



LH28F008SC-V 8-MBIT (1 MB x 8) SmartVoltage Flash MEMORY

- SmartVoltage Technology
 - 5V V_{CC}
 - 5V or 12V Vpp
- High-Performance
 - 85 ns Read Access Time
- **■** Enhanced Automated Suspend Options
 - Byte Write Suspend to Read
 - Block Erase Suspend to Byte Write
 - Block Erase Suspend to Read
- **■** Enhanced Data Protection Features
 - Absolute Protection with Vpp=GND
 - Flexible Block Locking
 - Block Erase/Byte Write Lockout during Power Transitions
- Industry-Standard Packaging
 - 40-Lead TSOP, 44-Lead PSOP
- Chip Size Packaging
 - 42-Lead CSP

- SRAM-Compatible Write Interface
- High-Density Symmetrically-Blocked Architecture
 - Sixteen 64-Kbyte Erasable Blocks
- **■** Extended Cycling Capability
 - 100,000 Block Erase Cycles
 - 1.6 Million Block Erase Cycles/Chip
- Low Power Management
 - Deep Power-Down Mode
 - Automatic Power Savings Mode
 Decreases I_{CC} in Static Mode
- Automated Byte Write and Block Erase
 - Command User Interface
 - Status Register
- ETOX^{TM*} V Nonvolatile Flash Technology
- Not designed or rated as radiation hardened

SHARP's LH28F008SC-V Flash memory with SmartVoltage technology is a high-density, low-cost, nonvolatile, read/write storage solution for a wide range of applications. Its symmetrically-blocked architecture, flexible voltage and extended cycling provide for highly flexible component suitable for resident flash arrays, SIMMs and memory cards. Its enhanced suspend capabilities provide for an ideal solution for code + data storage applications. For secure code storage applications, such as networking, where code is either directly executed out of flash or downloaded to DRAM, the LH28F008SC-V offers three levels of protection: absolute protection with V_{PP} at GND, selective hardware block locking, or flexible software block locking. These alternatives give designers ultimate control of their code security needs.

The LH28F008SC-V is manufactured on SHARP's 0.4µm ETOXTM V process technology. It comes in industry-standard packages: the 40-lead TSOP and 42-Lead CSP, ideal for board constrained applications, and the rugged 44-lead PSOP. Based on the 28F008SA architecture, the LH28F008SC-V enables quick and easy upgrades for designs demanding the state-of-the-art.

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CONTENTS

PAGE	PA	\GE
1.0 INTRODUCTION 4	5.0 DESIGN CONSIDERATIONS	25
1.1 New Features 4	5.1 Three-Line Output Control	25
1.2 Product Overview 4	5.2 RY/BY# and Block Erase, Byte Write and Lock	-Bit
	Configuration Polling	25
2.0 PRINCIPLES OF OPERATION 9	5.3 Power Supply Decoupling	25
2.1 Data Protection9	5.4 V _{PP} Trace on Printed Circuit Boards	25
:	5.5 V _{CC} , V _{PP} , RP# Transitions	26
3.0 BUS OPERATION 10	5.6 Power-Up/Down Protection	26
3.1 Read 10	5.7 Power Dissipation	26
3.2 Output Disable		
3.3 Standby 10	6.0 ELECTRICAL SPECIFICATIONS	27
3.4 Deep Power-Down 10	6 1 Absolute Maximum Ratings	27
3.5 Read Identifier Codes Operation 11	6.2 Operating Conditions	27
3.6 Write	6.2.1 Capacitance	27
•	6.2.2 AC Input/Output Test Conditions	28
4.0 COMMAND DEFINITIONS 11	6.2.3 DC Characteristics	29
4.1 Read Array Command 14	6.2.4 AC Characteristics - Read-Only Operations	.31
4.2 Read Identifier Codes Command 14	6.2.5 AC Characteristics - Write Operations	33
4.3 Read Status Register Command	6.2.6 Alternative CE#-Controlled Writes	35
4.4 Clear Status Register Command	6.2.7 Reset Operations	37
4.5 Block Erase Command	6.2.8 Block Erase, Byte Write and Lock-Bit	
4.6 Byte Write Command	Configuration Performance	38
4.7 Block Erase Suspend Command		
4.8 Byte Write Suspend Command	7.0 ADDITIONAL INFORMATION	39
4.9 Set Block and Master Lock-Bit Commands 16	7.1 Ordering Information	39
4.10 Clear Block Look Bite Command 17		



1 INTRODUCTION

This datasheet contains LH28F008SC-V specifications. Section 1 provides a flash memory overview. Sections 2, 3, 4, and 5 describe the memory organization and functionality. Section 6 covers electrical specifications. LH28F008SC-V Flash memory documentation also includes application notes and design tools which are referenced in Section 7.

1.1 New Features

The LH28F008SC-V SmartVoltage Flash memory maintains backwards-compatibility with SHARP's 28F008SA. Key enhancements over the 28F008SA include:

- SmartVoltage Technology
- Enhanced Suspend Capabilities
- •In-System Block Locking

Both devices share a compatible pinout, status register, and software command set. These similarities enable a clean upgrade from the 28F008SA to LH28F008SC-V. When upgrading, it is important to note the following differences:

- •Because of new feature support, the two devices have different device codes. This allows for software optimization.
- •V_{PPLK} has been lowered from 6.5V to 1.5V to support 5V block erase, byte write, and lock-bit configuration operations. Designs that switch V_{PP} off during read operations should make sure that the V_{PP} voltage transitions to GND.
- To take advantage of SmartVoltage technology, allow V_{PP} connection to 5V.

1.2 Product Overview

The LH28F008SC-V is a high-performance 8-Mbit SmartVoltage Flash memory organized as 1 Mbyte of

8 bits. The 1 Mbyte of data is arranged in sixteen 64-Kbyte blocks which are individually erasable, lockable, and unlockable in-system. The memory map is shown in Figure 6.

SmartVoltage technology provides a choice of V_{CC} and V_{PP} combinations, as shown in Table 1, to meet system performance and power expectations. V_{PP} at 5V eliminates the need for a separate 12V converter, while V_{PP} =12V maximizes block erase and byte write performance. In addition to flexible erase and program voltages, the dedicated V_{PP} pin gives complete data protection when $V_{PP} \le V_{PPLK}$.

Table 1. V_{CC} and V_{PP} Voltage Combinations Offered by SmartVoltage Technology

V _{CC} Voltage	V _{pp} Voltage
5V	5V, 12V

Internal V_{CC} and V_{PP} detection Circuitry automatically configures the device for optimized read and write operations.

A Command User Interface (CUI) serves as the interface between the system processor and internal operation of the device. A valid command sequence written to the CUI initiates device automation. An internal Write State Machine (WSM) automatically executes the algorithms and timings necessary for block erase, byte write, and lock-bit configuration operations.

A block erase operation erases one of the device's 64-Kbyte blocks typically within 1 second (5V V_{CC} , 12V V_{PP}) independent of other blocks. Each block can be independently erased 100,000 times (1.6 million block erases per device). Block erase suspend mode allows system software to suspend block erase to read or write data from any other block.

Writing memory data is performed in byte increments typically within 6 μs (5V V_{CC}, 12V V_{PP}). Byte write suspend mode enables the system to read data or execute code from any other flash memory array location.

Individual block locking uses a combination of bits, sixteen block lock-bits and a master lock-bit, to lock and unlock blocks. Block lock-bits gate block erase and byte write operations, while the master lock-bit gates block lock-bit modification. Lock-bit configuration operations (Set Block Lock-Bit, Set Master Lock-Bit, and Clear Block Lock-Bits commands) set and cleared lock-bits.

The status register indicates when the WSM's block erase, byte write, or lock-bit configuration operation is finished.

The RY/BY# output gives an additional indicator of WSM activity by providing both a hardware signal of status (versus software polling) and status masking (interrupt masking for background block erase, for example). Status polling using RY/BY# minimizes both CPU overhead and system power consumption. When low, RY/BY# indicates that the WSM is performing a block erase, byte write, or lock-bit configuration. RY/BY#-high indicates that the WSM is ready for a new command, block erase is suspended (and byte write is inactive), byte write is suspended, or the device is in deep power-down mode.

The access time is 85 ns (t_{AVAV}) over the commercial temperature range (0°C to +70°C) and V_{CC} supply voltage range of 4.75V-5.25V. At lower V_{CC} voltage, the access time is 90ns (4.5V-5.5V).

The Automatic Power Savings (APS) feature substantially reduces active current when the device is in static mode (addresses not switching). In APS mode, the typical $I_{\rm CCR}$ current is 1 mA at 5V $V_{\rm CC}$.

When CE# and RP# pins are at V_{CC}, the I_{CC} CMOS standby mode is enabled. When the RP# pin is at GND, deep power-down mode is enabled which minimizes power consumption and provides write protection during reset. A reset time (t_{PHQV}) is required from RP# switching high until outputs are valid. Likewise, the device has a wake time (t_{PHEL}) from RP#-high until writes to the CUI are recognized. With RP# at GND, the WSM is reset and the status register is cleared.

The device is available in 40-lead TSOP (Thin Small Outline Package, 1.2 mm thick), 44-lead PSOP (Plastic Small Outline Package) and 42-lead CSP (Chip Size Package). Pinouts are shown in Figures 2, 3, 4 and 5.

