
0	0							fcode00: 256 × 44.1 kHz
0	1							fcode01: 256 × 32 kHz
1	0							fcode10: 256 × 48 kHz
1	1							fcode11: 256 × 44.1 kHz
		Χ	Χ					reserved
								reset PSIE-MMU top module
				1				upc_rst_mmu: resetting the USB protocol block (called PSIE-MMU) during tests or in case of errors
				0				no reset
					Χ			reserved
								reset ADIF top module
						1		upc_rst_adif: resetting the digital audio part during tests or in case of errors
						0		no reset
								reset AGC module
							1	upc_rst_AGC: resetting the AGC control during tests or in case of errors
							0	no reset

Table 70: Detailed description of I²C-bus control top registers 0x0A

Bit								Top register 0x0A: io_mux_control
7	6	5	4	3	2	1	0	Parameter
Х	Χ	Х	Χ	Χ	Χ	Χ	Χ	reserved

Table 71: Detailed description of I²C-bus control top registers 0x0B

Bit								Top register 0x0B: power_control_of_analog_modules
7	6	5	4	3	2	1	0	Parameter
								power control oscillator module
1								upc_osc_off: power management 48 MHz enabled
0								power management 48 MHz disabled
								power control audio module
	1							upc_osc_ad_off: power management audio enabled
	0							power management audio disabled
								power control PLL module
		1						upc_pll_off: PLL power-off
		0						power-on
			Χ					reserved
								power control ADC module left channel
				1				upc_adl_off: power-off
				0				power-on
								power control ADC module right channel
					1			upc_adr_off: power-off
					0			power-on
								power control AGC module left channel
						1		upc_AGCI_off: power-off
						0		power-on
								power control AGC module right channel
							1	upc_AGCr_off: power-off
							0	power-on

9.2.4 Video FIFO registers

Table 72: I²C-bus video FIFO registers overview

Address	Video FIFO registers (base address: 0x04)
0x04	FIFO offset (8 LSBs)
0x05	FIFO active and FIFO offset (3 MSBs)
0x06	packet size (8 LSBs)
0x07	read spacing and packet size (2 MSBs)

Table 73: Detailed description of I²C-bus video FIFO registers 0x04

Bit								FIFO register 0x04: FIFO_offset
7	6	5	4	3	2	1	0	Parameter
								FIFO_OFFSET
Х	Х	X	Х	X	Х	Х	Х	mode_fifo_offset: sets the minimum contents of the FIFO that has to be reached, before a new video frame will be put on the USB. This value can be set between 0 and 2047. Total 11 bits with 8 LSBs in this register and 3 MSBs in register 0x05.

Table 74: Detailed description of I²C-bus video FIFO registers 0x05

Bit								FIFO register 0x05: FIFO_active and FIFO_offset				
7	6	5	4	3	2	1	0	Parameter				
								FIFO_ACTIVE				
1							mode_active: FIFO is active and the contents of the other mode registers should not be updated by the microcontroller (maledictive) FIFO not active					
0								FIFO not active				
	Χ	Χ	Χ	Χ				reserved				
								FIFO_OFFSET (MSBs)				
					Χ	Χ	Χ	3 MSBs of the offset value; see also register 0x04				

Table 75: Detailed description of I²C-bus video FIFO registers 0x06

								-
Bit								FIFO register 0x06: packet_size
7	6	5	4	3	2	1	0	Parameter
								PACKET_SIZE
Х	Χ	X	X	Χ	X	Χ	X	mode_packet_size: sets the packet size of the USB video channel. Packets can vary in size between 0 and 1023. Total 10 bits with 8 LSBs in this register and 2 MSBs in register 0x07.

