

# **3-Phase Brushless Motor Driver** for CD-ROM Spindle Motors

### Overview

The LB1894M is a 3-phase brushless motor driver for use in CD-ROM spindle motors.

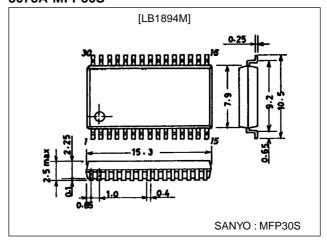
#### **Function and Features**

- 3-phase bipolar brushless motor driver.
- Voltage linear drive, enabling the external capacitance to be reduced.
- Thermal shutdown circuit built-in.
- Overcurrent protection circuit built-in.
- V-type control amplifier built-in.
- 2-step switching control gain.
- Control gain switchable using operational amplifier.

## **Package Dimensions**

unit:mm

#### 3073A-MFP30S



## **Specifications**

## Absolute Maximum Ratings at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Maximum supply voltage	V <sub>CC</sub> 1 max		20	V
waximum supply voltage	V <sub>CC</sub> 2 max		7.0	V
Output supply current	V <sub>OU</sub> , v, w		22	V
Output current	lout		1.5	Α
Allowable power dissipation	Pd max		1.05	W
Operating temperature	Topr		-20 to +75	°C
Storage temperature	Tstg		-55 to +150	°C

#### Allowable Operating Ranges at Ta = 25°C

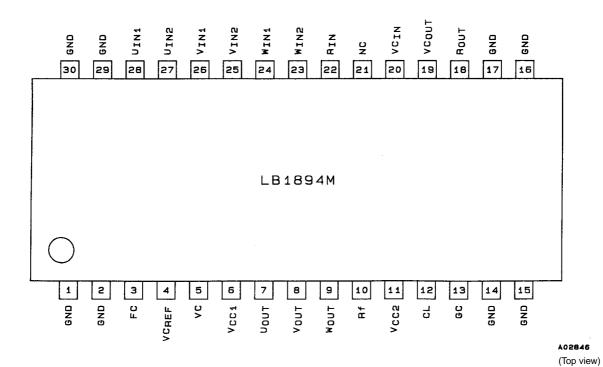
Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	V <sub>CC</sub> 1		5 to 18	V
Supply voltage	V <sub>CC</sub> <sup>2</sup>		4.3 to 6.5	V

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# Electrical Characteristics at Ta = 25 $^{\bullet}C,\,V_{CC}1\text{=}12V,\,V_{CC}2\text{=}5V$

Parameter	Cumbal	Symbol Conditions	Ratings			Unit
Farameter	Symbol		min	typ	max	UIII
Supply current	I <sub>CC</sub> 1	VC=VC <sub>REF</sub> , R <sub>L</sub> =∞		17	30	mA
Supply current	I <sub>CC</sub> 2	VC=VC <sub>REF</sub>		6.5	9.5	mA
[Driver stage]	,					
Output saturation voltage	V <sub>O(sat)</sub> 1	I <sub>OUT</sub> =0.5A, sink+source		1.6	2.2	V
Output Saturation Voltage	V <sub>O(sat)</sub> 2	I <sub>OUT</sub> =1.0A, sink+source		2.0	3.0	V
Output transistor blocking voltage	V <sub>O(sus)</sub>	I <sub>OUT</sub> =20mA, design value	20			V
Output rest voltage	V <sub>OQ</sub>	VC=VC <sub>REF</sub>	5.7	6.0	6.3	V
Hall amplifier input offset voltage	V <sub>H</sub> offset		-5		+5	mV
Hall amplifier input bias current	I <sub>H bias</sub>			1	5	μΑ
Hall amplifier common-mode input voltage range	V <sub>Hch</sub>		1.3		2.2	V
Hall amplifier input-output voltage gain	G <sub>VHO</sub>		42	45	48	dB
[Control stage]	•					
Control-output drive gain	G <sub>VCO</sub> 1	High gain, GC=high	32	35	38	dB
Control-output unive gain	G <sub>VCO</sub> 2	Low gain, GC=low	26	29	32	dB
Control-output channel difference	∆G <sub>VCO</sub>		-2		+2	dB
Control rising threshold voltage	VCTH	VC <sub>REF</sub> =2.5V, V <sub>OUT</sub> =0.1Vp-p	2.35		2.65	V
Control rising threshold voltage width	∆VC <sub>TH</sub>	VC <sub>REF</sub> =2.5V, V <sub>OUT</sub> =0.1Vp-p	50		150	mV
Gain control switching high-level voltage	<sup>V</sup> GCH		4		5	V
Gain control switching low-level voltage	VGCL	Inputs are low level when left open	0		+2	V
[Op-amplifiers]						
Op-amplifier intput offset voltage	VFG offset		-8		+8	mV
Open-loop voltage gain	G <sub>VFG</sub>	f=1kHz		60		dB
Source output saturation voltage	VFG OU	I <sub>O</sub> =-2mA	3.7			V
Sink output saturation voltage	VFG OD	I <sub>O</sub> =2mA			1.3	V
Common-mode signal rejection	CHR	Design value		80		dB
Op-amplifier common-mode input voltage range	V <sub>FG</sub> CH	VC <sub>REF</sub> =1.5V to V <sub>CC</sub> 2, design value	0		+3.5	V
Phase margin	φМ	Design value		20		deg
[Thermal shutdown]						
Thermal shutdown operating temperature	TSD	Design value	150	180	210	°C
TSD hysteresis	ΔTSD	Design value		15		°C