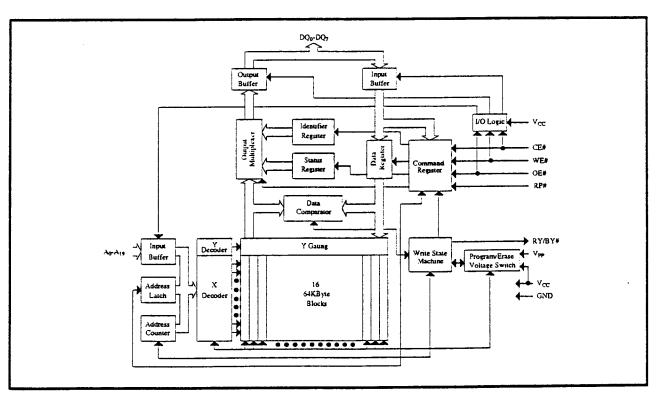


Figure 1. Block Diagram



Table 2. Pin Descriptions

Sym	Type	Name and Function
A ₀ -A ₁₉	INPUT	ADDRESS INPUTS: Inputs for addresses during read and write operations. Addresses
		are internally latched during a write cycle.
DQ ₀ -DQ ₇	INPUT/	DATA INPUT/OUTPUTS: Inputs data and commands during CUI write cycles; outputs
,	OUTPUT	data during memory array, status register, and identifier code read cycles. Data pins float
		to high-impedance when the chip is deselected or outputs are disabled. Data is internally
		latched during a write cycle.
CE#	INPUT	CHIP ENABLE: Activates the device's control logic, input buffers, decoders, and sense
		amplifiers. CE#-high deselects the device and reduces power consumption to standby
		leveis.
RP#	INPUT	RESET/DEEP POWER-DOWN: Puts the device in deep power-down mode and resets
		internal automation. RP#-high enables normal operation. When driven low, RP# inhibits
		write operations which provides data protection during power transitions. Exit from deep
		power-down sets the device to read array mode. RP# at V _{HH} enables setting of the
		master lock-bit and enables configuration of block lock-bits when the master lock-bit is
		set. RP#=V _{HH} overrides block lock-bits thereby enabling block erase and byte write
		operations to locked memory blocks. Block erase, byte write, or lock-bit configuration
		with V _{IH} <rp#<v<sub>HH produce spurious results and should not be attempted.</rp#<v<sub>
OE#	INPUT	OUTPUT ENABLE: Gates the device's outputs during a read cycle.
WE#	INPUT	WRITE ENABLE: Controls writes to the CUI and array blocks. Addresses and data are
		latched on the rising edge of the WE# pulse.
RY/BY#	OUTPUT	READY/BUSY#: Indicates the status of the internal WSM. When low, the WSM is
		performing an internal operation (block erase, byte write, or lock-bit configuration).
		RY/BY#-high indicates that the WSM is ready for new commands, block erase is
		suspended, and byte write is inactive, byte write is suspended, or the device is in deep
		power-down mode. RY/BY# is always active and does not float when the chip is
V	SUPPLY	deselected or data outputs are disabled. BLOCK ERASE, BYTE WRITE, LOCK-BIT CONFIGURATION POWER SUPPLY: For
V _{PP}	SUPPLI	erasing array blocks, writing bytes, or configuring lock-bits. With V _{PP} ≤ V _{PPLK} , memory
		contents cannot be altered. Block erase, byte write, and lock-bit configuration with an
		invalid V _{PP} (see DC Characteristics) produce spurious results and should not be
		attempted.
V _{CC}	SUPPLY	DEVICE POWER SUPPLY: Do not float any power pins. With V _{CC} ≤V _{LKO} , all write
*CC	001121	attempts to the flash memory are inhibited. Device operations at invalid V _{CC} voltage (see
		DC Characteristics) produce spurious results and should not be attempted.
GND	SUPPLY	GROUND: Do not float any ground pins.
NC	301121	NO CONNECT: Lead is not internal connected; it may be driven or floated.
110		TO CONTILOR. Lead is not internal connected, it may be diverse. Induced.



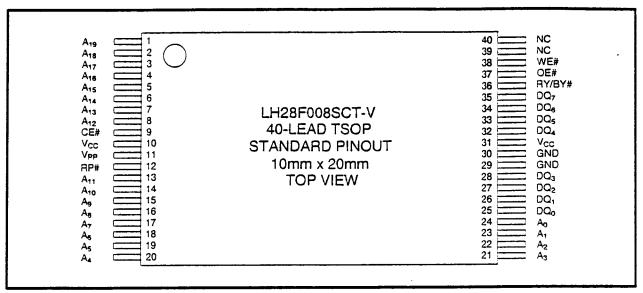


Figure 2. TSOP(Normal Bend) 40-Lead Pinout

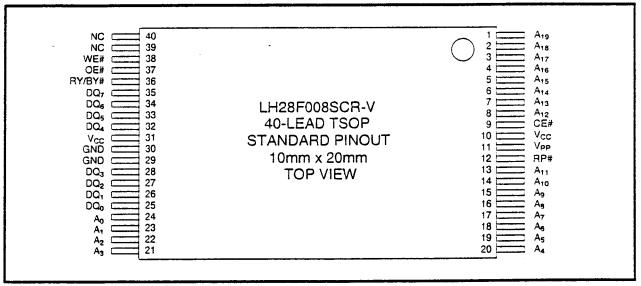


Figure 3. TSOP(Reverse Bend) 40-Lead Pinout

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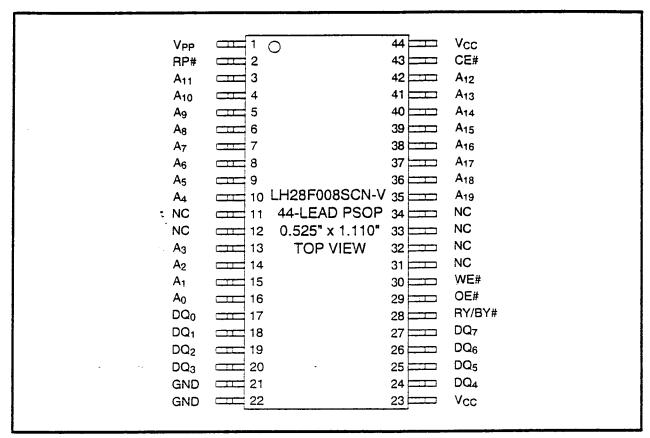


Figure 4. PSOP 44-Lead Pinout

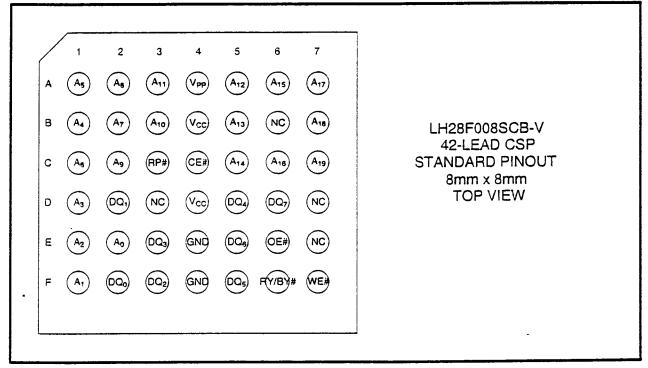


Figure 5. CSP 42-Lead Pinout



2 PRINCIPLES OF OPERATION

The LH28F008SC-V SmartVoltage Flash memory includes an on-chip WSM to manage block erase, byte write, and lock-bit configuration functions. It allows for: 100% TTL-level control inputs, fixed power supplies during block erasure, byte write, and lock-bit configuration, and minimal processor overhead with RAM-Like interface timings.

After initial device power-up or return from deep power-down mode (see Bus Operations), the device defaults to read array mode. Manipulation of external memory control pins allow array read, standby, and output disable operations.

Status register and identifier codes can be accessed through the CUI independent of the V_{PP} voltage. High voltage on V_{PP} enables successful block erasure, byte writing, and lock-bit configuration. All functions associated with altering memory contents—block erase, byte write, Lock-bit configuration, status, and identifier codes—are accessed via the CUI and verified through the status register.

Commands are written using standard microprocessor write timings. The CUI contents serve as input to the WSM, which controls the block erase, byte write, and lock-bit configuration. The internal algorithms are regulated by the WSM, including pulse repetition, internal verification, and margining of data. Addresses and data are internally latch during write cycles. Writing the appropriate command outputs array data, accesses the identifier codes, or outputs status register data.

Interface software that initiates and polls progress of block erase, byte write, and lock-bit configuration can be stored in any block. This code is copied to and executed from system RAM during flash memory updates. After successful completion, reads are again possible via the Read Array command. Block erase suspend allows system software to suspend a block erase to read or write data from any other block. Byte write suspend allows system software to suspend a byte write to read data from any other flash memory array location.

FOOOD	64-Kbyte Block	15
EFFFF	64-Kbyte Block	14
DFFFF	64-Kbyte Block	13
CFFFF	64-Kbyte Block	12
BFFFF	64-Kbyte Block	11
AFFFF	64-Kbyte Block	10
9FFFF 90000	64-Kbyte Block	9
8FFFF 80000	64-Kbyte Block	8
7FFFF 70000	64-Kbyte Block	7
6FFFF 50000	64-Kbyte Block	6
5FFFF 50000	64-Kbyte Block	5
4FFFF 40000	64-Kbyte Block	4
3FFFF 30000	64-Kbyte Block	3
2FFFF	64-Kbyte Block	2
20000 1FFFF	64-Kbyte Block	1
10000 0FFFF	64-Kbyte Block	C

Figure 6. Memory Map

2.1 Data Protection

Depending on the application, the system designer may choose to make the V_{PP} power supply switchable (available only when memory block erases, byte writes, or lock-bit configurations are required) or hardwired to $V_{PPH1/2}$. The device accommodates either design practice and encourages optimization of the processor-memory interface.



When $V_{PP} \le V_{PPLK}$, memory contents cannot be altered. The CUI, with two-step block erase, byte write, or lock-bit configuration command sequences, provides protection from unwanted operations even when high voltage is applied to V_{PP} . All write functions are disabled when V_{CC} is below the write lockout voltage V_{LKO} or when RP# is at V_{IL} . The device's block locking capability provides additional protection from inadvertent code or data alteration by gating erase and byte write operations.

3 BUS OPERATION

The local CPU reads and writes flash memory in-system. All bus cycles to or from the flash memory conform to standard microprocessor bus cycles.

3.1 Read

Information can be read from any block, identifier codes, or status register independent of the V_{PP} voltage. RP# can be at either V_{IH} or V_{HH} .

The first task is to write the appropriate read mode command (Read Array, Read Identifier Codes, or Read Status Register) to the CUI. Upon initial device power-up or after exit from deep power-down mode, the device automatically resets to read array mode. Four control pins dictate the data flow in and out of the component: CE#, OE#, WE#, and RP#. CE# and OE# must be driven active to obtain data at the outputs. CE# is the device selection control, and when active enables the selected memory device. OE# is the data output (DQ0-DQ7) control and when active drives the selected memory data onto the I/O bus. WE# must be at V_{IH} and RP# must be at V_{IH} or V_{HH} . Figure 17 illustrates a read cycle.

3.2 Output Disable

With OE# at a logic-high level (V_{IH}), the device outputs are disabled. Output pins DQ₀-DQ₇ are placed in a high-impedance state.

3.3 Standby

CE# at a logic-high level (V_{IH}) places the device in standby mode which substantially reduces device power consumption. DQ_0 - DQ_7 outputs are placed in a high-impedance state independent of OE#. If deselected during block erase, byte write, or lock-bit configuration, the device continues functioning, and consuming active power until the operation completes.

