

ETR Microcontrollers

Overview

The LC723700 Series are large-capacity ETR microcontrollers that achieve an instruction execution time of 1.33 μs and provide up to 64 KB of ROM and up to 2 KB of RAM. They include an on-chip high-performance PLL circuit that features an added high-speed lock circuit and can control the C/N characteristics of a local oscillator. They also provide a rich set of on-chip interface circuits, including a 3-channel serial I/O port, and an 8-input 8-bit A/D converter.

Functions

- ROM
 - Up to 32K steps $(32,767 \times 16 \text{ bits})$
 - The subroutine area holds 4 K steps $(4,096 \times 16 \text{ bits})$
- RAM
 - Up to 4 K × 4 bits (In banks 00 through 3F) LC723732 – ROM: 32 KB, RAM 1 KB LC723740 – ROM: 40 KB, RAM 2 KB LC723748 – ROM: 48 KB, RAM 2 KB LC723756 – ROM: 56 KB, RAM 2 KB LC723764 – ROM: 64 KB, RAM 2 KB
- Stack
 - 32 levels
- Serial I/O
 - Three channels. These circuits can support both 2wire and 3-wire 8-bit communication techniques, and can be switched between MSB first and LSB first operation.
 - One of six internally generated serial transfer clock rates can be selected: 12.5, 37.5, 187.5, 281.25, 375, and 450 kHz.
- External interrupts
 - Seven interrupt inputs (pins INT0 through INT5, and the HOLD pin)
 - These interrupts can be set to switch between rising and falling edges, although the HOLD pin only supports falling edge detection.
- · Internal interrupts
 - Seven interrupts; four internal timer interrupts, and three serial I/O interrupts.
- Interrupt nesting levels
 - 16 levels
 - Interrupt are prioritized in hardware as follows:

HOLD pin > INT0 pin > INT1 pin > INT2 pin > INT3 pin > INT4 pin > INT5 pin > S-I/O0 > S-I/O1 > S-I/O2 > internal TMR0 > internal TMR1 > internal TMR2 > internal TMR3

- A/D converter
 - 8-bit resolution and 8 inputs
- General-purpose ports
 - Input ports: 12
 - Output ports: 4
 - I/O ports: 62 (These pins can be switched between input and output in 1-bit units.)
- · PLL block
 - Includes a sub-charge pump for high-speed locking.
 - Supports dead zone control.
 - Built-in unlock detection circuit.
 - Twelve reference frequencies: 1, 3, 3.125, 5, 6.25, 9, 10, 12.5, 25, 30, 50, and 100 kHz.
 - A second PLL circuit is also included for use in AM up conversion.
- Universal counter
 - This 20-bit counter can be used for either frequency or period measurement and supports four measurement (calculation) periods: 1, 4, 8, and 32 ms.
- Timers
 - Two fixed timers and two programmable timers (8bit counters)

TMR0: Supports four periods: 10 μs , 100 μs , 1 ms, and 5 ms

TMR1: Supports four periods: 10 μs , 100 μs , 1 ms, and 10 ms

TMR2 and TMR3: Programmable 8-bit counters. Input clocks with 10 μ s, 100 μ s, and 1 ms periods are provided.

- One 125-ms timer flip-flop provided.
- Beep circuit
 - Provides 12 fixed beep tones: 0.5, 1, 2, 2.08, 2.2, 2.5, 3.33, 3.75, 4.17, and 7.03 kHz.
 - Programmable 8-bit beep tone generator. Reference clocks with frequencies of 5 kHz, 15 kHz, and 50 kHz are provided.
- Reset
 - Built-in voltage detection reset circuit
 - External reset pin

- Cycle time
 - 1.33 μs (All instructions are one word.)
- Halt mode
 - The microcontroller operating clock is stopped in halt mode.

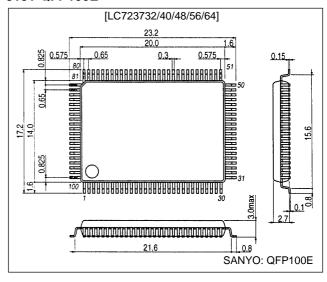
There are four conditions that can clear halt mode: an interrupt request, a timer flip-flop overflow, a PA port input, or a HOLD pin input.

- Operating supply voltage
 - 4.5 to 5.5 V (Microcontroller block only: 3.5 to 5.5 V)
- Package
 - QIP100E
- OTP version
 - LC72P3700
- Development tools
 - Emulator :RE32N
 - Evaluation chip: LC72EV3700
 - Evaluation chip board: EB-72EV3700