Table 76: Detailed description of I²C-bus video FIFO registers 0x07

Bit								FIFO register 0x07: read_spacing and packet_size
7	6	5	4	3	2	1	0	Parameter
								READ_SPACING
X	Χ	Χ	Χ	Χ	Χ			mode_read_spacing: sets the periodicity of the read pulses; the periodicity can be set from 1 to 63 (from '000001' to '1111111')
								PACKET_SIZE
						Χ	Χ	mode_packet_size: 2 MSBs of the value (8 LSBs in register 0x06)

9.2.5 ADIF top registers

Table 77: I²C-bus ADIF top registers overview

Address	ADIF top registers (base address: 0x0C)
0x0C	reserved
0x0D	reserved
0x0E	VGA control gain
0x0F	ADIF control (ADIF2MMU)

Table 78: Detailed description of I²C-bus ADIF top registers 0x0E

Bit								ADIF register 0x0E: GAIN_control
7	6	5	4	3	2	1	0	Parameter
Χ								reserved
								GAIN_SOURCE_SELECT
	0							reserved
	1							gain is controlled directly by bits 3 to 0
		Х	Χ					reserved
								GAIN_CONTROL; 0 to 30 dB in steps of 2 dB
				0	0	0	0	0 dB
				0	0	0	1	2 dB
				:	:	:	:	:
				0	1	1	1	28 dB
				1	1	1	1	30 dB

Table 79: Detailed description of I²C-bus ADIF top registers 0x0F

Bit								ADIF register 0x0F: ADIF_control
7	6	5	4	3	2	1	0	Parameter
Χ								reserved
								number of bytes per sample
	0	0						0 (reserved)
	0	1						1 (8 bits audio samples)
	1	0						2 (16 bits audio samples)
	1	1						3 (24 bits audio samples)
								selection mono/stereo operation
			0					mono
			1					stereo
								selection input for ADC path (ADIF mux)
				0				digital input (from I ² S-bus)
				1				analog input (from Vin_left and Vin_right)
								selection high-pass filter (DC filter) for ADC down sample filter
					0			high-pass filter off
					1			high-pass filter on
								selection audio serial input format
						0	0	I ² S-bus
						0	1	LSB-justified, 16 bits
						1	0	LSB-justified, 18 bits
						1	1	LSB-justified, 20 bits

10. Limiting values

Table 80: Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V_{DDA}	analog supply voltage		-0.5	+4.0	V
$V_{\text{DDA(USB)}}$	analog supply voltage from USB		[1] -0.5	+5.5	V
V_{DDD}	digital supply voltage		-0.5	+4.0	V
V _n	voltage on				
	pins AGND and DGND		-0.5	+4.0	V
	all other pins		-0.5	$V_{DD} + 0.5$	V
T_{stg}	storage temperature		– 55	+150	°C
T _{amb}	ambient temperature		0	70	°C
Tj	junction temperature		-40	+125	°C

^[1] This concerns pins VBUS1 and VBUS2.

11. Thermal characteristics

Table 81: Thermal characteristics

Symbol	Parameter	Conditions	Value	Unit
R _{th(j-a)}	thermal resistance from junction to ambient	in free air	45	K/W

12. Characteristics

Table 82: Characteristics

 $V_{DDD}=V_{DDA}=3.3~V\pm10\%;~T_{amb}=0~to~70\,^{\circ}C.$

Symbol	Parameter	Conditions		Min	Тур	Max	Unit
Supplies							
V_{DDDn}	digital supply voltage			3.0	3.3	3.6	V
V_{DDAn}	analog supply voltage			3.0	3.3	3.6	V
V _{DDA(USB)}	analog supply voltage from USB		[1]	4.3	5.0	5.5	V
V_{DGND}	digital ground supply			-0.3	0.0	+0.3	V
V_{AGND}	analog ground supply			-0.3	0.0	+0.3	V
I_{DD}	supply current		[2]	_	100	125	mΑ
$I_{DD(DC-DC)}$	DC-DC supply current		[3]	_	240	320	mΑ
Data and o	control inputs						
V_{IL}	LOW-level input voltage			_	_	0.8	V
V_{IH}	HIGH-level input voltage			2.0	_	_	V
Data and o	control outputs						
V_{OL}	LOW-level output voltage			0	_	$0.1V_{DDD}$	V
V_{OH}	HIGH-level output voltage			$0.9V_{DDD}$	_	V_{DDD}	V
Microphor	ne supply						
I _{DD0}	supply current			_	0.85	1.2	mΑ