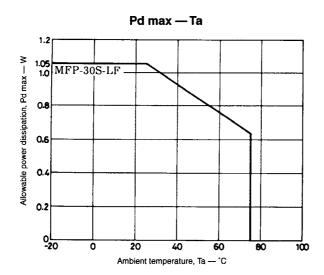
## **Pin Assignment**



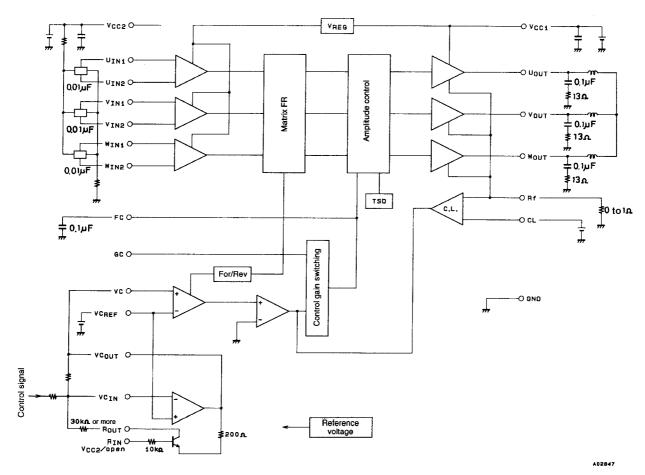
## **Truth Table**

	Source→Sink	Hall Input			Control	
	Godice— Silik	U <sub>IN</sub>	VIN	WIN	VC	
1	W-phase $\rightarrow$ V-phase	HIGH	HIGH	LOW	HIGH	
	V-phase → W-phase	TIIGH			LOW	
2	W-phase $\rightarrow$ U-phase	HIGH	LOW	LOW	HIGH	
	U-phase →W-phase	TIIGH			LOW	
3	V-phase →W-phase	LOW	LOW	HIGH	HIGH	
	W-phase $\rightarrow$ V-phase	LOW			LOW	
4	U-phase →V-phase	LOW	OW HIGH	LOW	HIGH	
	V-phase →U-phase	LOW HIGH LOW		LOW		
5	V-phase →U-phase	HIGH	LOW	HIGH	HIGH	
	U-phase → V-phase	півп	LOW		LOW	
6	U-phase → W-phase	LOW	HIGH	HIGH	HIGH	
	W-phase → U-phase	LOW			LOW	

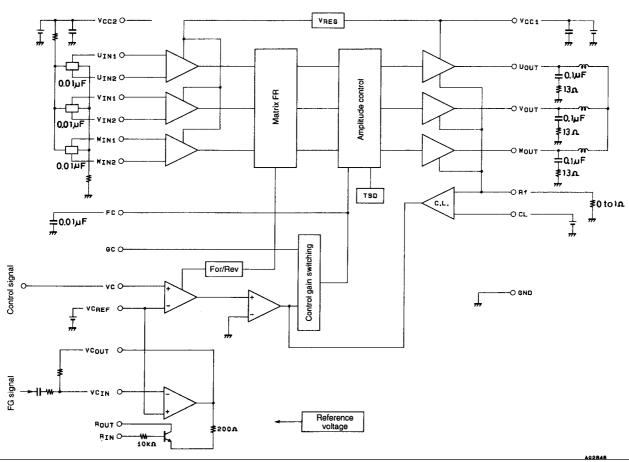
An input is considered to be HIGH when  $U_{IN}1 > U_{IN}2$ ,  $V_{IN}1 > V_{IN}2$ , and  $W_{IN}1 > W_{IN}2$  by 0.2V more, and is considered to be LOW when  $U_{IN}1 > U_{IN}2$ ,  $V_{IN}1 > V_{IN}2$ , and  $W_{IN}1 > W_{IN}2$  by 0.2V or less.



