# 32K x 18 Bit BurstRAM<sup>™</sup> Synchronous Fast Static RAM With Burst Counter and Self-Timed Write

The MCM67M518 is a 589,824 bit synchronous static random access memory designed to provide a burstable, high–performance, secondary cache for the MC68040 and PowerPC™ microprocessors. It is organized as 32,768 words of 18 bits, fabricated using Motorola's high–performance silicon–gate BiCMOS technology. The device integrates input registers, a 2–bit counter, high speed SRAM, and high drive capability outputs onto a single monolithic circuit for reduced parts count implementation of cache data RAM applications. Synchronous design allows precise cycle control with the use of an external clock (K). BiCMOS circuitry reduces the overall power consumption of the integrated functions for greater reliability.

Addresses (A0 - A14), data inputs (DQ0 - DQ17), and all control signals, except output enable ( $\overline{G}$ ), are clock (K) controlled through positive–edge–triggered noninverting registers.

Bursts can be initiated with either transfer start processor (TSP) or transfer start cache controller (TSC) input pins. Subsequent burst addresses are generated internally by the MCM67M518 (burst sequence imitates that of the MC68040 and PowerPC) and controlled by the burst address advance (BAA) input pin. The following pages provide more detailed information on burst controls.

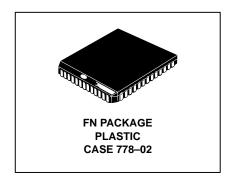
Write cycles are internally self–timed and are initiated by the rising edge of the clock (K) input. This feature eliminates complex off–chip write pulse generation and provides increased flexibility for incoming signals.

Dual write enables ( $\overline{LW}$  and  $\overline{UW}$ ) are provided to allow individually writeable bytes.  $\overline{LW}$  controls DQ0 – DQ8 (the lower bits), while  $\overline{UW}$  controls DQ9 – DQ17 (the upper bits).

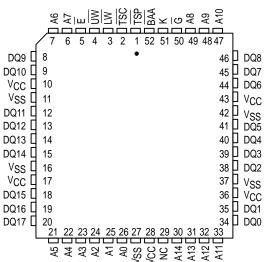
This device is ideally suited for systems that require wide data bus widths and cache memory.

- Single 5 V ± 5% Power Supply
- Fast Access Times: 9/11/14 ns Max and Cycle Times: 12.5/15/20 ns Min
- Byte Writeable via Dual Write Strobes
- Internal Input Registers (Address, Data, Control)
- Internally Self–Timed Write Cycle
- TSP, TSC, and BAA Burst Control Pins
- Asynchronous Output Enable Controlled Three-State Outputs
- Common Data Inputs and Data Outputs
- · High Board Density 52-PLCC Package
- 3.3 V I/O Compatible

## MCM67M518



#### **PIN ASSIGNMENT**



PIN NAMES
A0 – A14 Address Inputs K. Clock BAA Burst Address Advance  \overline{LW} Lower Byte Write Enable \overline{UW} Upper Byte Write Enable \overline{TSP, TSC} Transfer Start \overline{E} Chip Enable \overline{G} Output Enable  DQ0 – DQ17 Data Input/Output VCC +5 V Power Supply VSS Ground NC No Connection

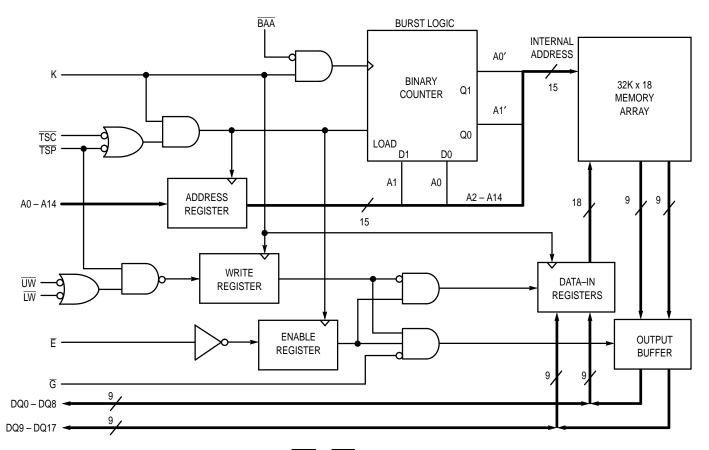
All power supply and ground pins must be connected for proper operation of the device.

