# Product Preview

# **Quad EIA-422-A Line Driver** CMOS

The MC26C31 is a quad differential line driver designed for digital data transmission over balanced lines. The MC26C31 meets all the requirements of standard EIA–422–A while retaining the low–power characteristics of CMOS.

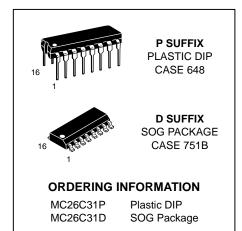
The MC26C31 accepts TTL or CMOS input levels and translates these to EIA–422–A output level. This part uses special output circuitry that enables the individual drivers to power down without loading down the bus. The MC26C31 also includes special circuitry which will set the outputs to a high impedance mode during power up or down, preventing spurious glitches. This device has enable and disable circuitry common for all four drivers.

The MC26C31 is pin compatible with the AM26LS31.

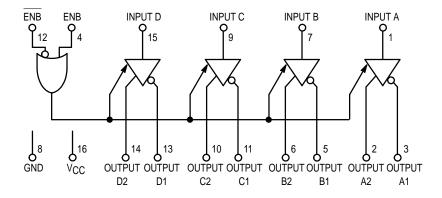
All pins are protected against damage due to electrostatic discharges.

- · Maximum Supply Current: 3 mA
- 2000 V ESD Protection on the Inputs and Outputs
- TTL/CMOS Input Compatible
- Typical Propagation Delay: 6 ns
- · Typical Output Skew: 1 ns
- Meets  $V_O = 6.0 \text{ V}$  (and  $V_O = 0.25 \text{ V}$ ),  $V_{CC} = 0 \text{ V}$ ,  $I_O < 100 \,\mu\text{A}$  Requirement
- · Meets the Requirements of Standard EIA-422-A
- Operation from Single 5 V Supply
- High Impedance Mode for Outputs Connected to System Buses

## MC26C31



#### **BLOCK DIAGRAM**



This document contains information on a product under development. Motorola reserves the right to change or discontinue this product without notice.

REV 3 1993



#### **TRUTH TABLE**

Control Inputs E/E	Input	Non-Inverting Output	Inverting Output
L/H	Х	Z	Z
All other combinations of	Н	Н	L
enable inputs	L	L	Н

X = Don't Care H = High Logic State Z = High Impedance L = Low Logic State

#### **MAXIMUM RATINGS**

Rating	Symbol	Value	Unit
Power Supply Voltage	VCC	7	V
DC Input Voltage	V <sub>in</sub>	- 1.5 to V <sub>CC</sub> + 1.5	V
DC Output Voltage*	V <sub>out</sub>	-0.5 to V <sub>CC</sub> + 0.5	V
DC Output Current, per Pin	l <sub>out</sub>	150	mA
DC V <sub>CC</sub> or GND Current, per Pin	IDD	150	mA
Storage Temperature	T <sub>stg</sub>	- 65 to + 150	°C
Power Dissipation	PD	500	mW
ESD (Human Body Model)		2000	V

This device contains circuitry to protect the inputs against damage due to high static voltages or electric fields; however, it is advised that normal precautions be taken to avoid applications of any voltage higher than the maximum rated voltages to this high impedance circuit.

For proper operation it is recommended that  $V_{\mbox{\scriptsize in}}$  and  $V_{\mbox{\scriptsize out}}$  be constrained to the range  $V_{\mbox{\scriptsize SS}} \leq$  $(V_{in} \text{ or } V_{out}) \leq V_{DD}$ . Reliability of operation is enhanced if unused inputs are tied to and appropriate logic voltage level (e.g., either VSS or V<sub>DD</sub>).

#### **OPERATING CONDITIONS**

Rating		Min	Max	Unit
Power Supply Voltage	VCC	4.5	5.5	V
DC Input Voltage	V <sub>in</sub>	0	VCC	V
Operating Temperature Range	TA	<b>- 40</b>	+ 85	°C
Input Rise and Fall Time	t <sub>r</sub> , t <sub>f</sub>	_	500	ns

## **DC CHARACTERISTICS** ( $V_{CC} = 4.5 \text{ to } 5.5 \text{ V}$ , $T_A = -40 \text{ to } +85^{\circ}\text{C}$ , unless otherwise stated)

Parameter	Symbol	Min	Тур	Max	Unit
Input Voltage (Low Logic State)	V <sub>IL</sub>	_	_	0.8	V
Input Voltage (High Logic State)	VIH	2.0	_	_	V
Output Voltage (Low Logic State) I <sub>Sink</sub> = 20 mA	VOL	_	0.3	0.5	V
Output Voltage (High Logic State) I <sub>source</sub> = 20 mA	Voн	2.5	2.8	_	V
Output Differential Voltage $R_L = 100 \Omega$ (Note 1)	VOD	2.0	_	_	V
Output Differential Voltage Difference R <sub>L</sub> = 100 $\Omega$ (Note 1)	D(V <sub>OD</sub> )	_	_	± 0.4	V
Output Offset Voltage R <sub>L</sub> = 100 $\Omega$ (Note 1)	Vos	_	_	3.0	V
Output Offset Voltage Difference $R_L = 100 \Omega$ (Note 1)	D(V <sub>OS</sub> )	_	_	± 0.4	V
Input Current VIH = VCC, GND, VIH or VIL	l <sub>in</sub>	_	_	± 1.0	μА
Quiescent Supply Current I <sub>out</sub> = 0 μA	Icc	_	_	3.0	mA
Output Short Circuit Current (Note 2)	los	- 30	- 100	- 150	mA
Output Leakage Current (High–Z State) V <sub>Out</sub> = V <sub>CC</sub> or GND	I <sub>O(Z)</sub>	_	_	± 1.0	μА
Input Leakage Current (Power Off) $ V_{out} = -0 $	= 6 V I <sub>oxh</sub> .25 V I <sub>oxl</sub>	_	_	100 -100	μΑ

#### NOTES:

- 1. See EIA specifications EIA-422-A for exact test conditions.
- 2. Only one output may be shorted at a time.

