

## 40× Playback/12× Write CD-R/RW Encoder/Decoder IC with Built-in ATAPI Interface

## **Preliminary**

### BURN-Proof

## **Functions**

- CD-ROM decoder/encoder functions
- CD decoder/encoder functions
- · Pit and wobble CLV servo
- · CAV audio functions
- ATAPI interface (include the register block)
- Subcode encoder/decoder functions
- · ATIP demodulator/ATIP decoder
- Write strategy function (CD-R/RW)

## **Features**

- ECC and EDC correction/addition (decoding/encoding) for CD-ROM data.
- ECC error correction/addition (decoding/encoding) for
- Servo control implemented in a digital servo system (decoding/encoding)
- CLV servo control using ATIP data (encoding)
- ATIP decoding function and CRC check function (decoding/encoding)
- · CIRC code generation and addition and EFM modulation (encoding)
- CAV audio functions
- Provides high-precision CD-R/RW write strategy signal
- Built-in ATAPI interface (with Ultra DMA 33 support)
- Supports 40× decoding and 12× encoding.
  - Clock frequency: 33.8688 MHz
- Transfer rates: Up to 16.6 MB/s (when 32× IORDY used), up to 33 MB/s when Ultra DMA used. These values apply when 16-bit 45 ns EDO DRAM is used.

"BURN-Proof" stands for Proof against Buffer Under RuN error, not for proof against burning.

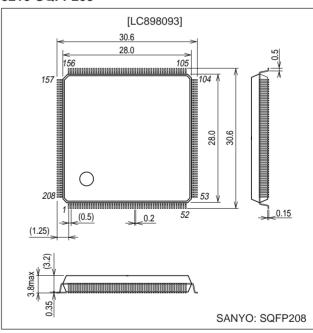
"BURN-Proof" is a trademark of SANYO Electric Co., Ltd.

- From 1 to 64 Mbits of buffer RAM can be used. (16-bit data bus EDO DRAM)
- The user can freely set up the CD main channel, C2 flag, and subcode areas in buffer RAM.
- Batch transfer function (Function for transferring the CD main channel, C2 flag, subcode, and other data in a single operation)
- Multi-transfer function (Function for automatically transferring multiple block to the host in a single operation)
- · CAV audio functions
- Supports Ultra DMA modes 0, 1, and 2.

## **Package Dimensions**

unit: mm

#### 3210-SQFP208



- Any and all SANYO products described or contained herein do not have specifications that can handle applications that require extremely high levels of reliability, such as life-support systems, aircraft's control systems, or other applications whose failure can be reasonably expected to result in serious physical and/or material damage. Consult with your SANYO representative nearest you before using any SANYO products described or contained herein in such applications.
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# $\label{eq:Specifications} \textbf{Absolute Maximum Ratings at } \mathbf{V}_{SS} = \mathbf{0} \ \mathbf{V}$

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	V <sub>DD</sub> 5 max	Ta ≤ 25°C	-0.3 to +6.0	V
Supply voltage	V <sub>DD</sub> 3 max	Ta ≤ 25°C	-0.3 to +4.6	V
I/O voltages	V <sub>I</sub> 5, V <sub>O</sub> 5	Ta ≤ 25°C	$-0.3$ to $V_{DD}5 + 0.3$	V
1/O voltages	V <sub>I</sub> 3, V <sub>O</sub> 3	Ta ≤ 25°C	$-0.3$ to $V_{DD}3 + 0.3$	V
Allowable power dissipation	Pd max	Ta ≤ 70°C	750	mW
Operating temperature	Topr		-30 to +70	°C
Storage temperature	Tstg		-55 to +125	°C
Soldering conditions (pins only)		10 seconds	260	°C

## Allowable Operating Ranges at $Ta = -30 \ to \ +70^{\circ}C, \ V_{SS} = 0 \ V$

Parameter	Symbol	Symbol Conditions	Ratings			Unit		
Farameter	Symbol		min	typ	max	Offic		
[I/O cells, 5.0 V power supply]	[I/O cells, 5.0 V power supply]							
Supply voltage	V <sub>DD</sub> 5		4.5	5.0	5.5	V		
Input voltage range	V <sub>IN</sub>		0		V <sub>DD</sub> 5	V		
[Internal cells, 3.3 V power supply]	[Internal cells, 3.3 V power supply]							
Supply voltage	V <sub>DD</sub> 3		3.0	3.3	3.6	V		
Input voltage range	V <sub>IN</sub>		0		$V_{DD}3$	V		