Table 82: Characteristics...continued

 $V_{DDD} = V_{DDA} = 3.3 \ V \pm 10\%; \ T_{amb} = 0 \ to \ 70 \ ^{\circ}C.$

Symbol	Parameter	Conditions		Min	Тур	Max	Unit
V_{ref}	input reference voltage	at ½ V _{DDA}		-	1.65	_	V
√o	output voltage	$V_{DDA} = 3.3 V$		_	3.0	_	V
0	output current			_	_	2.0	mΑ
Low noise	e amplifier						
Transfer fu	ınction						
R _i	input impedance			3.5	5.0	_	kΩ
I_{DD1}	supply current			_	0.85	1.2	mA
A	amplification			27	28	29	dB
V _{o(rms)}	output voltage (RMS value)			_	-	800	mV
THD	total harmonic distortion		[4]	_	-69	-63	dB
V ₀₀₁	output offset voltage			_	0.0	1.0	mV
Biasing							
I _{ref1}	reference current			_	10	_	μΑ
Variable g	gain amplifier						
Transfer fu	ınction						
R _i	input impedance			7.0	10.5	13	kΩ
I _{DD2}	supply current			_	0.45	0.6	mA
A	amplification			0.0	_	32	dB
THD	total harmonic distortion		[5]	_	-88	-82	dB
			[6]	_	-65	-57	dB
V _{OO2}	output offset voltage	A = 0 dB		_	1.0	2.0	mV
		A = 30 dB		_	14	30	mV
Biasing							
I _{ref2}	reference current			_	10	_	μΑ
Audio PLI	L						
f _{i(clk)}	clock input frequency			_	48	_	MHz
f _{o(clk)}	clock output frequency		[7]	_	11.2996	_	MHz
В	bandwidth			_	2.3	_	kHz
ζ	damping			_	0.98	_	
Audio AD	C (∑∆ converter)						
Inputs							
f _i	input signal frequency			1	_	20	kHz
V _{i(rms)}	input voltage (RMS value)			_	800	_	mV
Transfer F	unction						
N	order of the $\Sigma\Delta$			_	3	_	
N _{bit}	number of output bits			_	1	_	
N _{bit(eq)}	equivalent output resolution (bit)			_	16	_	
DRi	dynamic range at input		[8]	_	96.6	_	dB
f _{clk}	clock frequency			_	_	5.6448	MHz
δ	clock frequency duty factor			_	50	_	%

Table 82: Characteristics...continued

 $V_{DDD} = V_{DDA} = 3.3 \text{ V} \pm 10\%; T_{amb} = 0 \text{ to } 70 \,^{\circ}\text{C}.$

Symbol	Parameter	Conditions		Min	Тур	Max	Unit
THD	total harmonic distortion			_	-70	-55	dB
ATX transo	ceiver						
Driver char	acteristics in full speed mode: pins ATXDP and	ATXDM					
f _{o(sample)}	sample output frequency			4	_	48	kHz
t _r	rise transition time	$C_L = 50 pF$		4	_	20	ns
t _f	fall transition time	$C_L = 50 pF$		4	_	20	ns
t _{match}	transition time matching		[9]	90	_	110	%
V _{cr}	output signal crossover voltage			1.3	_	2.0	V
Z _o	driver output impedance	steady state drive		30	_	42	Ω
Receiver cl	naracteristics in full speed mode: pins ATXDP a	nd ATXDM					
f _{i(sample)}	sample input frequency			5	_	55	kHz
$f_{i(D)}$	data input frequency rate			_	12.00	_	Mbits/s
t _{frame}	frame interval			_	1.000	_	ms
DC-to-DC	converter						
5 V up and	down converter (switchable supply domain)						
Vo	output voltage			4.9	5.0	5.1	V
V_{ripple}	ripple on output voltage			_	20	_	mV
IL	load current			_	_	150	mA
R _{DSON_P1}	PMOS switch-on resistance; down converter		[10]	_	1.0	_	Ω
R _{DSON_N1}	NMOS switch-on resistance; down converter		[10]	_	4.5	_	Ω
R_{DSON_P2}	PMOS switch-on resistance; up converter		[10]	_	1.1	_	Ω
R_{DSON_N2}	NMOS switch-on resistance; up converter		[10]	_	4.6	_	Ω

