

**DESCRIPTION**

The M56789FP is a semiconductor integrated circuit in order to drive 4ch actuator.

**FEATURES**

- Large power dissipation (Power Package).
- 3.3V DSP available.
- Low saturation voltage (typical 0.6V at load current 500mA).
- Low cross-over distortion.
- Wide supply voltage range.(4.5V–13.2V)
- Divided Motor power supplies into three parts.
- Ch1, Ch2 and Ch3 can be controlled by PWM.
- Ch1 and Ch2 can act in the Current Control mode.
- Two naked Operational Amplifiers.
- TSD(Thermal Shut Down) circuit.
- Two mute circuits.

**APPLICATION**

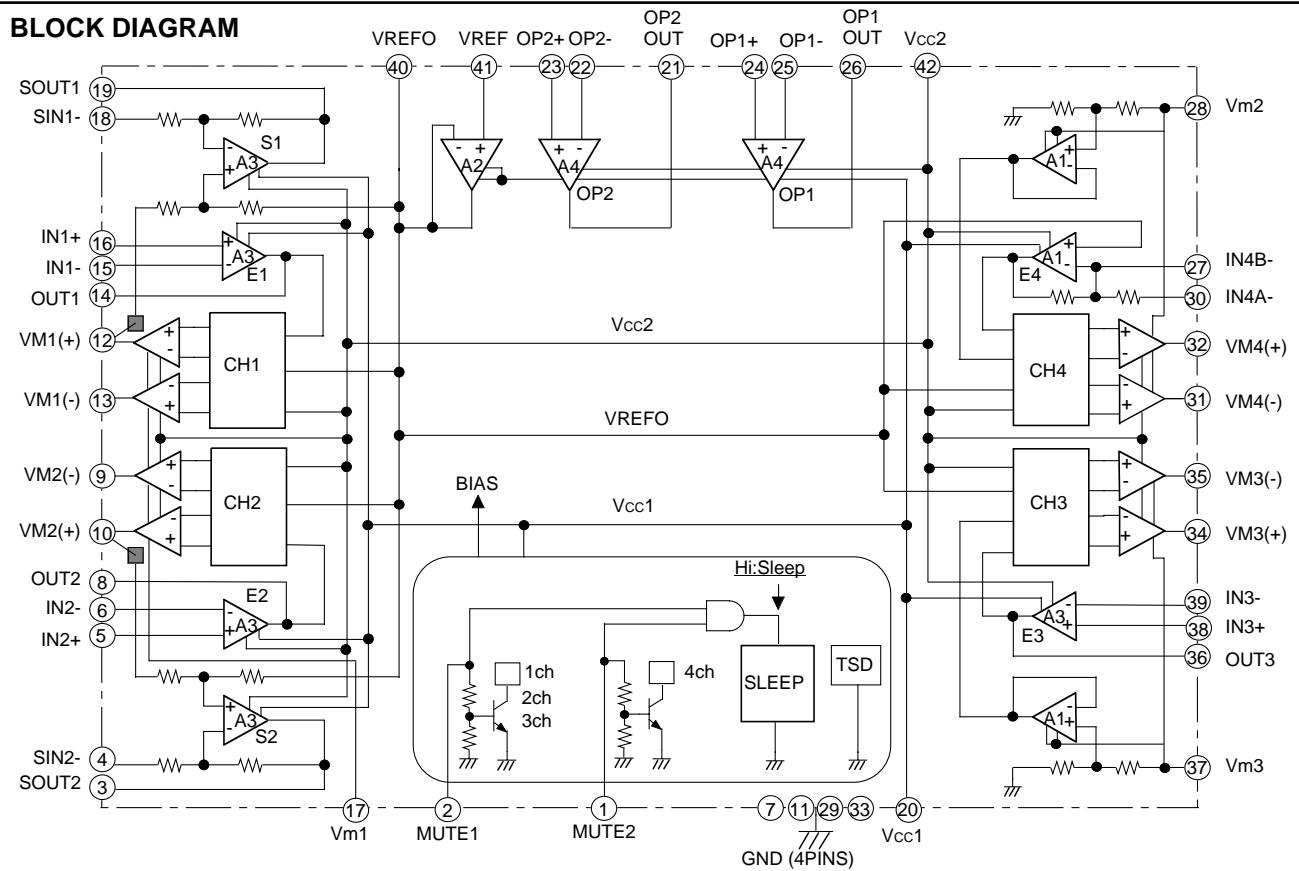
CD-ROM, DVD, DVD-ROM etc.

**PIN CONFIGURATION (TOP VIEW)**

MUTE2	1	○	42	Vcc2
MUTE1	2		41	VREF
SOUT2	3		40	VREFO
SIN2-	4		39	IN3-
IN2+	5		38	IN3+
IN2-	6		37	Vm3
GND	7		36	OUT3
OUT2	8		35	VM3-
VM2-	9		34	VM3+
VM2+	10		33	GND
GND	11		32	VM4+
VM1+	12		31	VM4-
VM1-	13		30	IN4A-
OUT1	14		29	GND
IN1-	15		28	Vm2
IN1+	16		27	IN4B-
Vm1	17		26	OP1OUT
SIN1-	18		25	OP1-
SOUT1	19		24	OP1+
Vcc1	20		23	OP2+
OP2OUT	21		22	OP2-

M56789FP

Outline 42P9R-B

**BLOCK DIAGRAM**

**PIN DESCRIPTIONS**

Pin No.	Symbol	Function	Pin No.	Symbol	Function
①	MUTE2	CH4 mute	④2	Vcc2	Bootstrap power supply
②	MUTE1	CH1,2 and 3 mute	④1	VREF	Reference voltage input
③	SOUT2	S2 amplifier output	④0	VREFO	Reference voltage output
④	SIN2-	S2 amplifier inverted input	③9	IN3-	E3 amplifier inverted input
⑤	IN2+	E2 amplifier non-inverted input	③8	IN3+	E3 amplifier non-inverted input
⑥	IN2-	E2 amplifier inverted input	③7	Vm3	Motor power supply - 3
⑧	OUT2	E2 amplifier output	③6	OUT3	E3 amplifier output
⑨	VM2(-)	CH2 inverted output	③5	VM3(-)	CH3 inverted output
⑩	VM2(+)	CH2 non-inverted output	③4	VM3(+)	CH3 non-inverted output
⑦, ⑪	GND	GND	②9, ③3	GND	GND
⑫	VM1(+)	CH1 non-inverted output	③2	VM4(+)	CH4 non-inverted output
⑬	VM1(-)	CH1 inverted output	③1	VM4(-)	CH4 inverted output
⑭	OUT1	E1 amplifier output	③0	IN4A-	E4 amplifier low gain input
⑮	IN1-	E1 amplifier inverted input	③8	Vm2	Motor power supply - 2
⑯	IN1+	E1 amplifier non-inverted input	③7	IN4B-	E4 amplifier high gain input
⑰	Vm1	Motor power supply - 1	③6	OP1OUT	OP1 amplifier output
⑱	SIN1-	S1 amplifier inverted input	③5	OP1-	OP1 amplifier inverted input
⑲	SOUT1	S1 amplifier output	③4	OP1+	OP1 amplifier non-inverted input
⑳	Vcc1	5V power supply	③3	OP2+	OP2 amplifier non-inverted input
㉑	OP2OUT	OP2 amplifier output	③2	OP2-	OP2 amplifier inverted input