BurstRAM is a trademark of Motorola, Inc. PowerPC is a trademark of IBM Corp.

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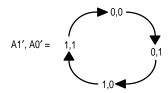
#### **BLOCK DIAGRAM** (See Note)



NOTE: All registers are positive—edge triggered. The TSC or TSP signals control the duration of the burst and the start of the next burst. When TSP is sampled low, any ongoing burst is interrupted and a read (independent of W and TSC) is performed using the new external address. Alternatively, a TSP—initiated two cycle WRITE can be performed by asserting TSP and a valid address on the first cycle, then negating both TSP and TSC and asserting LW and/or UW with valid data on the second cycle (see Single Write Cycle in WRITE CYCLES timing diagram).

When  $\overline{\mathsf{TSC}}$  is sampled low (and  $\overline{\mathsf{TSP}}$  is sampled high), any ongoing burst is interrupted and a read or write (dependent on  $\overline{\mathsf{W}}$ ) is performed using the new external address. Chip enable ( $\overline{\mathsf{E}}$ ) is sampled only when a new base address is loaded. After the first cycle of the burst,  $\overline{\mathsf{BAA}}$  controls subsequent burst cycles. When  $\overline{\mathsf{BAA}}$  is sampled low, the internal address is advanced prior to the operation. When  $\overline{\mathsf{BAA}}$  is sampled high, the internal address is not advanced, thus inserting a wait state into the burst sequence accesses. Upon completion of a burst, the address will wrap around to its initial state. See **BURST SEQUENCE TABLE**. Write refers to either or both byte write enables ( $\overline{\mathsf{LW}}$ ,  $\overline{\mathsf{UW}}$ ).

#### **BURST SEQUENCE GRAPH (See Note)**



NOTE: The external two values for A1 and A0 provide the starting point for the burst sequence graph. The burst logic advances A1 and A0 as shown above.

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#### SYNCHRONOUS TRUTH TABLE (See Notes 1, 2, and 3)

E	TSP	TSC	BAA	LW or UW	К	Address	Operation
Н	L	Х	Х	Х	L–H	N/A	Deselected
Н	Х	L	Х	Х	L–H	N/A	Deselected
L	L	Х	Х	Х	L–H	External Address	Read Cycle, Begin Burst
L	Н	L	Х	L	L–H	External Address	Write Cycle, Begin Burst
L	Н	L	Х	Н	L–H	External Address	Read Cycle, Begin Burst
Х	Н	Н	L	L	L–H	Next Address	Write Cycle, Continue Burst
Х	Н	Н	L	Н	L–H	Next Address	Read Cycle, Continue Burst
Х	Н	Н	Н	L	L–H	Current Address	Write Cycle, Suspend Burst
Х	Н	Н	Н	Н	L–H	Current Address	Read Cycle, Suspend Burst

#### NOTES:

- 1. X means Don't Care.
- 2. All inputs except  $\overline{\mathbf{G}}$  must meet setup and hold times for the low–to–high transition of clock (K).
- 3. Wait states are inserted by suspending burst.

#### ASYNCHRONOUS TRUTH TABLE (See Notes 1 and 2)

Operation	G	I/O Status	
Read	L	Data Out	
Read	H High–Z		
Write	Х	High–Z — Data In	
Deselected	Х	High–Z	

#### NOTES:

- 1. X means Don't Care.
- 2. For a write operation following a read operation,  $\overline{G}$  must be high before the input data required setup time and held high through the input data hold time.

