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SPEC	IFICATIONS
Product Type	8M Flash Memory
LH28	F 8 0 0 S G H E – L 7 0
Model No	(LHF80G05)
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LHF80G05



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LH28F800SGHE-L70 (LHF80G05) 8M (512Kbit × 16) SmartVoltage Flash Memory

FEATURES

SmartVoltage Technology

- 3.0V (2.7V min.) or 5V V_{cc}
- 3.0V (2.7V min.), 5V or 12V V_{PP}

■ High-Performance

- 70 ns (5V V_{cc}) Read Access Time
- 100 ns (2.7V V_{cc}) Read Access Time

Enhanced Automated Suspend Options

- · Word Write Suspend to Read
- · Block Erase Suspend to Word Write
- Block Erase Suspend to Read

Enhanced Data Protection Features

- Absolute Protection with V_{pp} = GND
- · Flexible Block Locking
- Block Erase/Write Lockout during Power Transitions

Industry Standard Packaging

- · 48-Lead TSOP
- SRAM-Compatible Write Interface

High-Density Symmetrically Blocked Architecture

Sixteen 32k-word Erasable Blocks

Extended Cycling Capability

- · 100,000 Block Erase Cycles
- 1.6 Million Block Erase Cycles/Device

Low Power Management

- Deep Power-Down Mode
- Automatic Power Savings Mode Decreases I_{cc} in Static Mode

Automated Word Write and Block Erase

- · Command User Interface
- Status Register

■ ETOX[™] V Nonvolatile Flash Technology

Not designed or rated as radiation hardened

SHARP's LH28F800SGHE-L70 Flash memory with SmartVoltage technology is a high-density, low-cost, nonvolatile, read/write storage solution for a wide range of applications. LH28F800SGHE-L70 can operate at $V_{\rm cc}=2.7$ V and $V_{\rm pp}=2.7$ V. Its low voltage operation capability realize longer battery life and suits for cellular phone application. Its symmetrically-blocked architecture, flexible voltage and extended cycling provide for highly flexible component suitable for resident flash arrays, SIMMs and memory cards. Its enhanced suspend capabilities provide for an ideal solution for code + data storage applications. For secure code storage applications, such as networking, where code is either directly executed out of flash or downloaded to DRAM, the LH28F800SGHE-L70 offers three levels of protection: absolute protection with $V_{\rm pp}$ at GND, selective hardware block locking, or flexible software block locking. These alternatives give designers ultimate control of their code security needs.

The LH28F800SGHE-L70 is manufactured on SHARP's 0.4 µm ETOX™ V process technology. It comes in industry-standard packages: the 48-lead TSOP ideal for board constrained applications.

* ETOX is a trademark of Intel Corporation.

1.0 INTRODUCTION

This datasheet contains LH28F800SGHE-L70 specifications. Section 1 provides a flash memory overview. Sections 2, 3, 4, and 5 describe the memory organization and functionality. Section 6 covers electrical specifications.

1.1 New Features

Key enhancements of LH28F800SGHE-L70 SmartVoltage Flash memory are:

- · SmartVoltage Technology
- · Enhanced Suspend Capabilities
- · In-System Block Locking
- · Permanent Lock Capability

Please note following important differences:

- V_{PPLK} has been lowered to 1.5V to support 3.3V and 5V block erase, word write, and lock-bit configuration operations. Designs that switch V_{PP} off during read operations should make sure that the V_{PP} voltage transitions to GND.
- To take advantage of SmartVoltage technology, allow V_{cc} connection to 3.3V (2.7V min.) or 5V.
- Once set the permanent lock bit, the blocks which have been set block lock-bit can not be erased, written forever.

1.2 Product Overview

The LH28F800SGHE-L70 is a high-performance 8-Mbit SmartVoltage Flash memory organized as 512 Kword of 16 bits. The 512 Kword of data is arranged in sixteen 32-Kword blocks which are individually erasable, lockable, and unlockable in-system. The memory map is shown in Figure 3.

SmartVoltage technology provides a choice of V_{cc} and V_{pp} combinations, as shown in Table 1, to meet system performance and power expectations. 3.3V V_{cc} consumes approximately one-fifth the power of 5V V_{cc} . But, 5V V_{cc} provides the highest read performance. V_{pp} at 3.3V and 5V eliminates the need for a separate 12V converter, while V_{pp} = 12V maximizes block erase and word write performance. In addition to flexible erase and program voltages, the dedicated V_{pp} pin gives complete data protection when $V_{pp} \leq V_{pplk}$.

Table 1. V_{cc} and V_{pp} Voltage Combinations Offered by SmartVoltage Technology

V _{CC} Voltage	V _{PP} Voltage		
3.3V ⁽¹⁾	3.3V ⁽²⁾ , 5V, 12V		
5V	5V, 12V		

NOTES:

- Block erase, word write and lock-bit configuration operations with V_{cc} < 2.7V are not supported.
- Block erase, word write and lock-bit configuration operations with V_{pp} < 2.7V are not supported.

Internal $V_{\rm cc}$ and $V_{\rm PP}$ detection circuitry automatically configures the device for optimized read and write operations.

A command User Interface (CUI) serves as the interface between the system processor and internal operation of the device. A valid command sequence written to the CUI initiates device automation. An internal Write State Machine (WSM) automatically executes the algorithms and timing necessary for block erase, word write, and lock-bit configuration operations.

A block erase operation erases one of the device's 32-Kword blocks typically within 1.2 second (5V $V_{\rm cc}$, 12V $V_{\rm pp}$) independent of other blocks. Each block can be independently erased 100,000 times (1.6 million block erases per device). Block erase suspend mode allows system software to suspend block erase to read or write data from any other block.

Writing memory data is performed in word increments typically within 7.5 μs (5V V_{CC}, 12V V_{PP}). Word write suspend mode enables the system to read data or execute code from any other flash memory array location.

The selected block can be locked or unlocked individually by the combination of sixteen block lock bits and the RP# or WP#. Block erase or word write must not be carried out by setting block lock bits and setting WP# to Low and RP# to $V_{\rm IH}$. Even if WP# is High state or RP# is set to $V_{\rm HH}$, block erase and word write to locked blocks is prohibited by setting permanent lock bit.

The status register or RY/BY# indicates when the WSM's block erase, word write, or lock-bit configuration operation is finished.

The RY/BY# output gives an additional indicator of WSM activity by providing both a hardware signal of status (versus software polling) and status masking (interrupt masking for background block erase, for example). Status polling using RY/BY# minimizes both CPU overhead and system power consumption. When low, RY/BY# indicates that the WSM is perform-

ing a block erase, word write, or lock-bit configuration. RY/BY#-high indicates that the WSM is ready for a new command, block erase is suspended (and word write is inactive), word write is suspended, or the device is in deep power-down mode.

The access time is 80 ns (t_{AVAV}) over the commercial temperature range (-40°C to +85°C) and V_{cc} supply voltage range of 4.5V-5.5V. At lower V_{cc} voltages, the access times are 85 ns (3.0V-3.6V), 100 ns (2.7V-3.0V).

The Automatic Power Saving (APS) feature substantially reduces active current when the device is in static mode (addresses not switching). In APS mode, the typical $I_{\rm CCR}$ current is 1 mA at 5V $V_{\rm CC}$.

When CE# and RP# pins are at $V_{\rm CC}$, the $I_{\rm CC}$ CMOS standby mode is enabled. When the RP# pin is at GND, deep power-down mode is enabled which minimizes power consumption and provides write protection during reset. A reset time $(t_{\rm PHQV})$ is required from RP# switching high until outputs are valid. Likewise, the device has a wake time $(t_{\rm PHEL})$ from RP#-high until writes to the CUI are recognized. With RP# at GND, the WSM is reset and the status register is cleared.

The device is available in 48-lead TSOP (Thin Small Outline Package, 1.2 mm thick), Pinouts are shown in Figures 2.

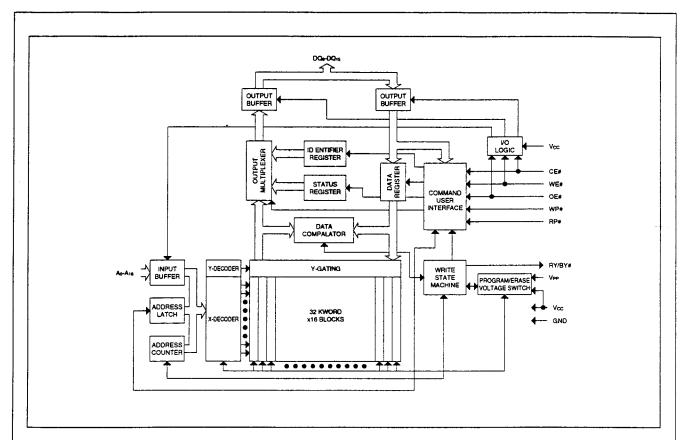


Figure 1. Block Diagram

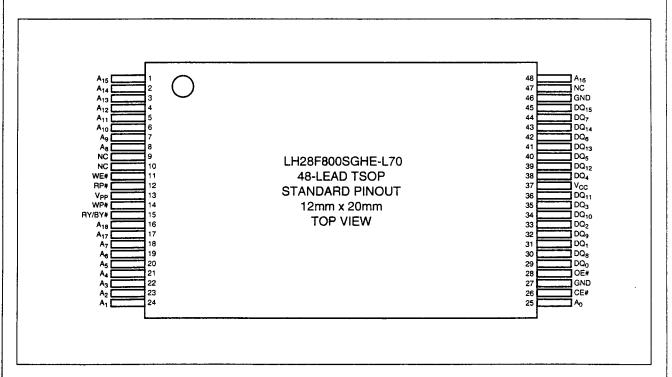


Figure 2. 48-Lead TSOP Standard Pinout Configuration



Table 2. Pin Descriptions

Symbol	Туре	Name and Function				
A ₀ - A ₁₈	INPUT	ADDRESS INPUTS: Inputs for addresses during read and write operations. Addresses are internally latched during a write cycle.				
DQ ₀ - DQ ₁₅	INPUT/OUTPUT	DATA INPUT/OUTPUTS: Inputs data and commands during CUI write cycles; outputs data during memory array, status register, and identifier code read cycles. Data pins float to high-impedance when the chip is deselected or outputs are disabled. Data is internally latched during a write cycle.				
CE#	INPUT	CHIP ENABLE: Activates the device's control logic, input buffers, decoders, and sense amplifiers. CE#-high deselects the device and reduces power consumption to standby levels.				
RP#	INPUT	power consumption to standby levels. RESET/DEEP POWER-DOWN: Puts the device in deep power-down mo and resets internal automation. RP#-high enables normal operation. Whe driven low, RP# inhibits write operations which provides data protection during power transitions. Exit from deep power-down sets the device to rearray mode. RP# at V _{HH} allows to set permanent lock-bit. Block erase, word write, or lock-bit configuration with V _{IH} < RP# < V _{HH} produce spurious results and should not be attempted.				
OE#	INPUT	OUTPUT ENABLE: Controls the device's outputs during a read cycle.				
WE#	INPUT	WRITE ENABLE: Controls writes to the CUI and array blocks. Addresses and data are latched on the rising edge of the WE# pulse.				
WP#	INPUT	WRITE PROTECT: Master control for block locking. When V _{IL} , locked blocks cannot be erased and programmed, and block lock-bits can not be set and reset.				
RŸ/BY#	OUTPUT	READY/BUSY#: Indicates the status of the internal WSM. When low, the WSM is performing an internal operation (block erase, word write, or lock-bit configuration). RY/BY#-high indicates that the WSM is ready for new commands, block erase is suspended, and word write is inactive, word write is suspended, or the device is in deep power-down mode. RY/BY# is always active and does not float when the chip is deselected or data outputs are disabled.				
V _{PP}	SUPPLY	BLOCK ERASE, WORD WRITE, LOCK-BIT CONFIGURATION POWER SUPPLY: For erasing array blocks, writing words, or configuration lock-bits. With V _{PP} ≤ V _{PPLK} , memory contents cannot be altered. Block erase, word write, and lock-bit configuration with an invalid V _{PP} (see DC Characteristics) produce spurious results and should not be attempted.				
V _{cc}	SUPPLY	DEVICE POWER SUPPLY: Internal detection configured the device for 3.3V or 5V operation. To switch from one voltage to another, ramp V_{CC} down to GND and then ramp V_{CC} to the new voltage. Do not float any power pins.With $V_{CC} \leq V_{LKO}$, all write attempts to the flash memory are inhibited. Device operations at invalid V_{CC} voltage (see DC Characteristics) produce spurious results and should not be attempted.				
GND	SUPPLY	GROUND: Do not float any ground pins.				
NC		NO CONNECT: Lead is not internal connected; it may be driven or floated.				

2.0 PRINCIPLES OF OPERATION

The LH28F800SGHE-L70 SmartVoltage Flash memory includes an on-chip WSM to manage block erase, word write, and lock-bit configuration functions. It allows for 100% TTL-level control inputs, fixed power supplies during block erasure, word write, and lock-bit configuration, and minimal processor overhead with RAM-like interface timings.

After initial device power-up or return from deep power-down mode (see Bus Operations), the device defaults to read array mode. Manipulation of external memory control pins allow array read, standby, and output disable operations.