- [1] This concerns pins VBUS1 and VBUS2.
- [2] Conditions:
 - a) typical: VGA at 15 fps; $V_{DDD} = V_{DDA} = 3.3 \text{ V}$; $T_{amb} = 25 \,^{\circ}\text{C}$
 - b) maximum: VGA at 30 fps; $V_{DDD} = V_{DDA} = 3.6$ V; $T_{amb} = 70$ °C.
- [3] Conditions (I_{OUT} = 125 mA):
 - a) typical: $V_{DD(USB)} = 5.0 \text{ V}$; $T_{amb} = 25 ^{\circ}\text{C}$
 - b) maximum: $V_{DD(USB)} = 4.3 \text{ V}$; $T_{amb} = 70 ^{\circ}\text{C}$.
- [4] The distortion is measured at 1 kHz, $V_{o(rms)} = 600$ mV.
- [5] The distortion is measured at 1 kHz, $V_{o(rms)} = 600$ mV and A = 0 dB.
- [6] The distortion is measured at 1 kHz, $V_{o(rms)} = 600$ mV and A = 30 dB.
- [7] Frequencies depend on PLL settings (see Table 5).
- [8] Defined here as: $20 \times log \frac{input \ voltage}{equivalent input \ noise \ voltage}$
- [9] Transition time matching: $t_{match} = \frac{t_r}{t_f} \times 100\%$
- [10] Including metal and contact resistance on chip and bonding wire resistance.

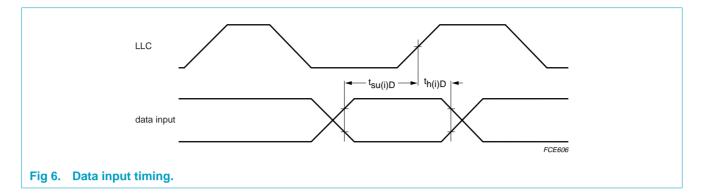
13. Timing

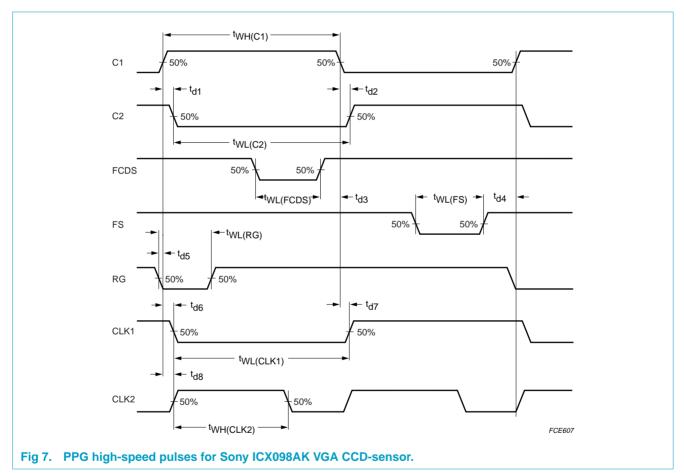
Table 83: Timing

 $V_{DDD} = V_{DDA} = 3.3 \ V \pm 10\%$; $T_{amb} = 0 \text{ to } 70 \,^{\circ}\text{C}$.

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
Data inpu	t related to LLC (see Figure 6)					
Pins YUV	to YUV7, HREF, VS					
t _{su(i)(D)}	data input set-up time		5	_	_	ns
t _{h(i)(D)}	data input hold time		3	_	_	ns
PPG high	-speed pulses for Sony ICX098AK VGA CCD-sensor a	t 15 fps (see Figure 7)				
t _{d1}	delay between falling edge C2 and rising edge C1		-3.5	-2.5	-1.5	ns
t_{d2}	delay between rising edge C2 and falling edge C1		0	1.5	3	ns
t _{d3}	delay between falling edge C1 and rising edge FCDS		19	21	23	ns
t _{d4}	delay between rising edge C1 and rising edge FS		20	22	24	ns
t _{d5}	delay between rising edge C1 and falling edge RG		0	2	4	ns
t _{d6}	delay between falling edge CLK1 and rising edge C1		0	0.5	3	ns
t _{d7}	delay between rising edge CLK1 and falling edge C1		1	3.0	4	ns
t _{d8}	delay between rising edge CLK2 and rising edge C1		0	1.5	2.5	ns
t _{WH(C1)}	C1 pulse width HIGH		80	81	_	ns
t _{WL(C2)}	C2 pulse width LOW		83	85	_	ns
t _{WL(FCDS)}	FCDS pulse width LOW		16	18.5	_	ns
t _{WL(FS)}	FS pulse width LOW		41	42	_	ns
t _{WL(RG)}	RG pulse width LOW		42	43	_	ns
t _{WL(CLK1)}	CLK1 pulse width LOW		82	84.5	_	ns
t _{WH(CLK2)}	CLK2 pulse width HIGH		38	40	_	ns
t _r	rise time	[1]				
	pulse C1		_	4	_	ns
	pulse C2		_	4	_	ns
	pulse RG		_	4	_	ns
	pulse FCDS		_	4	_	ns
	pulse FS		_	4	_	ns
t _f	fall time	[1]				
	pulse C1		_	4	_	ns
	pulse C2		_	4	_	ns
	pulse RG		_	4	_	ns
	pulse FCDS		_	4	_	ns
	pulse FS		_	4	_	ns