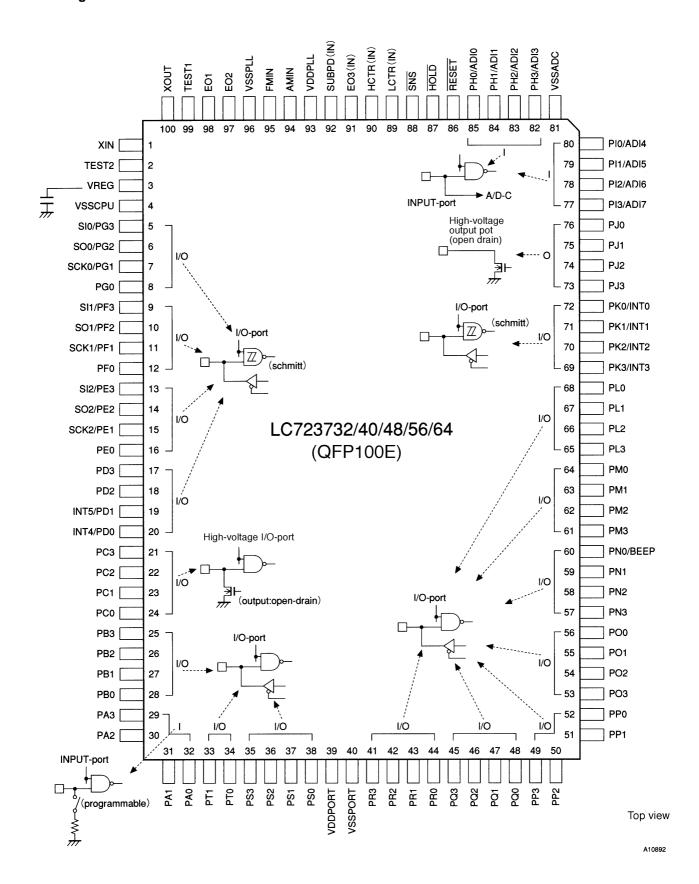
Package Dimensions

unit: mm

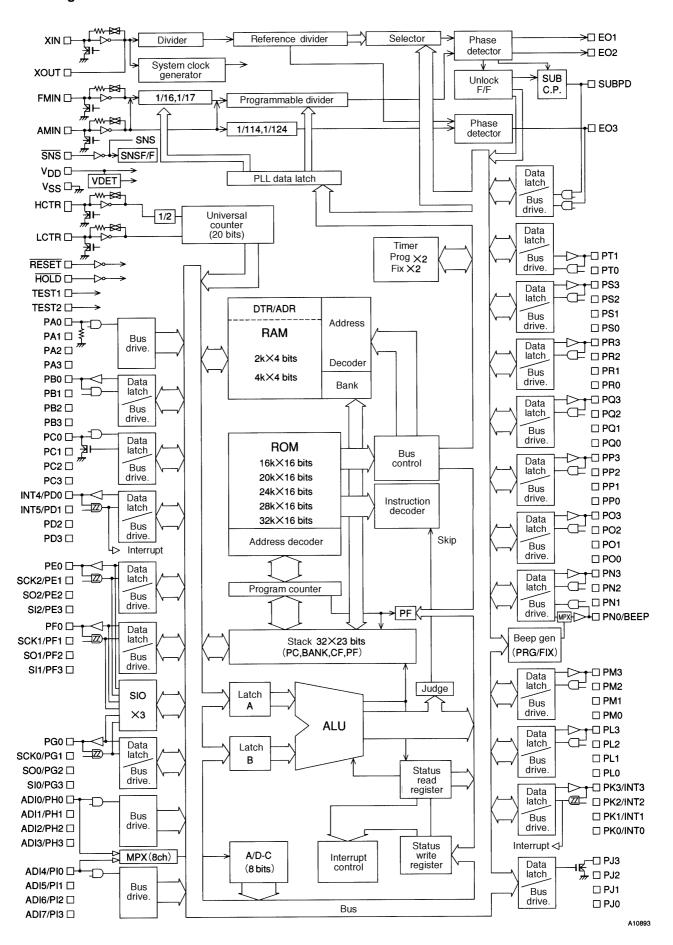
3151-QFP100E



Pin Assignment



Block Diagram



Specifications Electrical Characteristics

Absolute Maximum Ratings at $Ta=25^{\circ}C,\,V_{SS}$ = 0 V

Parameter	Symbol	Conditions	Ratings	Unit
Maximum supply voltage	V _{DD} max		-0.3 to +6.5	V
lanut valtaga	V _{IN} 1	PC-PORT	-0.3 to +15	V
Input voltage	V _{IN} 2	All input pins other than V _{IN} 1	-0.3 to V _{DD} + 0.3	V
Output voltage	V _{OUT} 1	PC, PJ-PORT	-0.3 to +15	V
Output voltage	V _{OUT} 2	All output pins other than V _{OUT} 1	-0.3 to V _{DD} + 0.3	V
	I _{OUT} 1	PC, PJ-PORT	0 to +5	mA
Output current	I _{OUT} 2	PB, PD, PE, PF, PG, PK, PL, PM, PN, PO, PP, PQ, PR, PS, PT, PT-PORT, EO1, EO2, EO3, SUBPD	0 to +3	mA
Allowable power dissipation	Pd max	$Ta = -40 \text{ to } +85^{\circ}\text{C}$	400	mW
Operating temperature	Topg		-40 to +85	°C
Storage temperature	Tstg		-45 to +125	°C

Allowable Operating Ranges at $Ta=-40~to~+85^{\circ}C,\,V_{DD}=3.5~to~5.5~V$

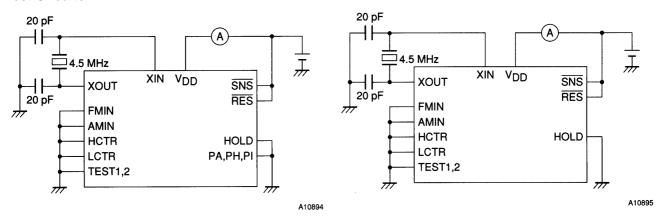
Danamatan	Oh al	Conditions	Ratings			- Unit
Parameter	Symbol	Conditions	min typ		max	Unit
	V _{DD} 1	CPU and PLL operating	4.5	5.0	5.5	V
Supply voltage	V _{DD} 2	CPU operating	3.5		5.5	V
	V _{DD} 3	Memory retention	1.3		5.5	V
	V _{IH} 1	PB, PC, PH, PI, PL, PM, PN, PO, PP, PQ, PR, PS, PT-PORT, HCTR, LCTR, E03, SUBPD (with the I/O ports set to input mode.)	0.7 V _{DD}		V _{DD}	V
Input high-level voltage	V _{IH} 2	PD, PE, PF, PG, PK-PORT, LCTR, (in period measurement mode), HOLD, RESET	0.8 V _{DD}		V _{DD}	V
	V _{IH} 3	SNS	2.5		V_{DD}	V
	V _{IH} 4	PA-PORT	0.6 V _{DD}		V_{DD}	V
	V _{IL} 1	PB, PC, PH, PI, PL, PM, PN, PO, PP, PQ, PR, PS, PT-PORT, HCTR, LCTR, E03, SUBPD (with the I/O ports set to input mode.)	0		0.3 V _{DD}	V
Input low-level voltage	V _{IL} 2	PA, PD, PE, PF, PG, PK-PORT, LCTR (in period measurement mode), RESET	0		0.2 V _{DD}	V
	V _{IL} 3	SNS	0		1.3	V
	V _{IL} 4	HOLD	0		0.4 V _{DD}	V
	f _{IN} 1	XIN	4.0	4.5	5.0	MHz
	f _{IN} 2	FMIN V _{IN} 2, V _{DD} 1	10		150	MHz
	f _{IN} 3	FMIN V _{IN} 3, V _{DD} 1	10		130	MHz
	f _{IN} 4	AMIN(H) V _{IN} 3, V _{DD} 1	2.0		40	MHz
Input frequency	f _{IN} 5	AMIN(L) V _{IN} 3, V _{DD} 1	0.5		10	MHz
	f _{IN} 6	HCTR V _{IN} 3, V _{DD} 1	0.4		12	MHz
	f _{IN} 7	LCTR V _{IN} 3, V _{DD} 1	100		500	kHz
	f _{IN} 8	LCTR(period measurement) V _{IH} 2, V _{IL} 2, V _{DD} 1	1		20 × 10 ³	Hz
	V _{IN} 1	XIN	0.5		1.5	Vrms
Input amplitude	V _{IN} 2	FMIN	0.07		1.5	Vrms
	V _{IN} 3	FMIN, AMIN, HCTR, LCTR	0.04		1.5	Vrms
Input voltage range	V _{IN} 4	ADI0 to ADI7	0		V_{DD}	V