Status register and identifier codes can be accessed through the CUI independent of the V_{pp} voltage. High voltage on V_{pp} enables successful block erasure, word writing, and lock-bit configuration. All functions associated with altering memory contents — block erase, word write, lock-bit configuration, status, and identifier codes — are accessed via the CUI and verified through the status register.

Commands are written using standard microprocessor write timings. The CUI contents serve as input to the WSM, which controls the block erase, word write, and lock-bit configuration. The internal algorithms are regulated by the WSM, including pulse repetition, internal verification, and margining of data. Addresses and data are internally latch during write cycles. Writing the appropriate command outputs array data, accesses the identifier codes, or outputs status register data

Interface software that initiates and polls progress of block erase, word write, and lock-bit configuration can be stored in any block. This code is copied to and executed from system RAM during flash memory updates. After successful completion, reads are again possible via the Read Array command. Block erase suspend allows system software to suspend a block erase to read or write data from any other block. Word write suspend allows system software to suspend a word write to read data from any other flash memory array location.

8000	32 Kword Block	15
F 0	32 Kword Block	14
=	32 Kword Block	13
F	32 Kword Block	12
F	32 Kword Block	11
	32 Kword Block	10
F	32 Kword Block	9
F 0	32 Kword Block	8
F	32 Kword Block	7
	32 Kword Block	6
	32 Kword Block	5
	32 Kword Block	4
F	32 Kword Block	3
F	32 Kword Block	2
F 00	32 Kword Block	1
F	32 Kword Block	0

Figure 3. Memory Map

2.1 Data Protection

Depending on the application, the system designer may choose to make the V_{pp} power supply switchable (available only when memory block erases, word writes, or lock-bit configurations are required) or hardwired to $V_{pph1/2/3}$. The device accommodates either design practice and encourages optimization of the processor-memory interface.

When $V_{PP} \leq V_{PPLK}$, memory contents cannot be altered. The CUI, with two-step block erase, word write, or lock-bit configuration command sequences, provides protection from unwanted operations even when high voltage is applied to V_{PP} . All write functions are disabled when V_{CC} is below the write lockout voltage V_{LKO} or when RP# is at V_{IL} . The device's block locking capability provides additional protection from inadvertent code or data alteration by gating erase and word write operations.



3.0 BUS OPERATION

The local CPU reads and writes flash memory in-system. All bus cycles to or from the flash memory conform to standard microprocessor bus cycles.

3.1 Read

Information can be read from any block, identifier codes, or status register independent of the $V_{\rm PP}$ voltage. RP# can be at either $V_{\rm IH}$ or $V_{\rm HH}$.

The first task is to write the appropriate read mode command (Read Array, Read Identifier Codes, or Read Status Register) to the CUI. Upon initial device power-up or after exit from deep power-down mode, the device automatically resets to read array mode. Five control pins dictate the data flow in and out of the component: CE#, OE#, WE#, RP# and WP#. CE# and OE# must be driven active to obtain data at the outputs. CE# is the device selection control, and when active enables the selected memory device. OE# is the data output (DQ $_0$ -DQ $_{15}$) control and when active drives the selected memory data onto the I/O bus. WE# must be at V $_{\rm IH}$ and RP# must be at V $_{\rm IH}$ or V $_{\rm HH}$. Figure 15 illustrates read cycle.

3.2 Output Disable

With OE# at a logic-high level ($V_{\rm IH}$), the device outputs are disabled. Output pins DQ $_{\rm 0}$ -DQ $_{\rm 15}$ are placed in a high-impedance state.

3.3 Standby

CE# at a logic-high level (V_{IH}) places the device in standby mode which substantially reduces device power consumption. DQ_0 - DQ_{15} outputs are placed in a high-impedance state independent of OE#. If deselected during block erase, word write, or lock-bit configuration, the device continues functioning, and consuming active power until the operation completes.

3.4 Deep Power-Down

RP# at V_{iL} initiates the deep power-down mode.

In read modes, RP#-low deselects the memory, places output drivers in a high-impedance state and turns off all internal circuits. RP# must be held low for a minimum of 100 ns. Time t_{PHOV} is required after return from power-down until initial memory access outputs are valid. After this wake-up interval, normal operation is restored. The CUI is reset to read array mode and status register is set to 80H.

During block erase, word write, or lock-bit configuration modes, RP#-low will abort the operation. RY/BY# remains low until the reset operation is complete. Memory contents being altered are no longer valid; the data may be partially erased or written. Time t_{PHWL} is required after RP# goes to logic-high (V_{IH}) before another command can be written.

As with any automated device, it is important to assert RP# during system reset. When the system comes out of reset, it expects to read from the flash memory. Automated flash memories provide status information when accessed during block erase, word write, or lock-bit configuration modes. If a CPU reset occurs with no flash memory reset, proper CPU initialization may not occur because the flash memory may be providing status information instead of array data. SHARP's flash memories allow proper CPU initialization following a system reset through the use of the RP# input. In this application, RP# is controlled by the same RESET# signal that resets the system CPU.



3.5 Read Identifier Codes

The read identifier codes operation outputs the manufacture code, device code, block lock configuration codes for each block, and the permanent lock configuration code (see Figure 4). Using the manufacture and device codes, the system CPU can automatically match the device with its proper algorithms. The block lock and permanent lock configuration codes identify locked and unlocked blocks and permanent lock-bit setting.

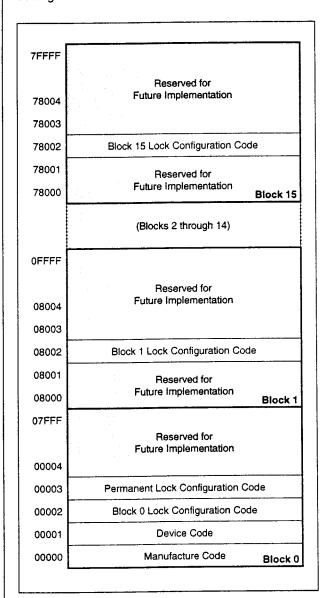


Figure 4. Device Identifier Code Memory Map

3.6 Write

Writing commands to the CUI enable reading of device data and identifier codes. They also control inspection and clearing of the status register.

The Block Erase command requires appropriate command data and an address within the block to be erased. The Word Write command requires the command and address of the location to be written. Set Permanent and Block Lock-Bit commands require the command and address within the device (Permanent Lock) or block within the device (Block Lock) to be locked. The Clear Block Lock-Bits command requires the command and address within the device.

The CUI does not occupy an addressable memory location. It is written when WE# and CE# are active. The address and data needed to execute a command are latched on the rising edge of WE# or CE# (whichever goes high first). Standard microprocessor write timings are used. Figures 16 and 17 illustrate WE# and CE# controlled write operations.

4.0 COMMAND DEFINITIONS

When the $V_{pp} \le V_{ppLK}$, Read operations from the status register, identifier codes, or blocks are enabled. Placing $V_{ppH1/2/3}$ on V_{pp} enables successful block erase, word write and lock-bit configuration operations.

Device operations are selected by writing specific commands into the CUI. Table 4 defines these commands.

Table 3. Bus Operations

LHF80G05

Mode	Notes	RP#	CE#	OE#	WE#	Address	V _{PP}	DQ ₀₋₁₅	RY/BY#
Read	1,2,	V _{IH} or	VıL	VIL	ViH	X	Х	Dout	X
	3,8	Vнн							
Output Disable	3	. Vih or Vhh	VIL	ViH	ViH	X	Х	High Z	Х
Standby	3	V _{IH} or V _{HH}	; Vін	Х	X	Х	Х	High Z	Х
Deep Power-Down	4	VIL	X	Х	X	X	X	High Z	Voн
Read Identifier Codes	8	V _{IH} or V _{HH}	VIL	VIL	VIH	See Figure 4	Х	Note 5	Voн
Write	3,6, 7,8	V _{IH} or V _{HH}	VIL	V _{IH}	VIL	Х	Х	DiN	Х

NOTES:

- 1. Refer to DC Characteristics. When $V_{PP} \le V_{PPLK}$, memory contents can be read, but not altered. 2. X can be V_{IL} or V_{IH} for control pins and addresses, and V_{PPLK} or $V_{PPH1/2/3}$ for V_{PP} . See DC Characteristics for V_{PPLK}
- and V_{PPH1/2/3} voltages.

 3. RY/BY# is V_{oL} when the WSM is executing internal block erase, word write, or lock-bit configuration algorithms. It is V_{oH} during when the WSM is not busy, in block erase suspend mode (with word write inactive), word write suspend mode, or deep power-down mode.
- 4. RP# at GND \pm 0.2V ensures the lowest deep power-down current.
- 5. See Section 4.2 for read identifier code data.
- $6.\ V_{IH}$ < RP# < V_{HH} produce spurious results and should not be attempted.
- 7. Refer to Table 4 for valid D_{IN} during a write operation.
- 8. Never hold OE# low and WE# low at the same timing.



Table.	A C	command:	Defin	itions	(9)
Ianie	4 (.ommana	Detin	enoru	(-,

	Bus Cycles		First Bus Cycle			Second Bus Cycle		
Command	Req'd	Notes	Oper ⁽¹⁾	Addr ⁽²⁾	Data ⁽³⁾	Oper ⁽¹⁾	Addr ⁽²⁾	Data ⁽³⁾
Read Array/Reset	1		Write	Х	FFH			
Read Identifier Codes	≥2	4	Write	Х	90H	Read	IA	ID
Read Status Register	2		Write	X	70H	Read	Χ	SRD
Clear Status Register	1		Write	Х	50H			
Block Erase	2	5	Write	BA	20H	Write	BA	D0H
Word Write	2	5,6	Write	WA	40H or 10H	Write	WA	WD
Block Erase and Word Write Suspend	1	5	Write	Х	вон			
Block Erase and Word Write Resume	1	5	Write	Х	D0H			
Set Block Lock-Bit	2	7	Write	BA	60H	Write	BA	01H
Set Permanent Lock-Bit	2	7	Write	Х	60H	Write	Х	F1H
Clear Block Lock-Bit	2	8	Write	Х	60H	Write	Х	DOH

NOTES:

- 1. Bus operations are defined in Table 3.
- 2. X = Any valid address within the device.
 - IA = Identifier Code Address: see Figure 4.
 - BA = Address within the block being erased or locked.
 - WA = Address of memory location to be written.
- 3. SRD = Data read from status register. See Table 7 for a description of the status register bits.
 - WD = Data to be written at location WA. Data is latched on the rising edge of WE# or CE# (whichever goes high first).
 - ID = Data read from identifier codes.
- 4. Following the Read Identifier Codes command, read operations access manufacture, device, block lock, and permanent lock codes. See Section 4.2 for read identifier code data.
- 5. If the block is locked, WP# must be at V_{IH} or RP# must be at V_{IH} to enable block erase or word write operations. Attempts to issue a block erase or word write to a locked block while WP# is V_{IH} or RP# is V_{IH}.
- 6. Either 40H or 10H are recognized by the WSM as the word write setup.
- 7. If the permanent lock-bit is set, WP# must be at V_{IH} or RP# must be at V_{IH} to set a block lock-bit. RP# must be at V_{IH} to set the permanent lock-bit. If the permanent lock-bit is set, a block lock-bit cannot be set. Once the permanent lock-bit is set, permanent lock-bit reset is unable.
- 8. If the permanent lock-bit is set, clear block lock-bits operation is unable. The clear block lock-bits operation simultaneously clears all block lock-bits. If the permanent lock-bit is not set, the Clear Block Lock-Bits command can be done while WP# is V_{IH} or RP# is V_H.
- 9. Commands other than those shown above are reserved by SHARP for future device implementations and should not be used.



4.1 Read Array Command

Upon initial device power-up and after exit from deep power-down mode, the device defaults to read array mode. This operation is also initiated by writing the Read Array command. The device remains enabled for reads until another command is written. Once the internal WSM has started a block erase, word write or lock-bit configuration, the device will not recognize the Read Array command until the WSM completes its operation unless the WSM is suspended via an Erase Suspend or Word Write Suspend command. The Read Array command functions independently of the V_{PP} voltage and RP# can be V_{IH} or V_{HH}.

4.2 Read Identifier Codes Command

The identifier code operation is initiated by writing the Read Identifier Codes command. Following the command write, read cycles from addresses shown in Figure 4 retrieve the manufacture, device, block lock configuration and permanent lock configuration codes (see Table 5 for identifier code values). To terminate the operation, write another valid command. Like the Read Array command, the Read Identifier Codes command functions independently of the V_{PP} voltage and RP# can be V_{IH} or V_{HH}. Following the Read Identifier Codes command, the following information can be read:

Table 5. Identifier Codes

Code	Address	Data
Manufacture Code	00000H	00B0H
Device Code	00001H	0050H
Block Lock Configuration	XX002H ⁽¹⁾	
·Unlocked		DQ ₀ =0
·Locked		DQ ₀ =1
·Reserved for future enhancement		DQ ₁₋₁₅
Permanent Lock Configuration	00003H	
·Unlocked		DQ ₀ =0
·Locked		DQ ₀ =1
·Reserved for future enhancement		DQ ₁₋₁₅

NOTES:

- X selects the specific block lock configuration code to be read. See Figure 4 for the device identifier code memory map.
- Block lock status and permanent lock status are output by DQ₀. DQ₁-DQ₁₅ are reserved for future enhancement.