#### ABSOLUTE MAXIMUM RATINGS (Voltages Referenced to V<sub>SS</sub> = 0 V)

Rating	Symbol	Value	Unit
Power Supply Voltage	Vcc	- 0.5 to + 7.0	V
Voltage Relative to VSS for Any Pin Except VCC	V <sub>in</sub> , V <sub>out</sub>	- 0.5 to V <sub>CC</sub> + 0.5	V
Output Current (per I/O)	l <sub>out</sub>	± 30	mA
Power Dissipation	PD	1.6	W
Temperature Under Bias	T <sub>bias</sub>	- 10 to + 85	°C
Operating Temperature	TA	0 to +70	°C
Storage Temperature	T <sub>stg</sub>	- 55 to + 125	°C

NOTE: Permanent device damage may occur if ABSOLUTE MAXIMUM RATINGS are exceeded. Functional operation should be restricted to RECOMMENDED OPER-ATING CONDITIONS. Exposure to higher than recommended voltages for extended periods of time could affect device reliability.

This device contains circuitry to protect the inputs against damage due to high static voltages or electric fields; however, it is advised that normal precautions be taken to avoid application of any voltage higher than maximum rated voltages to this high-impedance circuit.

This BiCMOS memory circuit has been designed to meet the dc and ac specifications shown in the tables, after thermal equilibrium has been established.

This device contains circuitry that will ensure the output devices are in High–Z at power up.

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#### DC OPERATING CONDITIONS AND CHARACTERISTICS

(V<sub>CC</sub> =  $5.0 \text{ V} \pm 5\%$ , T<sub>A</sub> =  $0 \text{ to} + 70^{\circ}\text{C}$ , Unless Otherwise Noted)

#### **RECOMMENDED OPERATING CONDITIONS** (Voltages referenced to $V_{SS} = 0 V$ )

Parameter	Symbol	Min	Max	Unit
Supply Voltage (Operating Voltage Range)	Vcc	4.75	5.25	V
Input High Voltage	VIH	2.2	V <sub>CC</sub> + 0.3**	V
Input Low Voltage	V <sub>IL</sub>	- 0.5*	0.8	V

#### DC CHARACTERISTICS AND SUPPLY CURRENTS

Parameter	Symbol	Min	Max	Unit
Input Leakage Current (All Inputs, V <sub>in</sub> = 0 to V <sub>CC</sub> )	l <sub>lkg(l)</sub>	_	± 1.0	μΑ
Output Leakage Current (G = V <sub>IH</sub> )	l <sub>lkg(O)</sub>	1	± 1.0	μΑ
AC Supply Current ( $\overline{G}$ = V <sub>IH</sub> , $\overline{E}$ = V <sub>IL</sub> , I <sub>Out</sub> = 0 mA, All Inputs = V <sub>IL</sub> or V <sub>IH</sub> , V <sub>IL</sub> = 0.0 V and V <sub>IH</sub> $\geq$ 3.0 V, Cycle Time $\geq$ t <sub>KHKH</sub> min)	ICCA9 ICCA11 ICCA14	I	290 275 250	mA
AC Standby Current ( $\overline{E}$ = V <sub>IH</sub> , I <sub>Out</sub> = 0 mA, All Inputs = V <sub>IL</sub> and V <sub>IH</sub> , V <sub>IL</sub> = 0.0 V and V <sub>IH</sub> $\geq$ 3.0 V, Cycle Time $\geq$ t <sub>KHKH</sub> min)	I <sub>SB1</sub>	_	75	mA
Output Low Voltage (I <sub>OL</sub> = + 8.0 mA)	VOL	_	0.4	V
Output High Voltage (I <sub>OH</sub> = – 4.0 mA)	VOH	2.4	3.3	V

NOTE: Good decoupling of the local power supply should always be used. DC characteristics are guaranteed for all possible MC68040 and PowerPC bus cycles.

