unit.



No.3348

LB1689M

# 3-Phase Brushless Motor Driver

### **Applications**

The LB1689M is a 3-phase brushless motor driver IC ideally suited for use in VTR capstan motor, drum motor drive applications, etc.

### **Features and Functions**

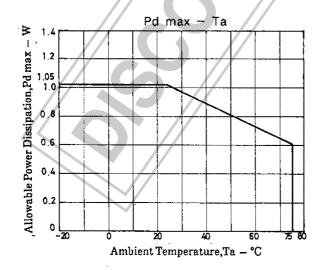
- (1) 120° voltage linear type
- (2) Soft switching type eliminating noises caused by current switching and making the values of external capacitors smaller (comparable to those of chip capacitors)
- (3) On-chip FG amplifier
- (4) On-chip thermal shutdown circuit
- (5) The FG signal can be used to detect the rotational speed of a motor so that the hall amp gain is changed in two steps, thus reducing torque ripple and noise.

### Absolute Maximum Ratings at Ta = 25°C

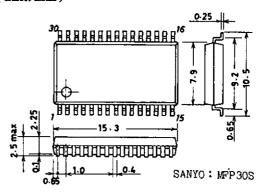
			4444
Maximum Supply Voltage	V <sub>CC</sub> max1	20	V
	V <sub>CC</sub> max2	7.0	V
Output Supply Voltage	V <sub>OUT.V.W.</sub>	22	V
Output Current	$I_{ m OUT}$	1.5	Α
Allowable Power Dissipation	Pd max	1.05	W
Operating Temperature	Topr	-20  to  +75	· °C
Storage Temperature	Tstg	-55  to  +125	$^{\circ}\mathrm{C}$

### Allowable Operating Conditions at Ta = 25°C

mowable operamig	Continues at 1a - 25 C		umu
Supply Voltage	$V_{CC}$ 1	8.5 to 18	V
	$V_{CC}2$	4.3 to 6.5	V



# Package Dimensions 3073A (unit: mm)

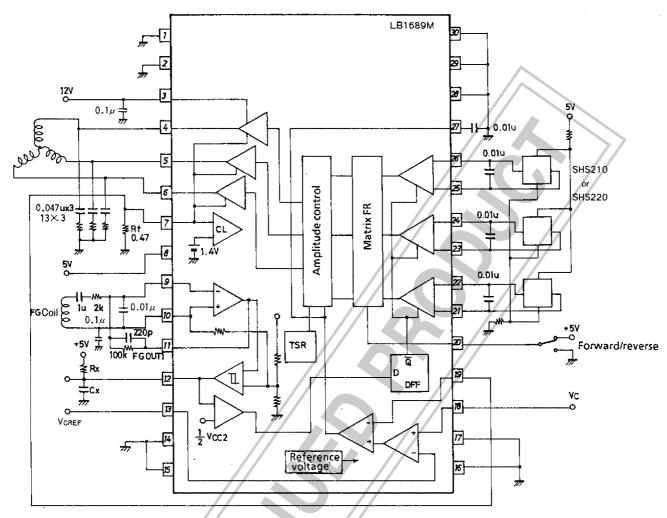


Electrical Characteristics at Ta = 2	$5^{\circ}\text{C,V}_{\text{CC}}$ 1 = 1	$12V, V_{CC}2 = 5V$	min	typ	max	unit
[Power Supply]	T .	W 0.D		1.77	20	A
Supply Current 1	I <sub>CC</sub> 1	$V_C = 0, R_L = \infty$		17	30	mΑ
Supply Current 2	$I_{CC}2$	$V_C = 0$		6.5	9.5	mA
[Output]						
Output Saturation Voltage	V <sub>O(sat)</sub> 1	$I_{OUT} = 0.5A$ , sink + source		1.6	2.2	V
	$V_{O(sat)}2$	$I_{OUT} = 1.0A$ , sink + source		2.0	3.0	V
Output TRS Voltage	$V_{O(sus)}$	I <sub>OUT</sub> = 20mA (See note.)	20			V
Output Quiescent Voltage	$v_{oq}$	$V_C = 0$	5.8	6.1	6.4	V
[Hall Input-Output]		//				>
Hall Amp Input Offset Voltage	V <sub>H</sub> offset		-5		+5	mV
Hall Amp Input Bias Current	I <sub>H</sub> bias			1	5	μΑ
Hall Amp Common-Mode	V <sub>H</sub> ch		1.3		3.7	V
Input Voltage Range						
Hall Input-Output Voltage Gain	G <sub>VHO</sub> 1			56		dB
•	$G_{VHO}2$			· <b>4</b> 3		dB
[Control-Output]						
Control-Output Voltage Gain	$G_{VCO}$		38	41	44	dB
Control-Output Voltage Gain	$\Delta G_{VCO}$		-2		+2	dB
CH Difference						
[FG Amplifier]						
FG Amp Input Offset Voltage	VFG offset		-8		+8	mV
Open Loop Voltage Gain	$G_{VFG}$	f=1kHz		60		dB
Source Output Saturation Voltage		$I_0 = 2mA$	3.7			V
Sink Output Saturation Voltage	$V_{FGOD}$	$I_0 = -2mA$			1.3	v
Common-Mode Signal	CHR	(See note.)		80		dB
Rejection Ratio				•		
FG Amp Common-Mode	V <sub>FGCH</sub>		0		3.5	v
Input Voltage Range						
Phase Margin		(Seë note.)		30		deg.
[Motor Detection]						Ŭ
Motor Detection Amp			35	50	65	mV
Hysteresis Width		' //		• •		
CR Pin Threshold Voltage		V <sub>CR</sub> changes from	2.35	2.5	2.65	V
		LOW to HIGH.				·
[Thermal Shutdown]		7				
Thermal Shutdown Temperature	$T_{SD}$	(See note.)	150	180	210	°C
Thermal Shutdown Hysteresis	$\Delta T_{SD}$	(See note.)	100	15	210	°C
===011041 0114140 1111 44,10001 0010	30	(~~~ 11000.)		10		U