<sup>\*</sup> Power-on conditions.

## **AC CHARACTERISTICS** ( $V_{CC} = 4.5 \text{ to } 5.5 \text{ V}$ , $T_A = -40 \text{ to } + 85^{\circ}\text{C}$ , unless otherwise stated)

Parameter	Symbol	Min	Тур	Max	Unit
Propagation Delay Input to Output (S1 Open)	tPLH tPHL	_	6	12	ns
Output Skew (S1 Open)*	Skew	_	1.0	4	ns
Differential Output Rise Time Fall Time (S1 Open)	<sup>t</sup> (TLH) <sup>t</sup> (THL)	_	4	8	ns
Output Enable Time (S1 Closed)	<sup>t</sup> PZH <sup>t</sup> PZL		16 15	_ _	ns
Output Disable Time (S1 Closed)	<sup>t</sup> PHZ <sup>t</sup> PLZ	_	6 9		ns

<sup>\*</sup> Skew: difference in propagation delays between complementary outputs.

## AC TEST CIRCUIT AND SWITCHING TIME WAVEFORMS

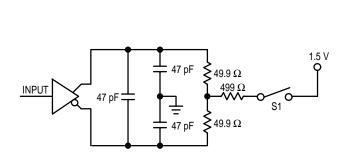


Figure 1. AC Test Circuit

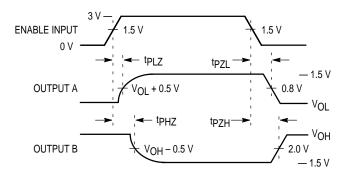


Figure 3. Enable and Disable Times

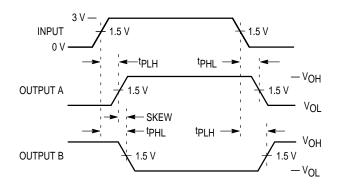


Figure 2. Propagation Delays and Skew Waveforms

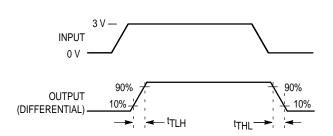


Figure 4. Differential Rise and Fall Times

#### **TYPICAL APPLICATIONS**

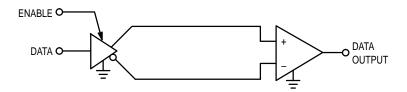
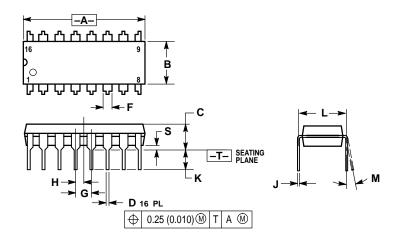


Figure 5. Two-Wire Balanced Systems (EIA-422-A)

MOTOROLA MC26C31

#### PACKAGE DIMENSIONS

#### **P SUFFIX** PLASTIC DIP **CASE 648-08**

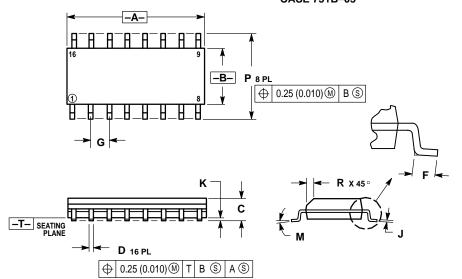


#### NOTES:

- DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982
- CONTROLLING DIMENSION: INCH.
- DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL
- DIMENSION B DOES NOT INCLUDE MOLD FLASH.
  ROUNDED CORNERS OPTIONAL.

	INC	HES	MILLIN	IETERS
DIM	MIN	MAX	MIN	MAX
Α	0.740	0.770	18.80	19.55
В	0.250	0.270	6.35	6.85
С	0.145	0.175	3.69	4.44
D	0.015	0.021	0.39	0.53
F	0.040	0.70	1.02	1.77
G	0.100 BSC		2.54 BSC	
Н	0.050 BSC		1.27 BSC	
٦	0.008	0.015	0.21	0.38
K	0.110	0.130	2.80	3.30
Ĺ	0.295	0.305	7.50	7.74
М	0°	10 °	0 °	10 °
S	0.020	0.040	0.51	1.01

#### **D SUFFIX** SOG PACKAGE CASE 751B-05



#### NOTES

- 1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982
- CONTROLLING DIMENSION: MILLIMETER.
- DIMENSIONS A AND B DO NOT INCLUDE MOLD PROTRUSION
- MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER SIDE.
- DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127 (0.005) TOTAL IN EXCESS OF THE D DIMENSION AT MAXIMUM MATERIAL CONDITION.

	MILLIMETERS		INCHES	
DIM	MIN	MAX	MIN	MAX
Α	9.80	10.00	0.386	0.393
В	3.80	4.00	0.150	0.157
С	1.35	1.75	0.054	0.068
D	0.35	0.49	0.014	0.019
F	0.40	1.25	0.016	0.049
G	1.27	BSC	0.050 BSC	
J	0.19	0.25	0.008	0.009
K	0.10	0.25	0.004	0.009
M	0 °	7°	0°	7°
Р	5.80	6.20	0.229	0.244
R	0.25	0.50	0.010	0.019

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