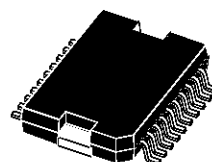


DUAL 5V MULTIFUNCTION VOLTAGE REGULATOR

PRELIMINARY DATA

- STANDBY OUTPUT VOLTAGE PRECISION 5V $\pm 2\%$
- OUTPUT 2 TRACKED TO THE STANDBY OUTPUT
- OUTPUT 2 DISABLE FUNCTION FOR STANDBY MODE
- VERY LOW QUIESCENT CURRENT, LESS THAN 260 μ A, IN STANDBY MODE
- OUTPUT CURRENTS : $I_{O1} = 50\text{mA}$, $I_{O2} = 500\text{mA}$
- VERY LOW DROPOUT (max 0.4V/0.6V)
- OPERATING TRANSIENT SUPPLY VOLTAGE UP TO 40V
- POWER-ON RESET CIRCUIT SENSING THE STANDBY OUTPUT VOLTAGE
- POWER-ON RESET DELAY PULSE DEFINED BY THE EXTERNAL CAPACITOR
- THERMAL SHUTDOWN AND SHORT CIRCUIT PROTECTIONS



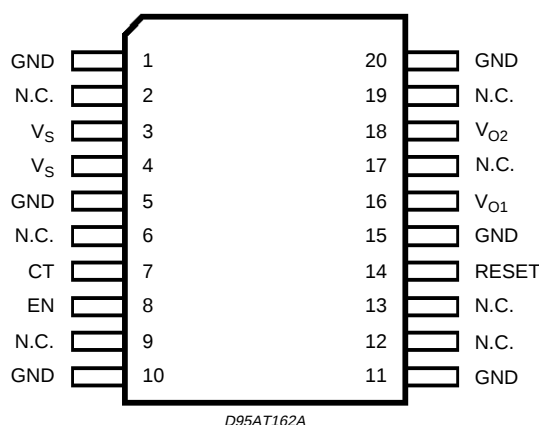
PowerSO20

ORDERING NUMBER: L4937NPD

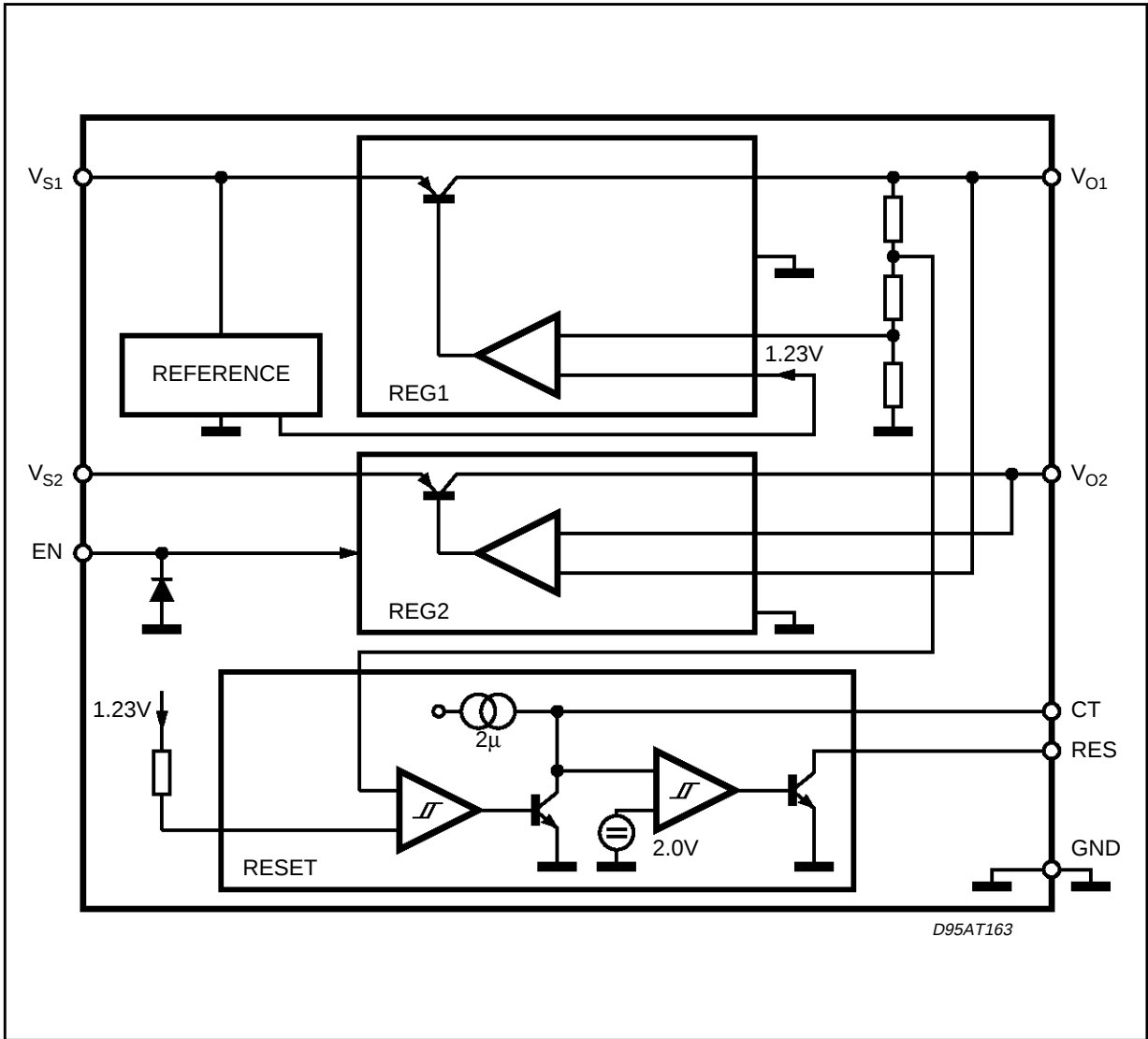
DESCRIPTION

The L4937NPD is a monolithic integrated dual voltage regulators with two very low dropout outputs and additional functions such as power-on reset and input voltage sense. They are designed for supplying microcomputer controlled systems specially in automotive applications.

PIN CONNECTION (top view)