3.4 Deep Power-Down

RP# at V_{IL} initiates the deep power-down mode.

In read modes, RP#-low deselects the memory, places output drivers in a high-impedance state and turns off all internal circuits. RP# must be held low for a minimum of 100 ns. Time t_{PHQV} is required after return from power-down until initial memory access outputs are valid. After this wake-up interval, normal operation is restored. The CUI is reset to read array mode and status register is set to 80H.

During block erase, byte write, or lock-bit configuration modes, RP#-low will abort the operation. RY/BY# remains low until the reset operation is complete. Memory contents being altered are no longer valid; the data may be partially erased or written. Time t_{PHWL} is required after RP# goes to logic-high (V_{IH}) before another command can be written.

As with any automated device, it is important to assert RP# during system reset. When the system comes out of reset, it expects to read from the flash memory. Automated flash memories provide status information when accessed during block erase, byte write, or lock-bit configuration modes. If a CPU reset occurs with no flash memory reset, proper CPU initialization may not occur because the flash memory may be providing status information instead of array data. SHARP's flash memories allow proper CPU initialization following a system reset through the use of the RP# input. In this application, RP# is controlled by the same RESET# signal that resets the system CPU.

3.5 Read Identifier Codes Operation

The read identifier codes operation outputs the manufacturer code, device code, block lock configuration codes for each block, and the master lock configuration code (see Figure 7). Using the manufacturer and device codes, the system CPU can automatically match the device with its proper algorithms. The block lock and master lock configuration codes identify locked and unlocked blocks and master lock-bit setting.

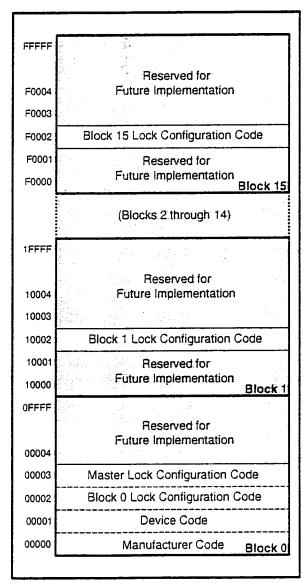


Figure 7. Device Identifier Code Memory Map

3.6 Write

Writing commands to the CUI enable reading of device data and identifier codes. They also control inspection and clearing of the status register. When $V_{PP}=V_{PPH1/2}$, the CUI additionally controls block erasure, byte write, and lock-bit configuration.

The Block Erase command requires appropriate command data and an address within the block to be erased. The Byte Write command requires the command and address of the location to be written. Set Master and Block Lock-Bit commands require the command and address within the device (Master Lock) or block within the device (Block Lock) to be locked. The Clear Block Lock-Bits command requires the command and address within the device.

The CUI does not occupy an addressable memory location. It is written when WE# and CE# are active. The address and data needed to execute a command are latched on the rising edge of WE# or CE# (whichever goes high first). Standard microprocessor write timings are used. Figures 18 and 19 illustrate WE# and CE#-controlled write operations.

4 COMMAND DEFINITIONS

When the V_{PP} voltage $\leq V_{PPLK}$, Read operations from the status register, identifier codes, or blocks are enabled. Placing $V_{PPH1/2}$ on V_{PP} enables successful block erase, byte write and lock-bit configuration operations.

Device operations are selected by writing specific commands into the CUI. Table 4 defines these commands.



Table 3. Bus Operations

Mode	Notes	RP#	CE#	OE#	WE#	Address	V_{pp}	DQ ₀₋₇	RY/BY#
Read	1,2,3	V _{IH} or V _{HH}	V _{IL}	V _{IL}	V _{IH}	X	Х	D _{OUT}	Х
Output Disable	3	V _{IH} or V _{HH}	V _{IL}	V _{IH}	VIH	X	Х	High Z	Х
Standby	3	V _{IH} or V _{HH}	V _{IH}	Х	Х	X	Х	High Z	Х
Deep Power-Down	4	V ₁₁	Х	X	X	X	X	High Z	VOH
Read Identifier Codes		V _{IH} or V _{HH}	VIL	V _{IL}	V _{tH}	See Figure 7	Х	Note 5	V _{ОН}
Write	3,6,7	V _{IH} or V _{HH}	V _{!L}	V _{IH}	V _{IL}	X	Х	D _{IN}	Х

NOTES:

- Refer to DC Characteristics. When V_{PP}≤V_{PPLK}, memory contents can be read, but not altered.
- 2. X can be V_{IL} or V_{IH} for control pins and addresses, and V_{PPLK} or V_{PPH1/2} for V_{PP}. See DC Characteristics for V_{PPLK} and V_{PPH1/2} voltages.
- V_{PPLK} and V_{PPH1/2} voltages.

 3. RY/BY# is V_{OL} when the WSM is executing internal block erase, byte write, or lock-bit configuration algorithms. It is V_{OH} during when the WSM is not busy, in block erase suspend mode (with byte write inactive), byte write suspend mode, or deep power-down mode.
- 4. RP# at GND±0.2V ensures the lowest deep power-down current.
- 5. See Section 4.2 for read identifier code data.
- Command writes involving block erase, write, or lock-bit configuration are reliably executed when V_{PP}=V_{PPH1/2} and V_{CC}=V_{CC1/2}. Block erase, byte write, or lock-bit configuration with V_{IH}<RP#<V_{HH} produce spurious results and should not be attempted.
- 7. Refer to Table 4 for valid D_{IN} during a write operation.



Table 4. Command Definitions⁽⁹⁾

	Bus Cycles		First Bus Cycle			Sec	ond Bus C	ycie
Command	Reg'd.	Notes	Oper ⁽¹⁾	Addr(2)	Data ⁽³⁾	Oper ⁽¹⁾	Addr ⁽²⁾	Data ⁽³⁾
Read Array/Reset	1		Write	X	FFH			
Read Identifier Codes	≥2	4	Write	Х	90H	Read	IA	Ū
Read Status Register	2		Write	Χ	70H	Read	Х	SRD
Clear Status Register	1		Write	X	50H			
Block Erase	2	5	Write	ВА	20H	Write	BA	DOH
Byte Write	2	5,6	Write	WA	40H or 10H	Write	WA	WD
Block Erase and Byte Write Suspend	1	5	Write	Х	вон			
Block Erase and Byte Write Resume	1	5	Write	Х	DOH			
Set Block Lock-Bit	2	7	Write	BA	60H	Write	BA	01H
Set Master Lock-Bit	2	7	Write	Χ	60H	Write	Χ	F1H
Clear Block Lock-Bits	2	8	Write	Χ	60H	Write	Χ	DOH

NOTES:

- 1. BUS operations are defined in Table 3.
- 2. X=Any valid address within the device.

IA=Identifier Code Address: see Figure 7.

BA=Address within the block being erased or locked.

WA=Address of memory location to be written.

- SRD=Data read from status register. See Table 7 for a description of the status register bits.
 WD=Data to be written at location WA. Data is latched on the rising edge of WE# or CE# (whichever goes high first).
 - ID=Data read from identifier codes.
- 4. Following the Read Identifier Codes command, read operations access manufacturer, device, block lock, and master lock codes. See Section 4.2 for read identifier code data.
- 5. If the block is locked, RP# must be at V_{HH} to enable block erase or byte write operations. Attempts to issue a block erase or byte write to a locked block while RP# is V_{IH}.
- 6. Either 40H or 10H are recognized by the WSM as the byte write setup.
- 7. If the master lock-bit is set, RP# must be at V_{HH} to set a block lock-bit. RP# must be at V_{HH} to set the master lock-bit. If the master lock-bit is not set, a block lock-bit can be set while RP# is V_{IH}.
- 8. If the master lock-bit is set, RP# must be at V_{HH} to clear block lock-bits. The clear block lock-bits operation simultaneously clears all block lock-bits. If the master lock-bit is not set, the Clear Block Lock-Bits command can be done while RP# is V_{IH}.
- Commands other than those shown above are reserved by SHARP for future device implementations and should not be used.



4.1 Read Array Command

Upon initial device power-up and after exit from deep power-down mode, the device defaults to read array mode. This operation is also initiated by writing the Read Array command. The device remains enabled for reads until another command is written. Once the internal WSM has started a block erase, byte write or lock-bit configuration, the device will not recognize the Read Array command until the WSM completes its operation unless the WSM is suspended via an Erase Suspend or Byte Write Suspend command. The Read Array command functions independently of the V_{PP} voltage and RP# can be V_{IH} or V_{HH}.

4.2 Read Identifier Codes Command

The identifier code operation is initiated by writing the Read Identifier Codes command. Following the command write, read cycles from addresses shown in Figure 7 retrieve the manufacturer, device, block lock configuration and master lock configuration codes (see Table 5 for identifier code values). To terminate the operation, write another valid command. Like the Read Array command, the Read Identifier Codes command functions independently of the V_{PP} voltage and RP# can be V_{IH} or V_{HH}. Following the Read Identifier Codes command, the following information can be read:

Table 5. Identifier Codes

12210 01 1201111101 00000							
Code	Address	Data					
Manufacture Code	00000	89					
Device Code	00001	A6					
Block Lock Configuration	X0002 ⁽¹⁾						
Block is Unlocked		DQ ₀ =0					
•Block is Locked		DQ ₀ =1					
Reserved for Future Use		DQ ₁₋₇					
Master Lock Configuration	00003						
Device is Unlocked		DQ ₀ =0					
Device is Locked		DQ ₀ =1					
•Reserved for Future Use		DQ ₁₋₇					

NOTE:

 X selects the specific block lock configuration code to be read. See Figure 7 for the device identifier code memory map.

4.3 Read Status Register Command

The status register may be read to determine when a block erase, byte write, or lock-bit configuration is complete and whether the operation completed successfully. It may be read at any time by writing the Read Status Register command. After writing this command, all subsequent read operations output data from the status register until another valid command is written. The status register contents are latched on the falling edge of OE# or CE#, whichever occurs. OE# or CE# must toggle to V_{IH} before further reads to update the status register latch. The Read Status Register command functions independently of the V_{PP} voltage. RP# can be V_{IH} or V_{HH}.

4.4 Clear Status Register Command

Status register bits SR.5, SR.4, SR.3, and SR.1 are set to "1"s by the WSM and can only be reset by the Clear Status Register command. These bits indicate various failure conditions (see Table 7). By allowing system software to reset these bits, several operations (such as cumulatively erasing or locking multiple blocks or writing several bytes in sequence) may be performed. The status register may be polled to determine if an error occurre during the sequence.

