32K x 18 Bit BurstRAM[™] Synchronous Fast Static RAM With Burst Counter and Registered Outputs

The MCM67C518 is a 589,824 bit synchronous static random access memory designed to provide a burstable, high–performance, secondary cache for the i486™ and Pentium™ microprocessors. It is organized as 32,768 words of 18 bits, fabricated with Motorola's high–performance silicon–gate BiCMOS technology. The device integrates input registers, a 2–bit counter, high speed SRAM, and high drive registered output drivers onto a single monolithic circuit for reduced parts count implementation of cache data RAM applications. Synchronous design allows precise cycle control with the use of an external clock (K). BiCMOS circuitry reduces the overall power consumption of the integrated functions for greater reliability.

Addresses (A0 – A14), data inputs (D0 – D17), and all control signals except output enable (\overline{G}) are clock (K) controlled through positive–edge–triggered non-inverting registers.

This device contains output registers for pipeline operations. At the rising edge of K, the RAM provides the output data from the previous cycle.

Output enable (\overline{G}) is asynchronous for maximum system design flexibility.

Burst can be initiated with either address status processor (ADSP) or address status cache controller (ADSC) input pins. Subsequent burst addresses can be generated internally by the MCM67C518 (burst sequence imitates that of the i486) and controlled by the burst address advance (ADV) input pin. The following pages provide more detailed information on burst controls.

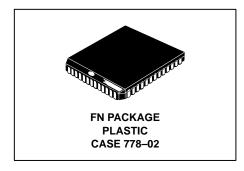
Write cycles are internally self—timed and are initiated by the rising edge of the clock (K) input. This feature eliminates complex off—chip write pulse generation and provides increased flexibility for incoming signals.

Dual write enables (\overline{LW} and \overline{UW}) are provided to allow individually writeable bytes. \overline{LW} controls DQ0 – DQ8 (the lower bits), while \overline{UW} controls DQ9 – DQ17 (the upper bits).

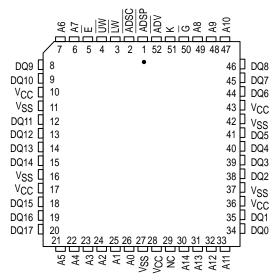
This device is ideally suited for systems that require wide data bus widths and cache memory. See Figure 2 for applications information.

- Single 5 V ± 5% Power Supply
- Fast Access Time/Fast Cycle Time = 6 ns/100 MHz, 7 ns/80 MHz, 9 ns/66 MHz
- Byte Writeable via Dual Write Enables
- Internal Input Registers (Address, Data, Control)
- · Output Registers for Pipelined Applications
- Internally Self-Timed Write Cycle
- ADSP, ADSC, and ADV Burst Control Pins
- Asynchronous Output Enable Controlled Three–State Outputs
- Common Data Inputs and Data Outputs
- 3.3 V I/O Compatible
- High Board Density 52–Lead PLCC Package

MCM67C518



PIN ASSIGNMENTS



PIN NAMES
A0 – A14 Address Inputs K. Clock ADV Burst Address Advance LW Lower Byte Write Enable UW Upper Byte Write Enable ADSC Controller Address Status ADSP Processor Address Status Chip Enable G Output Enable DQ0 – DQ17 Data Input/Output VCC +5 V Power Supply VSS Ground NC No Connection

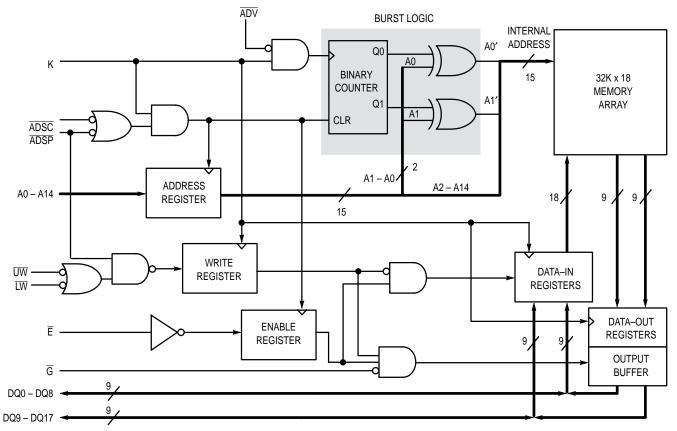
All power supply and ground pins must be connected for proper operation of the device.