## Electrical Characteristics at $Ta=-30~to~+70^{\circ}C,\,V_{SS}=0~V,\,V_{DD}=4.5~to~5.5~V$

Parameter	Symbol	Conditions		Ratings		Unit
Farameter	Symbol	Conditions	min	typ	max	Offic
High-level input voltage	V <sub>IH</sub>	TTI level inpute: (4)	2.2			V
Low-level input voltage	V <sub>IL</sub>	TTL level inputs: (1)			0.8	V
High-level input voltage	V <sub>IH</sub>	TTI level inpute with built in pull up registers. (4)	2.2			V
Low-level input voltage	V <sub>IL</sub>	TTL level inputs with built-in pull-up resistors: (4)			0.8	V
High-level input voltage	V <sub>IH</sub>	TTL level Schmitt trigger inputs: (0), (7)	2.4			V
Low-level input voltage	V <sub>IL</sub>	TTE level Schillitt trigger inputs. (0), (7)			0.8	V
High-level input voltage	V <sub>IH</sub>	TTL level Schmitt trigger inputs	2.4			V
Low-level input voltage	V <sub>IL</sub>	Built-in pull-up resistors: (9), (14)			0.8	V
High-level input voltage	V <sub>IH</sub>	CMOS lovel inpute with built in pull up registers: (10)	0.7 V <sub>DD</sub>			V
Low-level input voltage	V <sub>IL</sub>	CMOS level inputs with built-in pull-up resistors: (10)			0.3 V <sub>DD</sub>	V
Analog input voltage	V <sub>ANI</sub>	(11)	1/4 V <sub>DD</sub>		3/4 V <sub>DD</sub>	V
High-level output voltage	V <sub>OH</sub>	$I_{OH} = -8 \text{ mA: } (3), (8)$	V <sub>DD</sub> – 2.1			V
Low-level output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 8 mA: (3), (8)			0.4	V
High-level output voltage	V <sub>OH</sub>	I <sub>OH</sub> = -2 mA: (2), (4), (6)	V <sub>DD</sub> – 2.1			V
Low-level output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 2 mA: (2), (4), (6)			0.4	V
Low-level output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 2 mA: (5)			0.4	V
High-level output voltage	V <sub>OH</sub>	I <sub>OH</sub> = -8 mA: (7), (12), (14), (15)	V <sub>DD</sub> – 2.1			V
Low-level output voltage	V <sub>OL</sub>	I <sub>OL</sub> = 24 mA: (7), (12), (14), (15)			0.4	V
Input leakage current	I <sub>IL</sub>	$V_{I} = V_{SS}, V_{DD}$ : (0), (1), (7), (9)	-10		+10	μΑ
Output leakage current	I <sub>OZ</sub>	In the high-impedance output state: (2), (7), (8), (12), (13) (14), (15)	-10		+10	μΑ
Pull-up resistance	R <sub>UP</sub>	(10)	50	100	200	kΩ
Pull-up resistance	R <sub>UP</sub>	(4), (5)	40	80	160	kΩ
Pull-up resistance	R <sub>UP</sub>	(9), (13), (14)	7	10	13	kΩ
Pull-up resistance	R <sub>UP</sub>	(15)	7	10	13	kΩ

The applicable pin groups are listed on the following page.