BLOCK DIAGRAM



THERMAL DATA

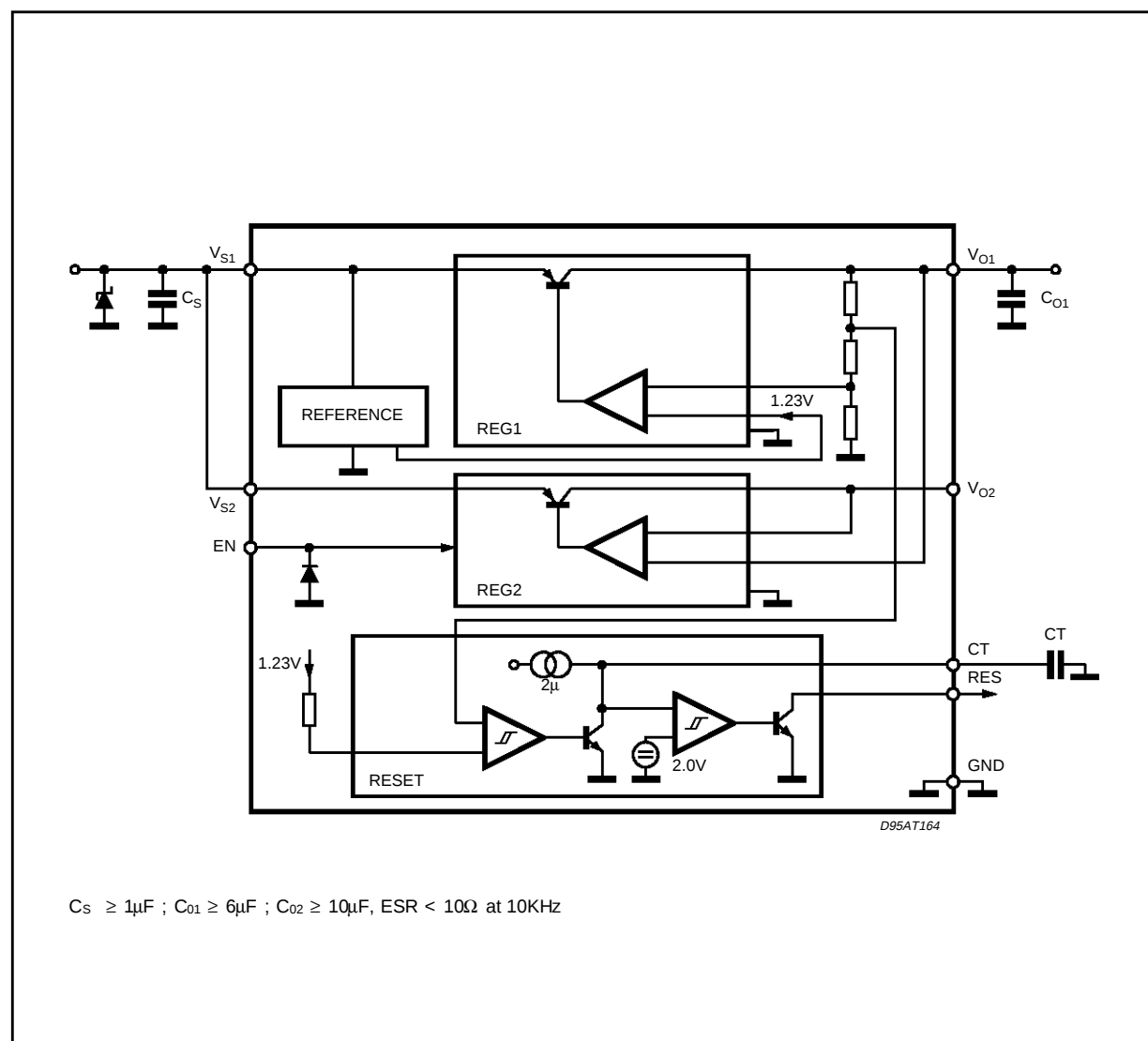
Symbol	Parameter	Value	Unit
$R_{thj-case}$	Thermal Resistance Junction-Case	Max. 1.5	$^{\circ}C/W$

ABSOLUTE MAXIMUM RATINGS

Symbol	Parameter	Value	Unit
V_S	DC Supply Voltage	28	V
	Transient Supply Voltage ($T < 1s$)	40	V
T_j, T_{stg}	Junction and Storage Temperature Range	-55 to 150	°C
I_{EN}	Enable Input Current ($V_{EN} \leq 0.3V$)	± 1	mA
V_{EN}	Enable Input Voltage	V_S	
V_{RES}	Reset Output Voltage	20	V
I_{RES}	Reset Output Current	5	mA
P_D	Power Dissipation	875	mW

Note : The circuit is ESD protected according to MIL-STD-883C.

APPLICATION CIRCUIT



ELECTRICAL CHARACTERISTICS ($V_S = 14V$; $-40^{\circ}C \leq T_J \leq 125^{\circ}C$ unless otherwise specified)

Symbol	Parameter	Test Conditions	Min.	Typ.	Max.	Unit
V_S	Operating Supply Voltage				25	V
V_{O1}	Standby Output Voltage	$6V \leq V_S \leq 25V$ $1mA \leq I_{O1} \leq 50mA$	4.90	5.00	5.10	V
$V_{O2} - V_{O1}$	Output Voltage 2 Tracking Error	$6V \leq V_S \leq 25V$ $5mA \leq I_{O2} \leq 500mA$ Enable = LOW	-25		+25	mV