Electrical Characteristics in the allowable operating ranges

Parameter	Symbol	Conditions		Unit		
raiametei	Symbol	Conditions	min	typ	max	Offic
	I _{IH} 1	$XIN: V_I = V_{DD} = 5.0 \text{ V}$	2.0	5.0	15	μA
	I _{IH} 2	FMIN, AMIN, HCTR, LCTR: V _I = V _{DD} = 5.0 V	4.0	10	30	μΑ
Input high-level current	I _{IH} 3	PA, PB, PC, PD, PE, PF, PG, PH, PI, PK, PL, PM, PN, PO, PP, PQ, PR, PS, PT-PORT, \overline{SNS} , \overline{HOLD} , \overline{RESET} , \overline{HCTR} , \overline{LCTR} , \overline{ESS} , \overline{HOLD} , \overline{RESET} , \overline{HCTR} , \overline{LCTR} , \overline{ESS} , \overline{HOLD} , \overline{RESET} , \overline{HCTR} , \overline{LCTR} , \overline{ESS} , \overline{HCTR} , $HCTR$			3.0	μА
	I _{IH} 4	Port PA (pull-down resistors enabled): $V_I = V_{DD} = 5.0 \text{ V}$		50		μΑ
	I _{IL} 1	$XIN: V_I = V_{SS}$	2.0	5.0	15	μA
	I _{IL} 2	FMIN, AMIN, HCTR, LCTR: V _I = V _{SS}	4.0	10	30	μA
Input low-level current	I _{IL} 3	PA, PB, PC, PD, PE, PF, PG, PH, PI, PK, PL, PM, PN, PO, PP, PQ, PR, PS, PT-PORT, SNS, HOLD, RESET, HCTR, LCTR, E03, SUBPD: V ₁ = V _{SS} (With the port PA pull-down resistors disabled, and PB, PC, PD, PE, PF, PG, PK, PL, PM, PN, PP, PO, PQ, PR, PS, and PT ports set to input mode.)			3.0	μА
Input floating voltage	V _{IF}	Port PA (pull-down resistors enabled)			0.05 V _{DD}	V
Hysteresis	V _H	PD, PE, PF, PG, PK-PORT, RESET, LCTR(in period measurement mode)	0.1 V _{DD}	0.2 V _{DD}		V
Output high-level voltage	V _{OH} 1	PB, PD, PE, PF, PG, PK, PL, PM, PN, PO, PP, PQ, PR, PS, PT-PORT: I _O = -1 mA	V _{DD} – 1.0			V
Output high level voltage	V _{OH} 2	EO1, EO2, EO3, SUBPD: I _O = -500 μA	V _{DD} – 1.0			V
	V _{OH} 3	XOUT: I _O = -200 μA	V _{DD} – 1.0			V
	V _{OL} 1	PB, PD, PE, PF, PG, PK, PL, PM, PN, PO, PP, PQ, PR, PS, PT-PORT: I _O = 1 mA			1.0	V
Output low-level voltage	V _{OL} 2	E01, E02, E03, SUBPD: I _O = 500 μA			1.0	V
	V _{OL} 3	XOUT: I _O = 200 μA			1.5	V
	V _{OL} 4	PC, PJ-PORT: I _O = 5 mA			2.0	V
Output off leakage current	I _{OFF} 1	PB, PD, PE, PF, PG, PK, PL, PM, PN, PO, PP, PQ, PR, PS, PT-PORT	-3.0		3.0	μΑ
output on leakage current	I _{OFF} 2	E01, E02, E03, SUBPD	-100		100	nA
	I _{OFF} 3	PC, PJ-PORT	-5.0		5.0	μA
A/D conversion error		ADI0 to ADI7 V _{DD} 1	-1.5		1.5	LSB
Rejected pulse width	P _{REJ}	SNS			50	µsec
Power down detection voltage	V _{DET}		2.6	3.0	3.4	V
Pull-down resistance	R _{PD} 1	Port PA (pull-down resistors enabled): V _{DD} = 5 V	75	100	200	kΩ
	R _{PD} 2	TEST1, TEST2		10		kΩ
	I _{DD} 1	During normal operation (PLL operating) V _{DD} 1, f _{IN} 2 = 130 MHz Ta = 25°C		20	30	mA
Current drain	I _{DD} 2	Halt mode (CPU operation stopped, crystal oscillator operating) (See figure 1.) V _{DD} 2, Ta = 25°C*		0.45		mA
	I _{DD} 3	Backup mode (crystal oscillator stopped) (See figure 2.) V _{DD} = 5.5 V, Ta = 25°C			5	μA
	I _{DD} 4	Backup mode (crystal oscillator stopped) (See figure 2.) V _{DD} = 2.5 V, Ta = 25°C			1	μA

Note *: Twenty instruction steps are executed every millisecond. The PLL, universal counter, and other functions are stopped.

Test Circuits



Note: Ports PB through PG, and PJ through PT are all left open. However, ports PB through PG, PK through PT, EO3, and SUBPD are left open in output mode. Note: Ports PA through PT are all left open.

Figure 1 IDD2 in Halt Mode

Figure 2 IDD3 and IDD4 in Backup Mode

Pin Descriptions

Pin No.	Symbol	I/O	Function	Equivalent circuit
32 31 30 29	PA0 PA1 PA2 PA3	I	Dedicated input ports. These ports are designed with a low threshold voltage. The pull-down resistors for all four pins are set up together with an IOS1 instruction. The pull-down resistors cannot be set individually. Input is disabled in backup mode.	BACK UP Programmable A10896
28 27 26 25	PB0 PB1 PB2 PB3	I/O	General-purpose I/O ports The mode (input or output) is set using the IOS2 instruction. Input is disabled and the pins go to the high-impedance state in backup mode. These ports are set up as general-purpose input ports after a power on reset.	BACK UP A10897
24 23 22 21	PC0 PC1 PC2 PC3	1/0	General-purpose I/O ports (high-voltage input and output) The mode (input or output) is set using the IOS2 instruction. External pull-up resistors are required since the output circuits are open drain circuits. Input is disabled and the pins go to the high-impedance state in backup mode. These ports are set up as general-purpose input ports after a power on reset.	BACK UP A10898
20 19 18 17	PD0/INT4 PD1/INT5 PD2 PD3	I/O	General-purpose I/O and external interrupt shared function ports The input formats are Schmitt inputs. The external interrupt function is enabled when the external interrupt enable flag is set. • When used as general-purpose I/O ports: The mode (input or output) is set in 1-bit units using the IOS2 instruction. • When used as external interrupt pins: The external interrupt functions are enabled by setting the corresponding external interrupt enable flag (INT4EN or INT5EN). Here, the pins must be set to input mode in advance. Input is disabled and the pins go to the high-impedance state in backup mode. These ports are set up as general-purpose input ports after a power on reset.	BACK UP Z A10899

Continued from preceding page.