#### **Applicable Pins**

#### [INPUT]

- $(0) \cdots \overline{CS}, \overline{RD}, \overline{WR}, \overline{WRITE}, \overline{SUA0} \text{ to SUA7}, \overline{RESET}, \overline{WOBBLE}, \overline{CS1FX}, \overline{CS3FX}, \overline{DIOR}, \overline{DIOW}, \overline{HRST}$
- $(9) \cdot \cdots \cdot \overline{DMACK}$
- $(1) \cdot \cdot \cdot \cdot \cdot \text{TEST0}$  to TEST4
- $(10) \cdot \cdot \cdot \cdot FG$
- (11) · · · · · AD0, AD1, RREC, FE, TE, VREF, AD2, TES

#### [OUTPUT]

- $(2) \cdot \cdot \cdot \cdot \cdot PDS1$  to PDS3, DSLB
- (3)····· RA0 to RA9,  $\overline{\text{CAS0}}$  and  $\overline{\text{CAS1}}$ ,  $\overline{\text{RAS0}}$  to  $\overline{\text{RAS2}}$ ,  $\overline{\text{LWE}}$ ,  $\overline{\text{UWE}}$ ,  $\overline{\text{OE}}$ , SSP2/1, RAPC, WAPC, H11T0, LDH, ATEST3/1, WDAT, NWDAT, EFMG, SHOCK, LOCK, EFMO, ATIPSYNC, ACRCNG, PCK2
- (6) · · · · · LDON
- $(12) \cdot \cdot \cdot \cdot \cdot INTRQ, \overline{IOCS16}$
- (13) · · · · · IORDY
- (15) · · · · · DMARQ

#### [INOUT]

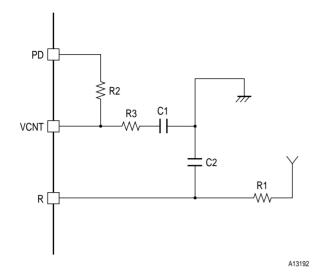
- $(4) \cdot \cdot \cdot \cdot \cdot D0$  to D7, IO0 to IO15
- (5)  $\cdots \overline{INT0}$  and  $\overline{INT1}$ ,  $\overline{SWAIT}$
- $(7) \cdot \cdots \cdot DD0$  to DD15
- (8) · · · · · · BIDATA, BICLK
- $(14) \cdot \cdot \cdot \cdot DASP, \overline{PDIAG}$

Note: The XTAL0 pin is not specified in the DC characteristics.

The pull-up and pull-down resistors on pins (9), (13), (14), and (15) are disabled after a reset.

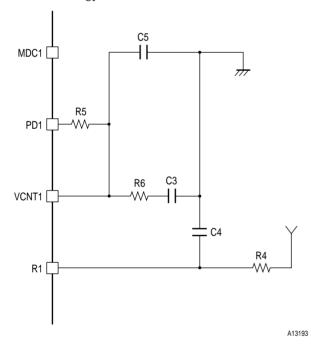
## **External Circuit for the PLL Circuit**

#### 1. Internal Reference Clock Oscillator Block



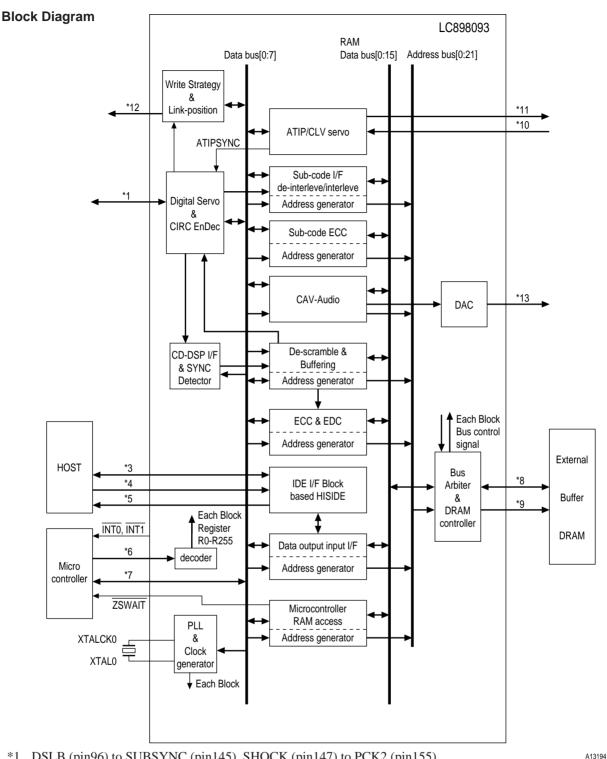
Symbol	Value (typ)	Unit
R1	5.6 k	Ω
R2	10 k	Ω
R3	200	Ω
C1	0.1 μ	F
C2	0.1 μ	F

2. Write Strategy Block



Symbol	Value (typ)	Unit
R4	5.6 k	Ω
R5	15 k	Ω
R6	220	Ω
C3	0.1 μ	F
C4	0.1 μ	F
C5	0.1 וו	F

The analog  $V_{DD}$  and  $V_{SS}$  pins (pins 52, 53, 90, and 91) must be completely isolated from the logic system power supply and must not be influenced by fluctuations in the logic system power supply.