#### **CAPACITANCE** (f = 1.0 MHz, dV = 3.0 V, $T_A = 25$ °C, Periodically Sampled Rather Than 100% Tested)

Parameter	Symbol	Тур	Max	Unit
Input Capacitance (All Pins Except DQ0 – DQ17)	C <sub>in</sub>	4	5	pF
Input/Output Capacitance (DQ0 – DQ17)	C <sub>I/O</sub>	6	8	pF

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<sup>\*</sup> $V_{IL}$  (min) = -0.5 V dc;  $V_{IL}$  (min) = -2.0 V ac (pulse width  $\leq 20.0$  ns) for  $I \leq 20.0$  mA. \*\* $V_{IH}$  (max) =  $V_{CC}$  + 2.0 V ac (pulse width  $\leq 20.0$  ns) for  $I \leq 20.0$  mA.

#### AC OPERATING CONDITIONS AND CHARACTERISTICS

 $(V_{CC} = 5.0 \text{ V} \pm 5\% \text{ T}_{A} = 0 \text{ to} + 70^{\circ}\text{C}, \text{ Unless Otherwise Noted})$ 

Input Timing Measurement Reference Level 1.5 V	Output Timing Reference Level 1.5 V
Input Pulse Levels 0 to 3.0 V	Output Load See Figure 1A Unless Otherwise Noted
Input Rise/Fall Time	

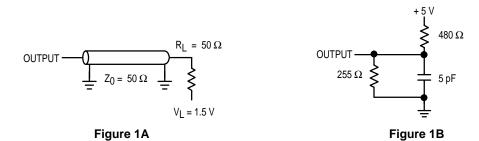
#### READ/WRITE CYCLE TIMING (See Notes 1, 2, 3, and 4)

			МСМ67	M518–9	MCM67I	VI518–11	MCM67I	VI518–14		
Parameter		Symbol	Min	Max	Min	Max	Min	Max	Unit	Notes
Cycle Time		<sup>t</sup> KHKH	12.5	_	15	_	20	_	ns	
Clock Access Time		<sup>t</sup> KHQV	_	9	_	11	_	14	ns	5
Output Enable to O	utput Valid	tGLQV	_	5	_	5	_	6	ns	
Clock High to Outpu	ut Active	<sup>t</sup> KHQX1	6	_	6	_	6	_	ns	
Clock High to Outpu	ut Change	tKHQX2	3	_	3	_	3	_	ns	
Output Enable to Output Active		<sup>t</sup> GLQX	0	_	0	_	0	_	ns	
Output Disable to Q High-Z		<sup>t</sup> GHQZ	_	6	_	7	_	7	ns	6
Clock High to Q High–Z		<sup>t</sup> KHQZ	3	6	3	7	3	7	ns	6
Clock High Pulse Width		<sup>t</sup> KHKL	5	_	5	_	6	_	ns	
Clock Low Pulse W	'idth	<sup>t</sup> KLKH	5	_	5	_	6	_	ns	
Setup Times:	Address Address Status Data In Write Address Advance Chip Select	tavkh ttsvkh tdvkh twvkh tbavkh tevkh	2.5	_	2.5	_	2.5	_	ns	7
Hold Times:	Address Address Status Data In Write Address Advance Chip Select	tKHAX tKHTSX tKHDX tKHWX tKHWX tKHBAX tKHEX	0.5	_	0.5	_	0.5	_	ns	7