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REV 3 5/95



BLOCK DIAGRAM (See Note)



NOTE: All registers are positive—edge triggered. The \overline{ADSC} or \overline{ADSP} signals control the duration of the burst and the start of the next burst. When \overline{ADSP} is sampled low, any ongoing burst is interrupted and a read (independent of \overline{W} and \overline{ADSC}) is performed using the new external address. Alternatively, an \overline{ADSP} —initiated two cycle WRITE can be performed by asserting \overline{ADSP} and a valid address on the first cycle, then negating both \overline{ADSP} and \overline{ADSC} and asserting \overline{LW} and/or \overline{UW} with valid data on the second cycle (see Single Write cycle in WRITE CYCLES timing diagram).

When \overline{ADSC} is sampled low (and \overline{ADSP} is sampled high), any ongoing burst is interrupted and a read or write (dependent on \overline{W}) is performed using the new external address. Chip enable (\overline{E}) is sampled only when a new base address is loaded. After the first cycle of the burst, \overline{ADV} controls subsequent burst cycles. When \overline{ADV} is sampled low, the internal address is advanced prior to the operation. When \overline{ADV} is sampled high, the internal address is not advanced, thus inserting a wait state into the burst sequence accesses. Upon completion of a burst, the address will wrap around to its initial state. See **BURST SEQUENCE TABLE**. Write refers to either or both byte write enables $(\overline{LW}, \overline{LW})$.

BURST SEQUENCE TABLE (See Note)

External Address	A14 – A2	A1	A0
1st Burst Address	A14 – A2	A1	A0
2nd Burst Address	A14 – A2	A1	A0
3rd Burst Address	A14 – A2	A1	A0

NOTE: The burst wraps around to its initial state upon completion.

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SYNCHRONOUS TRUTH TABLE (See Notes 1, 2, and 3)

E	ADSP	ADSC	ADV	UW or LW	К	Address Used	Operation
Н	L	Х	Х	Х	L–H	N/A	Deselected
Н	Х	L	Х	Х	L–H	N/A	Deselected
L	L	Х	Х	Х	L–H	External Address	Read Cycle, Begin Burst
L	Н	L	Х	L	L–H	External Address	Write Cycle, Begin Burst
L	Н	L	Х	Н	L–H	External Address	Read Cycle, Begin Burst
Х	Н	Н	L	L	L–H	Next Address	Write Cycle, Continue Burst
Х	Н	Н	L	Н	L–H	Next Address	Read Cycle, Continue Burst
Х	Н	Н	Н	L	L–H	Current Address	Write Cycle, Suspend Burst
Х	Н	Н	Н	Н	L–H	Current Address	Read Cycle, Suspend Burst

NOTES:

- 1. X means Don't Care.
- 2. All inputs except \overline{G} must meet setup and hold times for the low-to-high transition of clock (K).
- 3. Wait states are inserted by suspending burst.

ASYNCHRONOUS TRUTH TABLE (See Notes 1 and 2)

Operation	G	I/O Status
Read	L	Data Out
Read	Н	High–Z
Write	Х	High–Z — Data In
Deselected	Х	High–Z

NOTES:

- 1. X means Don't Care.
- 2. For a write operation following a read operation, \overline{G} must be high before the input data required setup time and held high through the input data hold time.

ABSOLUTE MAXIMUM RATINGS (Voltages Referenced to VSS = 0 V)

Rating	Symbol	Value	Unit
Power Supply Voltage	Vcc	- 0.5 to + 7.0	V
Voltage Relative to VSS for Any Pin Except VCC	V _{in} , V _{out}	- 0.5 to V _{CC} + 0.5	V
Output Current (per I/O)	l _{out}	± 30	mA
Power Dissipation	PD	1.6	W
Temperature Under Bias	T _{bias}	- 10 to + 85	°C
Operating Temperature	TA	0 to +70	°C
Storage Temperature	T _{stg}	- 55 to + 125	°C

NOTE: Permanent device damage may occur if ABSOLUTE MAXIMUM RATINGS are exceeded. Functional operation should be restricted to RECOMMENDED OPER-ATING CONDITIONS. Exposure to higher than recommended voltages for extended periods of time could affect device reliability.