V_{DP1}	Dropout Voltage 1	$I_{O1} = 10mA$ $I_{O1} = 50mA$		0.1 0.2	0.25 0.4	V V
V_{IO1}	Input to Output Voltage Difference in Undervoltage Condition	$V_S = 4V, I_{O1} = 35mA$			0.4	V
V_{DP2}	Dropout Voltage 2	$I_{O1} = 100mA$ $I_{O1} = 500mA$		0.2 0.3	0.3 0.6	V V
V_{IO2}	Input to Output Voltage Difference in Undervoltage Condition	$V_S = 4.6V, I_{O1} = 350mA$			0.6	V
$V_{OL1,2}$	Line Regulation	$6V \leq V_S \leq 25V$ $I_{O1} = 1mA; I_{O2} = 5mA$			20	mV
V_{OLO1}	Load Regulation 1	$1mA \leq I_{O1} \leq 50mA$			25	mV
V_{OLO2}	Load Regulation 2	$5mA \leq I_{O2} \leq 500mA$			50	mV
I_{LIM1}	Current Limit 1	$V_{O1} = 4.5V$ $V_{O1} = 0V$ (note 1)	55 25	100 50	200 100	mA mA
I_{LIM2}	Current Limit 2	$V_{O2} = 0V$	550	1000	1700	mA
I_{QSB}	Quiescent Current Standby Mode (output 2 disabled)	$I_{O1} = 0.3mA; T_J < 100^{\circ}C$ $V_{EN} \geq 2.4V$ $V_S = 14V$ $V_S = 3.5V$		210 340	290 850	μA μA
I_Q	Quiescent Current	$I_{O1} = 50mA$ $I_{O1} = 500mA$			30	mA