4.3 Read Status Register Command

The status register may be read to determine when a block erase, word write, or lock-bit configuration is complete and whether the operation completed successfully. It may be read at any time by writing the Read Status Register command. After writing this command, all subsequent read operations output data from the status register until another valid command is written. The status register contents are latched on the falling edge of OE# or CE#, whichever occurs. OE# or CE# must toggle to V_{IH} before further reads to update the status register latch. The Read Status Register command functions independently of the V_{PP} voltage. RP# can be V_{IH} or V_{HH} .

4.4 Clear Status Register Command

Status register bits SR.5, SR.4, SR.3, and SR.1 are set to "1"s by the WSM and can only be reset by the Clear Status Register command. These bits indicate various failure conditions (see Table 7). By allowing system software to reset these bits, several operations (such as cumulatively erasing or locking multiple blocks or writing several words in sequence) may be performed. The status register may be polled to determine if an error occurred during the sequence.

To clear the status register, the Clear Status Register command (50H) is written. It functions independently of the applied $V_{\rm pp}$ voltage. RP# can be $V_{\rm IH}$ or $V_{\rm HH}$. This command is not functional during block erase or word write suspend modes.

4.5 Block Erase Command

Erase is executed one block at a time and initiated by a two-cycle command. A block erase setup is first written, followed by an block erase confirm. This command sequence requires appropriate sequencing and an address within the block to be erased (erase changes all block data to FFH). Block preconditioning, erase, and verify are handled internally by the WSM (invisible to the system). After the two-cycle block erase sequence is written, the device automatically outputs status register data when read (see Figure 5). The CPU can detect block erase completion by analyzing the output data of the RY/BY# pin or status register bit SR.7.

When the block erase is complete, status register bit SR.5 should be checked. If a block erase error is detected, the status register should be cleared before system software attempts corrective actions. The CUI remains in read status register mode until a new command is issued.



This two-step command sequence of set-up followed by execution ensures that block contents are not accidentally erased. An invalid Block Erase command sequence will result in both status register bits SR.4 and SR.5 being set to"1". Also, reliable block erasure can only occur when $\rm V_{\rm CC} = \rm V_{\rm CC1/2/3/4}$ and $\rm V_{\rm PP} = \rm V_{\rm PPH1/2/3}.$ In the absence of this high voltage, block contents are protected against erasure. If block erase is attempted while $V_{PP} \le V_{PPLK}$, SR.3 and SR.5 will be set to "1". Successful block erase requires that the corresponding block lock-bit be cleared or, if set, that WP# = V_{IH} or $RP# = V_{HH}$. If block erase is attempted when the corresponding block lock-bit is set and WP# = V, and RP# = V_{III}, SR.1 and SR.5 will be set to "1". Once permanent lock-bit is set, the blocks which have been set block lock-bit are unable to erase forever. Block erase operations with V_{IH} < RP# < V_{HH} produce spurious results and should not be attempted.

4.6 Word Write Command

Word write is executed by a two-cycle command sequence. Word write setup (standard 40H or alternate 10H) is written, followed by a second write that specifies the address and data (latched on the rising edge of WE#). The WSM then takes over, controlling the word write and write verify algorithms internally. After the word write sequence is written, the device automatically outputs status register data when read (see Figure 6). The CPU can detect the completion of the word write event by analyzing the RY/BY# pin or status register bit SR.7.

When word write is complete, status register bit SR.4 should be checked. If word write error is detected, the status register should be cleared. The internal WSM verify only detects errors for "1"s that do not successfully write to "0"s. The CUI remains in read status register mode until it receives another command.

Reliable word writes can only occur when $V_{\rm cc} = V_{\rm CC1/2J}$ and $V_{\rm pp} = V_{\rm ppH1/2J3}$. In the absence of this high voltage, memory contents are protected against word writes. If word write is attempted while $V_{\rm pp} \leq V_{\rm ppLK}$, status register bits SR.3 and SR.4 will be set to "1". Successful word write requires that the corresponding block lock-bit be cleared or, if set, that WP# = $V_{\rm H}$ or RP# = $V_{\rm HH}$. If word write is attempted when the corresponding block lock-bit is set and WP# = $V_{\rm LL}$ and RP# = $V_{\rm HH}$, SR.1 and SR.4 will be set to "1". Once permanent lock-bit is set, the blocks which have been set block lock-bit are unable to write forever. Word write operations with $V_{\rm H}$ < RP# < $V_{\rm HH}$ produce spurious results and should not be attempted.

4.7 Block Erase Suspend Command

The Block Erase Suspend command allows blockerase interruption to read or word-write data in another block of memory. Once the block-erase process starts, writing the Block Erase Suspend command requests that the WSM suspend the block erase sequence at a predetermined point in the algorithm. The device outputs status register data when read after the Block Erase Suspend command is written. Polling status register bits SR.7 and SR.6 can determine when the block erase operation has been suspended (both will be set to "1"). RY/BY# will also transition to $V_{\rm OH}$. Specification $t_{\rm WHRH2}$ defines the block erase suspend latency.

At this point, a Read Array command can be written to read data from blocks other than that which is suspended. A Word Write command sequence can also be issued during erase suspend to program data in other blocks. Using the Word Write Suspend command (see Section 4.8), a word write operation can also be suspended. During a word write operation with block erase suspended, status register bit SR.7 will return to "0" and the RY/BY# output will transition to V_{OL} . However, SR.6 will remain "1" to indicate block erase suspend status.

The only other valid commands while block erase is suspended are Read Status Register and Block Erase Resume. After a Block Erase Resume command is written to the flash memory, the WSM will continue the block erase process. Status register bits SR.6 and SR.7 will automatically clear and RY/BY# will return to Vor. After the Erase Resume command is written, the device automatically outputs status register data when read (see Figure 7). V_{PP} must remain at $V_{PPH1/2/3}$ (the same V_{PP} level used for block erase) while block erase is suspended. RP# must also remain at V_{IH} or V_{HH} (the same RP# level used for block erase). WP# must also remain at V_{IL} or V_{IH} (the same WP# level used for block erase). Block erase cannot resume until word write operations initiated during block erase suspend have completed.

4.8 Word Write Suspend Command

The Word Write Suspend command allows word write interruption to read data in other flash memory locations. Once the word write process starts, writing the Word Write Suspend command requests that the WSM suspend the word write sequence at a predetermined point in the algorithm. The device continues to output status register data when read after the Word Write Suspend command is written. Polling status register bits SR.7 and SR.2 can determine when the word write operation has been suspended (both will be set



to "1"). RY/BY# will also transition to $\rm V_{OH}$. Specification $\rm t_{WHBH1}$ defines the word write suspend latency.

At this point, a Read Array command can be written to read data from locations other than that which is suspended. The only other valid commands while word write is suspended are Read Status Register and Word Write Resume. After Word Write Resume command is written to the flash memory, the WSM will continue the word write process. Status register bits SR.2 and SR.7 will automatically clear and RY/BY# will return to V_{oL} . After the Word Write Resume command is written, the device automatically outputs status register data when read (see Figure 8). $V_{\rm pp}$ must remain at $V_{PPH1/2/3}$ (the same V_{PP} level used for word write) while in word write suspend mode. RP# must also remain at V_{H} or V_{HH} (the same RP# level used for word write). WP# must also remain at V_{II} or V_{II} (the same WP# level used for word write).

4.9 Set Block and Permanent Lock-Bit Commands

The combination of the software command sequence and hardware WP#, RP# pin provides most flexible block lock (write protection) capability. The word write/block erase operation is restricted by the status of block lock-bit, WP# pin, RP# pin and permanent lock-bit. The status of WP# pin, RP# pin and permanent lock-bit restricts the set block bit. When the permanent lock-bit has not been set, and when WP# = V_{IH} , or RP# = V_{HH} , the block lock bit can be set with the status of the RP#pin. When RP# = V_{HH} , the permanent lock-bit can be set with the permanent lock-bit set command. After the permanent lock-bit has been set, the write/erase operation to the block lock bit can never be accepted. Please refer to the Table 6 for the hardware and the software write protection.

Set block lock-bit and permanent lock-bit are executed by a two-cycle command sequence. The set block or permanent lock-bit setup along with appropriate block or device address is written followed by either the set block lock-bit confirm (and an address within the block to be locked) or the set permanent lock-bit confirm (and any device address). The WSM then controls the set lock-bit algorithm. After the sequence is written, the device automatically outputs status register data when read (see Figure 9). The CPU can detect the completion of the set lock-bit event by analyzing the RY/BY# pin output or status register bit SR.7.

When the set lock-bit operation is complete, status register bit SR.4 should be checked. If an error is detected, the status register should be cleared. The CUI will remain in read status register mode until a new

command is issued.

This two-step sequence of set-up followed by execution ensures that lock-bits are not accidentally set. An invalid Set Block or Permanent Lock-Bit command will result in status register bits SR.4 and SR.5 being set to "1". Also, reliable operations occur only when $V_{\rm CC} = V_{\rm CC1/2/3/4}$ and $V_{\rm PP} = V_{\rm PPH1/2/3}$. In the absence of this high voltage, lock-bit contents are protected against alteration.

A successful set block lock-bit operation requires that the permanent lock-bit be cleared and WP# = V_{HH} or RP# = V_{HH} . If it is attempted with the permanent lock-bit set, SR.1 and SR.4 will be set to "1" and the operation will fail. Set block lock-bit operations while V_{HH} = V_{HH} produce spurious results and should not be attempted. A successful set permanent lock-bit operation requires that RP# = V_{HH} . If it is attempted with RP# = V_{HH} , SR.1 and SR.4 will be set to "1" and the operation will fail. Set permanent lock-bit operations with V_{HH} = V_{HH} produce spurious results and should not be attempted.

4.10 Clear Block Lock-Bits Command

All set block lock-bits are cleared in parallel via the Clear Block Lock-Bits command. With the permanent lock-bit not set and WP# = $V_{\rm IH}$ or RP# = $V_{\rm HH}$, block lock-bits can be cleared using the Clear Block Lock-Bits command. If the permanent lock-bit is set, clear block lock-bits operation is unable. See Table 6 for a summary of hardware and software write protection options.

Clear block lock-bits option is executed by a two-cycle command sequence. A clear block lock-bits setup is first written. After the command is written, the device automatically outputs status register data when read (see Figure 10). The CPU can detect completion of the clear block lock-bits event by analyzing the RY/BY# pin output or status register bit SR.7.

When the operation is complete, status register bit SR.5 should be checked. If a clear block lock-bit error is detected, the status register should be cleared. The CUI will remain in read status register mode until another command is issued.

This two-step sequence of set-up followed by execution ensures that block lock-bits are not accidentally cleared. An invalid Clear Block Lock-Bits command sequence will result in status register bits SR.4 and SR.5 being set to "1". Also, a reliable clear block lock-bits operation can only occur when $V_{\rm CC} = V_{\rm CC1/2/3/4}$ and $V_{\rm PP} = V_{\rm PPH1/2/3}$. In a clear block lock-bits operation is attempted while $V_{\rm PPLK}$, SR.3 and SR.5 will be set



to "1". In the absence of this high voltage, the block lock-bits content are protected against alteration. A successful clear block lock-bits operation requires that the permanent lock-bit is not set and WP# = $V_{\rm IH}$ or RP# = $V_{\rm HH}$. If it is attempted with the permanent lock-bit set or WP# = $V_{\rm IL}$ and RP# = $V_{\rm IH}$, SR.1 and SR.5 will be set to "1" and the operation will fail. A clear block lock-bits operation with $V_{\rm IH}$ < RP# < $V_{\rm HH}$ produce spurious results and should not be attempted.

If a clear block lock-bits operation is aborted due to V_{PP} or V_{CC} transitioning out of valid range or WP# or RP# active transition, block lock-bit values are left in an undetermined state. A repeat of clear block lock-bits is required to initialize block lock-bit contents to known values. Once the permanent lock-bit is set, it cannot be cleared.