### **Block Diagram 1**



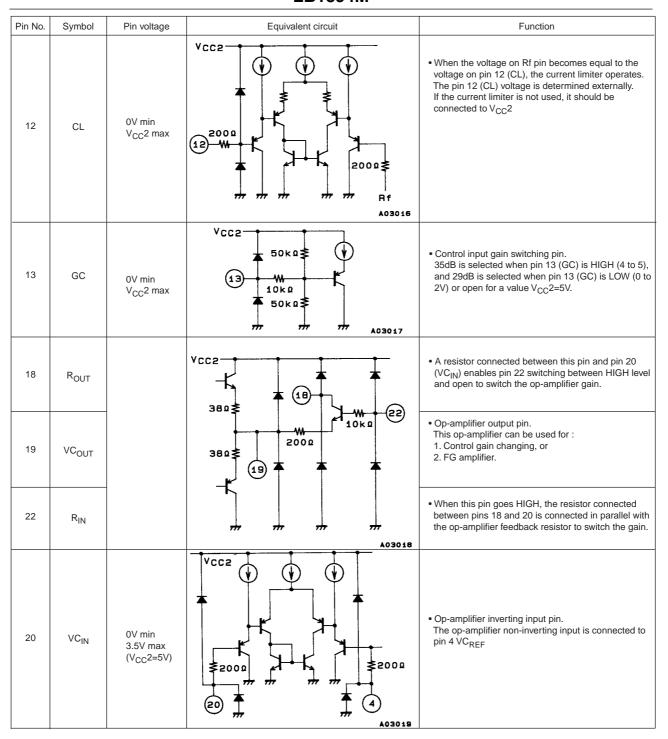
## **Block Diagram 2**



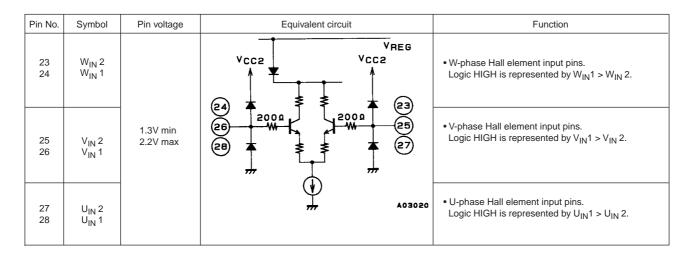
## **Pin Functions**

Pin No.	Symbol	Pin voltage	Equivalent circuit	Function
1, 2, 14, 15, 16, 17, 29, 30	FRAME (GND)			Ground connection for all circuit except the outputs.
3	FC		3.9k0 A03013	Connect a capacitor between this pin and ground to reduce the control input-output gain frequency response and to stop the oscillator.
4	VC <sub>REF</sub>	1.5V min V <sub>CC</sub> 2 max	VCC2 50#F 200#F 50#F	Speed control pins.     Pin 4 voltage determines the control start voltage.     Pin 5 voltage is used to control the output voltage
5	VC	0V min V <sub>CC</sub> 2 max	\$2000 \$ 2000 \$ 2000 \$ 2000 \$ 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	(voltage control method).
6	V <sub>CC</sub> 1	5 to 18V		Output-stage supply pin.
7 8 9	Uout Vout Wout		VCC1  VCC1  7 1kg 8 9 A03015	• Output pins.
10	Rf			Output transistor ground.     A resistor can be connected between this pin and GND to sense the output current as a voltage drop to provide for overcurrent protection.
11	V <sub>CC</sub> 2	4.3 to 6.5V		Supply for all circuits except the output stage. This supply should be kept stable to prevent ripple and noise from sntering this pin.

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