This device contains circuitry to protect the inputs against damage due to high static voltages or electric fields; however, it is advised that normal precautions be taken to avoid application of any voltage higher than maximum rated voltages to this high–impedance circuit.

This BiCMOS memory circuit has been designed to meet the dc and ac specifications shown in the tables, after thermal equilibrium has been established.

This device contains circuitry that will ensure the output devices are in High-Z at power up.

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DC OPERATING CONDITIONS AND CHARACTERISTICS

(V_{CC} = $5.0 \text{ V} \pm 5\%$, T_A = $0 \text{ to} + 70^{\circ}\text{C}$, Unless Otherwise Noted)

RECOMMENDED OPERATING CONDITIONS (Voltages referenced to $V_{SS} = 0 V$)

Parameter	Symbol	Min	Max	Unit
Supply Voltage (Operating Voltage Range)	Vcc	4.75	5.25	V
Input High Voltage	VIH	2.2	V _{CC} + 0.3**	V
Input Low Voltage	V _{IL}	- 0.5*	0.8	V

DC CHARACTERISTICS

Parameter	Symbol	Min	Max	Unit
Input Leakage Current (All Inputs, V _{in} = 0 to V _{CC})	l _{lkg(l)}	_	± 1.0	μΑ
Output Leakage Current (G = V _{IH})	l _{lkg(O)}	_	± 1.0	μΑ
AC Supply Current (\overline{G} = V _{IH} , \overline{E} = V _{IL} , I _{Out} = 0 mA, All Inputs = V _{IL} or V _{IH} , V _{IL} = 0.0 V and V _{IH} \geq 3.0 V, Cycle Time \geq t _{KHKH} min)	I _{CCA6} I _{CCA7} I _{CCA9}	_	310 290 275	mA
AC Standby Current (\overline{E} = V _{IH} , I _{Out} = 0 mA, All Inputs = V _{IL} and V _{IH} , V _{IL} = 0.0 V and V _{IH} \geq 3.0 V, Cycle Time \geq t _{KHKH} min)	ISB1	_	75	mA
Output Low Voltage (I _{OL} = + 8.0 mA)	VOL	_	0.4	V
Output High Voltage (I _{OH} = – 4.0 mA)	Voн	2.4	3.3	V

NOTE: Good decoupling of the local power supply should always be used. DC characteristics are guaranteed for all possible i486 and Pentium bus cycles.

$\textbf{CAPACITANCE} \text{ (f = 1.0 MHz, dV = 3.0 V, T}_{A} = 25^{\circ}\text{C, Periodically Sampled Rather Than 100\% Tested)}$

Parameter	Symbol	Тур	Max	Unit
Input Capacitance (All Pins Except DQ0 – DQ17)	C _{in}	4	5	pF
Input/Output Capacitance (DQ0 - DQ17)	C _{I/O}	6	8	pF

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^{*} V_{IL} (min) = -0.5 V dc; V_{IL} (min) = -2.0 V ac (pulse width ≤ 20 ns) for $I \le 20.0$ mA. ** V_{IH} (max) = V_{CC} + 0.3 V dc; V_{IH} (max) = V_{CC} + 2 V ac (pulse width ≤ 20 ns) for $I \le 20.0$ mA.

AC OPERATING CONDITIONS AND CHARACTERISTICS

 $(V_{CC} = 5.0 \text{ V} \pm 5\% \text{ T}_{A} = 0 \text{ to} + 70^{\circ}\text{C}, \text{ Unless Otherwise Noted})$

Input Timing Measurement Reference Level 1.5 V	Output Timing Reference Level 1.5 V
Input Pulse Levels 0 to 3.0 V	Output Load See Figure 1A Unless Otherwise Noted
Input Rise/Fall Time	

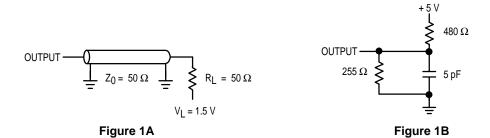
READ/WRITE CYCLE TIMING (See Notes 1, 2, 3, and 4)