Pin No.	Symbol	I/O	Function	Equivalent circuit
16 15 14 13 12 11 10 9 8 7 6	PE0 PE1/SCK2 PE2/S02 PE3/S12 PF0 PF1/SCK1 PF2/S01 PF3/S11 PG0 PG1/SCK0 PG2/S00 PG3/S10	I/O	General-purpose I/O ports with shared functions as serial I/O ports The input formats are Schmitt inputs. The PE1/SCK2 and PE2/SO2 pins can be switched to function as open drain outputs. The IOS1 instruction is used to switch between the general-purpose I/O port and serial I/O port functions. • When used as general-purpose I/O ports: The pins are set to the general-purpose I/O port function using the IOS1 instruction. The mode (input or output) is set in 1-bit units using the IOS1 instruction. • When used as serial I/O ports: The pins are set to the serial I/O port function using the IOS1 instruction. [Pin states when set to the serial I/O port function] PE0, PF0, PG0 General-purpose I/O PE1, PF1, PG1 SCK input or output PE2, PF2, PG2 SO output PE3, PF3, PG3 SI input The PE1/SCK2 and PE2/SO2 pins can be switched to function as open drain outputs with the IOS2 instruction. When using this circuit type, the external pull-up resistors must be connected to the same power supply as that used by the IC. Input is disabled and the pins go to the high-impedance state in backup mode. These ports are set up as general-purpose input ports after a power on reset.	BACK UP Open drain CONTROL PE1/PE2-PORT A10900
1 100	XIN XOUT	I 0	Connections for a 4.5-MHz crystal oscillator element	XIN A10901
98 97	E01 E02	0	Main charge pump outputs These pins output a high level when the frequency of the local oscillator divided by n is higher than that of the reference frequency, and they output a low level when that frequency is lower. They go to the high-impedance state when the frequencies match. These pins go to the high-impedance state in backup mode, after a power on reset, and in the PLL stopped state.	A10902
39 93 4 40 81 96	V _{DD} PORT V _{DD} PLL V _{SS} CPU V _{SS} PORT V _{SS} ADC V _{SS} PLL	_	Power supply connections The $V_{DD}PORT$ and $V_{SS}PORT$ pins mainly supply power for the peripheral I/O blocks and the regulator. The $V_{DD}PLL$ and $V_{SS}PLL$ pins mainly for the PLL circuits. The $V_{SS}CPU$ pin is mainly used by the CPU block. The $V_{SS}ADC$ pin is mainly used by the A/D converter block. Since all the V_{DD} and V_{SS} pins are independent, all must be connected to the same power supply.	
3	V_{REG}	0	Internal low voltage output Connect a bypass capacitor to this pin.	
95	FM _{IN}	I	FM VCO (local oscillator) input This pin is selected with CW1 in the PLL instruction. The signal input to this pin must be capacitor coupled. Input is disabled in backup mode, after a power on reset, and in the PLL stopped state.	;
94	AM _{IN}	I	AM VCO (local oscillator) input This pin is selected and the band set with CW1 (b1, b0) in the PLL instruction. b1 b0 Band 1 0 2 to 40 MHz (SW) 1 1 0.5 to 10 MHz (MW, LW) The signal input to this pin must be capacitor coupled. Input is disabled in backup mode, after a power on reset, and in the PLL stopped state.	PLL STOP instruction A10903

Continued from preceding page.