^[1] $C_L = 11 \text{ pF}; T_{amb} = 25 \,^{\circ}\text{C}.$





Application information

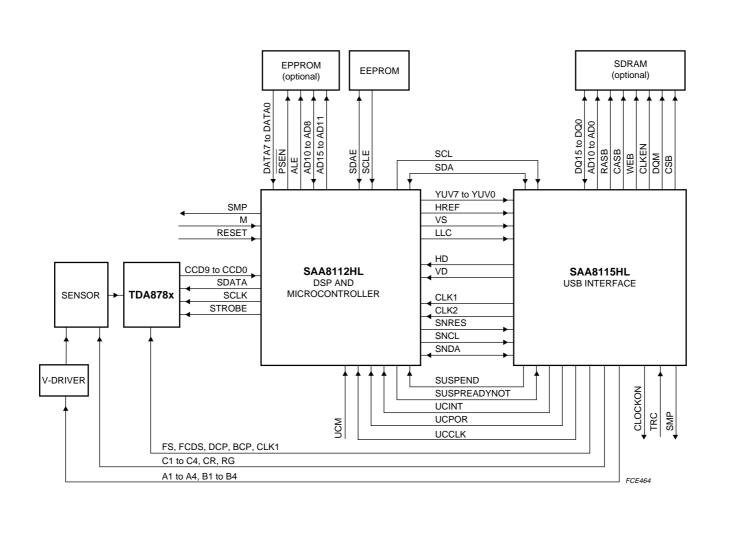


Fig 8. Typical USB camera application.

Product specification

Rev. 04 —

10 August 2000

9397 750 07395

15. Package outline

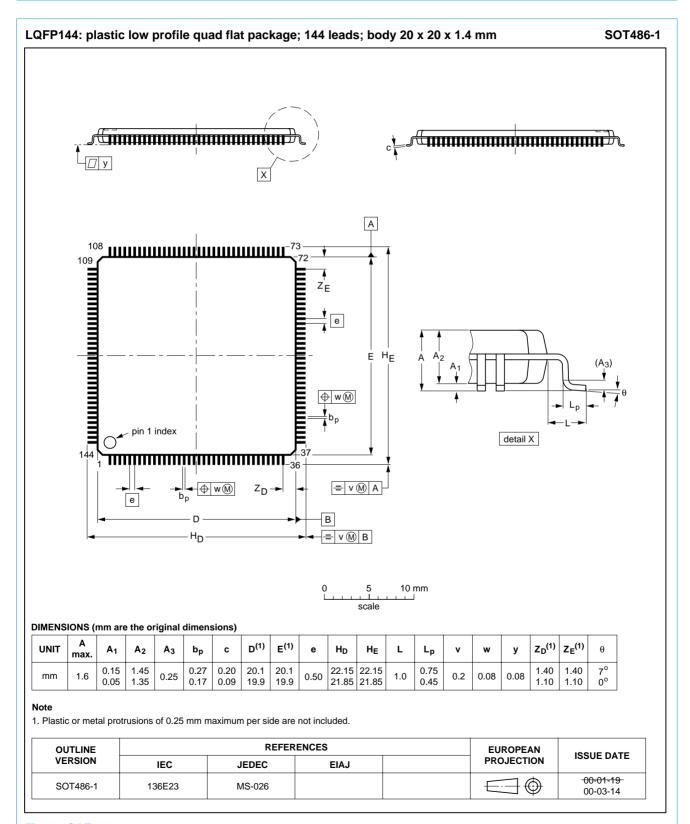


Fig 9. SOT486-1.