ENABLE

V_{ENL}	Enable Input LOW Voltage (output 2 active)		-0.3		1.5	V
V_{ENH}	Enable Input HIGH Voltage		2.4		7	V
V_{ENhyst}	Enable Hysteresis		30	75	200	mV
I_{EN}	Enable Input Current	$0V < V_{EN} < 1.2V$ $2.5V < V_{EN} < 7V$	-10 -1	-1.5 0	-0.5 +1	μA μA

ELECTRICAL CHARACTERISTICS (continued)

RESET

Symbol	Parameter	Test Conditions	Min.	Typ.	Max.	Unit
V_{Rl}	Reset Low Threshold Voltage		$V_{o1} - 0.4$	4.7	$V_{o1} - 0.1$	V
V_{Rth}	Reset Threshold Hysteresis		50	100	200	mV
t_{RD}	Reset Pulse Delay	$C_T = 100\text{nF}$; $t_R > 100\mu\text{s}$	55	100	180	ms
t_{RR}	Reset Reaction Time	$C_T = 100\text{nF}$	1	10	50	μs
V_{RL}	Reset Output LOW Voltage	$R_{RES} = 10\text{k}\Omega$ to V_{o1} $V_S = 1.5\text{V}$			0.4	V
I_{LRES}	Reset Output HIGH Leakage	$V_{RES} = 5\text{V}$			1	μA
V_{CTh}	Delay Comparator Threshold			2.0		V
$V_{CTh, hyst}$	Delay Comparator Threshold Hysteresis			100		mV

Note : 1: Foldback characteristic

FUNCTIONAL DESCRIPTION

The L4937ND is based on the SGS-THOMSON Microelectronics modular voltage regulator approach. Several out-standing features and auxiliary functions are provided to meet the requirements of supplying the microprocessor systems used in automotive applications.

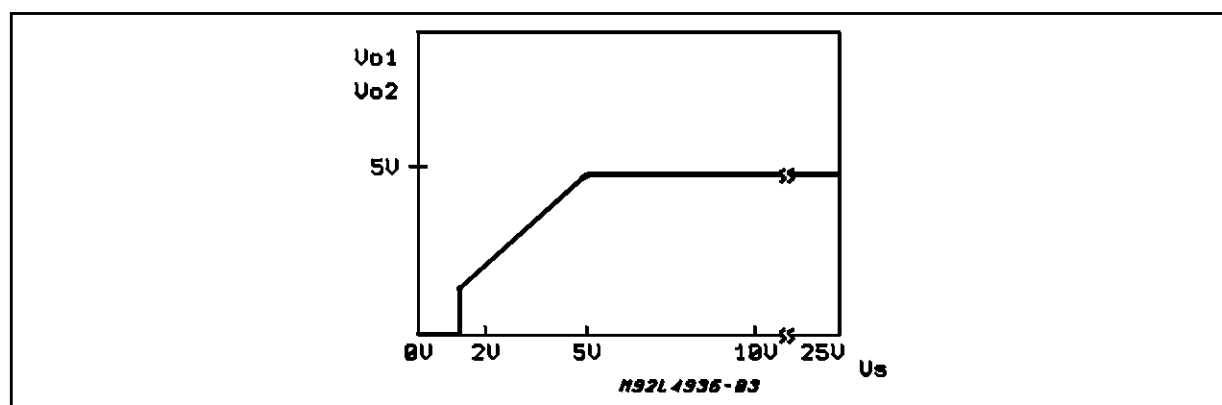
Furthermore the device is suitable also in other applications requiring two stabilized voltages.