Sub-charge pump couput and general-purpose input shared function port. The IOS2 instruction is used for switching between the sub-charge pump output and general-pumpose input functions. When used as the sub-charge pump output. The sub-charge pump output function is set up with the IOS2 instruction. Main charge pump, custor and so formed by using the pin in conjunction with the main charge pump. The sub-charge pump is controlled using the IDS2 instruction. Bis Dis Display persists when the PLL is unlocked (500 kHz)	Pin No.	Symbol	I/O			Function	Equivalent circuit			
SUBPD I/O 10 High impedances 10 10 10 10 10 10 10 1				The IOS2 general-p • When u The su A high- main cl	2 instruction instruction in the control of the con	ction is used for switching between the sub-charge pump output and input functions. the sub-charge pump output: e pump output function is set up with the IOS2 instruction. ocking circuit can be formed by using this pin in conjunction with the ump.				
SUBPD I/O 10 High impedances 10 10 10 10 10 10 10 1				h3	h2	Operation				
SUBPO 10		011000	.,,	l -						
Second PLL charge pump output and general-purpose input shared function port The IOS2 instruction. Data is read from the port using the INR instruction. This pin goes to the high-impedance state in backup mode, after a power on reset, and in the PLL stopped state. Second PLL charge pump output and general-purpose input shared function port The IOS2 instruction is used for switching between the second PLL charge pump output and general-purpose input functions. When used as a charge pump output functions.	92	SUBPD	1/0	l —	-	5 .				
When used as a general-purpose input: The general-purpose input (Incition is set up with the IOS2 instruction.) Data is read from the port using the INR instruction. This pin goes to the high-impedance state in backup mode, after a power on reset, and in the PLL stopped state. Second PLL charge pump output and general-purpose input shared function port The IOS2 instruction is used for switching between the second PLL charge pump output and general-purpose input functions. When used as a charge pump output the IOS2 instruction. This pin outputs a low level when the frequency of the local oscillator divided by n is higher than that of the reference frequency, and it outputs a high level when that groupency is lower. It goes to the high-impedance state when the frequencies match. (Note that the logic of this pin is inverted from that of the EO1 and EO2 when used as a general-purpose input. The general-purpose input function is set up with the IOS2 instruction. Data is read from the port using the INR instruction. This pin goes to the high-impedance state when the requencies and in the PLL stopped state. Universal counter and general-purpose input shared function input port The IOS1 instruction is used for switching between the universal counter and general-purpose input shared function input port The IOS1 instruction is used for switching between the universal counter and general-purpose input pin: The universal counter function is set up with the IOS1 instruction. The universal counter struction is set up with the IOS1 instruction. Data is send from the port using the INR (IO) instruction. Data is send from the port using the INR (IO) instruction. Data is send from the port using the INR (IO) instruction. Set up LCTR frequency measurement: The universal counter function is set up with the IOS1 instruction, and control operation with the UCS instruction is an AC ampiller in this mode, the input signal must be input with copacitor coupling. When used for frequency measurement mode with the UCS instruction, a				1	0					
The general-purpose input function is set up with the IOS2 instruction. Data is read from the port using the INR instruction. This pin goes to the high-impedance state in backup mode, after a power on reset, and in the PLL stopped state. Second PLL charge pump output and general-purpose input shared function port The IOS2 instruction is used for switching between the second PLL charge pump output and general-purpose input functions. When used as a charge pump output. The charge pump output function is set up with the IOS2 instruction. This pin outputs a fix wheel when the frequency of the local oscillator divided by in is higher than that of the reference frequency, and it outputs a high level when that is higher than that of the reference frequency, and it outputs a high level when that is higher than that of the reference frequency, and it outputs a high level when that is higher than that of the reference frequency, and it outputs a high level when that is higher than that of the reference frequency, and it outputs a high level when that is higher than that of the reference frequency, and it outputs a high level when that is higher than that of the reference frequency, and it outputs a high level when that is higher than that of the reference in the local control of the local oscillator divided by it is higher than that of the reference in the local oscillator divided by it is higher than the local oscillator divided by it is an interest to the local oscillator divided by it is a local oscillator divided by it is an interest to the local oscillator divided by it is a local oscillato				1	1	Normal operation	BACK UP			
The IOS2 instruction is used for switching between the second PLL charge pump output and general-purpose input functions. When used as a charge pump output. The charge pump output function is set up with the IOS2 instruction. This pin outputs a low level when the frequency of the local oscillator divided by n is higher than that of the reference frequency, and it outputs a high level when that frequency is lower. It goes to the high-impedance state when the frequencies match. (Note that the logs of this pin is inverted from that of the EO1 and EO2 pins) When used as a general-purpose input: The general-purpose input function is set up with the IOS2 instruction. Data is read from the port using the INR instruction. This pin goes to the high-impedance state in backup mode, after a power on reset, and in the PLL stopped state. Universal counter and general-purpose input shared function input port The IOS1 instruction is used for switching between the universal counter and general-purpose input functions. • When used for frequency measurement: The counter is controlled using the IOS3 and UCC instruction. This peneral-purpose input function is set up with the IOS1 instruction. Data is read from the port using the INR (10) instruction. Data is read from the port using the INR (10) instruction. Data is read from the port using the INR (10) instruction. Data is read from the port using the INR (10) instruction. Set up LCTR frequency measurement: The universal counter function is set up with the IOS1 instruction, and control operation with the UCC instruction. Set up LCTR frequency measurement: The universal counter function is set up with the IOS1 instruction, and control operation with the UCC instruction. Since the pins functions as an AC amplifier in this mode, the input signal must be input with capacitor coupling. • When used for frequency measurement mode with the UCS instruction, and control operation with the UCC instruction. Since the pins function is set up with the IOS1 instruction. Set up LCTR frequen				The ge Data is This pin	neral-po read fro goes to	urpose input function is set up with the IOS2 instruction. om the port using the INR instruction. the high-impedance state in backup mode, after a power on reset,				
The IOS1 instruction is used for switching between the universal counter and general-purpose input functions. • When used for frequency measurement: The universal counter function is set up with the IOS1 instruction. The counter is controlled using the UCS and UCC instructions. Since this pin functions as an AC amplifier in this mode, the input signal must be input with capacitor coupling. • When used as a general-purpose input pin: The general-purpose input function is set up with the IOS1 instruction. Data is read from the port using the INR (b0) instruction. Input is disabled in backup mode. (The input pin will be pulled down.) The universal counter function is selected after a power on reset. Universal counter (frequency or period measurement) and general-purpose input shared function input port The IOS1 instruction is used for switching between the universal counter and general-purpose input functions. • When used for frequency measurement: The universal counter function is set up with the IOS1 instruction, and control operation with the UCC instruction. Since this pin functions as an AC amplifier in this mode, the input signal must be input with capacitor coupling. • When used for period measurement: The universal counter function is set up with the IOS1 instruction, and control operation with the UCC instruction. Since the bias feedback resistor is disconnected in this mode, the input signal must be input with DC coupling. • When used as a general-purpose input prin: The general-purpose input prin: The general-purpose input prince the bias feedback resistor is disconnected in this mode, the input signal must be input with DC coupling. • When used as a general-purpose input prince the bias feedback resistor is disconnected in this mode, the input signal must be input with DC coupling. • When used on the port using the INR (b1) instruction. Input is disabled in backup mode. (The input pin will be pulled down.) The universal counter function (ICTR frequency measurement mode) is selected	91	E03	I/O	The IOS output ar • When to the Charles pin is higher frequent match. pins.) • When to the Charles pins. The ge Data is This pin	2 instructed as a repeated as a repeated as a repeated as a repeated as a read frogoes to	cition is used for switching between the second PLL charge pump ral-purpose input functions. a charge pump output: mp output function is set up with the IOS2 instruction. ts a low level when the frequency of the local oscillator divided by n that of the reference frequency, and it outputs a high level when that ower. It goes to the high-impedance state when the frequencies that the logic of this pin is inverted from that of the EO1 and EO2 a general-purpose input: urpose input function is set up with the IOS2 instruction. on the port using the INR instruction.	A10904			
shared function input port The IOS1 instruction is used for switching between the universal counter and general-purpose input functions. • When used for frequency measurement: The universal counter function is set up with the IOS1 instruction. Set up LCTR frequency measurement mode with the UCS instruction, and control operation with the UCC instruction. Since this pin functions as an AC amplifier in this mode, the input signal must be input with capacitor coupling. • When used for period measurement: The universal counter function is set up with the IOS1 instruction. Set up LCTR frequency measurement mode with the UCS instruction, and control operation with the UCC instruction. Since the bias feedback resistor is disconnected in this mode, the input signal must be input with DC coupling. • When used as a general-purpose input pin: The general-purpose input port function is set up with the IOS1 instruction. Data is read from the port using the INR (b1) instruction. Input is disabled in backup mode. (The input pin will be pulled down.) The universal counter function (HCTR frequency measurement mode) is selected	90	HCTR	I	The IOS general-p • When the un The consince to input when the un The general states and the states are the states and the states are the states and the states are the sta	ourpose used for iversal outpose uniter is his pin ith capaused as neral-puread frost in the capaused from the capaused as the capaused from the capaused fr	uction is used for switching between the universal counter and input functions. frequency measurement: counter function is set up with the IOS1 instruction. controlled using the UCS and UCC instructions. functions as an AC amplifier in this mode, the input signal must be actor coupling. a general-purpose input pin: urpose input function is set up with the IOS1 instruction. om the port using the INR (b0) instruction. I in backup mode. (The input pin will be pulled down.) The universal				
	89	LCTR	I	shared fu. The IOS general-p • When u The un Set up operati this mo • When u The un Set up operati disconr • When u The ge Data is Input is	unction in instruction in instruction in instruction in instruction in instruction with index, the used for inversal (instructed in used as neral-pure read for instruction in instruction	input port uction is used for switching between the universal counter and input functions. If requency measurement: counter function is set up with the IOS1 instruction. If requency measurement mode with the UCS instruction, and control the UCC instruction. Since this pin functions as an AC amplifier in input signal must be input with capacitor coupling. If period measurement: counter function is set up with the IOS1 instruction. If requency measurement mode with the UCS instruction, and control the UCC instruction. Since the bias feedback resistor is in this mode, the input signal must be input with DC coupling. If a general-purpose input pin: If urpose input port function is set up with the IOS1 instruction. If the port using the INR (b1) instruction. If the port using the INR (b1) instruction. If the port using the INR (b1) instruction. If the input pin will be pulled down.	instruction			

Continued from preceding page.