- \*1 DSLB (pin96) to SUBSYNC (pin145), SHOCK (pin147) to PCK2 (pin155)
- \*3 DD0 to DD15, DASP, PDIAG
- \*4 CS1FX, CS3FX, DA0 to DA2, DIOR, DIOW, DMACK
- \*5 DMARQ, HINTRQ, IOCS16, IORDY
- \*6  $\overline{RD}$ ,  $\overline{WR}$ , SUA0 to SUA7,  $\overline{CS}$
- \*7 D0 to D7
- \*8 IO0 to IO15
- \*9 RA0 to RA9, RAS0, RAS1, RAS2, CAS0, CAS1, OE, UWE, LWE
- \*10 WOBBLE
- \*11 ATIPSYNC, BIDATA, BICLK
- \*12 WRITE, SSP2/1, RAPC, WAPC, H11T0, LDH, ATEST3, ATEST1, WDAT, NWDAT, EFMG
- \*13 LOUT, ROUT
- \*\*1 HISIDE (WD25C32) is made by WESTERN DIGITAL.

## **Pin Functions**

			Pin type		
- 1	Input	В	Bidirectional pin	NC	Not connected
0	Output	Р	Power supply	А	Analog pin

Pin No.	Pin name	Туре	Pin function
1	V <sub>SS</sub>	Р	Digital system ground (V <sub>SS</sub> )
2	RA4	0	
3	RA5	0	
4	RA6	0	CD DOM as a day/daya day DDAM a dayara Kara
5	RA7	0	CD-ROM encoder/decoder DRAM address lines
6	RA8	0	
7	RA9	0	
8	V <sub>DD</sub>	Р	Digital system power supply (5 V)
9	V <sub>SS</sub>	Р	Digital system ground (V <sub>SS</sub> )
10	IO0	В	
11	IO1	В	
12	IO2	В	CD-ROM encoder/decoder buffer RAM data lines
13	IO3	В	These pins have built-in pull-up resistors.
14	104	В	
15	IO5	В	
16	V <sub>DD</sub>	Р	Digital system power supply (3.3 V)
17	V <sub>SS</sub>	Р	Digital system ground (V <sub>SS</sub> )
18	IO6	В	
19	107	В	CD-ROM encoder/decoder buffer RAM data lines
20	IO8	В	
21	109	В	These pins have built-in pull-up resistors.
22	IO10	В	
23	V <sub>SS</sub>	Р	Digital system ground (V <sub>SS</sub> )
24	V <sub>DD</sub>	Р	Digital system power supply (5 V)
25	IO11	В	
26	IO12	В	
27	IO13	В	CD-ROM encoder/decoder buffer RAM data lines
28	IO14	В	These pins have built-in pull-up resistors.
29	IO15	В	
30	ATIPSYNC	0	ATIP SYNC detection signal
31	BIDATA	В	
32	BICLK	В	ATIP demodulator signals
33	WOBBLE	ı	
34	V <sub>DD</sub>	Р	Digital system power supply (5 V)
35	V <sub>SS</sub>	Р	Digital system ground (V <sub>SS</sub> )
36	ACRCNG	0	ATIP CRC result output signal
37	WRITE	ı	Write strategy signal control input
38	SSP2	0	Servo sampling pulse output
39	SSP1	0	Servo sampling pulse output
40	RAPC	0	Laser control sampling pulse output
41	WAPC	0	Laser control sampling pulse output
42	H11T0	0	Running OPC sampling pulse