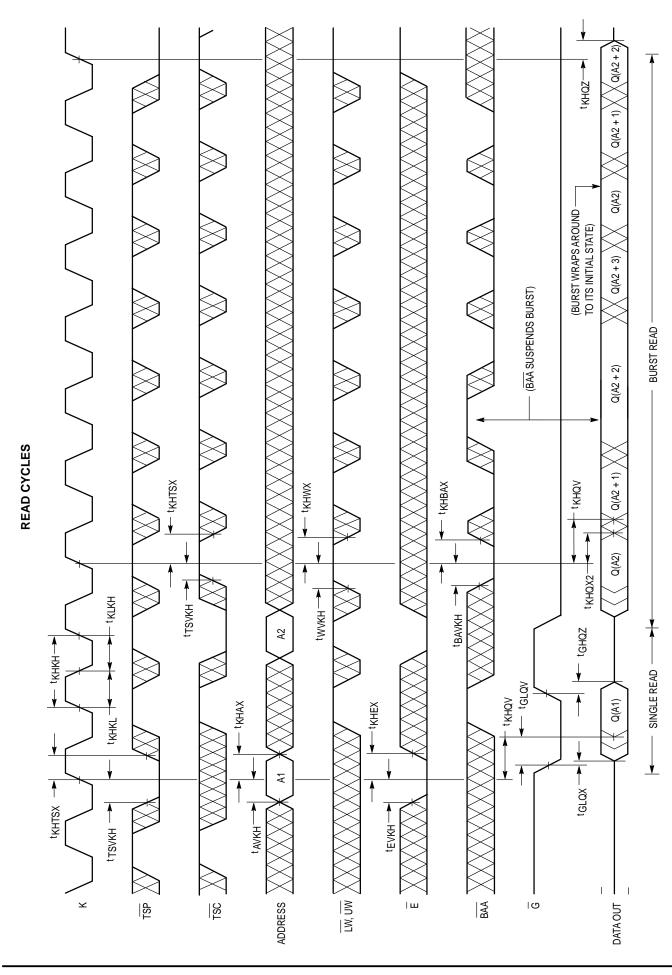
#### NOTES:

- 1. In setup and hold times, W (write) refers to either one or both byte write enables  $\overline{LW}$  and  $\overline{UW}$ .
- 2. A read cycle is defined by  $\overline{\text{LW}}$  and  $\overline{\text{LW}}$  high or  $\overline{\text{TSP}}$  low for the setup and hold times. A write cycle is defined by  $\overline{\text{LW}}$  or  $\overline{\text{UW}}$  low and  $\overline{\text{TSP}}$  high for the setup and hold times.
- 3. All read and write cycle timings are referenced from K or  $\overline{G}$ .
- 4.  $\overline{G}$  is a don't care when  $\overline{UW}$  or  $\overline{LW}$  is sampled low.
- 5. Maximum access times are guaranteed for all possible MC68040 and PowerPC external bus cycles.
- 6. Transition is measured  $\pm$  500 mV from steady–state voltage with load of Figure 1B. This parameter is sampled and not 100% tested. At any given voltage and temperature, tkHQZ max is less than tkHQX1 min for a given device and from device to device.
- 7. This is a synchronous device. All addresses must meet the specified setup and hold times for *ALL* rising edges of clock (K) whenever TSP or TSC are low and the chip is selected. All other synchronous inputs must meet the specified setup and hold times for *ALL* rising edges of K when the chip is selected. Chip enable must be valid at each rising edge of clock for the device (when TSP or TSC is low) to remain enabled.