Pin No.	Symbol	I/O	Function	Equivalent circuit
88	sns	I	Voltage sense and general-purpose input shared function port This input circuit is designed with a low input threshold voltage. • When used as a voltage sense input: This pin is used to test for power failures on the return from backup mode. Application can test this condition using the internal SNS flip-flop. The SNS flip-flop can be tested with the TST instruction. (This usage requires external components (capacitors and resistors). See the sample application circuit in the user's manual.) • When used as a general-purpose input port: When used as a general-purpose input port the pin state can be tested with the TST instruction. Unlike the other input ports, input to this pin is not disabled in backup mode and after a power on reset. As a result, through currents must be taken into account when designing applications that use this pin as a general-purpose input.	A10906
87	HOLD	I	Power supply monitor (with interrupt function) This pin is designed with a high input threshold voltage. This pin is normally connected to the ACC line and used for power off detection. When a power off state is detected, the HOLDON flag and the hold interrupt request flag will be set. To enter backup mode, execute a CKSTP instruction when the HOLD pin is low. Set this pin high to clear backup mode.	A10907
86	RESET	I	System reset pin When the CPU is operating or in halt mode, the system is reset when this pin is held low for at least one machine cycle. Execution starts with the PC pointing to location 0. At this time the SNS flip-flop is set. A low level must be applied for at least 50 ms when power is first applied.	A10908
85 84 83 82 81 80 79 78	PH0/ADI0 PH1/ADI1 PH2/ADI2 PH3/ADI3 PI0/ADI4 PI1/ADI5 PI2/ADI6 PI3/ADI7	ı	General-purpose input and A/D converter input shared function ports The IOS1 instruction is used to switch between the general-purpose input and the A/D converter input functions. • When used as a general-purpose input ports: The general-purpose input port function is set up with the IOS1 instruction. (In bit units) • When used as A/D converter input pins: The A/D converter input port function is set up with the IOS1 instruction. (In bit units) The pin whose voltage is to be converted is specified with the IOS1 instruction, and the conversion is started with the UCC instruction. Note: Since input is disabled for ports specified for the ADI function, executing an input instruction for such a port will always return a low level. Input is disabled in backup mode. These ports are set up as general-purpose input ports after a power on reset.	To the A/D converter input
76 75 74 73	PJ0 PJ1 PJ2 PJ3	0	General-purpose output ports Since these are open-drain output circuits, external pull-up resistors are required. The internal transistors are turned off (resulting in a high-level output) in backup mode and after a power on reset.	BACK UP
72 71 70 69	PK0/INT0 PK1/INT1 PK2/INT2 PK3/INT3	I/O	General-purpose I/O and external interrupt shared function ports The input formats are Schmitt inputs. The external interrupt function is enabled when the external interrupt enable flag is set. • When used as general-purpose I/O ports: The mode (input or output) is set in 1-bit units using the IOS1 instruction. • When used as external interrupt pins: The external interrupt functions are enabled by setting the corresponding external interrupt enable flag (INTOEN through INT3EN). Here, the pins must be set to input mode in advance. Input is disabled and the pins go to the high-impedance state in backup mode. These ports are set up as general-purpose input ports after a power on reset.	BACK UP A10911

Continued from preceding page.

Pin No.	Symbol	I/O	Function	Equivalent circuit
68 to 61	PL0 to 3 PN0 to 3	I/O	General-purpose I/O ports The mode is switched between input and output with the IOS instruction. Input is disabled and the pins go to the high-impedance state in backup mode. These ports are set up as general-purpose input ports after a power on reset.	
60 59 58 57	PN0/BEEP PN1 PN2 PN3	I/O	General-purpose I/O port and beep tone output shared function ports The IOS2 instruction is used to switch between the general-purpose I/O port and the beep tone output functions. • When used as a general-purpose input ports: The general-purpose I/O port function is set up with the IOS2 instruction. (Pins PN1 through PN3 are general-purpose I/O pins.) • When used as the beep tone output pin: The beep tone output function is set up with the IOS2 instruction. The frequency is set with the BEEP instruction. When this pin is used as the beep tone output pin, executing an output instruction for this pin only sets the internal latch and has no influence on the output. Input is disabled and the pins go to the high-impedance state in backup mode. These ports are set up as general-purpose input ports after a power on reset.	BACK UP A10912
56 to 49	P00 to 3 PP0 to 3	I/O	General-purpose I/O ports The mode is switched between input and output with the IOS instruction. Input is disabled and the pins go to the high-impedance state in backup mode. These ports are set up as general-purpose input ports after a power on reset.	
48 to 41 38 to 33	PQ0 to 3 PR0 to 3 PS0 to 3 PT0 to 1	I/O	General-purpose I/O ports The mode is switched between input and output with the IOS instruction, and data is input with the INR instruction and output with the OUTR instruction. The SPB, RPB, TPT, and TPF instruction cannot be used with these ports. Input is disabled and the pins go to the high-impedance state in backup mode. These ports are set up as general-purpose input ports after a power on reset.	BACK UP
99 2	TEST1 TEST2		IC test pins These pins must be tied to ground.	