## Continued from preceding page.

Pin No.	Pin name	Туре	Pin function
43	LDH	0	Recording laser diode control signal output
44	$V_{DD}$	Р	Analog system power supply (3.3 V)
45	V <sub>SS</sub>	Р	Analog system ground (V <sub>SS</sub> )
46	ATEST3	0	RW output
47	ATEST1	0	Internal monitor test output
48	WDAT	0	Recording laser diode control signal output
49	NWDAT	0	Recording laser diode control signal output (WDAT inverted)
50	$V_{DD}$	Р	Analog system power supply (3.3 V)
51	V <sub>SS</sub>	Р	Analog system ground (V <sub>SS</sub> )
52	$V_{DD}$	Р	Digital system power supply (5 V)
53	V <sub>SS</sub>	Р	Digital system ground (V <sub>SS</sub> )
54	R1	I	
55	VCNT1	I	White states are and a simple
56	MDC1	0	Write strategy analog signals
57	PD1	0	
58	SWAIT	0	Wait signal to the microcontroller
59	ĪNT0	0	Interrupt request signal outputs to the microcontroller
60	ĪNT1	0	These are open-drain outputs with built-in pull-up resistors.
61	D0	В	
62	D1	В	
63	D2	В	
64	D3	В	Microcontroller data signal lines
65	D4	В	These pins have built-in pull-up resistors.
66	D5	В	
67	D6	В	
68	$V_{DD}$	Р	Digital system power supply (5 V)
69	V <sub>SS</sub>	Р	Digital system ground (V <sub>SS</sub> )
70	D7	В	Microcontroller data signal line
71	SUA0	I	
72	SUA1	I	
73	SUA2	I	
74	SUA3	I	Command register colection address
75	SUA4	I	Command register selection address
76	SUA5	I	
77	SUA6	I	
78	SUA7	I	
79	CS	I	Chip select signal input from the microcontroller
80	RD	I	Data read signal input from the microcontroller
81	WR	I	Data write signal input from the microcontroller
82	TEST0	I	Test pin. This pin must be tied to V <sub>SS</sub> .
83	VCNT	I	VCO control voltage
84	R	I	VCO bias resistor connection
85	PD	0	Charge pump output
86	$V_{DD}$	Р	Analog system power supply (3.3 V)
87	V <sub>SS</sub>	Р	Analog system ground (V <sub>SS</sub> )
88	TEST1	I	Test pin. This pin must be tied to V <sub>SS</sub> .
89	RESET	I	Reset input
90	XTALCK0	I	Crystal oscillator circuit input (33.8688 MHz)

## Continued from preceding page.

Pin No.	Pin name	Туре	Pin function
91	XTAL0	0	Crystal oscillator circuit output
92	ROUT	0	D/A converter output
93	V <sub>SS</sub>	Р	Analog system ground (V <sub>SS</sub> )
94	$V_{DD}$	Р	Analog system power supply (5 V)
95	LOUT	0	D/A converter output
96	DSLB	0	SLC PWM output
97	SLCIST1	1	EEM eliza lavel author insut
98	SLCIST2	1	EFM slice level setting input
99	V <sub>SS</sub>	Р	Analog system ground (V <sub>SS</sub> )
100	$V_{DD}$	Р	Analog system power supply (3.3 V)
101	SLCO0	0	
102	SLCO1	0	EFM slice level output
103	SLCO2	0	
104	$V_{DD}$	Р	Digital system power supply (5 V)
105	V <sub>SS</sub>	Р	Digital system ground (V <sub>SS</sub> )
106	SLCO3	0	EFM slice level output
107	EFMIN	ı	ETH: .
108	EFMIN2	ı	- EFM input
109	JITIN	ı	Jitter discrimination input
110	JITC	0	Jitter output
111	RPO	0	DALL I
112	OPP	ı	P/N balance adjustment
113	PCKISTF	ı	Frequency comparator charge pump
114	PCKISTP	ı	Phase comparator charge pump
115	V <sub>SS</sub>	Р	Analog system ground (V <sub>SS</sub> )
116	$V_{DD}$	Р	Analog system power supply (3.3 V)
117	PDO	0	Charge pump filter
118	PDS1	0	
119	PDS2	0	Charge pump selection
120	$V_{DD}$	Р	Digital system power supply (3.3 V)
121	V <sub>SS</sub>	Р	Digital system ground (V <sub>SS</sub> )
122	PDS3	0	Charge pump selection
123	FR	I	VCO frequency setting
124	TEST2	I	Test pin. This pin must be tied to V <sub>SS</sub> .
125	TEST3	I	Test pin. This pin must be tied to V <sub>SS</sub> .
126	TEST4	I	Test pin. This pin must be tied to V <sub>SS</sub> .
127	AD0	I	AD input
128	RREC	I	Optical signal discrimination input
129	FE	I	FE input
130	TE	I	TE input
131	VREF	I	VREF input
132	AD1	I	AD input
133	V <sub>SS</sub>	Р	Analog system ground (V <sub>SS</sub> )
134	DA0	0	DA output
135	DA1	0	DA output
136	DA2	0	DA output
137	TDO	0	Tracking output