			мсм67	7C518–6	518-6 MCM67C518-7		МСМ67	C518-9		
Par	ameter	Symbol	Min	Max	Min	Max	Min	Max	Unit	Notes
Cycle Time		^t KHKH	10	_	12.5	_	15	_	ns	
Clock Access Time		^t KHQV	_	6	_	7	_	9	ns	5
Output Enable to Out	tput Valid	tGLQV	_	5	_	5	_	6	ns	
Clock High to Output	Active	tKHQX1	2	_	2	_	2	_	ns	
Clock High to Output	Change	^t KHQX2	2	_	2	_	2	_	ns	
Output Enable to Out	tput Active	^t GLQX	0	_	0	_	0	_	ns	
Output Disable to Q	High–Z	^t GHQZ	_	6	_	6	_	6	ns	6
Clock High to Q High	ı–Z	^t KHQZ	2	6	2	6	2	6	ns	
Clock High Pulse Wi	dth	^t KHKL	4	_	5	_	5	_	ns	
Clock Low Pulse Wic	lth	^t KLKH	4	_	5	_	5	_	ns	
Setup Times:	Address Address Status Data In Write Address Advance Chip Enable	tavkh tadsvkh tdvkh twvkh tadvvkh tevkh	2.5	_	2.5	_	2.5	_	ns	7
Hold Times:	Address Address Status Data In Write Address Advance Chip Enable	tKHAX tKHADSX tKHDX tKHWX tKHADVX tKHADVX	0.5	_	0.5	_	0.5	_	ns	7

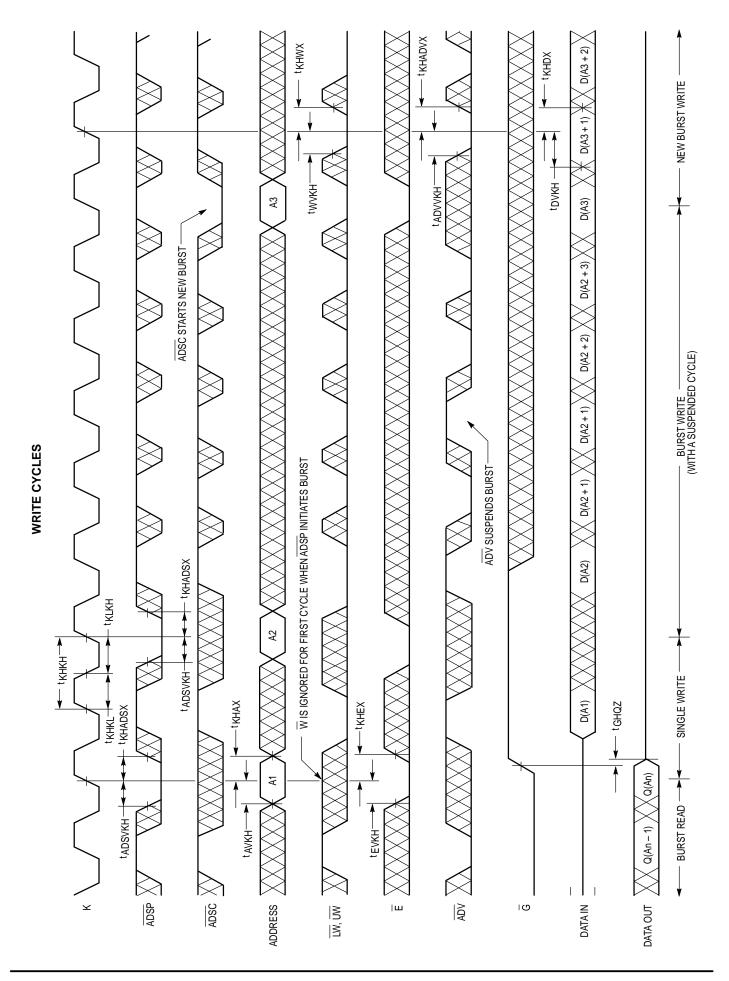
NOTES:

- 1. In setup and hold times, W (write) refers to either one or both byte write enables \overline{LW} and \overline{UW} .
- 2. A read cycle is defined by $\overline{\text{LW}}$ and $\overline{\text{LW}}$ high or $\overline{\text{ADSP}}$ low for the setup and hold times. A write cycle is defined by $\overline{\text{LW}}$ or $\overline{\text{LW}}$ low and $\overline{\text{ADSP}}$ high for the setup and hold times.
- 3. All read and write cycle timings are referenced from K or \overline{G} .
- 4. \overline{G} is a don't care when \overline{UW} or \overline{LW} is sampled low.
- 5. Maximum access times are guaranteed for all possible i486 and Pentium external bus cycles.
- 6. Transition is measured ± 500 mV from steady–state voltage with load of Figure 1B. This parameter is sampled rather than 100% tested. At any given voltage and temperature, tkHOZ max is less than tkHOZ1 min for a given device and from device to device.
- 7. This is a synchronous device. All addresses must meet the specified setup and hold times for *ALL* rising edges of K whenever ADSP or ADSC is low, and the chip is selected. All other synchronous inputs must meet the specified setup and hold times for *ALL* rising edges of K when the chip is enabled. Chip enable must be valid at each rising edge of clock for the device (when ADSP or ADSC is low) to remain enabled.

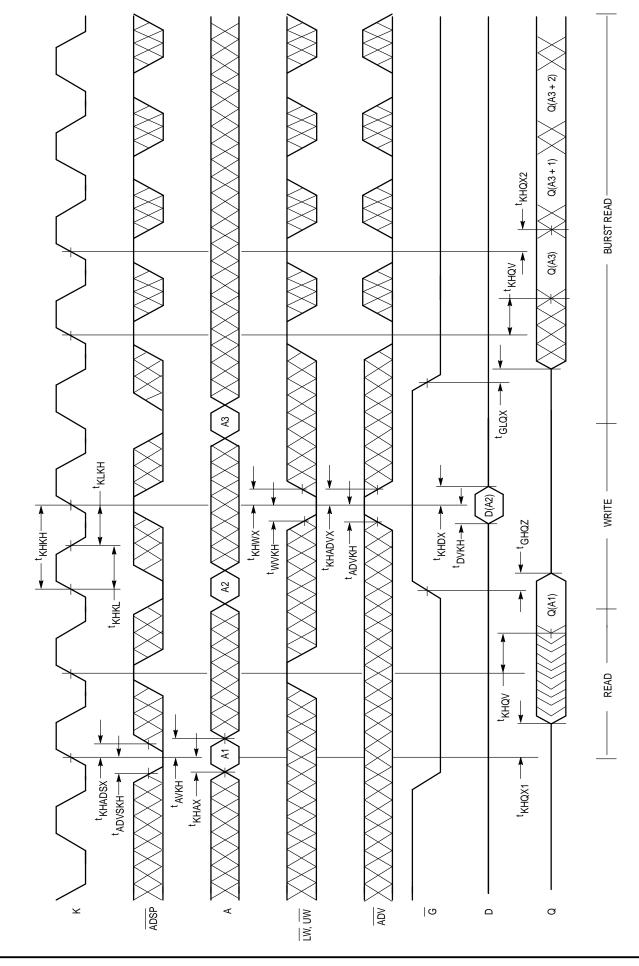
AC TEST LOADS



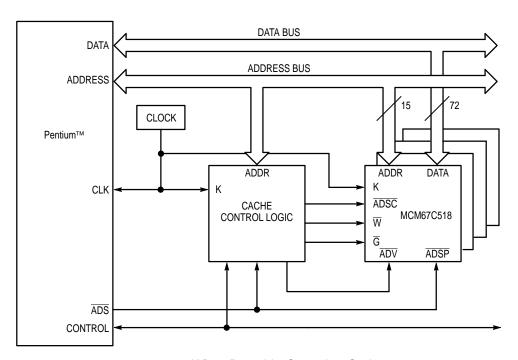
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COMBINATION READ/WRITE CYCLES ($\overline{\mathsf{E}}$ low, $\overline{\mathsf{ADSC}}$ high)



APPLICATION EXAMPLE



256K Byte Burstable, Secondary Cache Using Four MCM67C518FN7s With a 75 MHz (bus speed) Pentium

Figure 2

MOTOROLA FAST SRAM MCM67C518

ORDERING INFORMATION (Order by Full Part Number)