To clear the status register, the Clear Status Register command (50H) is written. It functions independently of the applied V_{PP} Voltage. RP# can be V_{IH} or V_{HH} . This command is not functional during block erase or byte write suspend modes.

4.5 Block Erase Command

Erase is executed one block at a time and initiated by a two-cycle command. A block erase setup is first written, followed by an block erase confirm. This command sequence requires appropriate sequencing and an address within the block to be erased (erase changes all block data to FFH). Block preconditioning, erase, and verify are handled internally by the WSM (invisible to the system). After the two-cycle block erase sequence is written, the device automatically outputs status register data when read (see Figure 8). The CPU can detect block erase completion by analyzing the output data of the RY/BY# pin or status register bit SR.7.



When the block erase is complete, status register bit SR.5 should be checked. If a block erase error is detected, the status register should be cleared before system software attempts corrective actions. The CUI remains in read status register mode until a new command is issued.

This two-step command sequence of set-up followed by execution ensures that block contents are not accidentally erased. An invalid Block Erase command sequence will result in both status register bits SR.4 and SR.5 being set to "1". Also, reliable block erasure can only occur when $V_{CC}=V_{CC1/2}$ and $V_{PP}=V_{PPH1/2}$. In the absence of this high voltage, block contents are protected against erasure. If block erase is attempted while $V_{PP} \le V_{PPLK}$, SR.3 and SR.5 will be set to "1". Successful block erase requires that the corresponding block lock-bit be cleared or, if set, that RP#=VHH. If block erase is attempted when the corresponding block lock-bit is set and RP#=V_{IH}, SR.1 and SR.5 will be set to "1". Block erase operations with V_{IH} <RP#< V_{HH} produce spurious results and should not be attempted.

4.6 Byte Write Command

Byte write is executed by a two-cycle command sequence. Byte write setup (standard 40H or alternate 10H) is written, followed by a second write that specifies the address and data (latched on the rising edge of WE#). The WSM then takes over, controlling the byte write and write verify algorithms internally. After the byte write sequence is written, the device automatically outputs status register data when read (see Figure 9). The CPU can detect the completion of the byte write event by analyzing the RY/BY# pin or status register bit SR.7.

When byte write is complete, status register bit SR.4 should be checked. If byte write error is detected, the status register should be cleared. The internal WSM verify only detects errors for "1"s that do not successfully write to "0"s. The CUI remains in read status register mode until it receives another command.

Reliable byte writes can only occur when $V_{CC}=V_{CC1/2}$ and $V_{PP}=V_{PPH1/2}$. In the absence of this high voltage, memory contents are protected against byte writes. If byte write is attempted while $V_{PP} \le V_{PPLK}$, status register bits SR.3 and SR.4 will be set to "1".

Successful byte write requires that the corresponding block lock-bit be cleared or, if set, that RP#= V_{HH} . If byte write is attempted when the corresponding block lock-bit is set and RP#= V_{IH} , SR.1 and SR.4 will be set to "1". Byte write operations with V_{IH} <RP#< V_{HH} produce spurious results and should not be attempted.

4.7 Block Erase Suspend Command

The Block Erase Suspend command allows block-erase interruption to read or byte-write data in another block of memory. Once the block-erase process starts, writing the Block Erase Suspend command requests that the WSM suspend the block erase sequence at a predetermined point in the algorithm. The device outputs status register data when read after the Block Erase Suspend command is written. Polling status register bits SR.7 and SR.6 can determine when the block erase operation has been suspended (both will be set to "1"). RY/BY# will also transition to V_{OH}. Specification t_{WHRH2} defines the block erase suspend latency.

At this point, a Read Array command can be written to read data from blocks other than that which is suspended. A Byte Write command sequence can also be issued during erase suspend to program data in other blocks. Using the Byte Write Suspend command (see Section 4.8), a byte write operation can also be suspended. During a byte write operation with block erase suspended, status register bit SR.7 will return to "0" and the RY/BY# output will transition to V_{OL}. However, SR.6 will remain "1" to indicate block erase suspend status.

The only other valid commands while block erase is suspended are Read Status Register and Block Erase Resume. After a Block Erase Resume command is written to the flash memory, the WSM will continue the block erase process. Status register bits SR.6 and SR.7 will automatically clear and RY/BY# will return to V_{OL} . After the Erase Resume command is written, the device automatically outputs status register data when read (see Figure 10). V_{PP} must remain at $V_{PPH1/2}$ (the same V_{PP} level used for block erase) while block erase is suspended. RP# must also remain at V_{IH} or V_{HH} (the same RP# level used for block erase). Block erase cannot resume until byte write operations initiated during block erase suspend have completed.



4.8 Byte Write Suspend Command

The Byte Write Suspend command allows byte write interruption to read data in other flash memory locations. Once the byte write process starts, writing the Byte Write Suspend command requests that the WSM suspend the byte write sequence at a predetermined point in the algorithm. The device continues to output status register data when read after the Byte Write Suspend command is written. Polling status register bits SR.7 and SR.2 can determine when the byte write operation has been suspended (both will be set to "1"). RY/BY# will also transition to VOH. Specification tWHRH1 defines the byte write suspend latency.

At this point, a Read Array command can be written to read data from locations other than that which is suspended. The only other valid commands while byte write is suspended are Read Status Register and Byte Write Resume. After Byte Write Resume command is written to the flash memory, the WSM will continue the byte write process. Status register bits SR.2 and SR.7 will automatically clear and RY/BY# will return to V_{OL}. After the Byte Write Resume command is written, the automatically outputs status register data when read (see Figure 11). Vpp must remain at VppH1/2 (the same V_{PP} level used for byte write) while in byte write suspend mode. RP# must also remain at VIH or VHH (the same RP# level used for byte write).

4.9 Set Block and Master Lock-Bit Commands

A flexible block locking and unlocking scheme is enabled via a combination of block lock-bits and a master lock-bit. The block lock-bits gate program and erase operations while the master lock-bit gates block-lock bit modification. With the master lock-bit not set, individual block lock-bits can be set using the Set Block Lock-Bit command. The Set Master Lock-Bit command, in conjunction with RP#=V_{HH}, sets the master lock-bit. After the master lock-bit is set, subsequent setting of block lock-bits requires both the Set Block Lock-Bit command and V_{HH} on the RP# pin. See Table 6 for a summary of hardware and software write protection options.

Set block lock-bit and master lock-bit are executed by a two-cycle command sequence. The set block or master lock-bit setup along with appropriate block or device address is written followed by either the set block lock-bit confirm (and an address within the block to be locked) or the set master lock-bit confirm (and any device address). The WSM then controls the set lock-bit algorithm. After the sequence is written, the device automatically outputs status register data when read (see Figure 12). The CPU can detect the completion of the set lock-bit event by analyzing the RY/BY# pin output or status register bit SR.7.

When the set lock-bit operation is complete, status register bit SR.4 should be checked. If an error is detected, the status register should be cleared. The CUI will remain in read status register mode until a new command is issued.

This two-step sequence of set-up followed by execution ensures that lock-bits are not accidentally set. An invalid Set Block or Master Lock-Bit command will result in status register bits SR.4 and SR.5 being set to "1". Also, reliable operations occur only when $V_{\rm CC}=V_{\rm CC1/2}$ and $V_{\rm PP}=V_{\rm PPH1/2}$. In the absence of this high voltage, lock-bit contents are protected against alteration.

A successful set block lock-bit operation requires that the master lock-bit be cleared or, if the master lock-bit is set, that RP#= V_{HH} . If it is attempted with the master lock-bit set and RP#= V_{IH} , SR.1 and SR.4 will be set to "1" and the operation will fail. Set block lock-bit operations while V_{IH} <RP#< V_{HH} produce spurious results and should not be attempted. A successful set master lock-bit operation requires that RP#= V_{HH} . If it is attempted with RP#= V_{IH} , SR.1 and SR.4 will be set to "1" and the operation will fail. Set master lock-bit operations with V_{IH} <RP#< V_{HH} produce spurious results and should not be attempted.

PRODUCT PREVIEW

4.10 Clear Block Lock-Bits Command

All set block lock-bits are cleared in parallel via the Clear Block Lock-Bits command. With the master lock-bit not set, block lock-bits can be cleared using only the Clear Block Lock-Bits command. If the master lock-bit is set, clearing block lock-bits requires both the Clear Block Lock-Bits command and V_{HH} on the RP# pin. See Table 6 for a summary of hardware and software write protection options.

Clear block lock-bits operation is executed by a two-cycle command sequence. A clear block lock-bits setup is first written. After the command is written, the device automatically outputs status register data when read (see Figure 13). The CPU can detect completion of the clear block lock-bits event by analyzing the RY/BY# Pin output or status register bit SR.7.

When the operation is complete, status register bit SR.5 should be checked. If a clear block lock-bit error is detected, the status register should be cleared. The CUI will remain in read status register mode until another command is issued.

This two-step sequence of set-up followed by execution ensures that block lock-bits are not accidentally cleared. An invalid Clear Block Lock-Bits command sequence will result in status register bits SR.4 and SR.5 being set to "1". Also, a reliable clear block lock-bits operation can only occur when V_{CC}=V_{CC1/2} and V_{PP}=V_{PPH1/2}. If a clear block lock-bits operation is attempted while V_{PP}≤V_{PPIK}, SR.3 and SR.5 will be set to "1". In the absence of this high voltage, the block lock-bits content are protected against alteration. A successful clear block lock-bits operation requires that the master lock-bit is not set or, if the master lock-bit is set, that RP#=VHH. If it is attempted with the master lock-bit set and RP#=V1H, SR.1 and SR.5 will be set to "1" and the operation will fail. A clear block lock-bits operation with VIH<RP#<VHH produce spurious results and should not be attempted.

If a clear block lock-bits operation is aborted due to V_{PP} or V_{CC} transitioning out of valid range or RP# active transition, block lock-bit values are left in an undetermined state. A repeat of clear block lock-bits is required to initialize block lock-bit contents to known values. Once the master lock-bit is set, it cannot be cleared.