## Continued from preceding page.

Pin No.	Pin name	Туре	Pin function
138	V <sub>DD</sub>	P	Analog system power supply (5 V)
139	V <sub>SS</sub>	Р	Analog system ground (V <sub>SS</sub> )
140	FDO	0	Focus output
141	SLDO	0	Sled output
142	SPDO	0	Spindle output
143	V <sub>SS</sub>	P	Digital system ground (V <sub>SS</sub> )
144	V <sub>DD</sub>	P	Digital system power supply (3.3 V)
145	SUBSYNC	0	Subcode SYNC signal
146	EFMG	0	Write gate signal
147	SHOCK	0	Shock detection signal
148	LOCK	0	PLL lock state output
149	DEF	ı	Defect detection signal input
150	HFL	1	Mirror detection signal input
151	TES		Tracking zero cross signal input
		1	
152	EFMO	0	Post-binarization EFM signal output
153	LDON	0	Laser control
154	FG	I	FG input
155	PCK2	0	PCK output
156	V <sub>DD</sub>	P	Digital system power supply (5 V)
157	V <sub>SS</sub>	Р	Digital system ground (V <sub>SS</sub> )
158	HRST	I	
159	DASP	В	  -
160	CS3FX	I	
161	CS1FX	I	_
162	DA2	I	
163	DA0	I	
164	PDIAG	В	IDE interface signals
165	DAI	I	
166	IOCS16	0	
167	INTRQ	0	
168	DMACK	I	
169	IORDY	0	
170	DIOR	ı	
171	DIOW	I	
172	$V_{DD}$	Р	Digital system power supply (5 V)
173	$V_{SS}$	Р	Digital system ground (V <sub>SS</sub> )
174	DMARQ	0	
175	DD15	В	
176	DD0	В	
177	DD14	В	IDE interface signals
178	DD1	В	
179	DD13	В	
180	DD2	В	
181	V <sub>SS</sub>	Р	Digital system ground (V <sub>SS</sub> )
182	DD12	В	
183	DD3	В	IDE interface signals
184	DD11	В	1
184	DD11	В	

Continued from preceding page.

Pin No.	Pin name	Туре	Pin function
185	DD4	В	
186	DD10	В	
187	DD5	В	IDE interface signals
188	DD9	В	
189	DD6	В	
190	V <sub>DD</sub>	Р	Digital system power supply (3.3 V)
191	V <sub>SS</sub>	Р	Digital system ground (V <sub>SS</sub> )
192	DD8	В	IDE interface signals
193	DD7	В	IDE interface signals
194	RAS0	0	
195	RAS1	0	DRAM RAS signal outputs
196	RAS2	0	
197	LWE	0	DRAM lower write enable
198	V <sub>DD</sub>	Р	Digital system power supply (5 V)
199	V <sub>SS</sub>	Р	Digital system ground (V <sub>SS</sub> )
200	UWE	0	DRAM upper write enable
201	CAS0	0	DRAM CAS signal output
202	CAS1	0	- DRAIN CAS signal output
203	ŌĒ	0	DRAM output enable
204	RA0	0	
205	RA1	0	CD-ROM encoder/decoder DRAM address lines
206	RA2	0	OD-NOINI etitodeti/decodet Draini addiess titles
207	RA3	0	
208	V <sub>DD</sub>	Р	Digital system power supply (5 V)

#### **Pin Functions**

<ATAPI Pins>

**CS1FX** (input)

Chip select signal that selects the command block register.