**ABSOLUTE MAXIMUM RATING (Ta=25°C )**

Symbol	Parameter	Conditions	Rating	Unit
Vcc2	Bootstrap power supply	④2 pin input voltage	15	V
Vm	Motor power supply	③7, ③8 and ③7 pins input voltage	15	V
Vcc1	5V power supply	③0 pin input voltage	7.0	V
Io	Output Current		700	mA
Vin1	Maximum input voltage of terminals	①, ②, ⑤, ⑥, ⑮, ⑯, ③2, ③3, ③4, ③5, ③6, ③7, ③8, ③9, ③0, ③1, ③2 pins	0 – Vcc1	V
Vin2		④, ⑮ pins	0 – Vm1	
Pt	Power dissipation	Free Air	1.2	W
Kθ	Thermal derating	Free Air	9.6	mW / °C
Tj	Junction temperature		150	°C
Topr	Operating temperature		-20 – +75	°C
Tstg	Storage temperature		-40 – +150	°C

**RECOMMENDED OPERATING CONDITIONS**

Symbol	Parameter	Limits			Unit
		Min.	Typ.	Max.	
Vcc1	5V power supply	4.5	5.0	5.5	V
Vcc2	Bootstrap power supply		Vm + 1.0		V
Vm1, 2, 3	Motor power supply-1, 2, 3		5.0		V

**ELECTRICAL CHARACTERISTICS**

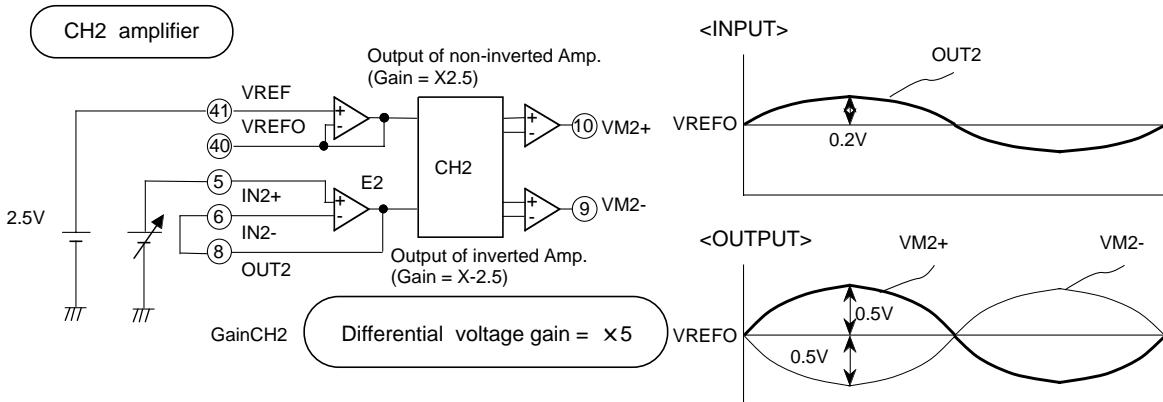
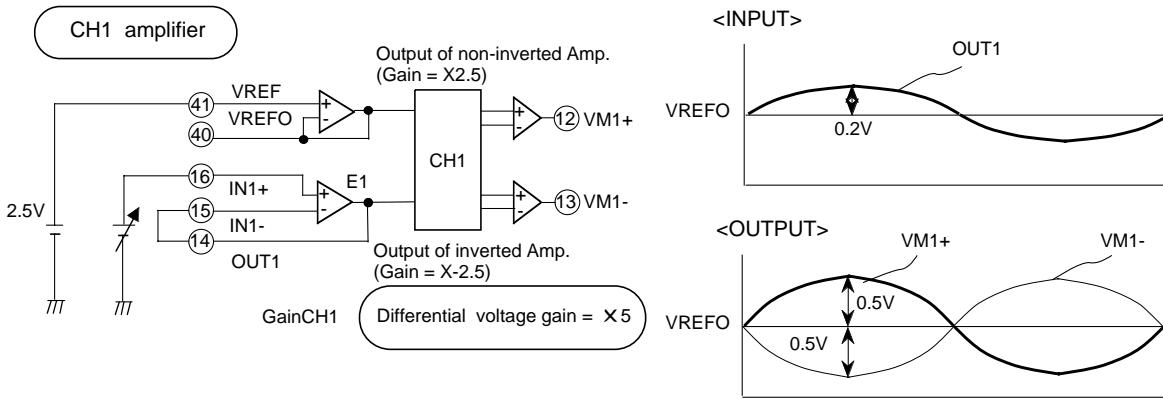
(Ta=25°C, Vcc1=Vm1=Vm2=Vm3=5V, Vcc2=12V, no-load current unless otherwise noted.)