Table 6. Write Protection Alternatives

Operation	Permanent Lock-Bit	Block Lock-Bit	WP#	RP#	Effect
	×	0	Х	VIH OF VHH	Block Erase and Word Write Enabled
)			VıH	Vih or Vih	Block Lock-Bit Override. Block Erase and Word Write Enabled
Word Write or	0			V _{НН}	Block Lock-Bit Override. Block Erase and Word Write Enabled
Block Erase		1	VıL	ViH	Block is Locked. Block Erase and Word Write Disabled
	1		X	Х	Permanent Lock-Bit is set. Block Erase and Word Write Disabled
			Vıн	VIH OF VHH	Set Block Lock-Bit Enabled
Set Block	Set Block 0	v	ViL	V _{нн}	Set Block Lock-Bit Enabled
Lock-Bit		X	VIL	Vін	Set Block Lock-Bit Disabled
	1		Х	х	Permanent Lock-Bit is set. Set Block Lock-Bit Disabled
Set Permanent	V		V	V _{нн}	Set Permanent Lock-Bit Enabled
Lock-Bit	X	X	X	ViH	Set Permanent Lock-Bit Disabled
			ViH	V _{IH} or V _{HH}	Clear Block Lock-Bits Enabled
Clear Block	0		VIL	V _{нн}	Clear Block Lock-Bits Enabled
Lock-Bits		X	ViL	V _{IH}	Clear Block Lock-Bits Disabled
	1		х	х	Permanent Lock-Bit is set. Clear Block Lock-Bits Disabled

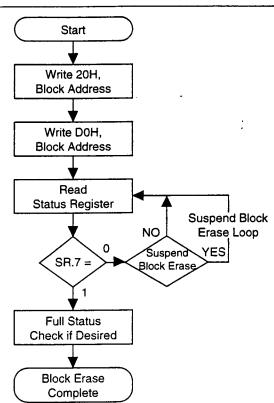


Table 7. Status Register Definition

WSMS	ESS	ECLBS	BWSLBS	VPPS	BWSS	DPS	R
7	6	5	4	3	2	1	0

SR.7 =	WRITE STATE MACHINE STATUS 1 = Ready 0 = Busy	NOTES: Check RY/BY# or SR.7 to determine block erase, word write, or lock-bit configuration completion. SR.6-0 are invalid while SR.7 = "0".
SR.6 =	ERASE SUSPEND STATUS 1 = Block Erase Suspended 0 = Block Erase in Progress/Completed	If both SR.5 and SR.4 are "1"s after a block erase or lock-bit configuration attempt, an improper command sequence was entered.
SR.5 =	ERASE AND CLEAR LOCK-BITS STATUS 1 = Error in Block Erasure or Clear Lock-Bits 0 = Successful Block Erase or Clear Lock-Bits WORD WRITE AND SET LOCK-BIT	SR.3 does not provide a continuous indication of V_{pp} level. The WSM interrogates and indicates the V_{pp} level only after Block Erase, Word Write, Set Block/Permanent Lock-Bit, or Clear Block Lock-Bits command sequences. SR.3 is not guaranteed to reports accurate feedback only when $V_{pp} = V_{pPH1/2/3}$.
	STATUS 1 = Error in Word Write or Set Permanent/Block Lock-Bit 0 = Successful Word Write or Set Permanent/Block Lock-Bit	SR.1 does not provide a continuous indication of permanent and block lock-bit values. The WSM interrogates the permanent lock-bit, block lock-bit, WP# and RP# only after Block Erase, Word Write, or Lock-Bit configuration command sequences. It informs the system, depending on
SR.3 =	V_{pp} STATUS 1 = V_{pp} Low Detect, Operation Abort 0 = V_{pp} OK	the attempted operation, if the block lock-bit is set, permanent lock-bit is set, and/or WP# is not V _H , RP# is not V _H . Reading the block lock and permanent lock configuration codes after writing the Read Identifier Codes
SR.2 =	WORD WRITE SUSPEND STATUS 1 = Word Write Suspended 0 = Word Write in Progress/Completed	command indicates permanent and block lock-bit status. SR.0 is reserved for future use and should be masked out
SR.1 =	DEVICE PROTECT STATUS 1 = Permanent Lock-Bit, Block Lock-Bit and/or WP#/RP# Lock Detected, Operation Abort 0 = Unlock	when polling the status register.
SR.0 =	RESERVED FOR FUTURE ENHANCEMENTS	





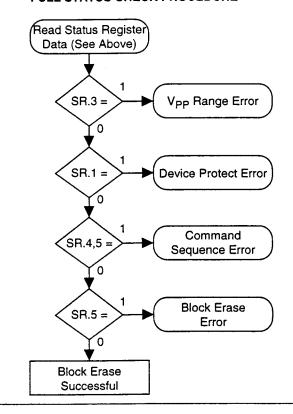
Bus Operation	Command	Comments			
Write	Erase Setup	Data = 20H Addr = Within Block to be Erased			
Write	Erase Confirm	Data = D0H Addr = Within Block to be Erased			
Read		Status Register Data			
Standby		Check SR.7 1=WSM Ready 0=WSM Busy			

Repeat for subsequent block erasures.

Full status check can be done after each block erase or after a sequence of block erasures.

Write FFH after the last operation to place device in read array mode.

FULL STATUS CHECK PROCEDURE



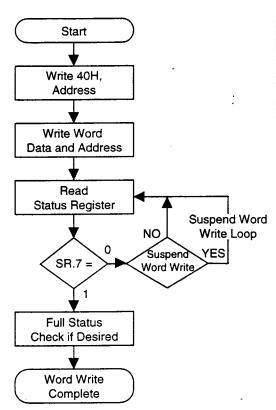
Bus Operation	Command	Comments
Standby		Check SR.3 1=V _{PP} Error Detect
Standby		Check SR.1 1 = Device Protect Detect RP#=V _{IH} , Block Lock-Bit is Set Only required for systems implementing lock-bit configuration
Standby		Check SR.4,5 Both 1 = Command Sequence Error
Standby		Check SR.5 1=Block Erase Error

SR.5, SR.4, SR.3 and SR.1 are only cleared by the Clear Status Register command in cases where multiple blocks are erased before full status is checked.

If error is detected, clear the Status Register before attempting retry or other error recovery.

Figure 5. Automated Block Erase Flowchart





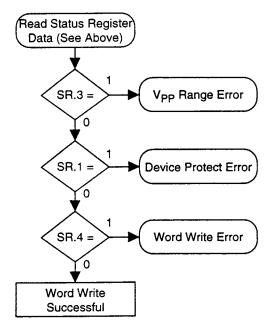
Bus Operation	Command	Comments			
Write Setup Word Write		Data=40H Addr=Location to Be Written			
Write	Word Write	Data = Data to Be Written Addr = Location to Be Written			
Read		Status Register Data			
Standby		Check SR.7 1 = WSM Ready 0 = WSM Busy			

Repeat for subsequent Word writes.

SR full status check can be done after each word write, or after a sequence of word writes.

Write FFH after the last word write operation to place device in read array mode.

FULL STATUS CHECK PROCEDURE



Bus Operation Command		Comments		
Standby		Check SR.3 1 = V _{PP} Error Detect		
Standby		Check SR.1 1 = Device Protect Detect RP#=V _{IH} , Block Lock-Bit is Set Only required for systems implementing lock-bit configuration		
Standby		Check SR.4 1 = Data Write Error		

SR.4, SR.3 and SR.1 are only cleared by the Clear Status Register command in cases where multiple locations are written before full status is checked.

If error is detected, clear the Status Register before attempting retry or other error recovery.

Figure 6. Automated Word Write Flowchart



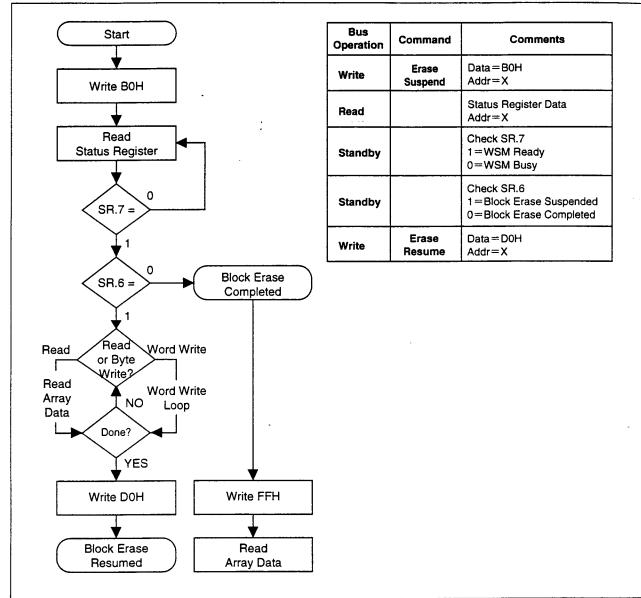


Figure 7. Block Erase Suspend/Resume Flowchart



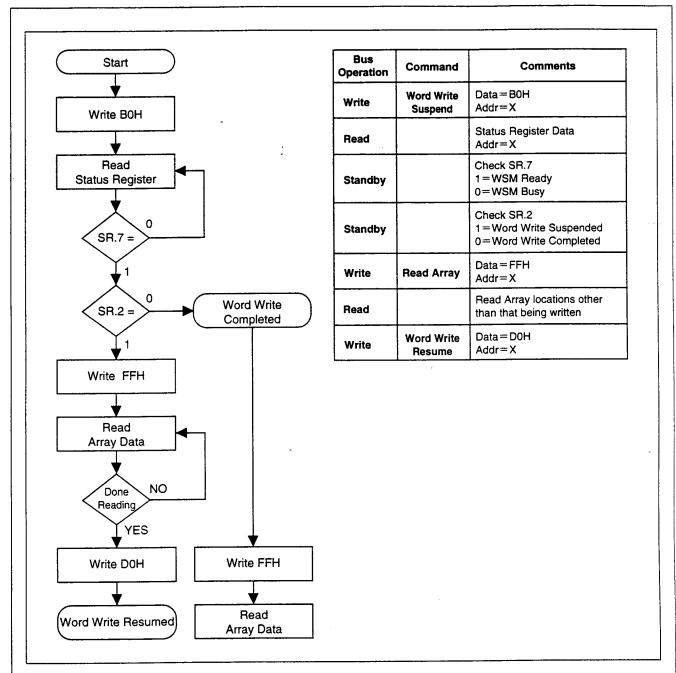
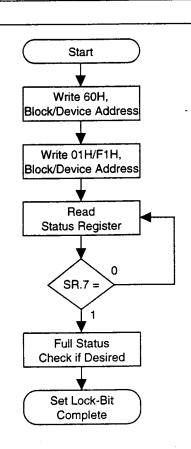


Figure 8. Word Write Suspend/Resume Flowchart





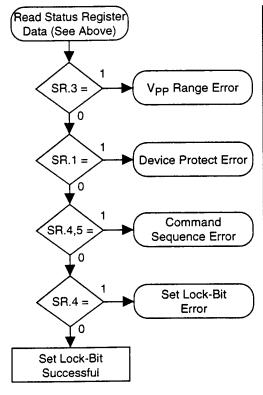
Bus Operation	Command	Comments				
Write	Set Block/ Permanent Lock-Bit Setup	Data=60H Addr=Block Address (Block), Device Address (Permanent)				
Write	Set Block/ Permanent Lock-Bit Confirm	Data = 01H (Block), F1H (Permanent) Addr = Block Address (Block), Device Address (Permanent)				
Read		Status Register Data				
Standby		Check SR.7 1=WSM Ready 0=WSM Busy				

Repeat for subsequent lock-bit set operations.

Full status check can be done after each lock-bit set operation or after a sequence of lock-bit set operations.

Write FFH after the last lock-bit set operation to place device in read array mode.

FULL STATUS CHECK PROCEDURE



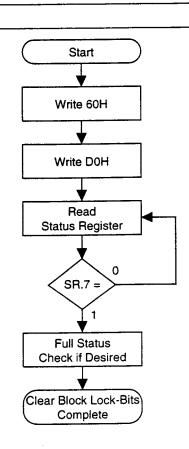
Bus Operation	Command	Comments
Standby		Check SR.3 1=V _{PP} Error Detect
Standby		Check SR.1 1 = Device Protect Detect RP#=V _{IH} (Set Permanent Lock-Bit Operation) WP#=V _{IL} and RP#=V _{IH} or Permanent Lock-Bit is Set (Set Block Lock-Bit Operation)
Standby		Check SR.4,5 Both 1=Command Sequence Error
Standby		Check SR.4 1 = Set Lock-Bit Error

SR.5, SR.4, SR.3 and SR.1 are only cleared by the Clear Status Register command in cases where multiple lock-bits are set before full status is checked.

If error is detected, clear the Status Register before attempting retry or other error recovery.

Figure 9. Set Block and Permanent Lock-Bit Flowchart

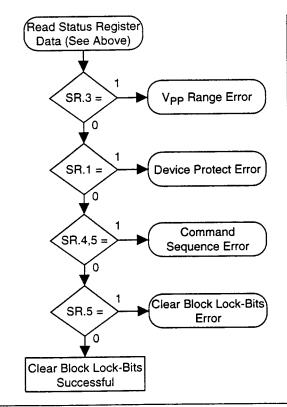




Bus Operation	Command	Comments		
Write Clear Block Lock-Bits Setup		Data=60H Addr=X		
Write	Clear Block Lock-Bits Confirm	Data=D0H Addr=X		
Read		Status Register Data		
Standby		Check SR.7 1=WSM Ready 0=WSM Busy		

Write FFH after the Clear Block Lock-Bits operation to place device in read array mode.

FULL STATUS CHECK PROCEDURE



Bus Operation	Command	Comments
Standby		Check SR.3 1=V _{PP} Error Detect
Standby		Check SR.1 1 = Device Protect Detect WP#=V _{IL} and RP#=V _{IH} or Permanent Lock-Bit is Set
Standby		Check SR.4,5 Both 1 = Command Sequence Error
Standby		Check SR.5 1=Clear Block Lock-Bits Error

SR.5, SR.4, SR.3 and SR.1 are only cleared by the Clear Status Register command.

Figure 10. Clear Block Lock-Bits Flowchart

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5.0 DESIGN CONSIDERATIONS

5.1 Three-Line Output Control

The device will often be used in large memory arrays. SHARP provides three control inputs to accommodate multiple memory connections. Three-line control provides for:

- a. Lowest possible memory power dissipation.
- b. Complete assurance that data bus contention will not occur.

To use these control inputs efficiently, an address decoder should enable CE# while OE# should be connected to all memory devices and the system's READ# control line. This assures that only selected memory devices have active outputs while deselected memory devices are in standby mode. RP# should be connected to the system POWERGOOD signal to prevent unintended writes during system power transitions. POWERGOOD should also toggle during system reset.