**CS3FX** (input)

Chip select signal that selects the control block register.

DA0 to DA2 (input)

Address for accessing the ATAPI interface registers.

**DASP** (input/output)

Drive 1 is output and drive 0 is input.

Signal used to indicate to drive 0 that drive 1 exists.

DD0 to DD15 (input/output)

16-bit data bus. This interface supports both 8-bit and 16-bit transfers.

**DIOR** (input)

Read strobe from the host.

**DIOW** (input)

Write strobe from the host.

**DMACK** (input)

Acknowledge signal from the host used during DMA transfers. Corresponds to the DMARQ request signal from the drive.

DMARQ (input)

Drive request signal used during DMA transfers.

**HINTRQ** (output)

Drive interrupt request signal to the host.

**IOCS16** (output)

Signal asserted by the drive when the drive supports 16-bit transfers.

This signal is not asserted during DMA transfers.

#### **IORDY** (output)

Indicates that the drive is ready to respond. Used during data transfers.

This signal will be low when the drive is not ready.

#### **PDIAG** (input/output)

Signal asserted by drive 1 to indicate to drive 0 that diagnostics have completed.

#### **HRST** (input)

Reset signal from the host. The IDE interface is reset by a low-level input to this pin.

#### <Microcontroller Interface Pins>

#### **CS** (input)

Chip select signal from the microcontroller. The microcontroller interface is active when this pin is low.

#### RD, WR (input)

Connect the microcontroller read and write lines to these inputs.

#### **SWAIT** (input)

Wait signal output to the microcontroller. When accessing buffer RAM, the microcontroller must wait if this pin is low

#### **SUA0 to SUA7** (input)

Internal register address lines

#### **D0 to D7** (input/output)

Microcontroller data bus. These pins have built-in pull-up resistors.

#### INTO, INT1 (output)

Interrupt request signals output to the microcontroller. <u>INT1</u> can be set to output the ATAPI interrupt by setting INT1EN (Conf-R11 bit 7)

These are open drain outputs with built-in  $80 \text{ k}\Omega$  (at room temperature, 5 V) pull-up resistors.

#### <Buffer RAM Pins>

#### **I/O0 to I/O15** (input/output)

Buffer RAM data bus. These pins have built-in pull-up resistors.

#### RA0 to RA9 (output)

Buffer RAM address lines.

#### RASO, RAS1, RAS2 (output)

Buffer DRAM RAS outputs. Normally,  $\overline{RAS0}$  is used. However, if two 16-Mbit DRAMs are used, connect the  $\overline{RAS0}$  and  $\overline{RAS1}$  lines to the RAS pins on the DRAMs. If four 16-Mbit DRAMs are used, connect the  $\overline{RAS0}$ ,  $\overline{RAS1}$ ,  $\overline{RAS2}$ , and  $\overline{LWE}$  lines to the RAS pins on the DRAMs.

#### CASO, CAS1 (output)

Buffer DRAM CAS outputs. Normally,  $\overline{\text{CAS0}}$  is used. However, if two 16-Mbit DRAMs are used, connect the  $\overline{\text{CAS0}}$  output to the CAS pins on the DRAMs. If 2-CAS type DRAMs are used, connect  $\overline{\text{CAS0}}$  to UCAS and  $\overline{\text{CAS1}}$  to LCAS.

#### **OE** (output)

Buffer RAM read output.

#### UWE, LWE (output)

Buffer RAM write outputs. Connect these to the corresponding pins. If 2-CAS type DRAMs are used, UWE must be connected. (Leave LWE open.)

#### 1. Analog Interface Pins

#### RREC (input)

Optical discrimination input.

#### **FE** (input)

Focus error signal input.

## **TE** (input)

Tracking error signal input.

### VREF (input)

Input for the servo system reference voltage.

#### ADO, AD1 (input)

A/D converter auxiliary inputs.

#### DA0, DA1, DA2 (input)

D/A converter auxiliary inputs.