LC723700 Instruction Set

Abbreviations

ADDR: Program memory address

b: Borrow c: Carry

DH: Data memory address High (Row address) [2 bits]
DL: Data memory address Low(Column address) [4 bits]

I: Immediate data [4 bits]M: Data memory addressN: Bit position [4 bits]

M_{ADR}: M specified by address register

ROM_{ADR}: Program memory data specified by address register

P1n, P2n: Port number [4 bits]

PW1n, PW2n: Port control word number [4 bits]
PEn: Peripheral register number [4 bits]

SR: ADR/DTR
ADR: Address register
DTR: Data register

r: General register (One of the address from 00H to 0FH of BANK0)

SWR: Status write register SRR: Status read register

(), []: Contents of register or memory M(DH, DL): Data memory specified by DH, DL

Instruction group Muei	Mnemonic -	Operand		Function	Operations function	Instruction format				
	winemonic	1st	2nd	Function	Operations function	f e d c b a 9 8 7 6 5 4 3 2 1 0				
_	AD	r	М	Add M to r	$r \leftarrow (r) + (M)$	0 1 0 0 0 0 DH DL r				
SU	ADS	r	М	ADD M to r, then skip if carry	$r \leftarrow (r) + (M)$, skip carry	0 1 0 0 0 1 DH DL r				
Addition instructions	AC	r	М	Add M to r with carry	$r \leftarrow (r) + (M) + C$	0 1 0 0 1 0 DH DL r				
stru	ACS	r	М	Add M to r with carry, then skip if carry	$r \leftarrow (r) + (M) + C$ skip if carry	0 1 0 0 1 1 DH DL r				
l E	Al	М		Add I to M	$M \leftarrow (M) + I$	0 1 0 1 0 0 DH DL I				
dific	AIS	М		Add I to M, then skip if carry	$M \leftarrow (M) + I$, skip if carry	0 1 0 1 0 1 DH DL I				
Ao	AIC	М		Add I to M with carry	$M \leftarrow (M) + I + C$	0 1 0 1 1 0 DH DL I				
	AICS	М	1	Add I to M with carry, then skip if carry	$M \leftarrow (M) + I + C$, skip if carry	0 1 0 1 1 1 DH DL I				
	SU	r	М	Subtract M from r	$r \leftarrow (r) - (M)$	0 1 1 0 0 0 DH DL r				
S	SUS	r	М	Subtract M from r, then skip if borrow	$r \leftarrow (r) - (M)$, skip if borrow	0 1 1 0 0 1 DH DL r				
fion	SB	r	М	Subtract M from r with borrow	$r \leftarrow (r) - (M) - b$	0 1 1 0 1 0 DH DL r				
Subtraction instructions	SBS	r	М	Subtract M from r with borrow, then skip if borrow	$r \leftarrow (r) - (M)$ –b, skip if borrow	0 1 1 0 1 1 DH DL r				
fjo	SI	М		Subtract I from M	$M \leftarrow (M) - I$	0 1 1 1 0 0 DH DL I				
tract	SIS	М	1	Subtract I from M, then skip if borrow	$M \leftarrow (M) - I$, skip if borrow	0 1 1 1 0 1 DH DL I				
Subi	SIB	М		Subtract I from M with borrow	$M \leftarrow (M) - I - b$	0 1 1 1 1 0 DH DL I				
	SIBS	М	 - -	Subtract I from M with borrow, then skip if borrw	$M \leftarrow (M) - I - b$, skip if borrow	0 1 1 1 1 DH DL I				
SU	SEQ	r	М	Skip if r equal to M	(r) – (M), skip if zero	0 0 0 1 0 0 DH DL r				
ctio	SEQI	М		Skip if M equal to I	(M) – I, skip if zero	0 0 0 1 0 1 DH DL I				
ıstru	SNEI	М		Skip if M not equal to I	(M) – I, skip if not zero	0 0 0 0 0 1 DH DL I				
l ir	SGE	r	М	Skip if r is greater than or equal to M	(r) – (M), skip if not borrow	0 0 0 1 1 0 DH DL r				
arisc	SLE	r	М	Skip if r is less than M	(r) – M, skip if borrow	0 0 0 0 1 0 DH DL r				
Comparison instructions	SGEI	М		Skip if M is greater than or equal to I	(M) – I, skip if not borrow	0 0 0 1 1 1 DH DL I				
ŏ	SLEI	М		Skip if M is less than I	(M) – I, skip if borrow	0 0 0 0 1 1 DH DL I				

Continued from preceding page.

E C		Opera	and			Instruction format
Instruction group	Mnemonic	1st	2nd	Function	Operations function	f e d c b a 9 8 7 6 5 4 3 2 1 0
드	AND	r	M	AND M with r	r ← (r) AND (M)	0 0 1 0 0 0 DH DL r
_	ANDI	М :	ı	AND I with M	$M \leftarrow (M) \text{ AND I}$	0 0 1 0 0 1 DH DL I
atior	OR	r	М	OR M with r	$r \leftarrow (r) OR (M)$	0 0 1 0 1 0 DH DL r
gical operati instructions	ORI	М	I	OR I with M	$M \leftarrow (M) \text{ OR I}$	0 0 1 0 1 1 DH DL I
stru	EXL	r	М	Exclusive OR M with r	$r \leftarrow (r) \text{ XOR (M)}$	0 0 1 1 0 0 DH DL r
Logical operation instructions	EXLI	М	I	Exclusive OR M with M	$M \leftarrow (M) XOR I$	0 0 1 1 0 1 DH DL I
	SHMR	N	И	Shift M right with carry	carry (M)	1 1 1 1 1 1 1 1 0 DH DL
	LD	r	М	Load M to r	$r \leftarrow (M)$	1 1 0 1 0 0 DH DL r
	ST	М	r	Strore r to M	$M \leftarrow (r)$	1 1 0 1 0 1 DH DL r
ons	LDA	ı	r	Load M specified by ADR to r	$r \leftarrow (M_{ADR})$	1 1 1 1 1 0 0 1 1 1 0 0 r
ucti	STA	ı	r	Store r to M specified by ADR	$M_{ADR} \leftarrow (r)$	1 1 1 1 1 0 0 1 1 1 0 1 r
Transfer instructions	MVRD	r	М	Move M to destination M referring to r in the same row	[DH, rn] ← (M)	1 1 0 1 1 0 DH DL r
Transf	MVRS	M	r	Move source M referring to r to M in the same row	$M \leftarrow (DH, rn)$	1 1 0 1 1 1 DH DL r
	MVSR	M1	M2	Move M to M in the same row	[DH, DL1] ← [DH, DL2]	1 1 1 0 0 0 DH DL DL2
	MVI	М	ı	Move I to M	$M \leftarrow I$	1 1 1 0 0 1 DH DL I
Bit test instructions	TMT	М	N	Test M bits, then skip if all bits specified are true	if M(N) = all 1, then skip	1 1 1 1 0 0 DH DL N
Bit test instruction	TMF	М	N	Test M bits, then skip if all bits specified are false	if M(N) = all 0, then skip	1 1 1 1 0 1 DH DL N
	JMP	AD	DR	Jump to the address	PC ← ADDR	1 0 ADDR(14 bits)
	JMPA			Jump to the address specified by ADR	PC ← (ADR)	0 0 0 0 0 0 0 0 1 1 1 0
	JMPR	ADDR		Jump to the relative address	PC ← (PC) + 1 + ADDR	1 1 1 1 1 0 1 0 ADDR (8 bits)
ctions	CAL	ADDR		Call subroutine	PC ← ADDR Stack ← (PC) + 1	1 1 0 0 ADDR(12 bits)
Jump and subroutine instructions	CALA	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		Call subroutine specified by ADR	$PC \leftarrow (ADR)$ $Stack \leftarrow (PC) + 1$	0 0 0 0 0 0 0 0 1 1 1 1
ltine [RT	i !		Return from subroutine	PC ← Stack	0 0 0 0 0 0 0 0 1 0 0 0
brou	RTS			Return from subroutine and skip	PC ← Stack + 1	0 0 0 0 0 0 0 0 1 0 1 0
and su	RTB			Return from subroutine with BANK data	PC ← Stack, BANK ← Stack	1 1 1 1 1 1 1 1 0 0
Jump	RTBS			Return from subroutine with BANK data and skip	PC ← Stack + 1, BANK ← Stack	1 1 1 1 1 1 1 1 0 1
	RTI			Return from interrupt	PC ← Stack, BANK ← Stack, CARRY ← Stack PAGE ← Stack	0 0 0 0 0 0 0 0 1 0 0 1
s ter	SS	SWR	N	Set status register	(Status W-reg)N ← 1	1 1 1 1 1 1 1 1 0 0 SWR N
Status register instructions	RS	SWR	N	Reset status register	(Status W-reg)N ← 0	1 1 1 1 1 1 1 1 0 1 SWR N
us r	TST	SRR	N	Test status register true	if (Status R-reg)N = all1, then skip	1 1 1 1 1 0 0 0 0 SRR N
Stat	TSF	SRR	N	Test status register false	· · · · · · · · · · · · · · · · · · ·	1 1 1 1 1 0 0 0 1 SRR N
ster	PLL	N	1	Load M to PLL register	PLL reg ← PLL data	1 1 1 1 0 0 1 0 1 DH DL
Internal register transfer instructions	PUT	PE	≣n	Put data of DTR to perifheral register	PEn ← (DTR)	1 1 1 1 1 0 0 1 1 0 1 0 PEn
Inter	GET	PEn		Get peripheral data to DTR	DTR ← (PEn)	1 1 1 1 1 0 0 1 1 0 1 1 PEn
suo	SIO	l1	12	Serial I/O control	SIO reg ← I1, I2	0 0 0 0 0 0 0 1 11 12
ncţi,	ucs	l	l	Set I to UCCW1	UCCW1 ← I	0 0 0 0 0 0 0 0 0 0 1 I
instr	UCC	l	l	Set I to UCCW2	UCCW2 ← I	0 0 0 0 0 0 0 0 0 1 0 I
	BEEP I		l	Beep control	BEEP reg ← I	0 0 0 0 0 0 0 0 0 1 1 0 I
				Dead zone control	DZC reg ← I	
Cont	DZC	l	l	Dead Zone Control		0 0 0 0 0 0 0 0 1 0 1 1
are cont	DZC TMS			Set timer register	Timer reg ← I	00000001100
Hardware control instructions			l		-	