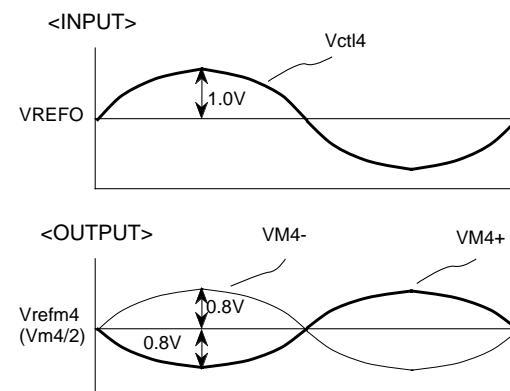
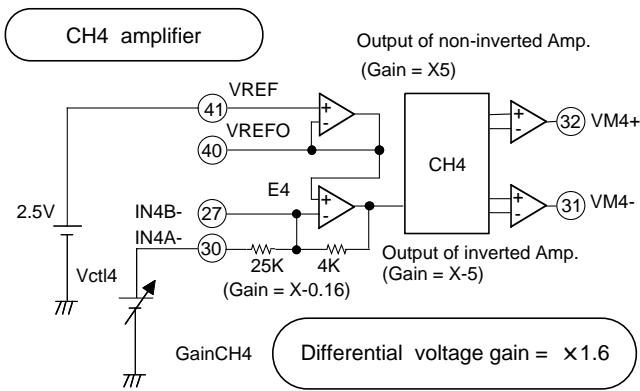
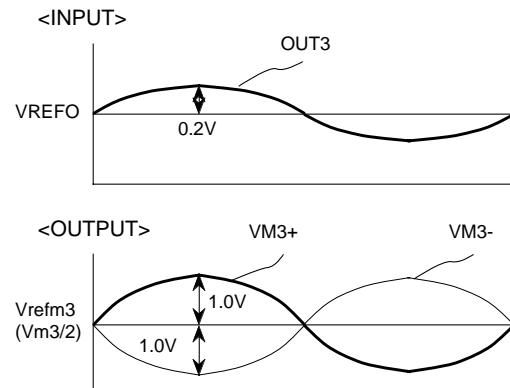
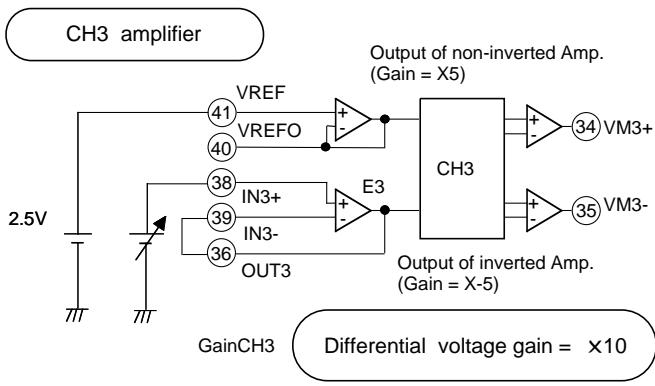
Symbol	Parameter	Conditions	Limits			Unit
			Min.	Typ.	Max.	
Icc1	Supply current - 1	(17,28,37,42) pins supply current ( Vref=Vctl=2.5V)	—	24	36	mA
Icc2	Supply current - 2	(20) pin[Vcc1] supply current ( Vref=Vctl=2.5V)	—	9.5	15	mA
Icc3	Sleep Mode Supply current - 3	(17,20,22,37,42) pins supply current (MUTE1,2=H)	—	—	500	µA
VsatCH1	Ch1 Saturation voltage	Top and Bottom saturation voltage. Load current 500mA. At bootstrap.	—	0.85	1.28	V
VsatCH2	Ch2 Saturation voltage		—	0.85	1.28	V
VsatCH3	Ch3 Saturation voltage		—	0.6	0.9	V
VsatCH4	Ch4 Saturation voltage		—	0.7	1.0	V
Vmute-on	Mute-on voltage	Mute-on	2.0	—	—	V
Vmute-off	Mute-off voltage	Mute-off	—	—	0.8	V
Imute	Mute terminals input current	(1)and(2)pin input current at 5V input voltage.	—	170	250	µA
VinOP	OP1 and OP2 amplifier Input voltage range	Io= ± 2.0mA	0.5	—	Vcc2-1.0	V
VoutOP	OP1 and OP2 amplifier output voltage range		0.5	—	Vcc1-0.5	V
VofOP	OP1 and OP2 amplifier input offset voltage	Vin = 2.5V(at buffer )	-10	—	+10	mV
linOP	OP1 and OP2 amplifier input current	inverted input = non-inverted input =2.5V	-1.0	-0.15	0	µA
lofOP	OP1 and OP2 amplifier input current offset	inverted input = non-inverted input =2.5V	-100	0	+100	nA
GBOP	OP1 and OP2 amplifier GB	E1,E2 and E3 amplifier Input voltage range	2.3	4	—	MHz
VinE	E1,E2 and E3 amplifier Input voltage range		0.5	—	Vcc2-2.0	V
VoutE	E1,E2 and E3 amplifier output voltage range	No load	1.0	—	Vcc1-0.5	V
VofE	E1,E2 and E3 amplifier input offset voltage	Vin = 2.5V(at buffer )	-10	—	+10	mV
linE	E1,E2 and E3 amplifier input current	inverted input = non-inverted input =2.5V	-1.0	-0.15	0	µA
lofE	E1,E2 and E3 amplifier input current offset	inverted input = non-inverted input =2.5V	-100	0	+100	nA
VoutS	S1 and S2 amplifier output voltage range	No load	1.0	—	Vcc1-0.5	V
VinVREF	VREF buffer amplifier Input voltage range	@1)pin input voltage = 2.5V	1.5	2.5	Vcc1-1.2	V
VofVREF	VREF buffer amplifier offset voltage		-10	—	+10	mV
VofCH1	Ch1 output offset voltage	VREFO = OUT1 = 2.5V when the OUT1 voltage is adjusted at the same VREFO voltage, at VREF= 2.5V	-26	—	+26	mV
VofCH2	Ch2 output offset voltage	VREFO = OUT2 = 2.5V when the OUT2 voltage is adjusted at the same VREFO voltage, at VREF= 2.5V	-26	—	+26	mV
VofCH3	Ch3 output offset voltage	VREFO = OUT3 = 2.5V when the OUT3 voltage is adjusted at the same VREFO voltage, at VREF= 2.5V	-26	—	+26	mV
VofCH4	Ch4 output offset voltage	VREFO = IN4A- = 2.5V when the IN4A- voltage is adjusted at the same VREFO voltage, at VREF= 2.5V	-26	—	+26	mV
VofS1	S1 output offset voltage	SOUT1-VREFO (at SI N1[-] = VM1[+] ) at VREF = 2.5V	-20	—	+20	mV
VofS2	S2 output offset voltage	SOUT2-VREFO (at SI N2[-] = VM2[+] ) at VREF = 2.5V	-20	—	+20	mV

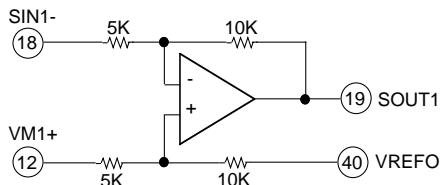
**ELECTRICAL CHARACTERISTICS**

(Ta=25°C, Vcc1=Vm1=Vm2=Vm3=5V, Vcc2=12V, no-load current unless otherwise noted.)