Note: Values shown are design targets only. No measurements have been taken.

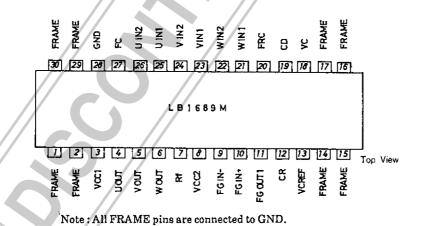
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# Equivalent Circuit Block Diagram



Pin Assignment

Unit (resistance: Ω, capacitance: F)



## Pin Description

Pin Name	Pin No.	Description
$U_{\rm IN}$ 1, $U_{\rm IN}$ 2 $V_{\rm IN}$ 1, $V_{\rm IN}$ 2 $W_{\rm IN}$ 1, $W_{\rm IN}$ 2	25, 26 23, 24 21, 22	U phase hall element input pin. 'H' of logic: $V_{IN}1>V_{IN}2$ V phase hall element input pin. 'H' of logic: $V_{IN}1>V_{IN}2$ W phase hall element input pin. 'H' of logic: $V_{IN}1>V_{IN}2$
U <sub>OUT</sub> V <sub>OUT</sub> W <sub>OUT</sub>	4 5 6	U phase output pin V phase output pin W phase output pin
V <sub>CC</sub> 1	3	Power supply pin for applying output
V <sub>CC</sub> 2	8	Power supply pin for applying voltage to each section other than output section. This voltage must be stabilized to be free from ripple, noise, etc.
Rf	7	Output current detect pin. By connecting Rf across this pin and GND pin, output current is detected as voltage. The result is used to control the overcurrent protection circuit.
CD	19	Pin for fetching current (voltage) detected with Rf. To take feedback for Rf, the control-output voltage gain can be reduced. Ground when not in use.
FC	27	Frequency characteristic correction
v <sub>c</sub>	18	Speed-phase control pin Control is of voltage-controlled type that controls output voltage.
V <sub>CREF</sub>	13	Control reference voltage
GND	28	GND for other than output Minimum potential of output transistor is at Rf pin.
F/RC	20	Forward/reverse control pin By setting this pin to 'H' (more than 2.0V)/'L' (less than 0.3V), truth value is changed to perform forward/reverse rotation.
FGin-, FGin+	9,10	FG signal input pin
FG <sub>OUT</sub>	11	FG amp output pin
CR	12	This pin voltage can be used to change the hall input-output gain. Connection of an external resistor and capacitor makes it possible to detect the rotational speed of a motor and change the hall input-output voltage gain in two steps.

### **Truth Table**

	Source			Input		Forward/Reverse Control	
		Sink	U	V	w	F/RC	
1	W phase	V phase	Н		L	L	
7	V phase -	W phase		H	ւ	Н	
2	W phase -	U phase	н	//.	L	L	
2	U phase -	W phase	1 n	L	L	Н	
3	V phase -	• W phase	Ĺ		,,,	L	
3	W phase -	V phase		L	LH	н	Н
4	U phase -	V phase		1.1		L	
4	V phase -	U phase	"	LH	L	Н	
5	V phase -	U phase	н	T	,,	L	
o	U phase -	V phase		L	Н	Н	
	U phase -	W phase	L	<b> </b>	7,		L
6	W phase	U phase		Н	Н	Н	

- Input:

  H: Each phase input 1 is more than
  0.2V higher than each phase input 2.
- Input 2.

  L: Each phase input 1 is more than 0.2V lower than each phase input 2.

  Forward/reverse control:

  H: 2.0 to V<sub>CC</sub>2

  L: 0 to 0.3V