16. Soldering

16.1 Introduction to soldering surface mount packages

This text gives a very brief insight to a complex technology. A more in-depth account of soldering ICs can be found in our *Data Handbook IC26; Integrated Circuit Packages* (document order number 9398 652 90011).

There is no soldering method that is ideal for all surface mount IC packages. Wave soldering can still be used for certain surface mount ICs, but it is not suitable for fine pitch SMDs. In these situations reflow soldering is recommended.

16.2 Reflow soldering

Reflow soldering requires solder paste (a suspension of fine solder particles, flux and binding agent) to be applied to the printed-circuit board by screen printing, stencilling or pressure-syringe dispensing before package placement.

Several methods exist for reflowing; for example, convection or convection/infrared heating in a conveyor type oven. Throughput times (preheating, soldering and cooling) vary between 100 and 200 seconds depending on heating method.

Typical reflow peak temperatures range from 215 to 250 °C. The top-surface temperature of the packages should preferable be kept below 220 °C for thick/large packages, and below 235 °C small/thin packages.

16.3 Wave soldering

Conventional single wave soldering is not recommended for surface mount devices (SMDs) or printed-circuit boards with a high component density, as solder bridging and non-wetting can present major problems.

To overcome these problems the double-wave soldering method was specifically developed.

If wave soldering is used the following conditions must be observed for optimal results:

- Use a double-wave soldering method comprising a turbulent wave with high upward pressure followed by a smooth laminar wave.
- For packages with leads on two sides and a pitch (e):
 - larger than or equal to 1.27 mm, the footprint longitudinal axis is preferred to be parallel to the transport direction of the printed-circuit board;
 - smaller than 1.27 mm, the footprint longitudinal axis must be parallel to the transport direction of the printed-circuit board.

The footprint must incorporate solder thieves at the downstream end.

• For packages with leads on four sides, the footprint must be placed at a 45° angle to the transport direction of the printed-circuit board. The footprint must incorporate solder thieves downstream and at the side corners.

During placement and before soldering, the package must be fixed with a droplet of adhesive. The adhesive can be applied by screen printing, pin transfer or syringe dispensing. The package can be soldered after the adhesive is cured.

Typical dwell time is 4 seconds at 250 °C. A mildly-activated flux will eliminate the need for removal of corrosive residues in most applications.

16.4 Manual soldering

Fix the component by first soldering two diagonally-opposite end leads. Use a low voltage (24 V or less) soldering iron applied to the flat part of the lead. Contact time must be limited to 10 seconds at up to 300 °C.

When using a dedicated tool, all other leads can be soldered in one operation within 2 to 5 seconds between 270 and 320 °C.

16.5 Package related soldering information

Table 84: Suitability of surface mount IC packages for wave and reflow soldering methods

Package	Soldering method	
	Wave	Reflow ^[1]
BGA, LFBGA, SQFP, TFBGA	not suitable	suitable
HBCC, HLQFP, HSQFP, HSOP, HTQFP, HTSSOP, SMS	not suitable ^[2]	suitable
PLCC ^[3] , SO, SOJ	suitable	suitable
LQFP, QFP, TQFP	not recommended [3][4]	suitable
SSOP, TSSOP, VSO	not recommended [5]	suitable

- [1] All surface mount (SMD) packages are moisture sensitive. Depending upon the moisture content, the maximum temperature (with respect to time) and body size of the package, there is a risk that internal or external package cracks may occur due to vaporization of the moisture in them (the so called popcorn effect). For details, refer to the Drypack information in the Data Handbook IC26; Integrated Circuit Packages; Section: Packing Methods.
- [2] These packages are not suitable for wave soldering as a solder joint between the printed-circuit board and heatsink (at bottom version) can not be achieved, and as solder may stick to the heatsink (on top version).
- [3] If wave soldering is considered, then the package must be placed at a 45° angle to the solder wave direction. The package footprint must incorporate solder thieves downstream and at the side corners.
- [4] Wave soldering is only suitable for LQFP, QFP and TQFP packages with a pitch (e) equal to or larger than 0.8 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.65 mm.
- [5] Wave soldering is only suitable for SSOP and TSSOP packages with a pitch (e) equal to or larger than 0.65 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.5 mm.