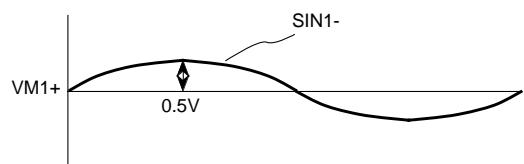
Symbol	Parameter	Conditions	Limits			Unit
			Min.	Typ.	Max.	
GainCH1	Ch1 power amplifier voltage gain	{VM1(+) – VM1(-)} at VREF=2.5V ( OUT1 – VREFO )	13.1	14	14.8	dB
GainCH2	Ch2 power amplifier voltage gain	{VM2(+) – VM2(-)} at VREF=2.5V ( OUT2 – VREFO )	13.1	14	14.8	dB
GainCH3	Ch3 power amplifier voltage gain	{VM3(+) – VM3(-)} at VREF=2.5V ( OUT3 – VREFO )	19.1	20	20.8	dB
GainCH4	Ch4 power amplifier voltage gain	-1• {VM4(+) – VM4(-)} at VREF=2.5V ( IN4A[-] – VREFO )	3.17	4.08	4.91	dB
GainS1	S1 amplifier voltage gain	{SOUT1 - VREFO} at VREF=2.5V ( VM1[+] - SI N1[-] )	5.11	6.02	6.85	dB
GainS2	S2 amplifier voltage gain	{SOUT2 - VREFO} at VREF=2.5V ( VM2[+] - SI N2[-] )	5.11	6.02	6.85	dB

**INPUT and OUTPUT CHARACTERISTICS of EACH CHANNELS**

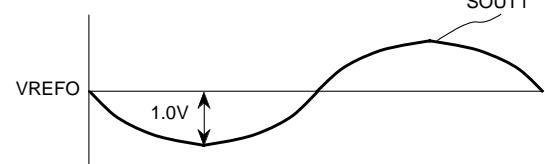
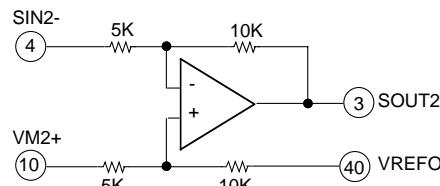
**4 CHANNEL ACTUATOR DRIVER**

**4 CHANNEL ACTUATOR DRIVER****S1 amplifier**GainS1      Voltage gain =  $\times 2$ 

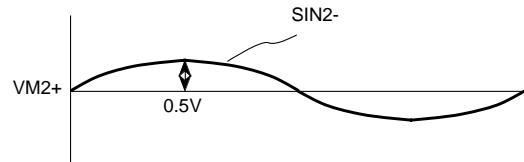
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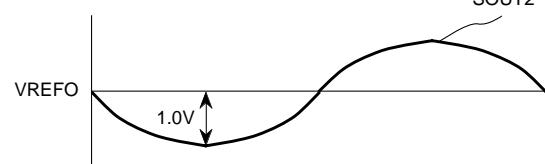
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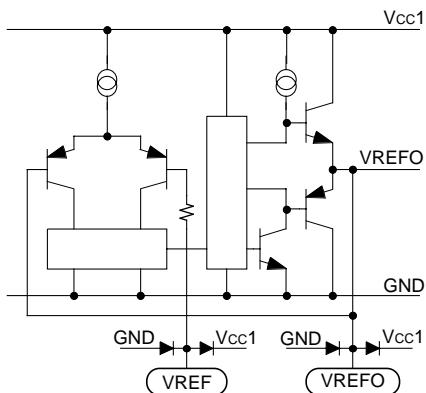
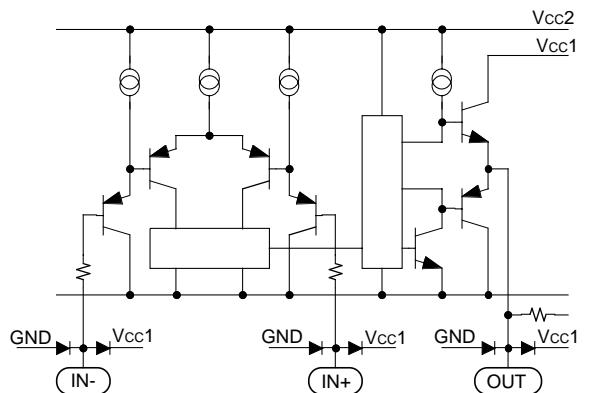
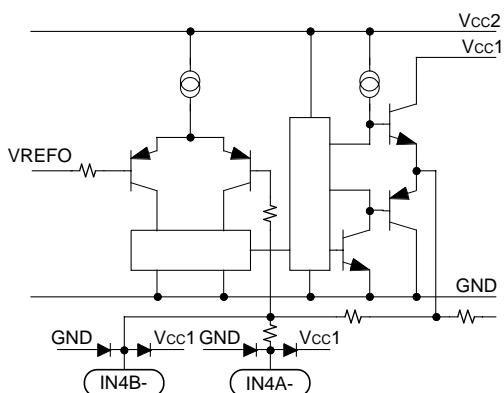
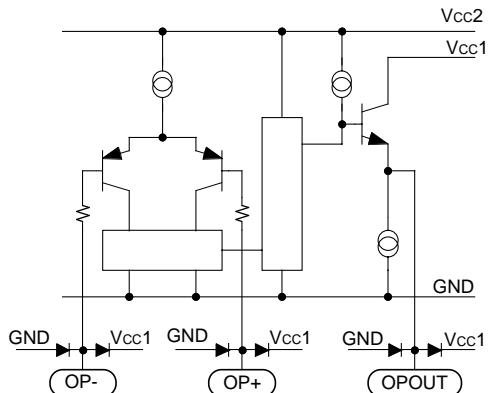
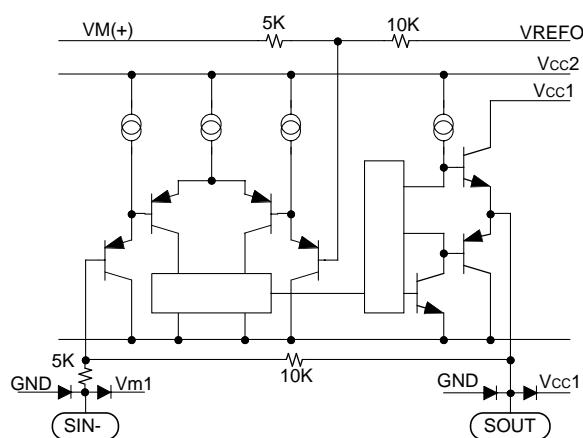
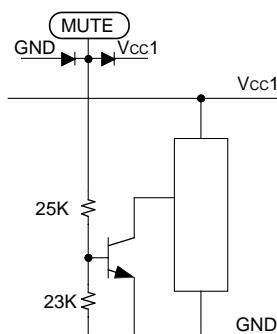
**S2 amplifier**GainS2      Voltage gain =  $\times 2$ 

&lt;INPUT&gt;



&lt;OUTPUT&gt;