The modular approach allows other features and functions to be realized easily when required.

STANDBY REGULATOR

The standby regulator uses an Isolated Collector Vertical PNP transistor as the regulating element. This structure allows a very low dropout voltage at currents up to 50mA. The dropout operation of the standby regulator is maintained down to 2V input supply voltage. The output voltage is regulated up to the transient input supply voltage of 40V. This feature avoids functional interruptions which could be generated by overvoltage pulses.

Figure 1 : Output Voltage vs. Input Voltage.



The typical curve of the standby output voltage as a function of the input supply voltage is shown in fig. 1.

The current consumption of the device (quiescent current) is less than 260 μA when output 2 is disabled (standby mode). The dropout voltage is controlled to reduce the quiescent current peak in the undervoltage region and to improve the transient response in this region.

The quiescent current is shown in fig. 2 as a function of the supply input voltage 2.

OUTPUT 2 VOLTAGE

The output 2 regulator uses the same output structure as the standby regulator, but rated for an output current of 500mA.

The output 2 regulator works in tracking mode with the standby output voltage as a reference voltage when the output 2.

The output 2 regulator can be switched off via the Enable input.

Figure 2 : Quiescent Current vs. Supply Voltage.

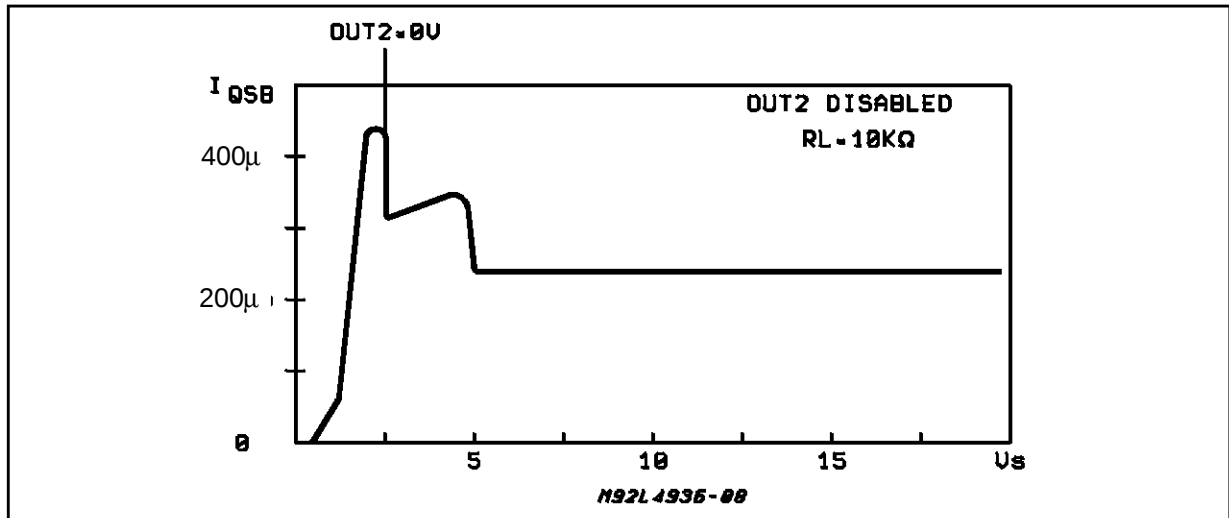
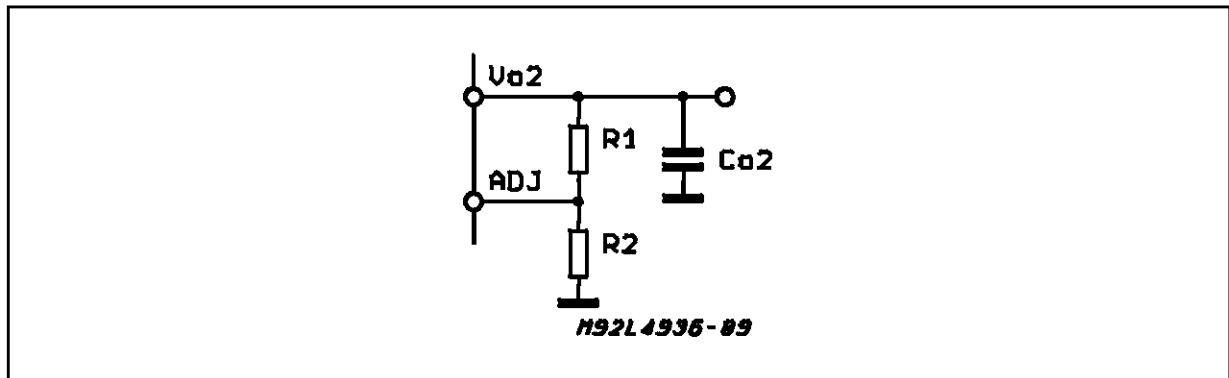