Table 6. Write Protection Alternatives

Operation	Master Lock-Bit	Block Lock-Bit	RP#	Effect
Block Erase or		0	V _{IH} or V _{HH}	Block Erase and Byte Write Enabled
Byte Write	X	1	V _{iH}	Block is Locked. Block Erase and Byte Write Disabled
·			V _{HH}	Block Lock-Bit Override. Block Erase and Byte Write Enabled
Set Block	0	X	V _{IH} or V _{HH}	Set Block Lock-Bit Enabled
Lock-Bit	1	X	V _{IH}	Master Lock-Bit is Set. Set Block Lock-Bit Disabled
			V _{HH}	Master Lock-Bit Override. Set Block Lock-Bit Enabled
Set Master	X	X	V _{IH}	Set Master Lock-Bit Disabled
Lock-Bit			V _{HH}	Set Master Lock-Bit Enabled
Clear Block	0	X	V _{IH} or V _{HH}	Clear Block Lock-Bits Enabled
Lock-Bits	1	X	V _{IH}	Master Lock-Bit is Set. Clear Block Lock-Bits Disabled
			V _{HH}	Master Lock-Bit Override. Clear Block Lock-Bits Enabled

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LH28F008SC-V SmartVoltage Flash MEMORY

Table 7. Status Register Definition



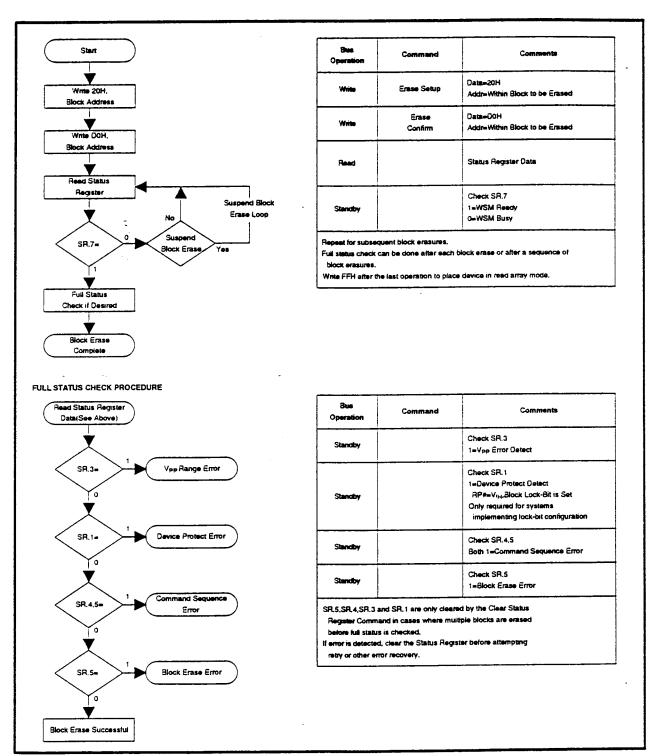


Figure 8. Automated Block Erase Flowchart



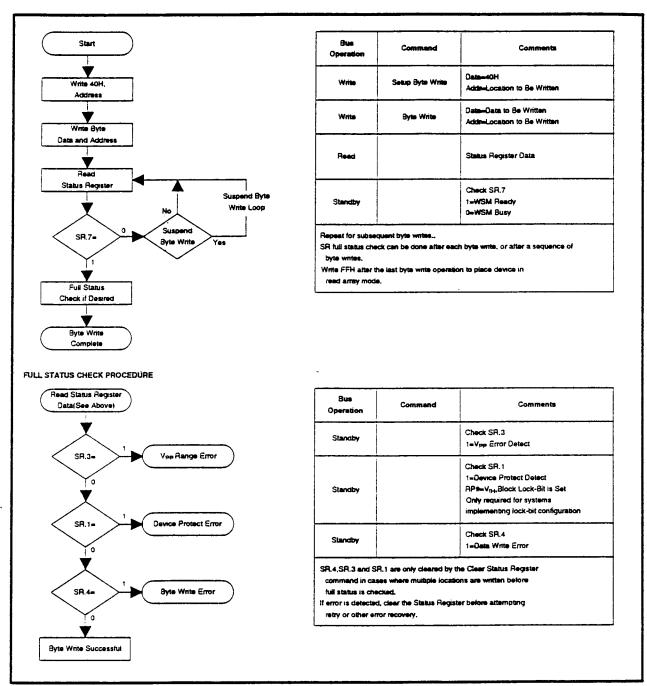


Figure 9. Automated Byte Write Flowchart



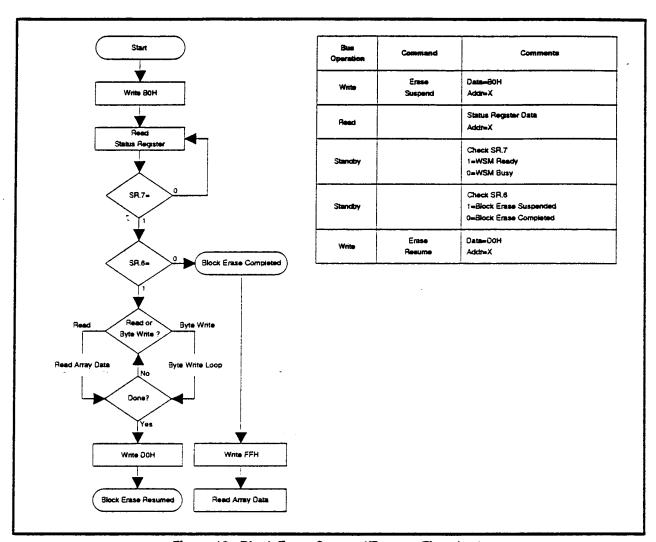


Figure 10. Block Erase Suspend/Resume Flowchart

PRODUCT PREVIEW 21

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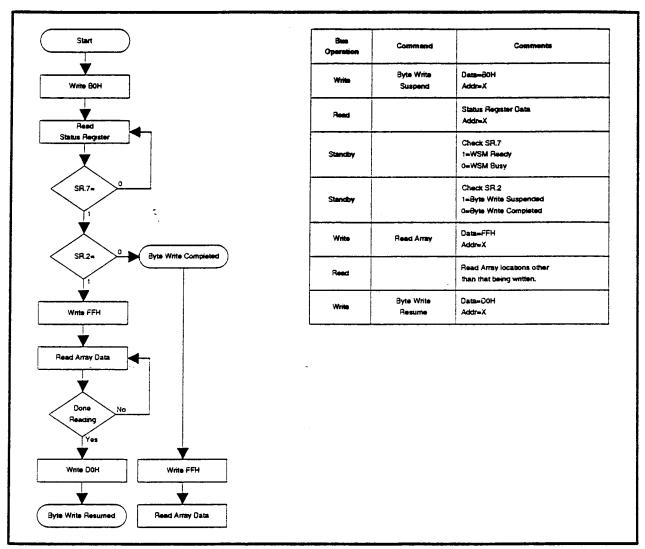


Figure 11. Byte Write Suspend/Resume Flowchart



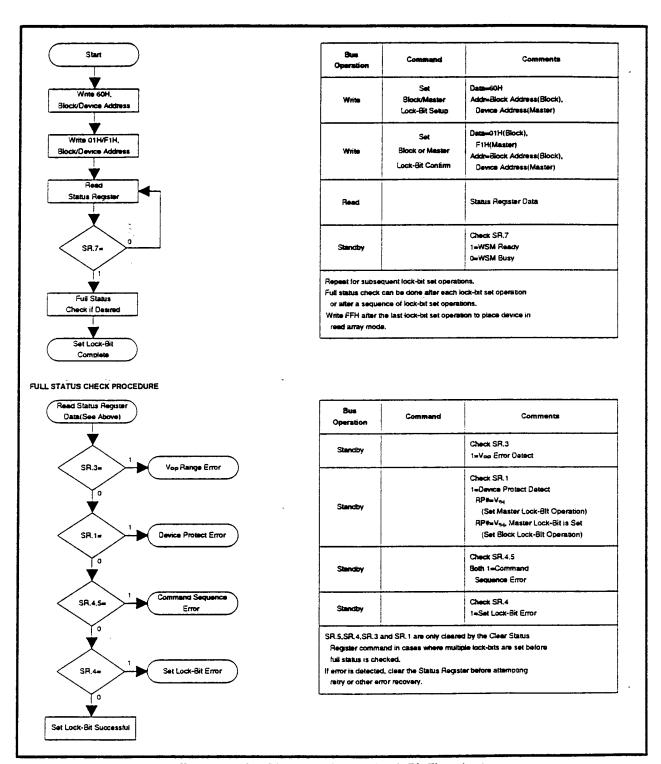


Figure 12. Set Block and Master Lock-Bit Flowchart

PRODUCT PREVIEW 23

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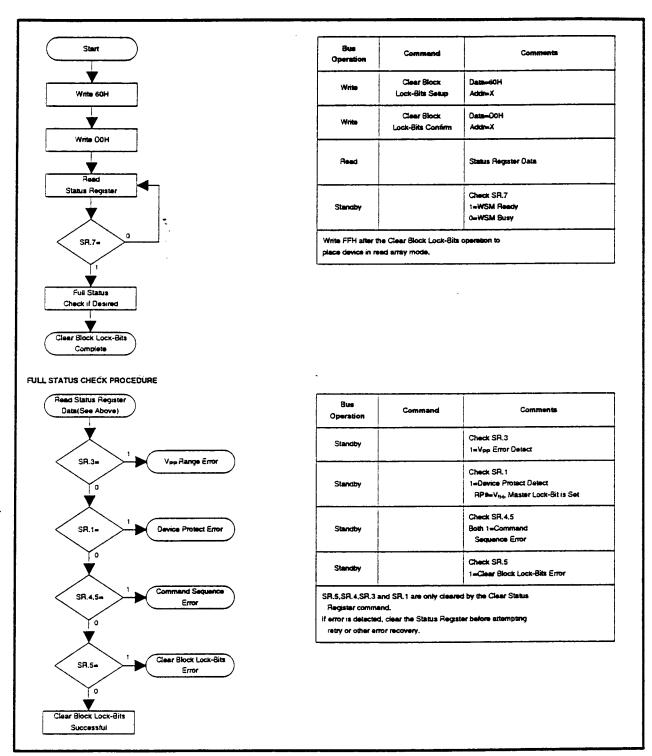


Figure 13. Clear Block Lock-Bits Flowchart



5 DESIGN CONSIDERATIONS

5.1 Three-Line Output Control

The device will often be used in large memory arrays. SHARP provides three control inputs to accommodate multiple memory connections. Three-line control provides for:

- a. Lowest possible memory power dissipation.
- Complete assurance that data bus contention will not occur.