5.2 RY/BY# and Block Erase, Word Write, and Lock-Bit Configuration Polling

RY/BY# is a full CMOS output that provides a hardware method of detecting block erase, word write and lock-bit configuration completion. It transitions low after block erase, word write, or lock-bit configuration commands and returns to V_{OH} when the WSM has finished executing the internal algorithm.

RY/BY# can be connected to an interrupt input of the system CPU or controller. It is active at all times. RY/BY# is also V_{OH} when the device is in block erase suspend (with word write inactive), word write suspend or deep power-down modes.

5.3 Power Supply Decoupling

Flash memory power switching characteristics require careful device decoupling. System designers are interested in three supply current issues; standby current levels, active current levels and transient peaks produced by falling and rising edges of CE# and OE#. Transient current magnitudes depend on the device outputs' capacitive and inductive loading. Two-line control and proper decoupling capacitor selection will suppress transient voltage peaks. Each device should have a 0.1 μF ceramic capacitor connected between its V_{cc} and GND and between its V_{pp} and GND. These high-frequency, low inductance capacitors should be placed as close as possible to package leads. Additionally, for every eight devices, a 4.7 μF electrolytic capacitor should be placed at the array's power sup-

ply connection between $V_{\rm cc}$ and GND. The bulk capacitor will overcome voltage slumps caused by PC board trace inductance.

5.4 V_{PP} Trace on Printed Circuit Boards

Updating flash memories that reside in the target system requires that the printed circuit board designer pay attention to the V_{pp} power supply trace. The V_{pp} pin supplies the memory cell current for word writing and block erasing. Use similar trace widths and layout considerations given to the V_{cc} power bus. Adequate V_{pp} supply traces and decoupling will decrease V_{pp} voltage spikes and overshoots.

5.5 V_{cc}, V_{pp}, RP# Transitions

Block erase, word write and lock-bit configuration are not guaranteed if V_{PP} falls outside of a valid $V_{CC1/2/3/4}$ range, V_{CC} falls outside of a valid $V_{CC1/2/3/4}$ range, or RP# \neq V_{IH} or V_{HH} . If V_{PP} error is detected, status register bit SR.3 is set to "1" along with SR.4 or SR.5, depending on the attempted operation. If RP# transitions to V_{IL} during block erase, word write, or lock-bit configuration, RY/BY# will remain low until the reset operation is complete. Then, the operation will abort and the device will enter deep power-down. The aborted operation may leave data partially altered. Therefore, the command sequence must be repeated after normal operation is restored. Device power-off or RP# transitions to V_{IL} clear the status register.

The CUI latches commands issued by system software and is not altered by V_{PP} or CE# transitions or WSM actions. Its state is read array mode upon power-up, after exit from deep power-down or after V_{CC} transitions below V_{LKO} .

After block erase, word write, or lock-bit configuration, even after V_{PP} transitions down to V_{PPLK} , the CUI must be placed in read array mode via the Read Array command if subsequent access to the memory array is desired.

5.6 Power-Up/Down Protection

The device is designed to offer protection against accidental block erasure, word writing, or lock-bit configuration during power transitions. Upon power-up, the device is indifferent as to which power supply (V_{PP} or V_{CC}) powers-up first. Internal circuitry resets the CUI to read array mode at power-up.

A system designer must guard against spurious writes for $V_{\rm CC}$ voltages above $V_{\rm LKO}$ when $V_{\rm PP}$ is active. Since both WE# and CE# must be low for a command write, driving either to $V_{\rm IH}$ will inhibit writes. The CUI's two-

step command sequence architecture provides added level of protection against data alteration.

In-system block lock and unlock capability prevents inadvertent data alteration. The device is disabled while RP# = V_{\parallel} regardless of its control inputs state.

5.7 Power Dissipation

When designing portable systems, designers must consider battery power consumption not only during device operation, but also for data retention during system idle time. Flash memory's nonvolatility increases usable battery life because data is retained when system power is removed.

In addition, deep power-down mode ensures extremely low power consumption even when system power is applied. For example, portable computing products and other power sensitive applications that use an array of devices for solid-state storage can consume negligible power by lowering RP# to $V_{\rm IL}$ standby or sleep modes. If access is again needed, the devices can be read following the $t_{\rm PHQV}$ and $t_{\rm PHWL}$ wake-up cycles required after RP# is first raised to $V_{\rm IH}$. See AC Characteristics — Read Only and Write Operations and Figures 15, 16 and 17 for more information.



6.0 ELECTRICAL SPECIFICATIONS

6.1 Absolute Maximum Ratings*

<Operating Temperature> **Extended Temperature Products** During Read, Block Erase, Word Write, and Lock-Bit Configuration -40°C to + 85°C(1) Temperature under Bias-40°C to + 85°C <Storage Temperature> - 65°C to + 125°C <Voltage On Any Pin> except V_{CC} , V_{PP} , and RP#-2.0V to + 7.0V (2) V_{cc} Supply Voltage-2.0V to + 7.0V (2) V_{PP} Update Voltage during Block Erase, Word Write, and Lock-Bit Configuration -2.0V to + 14.0V (2,3) RP# Voltage with Respect to **GND during Lock-Bit** Configuration Operations -2.0V to + 14.0V (2.3) <Output Short Circuit Current> 100 mA (4)

NOTICE: Revised information will be published when the product is available. Verify with your local SHARP Sales office that you have the latest datasheet before finalizing a design.

*WARNING: Stressing the device beyond the "Absolute Maximum Ratings" may cause permanent damage. These are stress ratings only. Operation beyond the "Operating Conditions" is not recommended and extended exposure beyond the "Operating Conditions" may affect device reliability.

NOTES:

- 1. Operating temperature is for commercial product defined by this specification.
- 2. All specified voltages are with respect to GND. Minimum DC voltage is - 0.5V on input/output pins and - 0.2V on V_{cc} and V_{pp} pins. During transitions, this level may undershoot to - 2.0V for periods < 20 ns. Maximum DC voltage on input/output pins and V_{cc} is V_{cc} + 0.5V which, during transitions, may overshoot to V_{cc} + 2.0V for periods < 20 ns. 3. Maximum DC voltage on V_{PP} and RP# may
- overshoot to +14.0V for periods < 20 ns.
- 4. Output shorted for no more than one second. No more than one output shorted at a time.

6.2 Operating Conditions

Temperature and V_{cc} Operating Conditions

Symbol	Parameter	Notes	Min.	Max.	Unit	Test Condition
TA	Operating Temperature		-40	+85	Ĉ	Ambient Temperature
	Extended Temperature Products					
V _{CC1}	V _{CC} Supply Voltage (2.7V-3.6V)		2.7	3.6	V	
V _{CC2}	Vcc Supply Voltage (3.3V±0.3V)		3.0	3.6	V	
V _{CC3}	V _{CC} Supply Voltage (5.0V±0.25V)		4.75	5.25	V	
V _{CC4}	Vcc Supply Voltage (5.0V±0.5V)		4.50	5.50	V	

6.2.1 Capacitance (1)

 $T_A = + 25$ °C, f = 1 MHz

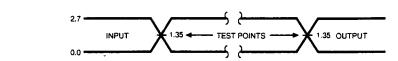
Symbol	Parameter	Typ.	Max.	Unit	Condition
Cin	Input Capacitance	7	10	pF	V _{IN} =0.0V
Соџт	Output Capacitance	9	12	pF	V _{out} =0.0V

NOTES:

1. Sampled, not 100% tested.

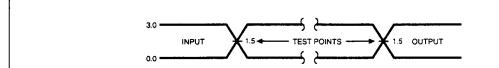


6.2.2 AC Input/Output Test Conditions



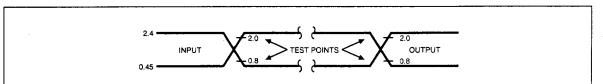
AC test inputs are driven at 2.7V for a Logic "1" and 0.0V for a Logic "0." Input timing begins, and output timing ends, at 1.35V. Input rise and fall times (10% to 90%) < 10 ns.

Figure 11. Transient Input/Output Reference Waveform for 2.7V ≤ V_{cc} < 3.0V



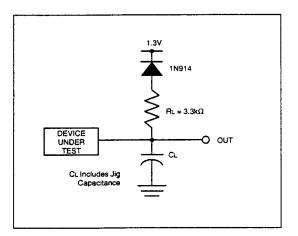
AC test inputs are driven at 3.0V for a Logic "1" and 0.0V for a Logic "0." Input timing begins, and output timing ends, at 1.5V. Input rise and fall times (10% to 90%) < 10 ns.

Figure 12. Transient Input/Output Reference Waveform for $3.0V \le V_{cc} \le 3.6V$ and $4.75V \le V_{cc} \le 5.25V$ (High Speed Testing Configuration)



AC test inputs are driven at V_{OH} (2.4 V_{TTL}) for a Logic "1" and V_{OL} (0.45 V_{TTL}) for a Logic "0." Input timing begins at V_{IH} (2.0 V_{TTL}) and V_{IL} (0.8 V_{TTL}). Output timing ends at V_{IH} and V_{IL} . Input rise and fall times (10% to 90%) < 10 ns

Figure 13. Transient Input/Output Reference Waveform for $4.5V \le V_{cc} \le 5.5V$ (Standard Testing Configuration)



Test Configuration Capacitance Loading Value

Test Configuration	C _L (pF)
V _{CC} =2.7V-3.6V	50
V _{CC} =5V±0.25V	30
V _{CC} =5V±0.5V	100