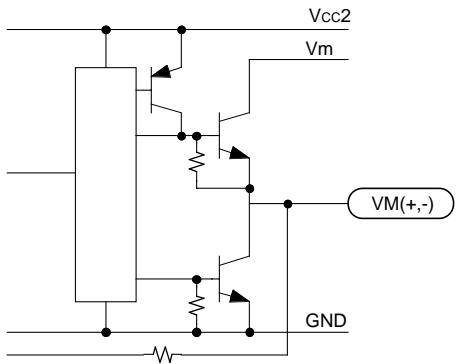


**4 CHANNEL ACTUATOR DRIVER****I/O terminal equivalent circuit**(1)VREF amplifier I/O terminal equivalent circuit  
(VREF, VREFO)(2)E1,E2,E3 amplifier I/O terminal equivalent circuit  
(IN1+, IN1-, OUT1, IN2+, IN2-, OUT2, IN3+, IN3-, OUT3)(3)E4 amplifier I/O terminal equivalent circuit  
(IN4A-, IN4B-)(4)OP1, OP2 amplifier I/O terminal equivalent circuit  
(OP1+, OP1-, OP1OUT, OP2+, OP2-, OP2OUT)(5)S1,S2 amplifier I/O terminal equivalent circuit  
(SIN1-, SOUT1, SIN2-, SOUT2)(6)MUTE circuits equivalent circuit  
(MUTE1, MUTE2)

## I/O terminal equivalent circuit

(7)CH1,2,3,4 power amplifier

OUTPUT terminal equivalent circuit  
(VM1(+), VM1(-), VM2(+), VM2(-),  
VM3(+), VM3(-), VM4(+), VM4(-), )



The equivalent circuits of an output stage of the power amplifier are shown in (7).

The power supplies of CH1,CH2 are  $V_m$ .

The power supply of CH3 is  $V_{m3}$ , and the power supply of CH4 is  $V_{m2}$ .

The source side of the power amplifier output stage consists of a PNP and a NPN. The emitters of the PNP is connected to  $V_{cc2}$ . So the power supplies of the PNP can be adjusted externally.

### [About bootstrap advantage]

The output stage of the power amplifier consists of the preceding components. If  $V_{cc2}$  is provided with higher voltage input than  $V_m^*$  (The recommendation voltage is  $V_m^*+1V$ ) externally, the output range can be wider than that of  $V_{cc2}=V_m^*$ .

Please take advantage of this bootstrap function for the system which has many power supplies. And it is the same with the external bootstrap circuit which provides  $V_{cc2}$  with higher voltage inputs than  $V_m^*$ .

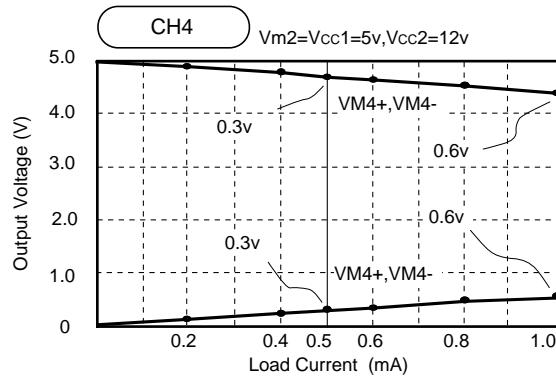
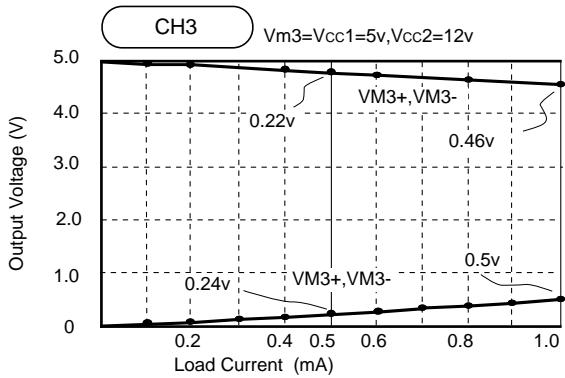
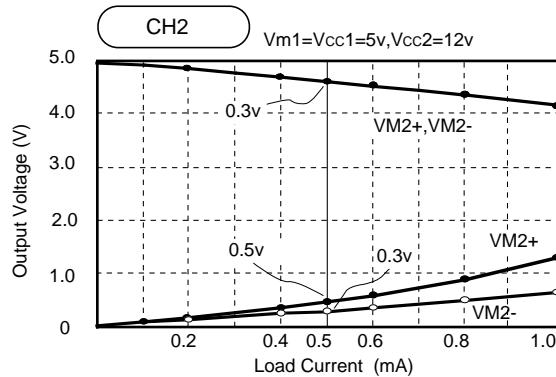
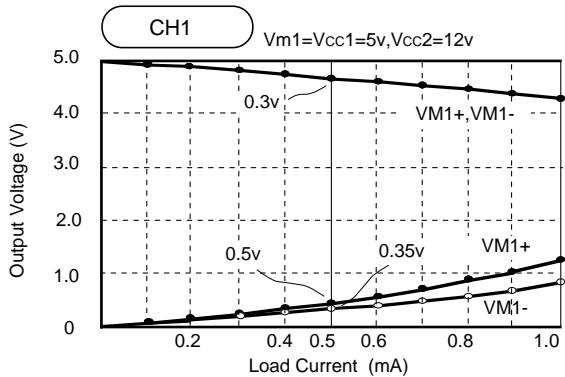
Also the bootstrap can decrease the saturation voltage at the source side of the power amplifier output stage. Therefore, when the outputs of the power amplifiers which drive motors and actuators are fully swung, the power dissipation of the IC will be decreased.