To use these control inputs efficiently, an address decoder should enable CE# while OE# should be connected to all memory devices and the system's READ# control line. This assures that only selected memory devices have active outputs while deselected memory devices are in standby mode. RP# should be connected to the system POWERGOOD signal to prevent unintended writes during system power transitions. POWERGOOD should also toggle during system reset.

5.2 RY/BY# and Block Erase, Byte Write, and Lock-Bit Configuration Polling

RY/BY# is a full CMOS output that provides a hardware method of detecting block erase, byte write and lock-bit configuration completion. It transitions low after block erase, byte write, or lock-bit configuration commands and returns to V_{OH} when the WSM has finished executing the internal algorithm.

RY/BY# can be connected to an interrupt input of the system CPU or controller. It is active at all times. RY/BY# is also V_{OH} when the device is in block erase suspend (with byte write inactive), byte write suspend or deep power-down modes.

5.3 Power Supply Decoupling

Flash memory power switching characteristics require careful device decoupling. System designers are interested in three supply current issues; standby current levels, active current levels and transient peaks produced by falling and rising edges of CE# and OE#. Transient current magnitudes depend on the device outputs' capacitive and inductive loading. Two-line control and proper decoupling capacitor selection will suppress transient voltage peaks. Each device should have a 0.1 µF ceramic capacitor connected between its V_{CC} and GND and between its VPP and GND. These high-frequency, low inductance capacitors should be placed as close as possible to package leads. Additionally, for every eight devices. a 4.7 µF electrolytic capacitor should be placed at the array's power supply connection between V_{CC} and GND. The bulk capacitor will overcome voltage slumps caused by PC board trace inductance.

5.4 V_{PP} Trace on Printed Circuit Boards

Updating flash memories that reside in the target system requires that the printed circuit board designer pay attention to the V_{PP} Power supply trace. The V_{PP} pin supplies the memory cell current for byte writing and block erasing. Use similar trace widths and layout considerations given to the V_{CC} power bus. Adequate V_{PP} supply traces and decoupling will decrease V_{PP} voltage spikes and overshoots.



5.5 V_{CC}, V_{PP}, RP# Transitions

Block erase, byte write and lock-bit configuration are not guaranteed if V_{PP} falls outside of a valid $V_{PPH1/2}$ range, V_{CC} falls outside of a valid $V_{CC1/2}$ range, or RP# \neq V $_{IH}$ or V $_{HH}$. If V_{PP} error is detected, status register bit SR.3 is set to "1" along with SR.4 or SR.5, depending on the attempted operation. If RP# transitions to V $_{IL}$ during block erase, byte write, or lock-bit configuration, RY/BY# will remain low until the reset operation is complete. Then, the operation will abort and the device will enter deep power-down. The aborted operation may leave data partially altered. Therefore, the command sequence must be repeated after normal operation is restored. Device power-off or RP# transitions to V_{IL} clear the status register.

The CUI latches commands issued by system software and is not altered by V_{pp} or CE# transitions or WSM actions. Its state is read array mode upon power-up, after exit from deep power-down or after V_{CC} transitions below V_{LKO} .

After block erase, byte write, or lock-bit configuration, even after V_{PP} transitions down to V_{PPLK}, the CUI must be placed in read array mode via the Read Array command if subsequent access to the memory array is desired.

5.6 Power-Up/Down Protection

The device is designed to offer protection against accidental block erasure, byte writing, or lock-bit configuration during power transitions. Upon power-up, the device is indifferent as to which power supply (V_{PP} or V_{CC}) powers-up first. Internal circuitry resets the CUI to read array mode at power-up.

A system designer must guard against spurious writes for V_{CC} voltages above V_{LKO} when V_{PP} is active. Since both WE# and CE# must be low for a command write, driving either to V_{IH} will inhibit writes. The CUI's two-step command sequence architecture provides added level of protection against data alteration.

In-system block lock and unlock capability prevents inadvertent data alteration. The device is disabled while RP#=V_{IL} regardless of its control inputs state.

5.7 Power Dissipation

When designing portable systems, designers must consider battery power consumption not only during device operation, but also for data retention during system idle time. Flash memory's nonvolatility increases usable battery life because data is retained when system power is removed.

In addition, deep power-down mode ensures extremely low power consumption even when system power is applied. For example, portable computing products and other power sensitive applications that use an array of devices for solid-state storage can consume negligible power by lowering RP# to V_{1L} standby or sleep modes. If access is again needed, the devices can be read following the t_{PHQV} and t_{PHWL} wake-up cycles required after RP# is first raised to V_{1H}. See AC Characteristics— Read Only and Write Operations and Figures 17, 18 and 19 for more information.

PRODUCT PREVIEW

6 ELECTRICAL SPECIFICATIONS

6.1 Absolute Maximum Ratings*

Commercial Operating Temperature During Read, Block Erase, Byte Write and Lock-Bit Configuration0°C to +70°C(1) Temperature under Bias10°C to +80°C
Storage Temperature65°C to +125°C
Voltage On Any Pin
(except V _{CC} , V _{PP} , and RP#)2.0V to +7.0V ⁽²⁾
V _{CC} Supply Voltage2.0V to +7.0V(2)
V _{PP} Update Voltage during Block Erase, Byte Write and Lock-Bit Configuration2.0V to +14.0V(2.3)
RP# Voltage with Respect to GND during Lock-Bit Configuration Operations2.0V to +14.0V(2.3)
Output Short Circuit Current 100mA(4)

NOTICE: This datasheet contains information only products in the design phase of development. Do not finalize a design with this information. Revised information will be published when the product is available. Verify with your local SHARP Sales office that you have the latest datasheet before finalizing all design.

"WARNING: Stressing the device beyond the "Absolute Maximum Ratings" may cause permanent damage. These are stress ratings only. Operation beyond the "Operating Conditions" is not recommended and extended exposure beyond the "Operating Conditions" may affect device reliability.

NOTES:

- Operating temperature is for commercial product defined by this specification.
- All specified voltages are with respect to GND. Minimum DC voltage is -0.5V on input/output pins and -0.2V on V_{CC} and V_{PP} pins. During transitions, this level may undershoot to -2.0V for periods <20ns. Maximum DC voltage on input/output pins and V_{CC} is V_{CC}+0.5V which, during transitions, may overshoot to V_{CC}+2.0V for periods <20ns.
- Maximum DC voltage on V_{PP} and RP# may overshoot to +14.0V for periods <20ns.
- Output shorted for no more than one second. No more than one output shorted at a time.

6.2 Operating Conditions

Temperature and V_{CC} Operating Conditions

Symbol	Parameter	Notes	Min	Max	Unit	Test Condition
T_{A}	Operating Temperature		0	+70	°C	Ambient Temperature
V _{CC1}	V _{CC} Supply Voltage (5V±5%)		4.75	5.25	V	1
Vccz	V _{CC} Supply Voltage (5V±10%)		4.50	5.50	V	

6.2.1 CAPACITANCE(1)

 $T_{\Delta}=+25$ °C, f=1MHz

Symbol	Parameter	Typ	Max	Unit	Condition
C _{IN}	Input Capacitance	6	8	ρF	V _{IN} =0.0V
COUT	Output Capacitance	8	12	ρF	V _{OLIT} =0.0V

1. Sampled, not 100% tested.

PRODUCT PREVIEW



6.2.2 AC INPUT/OUTPUT TEST CONDITIONS

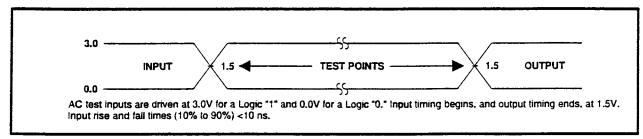


Figure 14. Transient Input/Output Reference Waveform for V_{CC}=5V±5% (High Speed Testing Configuration)

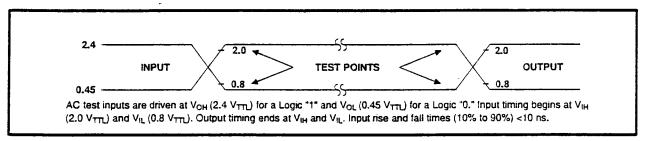


Figure 15. Transient Input/Output Reference Waveform for V_{CC}=5V±10% (Standard Testing Configuration)

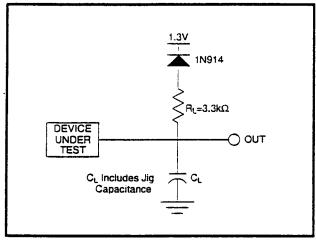


Figure 16. Transient Equivalent Testing

Load Circuit

Test Configuration Capacitance Loading Value

Test Configuration	C _t (pF)
V _{CC} =5V±5%	30
V _{CC} =5V±10%	100



6.2.3 DC CHARACTERISTICS

DC Characteristics

	DC Characteristics V _{CC} =5V Test								
		Test							
Sym	Parameter	Notes	Тур	Max	Unit	Conditions			
1,,	Input Load Current	1		±1	μA	V _{CC} =V _{CC} Max, V _{IN} =V _{CC} or GND			
1,0	Output Leakage Current	1		±10	μA	V _{CC} =V _{CC} Max, V _{OUT} =V _{CC} or GND			
Iccs	V _{CC} Standby Current	1,3,6		100	μА	CMOS Inputs			
003	,					V _{CC} =V _{CC} Max			
		1				CE#=RP#=V _{CC} ±0.2V			
				2	mA	TTL Inputs			
		İ				V _{CC} =V _{CC} Max			
		1				CE#=RP#=V _{IH}			
ICCD	V _{CC} Deep Power-Down	1		16	μA	RP#=GND±0.2V			
CCD	Current	İ				I _{OUT} (RY/BY#)=0mA			
ICCR	V _{CC} Read Current	1,5,6		35	mA	CMOS Inputs			
CON						V _{CC} =V _{CC} Max, CE#=GND			
						f=8MHz, I _{OUT} =0mA			
		-		50	mA.	TTL Inputs			
		ļ				V _{CC} =V _{CC} Max, CE#=GND			
						f=8MHz, I _{OUT} =0mA			
Iccw	V _{CC} Byte Write or	1,7		35	mA	V _{PP} =5.0V±10%			
	Set Lock-Bit Current			30	mA	V _{pp} =12.0V±5%			
ICCE	V _{CC} Block Erase or Clear	1,7		30	mA_	V _{PP} =5.0V±10%			
	Block Lock-Bits Current			25	mA	V _{PP} =12.0V±5%			
Iccws	V _{CC} Byte Write or Block	1,2		10	mA	CE#=V _{IH}			
CCES	Erase Suspend Current								
IPPS	V _{PP} Standby or Read	1 [±15	μΑ	V _{PP} ≤V _{CC}			
IPPR	Current			200	μА	V _{PP} >V _{CC}			
IPPD	V _{PP} Deep Power-Down	1		5	μA	RP#=GND±0.2V			
	Current								
I _{PPW}	V _{PP} Byte Write or Set	1,7		40	mA_	V _{PP} =5.0V±10%			
	Lock-Bit Current			15	mA	V _{PP} =12.0V±5%			
IPPE	V _{PP} Block Erase or	1,7		20	mA_	V _{PP} =5.0V±10%			
-	Clear Lock-Bit Current			15	mA	V _{pp} =12.0V±5%			
PPWS	V _{PP} Byte Write or Block Erase	1		200	μА	V _{PP} =V _{PPH1/2}			
PPES	Suspend Current				<u> </u>				