Figure 3 : Programmable Output 2 Voltage with External Resistors.



RESET CIRCUIT

The block circuit diagram of the reset circuit is shown in fig. 4. The reset circuit supervises the standby output voltage. The reset threshold of 4.7V is defined by the internal reference voltage and the standby output divider.

The reset pulse delay time t_{RD} , is defined by the charge time of an external capacitor C_T :

$$t_{RD} = \frac{C_T \times 2V}{2\mu A}$$

The reaction time of the reset circuit depends on the discharge time limitation of the reset capacitor C_T and is proportional to the value of C_T .

The reaction time of the reset circuit increases the noise immunity. In fact, if the standby output voltage drops below the reset threshold for a time shorter than the reaction time t_{RR} , no reset output variation occurs. The nominal reset delay is generated for standby output voltage drops longer than the time necessary for the complete discharging of the capacitor C_T . This time is typically equal to 50μs if $C_T = 100nF$. The typical reset output waveforms are shown in fig. 5.

Figure 4 :Block Diagram of the Reset Circuit.

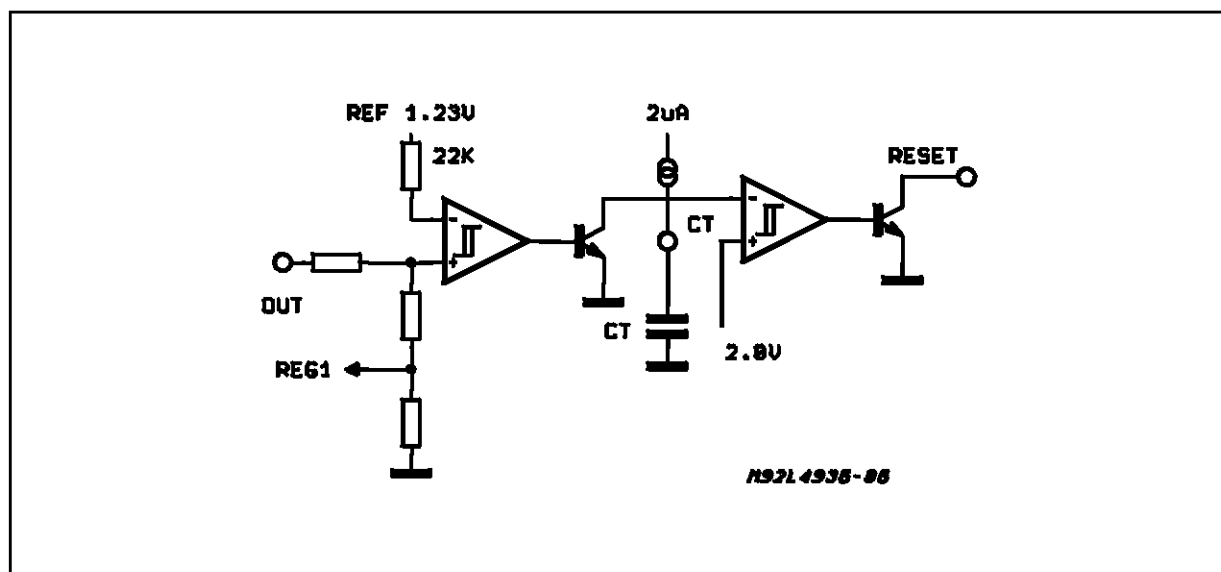
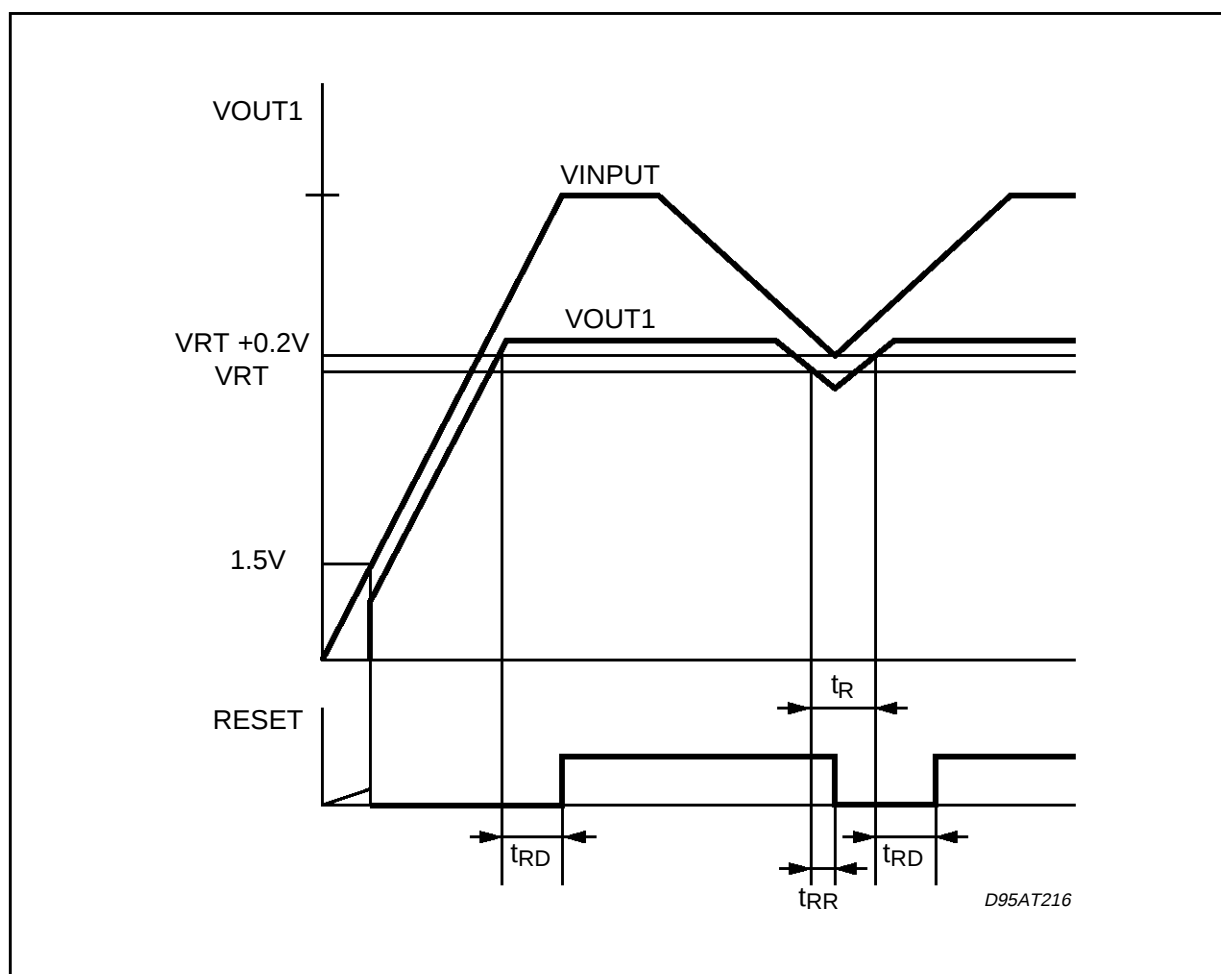