#### **TES** (input)

TES comparator input.

#### **TDO** (output)

Tracking control signal output.

#### FDO (output)

Focus control signal output.

#### **SLDO** (output)

Sled control signal output.

#### SPDO (output)

Spindle control signal output.

#### 2. EFM Input Block Pins

#### **EFMIN** (input)

EFM signal input.

The high-frequency components of the RF signal acquired from the RF amplifier are cut with a capacitor, and this pin inputs that signal biased by the value of the SLCO0 to SLCO3 outputs passed through a low-pass filter.

#### **EFMIN2** (input)

Used to change the time constant of the low-pass filter.

#### SLCIST1, SLCIST2 (input)

Slice level controller charge pump bias resistor connection.

#### SLCO0, SLCO1, SLCO2, SLCO3 (output)

Slice level controller charge pump outputs.

These levels bias the RF signal input to the EFMIN pin after being passed through a low-pass filter.

#### **DSLB** (output)

Slice level control PWM output.

#### **EFMO** (output)

Post-binarization EFM signal output. (For monitoring)

#### 3. EFM Clock Generation Block Pins

#### FR (input)

EFM reproduction PLL VCO bias resistor connection.

#### PDO, PDS1, PDS2, PDS3 (output)

EFM reproduction PLL lag-lead filter connection.

#### **PCKISTF** (input)

EFM reproduction PLL frequency comparator charge pump bias resistor connection.

#### **PCKISTP** (input)

EFM reproduction PLL phase comparator charge pump bias resistor connection.

#### RPO (output)

P/N balance adjustment.

#### **OPP** (input)

P/N balance adjustment.

#### PCK2 (output)

EFM reproduction bit clock output.

#### 4. Jitter Discrimination Pins

#### JITIN (input)

Jitter discrimination input.

## JITC (output)

Jitter output.

#### 5. Spindle Speed Detection Pins

#### FG (input)

Input for the speed monitor signal from the spindle driver.

#### 6. Audio Interface Pins

#### LOUT, ROUT (output)

Left and right channel audio signal outputs.

#### 7. RF Amplifier Interface Pins

#### **LDON** (output)

RF amplifier interface.

#### 8. Write Strategy Pins

#### WRITE, SSP2/1, RAPC, WAPC, H11T0, LDH, ATEST3, 1, WDAT, NWDAT (I/O)

Write strategy signal connections.

#### 9. ATIP Decoder Related Pins

#### ATIPSYNC (output)

ATIP synchronization detection signal. (For monitoring)

#### BIDATA, BICLK (I/O)

Input mode: Input for the biphase data and biphase clock when an external ATIP demodulator is used.

Output mode: Output of the biphase data and biphase clock when the internal ATIP demodulator is used. (For monitoring)

#### **WOBBLE** (input)

Wobble signal input when the internal ATIP demodulator is used.

#### **ACRCNG** (output)

Outputs the result of the ATIP decoder CRC check. (For monitoring)

#### <Other Pins>

#### **RESET** (input)

The LC898093 reset input. A low level input resets the LC898093.

This pin must be held low for at least 1 µs when power is first applied.

#### TEST4 to TEST0 (input)

Test inputs. These pins must be connected to ground.

#### XTALCKO (input), XTALO (output)

Drive these pins at 33.8688 MHz. This signal is used, without modification, as main clock for the CD-ROM encoder and decoder blocks, including the DRAM interface.

Consult the manufacturer of the oscillator element concerning the design of the oscillator circuit.

#### R, VCNT, PDO, R1, VCNT1, PD1, MDC1 (I/O)

Clock reproduction PLL circuit pins.

#### **SUBSYNC** (output)

Subcode SYNC output signal from the CIRC encoder during encoding. (For monitoring)

#### **EFMG** (output)

Outputs a high-level signal (5 V) during write operations.

#### SHOCK (output)

Outputs a high level (5 V) when a mechanical shock is detected during decodeing.

#### LOCK (output)

Outputs a high level (5 V) when the PLL circuit is locked.

#### **DEF** (input)

Inputs the defect detection signal.

#### **HFL** (input)

Inputs the mirror detection signal.

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