DC Characteristics (Continued)

			V _{CC} =5V			Test
Sym	Parameter	Notes	Min	Max	Unit	Conditions
V_{ii}	Input Low Voltage	7	-0.5	0.8	V	
V _{IH}	Input High Voltage	7	2.0	V _{CC} +0.5	٧	
VOL	Output Low Voltage	3,7		0.45	V	V _{CC} =V _{CC} Min, I _{OI} =5.8mA
V _{OH1}	Output High Voltage (TTL)	3,7	2.4		V	V _{CC} =V _{CC} Min, l _{OH} =-2.5mA
V _{OH2}	Output High Voltage (CMOS)	3,7	0.85 V _{CC}		٧	V _{CC} =V _{CC} Min, I _{OH} =-2.5µA
			V _{CC} -0.4		V	V _{CC} =V _{CC} Min, I _{OH} =-100μA
V _{PPLK}	V _{PP} Lockout during Normal Operations	4,7		1.5	V	
V _{PPH1}	V _{PP} during Byte Write, Block Erase, or Lock-Bit Operations		4.5	5.5	V	
V _{PPH2}	V _{PP} during Byte Write, Block Erase, or Lock-Bit Operations		11.4	12.6	V	
VLKO	V _{CC} Lockout Voltage		2.0		V	
V _{HH}	RP# Unlock Voltage	8	11.4	12.6	٧	Set Master Lock-Bit Override Master and Block Lock-Bit

NOTES:

- 1. All currents are in RMS unless otherwise noted. These currents are valid for all product versions (packages and speeds). Contact SHARP's Application Support Hotline or your local sales office for information about typical
- 2. I_{CCWS} and I_{CCES} are specified with the device de-selected. If read or byte written while in erase suspend mode, the device's current draw is the sum of I_{CCWS} or I_{CCES} and I_{CCR} or I_{CCW}, respectively.
- 3. Includes RY/BY#.
- Block erases, byte writes, and lock-bit configurations are inhibited when V_{PP}≤V_{PPLK}, and not guaranteed in the range between $V_{PPLK}(max)$ and $V_{PPH1}(min)$, between $V_{PPH1}(max)$ and $V_{PPH2}(min)$, and above $V_{PPH2}(max)$. 5. Automatic Power Savings (APS) reduces typical I_{CCR} to 1mA at 5V V_{CC} in static operation.
- 6. CMOS inputs are either $V_{CC}\pm0.2V$ or GND $\pm0.2V$. TTL inputs are either V_{IL} or V_{IH} .
 - 7. Sampled, not 100% tested.
 - 8. Master lock-bit set operations are inhibited when $RP\#=V_{IH}$. Block lock-bit configuration operations are inhibited when the master lock-bit is set and RP#= V_{IH} . Block erases and byte writes are inhibited when the corresponding block-lock bit is set and RP#= V_{IH} . Block erase, byte write, and lock-bit configuration operations are not guaranteed with VIH<RP#<VHH.



6.2.4 AC CHARACTERISTICS - READ-ONLY OPERATIONS(1)

 $V_{CC}=5V\pm0.5V$, $5V\pm0.25V$, $T_{A}=0^{\circ}C$ to $+70^{\circ}C$

			±5%		008SC- 5 ⁽⁵⁾					
	Versions ⁽⁴⁾	V _{CC}	±10%				008SC- 0 ⁽⁶⁾		008SC- 20 ⁽⁶⁾	
Sym	Parameter		Notes	Min	Max	Min	Max	Min	Max	Unit
TAVAV	Read Cycle Time			85		90		120		ns
TAVOV	Address to Output Delay	/			85		90		120	ns
telov	CE# to Output Delay		2		85		90		120	ns
teHOV	RP# High to Output Dela	ay			400		400		400	ns
tGLOV	OE# to Output Delay		2		40		45		50	ns
tFLOX	CE# to Output in Low Z		3	0		0		0		ns
teHOZ	CE# High to Output in H	igh Z	3		55		55		55	ns
tGLOX	OE# to Output in Low Z		3	0		0		0		ns
tGHOZ	OE# High to Output in H	ligh Z	3		10		10		15	ns
tон	Output Hold from Addre CE# or OE# Change, Whichever Occurs First	SS,	3	0		0		0		ns

NOTES:

- 1. See AC Input/Output Reference Waveform for maximum allowable input slew rate.
- 2. OE# may be delayed up to t_{ELQV}-t_{GLQV} after the falling edge of CE# without impact on t_{ELQV}.
- 3. Sampled, not 100% tested.
- 4. See Ordering Information for device speeds (valid operational combinations).
- 5. See Transient Input/Output Reference Waveform and Transient Equivalent Testing Load Circuit (High Speed Configuration) for testing characteristics.
- 6. See Transient Input/Output Reference Waveform and Transient Equivalent Testing Load Circuit (Standard Configuration) for testing characteristics.

SHARP

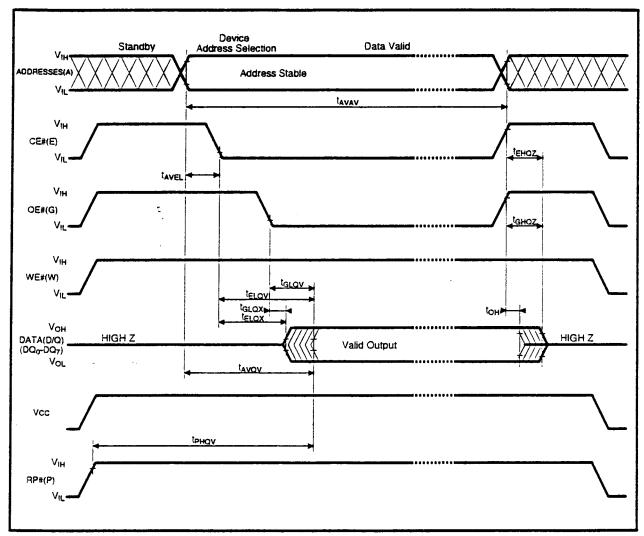


Figure 17. AC Waveform for Read Operations





6.2.5 AC CHARACTERISTICS - WRITE OPERATION(1)

 $V_{CC}=5V\pm0.5V$, $5V\pm0.25V$, $T_{A}=0^{\circ}C$ to $+70^{\circ}C$

		V _{CC} :	±5%		008SC- 5 ⁽⁶⁾					
	Versions ⁽⁵⁾	V _{CC} ±	:10%			LH28F008SC- V90 ⁽⁷⁾		LH28F008SC- V120 ⁽⁷⁾		
Sym	Parameter		Notes	Min	Max	Min	Max	Min	Max	Unit
tavav	Write Cycle Time			85		90		120		ns
t _{PHWL}	RP# High Recovery to W Going Low	VE#	2	1		1		1		μs
t _{FI WI}	CE# Setup to WE# Goin	g Low		10		10		10		ns
twi wh	WE# Pulse Width			40		40		40		ns
^t РННWН	RP# V _{HH} Setup to WE# High	Going	2	100		100		100		ns
t _{VPWH}	Vpp Setup to WE# Going	High	2	100		100		100		ns
t _{AVWH}	Address Setup to WE# 0	Soing	3	40		40		40		ns
tovwh	Data Setup to WE# Goin	a High	3	40		40		40		ns
twhox	Data Hold from WE# Hig			5		5		5		ns
twhax	Address Hold from WE#	High		5		5		5		ns
twhen	CE# Hold from WE# Hig			10		10		10		ns
t _{w+w1}	WE# Pulse Width High			30		30		30		ns
twhat.	WE# High to RY/BY# Go Low	oing			90		90		90	ns
twigi	Write Recovery before R	lead		0		0		0		ns
^t avvl	V _{PP} Hold from Valid SRI RY/BY# High	Ο,	2,4	0		0		0		ns
^t QVPH	RP# V _{HH} Hold from Valid RY/BY# High	SRD,	2,4	0		0		0		ns

NOTES:

- 1. Read timing characteristics during block erase, byte write and lock-bit configuration operations are the same as during read-onry operations. Refer to AC Characteristics for read-only operations.
- 2. Sampled, not 100% tested.
- Refer to Table 4 for valid A_{IN} and D_{IN} for block erase, byte write, or lock-bit configuration.
 V_{PP} should be held at V_{PPH1/2} (and if necessary RP# should be held at V_{HH}) until determination of block erase, byte write, or lock-bit configuration success (SR.1/3/4/5=0).
- 5. See Ordering Information for device speeds (valid operational combinations).
- 6. See Transient Input/Output Reference Waveform and Transient Equivalent Testing Load Circuit (High Seed Configuration) for testing characteristics.
- 7. See Transient Input/Output Reference Waveform and Transient Equivalent Testing Load Circuit (Standard Configuration) for testing characteristics.