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Digital camera USB interface

17. Revision history

Table 85: Revision history

Rev	Date	CPCN	Description
04	20000810	-	Product specification; fourth version
03	20000127	-	Preliminary specification; third version
02	19991126	-	Preliminary specification; second version
01	19990628	-	Preliminary specification; initial version

18. Data sheet status

Datasheet status	Product status	Definition [1]
Objective specification	Development	This data sheet contains the design target or goal specifications for product development. Specification may change in any manner without notice.
Preliminary specification	Qualification	This data sheet contains preliminary data, and supplementary data will be published at a later date. Philips Semiconductors reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.
Product specification	Production	This data sheet contains final specifications. Philips Semiconductors reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.

[1] Please consult the most recently issued data sheet before initiating or completing a design.

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Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 60134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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Philips Semiconductors - a worldwide company

Argentina: see South America

Australia: Tel. +61 2 9704 8141, Fax. +61 2 9704 8139 **Austria:** Tel. +43 160 101, Fax. +43 160 101 1210 **Belarus:** Tel. +375 17 220 0733, Fax. +375 17 220 0773

Belgium: see The Netherlands **Brazil:** see South America

Bulgaria: Tel. +359 268 9211, Fax. +359 268 9102

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Denmark: Tel. +45 3 288 2636, Fax. +45 3 157 0044 **Finland:** Tel. +358 961 5800, Fax. +358 96 158 0920 **France:** Tel. +33 14 099 6161, Fax. +33 14 099 6427 **Germany:** Tel. +49 40 23 5360, Fax. +49 402 353 6300

Hungary: see Austria

India: Tel. +91 22 493 8541, Fax. +91 22 493 8722

Indonesia: see Singapore

Ireland: Tel. +353 17 64 0000, Fax. +353 17 64 0200 Israel: Tel. +972 36 45 0444, Fax. +972 36 49 1007 Italy: Tel. +39 039 203 6838, Fax +39 039 203 6800 Japan: Tel. +81 33 740 5130, Fax. +81 3 3740 5057 Korea: Tel. +82 27 09 1412, Fax. +82 27 09 1415 Malaysia: Tel. +60 37 50 5214, Fax. +60 37 57 4880

Mexico: Tel. +9-5 800 234 7381

Middle East: see Italy

For all other countries apply to: Philips Semiconductors,

Marketing Communications,

Building BE, P.O. Box 218, 5600 MD EINDHOVEN,

The Netherlands, Fax. +31 40 272 4825

Netherlands: Tel. +31 40 278 2785, Fax. +31 40 278 8399 New Zealand: Tel. +64 98 49 4160, Fax. +64 98 49 7811 Norway: Tel. +47 22 74 8000, Fax. +47 22 74 8341 Philippines: Tel. +63 28 16 6380, Fax. +63 28 17 3474 Poland: Tel. +48 22 5710 000, Fax. +48 22 5710 001

Portugal: see Spain **Romania:** see Italy

Russia: Tel. +7 095 755 6918, Fax. +7 095 755 6919 **Singapore:** Tel. +65 350 2538, Fax. +65 251 6500

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South Africa: Tel. +27 11 471 5401, Fax. +27 11 471 5398 **South America:** Tel. +55 11 821 2333, Fax. +55 11 829 1849

Spain: Tel. +34 33 01 6312, Fax. +34 33 01 4107 **Sweden:** Tel. +46 86 32 2000, Fax. +46 86 32 2745 **Switzerland:** Tel. +41 14 88 2686, Fax. +41 14 81 7730 **Taiwan:** Tel. +886 22 134 2451, Fax. +886 22 134 2874 **Thailand:** Tel. +66 23 61 7910, Fax. +66 23 98 3447 **Turkey:** Tel. +90 216 522 1500, Fax. +90 216 522 1813 **Ukraine:** Tel. +380 44 264 2776, Fax. +380 44 268 0461

United Kingdom: Tel. +44 208 730 5000, Fax. +44 208 754 8421

United States: Tel. +1 800 234 7381 Uruguay: see South America Vietnam: see Singapore

Yugoslavia: Tel. +381 11 3341 299, Fax. +381 11 3342 553

Internet: http://www.semiconductors.philips.com

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Date of release: 10 August 2000 Document order number: 9397 750 07395



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