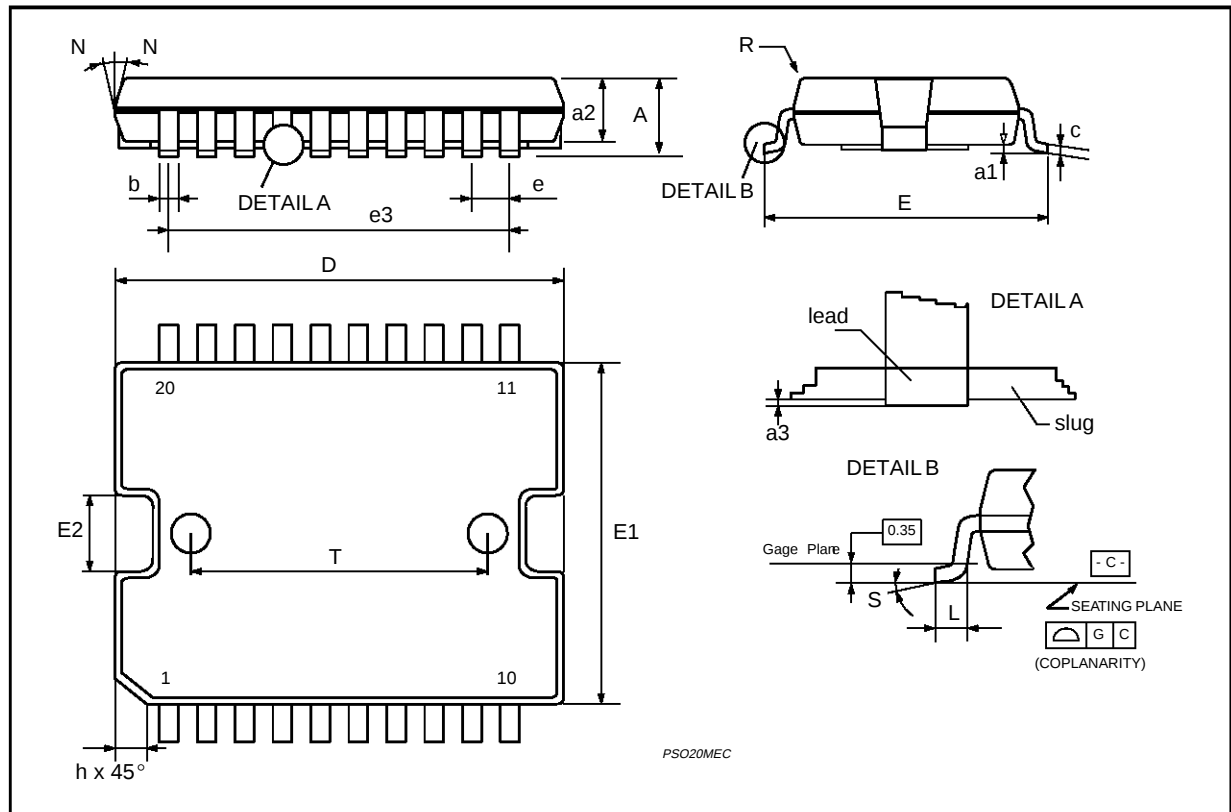
Figure 5 : Typical Reset Output Waveforms.



PowerSO20 PACKAGE MECHANICAL DATA

DIM.	mm			inch		
	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.
A			3.60			0.1417
a1	0.10		0.30	0.0039		0.0118
a2			3.30			0.1299
a3	0		0.10	0		0.0039
b	0.40		0.53	0.0157		0.0209
c	0.23		0.32	0.009		0.0126
D (1)	15.80		16.00	0.6220		0.6299
E	13.90		14.50	0.5472		0.570
e		1.27			0.050	
e3		11.43			0.450	
E1 (1)	10.90		11.10	0.4291		0.437
E2			2.90			0.1141
G	0		0.10	0		0.0039
h			1.10			
L	0.80		1.10	0.0314		0.0433
N	10° (max.)					
S	8° (max.)					
T		10.0			0.3937	

- (1) "D and E1" do not include mold flash or protrusions
- Mold flash or protrusions shall not exceed 0.15mm (0.006")



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