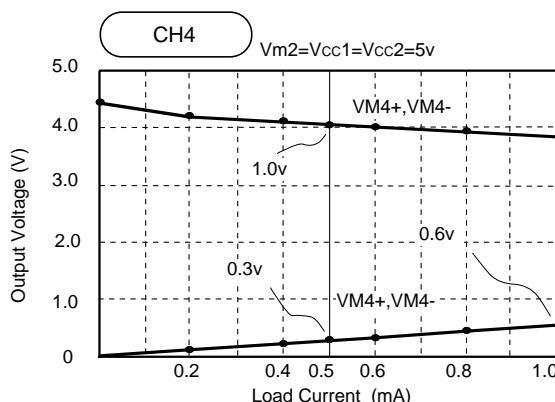
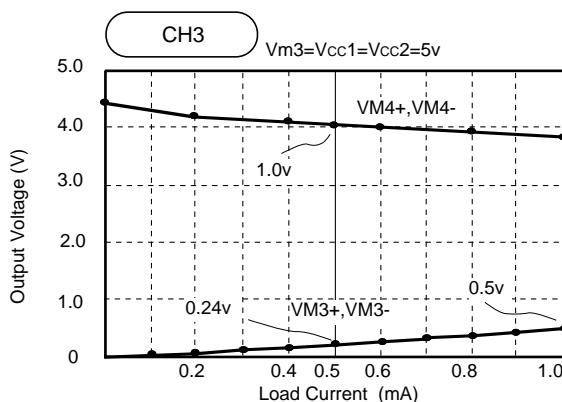
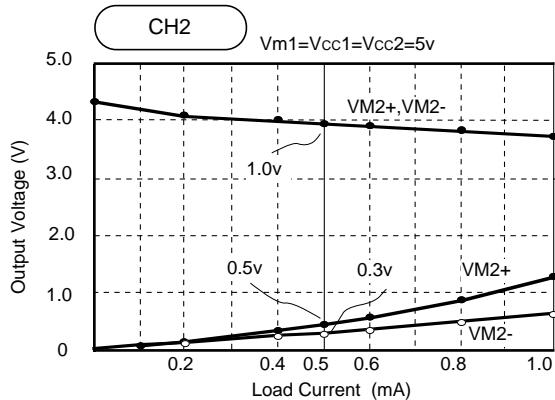
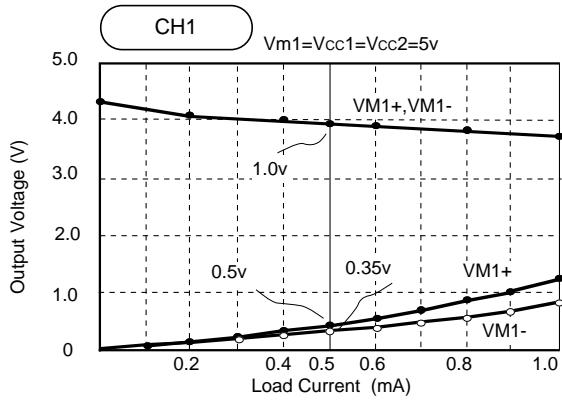
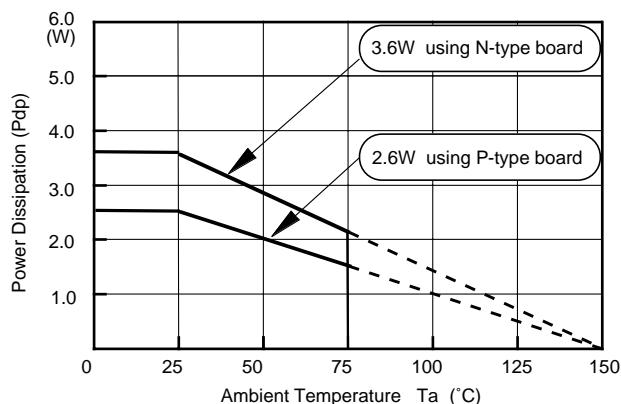
## BASICALLY CHARACTERISTICS

Output saturation voltage and Load current characteristic.

This data is an example for typical sample.

### BOOTSTRAP



**4 CHANNEL ACTUATOR DRIVER**NON-BOOTSTRAP**THERMAL DERATING**

This IC's package is POWER-SSOP, so improving the board on which the IC is mounted enables a large power dissipation without a heat sink.

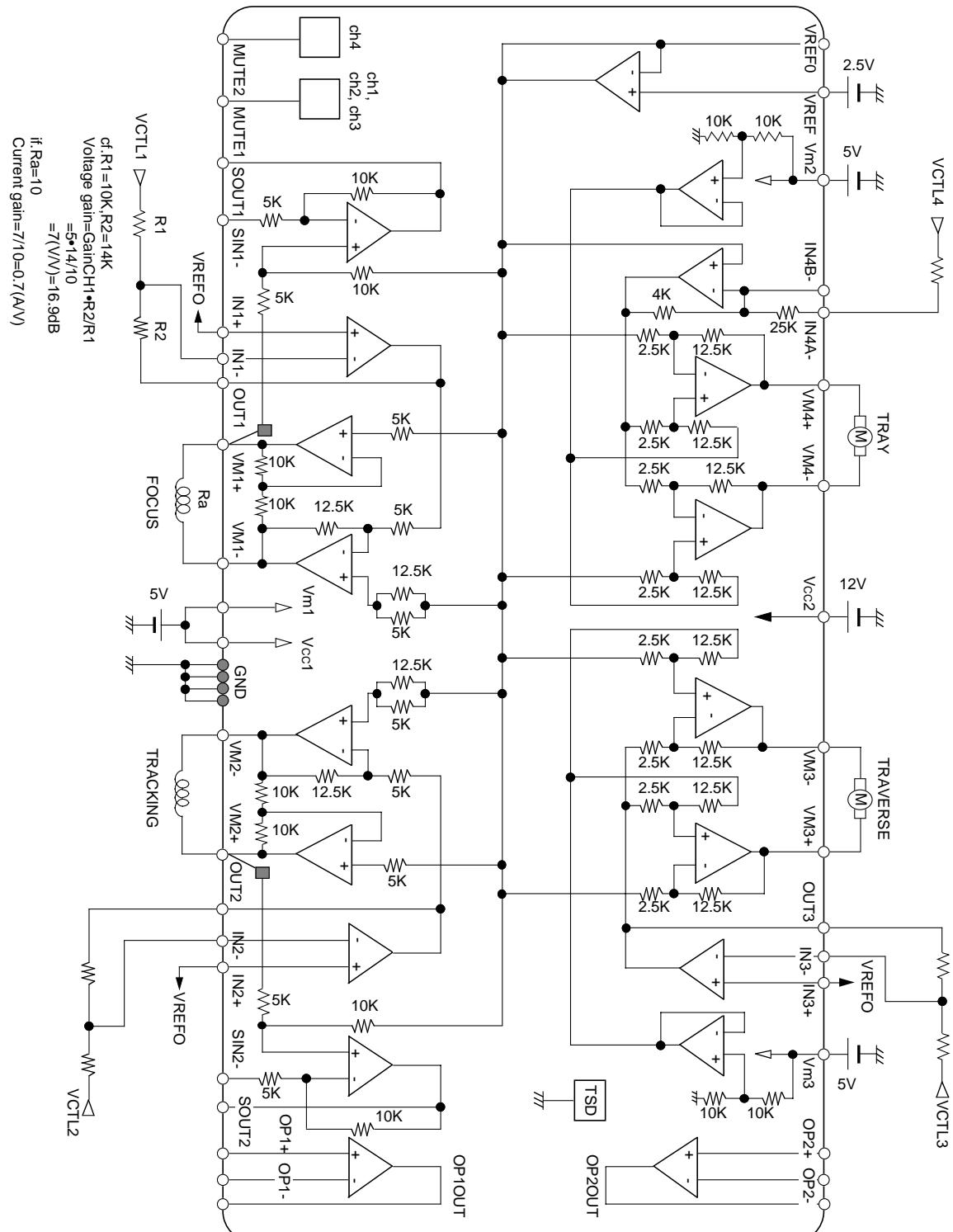
For example, using an 1 layer glass epoxy resin board, the IC's power dissipation is 2.6W at least. And it comes to 3.6W by using an improved 2 layer board.