Figure 14. Transient Equivalent Testing Load Circuit

6.2.3 DC Characteristics

DC Characteristics

Typ.	.7V-3.6V	Тур.	V±0.5V Max. ±1 ±10 100 2 16 50	MA μA μA μA μA mA mA	Test Conditions Vcc=VccMax, ViN=Vcc or GND Vcc=VccMax, Vout=Vcc or GND CMOS inputs Vcc=Vcc Max CE#=RP#=Vcc±0.2V TTL inputs Vcc=VccMax CE#=RP#=ViH RP#=GND±0.2V lout(RY/BY#)=0mA CMOS inputs Vcc=VccMax, CE#=GND f=5MHz(3.3V, 2.7V), 8MHz(5V) lout=OmA TTL inputs Vcc=VccMax, CE#=GND f=5MHz(3.3V, 2.7V), 8MHz(5V) lout=OmA
	±0.5 100 2 12 25 30		±10 100 2 16 50	μA μA mA μA	V _{IN} =V _{CC} or GND V _{CC} =V _{CC} Max, V _{OUT} =V _{CC} or GND CMOS inputs V _{CC} =V _{CC} Max CE#=RP#=V _{CC} ±0.2V TTL inputs V _{CC} =V _{CC} Max CE#=RP#=V _{IH} RP#=GND±0.2V Iout(RY/BY#)=0mA CMOS inputs V _{CC} =V _{CC} Max, CE#=GND f=5MHz(3.3V, 2.7V), 8MHz(5V) Iout=0mA TTL inputs V _{CC} =V _{CC} Max, CE#=GND f=5MHz(3.3V, 2.7V),
	100 2 12 25 30		100	μA mA μA mA	Vcc=VccMax, VouT=Vcc or GND CMOS inputs Vcc=Vcc Max CE#=RP#=Vcc±0.2V TTL inputs Vcc=VccMax CE#=RP#=VIH RP#=GND±0.2V IouT(RY/BY#)=0mA CMOS inputs Vcc=VccMax, CE#=GND f=5MHz(3.3V, 2.7V), 8MHz(5V) IouT=0mA TTL inputs Vcc=VccMax, CE#=GND f=5MHz(3.3V, 2.7V),
	100 2 12 25 30		100	μA mA μA mA	Vout=Vcc or GND CMOS inputs Vcc=Vcc Max CE#=RP#=Vcc±0.2V TTL inputs Vcc=VccMax CE#=RP#=VIH RP#=GND±0.2V Iout(RY/BY#)=0mA CMOS inputs Vcc=VccMax, CE#=GND f=5MHz(3.3V, 2.7V), 8MHz(5V) Iout=0mA TTL inputs Vcc=VccMax, CE#=GND f=5MHz(3.3V, 2.7V),
	2 12 25 30		16 50	mA μA mA	CMOS inputs Vcc=Vcc Max CE#=RP#=Vcc±0.2V TTL inputs Vcc=VccMax CE#=RP#=V _{IH} RP#=GND±0.2V lout(RY/BY#)=0mA CMOS inputs Vcc=VccMax, CE#=GND f=5MHz(3.3V, 2.7V), 8MHz(5V) lout=0mA TTL inputs Vcc=VccMax, CE#=GND f=5MHz(3.3V, 2.7V),
	2 12 25 30		16 50	mA μA mA	Vcc=Vcc Max CE#=RP#=Vcc±0.2V TTL inputs Vcc=VccMax CE#=RP#=V _{IH} RP#=GND±0.2V tout(RY/BY#)=0mA CMOS inputs Vcc=VccMax, CE#=GND f=5MHz(3.3V, 2.7V), 8MHz(5V) lout=0mA TTL inputs Vcc=VccMax, CE#=GND f=5MHz(3.3V, 2.7V),
	12 25 30		16	μA mA	CE#=RP#=Vcc±0.2V TTL inputs Vcc=VccMax CE#=RP#=ViH RP#=GND±0.2V tout(RY/BY#)=0mA CMOS inputs Vcc=VccMax, CE#=GND f=5MHz(3.3V, 2.7V), 8MHz(5V) lout=0mA TTL inputs Vcc=VccMax, CE#=GND f=5MHz(3.3V, 2.7V),
	12 25 30		16	μA mA	TTL inputs V _{CC} =V _{CC} Max CE#=RP#=V _{IH} RP#=GND±0.2V lout(RY/BY#)=0mA CMOS inputs V _{CC} =V _{CC} Max, CE#=GND f=5MHz(3.3V, 2.7V), 8MHz(5V) lout=0mA TTL inputs V _{CC} =V _{CC} Max, CE#=GND f=5MHz(3.3V, 2.7V),
	12 25 30		16	μA mA	Vcc=VccMax CE#=RP#=VIH RP#=GND±0.2V IouT(RY/BY#)=0mA CMOS inputs Vcc=VccMax, CE#=GND f=5MHz(3.3V, 2.7V), 8MHz(5V) IouT=0mA TTL inputs Vcc=VccMax, CE#=GND f=5MHz(3.3V, 2.7V),
	30		50	mA	CE#=RP#=V _{IH} RP#=GND±0.2V louT(RY/BY#)=0mA CMOS inputs V _{CC} =V _{CC} Max, CE#=GND f=5MHz(3.3V, 2.7V), 8MHz(5V) louT=0mA TTL inputs V _{CC} =V _{CC} Max, CE#=GND f=5MHz(3.3V, 2.7V),
	30		50	mA	RP#=GND±0.2V lout(RY/BY#)=0mA CMOS inputs Vcc=VccMax, CE#=GND f=5MHz(3.3V, 2.7V), 8MHz(5V) lout=0mA TTL inputs Vcc=VccMax, CE#=GND f=5MHz(3.3V, 2.7V),
	30		50	mA	Iout(RY/BY#)=0mA CMOS inputs Vcc=VccMax, CE#=GND f=5MHz(3.3V, 2.7V), 8MHz(5V) Iout=0mA TTL inputs Vcc=VccMax, CE#=GND f=5MHz(3.3V, 2.7V),
	30				CMOS inputs V _{CC} =V _{CC} Max, CE#=GND f=5MHz(3.3V, 2.7V), 8MHz(5V) I _{OUT} =0mA TTL inputs V _{CC} =V _{CC} Max, CE#=GND f=5MHz(3.3V, 2.7V),
·····	30				V _{CC} =V _{CC} Max, CE#=GND f=5MHz(3.3V, 2.7V), 8MHz(5V) l _{OUT} =0mA TTL inputs V _{CC} =V _{CC} Max, CE#=GND f=5MHz(3.3V, 2.7V),
			65	mA	f=5MHz(3.3V, 2.7V), 8MHz(5V) lout=0mA TTL inputs Vcc=VccMax, CE#=GND f=5MHz(3.3V, 2.7V),
			65	mA	8MHz(5V) lout=0mA TTL inputs Vcc=VccMax, CE#=GND f=5MHz(3.3V, 2.7V),
			65	mA	I _{OUT} =0mA TTL inputs V _{CC} =V _{CC} Max, CE#=GND f=5MHz(3.3V, 2.7V),
<u> </u>			65	mA	TTL inputs V _{CC} =V _{CC} Max, CE#=GND f=5MHz(3.3V, 2.7V),
			65	mA	V _{CC} =V _{CC} Max, CE#=GND f=5MHz(3.3V, 2.7V),
·····					f=5MHz(3.3V, 2.7V),
	1-	:			, , , , , , , , , , , , , , , , , , , ,
·····	ļ., <u>.</u>				8MHZ(5V)
				1	l
			<u> </u>		Ιουτ=0mA
	17		35	mA mA	V _{PP} =3.3V±0.3V
	12		30	mA mA	V _{PP} =5.0V±0.5V V _{PP} =12.0V±0.6V
	17	_	30	mA	Vpp=12.0V±0.0V Vpp=3.3V±0.3V
	17		30	mA	V _{PP} =5.0V±0.5V
	12		25	mA	V _{PP} =12.0V±0.6V
	6		10	mA	CE#=V _{IH}
			'		OE" VIII
	±15		±15	μА	V _{PP} ≤V _{CC}
	200		200		V _{PP} >V _{CC}
	5		5		RP#=GND±0.2V
	1		1	'	
	80			mA	V _{PP} =3.3V±0.3V
	80		80	mA	V _{PP} =5.0V±0.5V
	30		30	mA	V _{PP} =12.0V±0.6V
	40	_	_	mA	V _{PP} =3.3V±0.3V
	40		40	mA	V _{PP} =5.0V±0.5V
	30		30	mA	V _{PP} =12.0V±0.6V
	200		200	μΑ	Vpp=VppH1/2/3
	1	,			
	4,	200 5 80 80 30 40 40	200 5 80 – 80 30 40 – 40 30	200 200 5 5 80 - 80 80 30 30 40 - 40 40 30 30	200 200 μA 5 μA 5 μA 1 1 1 1 1 1 1 1 1

HAR

DC Characteristics (Continued)

A	D	Natas	Vcc=	=3.3V	Vcc	V _{CC} =5V		Test Conditions
Symbol	Parameter	Notes	Min.	Max.	Min.	Max.	Unit	rest Conditions
VIL	Input Low Voltage	7	-0.5	0.8	-0.5	0.8	V	
ViH	Input High Voltage	7	2.0	Vcc +0.5	2.0	V _{CC} +0.5	V	
Vol	Output Low Voltage	3,7		0.4		0.45	٧	V _{CC} =V _{CC} Min I _{OL} =5.8mA(V _{CC} =5V), I _{OL} =2.0mA(V _{CC} =3.3V)
V _{OH1}	Output High Voltage (TTL)	3,7	2.4		2.4		V	V _{CC} =V _{CC} Min I _{OH} =-2.5mA(V _{CC} =5V), I _{OH} =-2.0mA(V _{CC} =3.3V)
V _{OH2}	Output High Voltage (CMOS)	3,7	0.85 V _{CC}		0.85 V _{CC}		V	Vcc=VccMin Iон=-2.5µA
	(Vcc -0.4		Vcc -0.4		V	V _{CC} =V _{CC} Min I _{OH} =-100µA
VPPLK	V _{PP} Lockout during Normal Operations	4,7		1.5		1.5	V	
V _{PPH1}	V _{PP} during Word Write, BLock Erase, or Lock-Bit Operations		2.7	3.6	_	_	V	
V _{PPH2}	V _{PP} during Word Write, BLock Erase, or Lock-Bit Operations		4.5	5.5	4.5	5.5	V	
V _{РРН3}	V _{PP} during Word Write, BLock Erase, or Lock-Bit Operations		11.4	12.6	11.4	12.6	V	
VLKO	Vcc Lockout Voltage		2.0		2.0		V	
V _{НН}	RP# Unlock Voltage	8	11.4	12.6	11.4	12.6	V	Set Permanent Lock-Bit Override Block Lock-Bit

- 1. All currents are in RMS unless otherwise noted. These currents are valid for all product versions (package and speeds). Contact your local sales office for information about typical specifications.
- 2. I_{ccws} and I_{cces} are specified with the device de-selected. If read or word written while in erase suspend mode, the device's current draw is the sum of I_{ccws} or I_{cces} and I_{cce} or I_{ccw}, respectively.
- Includes RY/BY#.
- 4. Block erases, word writes, and lock-bit configurations are inhibited when $V_{pp} \leq V_{ppLK}$, and not guaranteed in the range between V_{ppLK} (max) and V_{ppH1} (min), between V_{ppH1} (max) and V_{ppH2} (max) and V_{ppH2} (max) and V_{ppH3} (min), and above V_{PPH3} (max).
- 5. Automatic Power Saving (APS) reduces typical I_{CCR} to 1 mA at 5V V_{CC} and 3 mA at 3.3V V_{CC} in static operation. 6. CMOS inputs are either $V_{CC} \pm 0.2$ V or GND ± 0.2 V. TTL inputs are either V_{IL} or V_{IH} .
- 7. Sampled, not 100% tested.
- 8. Permanent lock-bit set operations are inhibited when RP# = V_{IH}. Block lock-bit configuration operations are inhibited when the permanent lock-bit is set or RP# = V_{IH} and WP# = V_{IL} . Block erases and word writes are inhibited when the corresponding block-lock bit is set and RP# = V_{IH} and WP# = V_{IL} or the permanent lock-bit is set. Block erase, word write, and lock-bit configuration operations are not guaranteed with V_{cc} < 2.7V or V_{H} < RP# $< V_{HH}$ and should not be attempted.

6.2.4 AC Characteristics - Read Only Operations (1)

	Versions ⁽⁴⁾		LH28F800	SGHE-L70	l lmia	
Symbol	Parameter	Notes	Min.	Max.	Unit	
tavav	Read Cycle Time		100		ns	
tavqv	Address to Output Delay			100	ns	
telav	CE# to Output Delay	2		100	ns	
tphqv	RP# High to Output Delay			600	ns	
tglav	OE# to Output Delay	2		45	ns	
tELQX	CE# to Output in Low Z	3	0		ns	
tehoz	CE# High to Output in High Z	3		45	ns	
tglax	OE# to Output in Low Z	3	0		ns	
tgнаz	OE# High to Output in High Z	3		20	ns	
tон	Output Hold from Address, CE# ot OE# Change, Whichever Occurs First	3	0		ns	

$\rm V_{cc}$ = 3.3V \pm 0.3V, $\rm T_{A}$ = -40°C to + 85°C

	Versions ⁽⁴⁾		LH28F800	SGHE-L70	Limit	
Symbol	Parameter	Notes	Min.	Max.	Unit	
tavav	Read Cycle Time		85		ns	
tavqv	Address to Output Delay			85	ns	
tELQV	CE# to Output Delay	2		85	ns	
tphqv	RP# High to Output Delay			600	ns	
tglav	OE# to Output Delay	2		40	ns	
telax	CE# to Output in Low Z	3	0		ns	
tehoz	CE# High to Output in High Z	3		40	ns	
tglax	OE# to Output in Low Z	3	0		ns	
tghaz	OE# High to Output in High Z	3		15	ns	
tон	Output Hold from Address, CE# ot OE# Change, Whichever Occurs First	3	0		ns	



6.2.4 AC Characteristics - Read Only Operations (Cont.) (1)

 $m V_{cc}$ = 5.0V \pm 0.5V, 5.0V \pm 0.25V, $\rm T_A$ = -40°C to + 85°C

	Versions ⁽⁴⁾		LH28F8009	SGHE-L70 ⁽⁵⁾			
	versions	Vcc±0.5V			LH28F800SGHE-L70 ⁽⁶⁾		Unit
Symbol	Parameter Parame	Notes	Min.	Max.	Min.	Max.	
tavav	Read Cycle Time		70		80		ns
tavqv	Address to Output Delay			70		80	ns
tELQV	CE# to Output Delay	2		70		80	ns
tphqv	RP# High to Output Delay			400		400	ns
tglav	OE# to Output Delay	2		40		45	ns
telax	CE# to Output in Low Z	3	0		0		ns
tehoz	CE# High to Output in High Z	3		55		55	ns
tgLax	OE# to Output in Low Z	3	0		0		ns
tgHQZ	OE# High to Output in High Z	3		10		10	ns
tон	Output Hold from Address, CE# ot	3	. 0		0		ns
	OE# Change, Whichever Occurs Fi	rst					

NOTES:

- 1. See AC Input/Output Reference Waveform for maximum allowable input slew rate.
- 2. OE# may be delayed up to t_{ELOV} t_{GLOV} after the falling edge of CE# without impact on t_{ELOV} .
- 3. Sampled, not 100% tested.
- 4. See Ordering Information for device speeds (valid operational combinations).
- 5. See Transient Input/Output Reference Waveform and Transient Equivalent Testing Load Circuit (High Speed Configuration) for testing characteristics.
- 6. See Transient Input/Output Reference Waveform and Transient Equivalent Testing Load Circuit (Standard Configuration) for testing characteristics.