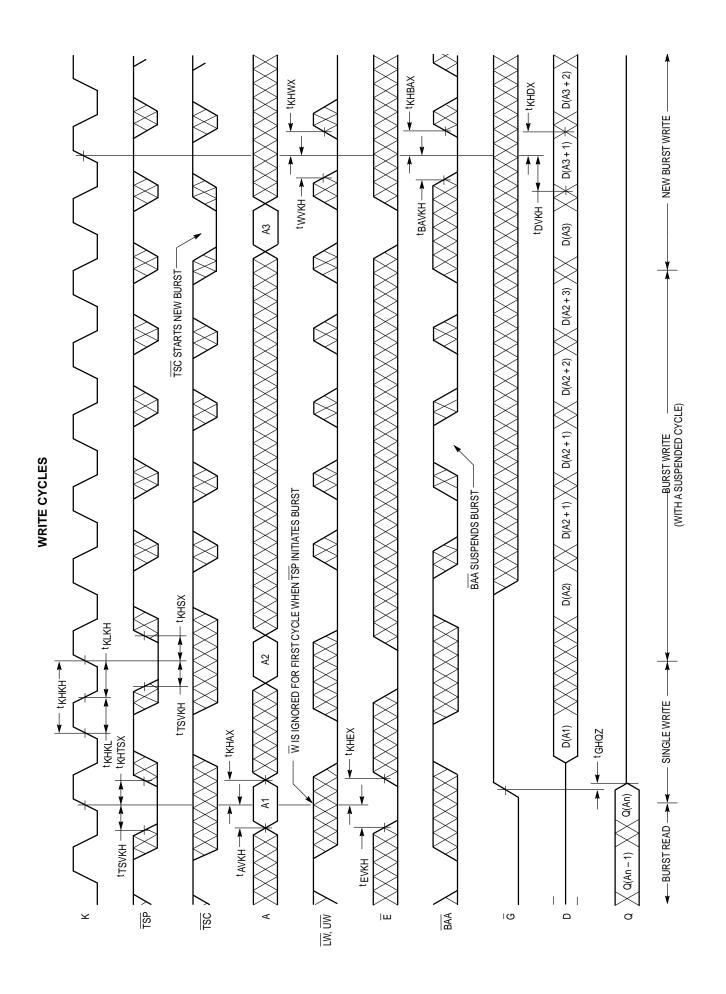
#### **AC TEST LOADS**



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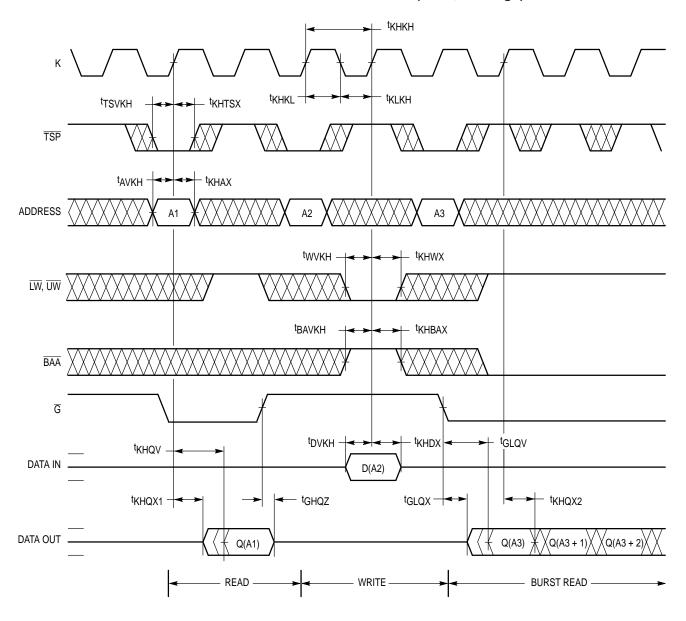


NOTE: Q(A2) represents the first output data from the base address A2; Q(A2 + 1) represents the next output data in the burst sequence with A2 as the base address.

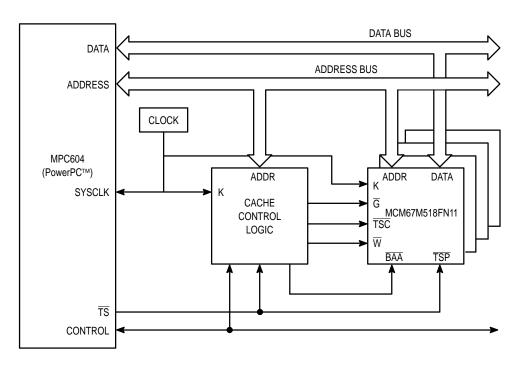


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### COMBINATION READ/WRITE CYCLE (E low, TSC high)



#### **APPLICATION EXAMPLE**



256K Byte Burstable, Secondary Cache
Using Four MCM67M518FN11s with a 66 MHz (bus speed) MPC604 PowerPC™

MOTOROLA FAST SRAM MCM67M518

# ORDERING INFORMATION (Order by Full Part Number)

	<u>MCM</u>	<u>67M518</u>	<u>XX</u>	<u> </u>	
Motorola Memory Prefix -					- Speed (9 = 9 ns, 11 = 11 ns, 14 = 14 ns)
Part Number ————					- Package (FN = PLCC)