The information of the N, P type board is shown in the board information.

**APPLICATION CIRCUIT No.1**

\* single input (linear signal)

\* Direct voltage control



## **APPLICATION CIRCUIT No.2**

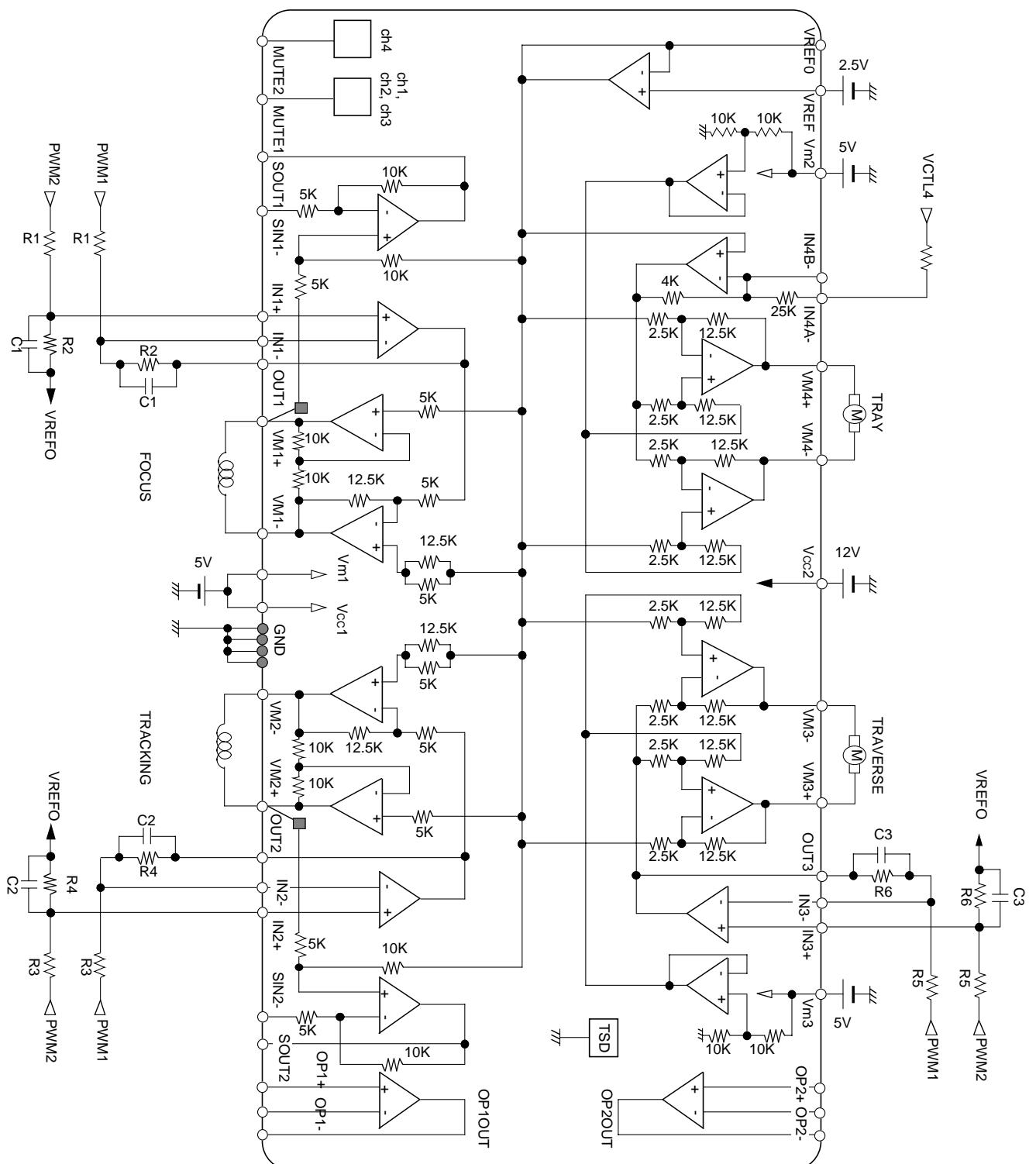
\* single input (linear signal)

\* Direct current control (for FOCUS and TRACKING)

cf.R1=10K, R2=14K, RS=1  
 Current gain=R2/(R1\*GainS1\*RS)  
 $=14/[10 \cdot 2^1] = 0.7(A/V)$