	<u>MCM</u>	<u>67C518</u>	<u> </u>	<u>X</u>	
Motorola Memory Prefix					Speed (6 = 6 ns, 7 = 7 ns, 9 = 9 ns)
Part Number					Package (FN = PLCC)

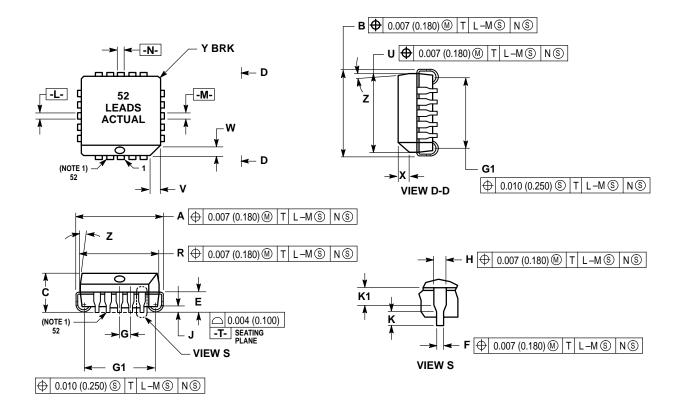
Full Part Numbers — MCM67C518FN6 MCM67C518FN7 MCM67C518FN9

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PACKAGE DIMENSIONS

FN PACKAGE 52-LEAD PLCC CASE 778-02



NOTES

- DUE TO SPACE LIMITATION, CASE 778-02 SHALL BE REPRESENTED BY A GENERAL (SMALLER) CASE OUTLINE DRAWING RATHER THAN SHOWING ALL 52
- DATUMS -L-, -M-, AND -N- DETERMINED WHERE TOP OF LEAD SHOULDER EXITS PLASTIC BODY AT MOLD PARTING LINE.
- DIM G1, TRUE POSITION TO BE MEASURED AT DATUM -T-, SEATING PLANE.
- SEATING PLANE.
 DIM R AND U DO NOT INCLUDE MOLD FLASH.
 ALLOWABLE MOLD FLASH IS 0.010 (0.250) PER SIDE.
 DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982
- CONTROLLING DIMENSION: INCH.
- CON ROLLING DIMENSION: INCH.
 THE PACKAGE TOP MAY BE SMALLER THAN THE
 PACKAGE BOTTOM BY UP TO 0.012 (0.300). DIMENSIONS
 R AND U ARE DETERMINED AT THE OUTERMOST
 EXTREMES OF THE PLASTIC BODY EXCLUSIVE OF MOLD
 FLASH, TIE BAR BURRS, GATE BURRS AND INTERLEAD
 FLASH, BUT INCLUDING ANY MISMATCH BETWEEN THE
- TOP AND BOTTOM OF THE PLASTIC BODY.
 DIMENSION H DOES NOT INCLUDE DAMBAR DIMENSION I DES NOT INCLUDE DAMBAR
 PROTRUSION OR INTRUSION. THE DAMBAR
 PROTRUSION(S) SHALL NOT CAUSE THE H DIMENSION
 TO BE GREATER THAN 0.037 (0.940). THE DAMBAR
 INTRUSION(S) SHALL NOT CAUSE THE H DIMENSION TO BE SMALLER THAN 0.025 (0.635).

	INC	HES	MILLIN	METERS		
DIM	MIN	MAX	MIN	MAX		
Α	0.785	0.795	19.94	20.19		
В	0.785	0.795	19.94	20.19		
С	0.165	0.180	4.20	4.57		
E	0.090	0.110	2.29	2.79		
F	0.013	0.019	0.33	0.48		
G	0.05	0 BSC	1.27	BSC		
Н	0.026	0.032	0.66	0.81		
J	0.020	_	0.51	_		
K	0.025	_	0.64	_		
R	0.750	0.756	19.05	19.20		
U	0.750	0.756	19.05	19.20		
٧	0.042	0.048	1.07	1.21		
W	0.042	0.048	1.07	1.21		
Х	0.042	0.056	1.07	1.42		
Y	_	0.020	_	0.50		
Z	2°	10°	2°	10°		
G1	0.710	0.730	18.04	18.54		
K1	0.040	_	1.02	_		

MOTOROLA FAST SRAM MCM67C518

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