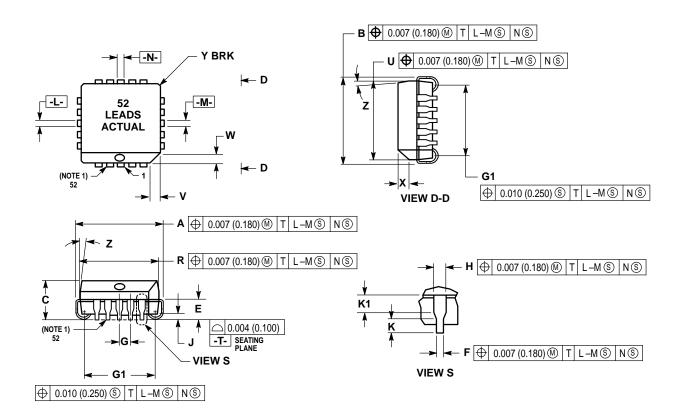
Full Part Numbers — MCM67M518FN9 MCM67M518FN11 MCM67M518FN14

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#### **PACKAGE DIMENSIONS**

**FN PACKAGE** 52-LEAD PLCC **CASE 778-02** 



- DUE TO SPACE LIMITATION, CASE 778-02 SHALL BE REPRESENTED BY A GENERAL (SMALLER) CASE
  OUTLINE DRAWING RATHER THAN SHOWING ALL 52
- DATUMS -L-, -M-, AND -N- DETERMINED WHERE TOP OF LEAD SHOULDER EXITS PLASTIC BODY AT MOLD
- PARTING LINE.
  DIM G1, TRUE POSITION TO BE MEASURED AT DATUM -T-,
- SEATING PLANE.

  5. DIM R AND U DO NOT INCLUDE MOLD FLASH.
  ALLOWABLE MOLD FLASH IS 0.010 (0.250) PER SIDE.

  5. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M,
- CONTROLLING DIMENSION: INCH.
- CONTROLLING DIMENSION: INCH.
  THE PACKAGE TOP MAY BE SMALLER THAN THE
  PACKAGE BOTTOM BY UP TO 0.012 (0.300). DIMENSIONS
  R AND U ARE DETERMINED AT THE OUTERMOST
  EXTREMES OF THE PLASTIC BODY EXCLUSIVE OF MOLD
  FLASH, TIE BAR BURRS, GATE BURRS AND INTERLEAD
  FLASH, BUT INCLUDING ANY MISMATCH BETWEEN THE
  TOP AND BOTTOM OF THE PLASTIC BODY.
  DIMENSION H DOES NOT INCLUDE DAMBAR
  PROTRUSION OR INTRUSION. THE DAMBAR
  PROTRUSION(S) SHALL NOT CAUSE THE H DIMENSION
  TO BE GREATER THAN 0.037 (0.940). THE DAMBAR
- INTRUSION(S) SHALL NOT CAUSE THE H DIMENSION TO BE SMALLER THAN 0.025 (0.635).

	INC	HES	MILLIMETERS		
DIM	MIN	MAX	MIN	MAX	
Α	0.785	0.795	19.94	20.19	
В	0.785	0.795	19.94	20.19	
С	0.165	0.180	4.20	4.57	
E	0.090	0.110	2.29	2.79	
F	0.013	0.019	0.33	0.48	
G	0.05	0 BSC	1.27	BSC	
Н	0.026	0.032	0.66	0.81	
J	0.020	_	0.51	_	
K	0.025	_	0.64	_	
R	0.750	0.756	19.05	19.20	
U	0.750	0.756	19.05	19.20	
٧	0.042	0.048	1.07	1.21	
W	0.042	0.048	1.07	1.21	
Х	0.042	0.056	1.07	1.42	
Y	_	0.020	_	0.50	
Z	2°	10°	2°	10°	
G1	0.710	0.730	18.04	18.54	
K1	0.040	_	1.02		

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