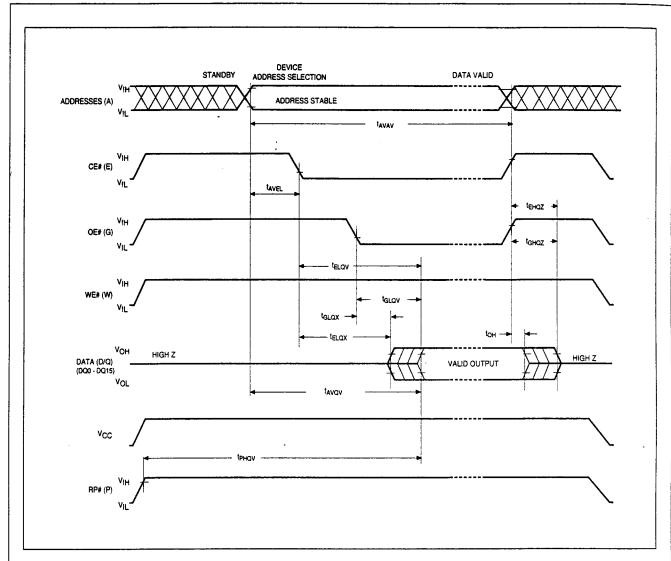


Figure 15. AC Waveform for Read Operations

6.2.5 AC Characteristics for WE#- Controlled Write Operations (1)

$$V_{cc} = 2.7V - 3.6V, T_A = -40^{\circ}C \text{ to } + 85^{\circ}C$$

	Versions ⁽⁵⁾		LH28F800	SGHE-L70	Unit
Symbol	Parameter	Notes	Min.	Max.	Unit
tavav	Write Cycle Time		100		ns
t _{PHWL}	RP# High Recovery to WE# Going Low	2	1		μs
telwl.	CE# Setup to WE# Going Low		10		ns
twLwH	WE# Pulse Width		50		ns
tehhwh	RP# V _{HH} Setup to WE# Going High	2	100		ns
tvpwh	VPP Setup to WE# Going High	2	100		ns
tavwh	Address Setup to WE# Going High	3	50		ns
tovwh	Data Setup to WE# Going High	3	50		ns
twnpx	Data Hold from WE# High		5		ns
twhax	Address Hold from WE# High		5		ns
twheh	CE# Hold from WE# High		10		ns
twhwL	WE# Pulse Width High		30		ns
twhrl	WE# High to RY/BY# Going Low			100	ns
twhgL	Write Recovery before Read		0		ns
tavvl	VPP Hold from Valid SRD, RY/BY# High	2,4	0	<u> </u>	ns
tavph	RP# V _{HH} Hold from Valid SRD, RY/BY# High	2,4	0		ns

$$\rm V_{cc}$$
 = 3.3V \pm 0.3V, $\rm T_A$ = -40°C to + 85°C

	Versions ⁽⁵⁾		LH28F800	SGHE-L70	11-14
Symbol	Parameter	Notes	Min.	Max.	Unit -
tavav	Write Cycle Time		85		ns
tphwl	RP# High Recovery to WE# Going Low	2	1		μs
telwl	CE# Setup to WE# Going Low		10		ns
twLwH	WE# Pulse Width		50		ns
tрннwн	RP# V _{HH} Setup to WE# Going High	2	100		ns
tvpwh	VPP Setup to WE# Going High	2	100		ns
tavwh	Address Setup to WE# Going High	3	50		ns
tруwн	Data Setup to WE# Going High	3	50		ns
twnpx	Data Hold from WE# High		5		ns
twhax	Address Hold from WE# High		5		ns
twhen	CE# Hold from WE# High		10		ns
twhwL	WE# Pulse Width High		30		ns
twirl	WE# High to RY/BY# Going Low			100	ns
twhgL	Write Recovery before Read		0		ns
tavvl	VPP Hold from Valid SRD, RY/BY# High	2,4	0		ns
toven	RP# VHH Hold from Valid SRD, RY/BY# High	2,4	0		ns

6.2.5 AC Characteristics for WE# - Controlled Write Operations (Cont.) (1)

 $V_{cc} = 5V \pm 0.5V$, $5V \pm 0.25V$, $T_A = -40^{\circ}C$ to + 85°C

	Versions ⁽⁵⁾	V _{CC} ±0.25V	LH28F8005	GHE-L70 ⁽⁶		2015 1 70(7)	11
		Vcc±0.5V				GHE-L70(7)	Unit
Symbol	Parameter	Notes	Min.	Max.	Min.	Max.	
tavav	Write Cycle Time		70		80	<u> </u>	ns
tphwL	RP# High Recovery to WE# Going Lo	w 2	1		11		μs
tELWL	CE# Setup to WE# Going Low		10		10		ns
twLwH	WE# Pulse Width		40		40		ns
tehhwh	RP# V _{HH} Setup to WE# Going High	2	100		100		ns
tvpwh	V _{PP} Setup to WE# Going High	2	100		100		ns
tavwh	Address Setup to WE# Going High	3	40		40		ns
tovwh	Data Setup to WE# Going High	3	40		40		ns
twnpx	Data Hold from WE# High		5		5		ns
twhax	Address Hold from WE# High		5		5		ns
twheh	CE# Hold from WE# High		10		10		ns
twhwL	WE# Pulse Width High		30		30		ns
twhal	WE# High to RY/BY# Going Low			90		90	ns
twhgL	Write Recovery before Read		0		0		ns
tavvL	VPP Hold from Valid SRD, RY/BY# Hi	gh 2,4	0		0		ns
toven	RP# VHH Hold from Valid SRD, RY/BY# H		0		0		ns

NOTES:

- 1. Read timing characteristics during block erase, word write and lock-bit configuration operations are the same as during read-only operations. Refer to AC Characteristics for read-only operations.
- 2. Sampled, not 100% tested.
- 3. Refer to Table 4 for valid $A_{\rm IN}$ and $D_{\rm IN}$ for block erase, word write, or lock-bit configuration.
- 4. V_{PP} should be held at V_{PPH1/2/3} (and if necessary RP# should be held at V_{HH}) until determination of block erase, word write, or lock-bit configuration success (SR.1/3/4/5 = 0).
- 5. See Ordering Information for device speeds (valid operational combinations).
- 6. See Transient Input/Output Reference Waveform and Transient Equivalent Testing Load Circuit (High Speed Configuration) for testing characteristics.
- 7. See Transient Input/Output Reference Waveform and Transient Equivalent Testing Load Circuit (Standard Configuration) for testing characteristics.



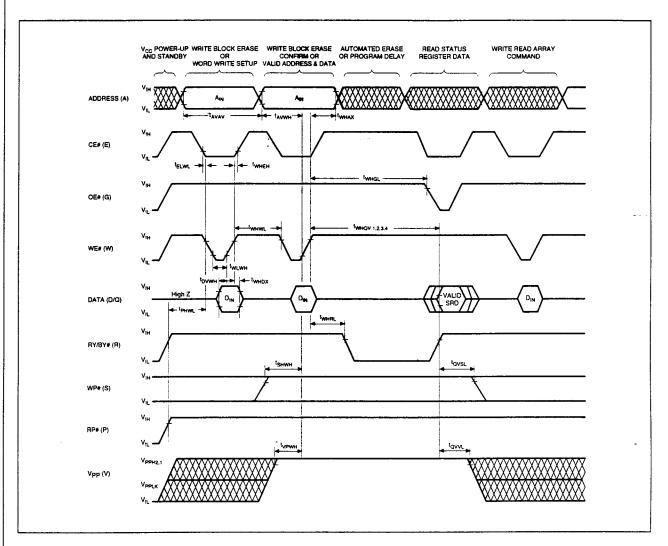


Figure 16. AC Waveform for WE#-Controlled Write Operations



6.2.6 AC Characteristics for CE#-Controlled Writes Operations (1)

 $V_{cc} = 2.7V - 3.6V, T_A = -40^{\circ}C \text{ to } + 85^{\circ}C$

	Versions ⁽⁵⁾				11
Symbol	Parameter	Notes	Min.	Max.	Unit
tavav	Write Cycle Time		100		ns
t _{PHEL}	RP# High Recovery to CE# Going Low	2	1		μs
twlel	WE# Setup to CE# Going Low		0		ns
teleh	CE# Pulse Width		70		ns
tehheh	RP# V _{HH} Setup to CE# Going High	2	100		ns
tvpeh	VPP Setup to CE# Going High	2	100		ns
taveh	Address Setup to CE# Going High	3	50		ns
toven	Data Setup to CE# Going High	3	50		ns
tenox	Data Hold from CE# High		5		ns
tEHAX	Address Hold from CE# High		5		ns
tehwh	WE# Hold from CE# High		0		ns
tehel	CE# Pulse Width High		25		ns
t _{EHRL}	CE# High to RY/BY# Going Low			100	ns
t _{EHGL}	Write Recovery before Read		0		ns
tavvl	VPP Hold from Valid SRD, RY/BY# High	2,4	0		ns
tovph	RP# V _{HH} Hold from Valid SRD, RY/BY# High	2,4	0		ns

$$\rm V_{cc}$$
 = 3.3V \pm 0.3V, $\rm T_{A}$ = -40°C to + 85°C

	Versions ⁽⁵⁾	LH28F800	11-14		
Symbol	Parameter	Notes	Min.	Max.	Unit
tavav	Write Cycle Time		85		ns
tphEL	RP# High Recovery to CE# Going Low	2	1		μs
twlel	WE# Setup to CE# Going Low		0		ns
telen	CE# Pulse Width		70		ns
tehheh	RP# V _{HH} Setup to CE# Going High	2	100		ns
tvpeh	V _{PP} Setup to CE# Going High	2	100		ns
taven	Address Setup to CE# Going High	3	50		ns
toven	Data Setup to CE# Going High	3	50		ns
tehox	Data Hold from CE# High		5		ns
tehax	Address Hold from CE# High		5		ns
tehwh	WE# Hold from CE# High		0		ns
tehel	CE# Pulse Width High		25		ns
tehru	CE# High to RY/BY# Going Low			100	ns
tengl	Write Recovery before Read		0		ns
tqvvl	VPP Hold from Valid SRD, RY/BY# High	2,4	0		ns
tavph	RP# V _{HH} Hold from Valid SRD, RY/BY# High	2,4	0		ns

6.2.6 AC Characteristics for CE#-Controlled Writes Operations (Cont.) (1)

 V_{cc} = 5V \pm 0.5V, 5V \pm 0.25V, T_{A} =-40°C to + 85°C

	Versions ⁽⁵⁾	cc±0.25V	LH28F8009	GHE-L70			
	versions	cc±0.5V			LH28F8005	GHE-L70 ⁽⁷⁾	Unit
Symbol	Parameter	Notes	Min.	Max.	Min.	Max.	
tavav	Write Cycle Time		70		80		ns
t _{PHEL}	RP# High Recovery to CE# Going Low	2	1		11		μs
twlel	WE# Setup to CE# Going Low		0		0		ns
teleh	CE# Pulse Width		50		50		ns
tphheh	RP# V _{HH} Setup to CE# Going High	2	100		100		ns
tvpeh	VPEH VPP Setup to CE# Going High		100		100		ns
taveh	AVEH Address Setup to CE# Going High		40		40		ns
toven	Data Setup to CE# Going High	3	40		40		ns
tehox	Data Hold from CE# High		5		5		ns
tEHAX	Address Hold from CE# High		5		5		ns
tehwh	WE# Hold from CE# High		0		0	ļ	ns
t _{EHEL}	CE# Pulse Width High		25		25		ns
tehal	CE# High to RY/BY# Going Low			90		90	ns
tengl	Write Recovery before Read		0		0		ns
tavvl	VPP Hold from Valid SRD, RY/BY# High	1 2,4	0		0		ns
tovph	RP# VHH Hold from Valid SRD, RY/BY# Hig	h 2,4	0		0		ns

- 1. In systems where CE# defines the write pulse width (within a longer WE# timing waveform), all setup, hold, and inactive WE# times should be measured relative to the CE# waveform.
- 2. Sampled, not 100% tested.
- 3. Refer to Table 4 for valid $A_{\rm IN}$ and $D_{\rm IN}$ for block erase, word write, or lock-bit configuration.
- 4. V_{pp} should be held at $V_{ppH1/2/3}$ (and if necessary RP# should be held at V_{HH}) until determination of block erase, word write, or lock-bit configuration success (SR.1/3/4/5 = 0).
- 5. See Ordering Information for device speeds (valid operational combinations).
- 6. See Transient Input/Output Reference Waveform and Transient Equivalent Testing Load Circuit (High Speed Configuration) for testing characteristics.
- 7. See Transient Input/Output Reference Waveform and Transient Equivalent Testing Load Circuit (Standard Configuration) for testing characteristics.



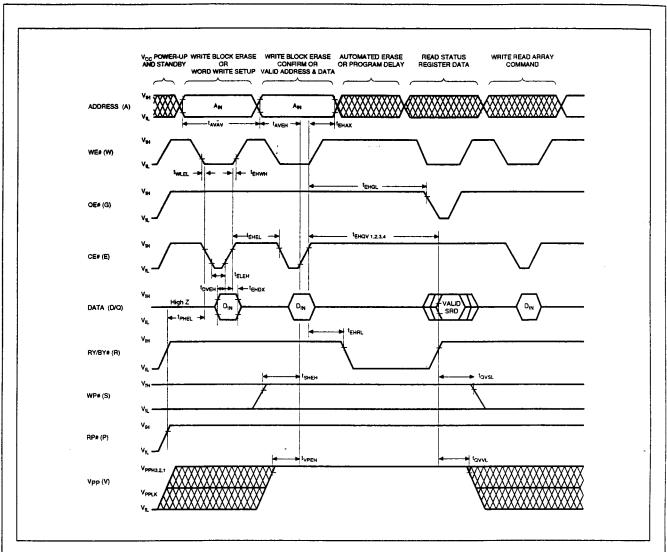


Figure 17. AC Waveform for CE#-Controlled Write Operations



6.2.7 Reset Operations

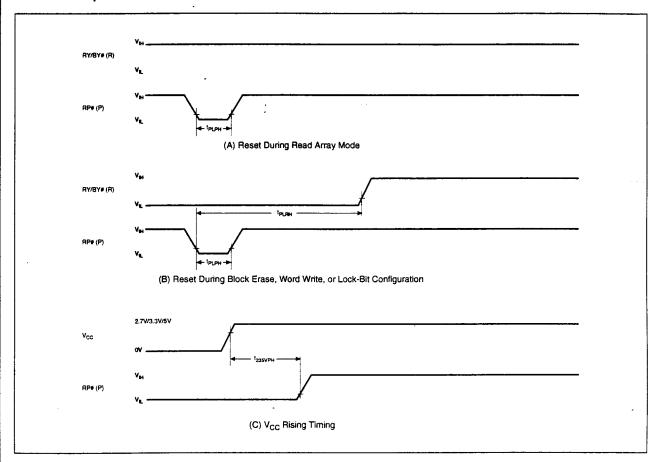


Figure 18. AC Waveform for Reset Operation

Reset AC Specifications (1)

Sumbal Beremeter		Notes	V _{cc} =	2.7V-3.6V	V _{CC} =5	Unit	
Symbol	Symbol Parameter N		Min.	Max.	Min.	Max.	Unik
tрцрн	RP# Pulse Low Time (If RP# is tied to Vcc, this specification is not applicable)		100		100		ns
tplah	RP# Low to Reset during Block Erase, Word Write, or Lock-Bit Configuration	2,3		20 28(2.7V Vcc)		12	μѕ
t ₂₃₅ VPH	V _{CC} 2.7V to RP# High V _{CC} 3.0V to RP# High V _{CC} 4.5V to RP# High	4	100		100		ns

- 1. These specifications are valid for all product versions (packages and speeds).
- 2. If RP# is asserted while a block erase, word write, or lock-bit configuration operation is not executing, the reset will complete within 100 ns.
- A reset time, t_{PHQV}, is required from the latter of RY/BY# or RP# going high until outputs are valid.
 When the device power-up, holding RP# low minimum 100 ns is required after V_{cc} has been in predefined range and also has been in stable there.