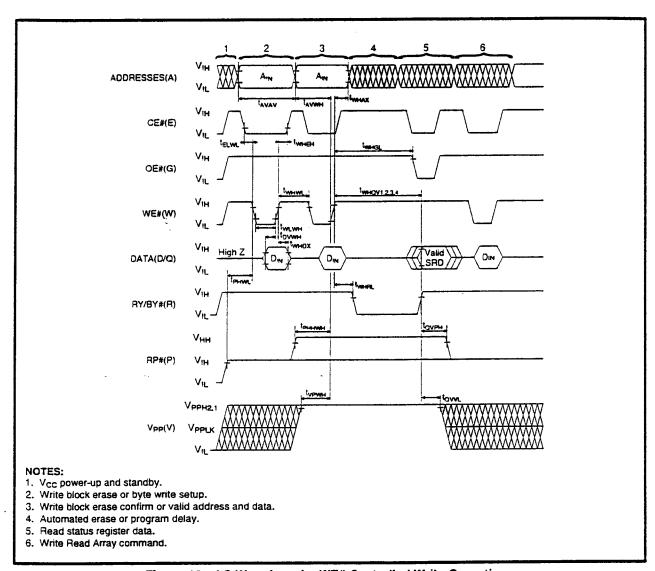


Figure 18. AC Waveform for WE#-Controlled Write Operations

6.2.6 ALTERNATIVE CE#-CONTROLLED WRITES(1)

V_a=5V±0.5V. 5V±0.25V. TA=0°C to +70°C

	Versions ⁽⁵⁾ V _{CC} ±			LH28F	008SC- 5 ⁽⁶⁾	10 +70				
			10%				008SC- 0 ⁽⁷⁾	LH28F008SC- V120 ⁽⁷⁾		
Sym	Parameter		Notes	Min	Max	Min	Max	Min	Max	Unit
TAVAV	Write Cycle Time			85		90		120		ns
^t PHEL	RP# High Recovery to C Going Low	E#	2	1		1		1		μs
twiFL	WE# Setup to CE# Going	g Low		0		0		0		ns
t _{FI FH}	CE# Pulse Width			50		50		50		ns
^t PHHEH	RP# V _{HH} Setup to CE# 0 High	Boing	2	100		100		100		ns
t _{VPFH}	V _{PP} Setup to CE# Going	High	2	100		100		100		ns
t _{AVEH}	Address Setup to CE# G		3	40		40		40		ns
t _{DVEH}	Data Setup to CE# Going	g High	3	40		40		40		ns
t _{EHDX}	Data Hold from CE# High	1		5		5		5		ns
t _{EHAX}	Address Hold from CE# I	High		5		5		5		ns
t _{EHWH}	WE# Hold from CE# High	h		0		0		0		ns
t _{EHEI}	CE# Pulse Width High			25		25		25		ns
t _{EHBI}	CE# High to RY/BY# Go	ing Low			90		90		90	ns
t _{EHGL}	Write Recovery before R	ead		0		0		0		ns
^t avvl	V _{PP} Hold from Valid SRD RY/BY# High	Ο,	2,4	0		0		0		ns
^t QVPH	RP# V _{HH} Hold from Valid RY/BY# High	SRD,	2,4	0		0		0		ns

NOTES:

- 1. In systems where CE# defines the write pulse width (within a longer WE# timing waveform), all setup, hold, and inactive WE# times should be measured relative to the CE# waveform.
- 2. Sampled, not 100% tested.
- Refer to Table 4 for valid A_{IN} and D_{IN} for block erase, byte write, or lock-bit configuration.
 V_{PP} should be held at V_{PPH1/2} (and if necessary RP# should be held at V_{HH}) until determination of block erase, byte write, or lock-bit configuration success (SR.1/3/4/5=0).
- 5. See Ordering Information for device speeds (valid operational combinations).
- 6. See Transient Input/Output Reference Waveform and Transient Equivalent Testing Load Circuit (High Seed Configuration) for testing characteristics.
- 7. See Transient Input/Output Reference Waveform and Transient Equivalent Testing Load Circuit (Standard Configuration) for testing characteristics.

SHARP

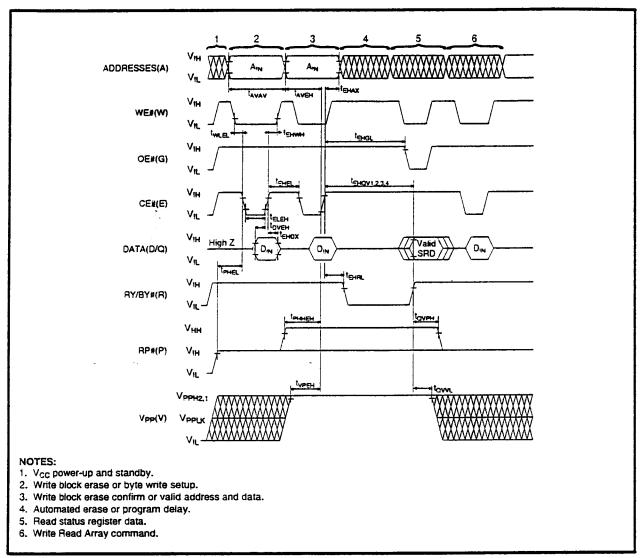


Figure 19. Alternate AC Waveform for CE#-Controlled Write Operations



6.2.7 RESET OPERATIONS

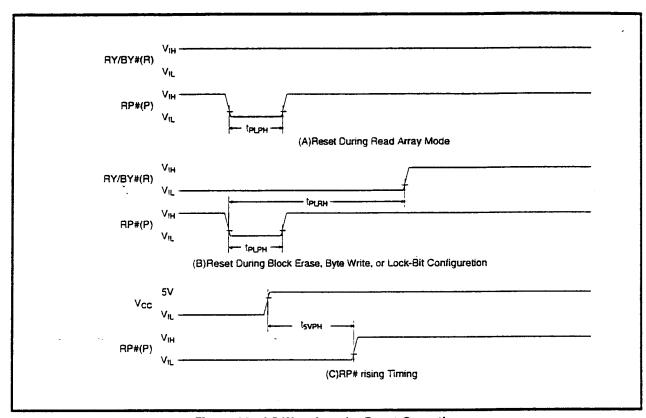


Figure 20. AC Waveform for Reset Operation

Reset AC Specifications(1)

			V _{CC}		
Sym	Parameter	Notes	Min	Max	Unit
t _{PLPH}	RP# Pulse Low Time (If RP# is tied to V _{CC} , this specification is not applicable)		100		ns
^t PLRH	RP# Low to Reset during Block Erase, Byte Write, or Lock-Bit Configuration	2,3		12	μs
t _{svph}	V _{CC} 4.5V to RP# High	4	100		ns

NOTES:

- 1. These specifications are valid for all product versions (packages and speeds).
- 2. If RP# is asserted while a block erase, byte write, or lock-bit configuration operation is not executing, the reset will complete within 100ns.
- 3. A reset time, t_{PHQV}, is required from the latter of RY/BY# or RP# going high until outputs are valid.
- 4. When the device power-up, holding RP# low minimum 100ns is required after V_{CC} has been in predefined range and also has been in stable there.



6.2.8 BLOCK ERASE, BYTE WRITE AND LOCK-BIT CONFIGURATION PERFORMANCE(3,4)

V_{CC}=5V±0.5V, 5V±0.25V, T_A=0°C to +70°C

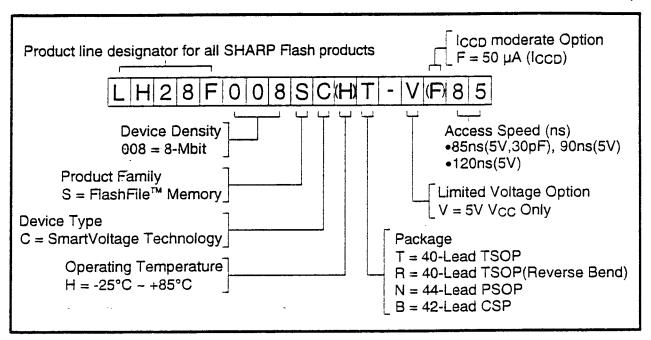
			V _{pp} =5V		V _{pp} =12V				
Sym	Parameter	Notes	Min	Typ ⁽¹⁾	Max	Min	Typ ⁽¹⁾	Max	Unit
twHQV1	Byte Write Time	2	6.5	8	TBD	4.8	6	TBD	μs
	Block Write Time	2	0.4	0.5	TBD	0.3	0.4	TBD	sec
twhqv2	Block Erase Time	2	0.9	1.1	TBD	0.3	1.0	TBD	sec
twhqv3	Set Lock-Bit Time	2	9.5	12	TBD	7.8	10	TBD	μs
twHQV4	Clear Block Lock-Bits Time	2	0.9	1.1	TBD	0.3	1.0	TBD	sec
twheht	Byte Write Suspend Latency Time to Read			5	6		4	5	μs
twhRH2	Erase Suspend Latency Time to Read			9.6	12		9.6	12	μs

NOTES

- 1. Typical values measured at T_A =+25°C and nominal voltages. Assumes corresponding lock-bits are not set. Subject to change based on device characterization.
- 2. Excludes system-level overhead.
- 3. These performance numbers are valid for all speed versions.
- 4. Sampled but not 100% tested.

7 ADDITIONAL INFORMATION

7.1 Ordering Information



		Valid Opera	tional Combinations
Option	Order Code	V _{CC} =5.0±10% 100pF load, TTL I/O Levels	V _{CC} =5.0±5% 30pF load, 1.5V I/O Levels
1	LH28F008SCX-V85	LH28F008SC-V90	LH28F008SC-V85
2	LH28F008SCX-V12	LH28F008SC-V120	



LH28F008SC SmartVoltage Flash MEMORY ERRATA

9600005. Block Locking and Unlocking

PROBLEM: The block locking and unlocking security feature is currently nonfunctional. Attempts to lock and unlock block may induce failure when executing a byte write or erase operation. The operations will fail because of a device protection error. The component incorrectly reads block lock-bit as being set when it is actually cleared.

IMPLICATION: Block locking feature is disabled. This erratum effects the following commands: Set Master Lock-Bit, Set Block Lock-Bits, and Clear Block Lock-Bits.

WORKAROUND: To prevent the accentual setting and clear of block lock-bits, SHARP sets the Master Lock-Bit during the test flow. Therefore device disables Lock-Bit operations even if RP# input is V_{IH}. (In this case, SR.1 and SR.4 will be set to "1".) Do not issue the Set Block Lock-Bit and Clear Block Lock-Bits command while 12V is applied to the RP# input. High voltage on RP# will override the Master Lock-Bit thereby enabling the lock-bit configuration command.

If data security is of utmost importance, lower V_{PP} voltage equal to or less than V_{PPLK} during normal operations. With V_{PP} equal to or less V_{PPLK} , the device is absolutely protected against all data manipulation operations.

LH28Fxxx FLASH MEMORY FLASH NON-VOLATILE MEMORY FLASH E2ROM FLASH ROM READ ONLY MEMORY ETOX LH28F008SC-V 8M (1Mx8) Smart Voltage