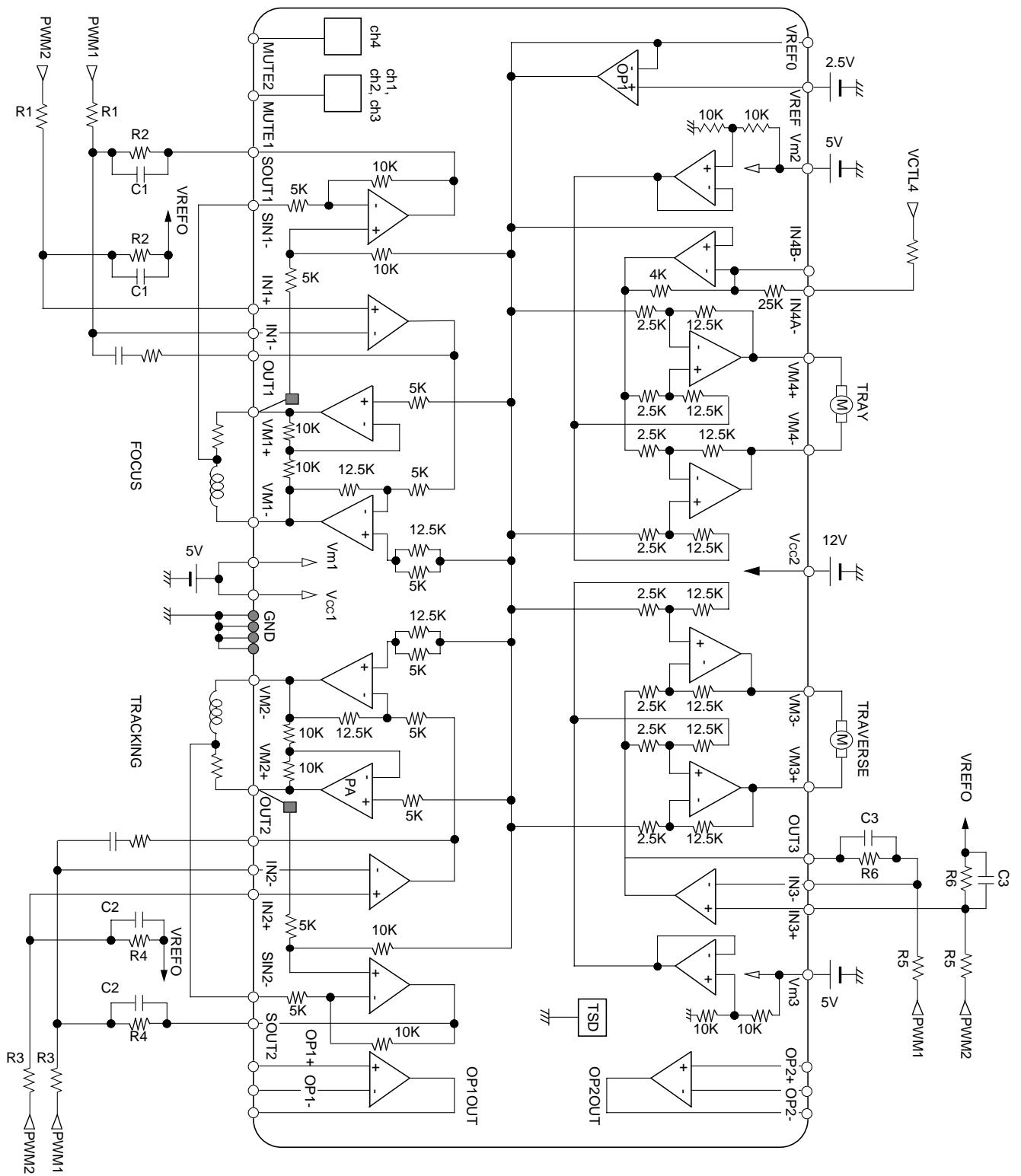
## APPLICATION CIRCUIT No.3

- \* Differential PWM input (for FOCUS,TRACKING and TRAVERSE)
- \* Direct voltage control



**APPLICATION CIRCUIT No.4**

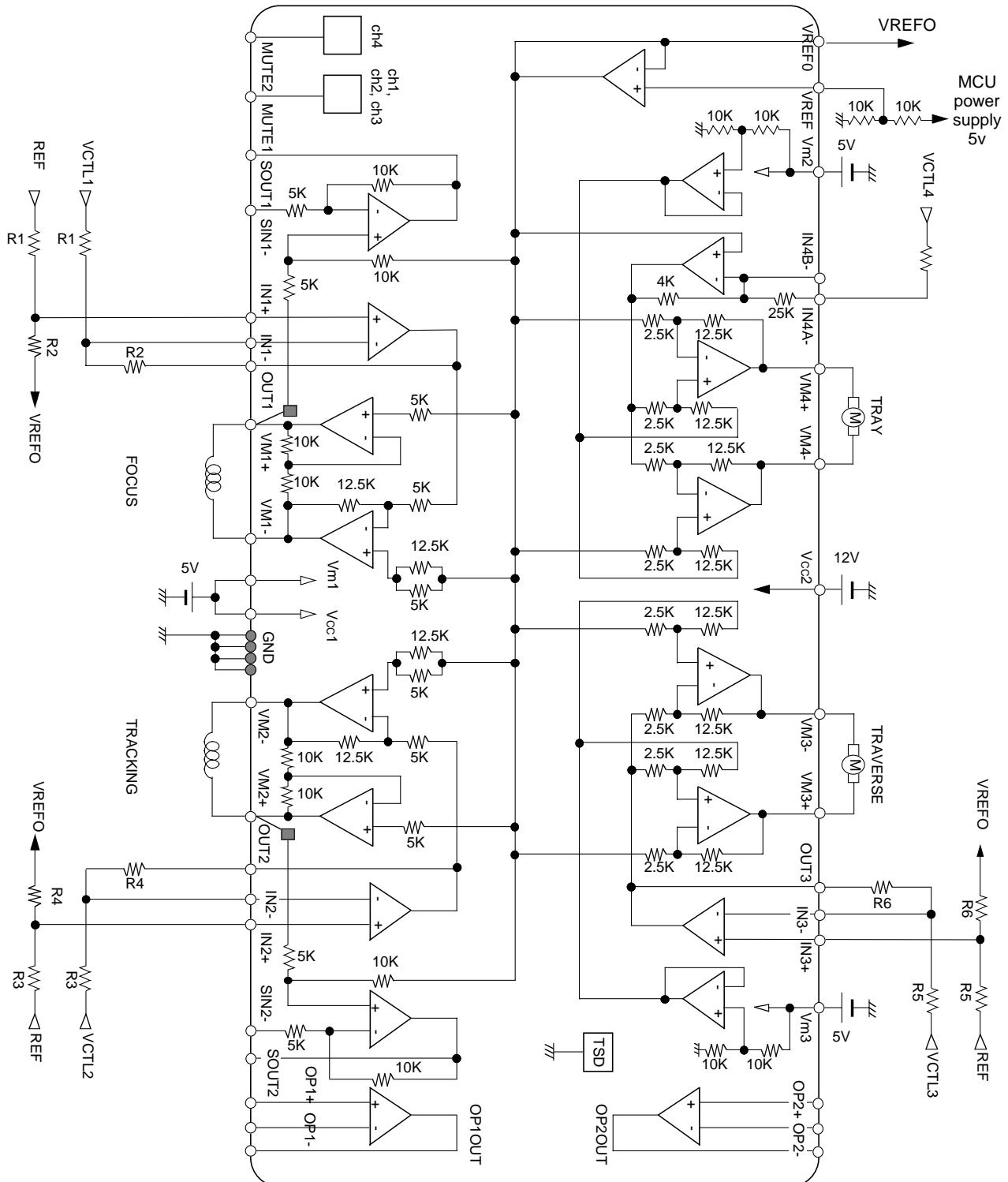
\* Differential PWM input (for FOCUS,TRACKING and TRAVERSE)  
 \* Direct current control (for FOCUS and TRACKING)



**4 CHANNEL ACTUATOR DRIVER****APPLICATION CIRCUIT No.5 (for 3.3V DSP)**

\* single input (linear signal)

\* Direct voltage control



**APPLICATION CIRCUIT No.6 (for 3.3V DSP)**

\* single input (linear signal)

\* Direct current control (for FOCUS and TRACKING)