Continued from preceding page.

Instruction group	Mnemonic	Operand		Function	Operations function	Instruction format				
Instru	ogo Inlemonic	1st	2nd	Function	Operations function	f e d c b a 9 8 7 6 5 4 3 2 1 0				
	IN	М	P1n	Input port1 data to M	$M \leftarrow (P1n)$	1 1 1 0 1 0 DH DL P1n				
	OUT	М	P1n	Output contents of M to port 1	P1n ← M	1 1 1 0 1 1 DH DL P1n				
	INR	М	P2n	Input port 2 data to M	M ← (P2n)	0 0 1 1 1 0 DH DL P2n				
I/O instructions	OUTR	М	P2n	Output contents of M to port 2	$P2n \leftarrow (M)$	0 0 1 1 1 1 DH DL P2n				
truci	SPB	P1n	N	Set port 1 bits	(P1n)N ← 1	0 0 0 0 0 0 1 0 P1n N				
ins	RPB	P1n	N	Reset port 1 bits	(P1n)N ← 0	0 0 0 0 0 0 1 1 P1n N				
9	TPT	P1n	N	Test port 1 bits, then skip if all bits specified are true	if (P1n)N = all 1, then skip	1 1 1 1 1 0 0 P1n N				
	TPF	P1n	N	Test port 1 bits, then skip if all bits specified are false	if (P1n)N = all 0, then skip	1 1 1 1 1 0 1 P1n N				
Bank switching instructions	BANK	ı		Select Bank	BANK ← I	1 1 1 1 1 0 0 1 0 0				
Table reference instructions	MVTL	 		Move program memory data specified by ADR to DTR	$DTR \leftarrow (ROM_ADR)$	0 0 0 0 0 0 0 0 0 0 1 1				
Stack manipulation instructions	PUSH	S	R	Move ADR/DTR to stack	Stack ← (ADR/DTR)	1 1 1 1 1 0 0 1 1 0 0 0 SR				
Stack ma instru	POP	SR		Move stack to ADR/DTR	ADR/DTR ← Stack	1 1 1 1 1 0 0 1 1 0 0 1 SR				
S	PAGE	l		Set page flag	PAGE flag ← I	0 0 0 0 0 0 0 0 0 1 1 1 I				
Other instructions	HALT	1		Halt mode control	HALT reg ← I, then CPU clock stop	0 0 0 0 0 0 0 0 0 1 0 0				
Other	CKSTP			Clock stop	Stop xtal OSC if HOLD = 0	0 0 0 0 0 0 0 0 0 1 0 1				
	NOP			No operation	No operation	0 0 0 0 0 0 0 0 0 0 0				

- No products described or contained herein are intended for use in surgical implants, life-support systems, aerospace equipment, nuclear power control systems, vehicles, disaster/crime-prevention equipment and the like, the failure of which may directly or indirectly cause injury, death or property loss.
- Anyone purchasing any products described or contained herein for an above-mentioned use shall:
 - ① Accept full responsibility and indemnify and defend SANYO ELECTRIC CO., LTD., its affiliates, subsidiaries and distributors and all their officers and employees, jointly and severally, against any and all claims and litigation and all damages, cost and expenses associated with such use:
 - ② Not impose any responsibility for any fault or negligence which may be cited in any such claim or litigation on SANYO ELECTRIC CO., LTD., its affiliates, subsidiaries and distributors or any of their officers and employees jointly or severally.
- Information (including circuit diagrams and circuit parameters) herein is for example only; it is not guaranteed for volume production. SANYO believes information herein is accurate and reliable, but no guarantees are made or implied regarding its use or any infringements of intellectual property rights or other rights of third parties.

This catalog provides information as of June, 1998. Specifications and information herein are subject to change without notice.