6.2.8 Block Erase, Word Write and Lock-Bit Configuration Performance (3.4)

$$V_{cc} = 3.3V \pm 0.3V$$
, $T_A = -40^{\circ}C$ to + 85°C

0	D	Nana	VPI	Vpp=3.0-3.6V		V _{PP} =4.5-5.5V			V _{PP} =11.4-12.6V			11
Symbol	Parameter	Notes	Min.	Typ.(1)	Max.	Min.	Typ.(1)	Max.	Min.	Typ. ⁽¹⁾	Max.	Unit
twhQv1 tehQv1	Word Write Time	2	35	45		14	20			11		μs
	Block Write Time	2	1.2	1.5		0.5	0.7			0.4		s
twhQv2 tehQv2	Block Erase Time	2		2.1			1.4			1.3		s
twhqv3 tehqv3	Set Lock-Bit Time	2		31			20			17.4		μs
twhQV4 tehQV4	Clear Block Lock-Bits Time	2		2.7			1.8			1.6		s
twhRH1 tehRH1	Word Write Suspend Latency Time to			9			7.5			7.5		μs
twhRH2 tehRH2	Read Erase Suspend			24.3			14.4			14.4		μs

$V_{\rm cc}$ = 5V \pm 0.5V, 5V \pm 0.25V, $T_{\rm A}$ = -40°C to + 85°C

0	Barram atau	Natas	Notes V _{PP} =4.5-5.5 Min. Typ.(1)		P=4.5-5.5V		V _{PP} =11.4-12.6V		
Symbol	Parameter	Notes			Max.	Min.	Typ.(1)	Max.	Unit
twhqv1 tehqv1	Word Write Time	2	10	14			7.5		μs
,	Block Write Time	2	0.4	0.5			0.25		s
twhav2 tehav2	Block Erase Time	2		1.3			1.2		s
twhqv3	Set Lock-Bit Time	2		18			15		μѕ
twhqv4	Clear Block Lock-Bits Time	2		1.6			1.5		s
twhah1 tehah1	Word Write Suspend Latency Time to Read			7.5			6		μs
twhRH2 tehRH2	Erase Suspend Latency Time to Read			14.4			14.4		μs

- 1. Typical values measured at $T_A = +25^{\circ}C$ and nominal voltages. Assumes corresponding lock-bits are not set. Subject to change based on device characterization.
- 2. Excludes system-level overhead.
- 3. These performance numbers are valid for all speed versions.
- 4. Sampled but not 100% tested.

$V_{cc} = 2.7V - 3.0V, T_A = -40^{\circ}C \text{ to } + 85^{\circ}C$

0		Madaa	V _{PP} =2.7-3.0V		V _{PP} =4.5-5.5V			Vpp=11.4~12.6V			11-14	
Symbol	Parameter	Notes	Min.	Typ.(1)	Max.	Min.	Typ.(1)	Max.	Min.	Typ.(1)	Max.	Unit
twhQV1	Word Write Time	2	49	63		20	28			15.4		μs
	Block Write Time	2	1.7	2.1		0.7	1.0			0.56		S
twhqv2 tehqv2	Block Erase Time	2	:	3.0			2.0			1.9		s
twhqv3	Set Lock-Bit Time	2		44			28			24.4		μs
twhQV4	Clear Block Lock-Bits Time	2		3.8			2.6			2.3		ø
twhahi tehahi	Word Write Suspend Latency Time to			12.6			10.5			10.5		μs
twhRH2 tehRH2	Read Erase Suspend			34.1			20.2			20.2		μs

- Typical values measured at T_A = + 25°C and nominal voltages. Assumes corresponding lock-bits are not set. Subject to change based on device characterization.
- 2. Excludes system-level overhead.
- 3. These performance numbers are valid for all speed versions.
- 4. Sampled but not 100% tested.



7.0 Package and packing specification

1. Package Outline Specification

Refer to drawing No. AA1142

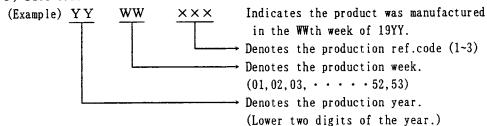
2. Markings

2-1. Marking contents

(1) Product name: LH28F800SGHE-L70

(2) Company name : SHARP

(3) Date code



(4) The marking of "JAPAN" indicates the country of origin.

2-2. Marking layout

Refer drawing No. AA1142

(This layout does not define the dimensions of marking character and marking position.)

3. Packing Specification (Dry packing for surface mount packages)

Dry packing is used for the purpose of maintaining IC quality after mounting packages on the PCB (Printed Circuit Board).

When the epoxy resin which is used for plastic packages is stored at high humidity, it may absorb 0.15% or more of its weight in moisture. If the surface mount type package for a relatively large chip absorbs a large amount of moisture between the epoxy resin and insert material (e.g. chip, lead frame) this moisture may suddenly vaporize into steam when the entire package is heated during the soldering process (e.g. VPS). This causes expansion and results in separation between the resin and insert material, and sometimes cracking of the package. This dry packing is designed to prevent the above problem from occurring in surface mount packages.

3-1. Packing Materials

Material Name	Material Specificaiton	Purpose
Tray	Conductive plastic (50devices/tray)	Fixing of device
Upper cover tray	Conductive plastic (1tray/case)	Fixing of device
Laminated aluminum bag	Aluminum polyethylene (1bag/case)	Drying of device
Desiccant	Silica gel	Drying of device
P P band	Polypropylene (3pcs/case)	Fixing of tray
Inner case	Card board (500device/case)	Packaging of device
Label	Paper	Indicates part number, quantity
		and date of manufacture
Outer case	Card board	Outer packing of tray

(Devices shall be placed into a tray in the same direction.)

- 3-2. Outline dimension of tray Refer to attached drawing
- 4. Storage and Opening of Dry Packing
 - 4-1. Store under conditions shown below before opening the dry packing

(1) Temperature range : 5~40℃

(2) Humidity : 80% RH or less

- 4-2. Notes on opening the dry packing
 - (1) Before opening the dry packing, prepare a working table which is grounded against ESD and use a grounding strap.
 - (2) The tray has been treated to be conductive or anti-static. If the device is transferred to another tray, use a equivalent tray.
- 4-3. Storage after opening the dry packing

Perform the following to prevent absorption of moisture after opening.

- (1) After opening the dry packing, store the ICs in an environment with a temperature of $5\sim25^{\circ}$ C and a relative humidity of 60% or less and mount ICs within 72 hours after opening dry packing.
- 4-4. Baking (drying) before mounting
 - (1) Baking is necessary
 - (A) If the humidity indicator in the desiccant becomes pink
 - (B) If the procedure in section 4-3 could not be performed
 - (2) Recommended baking conditions If the above conditions (A) and (B) are applicable, bake it before mounting. The recommended conditions are 16-24 hours at 120℃. Heat resistance tray is used for shipping tray.
- 5. Surface Mount Conditions

Please perform the following conditions when mounting ICs not to deteriorate IC quality.

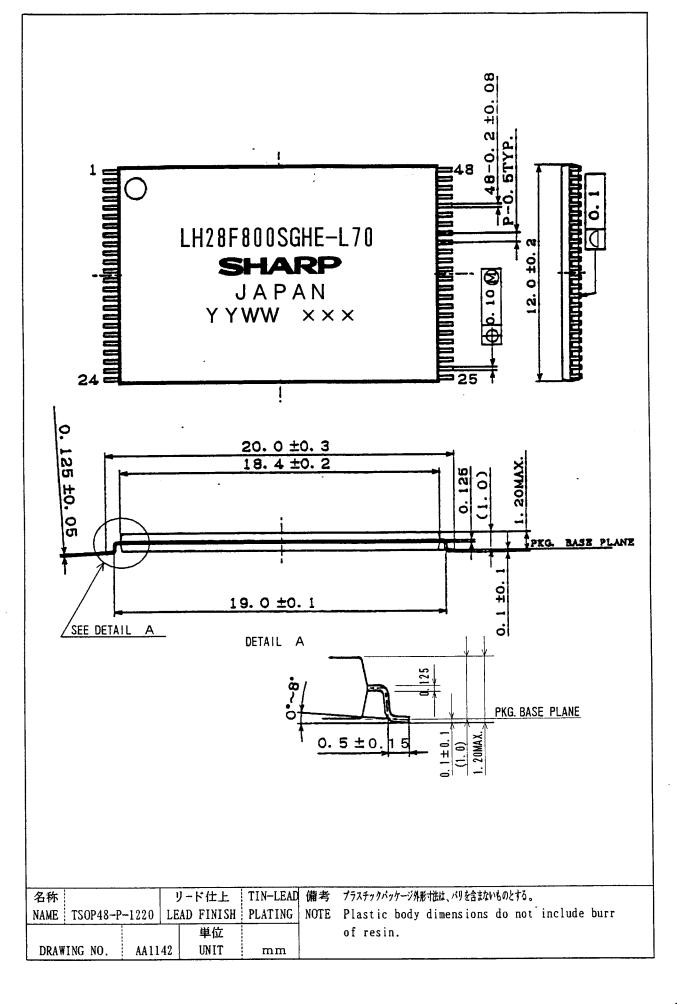
5-1 . Soldering conditions (The following conditions are valid only for one time soldering.)

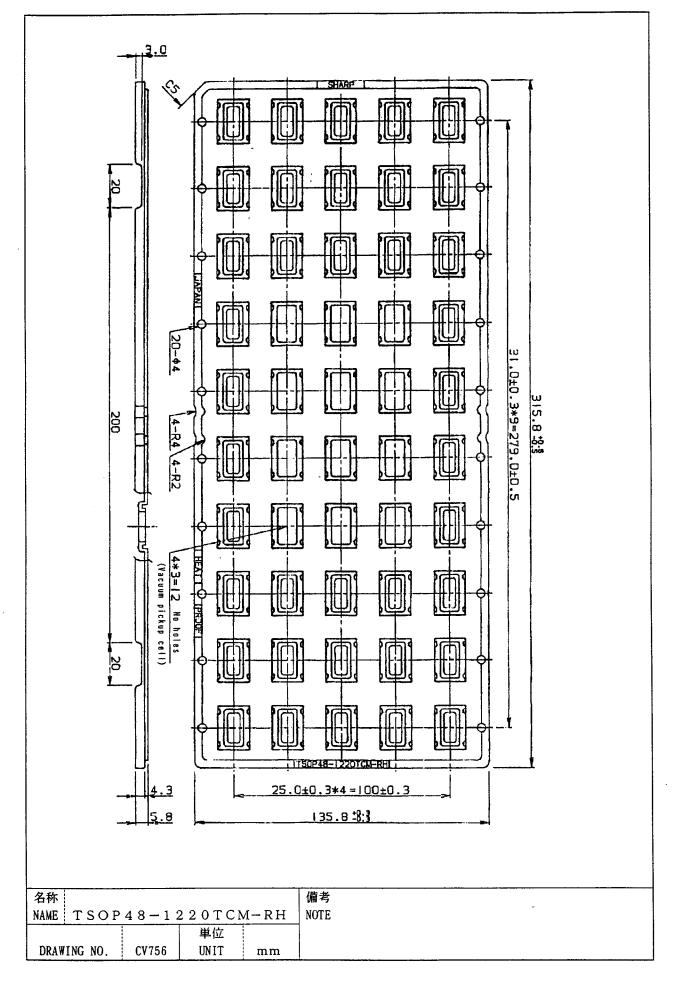
Mounting Method	Temperature and Duration	Measurement Point
Reflow soldering	Peak temperature of 230°C or less,	IC package
(air)	duration of less than 15 seconds.	surface
	200℃ or over,duration of less than 40 seconds.	
	Temperature increase rate of 1∼4°C/second	
Manual soldering	260℃ or less, duration of less	IC outer lead
(soldering iron)	than 10 seconds.	surface

5-2. Conditions for removal of residual flux

(1) Ultrasonic washing power(2) Washing time25 Watts/liter or lessTotal 1 minute maximum

(3) Solvent temperature : $15\sim40^{\circ}$ C





8 Mb, Queen Cobra, I-temp, ETOX, LH28F800SGHEL70